Feature Induction in Machine Learning

Ganesh Ramakrishnan

Collaboration: J. Saketha Nath, Pratik J., Naveen Nair and Amrita Saha.

October. 21, 2012



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Efficient Feature Induction

- Information Extraction and Disambiguation (in the enterprise domain)
- Search over Entities and Relationships (in the enterprise domain)

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Outline



- 2 Feature Classes
- 3 Problem Definition
- 4 Efficiently Discovering Conjuctive Features
- 5 Conjuctive Features in Sequence Labeling
- 6 Efficiently Inducing Disjunctive Features
- 7 Are Richer Classes of Features More Useful?



Introduction

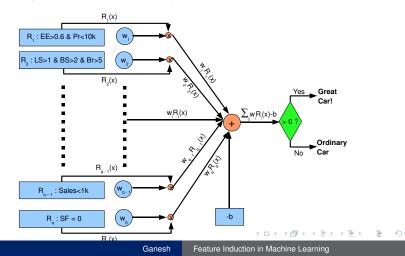
Ganesh Feature Induction in Machine Learning

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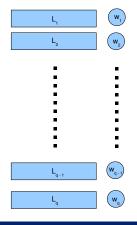
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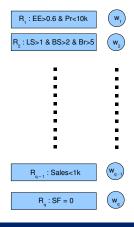
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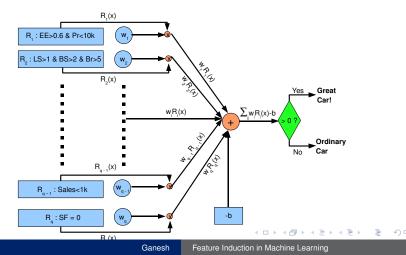


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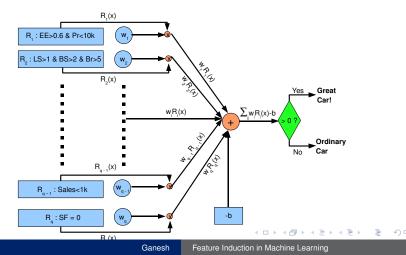


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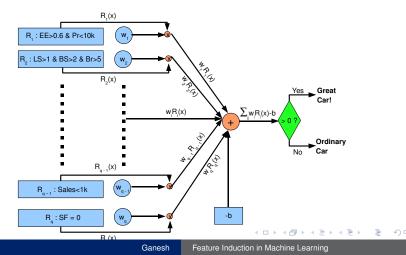
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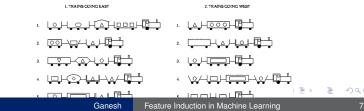
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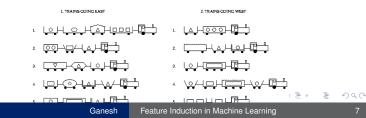
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- Simple Disjunctive features (under review)
 - Eg. Rules Like PositiveSentiment ← exquisite ∨ elegant (Sentiment Analysis)
- Features in the more general language of First order logic [MLJ2009, ILP2012a, EMNLP2012, ILP2012b]
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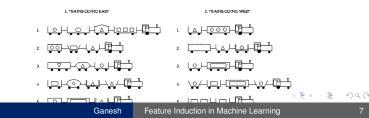
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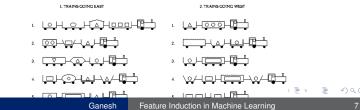
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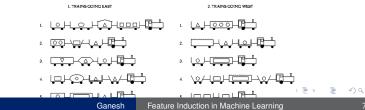
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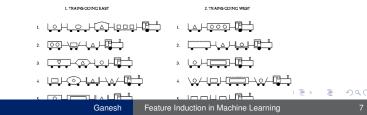
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Problem Definition

Desired Features

Highly interpretable hypothesis

- Small set of features/rules i.e., low g
- Simple features e.g., short conjunctive propositions

Better generalization than conventional rule learners

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Input:

Training Set: 𝒴={(x¹,y¹),...,(x^m,y^m)}, xⁱ∈ℝⁿ and yⁱ∈𝒞^r
 𝒞 is set of class labels. For binary: 𝒞 ∈ {−1,1}
 If r > 1, we are dealing with a sequence prediction problem
 Initially y_i ∈ {−1,1}. That is, 𝒞 ∈ {−1,1} and r = 1.

 Basic propositions regarding input features (say, p in number)

> Nominal e.g., $x_i = a$ and $x_i \neq a$ Numeric e.g., $x_i \ge b$ and $x_i \le b$

Goal:

Input:

• Training Set: $\mathscr{D} = \left\{ (\mathbf{x}^1, \mathbf{y}^1), ..., (\mathbf{x}^m, \mathbf{y}^m) \right\}, \mathbf{x}^i \in \mathbb{R}^n \text{ and } \mathbf{y}^i \in \mathscr{C}^r$

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Few in number

Short conjunctions

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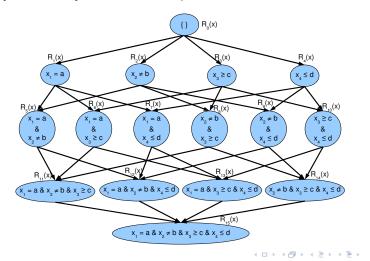
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Compute corresponding woights (m. h)

Problem Definition

Challenge:

Extremely large search space over features! Atleast $O(2^n)$ (conjunctive/disjunctive features)



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Optimal search for rules over all conjunctions

Regularized loss minimization

- Convex formulation
- Discovers compact ruleset (small set with short rules)

Technical Contribution:

Efficient mirror-descent based active set method

Key Structure Exploited

Sub-lattices with long features are discouraged.

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• Decision function¹: sign $(\sum_{v \in \mathscr{V}} w_v R_v(\mathbf{x}) - b)$

*l*₁ regularizer to force many *w_v* to zero

regularized formulation:

$$\min_{\mathbf{w}, b} \frac{1}{2} \left(\sum_{\mathbf{v} \in \mathcal{V}} |w_{\mathbf{v}}| \right)^2 + C \sum_{i=1}^m L \left(y^i, \sum_{\mathbf{v} \in \mathcal{V}} w_{\mathbf{v}} R_{\mathbf{v}}(\mathbf{x}^i) - b \right)$$

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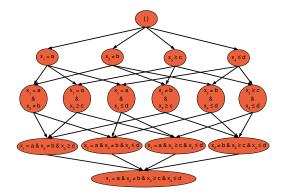


- Decision function¹: sign $(\sum_{v \in \mathscr{V}} w_v R_v(\mathbf{x}) b)$
- l_1 regularizer to force many w_v to zero

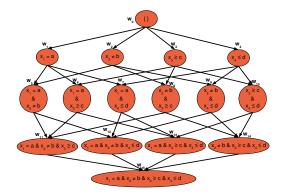
l_1 regularized formulation:

$$\min_{\mathbf{w},b} \frac{1}{2} \left(\sum_{\nu \in \mathscr{V}} |w_{\nu}| \right)^{2} + C \sum_{i=1}^{m} L \left(y^{i}, \sum_{\nu \in \mathscr{V}} w_{\nu} R_{\nu}(\mathbf{x}^{i}) - b \right)$$

