

2 points related to

viterbi (max product)

1)  $\arg \max_y \omega^T \phi(x, y)$

can be computed efficiently using

max product  
# labels =  $m$   
length of sequence =  $n$  }  $O(mn^2)$

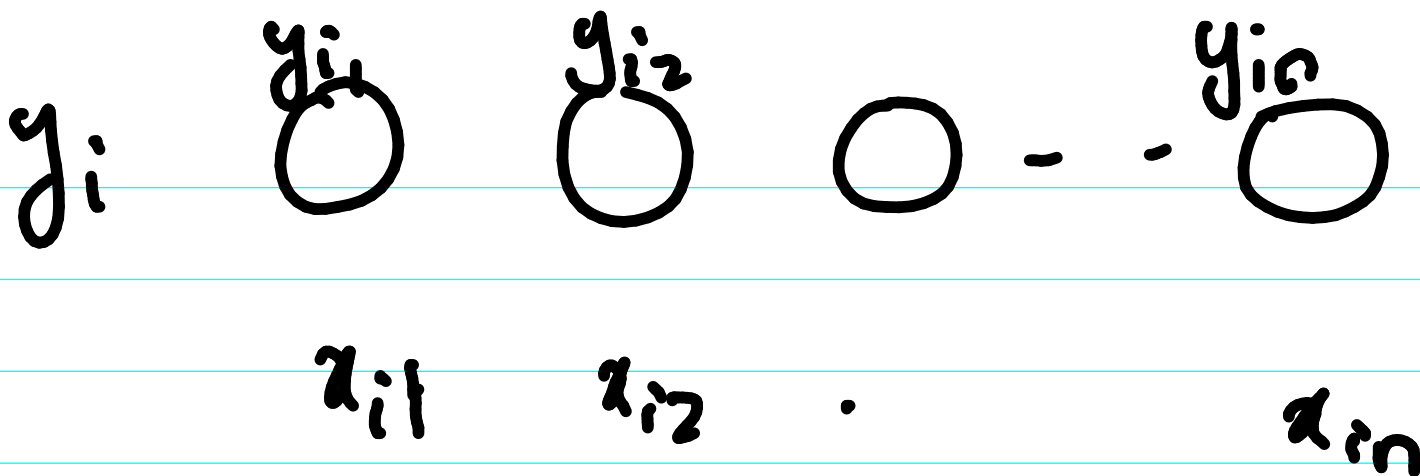
2) Can you use some

dynamic programming  
even while computing

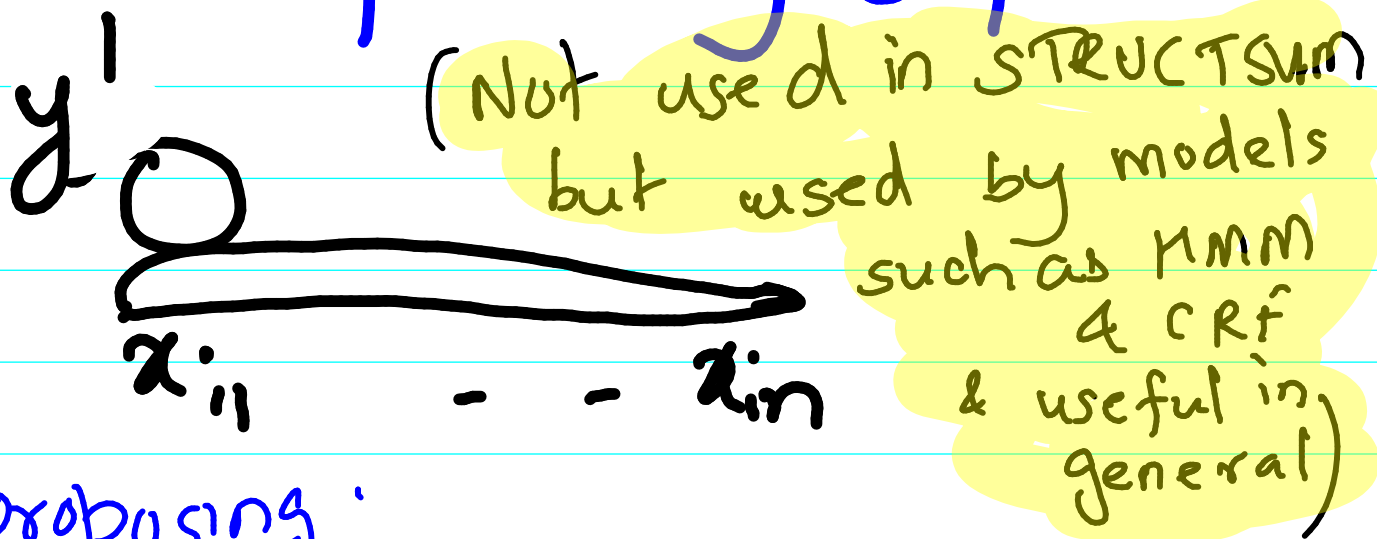
$\omega^T \phi(x_i, y_i)$  across diff  $i$ 's

