FaSTIP: A New Method for Detection and Description of Space-Time Interest Points for Human Activity Classification

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Human activity Analysis

• Due to applications in surveillance, video indexing and automatic video navigation, human activity analysis is quite a hot topic in Computer vision.

Aggarwal and Ryoo, "Human Activity Analysis: A Review", ACM Computing Surveys, 2011 + 🛛 🛓 🚽 🤉 🖉

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- Human activity analysis may be broadly classified into two main approaches¹
 - Single layered approaches
 - Hierarchical approaches

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 - Single layered approaches
 - Spatio-temporal features
 - Hierarchical approaches

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• Spatio-temporal feature based approaches may further be grouped into **Two** categories.

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- histograms of gradient and optical flow computed over the frames (e.g., $\ensuremath{\text{HOG}}$ and $\ensuremath{\text{HOF}})$

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• Local feature based approach is so far the most successful.

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- Describe the interest points in terms of locally computed features

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Human activity analysis based on local spatio-temporal features

 $^{^{3}}$ Dollar et al., Behavior Recognition via Sparse Spatio-Temporal Features, VS-PETS, 2005 = + (=) 2

Human activity analysis based on local spatio-temporal features

• Dollar et al.³ have used two-dimensional Gaussian smoothing kernel in the spatial domain, and two one-dimensional Gabor filters in the temporal domain to detect the interest points.

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Human activity analysis based on local spatio-temporal features

- Dollar et al.³ have used two-dimensional Gaussian smoothing kernel in the spatial domain, and two one-dimensional Gabor filters in the temporal domain to detect the interest points.
- They try to capture salient periodic motion.
- Feature
 - Color / intensity
 - Gradient
 - Optical flow



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Human activity analysis based on local spatio-temporal features (cont.)

• Laptev et al.⁴ have detected interest points by extending the two-dimensional **Harris corner** to three-dimension

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Human activity analysis based on local spatio-temporal features (cont.)

- Laptev et al.⁴ have detected interest points by extending the two-dimensional **Harris corner** to three-dimension
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Human activity analysis based on local spatio-temporal features (cont.)

- Laptev et al.⁴ have detected interest points by extending the two-dimensional **Harris corner** to three-dimension
- They formed a 3×3 spatio-temporal second-moment matrix of first order spatial and temporal derivatives
- Features are computed from a volume around each interest point divided into a grid of cells
- For each cell a 4-bin histogram of oriented gradient (HOG) and 5-bin histogram of oriented optical flow (HOF) are computed and concatenated to generate the feature vector.



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 $\mathsf{UCF} \ \mathsf{sports} \ (\mathsf{lifting})$

KTH (boxing) The points show using Laptev STIP. Weizmann (pjump)

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• Less sensitive to smooth motion



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- Less sensitive to smooth motion
- Many points are outside the interest region



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To address these problems we propose a novel method based on the facet model.

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• Two dimensional facet model

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Proposed method

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- Proposed method
- Experimental evaluation

• Two dimensional facet model

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- Proposed method
- Experimental evaluation
- Conclusion

An image region may be approximated by piecewise bi-cubic function f : N × N → ℝ given by⁵

$$f(x,y) = k_1 + k_2 x + k_3 y + k_4 x^2 + k_5 x y + k_6 y^2 + k_7 x^3 + k_8 x^2 y + k_9 x y^2 + k_{10} y^3$$

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where coefficients k_1, \ldots, k_{10} are calculated by convolving the image with different two dimensional masks.

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-13	2 7		2	-13				
2	17	22	17	2				
7	22	27	22	7				
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2	17	22	17	2	-44	-62	-68	-62	-44
7	22	27	22	7	0	0	0	0	0
2	17	22	17	2	44	62	68	62	44
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• A corner point is where the gradient changes abruptly along the direction orthogonal to the gradient direction.

