

## Workshop on Essential Abstractions in GCC

# Graybox Probing for Machine Independent Optimizations

GCC Resource Center  
 (www.cse.iitb.ac.in/grc)

Department of Computer Science and Engineering,  
 Indian Institute of Technology, Bombay



30 June 2011

## Outline

- Example 1
  - ▶ Constant Propagation
  - ▶ Copy Propagation
  - ▶ Dead Code Elimination
  - ▶ Loop unrolling
- Example 2
  - ▶ Partial Redundancy Elimination
  - ▶ Copy Propagation
  - ▶ Dead Code Elimination



## Example Program 1

```
int main()
{ int a, b, c, n;

  a = 1;
  b = 2;
  c = 3;
  n = c*2;
  while (a <= n)
  {
    a = a+1;
  }
  if (a < 12)
    a = a+b+c;
  return a;
}
```

- What does this program return?
- 12
- We use this program to illustrate various shades of the following optimizations:  
 Constant propagation, Copy propagation, Loop unrolling, Dead code elimination

*Part 1*

## First Example Program



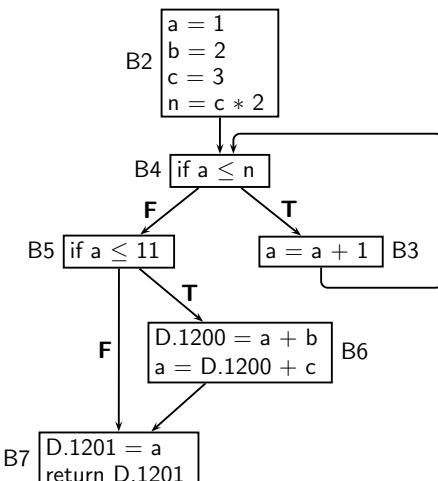
## Compilation Command

```
$gcc -fdump-tree-all -O2 ccp.c
```



## Control Flow Graph: Pictorial and Textual View

### Control flow graph



### Dump file ccp.c.013t.cfg



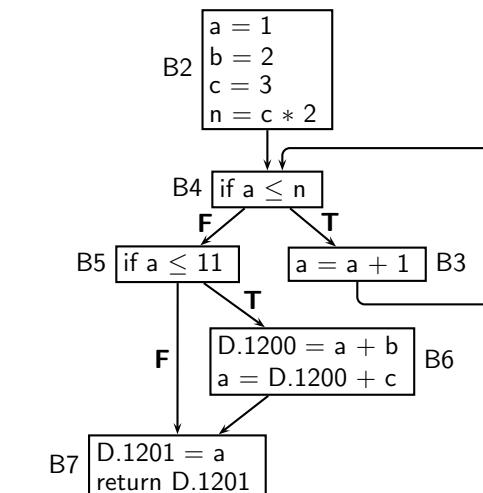
## Example Program 1

### Program ccp.c

```
int main()
{ int a, b, c, n;

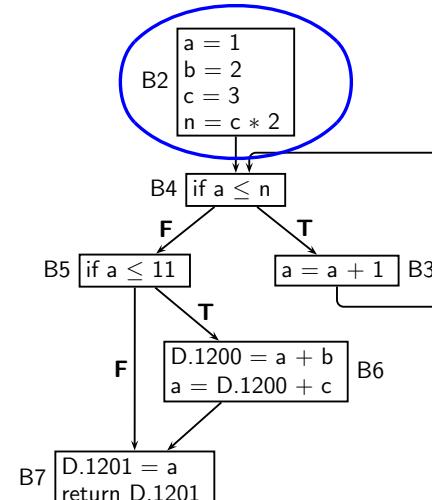
  a = 1;
  b = 2;
  c = 3;
  n = c*2;
  while (a <= n)
  {
    a = a+1;
  }
  if (a < 12)
    a = a+b+c;
  return a;
}
```

### Control flow graph



## Control Flow Graph: Pictorial and Textual View

### Control flow graph



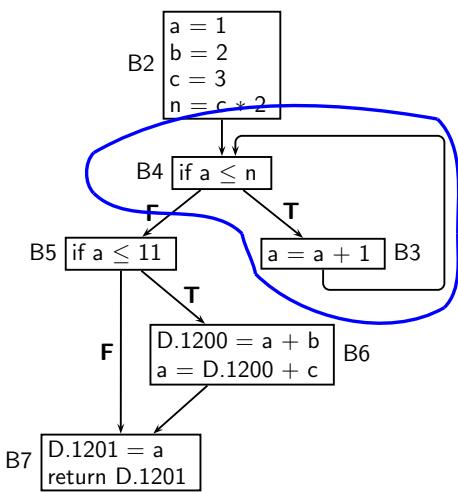
### Dump file ccp.c.013t.cfg

```
<bb 2>:
a = 1;
b = 2;
c = 3;
n = c * 2;
goto <bb 4>;
```