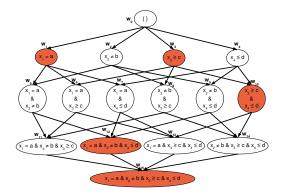
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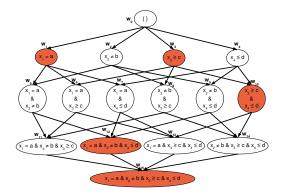
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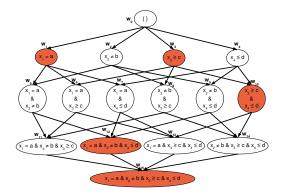
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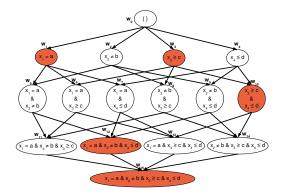
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An Improved Formulation

Key Idea:

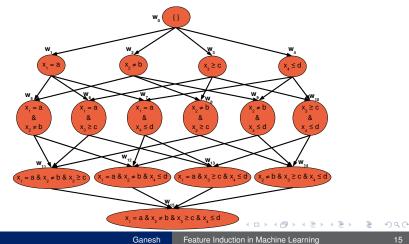
Block l_1 regularizer discourages long rules: $(\sum_{v \in \mathscr{V}} \|\mathbf{w}_{D(v)}\|_2)^2$

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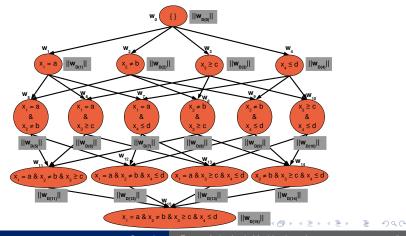
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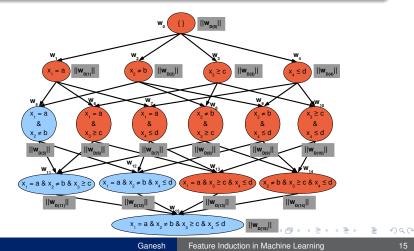
Block l_1 regularizer discourages long rules: $(\sum_{v \in \mathscr{V}} \|\mathbf{w}_{D(v)}\|_2)^2$



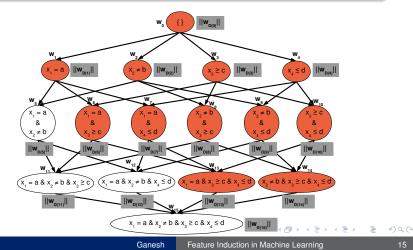
Features An Improved Formulation

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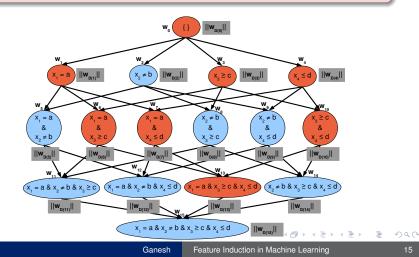
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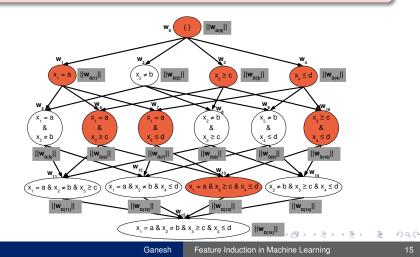
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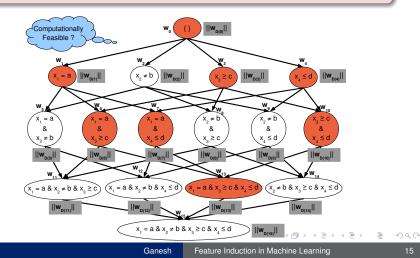
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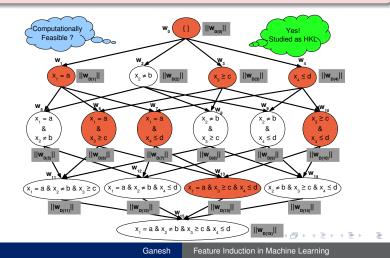


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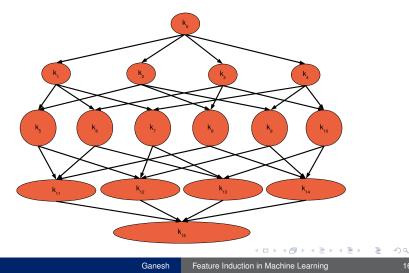
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Ganesh Feature Induction in Machine Learning

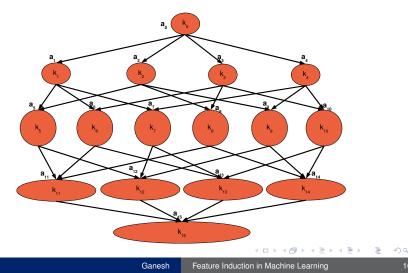
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- Kernels arranged on DAG (lattice) are given
- Optimal combination of kernels (Multiple Kernel Learning)

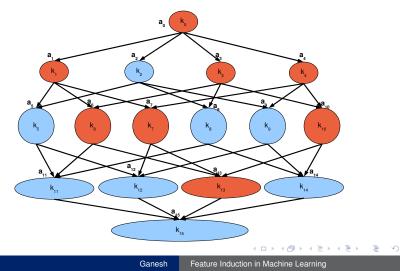
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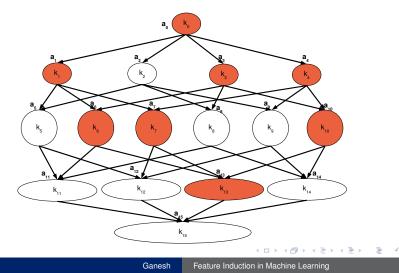
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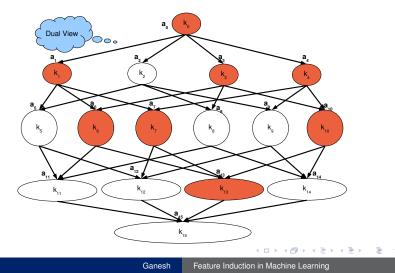
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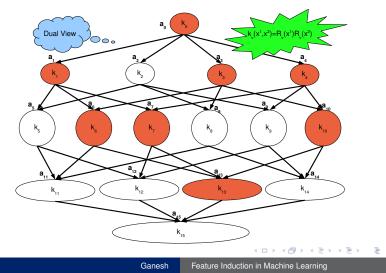
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HKL — Key Result

Active Set Algorithm:

- Complexity: Polynomial in number of selected kernels
- Condition: kernels are summable in *linear* time over a sub-lattice

Our case:

Kernels indeed easily summable

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 - E.g., $1 + R_1 + R_2 + R_1R_2 = (1 + R_1)(1 + R_2)$
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Dataset	RuleFit	SLI	ENDER	HKL
TIC-TAC-TOE	0.652±0.068 (40, 2.51)	0.747±0.026 (39, 2.35)	0.633±0.011 (111,2.46)	0.889±0.029 (129,1.85)
BALANCE	0.835±0.034 (17, 2.18)	0.856±0.027 (25, 1.88)	0.827±0.013 (64, 1.99)	0.893±0.027 (85, 1.65)
HABERMAN	0.512±0.072 (0.1.68)	0.565±0.066 (0.1.14)	0.424±0.000 (18, 1.87)	0.594 ±0.056 (32, 1.27)
CAR	0.913±0.033 (34, 3.12)	0.895±0.024 (141, 2.27)	0.755±0.028 (80, 1.85)	$\begin{array}{c} \textbf{0.943} \pm 0.024 \\ \textbf{(37, 1.78)} \end{array}$
BLOOD TRANS.	0.549±0.092 (18, 1.99)	$\begin{array}{c} 0.559 \pm 0.100 \\ (0, \ \textbf{1.07}) \end{array}$	0.489±0.054 (58, 1.5)	0.594 ±0.009 (242, 1.64)
CMC	0.632±0.013 (00,2.41)	0.601±0.041 (13, 2.13)	0.644±0.026 (*4, 2.65)	$\begin{array}{c} \textbf{0.656} \pm 0.014 \\ \textbf{(127, 1.96)} \end{array}$

