

# An Efficient Data Dependence Analysis for Parallelizing Compilers

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# Agenda

- Background
- Basic Concepts
- Algorithm
- Examples
- Conclusion
- References

# Approaches in Dependence Testing

- Based on Numerical Methods, Inaccurate
  - Multiple Dimensions simultaneously, Time Consuming
  - $\lambda$  test, Efficient and Accurate

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# Numerical Methods

- Based on solving Diophantine Equations and the Bounds on real functions
- Data areas accessed by two array references are examined Dimension by Dimension
- Inaccurate

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# Example

$N = 50$

DO  $I = 1, N$

DO  $J = 2, N$

S1 :  $A[2 * I + 3 * J + N, 3 * I + J + N - 1] = \dots (r1)$

S2 :  $\dots = A[I - J + N + 1, 2 * I - J + N - 2] (r2)$

ENDO

ENDDO

- Let  $x_1 = I$  and  $x_2 = J$  for reference r1
- Let  $x_3 = I$  and  $x_4 = J$  for reference r2
- Diophantine Equations are

$$2x_1 + 3x_2 - x_3 + x_4 = 1 \dots \dots (1)$$

$$3x_1 + x_2 - 2x_3 + x_4 = -1 \dots \dots (2)$$

where  $1 \leq x_1, x_3 \leq 50, 2 \leq x_2, x_4 \leq 50$

## Example (Cont...)

- Solution by previous Numerical Methods :-
  - Each Dimension is treated seperately
  - Any equation has no solution within loop bounds, no dependence
  - If each equation has solution independently, dependence has to be assumed
  - $(x_1, x_2, x_3, x_4) = (1, 2, 9, 2)$  - solution to (1)
  - $(x_1, x_2, x_3, x_4) = (1, 2, 4, 2)$  - solution to (2)
- So we assume dependence exists

## Example (Cont...)

- Actual solution  $(1) \times 3 - (2) \times 2$
- Reduced Equation  $7x_2 + x_3 + x_4 = 5$
- No solution
- Previous Numerical Methods failed because of presence **coupled subscripts**

# Effect of *coupled subscripts* on determination of *dependence directions*

```
DO I = 1, 100
DO J = 1, 100
S1 :      A[I, J] = .....(3)
S2 :      A[J, I] = .....(4)
ENDO
ENDO
```

$$\Downarrow$$
$$i_1 = j_2 \dots \dots \dots (5)$$
$$j_1 = i_2 \dots \dots \dots (6)$$
$$1 \leq i_1, i_2, j_1, j_2 \leq 100 \dots \dots \dots (7)$$
$$i_1 = i_2, j_1 < j_2 \dots \dots \dots (8)$$

# Effect of *coupled subscripts* on determination of *dependence directions*

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$$i_1 = j_2 \dots \dots \dots (5)$$

$$j_1 = i_2 \dots \dots \dots (6)$$

$$1 \leq i_1, i_2, j_1, j_2 \leq 100 \dots \dots \dots (7)$$

$$i_1 = i_2, j_1 < j_2 \dots \dots \dots (8)$$

## Effect of *coupled subscripts* on determination of *dependence directions* (Cont...)

- Previous Methods treat each dimension separately
- (5), (7), (8) is considered, solution is  $i_1 = j_2 = 100$
- (6), (7), (8) is considered, solution is  $j_1 = i_2 = 1$
- Actually there is no solution, if both equations are considered simultaneously
- Previous Methods failed because of presence of *coupled subscripts*

# Notations used

1. Reference pair  $(r1, r2)$
2.  $r1$  is  $A(f_1(i_1, i_2, \dots, i_{l_1}), f_2(i_1, i_2, \dots, i_{l_1}), \dots, f_m(i_1, i_2, \dots, i_{l_1}))$
3.  $r2$  is  $A(g_1(j_1, j_2, \dots, j_{l_2}), g_2(j_1, j_2, \dots, j_{l_2}), \dots, g_m(j_1, j_2, \dots, j_{l_2}))$

# Basic Concepts

$$f_1(i_1, i_2, \dots, i_{l_1}) = g_1(j_1, j_2, \dots, j_{l_2})$$

$$f_2(i_1, i_2, \dots, i_{l_1}) = g_2(j_1, j_2, \dots, j_{l_2})$$

$$\vdots$$

$$f_m(i_1, i_2, \dots, i_{l_1}) = g_m(j_1, j_2, \dots, j_{l_2})$$

$$a_1^{(1)} v^{(1)} + a_1^{(2)} v^{(2)} + \dots + a_1^{(n)} v^{(n)} + c_1 = 0$$

$$a_2^{(1)} v^{(1)} + a_2^{(2)} v^{(2)} + \dots + a_2^{(n)} v^{(n)} + c_2 = 0$$

$$\vdots$$

$$a_m^{(1)} v^{(1)} + a_m^{(2)} v^{(2)} + \dots + a_m^{(n)} v^{(n)} + c_m = 0$$



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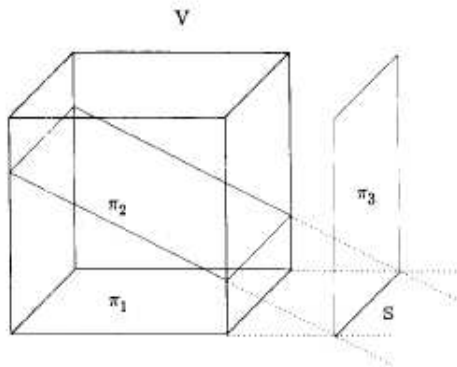
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$$a_m^{(1)} v^{(1)} + a_m^{(2)} v^{(2)} + \dots + a_m^{(n)} v^{(n)} + c_m = 0$$