## Control Flow Graph: Pictorial and Textual View

Control flow graph



Dump file ccp.c.013t.cfg

```

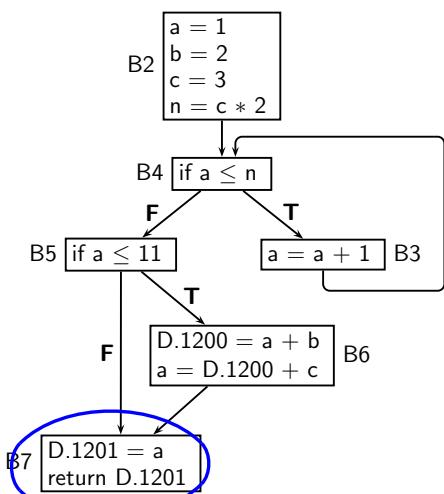
<bb 3>:
a = a + 1;

<bb 4>:
if (a <= n)
  goto <bb 3>;
else
  goto <bb 5>;
  
```



## Control Flow Graph: Pictorial and Textual View

Control flow graph



Dump file ccp.c.013t.cfg

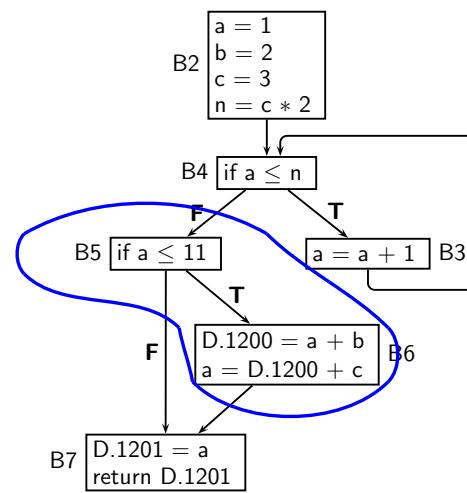
```

<bb 7>:
D.1201 = a;
return D.1201;
  
```



## Control Flow Graph: Pictorial and Textual View

Control flow graph



Dump file ccp.c.013t.cfg

```

<bb 5>:
if (a <= 11)
  goto <bb 6>;
else
  goto <bb 7>;
  
```

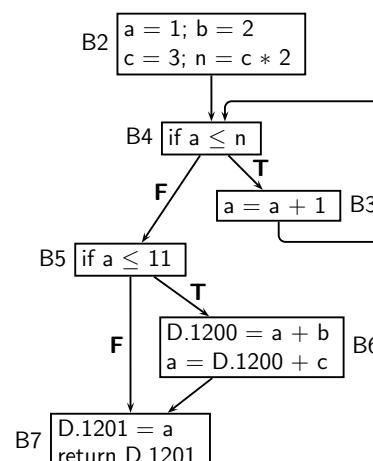
```

<bb 6>:
D.1200 = a + b;
a = D.1200 + c;
  
