PAGES 216 TO 231 OF http://www.cse.iitb.ac.in/~ cs709/notes/BasicsOfConvexOptimiz ation.pdf, interspersed with pages between 239 and 253 and summary of material thereafter, which extend univariate concepts to generic spaces

## Maximum and Minimum values of univariate functions

Let f be a function with domain  $\mathcal{D}$ . Then f has an *absolute maximum* (or global maximum) value at point  $c \in \mathcal{D}$  if

 $f(x) \le f(c), \ \forall x \in \mathcal{D}$ 

and an *absolute minimum* (or global minimum) value at  $c \in \mathcal{D}$  if

 $f(x) \ge f(c), \ \forall x \in \mathcal{D}$ 

If there is an open interval  $\mathcal{I}$  containing c in which  $f(c) \geq f(x)$ ,  $\forall x \in \mathcal{I}$ , then we say that f(c) is a *local maximum value* of f. On the other hand, ifthere is an open interval  $\mathcal{I}$  containing c in which  $f(c) \leq f(x)$ ,  $\forall x \in \mathcal{I}$ , then we say that f(c) is a *local minimum value* of f. If f(c) is either a local maximum or local minimum value of f in an open interval  $\mathcal{I}$  with  $c \in \mathcal{I}$ , the f(c) is called a *local extreme value* of f.

Theorem 39 If f(c) is a local extreme value and if f is differentiable at x = c, then f'(c) = 0.  $\rightarrow |f a|| p ds of f exist at <math>x = c \oplus D \subseteq R^{n}$ 4 If f(c) is local extreme  $\gamma f(c) = 0$ 

**Theorem 40** A continuous function f(x) on a closed and bounded interval [a,b] attains a minimum value f(c) for some  $c \in [a,b]$  and a maximum value f(d) for some  $d \in [a,b]$ . That is, a continuous function on a closed, bounded interval attains a minimum and a maximum value.

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Note: [a, ∞) is closed bat NOT bounded So both conditions are needed

## FOR Rn

**Theorem 60** If  $f(\mathbf{x})$  defined on a domain  $\mathcal{D} \subseteq \Re^n$  has a local maximum or minimum at  $\mathbf{x}^*$  and if the first-order partial derivatives exist at  $\mathbf{x}^*$ , then  $f_{x_i}(\mathbf{x}^*) = 0$  for all  $1 \le i \le n$ .

**Definition 27 [Critical point]:** A point  $\mathbf{x}^*$  is called a critical point of a function  $f(\mathbf{x})$  defined on  $\mathcal{D} \subseteq \Re^n$  if

- 1. If  $f_{x_i}(\mathbf{x}^*) = 0$ , for  $1 \le i \le n$ .
- 2. OR  $f_{x_i}(\mathbf{x}^*)$  fails to exist for any  $1 \leq i \leq n$ .

A procedure for computing all critical points of a function f is:

- 1. Compute  $f_{x_i}$  for  $1 \le i \le n$ .
- 2. Determine if there are any points where any one of  $f_{x_i}$  fails to exist. Add such points (if any) to the list of critical points.
- 3. Solve the system of equations  $f_{x_i} = 0$  simultaneously. Add the solution points to the list of saddle points.

