CS101 Computer Programming and Utilization

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May 15, 2006

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May 15, 2006 1 / 31









The story so far ...

- We have written some non-trivial programs
- We have seen various control flows.
- We have seen multi-dimensional arrays and the char data type.
- We saw how to get formatted output.
- We saw the use of functions

More Functions

We see in this talk (i) how functions are implemented, (ii) and certain calling methods. Finally, we solve some more non-trivial problems. Again www.cplusplus.com/doc/tutorial for reference.

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How are functions implemented?

```
Consider the following simple C++ code:
```

```
#include <iostream.h>
int by2(int a)
ſ
   return(a/2);
}
int main()
ſ
  int N,x,y;
  cout << "N?":
  cin >> N:
  x=by2(N);
  y=by2(x);
  xout << y;</pre>
}
```

What issues arise in the translation of C++ intp PCAL?

- What is the translation of a function into PCAL?
- How is the argument/parameter to be passed to the function?
- How is the output to be received?
- How is the control flow to be implemented?

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What issues arise in the translation of C++ intp PCAL?

- What is the translation of a function into PCAL?
- How is the argument/parameter to be passed to the function?
- How is the output to be received?
- How is the control flow to be implemented?
- Allot different memory segments for the function and the amin program.

а	output	Ν	х	у
M10	M11	M1	M2	M3

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• Allot different memory segments for the function and the amin program.

а	output	Ν	х	у
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• Translate the function:

150 RCL M10; M11=M10 DIV 2; JUMP 25

And the main program

23 M10=M1 %copy N into input

- 24 JUMP 150
- 25 M2=M11 % copy output into

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Call by Value

Consider the following simple C++ code:

```
#include <iostream.h>
int by2(int a)
ſ
   return(a/2);
}
int main()
ſ
  int N,x,y;
  cout << "N?";
  cin >> N;
  x=by2(N);
  y=by2(x);
  xout << y;</pre>
}
```

In other words,

- There is a separation of memories.
- The contents (values) of the input arguments are copied out into appropriate registers of the function.
- The function works out the answer.
- The output is copied back into appropriate registers in the calling program.
- Execution resumes.

This procedure is called CALL BY VALUE.

Call by Reference

Consider the following simple C++ code:

```
#include <iostream.h>
int by2(int a)
ſ
   return(a/2);
}
int main()
ł
  int N,x,y;
  cout << "N?":
  cin >> N:
  x=by2(N);
  y=by2(x);
  xout << y;</pre>
}
```

There is another possible scenario:

• Create the function body as before.

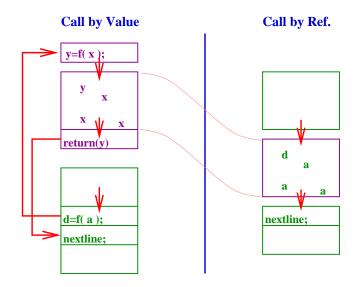
RCL M10; M11=M10 DIV 2

• For every function call, insert the function code in the main program, suitably modified:

> RCL M1 M2=M1 DIV 2

Thus, the program code of the function is copied out into the main body and actually acts on the variables of the main program. This is called Call by Reference.

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```
#include <iostream.h>
int by2ref(int& a)
ſ
   b=a/2:
   a=a-2:
   return(b);
}
int by2value(int a)
{
   b=a/2;
   a=a-2;
   return(b);
}
int main()
Ł
  N=10;
  o1=by2value(N);
  o2=by2ref(N);
  o3=by2value(N);
}
```

The observed outputs will be:

o1	o2	о3
5	5	4

This is because:

- The first call by value by2val copied out N into its own space and returned the value 5.
- The second call by reference by2ref used the memory location *N* in its working and changed it to 8.

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• The third call will now reflect N/2 = 4.

```
#include <iostream.h>
int by2ref(int& a)
{
   b=a/2;
   a=a-2;
   return(b);
}
int by2value(int a)
{
   b=a/2:
   a=a-2;
   return(b);
7
int main()
  N=10:
  o1=by2value(N);
  o2=by2ref(N);
  o3=by2value(N);
```

How do I specify Call by Reference?:

- Put an "&" after the type declaration that you want passed by reference. A function may have some arguments by value and others by reference.
- The calling syntax remains the same. Everything else remains the same.
- The caller does not know, without looking at the function definition, if his input parameters are going to change!.

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• Having more than one outputs from a function.

The GCD problem

Recall that if g is the gcd of m and n, then

$$g = \alpha m + \beta m$$

Write a program to compute g, α, β .

We use Euclid's algorithm.

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Write a program to compute g, α, β .

We use Euclid's algorithm.

• If m > n and $m = n \cdot q + r$, then

gcd(m, n) = gcd(n, r)

This is used to reduce the two arguments systematically.

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• If m > n and $m = n \cdot q + r$, then

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- At each step if *m*' and *n*' are such that
 - gcd(m', n') = gcd(m, n).

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► Each *m*′, *n*′ is a linear combination of *m*, *n*.

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Write a program to compute g, α, β .

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• If m > n and $m = n \cdot q + r$, then

gcd(m, n) = gcd(n, r)

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- At each step if *m*' and *n*' are such that
 - gcd(m', n') = gcd(m, n).
 - ► Each *m*′, *n*′ is a linear combination of *m*, *n*.
- The above two steps are used recursively. If $m' = n' \cdot q' + r'$, then:
 - ▶ gcd(n', r') = gcd(m', n') = gcd(m, n).

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Each n', r' is a linear combination of m, n.

 Having more than one outputs from a function.