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HABERMAN	0.512±0.072 (6, 1.68)	0.565±0.066 (8, 1.14)	0.424±0.000 (18, 1.87)	0.594 ±0.056 (32, 1.27)
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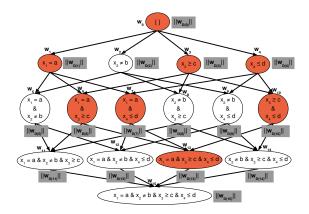
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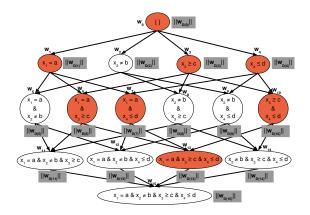
HKL — Introspection



- Node selected only if all its ancesters are!
- *l*₁ promotes sparsity.
- l_2 promotes non-sparsity.

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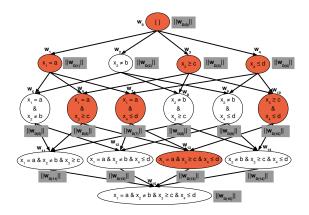
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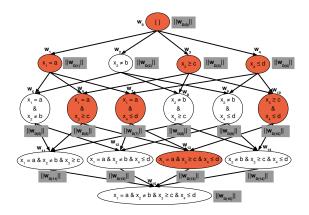
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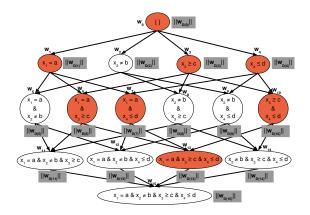
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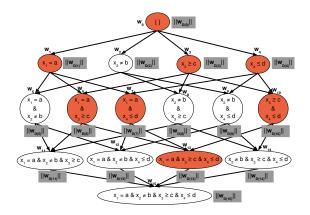
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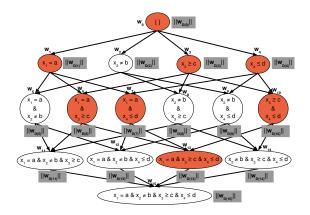
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Proposed Formulation

Generalized HKL

$$\min_{\mathbf{w},b} \frac{1}{2} \left(\sum_{\nu \in \mathscr{V}} d_{\nu} \| \mathbf{w}_{D(\nu)} \|_{\rho} \right)^2 + C \sum_{i=1}^m L \left(y^i, \sum_{\nu \in \mathscr{V}} w_{\nu} R_{\nu}(\mathbf{x}^i) - b \right)$$

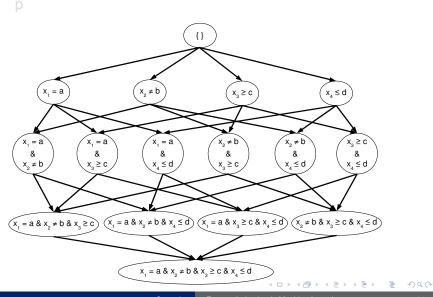
where $1 < \rho \leq 2$.

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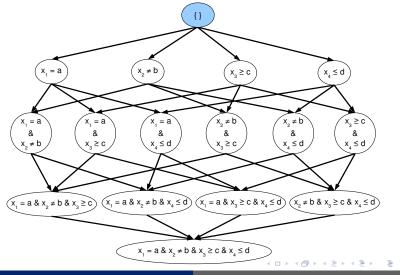
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Active Set Method



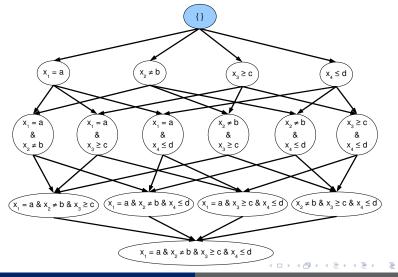
Active Set Method

Initialize active set with root node ($\mathcal{W} = \{0\}$).p



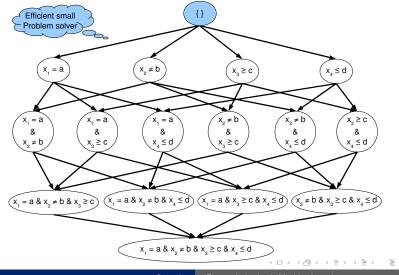
Active Set Method

Solve small problem



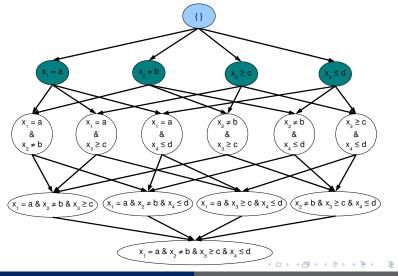
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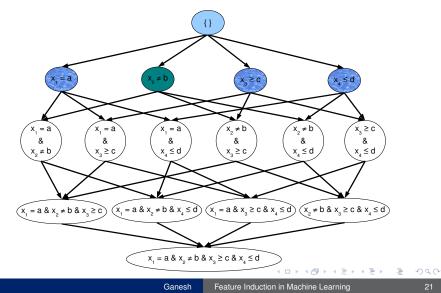
Active Set Method

Identify potential active set entries (i.e., $sources(\mathscr{W}^c)$)



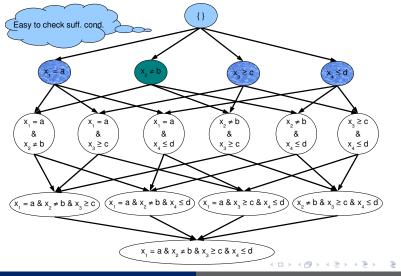
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Among them, optimality condition violators



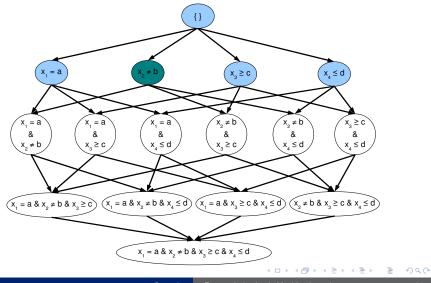
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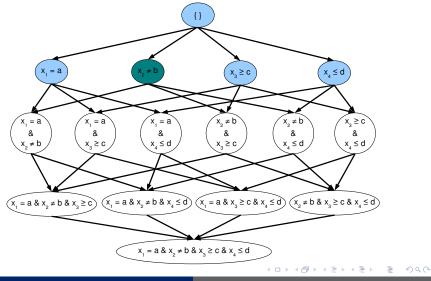
Active Set Method

Append them to active set ($\mathscr{W}=\{0,1,3,4\}$). (repeat until suff. cond. satisfied)