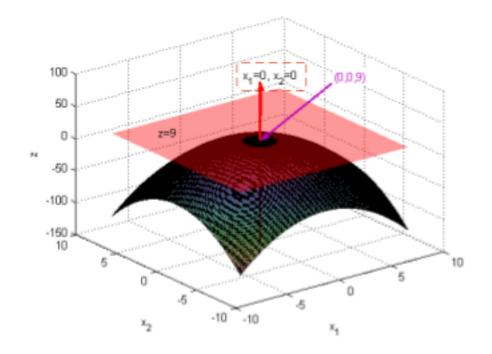
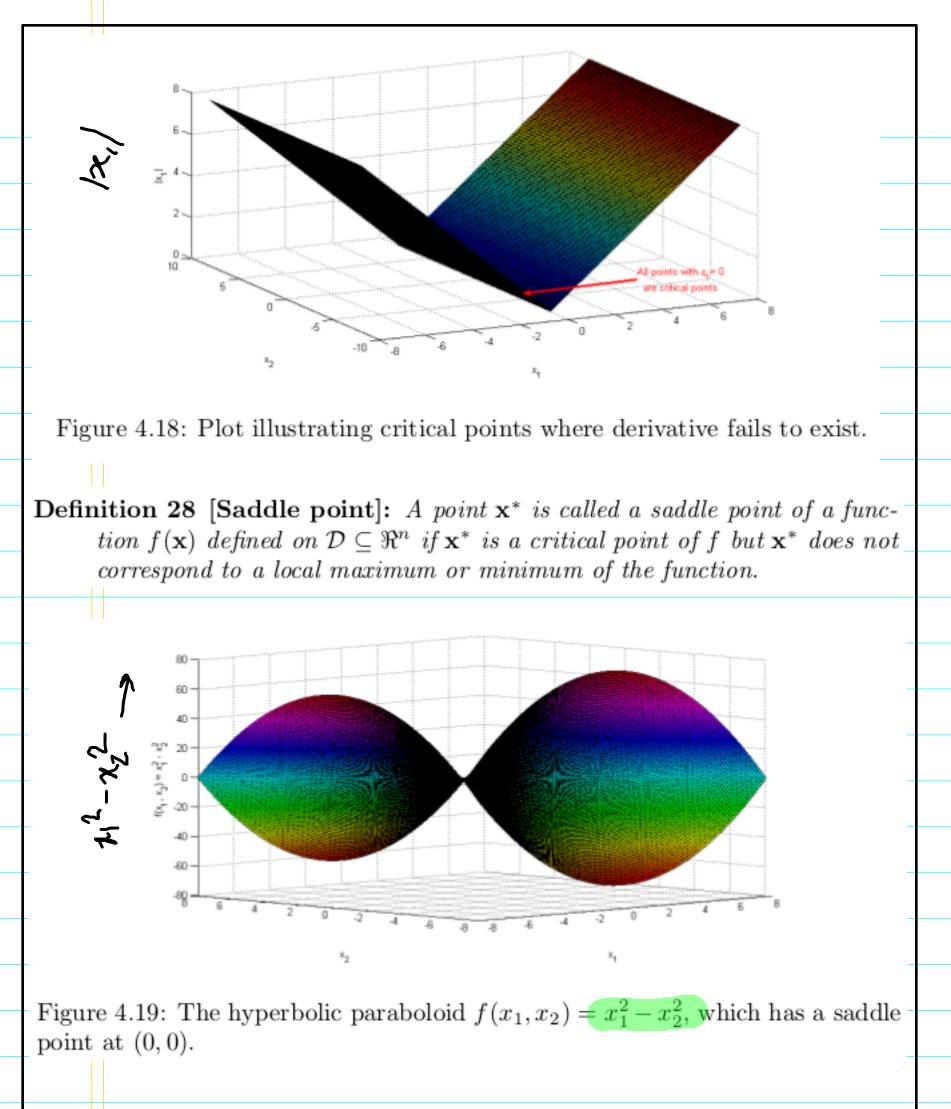


Figure 4.17: The paraboloid  $f(x_1, x_2) = 9 - x_1^2 - x_2^2$  attains its maximum at (0,0). The tanget plane to the surface at (0,0, f(0,0)) is also shown, and so is



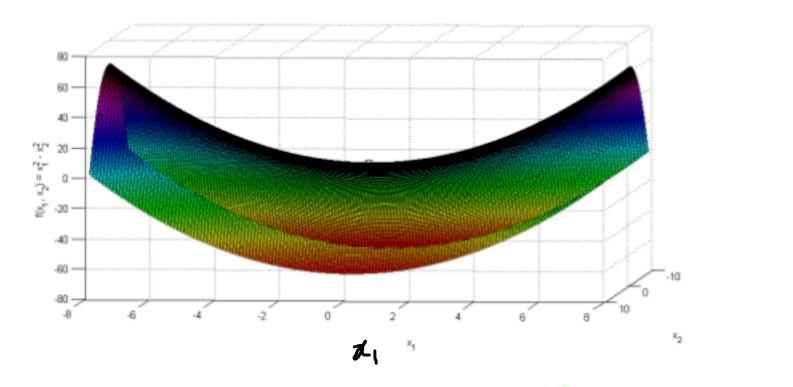


Figure 4.20: The hyperbolic paraboloid  $f(x_1, x_2) = x_1^2 - x_2^2$ , when viewed from the  $x_1$  axis is concave up.