```
    Having more than one
outputs from a function.
```

We see here that A(a,b,q,r) have four arguments.

- The assumption is that a > b.
- a,b are the input arguments, passed by value.
- q,r are the output arguments, passed by reference.

The function implements:

a = b * q + r

Lets look at the main program:

- M,N are read in with M > N.
- *m*, *n* are the running arguments with the following invariants.
 - ▶ *m* > *n*.
 - ►
- $\begin{array}{rcl} m & = & x[0] * m + x[1] * n \\ n & = & y[0] * m + y[1] * n \end{array}$
- The next pair is $(m, n) \rightarrow (n, r)$, where

$$r = m - q * n = (x[0] - q * y[0]) * m + (x[1] - q * y[1]) * n$$

```
int main()
ł
  int ...,x[2],y[2],t[2];
  x[0]=1; x[1]=0; y[0]=0; y[1]=1
  cout << "M>N?\n";
  cin >> M >> N;
  m=M; n=N;
  A(m,n,q,r);
  while (r!=0)
  ſ
    m=n; n=r;
    t[0] = x[0] - q * y[0];
    t[1]=x[1]-q*y[1];
    for (int i=0;i<2;i=i+1)
    { x[i]=y[i];
       y[i]=t[i];
    }
    A(m,n,q,r);
  }
  cout << ...
}
        ・ロト ・雪ト ・ヨト
                          - 21
```

May 15, 2006

22 / 31

```
Uses of Call by reference
                                    int main()
                                    ſ

    Having more than one

       outputs from a function.
                                      m=M; n=N;
   [sohoni@nsl-13 lectures]$ ./a.out
   M > N?
   99 87
                                      ł
   gcd=3 alpha=-7 beta=8
   [sohoni@nsl-13 lectures]$ ./a.out
   M>N?
   115 78
   gcd=1 alpha=19 beta=-28
                                        }
                                      }
                                    }
                                            (a)
```

int ...,x[2],y[2],t[2]; x[0]=1; x[1]=0; y[0]=0; y[1]=1 cout << "M>N?\n"; cin >> M >> N;A(m,n,q,r);while (r!=0) m=n; n=r; t[0] = x[0] - q * y[0];t[1]=x[1]-q*y[1]; for (int i=0;i<2;i=i+1) { x[i]=y[i]; y[i]=t[i]; A(m,n,q,r);cout << ...

- Having more than one outputs from a function.
- Processing a large data-structure locally, without making copies.

Layer Fill

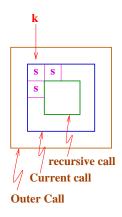
Fill up an $n \times N$ array in layers.





Strategy:

- Start with the outermost layer.
- Each call fills up the *k*-th layer and calls recursively, for the next layer.



() < </p>

```
void layer(int a[10][10],int k,
              int N, int start)
{ int low,hi,i,j;
  low=k; hi=N-k;
  if (low+1==hi){
     a[low][low]=start;
     return;
  }
  for (i=low;i<hi;i=i+1)</pre>
  { for (j=low; j<hi; j=j+1)</pre>
     {if ((i==low) || (i==hi-1)
      || (j==low) || (j==hi-1))
          a[i][j]=start;
     };
  };
  if (low+1==hi-1) return:
  layer(a,k+1,N,start+1);
  return;
}
```

```
void layer(int a[10][10],int k,
              int N, int start)
{ int low,hi,i,j;
  low=k; hi=N-k;
  if (low+1==hi){
     a[low][low]=start;
     return;
  }
  for (i=low;i<hi;i=i+1)</pre>
  { for (j=low; j<hi; j=j+1)</pre>
     {if ((i==low) || (i==hi-1)
      || (j==low) || (j==hi-1))
          a[i][j]=start;
     };
  };
  if (low+1==hi-1) return:
  layer(a,k+1,N,start+1);
  return;
}
```

Whats Happening

- The red code is the meat of the procedure.
- The green code is to terminate/continue the recursion.
- a is already filled correctly for 1,2,...,k-1.
- hi, low locate the boundaries.
- a is modified at the boundary and then a recursion.

```
void layer(int a[10][10],int k,
              int N, int start)
{ int low,hi,i,j;
  low=k; hi=N-k;
  if (low+1==hi){
     a[low][low]=start;
     return;
  }
  for (i=low;i<hi;i=i+1)</pre>
  { for (j=low; j<hi; j=j+1)</pre>
     {if ((i==low) || (i==hi-1)
      || (j==low) || (j==hi-1))
          a[i][j]=start;
     };
  };
  if (low+1==hi-1) return;
  layer(a,k+1,N,start+1);
  return;
}
```



- a: array always passed by reference, no need to declare it as such.
- k: layer to start
- N: array size
- start: the entry for layer k

```
int main()
{
    int a[10][10], N,i,j;
    cout << "N?\n";
    cin >> N;
    layer(a,0,N,1);
}
```

Assignments

• Write a program which on input N and k, outputs the $\binom{N}{k}$ subsets of $\{1, \ldots, N\}$ in an array of size $k \times \binom{N}{k}$. For example, for the input 4, 2 the following output is expected (upto column re-ordering):

1	1	1	2	2	3
2	3	4	3	4	4

Let A be an N × N entries 0-1. Given p = (i₀, j₀) and p' = (i₁, j₁), we must check if there is a path in the matrix from p to p' which moves left/right/up/down, but does not visit any point (i, j) such that A[i][j]=0. See example below:

$$(2,0) \longrightarrow (2,4)$$

1	0	0	1	0	1
1	1	0	0	0	0
1	0	1	0	1	0
1	0	1	1	1	0
1	1	1	0	0	1
0	0	0	0	0	0