$O(n)$

Both known



3) belief that label  $y_j$  appears in 1st position of sequence



I am proposing:

$$u(y') = \sum_{y \text{ s.t. } y[i] = y'} w^T \phi(x_{ij}, y)$$

write DP steps

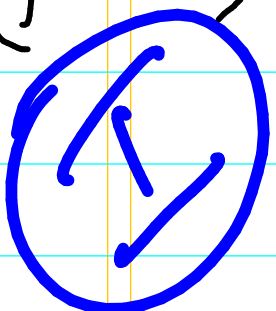
Hint: Just as

Max product :  $\max_{a,b} g(a) f(a,b) = \max_a g(a) \max_b f(a,b)$   
 Sum product :  $\sum_{a,b} g(a) f(a,b) = \sum_a g(a) \sum_b f(a,b)$

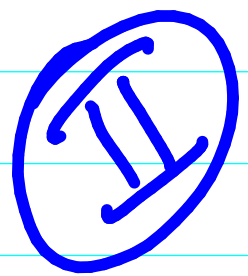
# We will now study more complex settings

<http://www.cse.iitb.ac.in/~cs717/notes/classNotes/StructuredOutput/STRUCTSVMWITHKERNELS.pdf>

STRUCTSVM with arbit kernels on i/p space



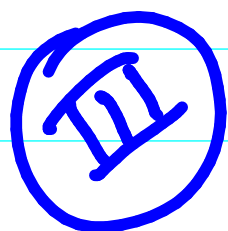
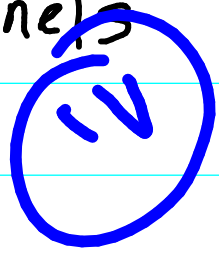
o/p / Structure more complex such as DAG's, cyclic graphs, higher order relations (MLN, BLP)



Constrained Conditional models: Adding complexity to runtime constraints instead of adding a number to features



Composing features to give "interpretable" composite features instead of a number as o/p by kernels



Require a bit of submodular optimisation

This formidable set of  $Y \neq Y_i$  &  $Y_i \neq Y_j$  have jumped from constraints to the objective

$$\max_{\alpha} \sum_{i, Y \neq Y_i} \alpha_{iY} - \frac{1}{2} \sum_{i, Y \neq Y_i} \sum_{j, Y' \neq Y_j} \alpha_{iY} \alpha_{jY'} \langle \psi_i^{\delta}(Y), \psi_j^{\delta}(Y') \rangle$$

such that,

$$\forall i, \forall Y \neq Y_i: \alpha_{iY} \geq 0$$

$$\forall i: n \sum_{Y \neq Y_i} \frac{\alpha_{iY}}{\Delta(Y_i, Y)} \leq C$$

2 summations  
1 summation

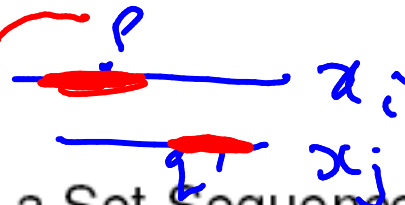
Recall:  $\psi_i^{\delta}(Y) = \psi(X_i, Y_i) - \psi(X_i, Y)$

desired features  
incidental features

$$\langle \mathbf{f}, \psi_i^{\delta}(Y) \rangle = \langle \mathbf{f}, \psi(X_i, Y_i) \rangle - \langle \mathbf{f}, \psi(X_i, Y) \rangle$$

⋮

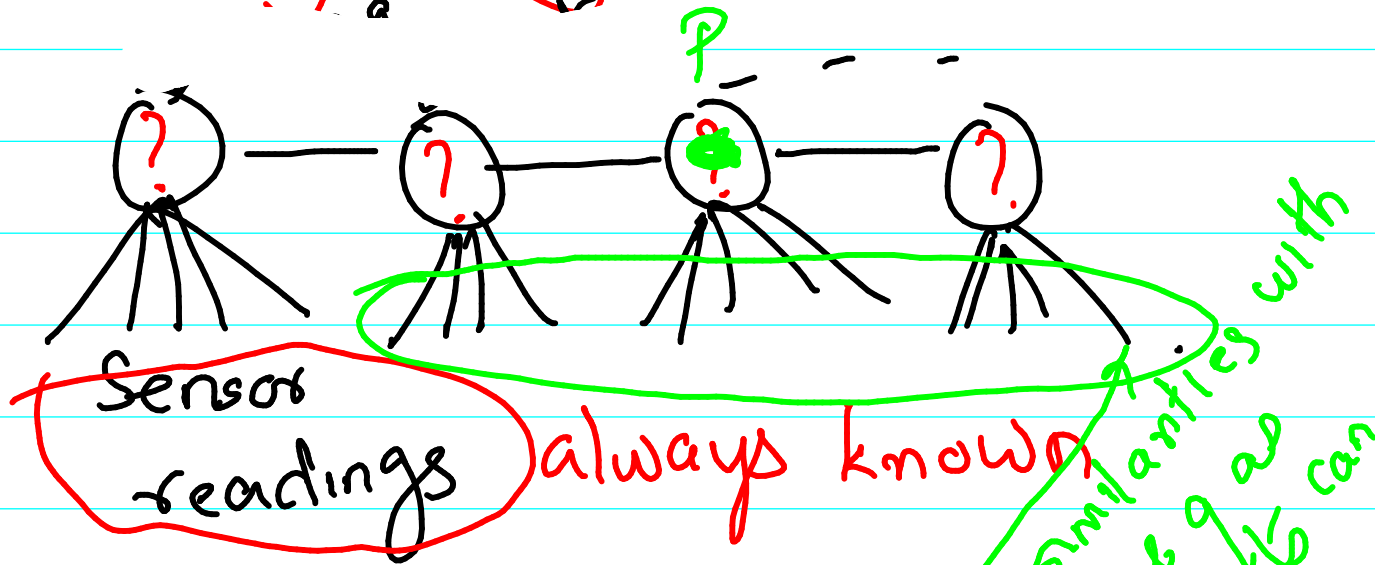
$$\kappa_E^{\delta}((X_i, Y_i, Y), (X_j, Y_j, Y')) = \sum_{p=1}^{l_i} \sum_{q=1}^{l_j} \kappa_E(x_i^p, x_j^q) (\Lambda(y_i^p, y_j^q) + \Lambda(y^p, y'^q))$$