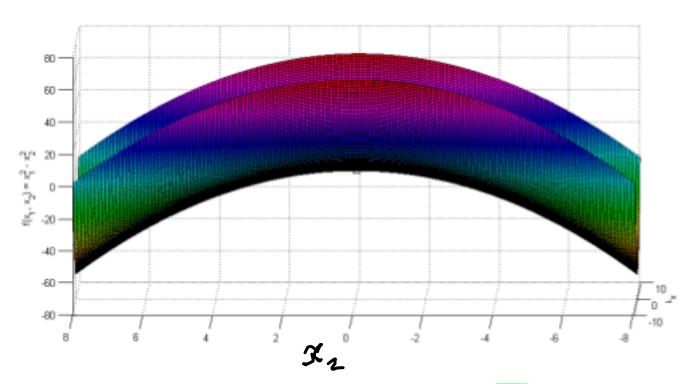
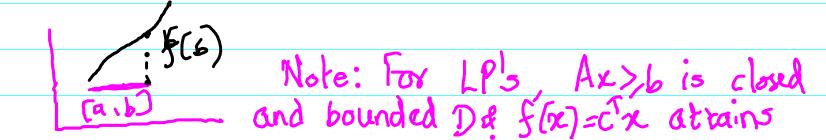


Figure 4.21: The hyperbolic paraboloid  $f(x_1, x_2) = x_1^2 - x_2^2$ , when viewed from the  $x_2$  axis is concave down.



**Theorem 41** A continuous function f(x) on a closed and bounded interval [a, b]attains a minimum value f(c) for some  $c \in [a, b]$  and a maximum value f(d)for some  $d \in [a, b]$ . If a < c < b and f'(c) exists, then f'(c) = 0. If a < d < band f'(d) exists, then f'(d) = 0. If f = 0 is closed f bounded f = 1 is closed f = 0. If f = 0 is closed f = 0. If f = 0 is closed f = 0. Theorem 42 If f is continuous on [a, b] and differentiable at all  $x \in (a, b)$  and if f(a) = f(b), then f'(c) = 0 for some  $c \in (a, b)$ .

Figure 4.1 illustrates Rolle's theorem with an example function  $f(x) = 9-x^2$ on the interval [-3, +3].

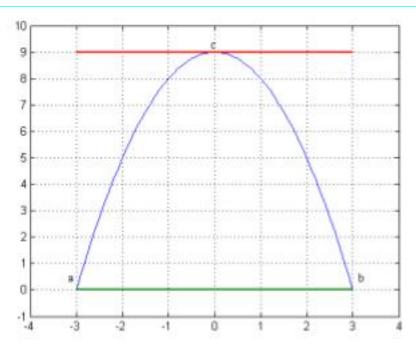


Figure 4.1: Illustration of Rolle's theorem with  $f(x) = 9 - x^2$  on the interval [-3, +3]. We see that f'(0) = 0.