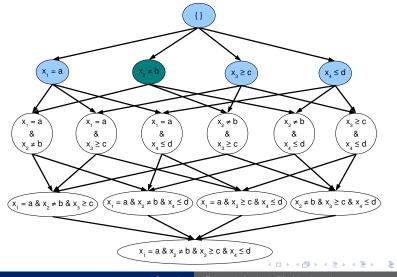
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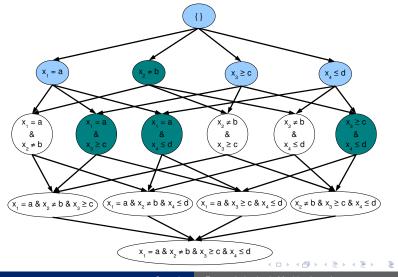
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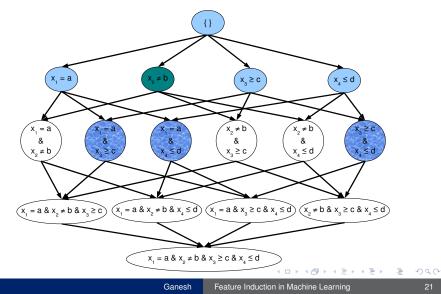
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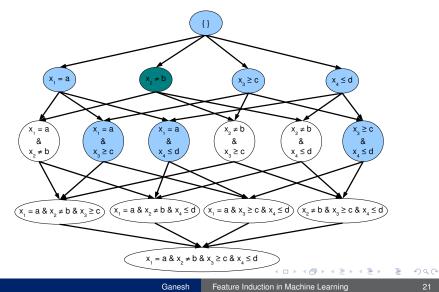
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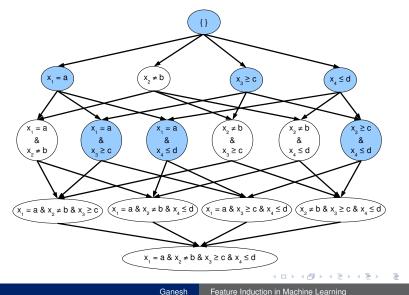
Active Set Method

Append them to active set ($\mathcal{W} = \{0, 1, 3, 4, 6, 7, 10\}$)



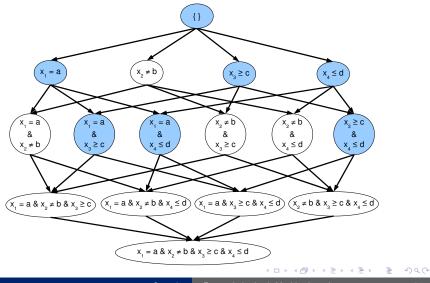
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Final active set: $\mathscr{W} = \{0, 1, 3, 4, 6, 7, 10\}$ (Complexity: Polynomial in active set size)



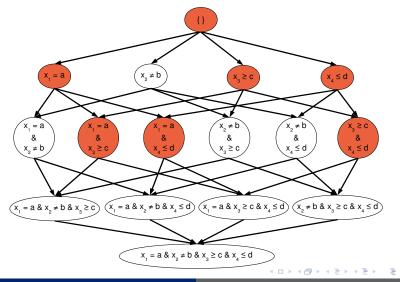
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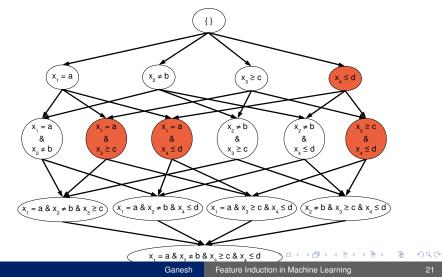
Active Set Method

Solution with HKL



Active Set Method

Key difference from HKL: Node selected without its ancestor!



Key Technical Result

Theorem

A highly specialized partial dual of generalized HKL is:

 $egin{array}{lll} \min_{m{\eta}\in^{|\mathscr{V}|}} & g(m{\eta}) \ {f s.t.} & m{\eta}\geq 0, \ \sum_{v\in\mathscr{V}}m{\eta}_v=1 \end{array}$

where $g(\eta)$ is the optimal objective value of the following convex problem:

 $\max_{\alpha \in {}^{m}} \sum_{i=1}^{m} \alpha_{i} - \frac{1}{2} \left(\sum_{v \in \mathscr{V}} \zeta_{v}(\eta) \left(\alpha^{\top} \mathbf{K}_{v} \alpha \right) \right)^{\perp} \text{ s.t. } 0 \leq \alpha_{i} \leq C, \sum_{i=1}^{m} \alpha_{i} y^{i} = 0.$ where $\zeta_{v}(\eta) = \left(\sum_{u \in A(v)} d_{u}^{\rho} \eta_{u}^{1-\rho} \right)^{\frac{1}{1-\rho}}, = \frac{\rho}{2(\rho-1)} \text{ and } \mathbf{K}_{v} \text{ is matrix}$ with entries: $y^{i} y^{j} k_{v}(\mathbf{x}^{i}, \mathbf{x}^{j}).$

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$$egin{array}{ll} \min_{oldsymbol{\eta}\in |^{|\mathcal{V}|}} & g(oldsymbol{\eta}) \ {f s.t.} & oldsymbol{\eta}\geq 0, \ \sum_{v\in \mathscr{V}}oldsymbol{\eta}_v=1 \end{array}$$

where $g(\eta)$ is the optimal objective value of the following convex problem:

$$\max_{\alpha \in {}^{m}} \sum_{i=1}^{m} \alpha_{i} - \frac{1}{2} \left(\sum_{v \in \mathscr{V}} \zeta_{v}(\eta) \left(\alpha^{\top} \mathbf{K}_{v} \alpha \right) \right)^{\perp} \text{ s.t. } 0 \le \alpha_{i} \le C, \sum_{i=1}^{m} \alpha_{i} y^{i} = 0.$$

where $\zeta_{v}(\eta) = \left(\sum_{u \in A(v)} d_{u}^{\rho} \eta_{u}^{1-\rho} \right)^{\frac{1}{1-\rho}}, = \frac{\rho}{2(\rho-1)} \text{ and } \mathbf{K}_{v} \text{ is matrix with entries: } y^{i} y^{j} k_{v}(\mathbf{x}^{i}, \mathbf{x}^{j}).$

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- Dual is min. of convex, Lipschitz conts., sub-differential objective over a simplex.
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Theorem

Suppose the active set \mathscr{W} is such that $\mathscr{W} = A(\mathscr{W})$. Let the reduced solution with this \mathscr{W} be $(\mathbf{w}_{\mathscr{W}}, b_{\mathscr{W}})$ and the corresponding dual variables be $(\eta_{\mathscr{W}}, \alpha_{\mathscr{W}})$. Then the reduced solution is a solution to the full problem with a duality gap less than ε if:

$$\max_{t \in sources(\mathscr{W}^{c})} \left(\sum_{\nu \in D(t)} \left(\frac{\alpha_{\mathscr{W}}^{\top} \mathbf{K}_{\nu} \alpha_{\mathscr{W}}}{\left(\sum_{u \in A(\nu) \cap D(t)} d_{u} \right)^{2}} \right) \right)^{1} \leq (\Omega(\mathbf{w}_{\mathscr{W}}))^{2} + 2(\varepsilon - \varepsilon_{\mathscr{W}})$$

where $\varepsilon_{\mathscr{W}}$ is a duality gap term associated with the computation of the reduced solution.