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- A corner point is where the gradient changes abruptly along the direction orthogonal to the gradient direction.
- A corner response function $\theta'_{\alpha}(0,0)$ at the center (i.e., candidate pixel) may be defined as

$$heta^{'}_{lpha}(0,0)=rac{-2(k_{2}^{2}k_{6}-k_{2}k_{3}k_{5}+k_{3}^{2}k_{4})}{(k_{2}^{2}+k_{3}^{2})^{rac{3}{2}}}$$

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- For a given threshold Ω , $| heta'_lpha(0,0)|>\Omega$

Propose methodology

• We extend the two-dimensional facet model to three-dimension to detect the interest points in video data.

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Propose methodology

- We extend the two-dimensional facet model to three-dimension to detect the interest points in video data.
- We estimate the video data as a tri-cubic function
 f : N × N × N → R over a neighborhood of each point in the space-time domain given by

$$f(x, y, t) = k_1 + k_2 x + k_3 y + k_4 t + k_5 x^2 + k_6 y^2 + k_7 t^2 + k_8 xy + k_9 yt + k_{10} xt + k_{11} x^3 + k_{12} y^3 + k_{13} t^3 + k_{14} x^2 y + k_{15} xy^2 + k_{16} y^2 t + k_{17} yt^2 + k_{18} x^2 t + k_{19} xt^2 + k_{20} xyt$$

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We derive twenty different masks to calculate the coefficients k₁,...., k₂₀ by simple convolution with those masks over the neighborhood of the candidate point.

• Calculate the rate of change of directional derivative of *f* in the direction orthogonal to the derivative direction.

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- Calculate the rate of change of directional derivative of *f* in the direction orthogonal to the derivative direction.
- Let T be the unit vector along the gradient of f(x, y, t) at any point (x, y, t), then

$$\overrightarrow{T}(x,y,t) = rac{1}{d}(f_x,f_y,f_t), ext{ where } d = \sqrt{f_x^2 + f_y^2 + f_t^2}$$

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• For a function f, the normal \overrightarrow{N} to the gradient vector \overrightarrow{T} is given by

$$\overrightarrow{N}(x,y,t) = \bigtriangledown^2 f - [\bigtriangledown^2 f \cdot \overrightarrow{T}]\overrightarrow{T}$$

where

$$\nabla^2 = \left(\frac{\partial^2}{\partial x^2}, \frac{\partial^2}{\partial y^2}, \frac{\partial^2}{\partial z^2}\right)$$

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• So to detect interest point we need to calculate $\vec{T}' \cdot \vec{N}$.

• Consider a straight line passing through the origin and any point on that line be $(\rho \sin \theta \sin \phi, \rho \sin \theta \cos \phi, \rho \cos \theta)$.

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- Let $\overrightarrow{T}'_{\theta,\phi}(\rho) = [T'_1(\rho), T'_2(\rho), T'_3(\rho)]$ be the directional derivative of \overrightarrow{T} in the direction (θ, ϕ) (where ' indicates derivative with respect to ρ).

$$\begin{aligned} \Gamma_1'(\rho) &= \frac{d}{d\rho} [\frac{f_{\chi}(\rho)}{d}] \\ &= \frac{A(\rho)f_y - B(\rho)f_y}{d^3} \end{aligned}$$

where

$$A(\rho) = f'_{x}f_{y} - f_{x}f'_{y}$$
, and $B(\rho) = f_{x}f'_{t} - f'_{x}f_{t}$

• Similarly

$$T_2'(\rho) = \frac{C(\rho)f_t - A(\rho)f_x}{d^3}$$
$$T_3'(\rho) = \frac{B(\rho)f_x - C(\rho)f_y}{d^3}$$

where

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• Let $\overrightarrow{N}_{\theta,\phi}(\rho) = [N_1(\rho), N_2(\rho), N_3(\rho)]$ be a normal to gradient vector $\overrightarrow{T}_{\theta,\phi}(\rho)$ at the point $(\rho \sin \theta \sin \phi, \rho \sin \theta \cos \phi, \rho \cos \theta)$.