```

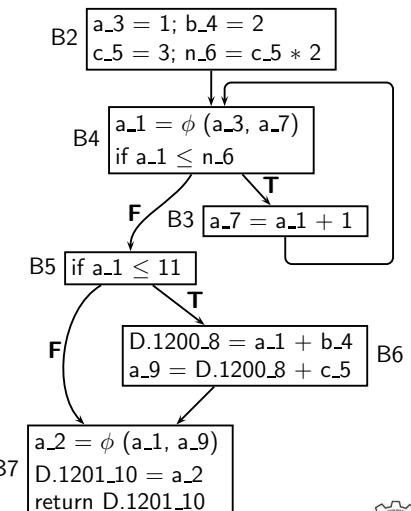


## Single Static Assignment (SSA) Form

Control flow graph

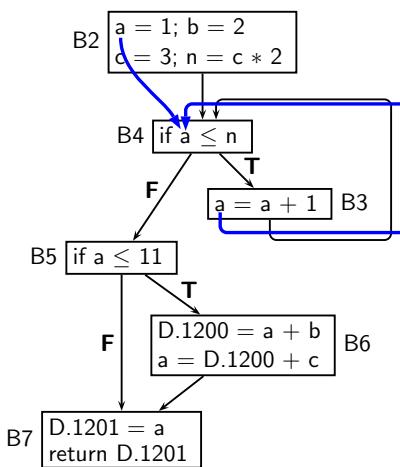


SSA Form

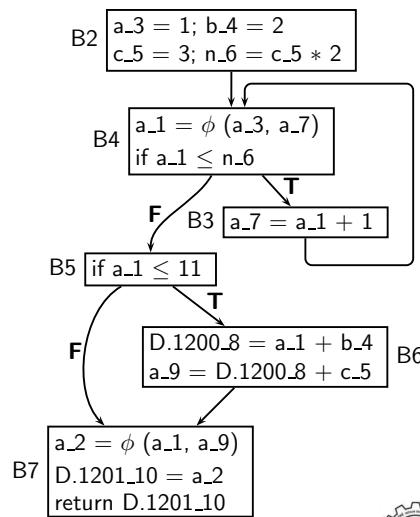


## Single Static Assignment (SSA) Form

Control flow graph

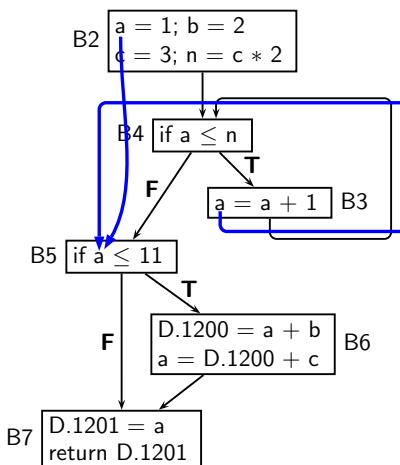


SSA Form

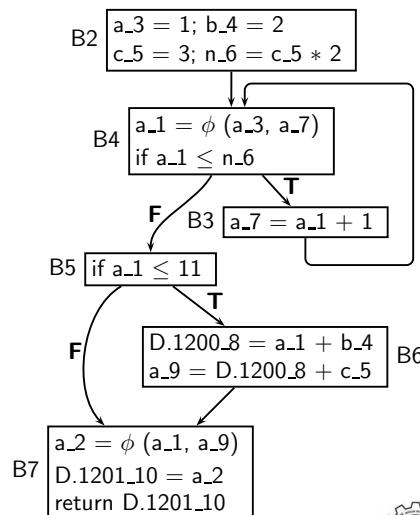


## Single Static Assignment (SSA) Form

Control flow graph

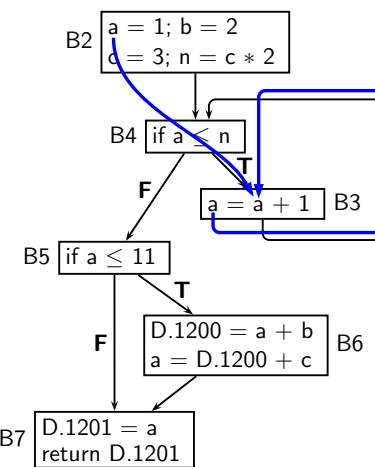


SSA Form

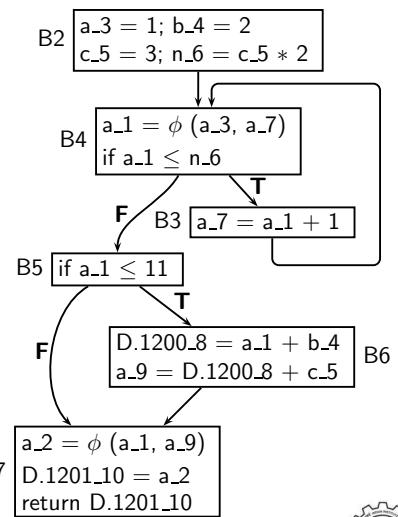


## Single Static Assignment (SSA) Form

Control flow graph

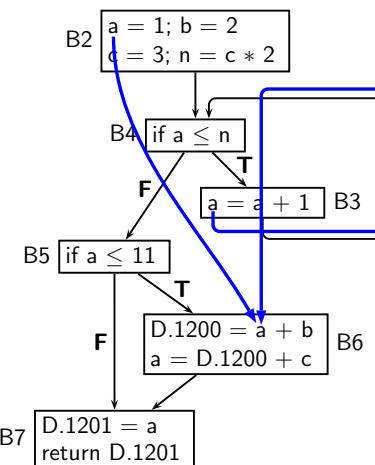


SSA Form

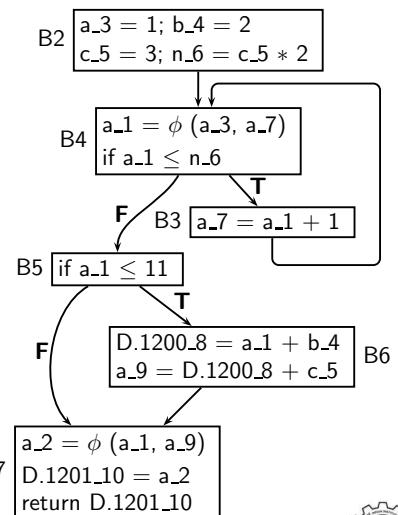


## Single Static Assignment (SSA) Form

Control flow graph

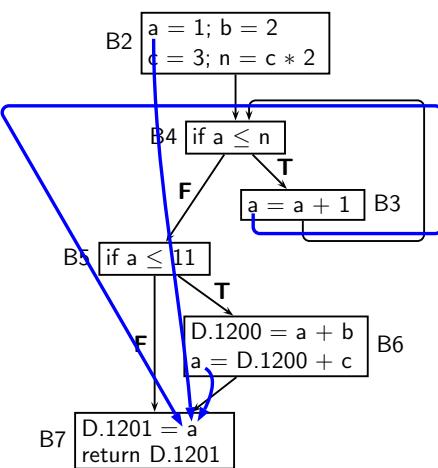


SSA Form

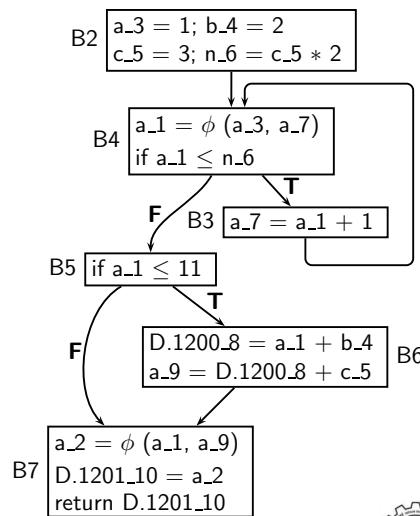