Final Sufficiency Condition:

$$\max_{t \in sources(\mathscr{W}^{c})} \left(\sum_{\nu \in D(t)} \left(\frac{\alpha_{\mathscr{W}}^{\top} \mathbf{K}_{\nu} \alpha_{\mathscr{W}}}{\left(\sum_{u \in A(\nu) \cap D(t)} du \right)^{2}} \right) \right)^{1} \leq (\Omega(\mathbf{w}_{\mathscr{W}}))^{2} + 2(\varepsilon - \varepsilon_{\mathscr{W}})$$

• $ho ightarrow 1 \ (ightarrow \infty)$, suff. cond. tight

- ho = 2 (= 1), suff. cond. loose; computationally **feasible**
- How much ground lost by replacing l_∞ with l₁ ?
 - Not much: As kernels near bottom are extremely sparse li

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Performance Comparison

Dataset	RuleFit	SLI	ENDER	HKL	$HKL_{\rho=1.1}$
TIC-TAC-TOE	0.652±0.068 (40 , 2.51)	0.747±0.026 (59, 2.35)	0.633±0.011 (111, 2.46)	0.889±0.029 (129, 1.85)	0.935 ±0.043 (79, 1.77)
BLOOD TRANS.	0.549±0.092 (18, 1.99)	0.559±0.100 (6 , 1.07)	0.489±0.054 (58, 1.5)	0.594 ±0.009 (242, 1.64)	0.593±0.011 (7,1.40)
BALANCE	0.835±0.034 (17 , 2.18)	0.856±0.027 (25, 1.88)	0.827±0.013 (64, 1.99)	$\begin{array}{c} 0.893 \pm 0.027 \\ (65, 1.65) \end{array}$	0.899 ±0.023 (28, 1.23)
HABERMAN	0.512±0.072 (6 , 1.68)	$\begin{array}{c} 0.565 \pm 0.066 \\ \textbf{(8, 1.14)} \end{array}$	0.424±0.000 (18, 1.87)	0.594 ±0.056 (32, 1.27)	0.594 ±0.056 (12,1.20)
CAR	$\begin{array}{c} 0.913 \pm 0.033 \\ \textbf{(34, 3.12)} \end{array}$	0.895±0.024 (141, 2.27)	$\begin{array}{c} 0.755 \pm 0.028 \\ (80, 1.85) \end{array}$	0.943 ±0.024 (87, 1.78)	$\begin{array}{c} 0.935 \pm 0.036 \\ (50, \textbf{1.68}) \end{array}$
СМС	$\begin{array}{c} 0.632 \pm 0.013 \\ \textbf{(39, 2.41)} \end{array}$	$\begin{array}{c} 0.601 \pm 0.041 \\ \textbf{(13, 2.13)} \end{array}$	0.644±0.026 (74, 2.65)	$\begin{array}{c} 0.656 \pm 0.014 \\ (127, 1.96) \end{array}$	0.659 ±0.008 (43, 1.70)

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Conjunctive Feature Induction for Sequence Labeling

Sequence Labeling: Assign a label to each instance in a sequence of observations.

Ex: Identify the sequence of activities performed by an old age person in a home based on sensor observations.

Observation: Labels at successive time steps are dependent. Ex: Cooking followed by dinner.





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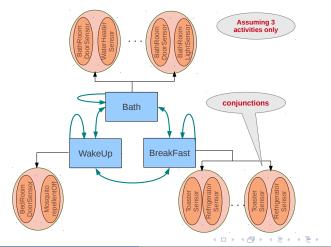
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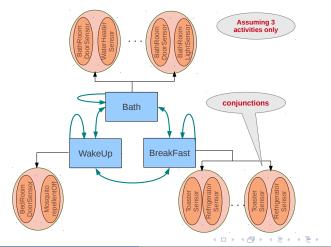
Feature Conjunctions for Sequence Labeling

- Objective is to learn emission features as conjunctions and combine them with all transition relations.
- Model desired



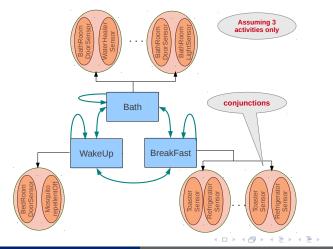
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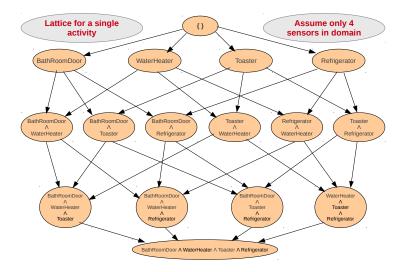


All possible features for a label can be ordered as a partially ordered set (Lattice).

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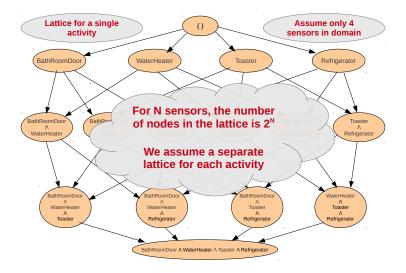
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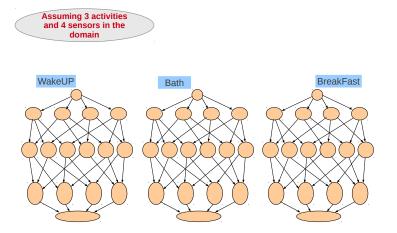
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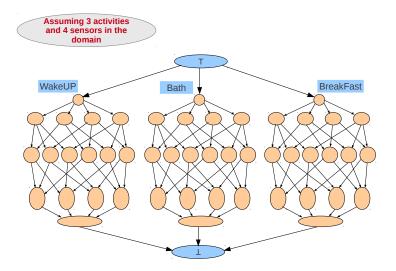
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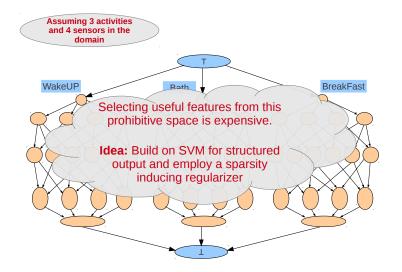
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Results - I

- Dataset Kasteren et al. [vKNEK08]
- Activities 8 (*sleeping*, *usingToilet*, *preparingDinner*, *preparingBreakfast*, *leavingOut*,*etc*.)
- No. of sensors 14
- No. of instances 40K

	Micro avg.	Macro avg.
Std. HMM	$25.40 (\pm 18.55)$	21.75 (±12.12)
B&B HMM	29.54 (±20.70)	$16.39 (\pm 02.74)$
Greedy FIHMM	58.08 (±10.14)	$26.84 (\pm 04.41)$
StructSVM	58.02 (±11.87)	35.00 (±05.24)
CRF	48.49 (±05.02)	20.65 (±04.82)
FICRF	59.52 (±11.76)	33.60 (±07.38)
RELHKL	46.28 (±11.44)	23.11 (±07.46)
StructRELHKL	$63.96 \ (\pm 05.74)$	$32.01 \ (\pm 03.04)$

Table: Micro (Weighted Per-Class) average accuracy and macro(Simple Per-Class) average accuracy of classification on UA dataset.

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Labeling Results - II

- Dataset MIT PlaceLab [TIL04] on Subject1 and Subject2
- No. of sensors 76 for Subject1 and 70 for Subject2
- No. of examples 20K and 24K resp.