# Geometrical illustrations



# Case for Two-dimensional array reference

Our equations are:  $f_1 = 0$  and  $f_2 = 0$

where  $f_i = a_i^{(1)}v^{(1)} + a_i^{(2)}v^{(2)} + \dots + a_i^{(n)}v^{(n)} + c_i$

Linear combination is:  $f_{\lambda_1, \lambda_2} = \lambda_1 f_1 + \lambda_2 f_2$

in expanded form

$$f_{\lambda_1, \lambda_2} = (\lambda_1 a_1^{(1)} + \lambda_2 a_2^{(1)})v^{(1)} + (\lambda_1 a_1^{(2)} + \lambda_2 a_2^{(2)})v^{(2)} + \dots + (\lambda_1 a_1^{(n)} + \lambda_2 a_2^{(n)})v^{(n)}$$

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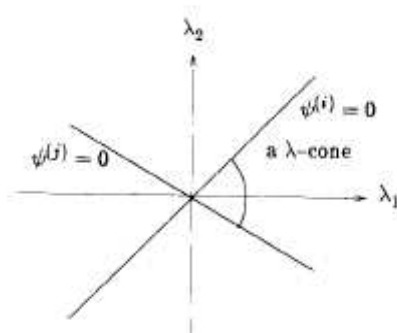
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$$f_{\lambda_1, \lambda_2} = (\lambda_1 a_1^{(1)} + \lambda_2 a_2^{(1)})v^{(1)} + (\lambda_1 a_1^{(2)} + \lambda_2 a_2^{(2)})v^{(2)} + \dots + (\lambda_1 a_1^{(n)} + \lambda_2 a_2^{(n)})v^{(n)}$$

# Definition

$$\psi^{(i)} = \lambda_1 a_1^{(i)} + \lambda_2 a_2^{(i)}$$

$\phi^{(i,j)} = \psi^{(i)} + \psi^{(j)}$  where  $v^{(i)}$  and  $v^{(j)}$  are related by a dependance direction



# Canonical Solution

$$a\lambda_1 + b\lambda_2 = 0$$

$$(\lambda_1, \lambda_2) = (1, 0), \text{ if } a = 0$$

$$(\lambda_1, \lambda_2) = (0, 1), \text{ if } b = 0$$

$$(\lambda_1, \lambda_2) = (b, -a), \text{ if } a, b \neq 0 \text{ and } b > 0$$

$$(\lambda_1, \lambda_2) = (-b, a), \text{ if } a, b \neq 0 \text{ and } b < 0$$

$\Lambda$  Set : Set of all canonical solutions to the  $\psi$  equations and  $\phi$  equations.

Every *canonical solution* determines a  $\lambda$  plane

Thorem :  $S$  intersects  $V$  if and only if every  $\lambda$  plane intersects  $V$



# Algorithm

- Determine the  $\psi$  equations and  $\phi$  equations
- Determine the  $\Lambda$  set
- Each element of  $\Lambda$  set determines a  $\lambda$  plane
- Each  $\lambda$  plane is tested to see if intersects  $V$  by checking its max and min values
- If any one of the  $\lambda$  planes does not intersect  $V$  we stop

$\lambda$  - test

$$f_{\lambda_1, \lambda_2} = (2\lambda_1 + 3\lambda_2)x_1 + (3\lambda_1 + \lambda_2)x_2 \\ + (-\lambda_1 - 2\lambda_2)x_3 + (\lambda_1 + \lambda_2)x_4 = 0$$

$\psi$  Equations :

$$2\lambda_1 + 3\lambda_2 = 0$$

$$3\lambda_1 + \lambda_2 = 0$$

$$-\lambda_1 - 2\lambda_2 = 0$$

$$\lambda_1 + \lambda_2 = 0$$

$\lambda$  - test

$$\Lambda = (3, -2), (1, -3), (2, -1), (1, -1)$$

Consider the loop bounds:

$$1 \leq x_1, x_3 \leq 50, \quad 2 \leq x_2, x_4 \leq 50$$

Here, (3, -2) shows the absence of data dependence and hence we stop and do not consider the next  $\lambda$  planes

$\lambda$  - test

$$i_1 = j_2$$

$$j_1 = i_2$$

$$1 \leq i_1, i_2, j_1, j_2 \leq 100$$

$$i_1 = i_2, j_1 < j_2$$

$$f_{\lambda_1, \lambda_2} = (\lambda_1 + 0\lambda_2)i_1 + (0\lambda_1 + \lambda_2)j_1 \\ + (-\lambda_1 + 0\lambda_2)j_2 + (0\lambda_1 - \lambda_2)i_2 = 0$$

$\psi$  Equations :

$$\lambda_1 + 0\lambda_2 = 0$$

$$0\lambda_1 + \lambda_2 = 0$$

$$-\lambda_1 + 0\lambda_2 = 0$$

$$0\lambda_1 - \lambda_2 = 0$$

$\lambda$  - test

$\phi$  Equations :

$$\lambda_1 - \lambda_2 = 0$$

$$-\lambda_1 + \lambda_2 = 0$$

$$\Lambda = (1, 0), (0, 1), (1, 1)$$

Consider the loop bounds:

$$1 \leq x_1, x_3 \leq 50, 2 \leq x_2, x_4 \leq 50$$

Here, (1,1) shows the absence of data dependence and hence we stop

# Conclusion

Discussed  $\lambda$  test and examined that it is better than previous Numerical methods

## References

- [1] An Efficient Data Dependence Analysis for Parallelizing Compilers, Zhiyuan Li and Pen-Chung Yew and Chuan-Qi Zhu  
IEEE Transactions on Parallel and Distributed Systems, 1990