## Single Static Assignment (SSA) Form

Control flow graph

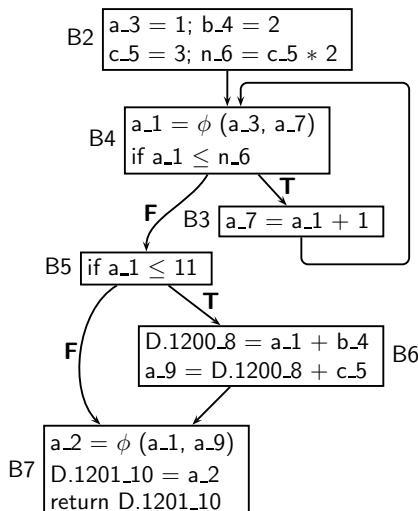


SSA Form



## SSA Form: Pictorial and Textual View

CFG in SSA form



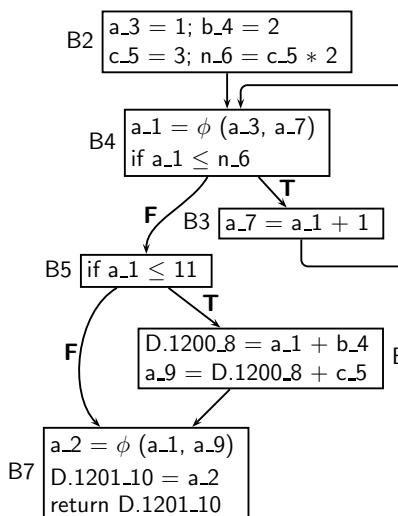
Dump file ccp.c.017t.ssa



## Properties of SSA Form

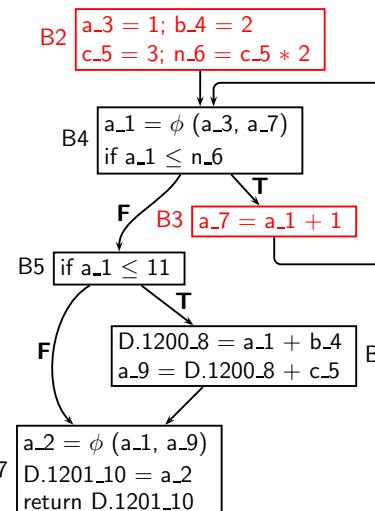
- A  $\phi$  function is a multiplexer or a selection function
- Every use of a variable corresponds to a unique definition of the variable
- For every use, the definition is guaranteed to appear on every path leading to the use

SSA construction algorithm is expected to insert as few  $\phi$  functions as possible to ensure the above properties



## SSA Form: Pictorial and Textual View

CFG in SSA form



Dump file ccp.c.017t.ssa

```

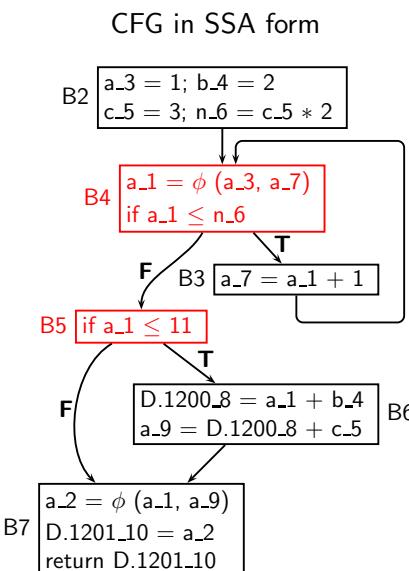
<bb 2>:
a_3 = 1;
b_4 = 2;
c_5 = 3;
n_6 = c_5 * 2;
goto <bb 4>;
  