		Micro avg.	Macro avg.
-	StructSVM	75.03 (±04.51)	26.99 (±07.73)
ect	CRF	65.54 (±06.80)	31.19 (±07.39)
Subject	FICRF	68.52 (±07.19)	29.77 (±03.59)
Ō	StructRELHKL	82.88 (±0.43)	28.92 (±01.53)
2	StructSVM	63.49 (±02.75)	25.33 (±05.8)
ect	CRF	50.23 (±06.80)	27.42 (±07.65)
Subject	FICRF	51.86 (±07.35)	26.11 (±05.89)
	StructRELHKL	$67.16 \ (\pm 08.64)$	24.32 (±02.12)

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Sample Rules/Features Induced

• $usingToilet \leftarrow bathroomDoor \land toiletFlush$

- $sleeping \leftarrow bedroomDoor \land toiletDoor \land bathroomDoor$,

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- $usingToilet \leftarrow bathroomDoor \land toiletFlush$
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- preparingDinner ← groceries Cupboard

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- Feature Extraction
 - Latent Dirichlet Allocation [BNJ03] and variants
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- Feature Subset Selection
 - wrappers provided in weka [WFH11]
 - legacy systems: Relief, Focus
 - L1-SVM
- Feature Extraction
 - Latent Dirichlet Allocation [BNJ03] and variants
 - Discriminant Analysis [YJ] and variants
 - Principal Component Analysis [Jol86] and variants
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Efficiently Inducing Disjunctive Features

Dimension Reduction Techniques

Method	Parameterized	Supervised	Integrated
Latent Dirichlet Allocation(LDA)	1	×	×
Supervised LDA	✓	1	 Image: A set of the set of the
Labeled LDA	 Image: A second s	MultiLabel Supervision	 Image: A set of the set of the
Discriminative LDA	1	1	1
Hierarchical Supervised LDA	 Image: A set of the set of the	Hierarchical Supervision	 Image: A set of the set of the
Kernel Dimension Reducion	 Image: A set of the set of the	1	×
Hierarchical Dirichlet Processes(HDP)	×	×	×
Hierarchical LDA	×	×	×
Supervised HDP	×	1	×
PCA,Kernel PCA,LSI,pLSI	✓	1	×
Random Projection	~	1	×
Self Organizing Map	~	1	×
Multidimensional Scaling	1	1	×
Discriminant Analysis	✓ Easter lade	< □ > < □ > < Ξ > < Ξ > <	E 🖌 🎽 🔊 ଏ ୯

Method	Parameterized	Supervised	Integrated
Max. Margin Dimension			
-Reduction(MMDR)	1	1	1
Linear MMDR	1	 Image: A set of the set of the	 Image: A set of the set of the
medLDA	1	 Image: A set of the set of the	 Image: A set of the set of the
mmPLSA	1	1	1

- We propose an approach of Max-Margin Dimension Reduction
 - non-parametric
 - supervised
 - Integrated with Classifier Training
 - leads to optimum model building
 - can incorporate further Background Knowledge

A (10) × (10) ×

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Discovering Small Set of Good & Maximal Disjunctive Projections

- maintains synonymity: {*elegant*,*exquisite*} •
- relevant: {method, algorithm} in Sentiment Analysis X
- maximal: {*elegant*,*exquisite*,*crude*} X
- Structure Induced
 - if {*elegant*, *exquisite*, *stately*} is a good Disjunctive Projection so is its subsets
 - if {*elegant,crude*} is not a good Disjunctive Projection, so isnt its supersets

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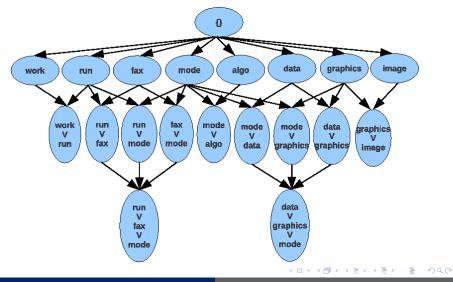
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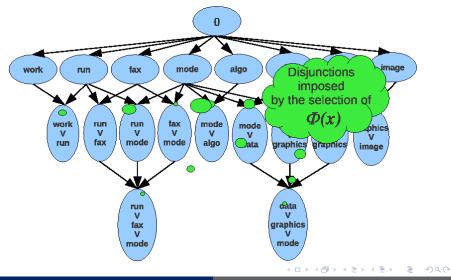
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For such structure : group Norm on Descendant Sets in HKL framework

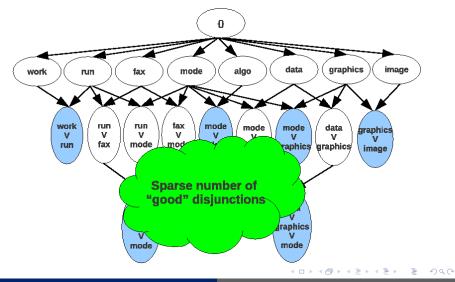
- Sparse number of disjunctions : ρ-norm
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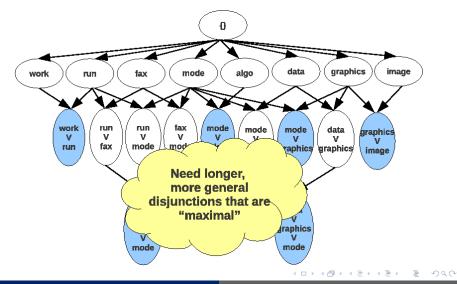
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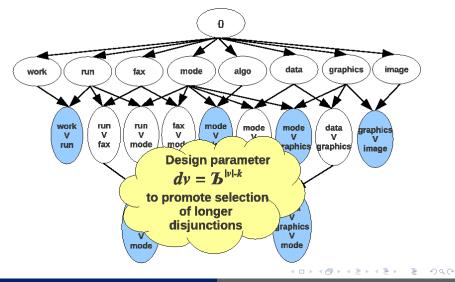
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Efficiently Inducing Disjunctive Features Max-Margin Objective

Max Margin Objective

$$\min_{\mathbf{w},b,\xi} \frac{1}{2} \Big(\sum_{v \in \mathscr{V}} \delta_v \| \mathbf{w}_{D(v)} \|_\rho \Big)^2 + C \mathbf{1}^\top \xi$$

s.t. $\forall i : y_i \Big(\sum_{v \in \mathscr{V}} \langle w_v, \phi_v(\mathbf{x}_i) \rangle - b \Big) \ge 1 - \xi_i, \xi \ge 0$

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Efficiently Inducing Disjunctive Features Experiment-1

- Dataset 20 Newsgroups Posting on 'alt.atheism' and 'talk.religion.misc'
- No of words/Features 18826
- No of instances 856

Approach	Accuracy	No. of Topics/Disjunctions
MMpLSA [Xu10]	84.7%	3
MedLDA [ZAX10]	$73.12\%^{2}$	20
DiscLDA [LJSJ08]	83.0%	60
Integ. Dim. Red.	94.55%	170

Table: Comparison of accuracies of different approaches on 20 *Newsgroups* [Lan] dataset.