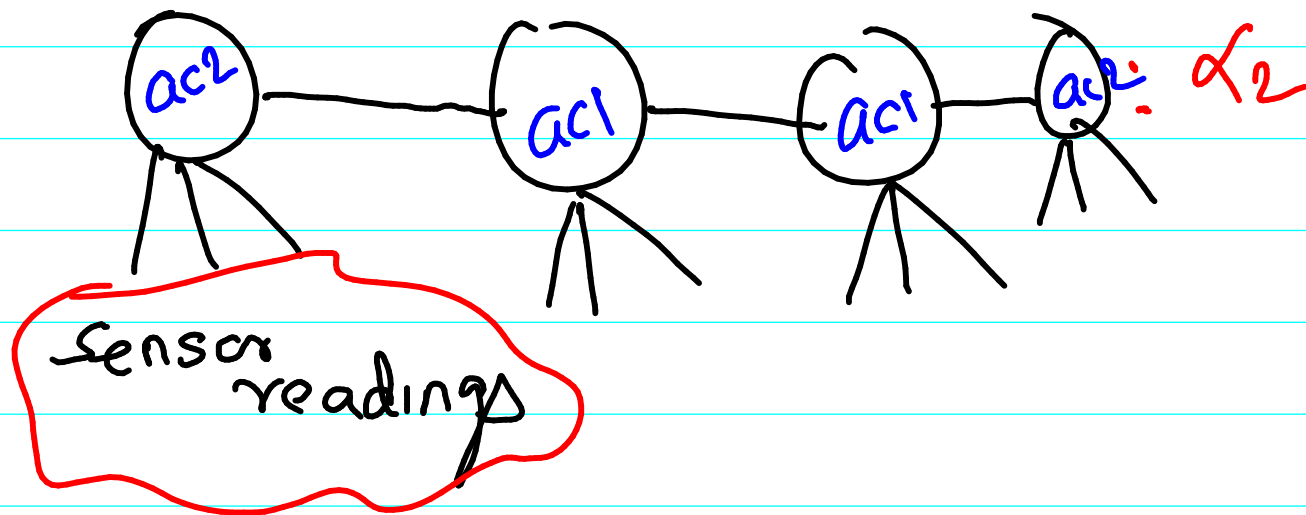
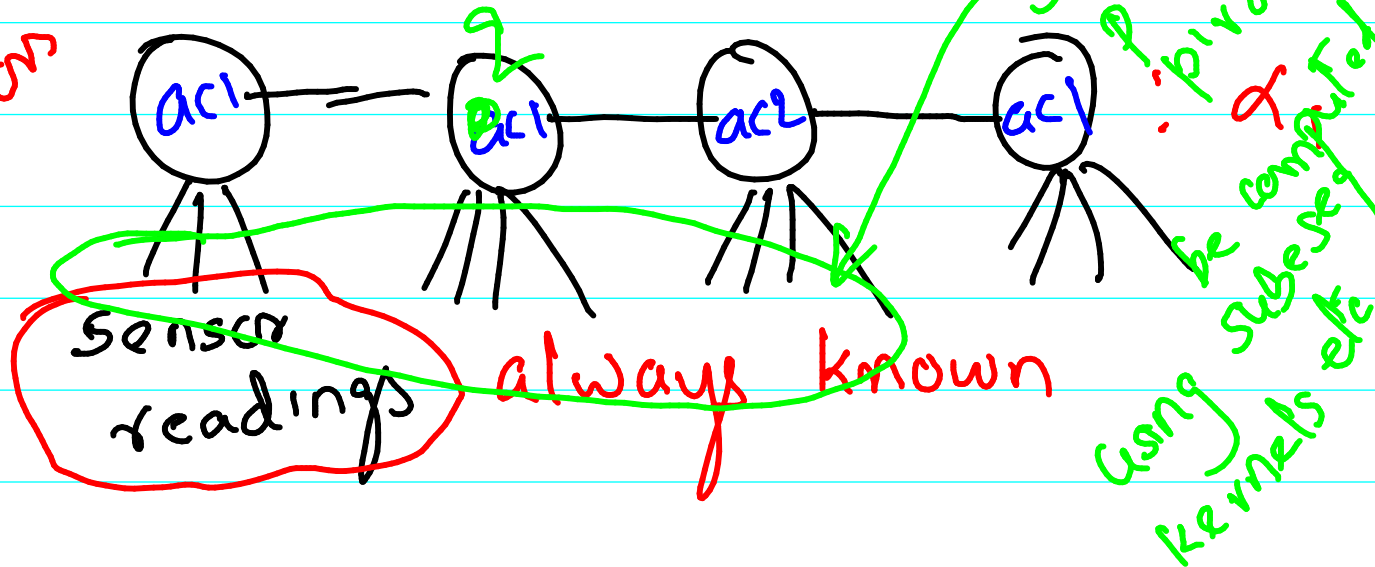
The kernel  $\kappa_E(x_i^p, x_j^q)$  can be defined as a Set-Sequence (String) kernel), where we may be considering some window time steps  $q$ , with  $p$  and  $q$  as pivots.