```

```

<bb 3>:
a_7 = a_1 + 1;
  
```



## SSA Form: Pictorial and Textual View



Dump file ccp.c.017t.ssa

```

<bb 4>:
# a_1 = PHI <a_3(2), a_7(3)>
if (a_1 <= n_6)
  goto <bb 3>;
else
  goto <bb 5>;

<bb 5>:
if (a_1 <= 11)
  goto <bb 6>;
else
  goto <bb 7>;
  
```



## A Comparison of CFG and SSA Dumps

Dump file ccp.c.013t.cfg

```

<bb 2>:
a = 1;
b = 2;
c = 3;
n = c * 2;
goto <bb 4>;

<bb 3>:
a = a + 1;
  
```

Dump file ccp.c.017t.ssa

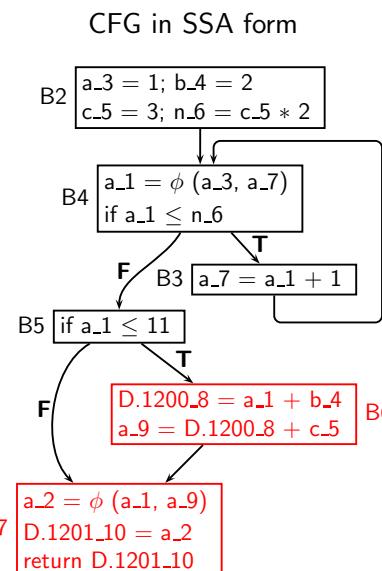
```

<bb 2>:
a_3 = 1;
b_4 = 2;
c_5 = 3;
n_6 = c_5 * 2;
goto <bb 4>;

<bb 3>:
a_7 = a_1 + 1;
  
```



## SSA Form: Pictorial and Textual View



Dump file ccp.c.017t.ssa

```

<bb 6>:
D.1200_8 = a_1 + b_4;
a_9 = D.1200_8 + c_5;

<bb 7>:
# a_2 = PHI <a_1(5), a_9(6)>
D.1201_10 = a_2;
return D.1201_10;
  
```



## A Comparison of CFG and SSA Dumps

Dump file ccp.c.013t.cfg

```

<bb 4>:
if (a <= n)
  goto <bb 3>;
else
  goto <bb 5>;

<bb 5>:
if (a <= 11)
  goto <bb 6>;
else
  goto <bb 7>;
  
```

Dump file ccp.c.017t.ssa

```

<bb 4>:
# a_1 = PHI <a_3(2), a_7(3)>
if (a_1 <= n_6)
  goto <bb 3>;
else
  goto <bb 5>;

<bb 5>:
if (a_1 <= 11)
  goto <bb 6>;
else
  goto <bb 7>;
  
```



## A Comparison of CFG and SSA Dumps

Dump file ccp.c.013t.cfg

```
<bb 6>:  
D.1200 = a + b;  
a = D.1200 + c;  
  
<bb 7>:  
D.1201 = a;  
return D.1201;
```

Dump file ccp.c.017t.ssa

```
<bb 6>:  
D.1200_8 = a_1 + b_4;  
a_9 = D.1200_8 + c_5;  
  
<bb 7>:  
# a_2 = PHI <a_1(5), a_9(6)>  
D.1201_10 = a_2;  
return D.1201_10;
```



## First Level Constant and Copy Propagation

Input dump: ccp.c.022t.copyrename1

```
<bb 2>:  
a_3 = 1;  
b_4 = 2;  
c_5 = 3;  
n_6 = c_5 * 2;  
goto <bb 4>;  
  
<bb 3>:  
a_7 = a_1 + 1;  
  
<bb 4>:  
# a_1 = PHI < a_3(2), a_7(3)>  
if (a_1 <= n_6)  
    goto <bb 3>;  
else  
    goto <bb 5>;
```

Output dump: ccp.c.023t ccp1

```
<bb 2>:  
a_3 = 1;  
b_4 = 2;  
c_5 = 3;  
n_6 = 6;  
goto <bb 4>;  
  
<bb 3>:  
a_7 = a_1 + 1;  
  
<bb 4>:  
# a_1 = PHI < 1(2), a_7(3)>  
if (a_1 <= 6)  
    goto <bb 3>;  
else  
    goto <bb 5>;
```



## Copy Renaming

Input dump: ccp.c.017t.ssa

```
<bb 7>:  
# a_2 = PHI <a_1(5), a_9(6)>  
D.1201_10 = a_2;  
return D.1201_10;
```

Output dump: ccp.c.022t.copyrename1

```
<bb 7>:  
# a_2 = PHI <a_1(5), a_9(6)>  
a_10 = a_2;  
return a_10;
```



## First Level Constant and Copy Propagation

Input dump: ccp.c.022t.copyrename1

```
<bb 2>:  
a_3 = 1;  
b_4 = 2;  
c_5 = 3;  
n_6 = 6;  
goto <bb 4>;
```

Output dump: ccp.c.023t ccp1

...

```
<bb 6>:  
D.1200_8 = a_1 + b_4;  
a_9 = D.1200_8 + c_5;
```

```
<bb 2>:  
a_3 = 1;  
b_4 = 2;  
c_5 = 3;  
n_6 = 6;  
goto <bb 4>;
```

...

```
<bb 6>:  
D.1200_8 = a_1 + 2;  
a_9 = D.1200_8 + 3;
```



## Second Level Copy Propagation

Input dump: ccp.c.023t ccp1

```
<bb 6>:
D.1200_8 = a_1 + 2;
a_9 = D.1200_8 + 3;

<bb 7>:
# a_2 = PHI <a_1(5), a_9(6)>
a_10 = a_2;
return a_10;
```

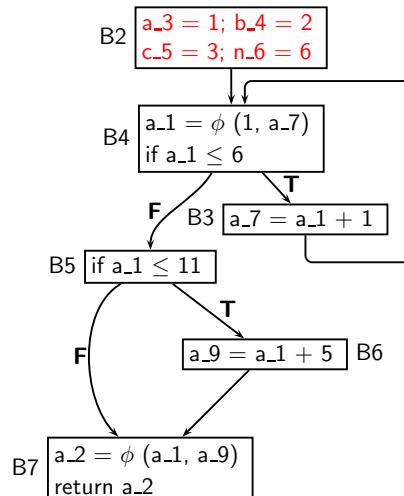
Output dump: ccp.c.027t.copyprop1

```
<bb 6>:
a_9 = a_1 + 5;

<bb 7>:
# a_2 = PHI <a_1(5), a_9(6)>
return a_2;
```



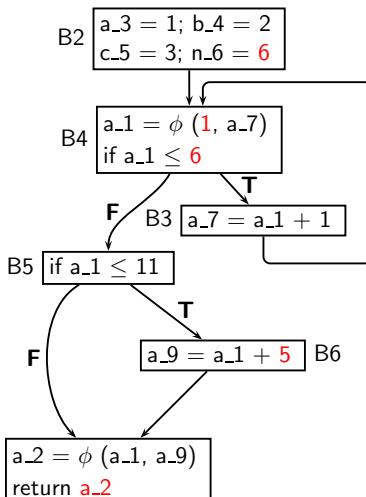
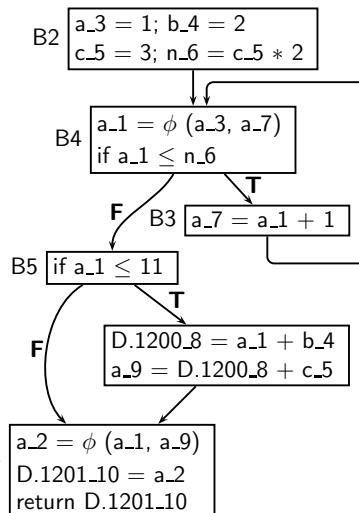
## The Result of Copy Propagation and Renaming



- No uses for variables a\_3, b\_4, c\_5, and n\_6
- Assignments to these variables can be deleted



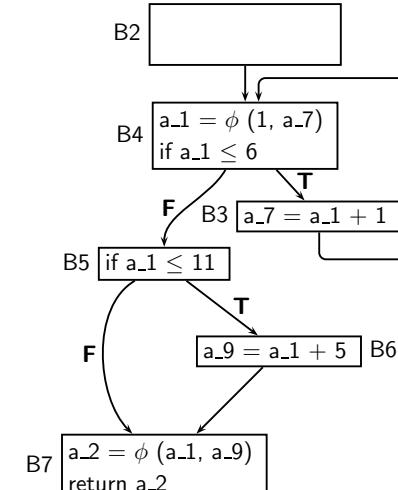
## The Result of Copy Propagation and Renaming



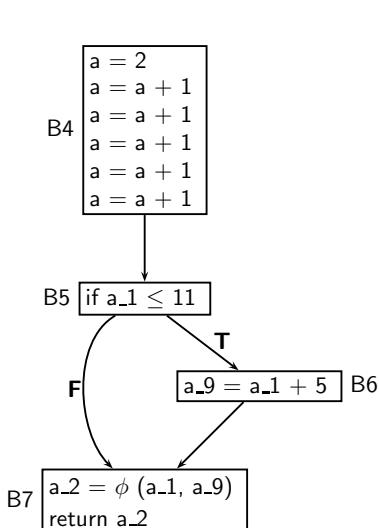
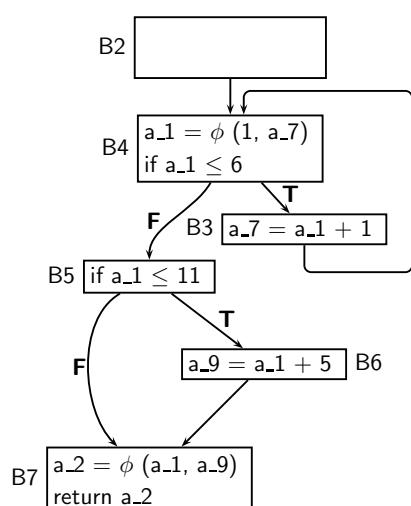
## Dead Code Elimination Using Control Dependence