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Efficiently Inducing Disjunctive Features Experiments-2

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		Breast	-cancer	Wisco	onsin	Hepatitis		20Newsgroups	
Subset	Search	\mathscr{L}_{2}	\mathscr{L}_1	\mathcal{L}_2	\mathscr{L}_1	\mathcal{L}_{2}	\mathscr{L}_1	\mathcal{L}_{2}	\mathscr{L}_1
Evaluator	Method	ω_2	<i>∞</i> 1	~2	~1	~2	~1	~2	~1
	BestFirst	74.64	70.65	93.84	94.72	95.0	93.75	93.67	89.10
NON	GreedyStep	74.64	67.75	93.84	94.72	95.0	93.75	93.76	89.10
10101	LinearFwd	74.64	67.75	93.84	94.72	95.0	93.75	92.09	89.98
Conelation	Rank	74.64	70.65	93.84	94.72	94.15	93.75	92.26	91.38
	SubsetSizeFwd	74.64	70.65	93.84	94.72	94.15	93.75	92.09	89.98
	BestFirst	67.39	72.46	95.31	95.89	88.75	86.25	89.98	92.97
. orit	GreedyStep	70.29	67.75	95.75	95.01	87.0	86.25	-	-
SIST	LinearFwd	70.65	71.01	94.72	94.43	88.75	87.5	87.34	89.28
Consistent	Rank	68.48	68.48	94.57	92.08	92.5	91.25	93.67	91.91
	SubsetSizeFwd	70.65	71.01	94.72	94.43	88.75	88.75	87.34	89.28
	BestFirst	77.54	70.29	94.43	94.14	91.25	91.25	93.14	91.56
à	GreedyStep	77.54	70.29	94.43	94.14	91.25	91.25	93.14	91.56
Filtered	LinearFwd	77.54	70.29	94.43	94.14	91.25	91.25	90.51	87.34
۲ ^۳	Rank	77.14	70.29	94.43	94.14	88.75	92.5	84.88	85.86
	SubsetSizeFwd	77.89	70.29	94.43	94.14	91.25	91.25	90.51	87.34
Integ.	Dim. Red.	75.3	6±0.49	96.34	±0.19	91.25	±0.29	94.55	5±0.23

Table: Comparison with Dimension Reduction Weka's Feature Selection Methods followed by SVM-2norm (\mathscr{L}_2) and SVM-1norm (\mathscr{L}_1)

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Efficiently Inducing Disjunctive Features Experiments

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		Trans	fusion	Vo	te	Tic-Tac-Toe	
Subset	Search	L	\mathscr{L}_1	L	\mathscr{L}_1	L	\mathscr{L}_1
Evaluator	Method	z_2	~1		~1	2	21
	BestFirst	91.04	91.04	96.28	96.28	80.88	73.88
ion	GreedyStep	91.04	91.04	96.28	96.28	80.88	73.88
10100	LinearFwd	91.04	91.04	96.28	96.28	80.88	73.88
correlation	Rank	91.04	91.04	96.28	96.28	80.88	73.88
	SubsetSizeFwd	91.04	91.04	96.28	96.28	80.88	73.88
	BestFirst	92.37	90.78	95.26	96.28	100.0	76.49
ent	GreedyStep	91.18	71.92	94.40	93.10	99.58	98.33
SIST	LinearFwd	91.44	90.78	97.41	95.69	99.68	75.44
consistent	Rank	91.57	89.84	94.6	93.1	99.68	80.45
	SubsetSizeFwd	91.04	91.04	96.28	96.28	99.68	75.44
	BestFirst	90.1	90.1	96.28	96.28	70.01	70.01
6	GreedyStep	90.1	90.1	96.28	96.28	70.01	70.01
Filtered	LinearFwd	90.1	90.1	96.28	96.28	70.01	70.01
<u>۲</u>	Rank	91.04	91.04	96.28	96.28	70.01	70.01
	SubsetSizeFwd	90.1	90.1	96.28	96.28	70.01	70.01
Integ.	Dim. Red.	91.04	±0.30	96.28	±0.17	100.0	0±0.0

Table: Comparison with Dimension Reduction Weka's Feature Selection Methods followed by SVM-2norm (\mathscr{L}_2) and SVM-1norm (\mathscr{L}_1)

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Efficiently Inducing Disjunctive Features Experiments

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		Mon	k-1	Mon	k-2	Mon	k-3	
Subset	Search	\mathcal{L}_2	\mathscr{L}_1	\mathscr{L}_2	\mathscr{L}_1	\mathscr{L}_2	\mathscr{L}_1	
Evaluator	Method	22	~1	2	~1	22	~1	
	BestFirst	69.37	74.94	63.34	59.63	97.22	97.22	
io ^r	GreedyStep	69.37	74.94	63.34	59.63	97.22	97.22	
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	SubsetSizeFwd	74.94	74.94	62.41	59.63	97.22	97.22	
Integ.	Dim. Red.	100.0	±0.0	85.15	±0.38	97.22	±0.16	

Table: Comparison with Dimension Reduction Weka's Feature Selection Methods followed by SVM-2norm (\mathscr{L}_2) and SVM-1norm (\mathscr{L}_1)

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Learning First Order Features

- Statistical Learner constructs model from features identified by a relational learner

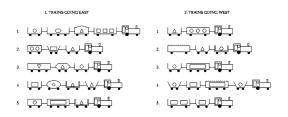


Figure: Reproduced from *Michalski's* famous trains example

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Learning First Order Features

- Statistical Learner constructs model from features identified by a relational learner
- Relational Features ↔ First Order Logic Clauses

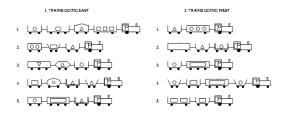


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What kind of features are useful?

- $eastbound(A) \leftarrow hasCar(A,B), hasCar(A,C), short(B), closed(C)$
- Is there some redundancy?
- Does this feature need to be learnt explicitly by the relational learner?

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Feature Classes: Definite Feature

• Definite Features (F_d) [SMSK96]

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• Independent Features (F_i) [CSC⁺02]

- Definite Clauses consisting of exactly 1 independent component
- $eastbound(A) \leftarrow hasCar(A,B), hasCar(A,C), short(B), closed(C)$
- Independent Clauses
 - 1 : $(eastbound(A) \leftarrow hasCar(A,B), short(B))$
 - 2 : $(eastbound(A) \leftarrow hasCar(A,C), \ closed(C))$

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Feature Classes: Relational Subgroup Discovery Feature

• *RSDFeatures* (*F_r*) [LZF02]

- Independent Features with no unused variable in clause body
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Feature Classes: Relational Subgroup Discovery Feature

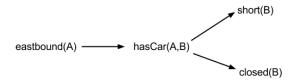
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• Simple Features (F_s) [MS98]

 Independent Features with one sink in the variable dependency graph

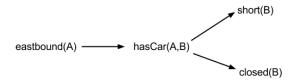


- eastbound(A) ← hasCar(A,B), short(B), closed(B) is Independent but not simple
- Simple Features
 - 1 : $eastbound(A) \leftarrow hasCar(A,B), short(B)$
 - ▶ 2 : $eastbound(A) \leftarrow hasCar(A,B), closed(B)$

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• Simple Features (F_s) [MS98]

 Independent Features with one sink in the variable dependency graph

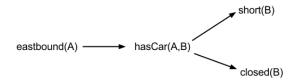


- eastbound(A) ← hasCar(A,B), short(B), closed(B) is Independent but not simple
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 - 1 : $eastbound(A) \leftarrow hasCar(A,B), short(B)$
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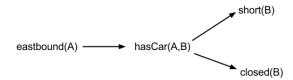
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Feature Classes: Elementary Feature

Elementary Feature [FL00]

Simple Features with no unused variable in body
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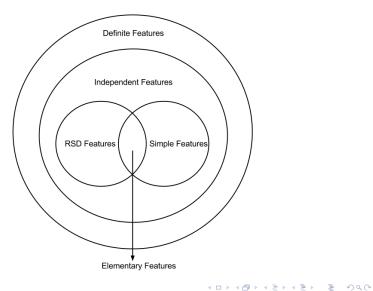
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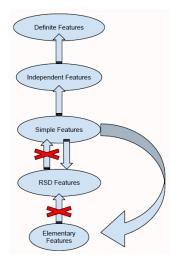
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Useful?