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Then we have

$$N_{1}(\rho) = f_{xx} - \frac{f_{x}}{d^{2}} (f_{x}f_{xx} + f_{y}f_{yy} + f_{t}f_{tt}) = \frac{D(\rho)f_{y} - E(\rho)f_{t}}{d^{2}}$$
(1)

where

$$D(\rho) = f_{xx}f_y - f_xf_{yy}, \text{ and } E(\rho) = f_xf_{tt} - f_{xx}f_t$$
(2)

• Similarly,

$$N_2(\rho) = \frac{F(\rho)f_t - D(\rho)f_x}{d^2}$$
(3)

$$N_3(\rho) = \frac{E(\rho)f_x - F(\rho)f_y}{d^2}$$
(4)

where

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(5)

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where

$$F(\rho) = f_{yy}f_t - f_y f_{tt}$$
(5)

Let Θ_{θ,φ}(ρ) be the rate of change of gradient in the direction orthogonal to the gradient of f at any point (ρ sin θ sin φ, ρ sin θ cos φ, ρ cos θ). Then

$$\Theta_{\theta,\phi}(\rho) = \overrightarrow{T}' \cdot \overrightarrow{N}$$

$$= \frac{AD + BE + CF}{d^3d'} (6)$$

where

$$d'^{2} = N_{1}^{2} + N_{2}^{2} + N_{3}^{2}$$
(7)

 At origin (i.e., at the candidate pixel over the neighborhood of which the function *f* is estimated) we calculate the rate of change of gradient of *f* along orthogonal direction by putting *ρ* = 0 in the equation (6) as

$$\Theta_{\theta,\phi}(0) = \frac{A(0)D(0) + B(0)E(0) + C(0)F(0)}{d^{3}(0)d'(0)}$$
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• Now from equation (13) we have

$$\begin{aligned} f_x(0) &= k_2, \quad f_{xx}(0) = 2k_5 \\ f_y(0) &= k_3, \quad f_{yy}(0) = 2k_6 \\ f_t(0) &= k_4, \quad f_{tt}(0) = 2k_7 \end{aligned}$$

and

$$\begin{aligned} f'_{x}(0) &= 2k_{5}\sin\theta\sin\phi + k_{8}\sin\theta\cos\phi + k_{10}\cos\theta \\ f'_{y}(0) &= 2k_{6}\sin\theta\cos\phi + k_{8}\sin\theta\sin\phi + k_{9}\cos\theta \\ f'_{t}(0) &= 2k_{7}\cos\theta + k_{9}\sin\theta\cos\phi + k_{10}\sin\theta\sin\phi \end{aligned}$$
(10)

• θ and ϕ are defined based on orthogonal vector (\overrightarrow{N}) as

$$\theta = \tan^{-1}(\frac{\sqrt{N_1^2 + N_2^2}}{N_3}) \text{ and } \phi = \tan^{-1}(\frac{N_1}{N_2})$$
 (11)

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• The point (0,0,0) is declared as a space-time interest point if the following two conditions are satisfied:

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- The point (0,0,0) is declared as a space-time interest point if the following two conditions are satisfied:
 - The point (0,0,0) is a spatio-temporal bounding surface point, and

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• For a given threshold Ω , $|\Theta_{ heta,\phi}(0)| > \Omega$

Interest points in video data



UCF sports (lifting) KTH (boxing) Weizmann (pjump) The points show on the first row using proposed FaSTIP method and second row using Laptev STIP.

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- Finally get the feature vector of length $\eta_{x}\eta_{y}\eta_{t} imes (14 imes L+1)$

Interest point description (cont.)

For our experiment Δx = Δy = 16σ and Δt = 8τ
 where σ and τ represent the spatial and temporal scales respectively

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Interest point description (cont.)