# Eg. Activity recognition

test instance



training instances that are support vectors

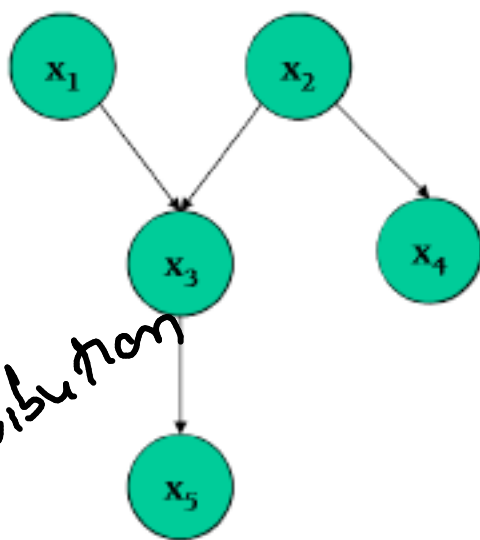


**Definition 1** Let  $\mathcal{R} = \{X_1, X_2, \dots, X_n\}$  be a set of random variables, with each  $X_i$  ( $1 \leq i \leq n$ ) assuming values  $x_i \in \mathcal{X}_i$ . Let  $\mathcal{X}_S = \{X_i \mid i \in S\}$  where  $S \subseteq \{1, 2, \dots, n\}$ . Let  $\mathcal{G} = \langle \mathcal{V}, \mathcal{E} \rangle$  be a directed acyclic graph with vertices  $\mathcal{V} = \{1, 2, \dots, n\}$  and  $\mathcal{E} \subseteq \mathcal{V} \times \mathcal{V}$  such that each edge  $e = (i, j) \in \mathcal{E}$  is a directed edge. We will assume a one to one correspondence between the set of variables  $\mathcal{R}$  and the vertex set  $\mathcal{V}$ ; vertex  $i$  will correspond to random variable  $X_i$ . Let  $\pi_i$  be the set of vertices from which there is edge incident on vertex  $i$ . That is,  $\pi_i = \{j \mid j \in \mathcal{V}, (j, i) \in \mathcal{E}\}$ . Then, the family  $\mathcal{F}(\mathcal{G})$  of joint distributions associated with the DAG<sup>2</sup>  $\mathcal{G}$  is specified by the factorization induced by  $\mathcal{G}$  as follows:

$$\mathcal{F}(\mathcal{G}) = \left\{ p(x) \mid p(x) = \prod_i p(x_i \mid x_{\pi_i}) \right\}$$

a filter

based on  
factorisation  
requirement  
on joint distribution



$$\pi_{x_4} = \{x_2\}$$

$$\pi_{x_3} = \{x_1, x_2\}$$

Figure 1.1: A directed graphical model.

$$P(x_1, x_2, \dots, x_5) = P(x_5 \mid x_3) P(x_3 \mid x_1, x_2) \\ P(x_4 \mid x_2) P(x_1) P(x_2)$$

**Definition 2** Let  $\mathcal{R} = \{X_1, X_2, \dots, X_n\}$  be a set of random variables, with each  $X_i$  ( $1 \leq i \leq n$ ) assuming values  $x_i \in \mathcal{X}_i$ . Let  $\mathbf{X}_S = \{X_i \mid i \in S\}$  where  $S \subseteq \{1, 2, \dots, n\}$ . Let  $\mathcal{G} = \langle \mathcal{V}, \mathcal{E} \rangle$  be a directed acyclic graph with vertices  $\mathcal{V} = \{1, 2, \dots, n\}$  and  $\mathcal{E} \subseteq \mathcal{V} \times \mathcal{V}$  such that each edge  $e = (i, j)$  is a directed edge. Let  $\pi_i = \{j \mid j \in \mathcal{V}, (j, i) \in \mathcal{E}\}$ . Then, the family  $\mathcal{C}(\mathcal{G})$  of joint distributions associated with the DAG  $\mathcal{G}$  is specified by the conditional independence induced by  $\mathcal{G}$  as follows:

family of distributions specified by the single graph  $\mathcal{G}$

$$\mathcal{C}(\mathcal{G}) = \left\{ p(\mathbf{x}) \mid X_i \perp \mathbf{X}_{\mu_{i-1}} \mid \mathbf{X}_{\pi_i} \quad \forall 1 \leq i \leq n, \sum_{\mathbf{x}} p(\mathbf{x}) = 1 \right\} \quad (1.9)$$

$\mathbf{X}_{\mu_{i-1}}$  = Set of all non-descendants of  $X_i$

Claim:  $F(\mathcal{G}) = \mathcal{C}(\mathcal{G})$

Simple eg:

①

$X_1$

$X_2$

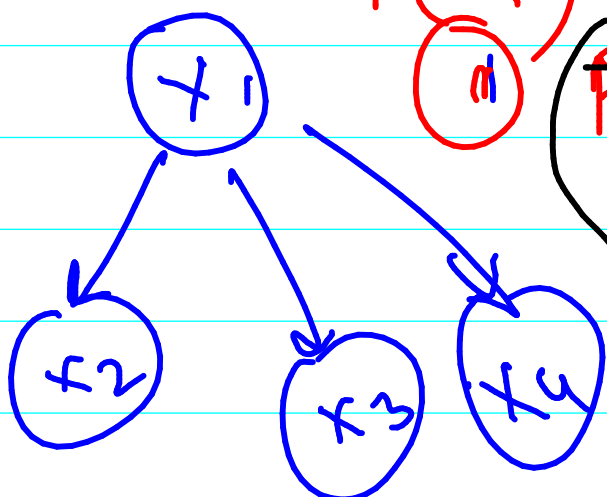
$X_3$

$\mathcal{C}(\mathcal{G})$ : ②

$P(X_1, X_2, X_3) = P(X_1)P(X_2)P(X_3)$   
 $X_1 \perp\!\!\!\perp X_2$   
 $X_1 \perp\!\!\!\perp X_3$

① & ② are equivalent? Prove.

②



$F(G)$   
①

$$P(x_1, x_2, x_3, x_4) = P(x_2|x_1) P(x_3|x_1) P(x_4|x_1) P(x_1)$$

$C(G)$

②

$$x_2 \perp\!\!\!\perp x_3 | x_1$$

$$x_2 \perp\!\!\!\perp x_4 | x_1$$

$$x_3 \perp\!\!\!\perp x_4 | x_1$$

Are ① & ② equivalent?

H/W: Prove equivalence

①  $\Rightarrow$  ②

$$P(x_2|x_1) \quad P(x_3|x_1)$$

$$P(x_1, x_2, x_3, x_4) = P(x_2/x_1, x_3, x_4) P(x_3/x_1, x_4) P(x_4/x_1) P(x_1)$$



To prove in general that

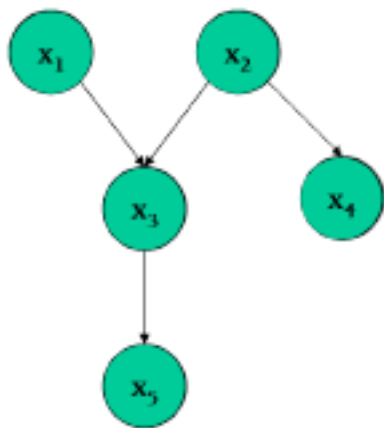
$$F(G) = C(G),$$

Prove that

for any  $P$ ,  $P \in F(G) \iff P \in C(G)$

Please read  
proof to Theorem 1  
from

<http://www.cse.iitb.ac.in/~cs717/notes/classNotes/graphicalModelsReading.pdf>



H/w: Verify that the following 2 are equivalent (and in fact are imposed by 2 different interpretations of the above graph)

Factorisation interpretation:  $F(G)$

$$P(x_1, \dots, x_5) = P(x_5 | x_3) P(x_3 | x_1, x_2) P(x_4 | x_2) P(x_1) P(x_2)$$

Conditional independence interpretation:  $(G)$

$$x_1 \perp\!\!\!\perp x_2, x_1 \perp\!\!\!\perp x_4, x_3 \perp\!\!\!\perp x_4 \mid x_1, x_2$$

$$x_5 \perp\!\!\!\perp x_4 \mid x_3$$

Verify that one follows from other

**Theorem 1** The sets  $\mathcal{F}(\mathcal{G})$  and  $\mathcal{C}(\mathcal{G})$  are equal. That is  $p \in \mathcal{F}(\mathcal{G})$  iff  $p \in \mathcal{C}(\mathcal{G})$

*Proof:*  $\Leftarrow$ : We will first prove that  $\mathcal{F}(\mathcal{G}) \subseteq \mathcal{C}(\mathcal{G})$ . Let  $p \in \mathcal{F}(\mathcal{G})$ . We will prove that  $p \in \mathcal{C}(\mathcal{G})$ , that is,  $p(x_i | \mathbf{x}_{\mu_{i-1}}, \mathbf{x}_{\pi_i}) = p(x_i | \mathbf{x}_{\pi_i})$ . This trivially holds for  $i = 1$ , since  $\mathbf{x}_{\pi_1} = \emptyset$ . For  $i = 2$ :

$$p(x_1, x_2) = p(x_1)p(x_1 | x_2) = p(x_1)p(x_1 | \mathbf{x}_{\pi_2})$$

where, the first equality follows by chain rule, whereas the second equality follows by virtue of (1.8). Consequently,

$$p(x_1 | x_2) = p(x_1 | \mathbf{x}_{\pi_2})$$

Assume that  $p(x_i | \mathbf{x}_{\mu_{i-1}}) = p(x_i | \mathbf{x}_{\pi_i})$  for  $i \leq k$ . For  $i = k + 1$ , it follows from chain rule and from (1.8) that

$$p(\mathbf{x}_{\mu_{k+1}}) = \prod_{i=1}^{k+1} p(x_i | \mathbf{x}_{\mu_{i-1}}) = \prod_{i=1}^{k+1} p(x_i | \mathbf{x}_{\pi_i})$$

Making use of the induction assumption for  $i \leq k$  in the equation above, we can derive that

$$p(x_k | \mathbf{x}_{\mu_{k-1}}) = p(x_k | \mathbf{x}_{\pi_k})$$

By induction on  $i$ , we obtain that  $p(x_i | \mathbf{x}_{\mu_{i-1}}) = p(x_i | \mathbf{x}_{\pi_i})$  for all  $i$ . That is,  $p \in \mathcal{C}(\mathcal{G})$ . Since this holds for any  $p \in \mathcal{F}(\mathcal{G})$ , we must have that  $\mathcal{F}(\mathcal{G}) \subseteq \mathcal{C}(\mathcal{G})$ .