Subset Relation between Feature Classes



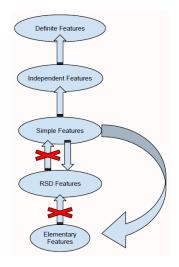
- Reconstruction by statistical learners using
 - exact logical operations (conjunctions)
 - approximation by weighted linear combinations



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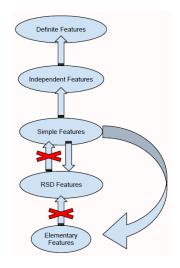


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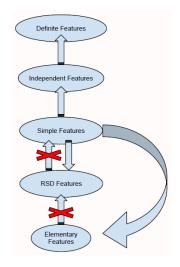
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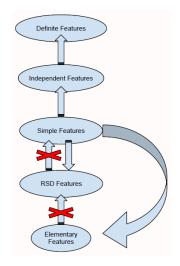
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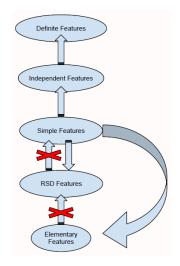
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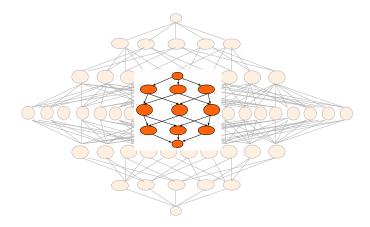
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Useful?

Goal: Discovering most effective subclass

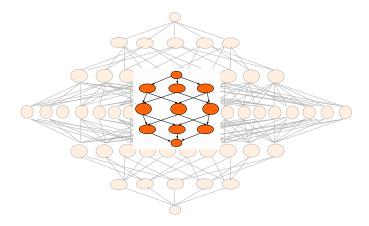
- The subclass that is yields most accurate statistical models
- The subclass that can be logically composed to yield other powerful subclasses



Useful?

Goal: Discovering most effective subclass

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Experiment-I: SVM as Model Builder

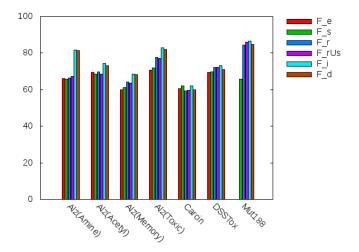


Figure: Accuracy of the Models Built by SVM-2 norm regularizer(LibSVM) [CL11] on the feature classes F_e , F_s , $F_{\underline{r}}$, $F_{r\cup s}$, $F_{i,_}F_d$

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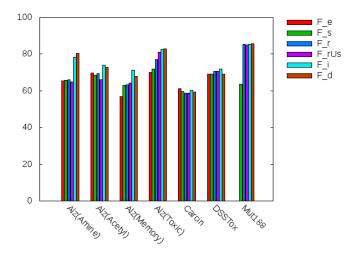


Figure: Accuracy of the Models Built by SVM-1 norm regularizer(LibLinear) [FCH⁺08] on the feature classes F_e , F_s , F_r , $F_{r\cup s}$, F_i , F_d

Experiment-II: LR as Model Builder

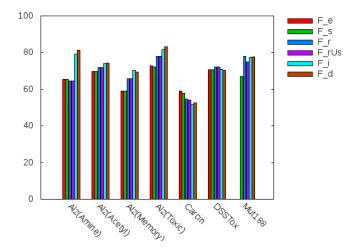


Figure: Accuracy of the Models Built by Logistic Regression on the feature classes F_e , F_s , F_r , $F_{r\cup s}$, F_i , F_d

Experiment-II: LR as Model Builder

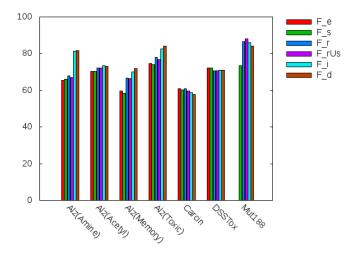


Figure: Accuracy of the Models Built by Sparse Multinomial Logistic Regression [KCFH05] on the feature classes F_e , F_s , F_r , $F_{r\cup s}$, F_i , F_d

Useful?

Experiment-III: Rule Ensemble learner MLRules

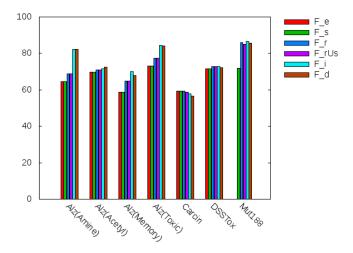


Figure: Accuracy of Model Built by Maximum Likelihood Rule Ensembles [DKS08] on the feature classes F_e , F_s , F_r , $F_{r\cup s}$, F_i , F_d

How significantly different?

Feature		Total				
Class	L1-SVM	L2-SVM	LR	SMLR	MLRules	Wins
F _e	1	0	1	1	1	4/35
F_s	0	1	0	1	0	2/35
F_r	0	1	1	1	0	3/35
$F_{r\cup s}$	0	0	1	1	1	3/35
F_i	3	6	1	1	4	15/35
F_d	3	0	4	3	1	11/35

Figure: Number of outright wins for a feature class. This is number of occasions out of the total number of possible occasions (*i.e.* 35) on which a statistical learners achieves the highest mean predictive accuracy using features from that class.

How significantly different?

Feature	Nu	Total No. of				
Class	L1-SVM	L2-SVM	LR	SMLR	MLRules	Good Models
F _e	2	1	2	2	2	9/35
F_s	2	1	2	2	2	9/35
F_r	2	2	1	4	4	13/35
$F_{r\cup s}$	3	2	1	4	4	14/35
F_i	7	7	6	7	7	34/35
F_d	4	5	6	7	7	25/35

Figure: Number of good enough models (out of all possible models *i.e.* 35), using a feature class. A model is taken to be good enough if its predictive accuracy is not statistically different to the model with the highest predictive accuracy.

Useful?

Comparison with Parameter-tuned ILP models

Data	Statistical Model	ILP Model With
		Parameter Selection & Optimization
Alz (Amine)	82.32±1.18	80.20
Alz (Acetyl)	74.16±0.24	77.40
Alz (Memory)	71.83±1.67	67.40
Alz (Toxic)	$84.50{\scriptstyle \pm 0.44}$	87.20
Carcin	62.15±1.75	59.10
DSSTox	73.12±0.94	73.10
Mut(188)	88.06±1.57	88.30

Figure: Comparison of mean predictive accuracies of statistical models against the ILP models constructed with parameter selection and optimisation (see [SR11]).

Results for Sequence Labeling

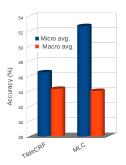
Katholieke Universiteit Data [Landwehr et al., 2009] (KU Data)

	Micro avg.(%)	Macro avg.(%)	F score
TildeCRF: Baseline	46.54	44.34	0.51
Independent Features (F_i)	52.69	44.06	0.57



19 activities

 20 sequences of around 250 time steps

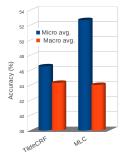


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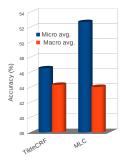
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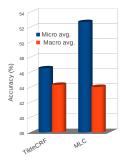
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Presented methods for learning statistically optimal features

- Improved generalization
- **Bridged gap** between statisical and rule learning communities
- Investigated feature in which class are worth learning
- Two-fold objective: Learning short and few features
 - Generalizes well while learning compact ruleset
 - Sometimes 25% improvement in generalization
 - Applicable elsewhere
- Efficient mirror-descent based active set method
 - Complexity: polynomial in active set size ($< O(2^{\circ})$ Searched rule space size $\sim 2^{20}$ in ~ 10 min.

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THANK YOU

Ganesh Feature Induction in Machine Learning

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