- For our experiment $\Delta x = \Delta y = 16\sigma$ and $\Delta t = 8\tau$ - where σ and τ represent the spatial and temporal scales
 - respectively
- Divide the neighborhood into 8 cells ($\eta_x = \eta_y = \eta_t = 2$)
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- Finally, describe each interest points by a feature vector of length **232**

Experimental evaluation

• We have tested our method on three state-of-the-art human action dataset: UCF sports, KTH and Weizmann

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- UCF sports dataset contain 10 sports activities: diving, golf swinging, kicking (a ball), weight-lifting, horse riding, running, skating, swinging (on the floor), waking and swinging (at the high bar)



• KTH dataset consists of six common human activities: boxing, hand clapping, hand waving, jogging, running and walking



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• KTH dataset consists of six common human activities: boxing, hand clapping, hand waving, jogging, running and walking



 Weizmann data has ten classes: two-hands waving, bending, jumping jack, jumping, jumping in place, running, sideways, skipping, walking and one-hand waving



• For each dataset, we randomly select different number of points to build the vocabulary

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- We use multi-channel non-linear SVM with a $\chi^2\text{-kernel}$ [7] for classification

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- We use multi-channel non-linear SVM with a $\chi^2\text{-kernel}$ [7] for classification
- Run the classier for different vocabulary size and report the result for optimal vocabulary size for each dataset

Experimental results on UCF sports dataset

• Randomly select 100000 points to build the vocabulary

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Approach	Year	Accuracy(%)
Rodriguez et al. [11]	2008	69.20
Yeffet & Wolf [15]	2009	79.30
Wang et al. [14]	2009	85.60
Kovashka & Grauman [6]	2010	87.27
Wang et al. [13]	2011	88.20
Guha & Ward [5]	2012	83.80
Our approach		87.33

Comparison of results with the state-of-the-art for UCF sports dataset

Experimental results on KTH dataset

• Randomly select 200000 points to build the vocabulary

⁶Laptev et al., On Space-Time Interest Points, IJCV, 2005

Experimental results on KTH dataset

- Randomly select 200000 points to build the vocabulary
- We follow the author suggested⁶ training, validation and test data partition and obtain average accuracy of 93.51%.

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Experimental results on KTH dataset

- Randomly select 200000 points to build the vocabulary
- We follow the author suggested⁶ training, validation and test data partition and obtain average accuracy of 93.51%.
- The optimal vocabulary size is 4000

Approach	Year	Accuracy(%)
Schuldt et al. [12]	2004	71.72
Dollár et al. [3]	2005	81.17
Nowozin et al. [10]	2007	84.72
Laptev et al. [7]	2008	91.80
Niebles et al. [9]	2008	81.50
Bregonzio et al. [1]	2009	93.17
Kovashka & Grauman [6]	2010	94.53
Wang et al. [13]	2011	94.20
Our approach		93.51

Comparison of results with the state-of-the-art for KTH dataset

⁶Laptev et al., On Space-Time Interest Points, IJCV, 2005

Experimental results on Weizmann dataset

• Randomly select 30000 points to build the vocabulary

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Experimental results on Weizmann dataset

- Randomly select 30000 points to build the vocabulary
- We have tested on Weizmann dataset with leave-one-out cross validation scheme and get on an average 96.67% accuracy

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Approach	Year	Accuracy(%)
Dollár et al. [3]	2005	85.20
Gorelick et al. [4]	2007	97.80
Niebles et al. [9]	2008	90.00
Zhe Lin et al. [8]	2009	100.00
Bregonzio et al. [2]	2012	96.67
Guha & Ward [5]	2012	98.90
Our approach		96.67

Comparison of results with the state-of-the-art for Weizman dataset

Comparison with other state-of-the-art STIP points based method

• We compare our results with interest points based activity classification schemes like popular STIP⁷, Cuboid⁸ and achieve much better performance

⁷Laptev et al., On Space-Time Interest Points, IJCV, 2005

⁸ Dollar et al., Behavior Recognition via Sparse Spatio-Temporal Features, WS-PETS, 2005 🖹 🕨 🔬 🚊 🔊 ९.०

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Figure: Comparison results with STIP and Cuboid

⁷Laptev et al., On Space-Time Interest Points, IJCV, 2005

⁸Dollar et al., Behavior Recognition via Sparse Spatio-Temporal Features, VS-PET\$, 2005 🖹 + 🛛 🚊 - 🔗 ९. 🤆

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- Though our method marginally falls behind the best result only in a few classes but we achieves far better performance compared the other state-of-the-art STIP methods.
- Our FaSTIP is supposed to perform better compared to STIP and Cuboid on others applications too.

THANKS

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