$\Rightarrow$ : Next we prove that  $\mathcal{C}(\mathcal{G}) \subseteq \mathcal{F}(\mathcal{G})$ . Let  $p' \in \mathcal{C}(\mathcal{G})$  satisfy the conditional independence assertions. That is, for any  $1 \leq i \leq n$ ,  $p'(x_i | \mathbf{x}_{\mu_{i-1}}) = p'(x_i | \mathbf{x}_{\pi_i})$ . Then by chain rule, we must have:

$$p'(\mathbf{x}_{\mu_n}) = \prod_{i=1}^n p'(x_i | \mathbf{x}_{\mu_{i-1}}) = \prod_{i=1}^{k+1} p'(x_i | \mathbf{x}_{\pi_i})$$

Initially true

By induction

Equating what ever remain after using equality from induction

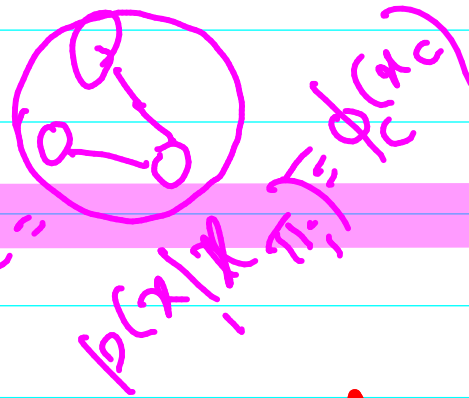
**Definition 4** The set of probability distributions  $\mathcal{D}(\mathcal{G})$  for a DAG  $\mathcal{G}$  is defined as follows:

$$\mathcal{D}(\mathcal{G}) = \{p(\mathbf{x}) \mid \mathbf{X}_A \perp \mathbf{X}_B \mid \mathbf{X}_C, \text{ whenever } A \text{ and } B \text{ are } d\text{-separated by } C\} \quad (1.10)$$

**Theorem 2** For any directed acyclic graph  $\mathcal{G}$ ,  $\mathcal{D}(\mathcal{G}) = \mathcal{C}(\mathcal{G}) = \mathcal{F}(\mathcal{G})$ .

*d*-separation based independence  $\rightarrow$  Conditional independence

For digraphs, cliques are sets containing node & its parents  
i.e.  $C_i = \{X_i, \text{Pa}(X_i)\}$



We can similarly discuss  $\mathcal{F}(\mathcal{G})$  &  $\mathcal{C}(\mathcal{G})$  for undirected graphs  $\mathcal{G}$

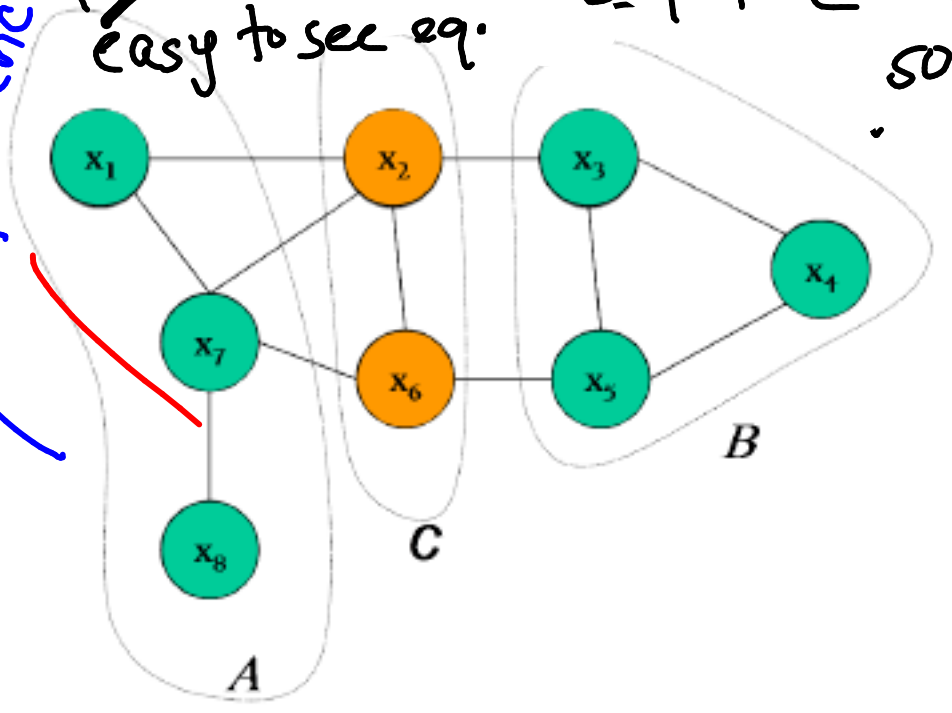
$\prod_{C \in \mathcal{C}} \phi_C(x_C) \rightarrow \mathcal{F}(\mathcal{G})$        $x \perp\!\!\!\perp y \mid z$  given  $\mathcal{G}$  if other nodes

$x_6 \perp\!\!\!\perp x_8, x_7$   
 $x_4 \perp\!\!\!\perp x_3, x_2, x_5$   
 $x_7 \perp\!\!\!\perp x_8$   
 $x_8 \perp\!\!\!\perp x_2$

$M(G)$

conditional independence

$x_A \perp\!\!\!\perp x_B \mid x_C$  & so on  
 easy to see eq.