Dump file ccp.c.029t.cddce1

```
<bb 2>:
goto <bb 4>;
<bb 3>:
a_7 = a_1 + 1;
<bb 4>:
# a_1 = PHI <a_1(2), a_7(3)>
if (a_1 <= 6) goto <bb 3>;
else goto <bb 5>;
<bb 5>:
if (a_1 <= 11) goto <bb 6>;
else goto <bb 7>;
<bb 6>:
a_9 = a_1 + 5;
<bb 7>:
# a_2 = PHI <a_1(5), a_9(6)>
return a_2;
```

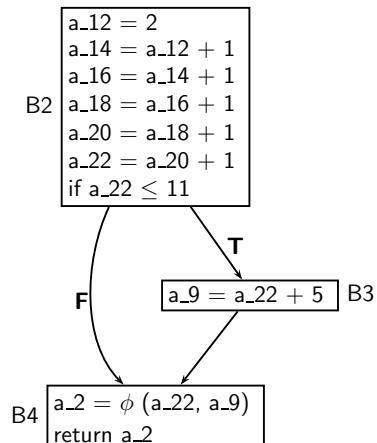


## Loop Unrolling



## Another Round of Constant Propagation

Input



Dump file: ccp.c.059t.cc2

```

main ()
{
    <bb 2>:
    return 12;
}
  
```



## Complete Unrolling of Inner Loops

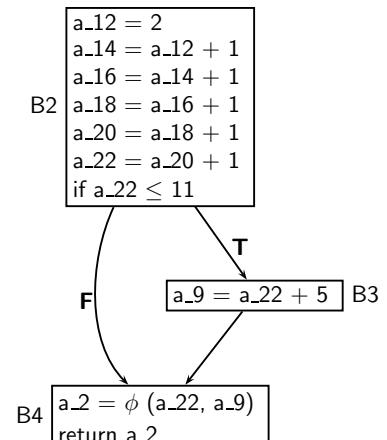
Dump file: ccp.c.058t.cunrolli

```

<bb 2>:
a_12 = 2;
a_14 = a_12 + 1;
a_16 = a_14 + 1;
a_18 = a_16 + 1;
a_20 = a_18 + 1;
a_22 = a_20 + 1
if a_22 ≤ 11 goto <bb 3>;
else goto <bb 4>;

<bb 3>:
a_9 = a_22 + 5;

<bb 4>:
# a_2 = PHI <a_22(2), a_9(3)>
return a_2;
  
```



Part 2

*Second Example Program*

## Example Program 2

```
int f(int b, int c, int n)
{ int a;

  do
  {
    a = b+c;
  }
  while (a <= n);

  return a;
}
```

We use this program to illustrate the following optimizations:

Partial Redundancy Elimination,  
Copy Propagation, Dead Code  
Elimination



## Example Program 2

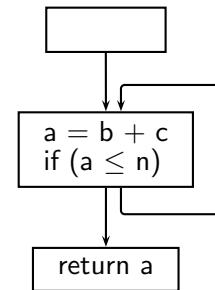
`loop.c`

```
int f(int b, int c, int n)
{ int a;

  do
  {
    a = b+c;
  }
  while (a <= n);

  return a;
}
```

Control Flow Graph



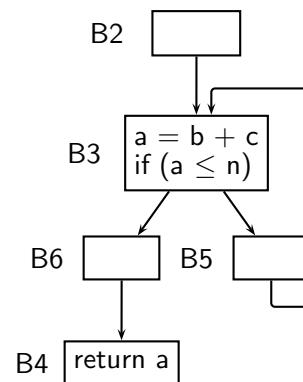
## Compilation Command

```
$gcc -fdump-tree-all -O2 -S ccp.c
```



## Dump of Input to PRE Pass

Control Flow Graph



`loop.c.091t.critd`

```
<bb 2>:
<bb 3>:
  a_3 = b_1(D) + c_2(D);
  if (a_3 <= n_4(D)) goto <bb 5>;
  else goto <bb 6>;

<bb 5>:
  goto <bb 3>;

<bb 6>:

<bb 4>:
  # a_6 = PHI <a_3(6)>
  return a_6;
```



## Input and Output of PRE Pass

```
loop.c.091t.crited

<bb 2>:
    pretmp.2_7 = b_1(D) + c_2(D);

<bb 3>:
    a_3 = b_1(D) + c_2(D);
    if (a_3 <= n_4(D))
        goto <bb 5>;
    else goto <bb 6>;

<bb 5>:
    goto <bb 3>;

<bb 6>:
<bb 4>:
    # a_6 = PHI <a_3(6)>
    return a_6;
```

```
loop.c.092t.pre

<bb 2>:
    pretmp.2_7 = b_1(D) + c_2(D);

<bb 3>:
    a_3 = pretmp.2_7;
    if (a_3 <= n_4(D))
        goto <bb 5>;
    else goto <bb 6>;

<bb 5>:
    goto <bb 3>;

<bb 6>:
<bb 4>:
    # a_6 = PHI <a_3(6)>
    return a_6;
```



## Dead Code Elimination

```
loop.c.097t.copyprop4

<bb 2>:
    pretmp.2_7 = b_1(D) + c_2(D);

<bb 3>:
    a_3 = pretmp.2_7;
    if (n_4(D) >= pretmp.2_7)
        goto <bb 4>;
    else
        goto <bb 5>;

<bb 4>:
    goto <bb 3>;

<bb 5>:
    # a_8 = PHI <pretmp.2_7(3)>
    a_6 = a_8;
    return a_8;
```

```
loop.c.098t.dceloop1

<bb 2>:
    pretmp.2_7 = b_1(D) + c_2(D);

<bb 3>:
    if (n_4(D) >= pretmp.2_7)
        goto <bb 4>;
    else
        goto <bb 5>;

<bb 4>:
    goto <bb 3>;

<bb 5>:
    # a_8 = PHI <pretmp.2_7(3)>
    return a_8;
```



## Copy Propagation after PRE

```
loop.c.092t.pre

<bb 2>:
    pretmp.2_7 = b_1(D) + c_2(D);

<bb 3>:
    a_3 = pretmp.2_7;
    if (a_3 <= n_4(D))
        goto <bb 5>;
    else goto <bb 6>;

<bb 5>:
    goto <bb 3>;

<bb 6>:
<bb 4>:
    # a_6 = PHI <a_3(6)>
    return a_6;
```

```
loop.c.097t.copyprop4

<bb 2>:
    pretmp.2_7 = b_1(D) + c_2(D);

<bb 3>:
    a_3 = pretmp.2_7;
    if (n_4(D) >= pretmp.2_7)
        goto <bb 4>;
    else
        goto <bb 5>;

<bb 4>:
    goto <bb 3>;

<bb 5>:
    # a_8 = PHI <pretmp.2_7(3)>
    a_6 = a_8;
    return a_8;
```



## Redundant $\phi$ Function Elimination and Copy Propagation

```
loop.c.098t.dceloop1

<bb 2>:
    pretmp.2_7 = b_1(D) + c_2(D);

<bb 3>:
    if (n_4(D) >= pretmp.2_7)
        goto <bb 4>;
    else
        goto <bb 5>;

<bb 4>:
    goto <bb 3>;

<bb 5>:
    # a_8 = PHI <pretmp.2_7(3)>
    return a_8;
```

```
loop.c.125t.phicprop2

<bb 2>:
    pretmp.2_7 = c_2(D) + b_1(D);
    if (n_4(D) >= pretmp.2_7)
        goto <bb 4>;
    else
        goto <bb 3>;

<bb 3>:
    return pretmp.2_7;

<bb 4>:
    goto <bb 4>;
```



## Final Assembly Program

```
loop.c.125t.phicprop2
<bb 2>:
  pretmp.2_7 = c_2(D) + b_1(D);
  if (n_4(D) >= pretmp.2_7)
    goto <bb 4>;
  else
    goto <bb 3>;
<bb 3>:
  return pretmp.2_7;
<bb 4>:
  goto <bb 4>;
```

```
loop.s
  movl 8(%esp), %eax
  addl 4(%esp), %eax
  cmpl %eax, 12(%esp)
  jge .L2
  rep
  ret
.L2:
.L3:
  jmp .L3
```

*Why infinite loop?*



Part 3

## Conclusions

## Infinite Loop in Example Program 2

```
int f(int b, int c, int n)
{ int a;

  do
  {
    a = b+c;
  }
  while (a <= n);

  return a;
}
```

The program does not terminate unless  $a > n$



## Conclusions

- GCC performs many machine independent optimizations
- The dumps of optimizations are easy to follow, particularly at the GIMPLE level
- It is easy to prepare interesting test cases and observe the effect of transformations
- One optimization often leads to another  
Hence GCC performs many optimizations repeatedly  
(eg. copy propagation, dead code elimination)