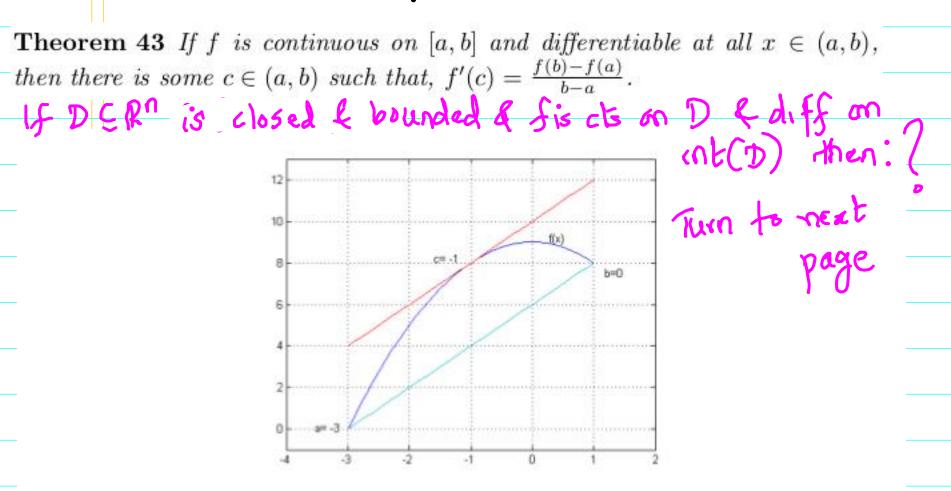


Figure 4.2: Illustration of mean value theorem with  $f(x) = 9 - x^2$  on the interval [-3, 1]. We see that  $f'(-1) = \frac{f(1) - f(-3)}{4}$ .

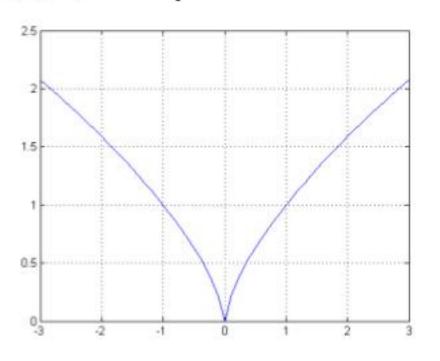


Figure 4.4: The mean value theorem can be violated if f(x) is not differentiable at even a single point of the interval. Illustration on  $f(x) = x^{2/3}$  with the

The mean value theorem in one variable generalizes to several variables by applying the theorem in one variable via parametrization. Let G be an open subset of  $\mathbf{R}^n$ , and let  $f: G \to \mathbf{R}$  be a differentiable function. Fix points  $x, y \in G$  such that the interval x y lies in G, and define g(t) = f((1 - t)x + ty). Since g is a differentiable function in one variable, the mean value theorem gives:

$$g(1) - g(0) = g'(c)$$

for some c between 0 and 1. But since g(1) = f(y) and g(0) = f(x), computing g'(c) explicitly we have:

$$f(y) - f(x) = \nabla f((1-c)x + cy) \cdot (y - x)$$
Convexity of the domain is fundamental
ance  $y \in C[0, \int], \frac{\chi(1-t) + ty \in Ponies}{1 + ty \in Ponies}$ 
That is, we taguise convexity if
set in some sense