$F(G)$

factorset definition

$$\begin{aligned}
 P(x_1, \dots, x_8) = & \phi_{x_1, x_2, x_7}(x_1, x_2, x_7) \phi_{x_7, x_6, x_2}(x_7, x_6, x_2) \\
 & \phi_{x_7, x_8}(x_7, x_8) \phi_{x_5, x_6}(x_5, x_6) \\
 & \phi_{x_2, x_3}(x_2, x_3) \phi_{x_5, x_3, x_4}(x_5, x_3, x_4)
 \end{aligned}$$

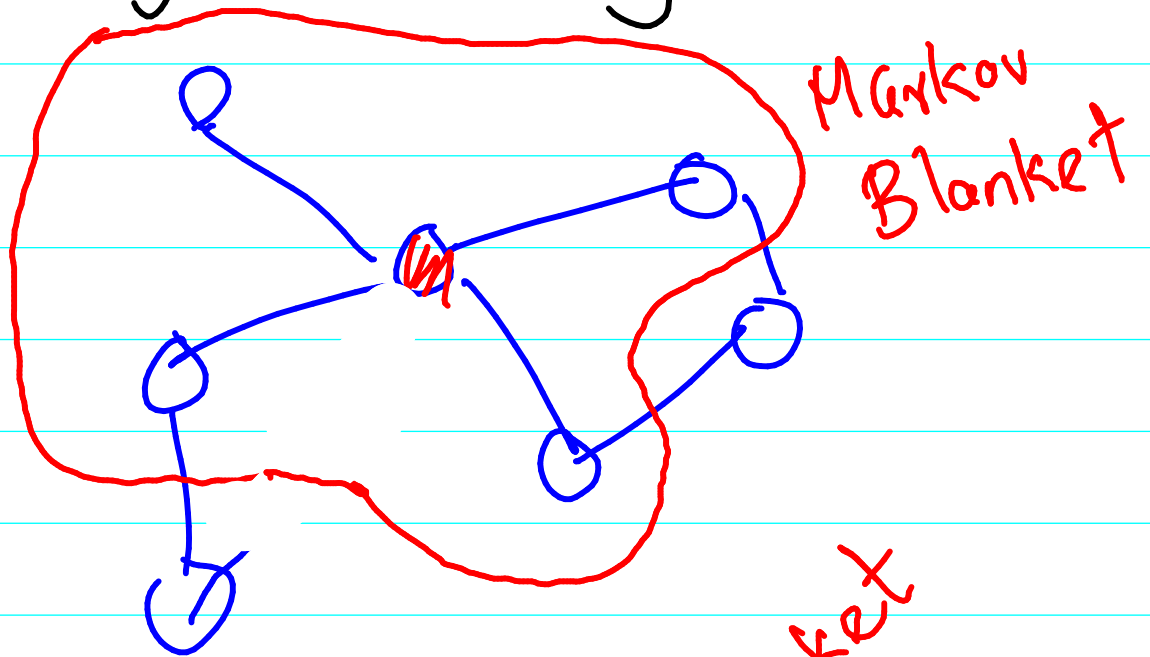
Claim :  $M(G) = F(G)$  for undirected graphs  $G$

Refer to notes & slides for details

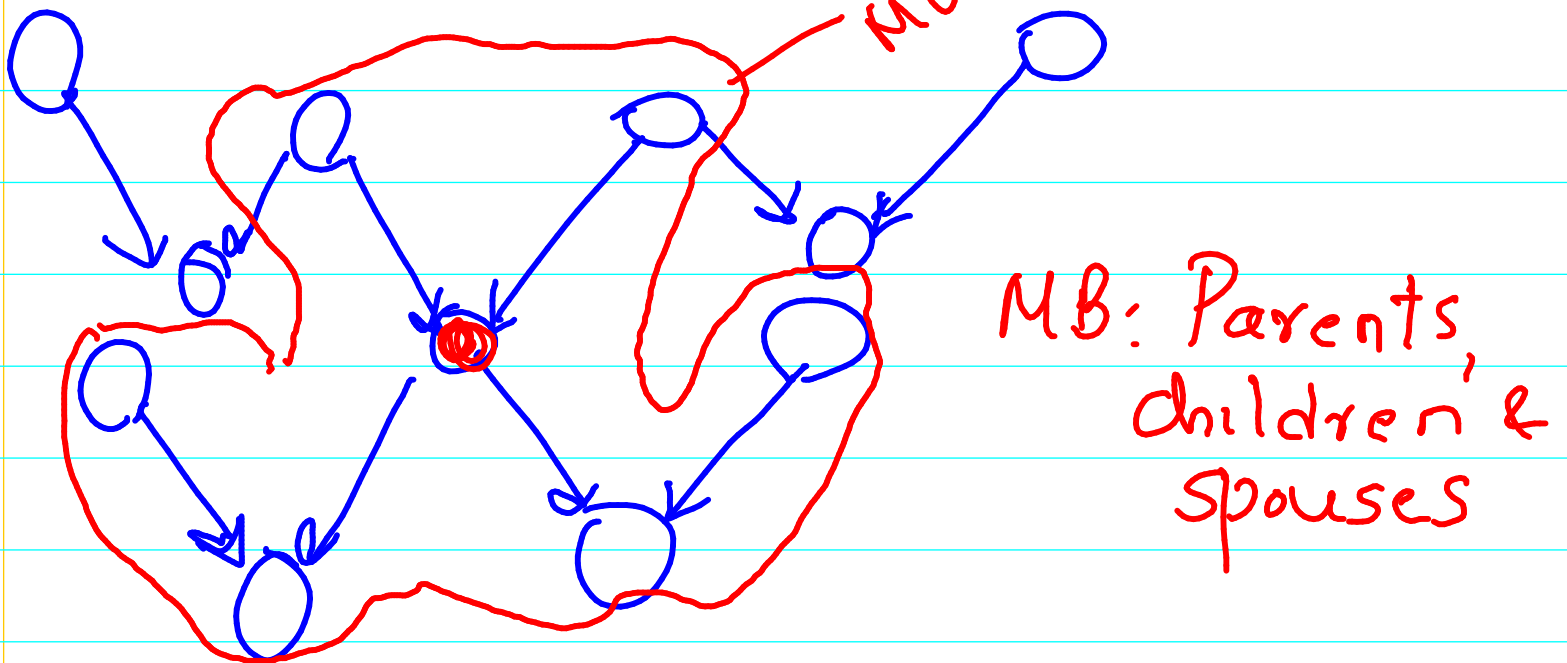
# Markov Blankets:

1) Undirected graph:

Set of nbrs of a node



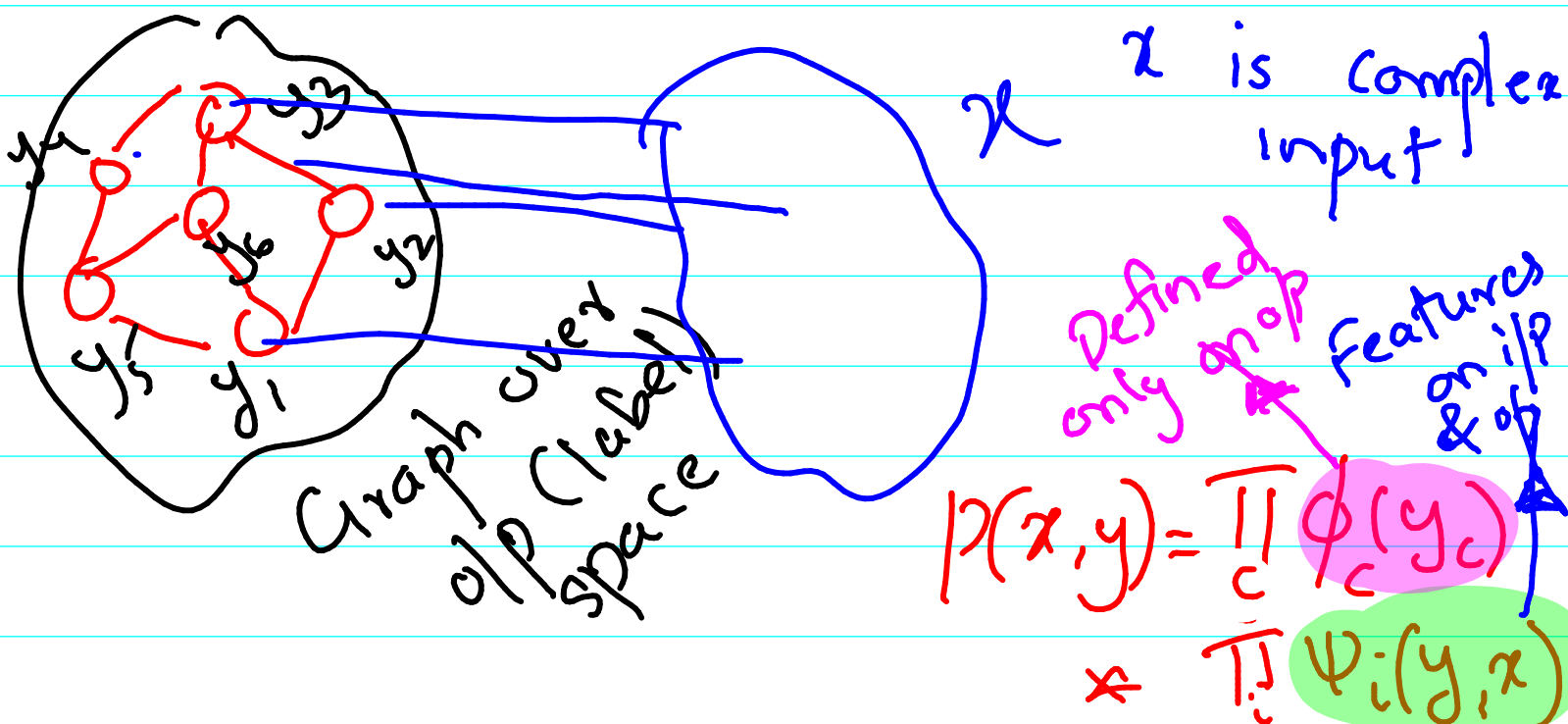
2) Directed graph:



Note: For linear & tree graphs, directed & undirected representations are equivalent

(eg: HMM can be treated as directed or undirected)

Markov Random fields



More on markov networks  
in next lecture

<http://www.cse.iitb.ac.in/~cs717/notes/classNotes/StructuredOutput/mmmn.pdf>