

In the last class we observed that whenever  $P[X=x] \neq 0$ , the distribution function  $F_X(x)$  is not continuous at  $x$ . Now we want to study such class of distribution functions which are discontinuous at countable number of points. Here goes the formal definition:

### DISCRETE RANDOM VARIABLE:

A random variable  $X$  is called a discrete random variable if ~~Pf~~ there exists a countable set  $E$  such that:

$$P[X \in E] = 1$$

In other words,  $P[X \notin E] = 0$ .

Let the set  $E$  be  $\{x_1, x_2, \dots\}$ . Now without loss of generality we can assume  $x_1 \leq x_2 \leq \dots$  and also assume  $P[X=x_i] \neq 0 \forall x_i \in E$ .

Now by the very defn. of discrete r.v. we have:  $\sum_{x_i \in E} P[X=x_i] = 1$ .

It is easy to see that the distribution function of  $X$  can now be written in terms of  $P[X=x_i]$  as follows:

$$F_X(x) = \sum_{\substack{x_i: x_i \leq x, \\ x_i \in E}} P[X=x_i]$$

This shows that given the values of  $P[X=x_i]$ , the distribution function gets uniquely determined. ①

Hence,  $P[X=x_i] = P[X \leq x_i] - P[X < x_i]$

$\downarrow$   $F_X(x_i)$                        $\downarrow$   $F_X(x_i^-) \rightarrow$  (the left limit)

Hence specifying  $P[X=x_i] \forall x_i \in E$  is equivalent to specifying the distribution function  $F_X(x)$  and vice-versa.

~~The~~ We give a name to the  $P[X=x_i]$  as probability mass function:

$$f_X(x) = \begin{cases} P[X=x_i] & \text{if } x=x_i \in E \\ 0 & \text{if } x \notin E \end{cases}$$

In case of discrete r.v. we always specify the prob. mass function (p.m.f.) i.e.  $f_X(x)$  instead of distribution function  $F_X(x)$ .

Now, the only constraints on  $f_X$  are as follows:

- (i)  $0 \leq f_X(x_i) \leq 1 \quad \forall x_i \in E$  ( $\because$  defn. of  $f_X$ )
  - (ii)  $\sum_{x_i \in E} f_X(x_i) = 1$  ( $\because P[X \in E] = 1$ )
- (I)

Recall that this is exactly what we did when we looked for "valid" probability functions on countable sets! (So we already know some eg. like geometric series etc. do the job)

We explore some special discrete r.v. now:

## (Discrete) Uniform R.V.

Our first eg. is as follows:

Consider the set  $E = \{1, 2, \dots, n\}$  & the pmf:  $f_X(i) = \frac{1}{n}, \forall i \in E$

It is easy to verify  $f_X$  is a valid p.m.f. ( $n$  is a parameter)

Now this can be applied to any situation where we know the outcomes are "equally likely". This basically "models" the classical probability. eg. coin toss, throwing die etc.

## Bernoulli R.V.

Consider the set  $E = \{0, 1\}$  & the pmf:  $f_X(1) = p, f_X(0) = 1-p$

Here  $0 \leq p \leq 1$  is a parameter. Again  $f_X$  satisfies (I) and hence is a valid p.m.f.

This r.v. models all random expts. with two outcomes. For eg. coin toss, manufacture of good/bad parts etc. Such expts. are known as Bernoulli trials (i.e. <sup>rand.</sup> expts. with two outcomes). Usually in a Bernoulli trial one of the two outcomes is called success<sup>(x=1)</sup> and the other failure (x=0). Hence prob. of success is  $p$ .

## Binomial R.V.

Consider the set  $E = \{0, 1, 2, \dots, n-1, n\}$  & the pmf:  $f_X(i) = \binom{n}{i} p^i (1-p)^{n-i}, \forall i \in E$

Here  $n \in \mathbb{N}$  &  $0 \leq p \leq 1$  are two parameters to the Binomial random variable. Now let's check if  $f_X$  is a p.m.f:

It is obvious that  $f_X(i) \geq 0, \forall i \in E$

So we need to verify if  $\sum_{i=0}^n \binom{n}{i} p^i (1-p)^{n-i} = 1$ . This is indeed true because  $\rightarrow = (p + (1-p))^n = 1^n = 1$ . Hence  $f_x$  is a valid p.m.f.