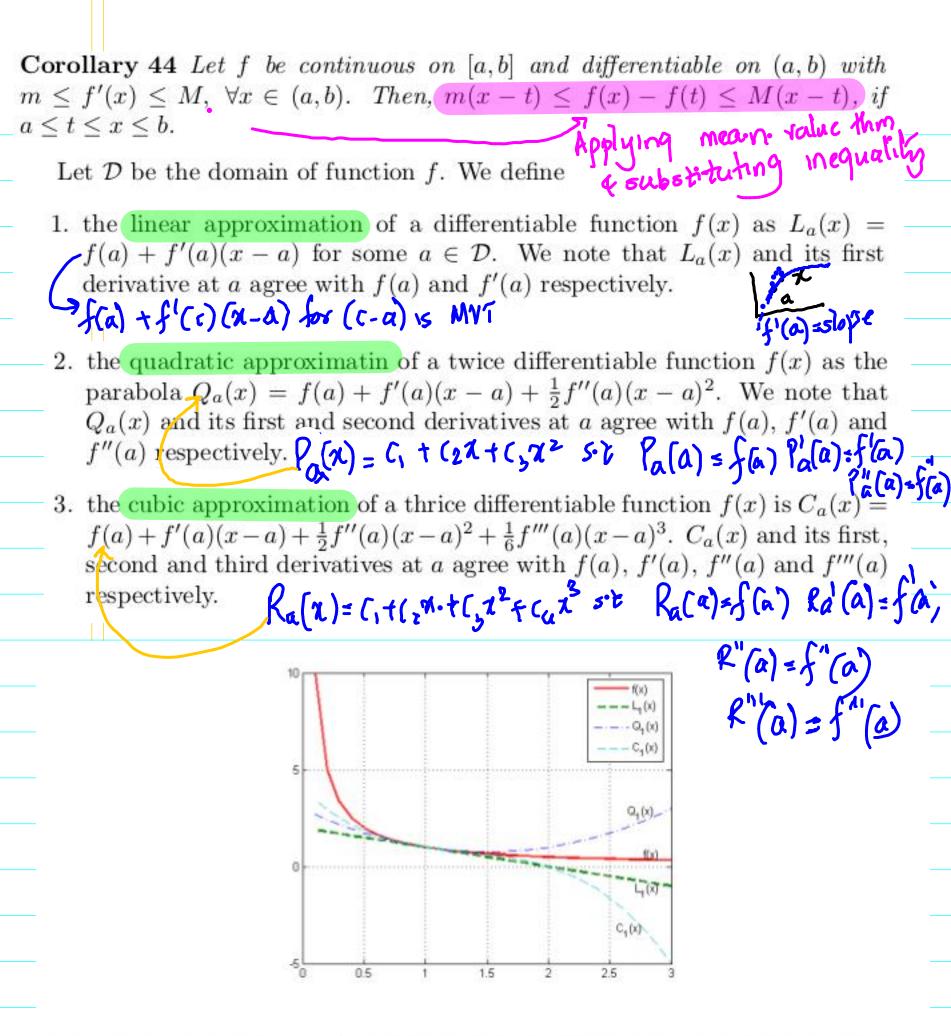


Figure 4.3: Plot of  $f(x) = \frac{1}{x}$ , and its linear, quadratic and cubic approximations.

**Can be thought if as general** all order **Theorem 45** The Taylor's theorem states that if f and its first n aerivatives f(f)  $f', f'', \ldots, f^{(n)}$  are continuous on the closed interval [a, b], and differentiable on (a, b), then there exists a number  $c \in (a, b)$  such that

$$f(b) = f(a) + f'(a)(b-a) + \frac{1}{2!}f''(a)(b-a)^2 + \dots + \frac{1}{n!}f^{(n)}(a)(b-a)^n + \frac{1}{(n+1)!}f^{(n+1)}(c)(b-a)$$

$$MVT is operiod Cose$$

$$MVT : \exists c \in (a, b) \ s \ f(b) = f(a) + f'(c)(b-a) \ ho \ c \ in \ he$$

$$f_{0} \ prove use \ MVT \ successively \ on \ f(\cdot), f'(\cdot), \dots f^{(n)}(\cdot) \ approximations$$

$$Consider the function \ \phi(t) = f(x + th) \ considered \ in \ theorem \ 71, \ defined \ on \ the \ domain \ \mathcal{D}_{\phi} = [0, 1].$$
Using the chain rule,
$$\phi'(t) = \sum_{i=1}^n f_{x_i}(x + th) \frac{dx_i}{dt} = h^T \cdot \nabla f(x + th)$$
Since f has partial and mixed partial derivatives,  $\phi'$  is a differentiable function of t on  $\mathcal{D}_{\phi}$  and
$$\phi''(t) = h^T \nabla^2 f(x + th)h$$
Since  $\phi$  and  $\phi'$  are continous on  $\mathcal{D}_{\phi}$  and  $\phi'$  is differentiable on  $int(\mathcal{D}_{\phi})$ , we can make use of the Taylor's theorem (45) with  $n = 3$  to obtain:
$$\phi(t) = \phi(0) + t \cdot \phi'(0) + t^2 \cdot \frac{1}{2} \phi''(0) + O(t^3)$$
Writing this equation in terms of f gives
$$f(x + th) = f(x) + th^T \nabla f(x) + t^2 \frac{1}{2}h^T \nabla^2 f(x)h + O(t^3)$$

$$f(x + th) = f(x) + th^T \nabla f(x) + t^2 \frac{1}{2}h^T \nabla^2 f(x)h + O(t^3)$$

We discussed in class, derivation of the second order Taylor expression. We also discussed that the matrix  $\nabla^2 f$ of mixed partial derivatives is symmetric if f has continuous mixed partial derivatives

We will introduce some definitions at this point:

- A function f is said to be *increasing* on an interval  $\mathcal{I}$  in its domain  $\mathcal{D}$  if f(t) < f(x) whenever t < x.
- The function f is said to be *decreasing* on an interval  $\mathcal{I} \in \mathcal{D}$  if f(t) > f(x) whenever t < x.

These definitions help us derive the following theorem: