

Enhancing Fine-grained parallelism

By -

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FINE-GRAINED PARALLELISM

- After Allen-Kennedy's codegen algo., what's next?
- Can we fine-grain the parallelism?
- Here we will look at some transformations that support it.

Loop Interchange

```
DO I=1,N
  DO J=1,M
S:    A(I, J+1) = A(I, J) + B
      ENDDO
    ENDDO
```

- The transformed code after loop interchange can be vectorised



Loop Interchange

Here we interchange the loop I and loop J.

```
DO I=1,N
  DO J=1,M
S:    A(I, J+1) = A(I, J) + B
      ENDDO
    ENDDO
```



```
DO J=1,M
  DO I=1,N
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      ENDDO
    ENDDO
```

- The transformed code after loop interchange can be vectorised



Loop Interchange

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DO I=1,N
  DO J=1,M
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ENDDO
```



```
DO J=1,M
  DO I=1,N
S:    A(I, J+1) = A(I, J) + B
      ENDDO
ENDDO
```



The transformed code after
loop interchange,
vectorised

```
DO J=1,M
S:  (1:N, J+1) = A(1:N, J) + B
ENDDO
```



Safety of Loop Interchange

Not all the loops can be
interchanged

```
DO I=1,M
  DO J=1,N
S:    A(I+1, J) = A(I, J+1) + B
      ENDDO
ENDDO
```

```
DO J=1,N
  DO I=1,M
S:    A(I+1, J) = A(I, J+1) + B
      ENDDO
ENDDO
```

Safety of Loop Interchange(cont.)

```
DO I=1,N
  DO J=1,M
    DO K=1,L
S:      A(I+1, J+1,K) = A(I, J,K) + A(I, J+1, K+1)
    ENDDO
  ENDDO
ENDDO
```

– SOURCE : $A(I+1, J+1,K)$
– SINK : $A(I, J,K)$

– D.V. : $<, <, =$

SOURCE : $A(I+1, J+1,K)$
SINK : $A(I, J+1,K+1)$

D.V. : $<, =, >$

Safety of Loop Interchange(cont.)

```
DO I=1,N
  DO J=1,N
    DO K=1,N
S :   A(I, J) = A(I, J) + B(I, K) + C(K, J)
      ENDDO
    ENDDO
  ENDDO
```

```
DO K=1,N
  DO I=1,N
    DO J=1,N
S:   A(I, J) = A(I, J) + B(I, K) + C
      (K, J)
      ENDDO
    ENDDO
  ENDDO
```


Safety of Loop Interchange(cont.)

```
DO I=1,N
  DO J=1,N
    DO K=1,L
S:      A(I, J) = A(I, J) + B(I, K) + C(K, J)
    ENDDO
  ENDDO
ENDDO
```

```
DO I=1,N
  FORALL (J=1,N)
S:      A(1:N, J) = A(1:N, J) + B(1:N, K) + C(K, J)
  END FORALL
ENDDO
```

Scalar Expansion

Example - Swapping of two vectors:

```
DO I =1, N
```

```
S1      T = A(I)
```

```
S2      A(I) = B(I)
```

```
S3      B(I) = T
```

```
ENDDO
```

Scalar Expansion

Code produced by scalar expansion :

```
DO I =1, N
S1      T$(I) = A(I)
S2      A(I) = B(I)
S3      B(I) = T$(I)
ENDDO
```

Vectorized code :

```
S1      T$(1:N) = A(1:N)
S2      A(1:N) = B(1:N)
S3      B(1:N) = T$(1:N)
```

Scalar Expansion

- Profitability of scalar expansion
- Deletable edges in the dependence graph
- Covering definition of a scalar



Scalar Expansion

- Edges that are deletable in the dependence graph by scalar expansion :
 - Backward carried antidependences
 - Forward carried output dependences
 - Loop independent antidependences into the covering definition
 - Loop carried true dependences from a covering definition
-
-

Scalar Renaming

Example :

```
    DO I = 1,100  
S1    T = A(I) + B(I)  
S2    C(I) = T + 2  
S3    T = B(I) + 3 * A(I)  
S4    B(I+1) = T - 4  
    ENDDO
```

Scalar Renaming

Example :

```
DO I = 1,100
S1    T = A(I) + B(I)
S2    C(I) = T + 2
S3    T = B(I) + 3 * A(I)
S4    B(I+1) = T - 4
      ENDDO
```

After scalar renaming :

```
DO I = 1,100
S1    T1 = A(I) + B(I)
S2    C(I) = T1 + 2
S3    T2 = B(I) + D(I)
S4    C(I+1) = T2 - 4
      ENDDO
```

Array Renaming

- Similar to Scalar Renaming.
- Idea is to remove loop independent anti-dependence and output dependence.
- Identify a define-use pair and rename it.

```
DO I = 1 , N
S1 : A[I] = A[I-1] + X
S2 : Y[I] = A[I] + Z
S3 : A[I] = B[I] + C
ENDDO
```



```
DO I = 1 , N
S1 : A$[I] = A[I-1]+X
S2 : Y[I] = A$[I] + Z
S3 : A[I] = B[I] + C
ENDDO
```



Vector code after array renaming :-

```
S3 : A(1:N) = B(1:N) + C
S1 : A$(1:N) = A(0:N-1) + X
S2 : Y(1:N) = A$(1:N) + Z
```


Index Set Splitting

- Dependence pattern in the iteration space.
- Idea is to split the loop based on the dependence.
- By splitting loop we are splitting the index of the array.

3 Methods of Index Set Splitting:-

- Threshold Analysis
 - Loop peeling
 - Section based splitting
-
-

Threshold Analysis

- Compute the threshold(dependence distance) for a reference pair.
- Breaks the loop into sizes smaller than the threshold.

Example for constant threshold.

```
DO I = 1, 20  
  A(I + 5) = A(I) + B  
ENDDO
```



```
DO I = 1, 20, 5  
  DO J = I, I + 4  
    A(J + 5) = A(J) + B  
  ENDDO  
ENDDO
```



Vector code generated :-

```
DO I = 1, 20, 5  
  A(I+5, I+9) = A(I:I+4) + B  
ENDDO
```



Threshold Analysis(cont)

Example for crossing threshold.

```
DO I = 1 , 100
```

```
    A[101 - I] = A[I] + B
```

```
ENDDO;
```

```
DO I = 1 , 100 , 50
```

```
    DO J = I , I + 49
```

```
        A[101 - J] = A[J] + B
```

```
    ENDDO
```

```
ENDDO;
```



Vector code generated :-

```
DO I = 1 , 100 , 50
```

```
    A(101-I:51-I) = A(I:I+49) + B
```

```
ENDDO
```

Loop Peeling

- Idea is to peel the loop or remove certain iterations outside the loop

Example which peels out
a single iteration

```
DO J = 1 , N  
  A(J) = A(J) + A(1)  
ENDDO
```



```
A(1) = A(1) + A(1)  
DO J = 2 , N  
  A(J) = A(J) + A(1)  
ENDDO
```



Vector Code generated :-
A(1) = A(1) + A(1)
A(2:N) = A(2:N) + A(1)



Loop Peeling(cont..)

Example where loop is split and loop carried dependency is converted into loop independent dependency.

```
DO I = 1 , N  
  A(I) = A(N/2) + B(I)  
ENDDO
```



```
M = N/2  
DO I = 1 , M  
  A(I) = A(N/2) + B(I)  
ENDDO  
DO I = M+1 , N  
  A(I) = A(N/2) + B(I)  
ENDDO
```



Section based splitting

- Variation of loop peeling where sections of loop involved in dependence are recognised.
- Loop is splitted to separate out the identified sections.

- Example :-

```
DO I = 1 , N
  DO J = 1 , N/2
    S1: B(J,I) = A(J,I) + C
  ENDDO

  DO J = 1 , N
    S2: A(J,I+1) = B(J,I) + D
  ENDDO
ENDDO
```

Section based splitting(cont)

```
DO I = 1 , N
  DO J = 1 , N/2
    S1: B(J,I) = A(J,I) + C
  ENDDO

  DO J = 1 , N/2
    S21: A(J,I+1) = B(J,I) + D
  ENDDO

  DO J = N/2+1 , N
    S22: A(J,I+1) = B(J,I) + D
  ENDDO
ENDDO
```

Here S22 is independent of S1 and S12.

Distributing the I-loop
we get :-

```
DO I = N/2+1 , N
  DO J = N/2+1 , N
    S22: A(J,I+1) = B(J,I) + D
  ENDDO
ENDDO
```

```
DO I = 1 , N
  DO J = 1 , N/2
    S1: B(J,I) = A(J,I) + C
  ENDDO
```

```
DO J = 1 , N/2
  S21: A(J,I+1) = B(J,I) + D
ENDDO
ENDDO
```

Reference

Chapter 5 of

Optimizing Compilers for modern architectures : a dependence-based approach.

By Ken Kennedy and John R. Allen.

Morgan Kaufmann Publishers Inc.,
San Francisco, CA, USA, 2002.