Binomial r.v. can be employed to "model" probability of 'k' successes in 'n' independent Bernoulli trials. Recall the defn. of Bernoulli trial: it is a rand. expt with two outcomes: success (prob. p) and failure (prob. 1-p). Now let ~~us~~ <sup>we</sup> denote ~~the~~ <sup>the i<sup>th</sup></sup> Bernoulli trial by  $(\Omega_i, \mathcal{F}_i, P_i)$ . Here  $\Omega_i = \{ \text{Success}(S), \text{Failure}(F) \}$ .  $P_i(S) = p$  &  $P_i(F) = 1-p$ .  $\forall i = 1$  to  $n$  Bernoulli trials.

Now consider the combined expt of all the n Bernoulli trials. The sample space of this is  $\Omega_1 \times \Omega_2 \times \dots \times \Omega_n$ . Now consider

this singleton ~~at~~ event of the combined expt.:  $\left\{ \underbrace{(S, S, \dots, S)}_k, \underbrace{(F, F, \dots, F)}_{n-k} \right\} = A$   
 In words this event is nothing but the event where first 'k' trials were a success & the remaining 'n-k' trials were failures.

Now consider the event: We want to calculate prob. of events in combined expt. using probabilities  $p_1, p_2, \dots, p_n$ .

$$A_1 = \{ (S, \omega_2, \omega_3, \dots, \omega_n) \mid \omega_2 \in \Omega_2, \omega_3 \in \Omega_3, \dots, \omega_n \in \Omega_n \}$$

In words, this event is the event of a success in 1st trial. Similarly define  $A_i$  for  $i = 1$  to  $n$ . Note that  $A_i$   $i = 1$  to  $k$  represent success in  $i^{\text{th}}$  trial.  $A_i$   $i = k+1$  to  $n$  " failures in  $i^{\text{th}}$  trial.

It is easy to see that  $A = A_1 \cap A_2 \cap \dots \cap A_n$

Now let P be a prob. function of the sample space  $\Omega_1 \times \Omega_2 \times \dots \times \Omega_n$  (4)

So,  $P(A) = P(A_1 \cap A_2 \cap \dots \cap A_n)$

$= P(A_1) P(A_2) \dots P(A_n) \rightarrow$  we assume each trial is independent of others so the event  $A_i$  are independent of each other

This is the assumption of Independent trials.

Now we take  $P(A_1) = P_1(S)$ ,  $P(A_2) = P_2(S)$  ... and no on  $P(A_n) = P_n(S)$

i.e. we construct the prob. in the combined exp. with  $\Omega = \Omega_1 \times \Omega_2 \times \dots \times \Omega_n$  such that it is "consistent" with the probabilities  $P_1, P_2, \dots, P_n$  in the individual trials!

~~Having mutual alignment~~

Hence we have  $P(A) = P(A_1 \cap A_2 \dots \cap A_n)$  Assumption of Independent trials

$= P(A_1) P(A_2) \dots P(A_n)$  Assumption of consistency

$= P_1(S) P_2(S) \dots P_k(S) P_{k+1}(F) \dots P_n(F)$

Assumption of identical Trials  $= p^k (1-p)^{n-k}$

Now we have that prob. of ~~k~~ first  $k$  trials a success & next ' $n-k$ ' trials failure  $= p^k (1-p)^{n-k}$ . Now actually prob. of any  $k$  trials success & remaining failures is again  $p^k (1-p)^{n-k}$ . But there are exactly  ${}^n C_k$  ways  $k$  successes can happen in ' $n$ ' trials.

Hence prob. of  $k$  successes in ' $n$ ' trials  $= p^k (1-p)^{n-k} + \dots + p^k (1-p)^{n-k}$

$= {}^n C_k p^k (1-p)^{n-k}$  5

Now let us ask a slightly different but related question: "what is prob. that the number of trials ~~that need to be done to see~~ <sup>for realizing</sup> the first success is 'k'." As we shall see below a geometric r.v. helps us ~~to do~~ this:  
 model

### Geometric R.V.

Consider the set  $E = \{1, 2, \dots\}$  i.e.  $E = \mathbb{N}$ . (Note that this is the first eg. for the countably infinite discrete r.v.). Define pmf as  $f_X(x_i) = p(1-p)^{x_i-1} \quad \forall x_i \in E$ . It is routine to verify this  $f_X$  is indeed a valid pmf.

This random variable models the trial at which the first success occurs in a sequence of  ~~Bernoulli~~ <sup>identical and independent</sup> Bernoulli trials. (i.i.B trials)

$X$  = trial at which the first success occurred

It is easy to see  $X$  can take values  $\{1, 2, \dots\}$  which is exactly the set  $E$  for geometric r.v. Also, using the ideas discussed in the previous section for analyzing i.i.B trials, we have:

$$P\{X=k\} = p(1-p)^{k-1}$$

Hence a geometric variable is suitable to model "trial at which first success occurs". Now, let us look at:

$$P\{X > m\} = 1 - P\{X \leq m\} = 1 - \sum_{i=1}^m p(1-p)^{i-1} = 1 - p \frac{1-(1-p)^m}{1-(1-p)} = (1-p)^m$$

$$\text{Also, } P\{X > k+m / X > k\} = \frac{P_X((k+m, \infty) / (k, \infty))}{P_X((k, \infty))} = \frac{P_X((k+m, \infty) \cap (k, \infty))}{P_X((k, \infty))}$$

This important observation that,  $P\{X > k+m / X > k\} = P\{X > m\}$  is called the

'memoryless' property. In words it says that prob. of achieving success after  $m$  steps is same immaterial of how many trials have been performed. (6)

In this lecture we will first complete our discussions on discrete r.v. by presenting the Poisson r.v. Then we will move on to continuous r.v. - their definition, examples and applications.

### POISSON R.V.

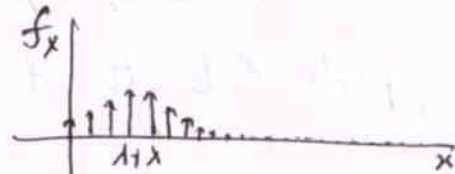
$E = \{0, 1, 2, \dots\}$ , the set of whole numbers.

pmf:  $f_x(x_i) = e^{-\lambda} \frac{\lambda^{x_i}}{x_i!}$   $\forall x_i \in E$ , where  $\lambda > 0$  is a parameter.

It's easy to verify  $f_x$  is non-negative &  $\sum_{x_i=0}^{\infty} e^{-\lambda} \left( \frac{\lambda^{x_i}}{x_i!} \right) = e^{-\lambda} \left( 1 + \lambda + \frac{\lambda^2}{2!} + \dots \right) = 1$

Hence  $f_x$  is indeed a valid pmf. Now let's plot this pmf. for that let's try to look at the ratio of pmf values at two consecutive numbers:

$$\frac{f_x(k+1)}{f_x(k)} = \frac{\lambda}{k+1}$$



In other words,  $f_x$  increases till  $\lambda-1$  & then decreases. This plot is similar to the binomial case; the difference being that this ~~is~~ <sup>extends</sup> to all (whole) numbers. The distribution function again is an (infinite) staircase of equal length steps by heights proportional to  $f_x$  values.

In fact, after the study of concept of convergence of r.v., one can show that the binomial distribution "converges" to the Poisson distribution in the case  $n \rightarrow \infty$ ,  $p \rightarrow 0$  such that  $np = \lambda$ ,

In other words,

$$\begin{array}{ccc} P[X_n = k] & & P[X_p = k] \\ \downarrow & & \downarrow \\ \binom{n}{k} p^k (1-p)^{n-k} & \xrightarrow[n_p = \lambda]{n \rightarrow \infty, p \rightarrow 0} & e^{-\lambda} \frac{\lambda^k}{k!} \end{array}$$

(no. trials large) (prob. of success low)

$X_n \rightarrow$  binomial r.v.  
 $X_p \rightarrow$  Poisson r.v.

Recall that Binomial r.v. can model 'no. successes in Bernoulli trials.'

Hence, by the above relation, we can say that the Poisson r.v. can be used to model 'no. of ~~occurrences~~ occurrences of a rare event in large no. of trials.'

eg: A person keeps buying lottery tickets. The no. times he wins a lottery follows Poisson distribution (why?)

eg: No. words written by IPL instructor which are perfectly legible: (on board of this notes)

→ Till now we have looked at random variable which took discrete values and had discontinuous distribution functions. Now let's turn our attention to r.v. whose distribution functions are continuous (infact absolutely conts.) Are we already discussed:

$$P[X \leq x] = P[X < x] + P[X = x]$$

$$\begin{array}{ccc} \downarrow & & \downarrow \\ F_x(x) & = & F_x(x^-) \Leftrightarrow P[X=x] = 0 \quad \forall x \in \mathbb{R}. \\ \text{(right limit)} & & \text{(left limit)} \end{array}$$

In other words, r.v. with continuous distribution functions cannot have  $P[X=x] \neq 0$  for any  $x \in \mathbb{R}$ ! Hence we cannot have a "pmf" function in this case. The idea is to have a prob. density function (pdf) instead ~~of~~ and finding area under the density function would give probabilities.

More formally we define continuous r.v. as follows:



# CONTINUOUS R.V.

A r.v.  $X$  is called a continuous r.v. if there exists a function  $f_X: \mathbb{R} \rightarrow \mathbb{R}$ , called the probability density function (pdf), such that:

$$P_X(B) = \int_B f_X(x) dx \quad \forall B \in \mathcal{B}$$

$\downarrow$  induced prob. function with r.v.  $X$        $\downarrow$  we know how to calculate integrals when  $B$  are intervals etc.       $\rightarrow$   $\sigma$ -algebra.

Here goes an intuition why  $f_X$  is called a pdf:

Suppose we consider  $B = (x - \epsilon/L, x + \epsilon/L)$  where  $\epsilon$  is tiny, i.e.  $B$  is a small interval around  $x$ . Then  $P_X((x - \epsilon/L, x + \epsilon/L)) = \int_{x - \epsilon/L}^{x + \epsilon/L} f_X(y) dy = \epsilon f_X(x)$

In other words  $f_X(x) = \frac{P_X((x - \epsilon/L, x + \epsilon/L))}{\epsilon}$  for  $\epsilon \rightarrow 0$ . ~~Here~~ Since  $f_X$  is ratio of prob. & length it is called as 'prob. density'.   
  $\downarrow$  since  $\epsilon$  is tiny  $f_X$  does not change.

Now,  $F_X(x) = P_X((-\infty, x]) = \int_{-\infty}^x f_X(y) dy$  (I)

In other words, given the p.d.f, the dist. func.  $F_X(x)$  is fixed. Functions like  $F_X$  which are expressible as integral over functions like  $f_X$  are known as absolutely continuous functions. Absolute continuity is a stricter condition than continuity. In fact, we even know that  $F_X$  is differentiable:

$$\frac{dF_X(x)}{dx} = f_X(x) \quad \forall x \text{ at which } f_X \text{ is continuous. (II)}$$

Now since one can obtain the dist. function  $F_X$  given  $f_X$  (pdf) and vice-versa, we characterize continuous r.v. using pdfs.

Lets look at some properties of the pdf:

Pdf ( $f_x$ ) satisfies:

(i) Non-negativity: i.e.  $f_x(x) \geq 0 \forall x \in \mathbb{R}$ . This follows from the monotonicity of  $F_x$ . Since  $F_x$  is area under  $f_x$ , there is no way the  $F_x$  (area) can monotonically increase if  $f_x < 0$ . Mathematically:  
 $x_1 \leq x_2 \Rightarrow F_x(x_2) - F_x(x_1) = P_x([x_1, x_2]) = \int_{x_1}^{x_2} f_x(y) dy \geq 0 \forall x_1 \leq x_2$   
 $\Rightarrow f_x(x) \geq 0 \forall x$ .

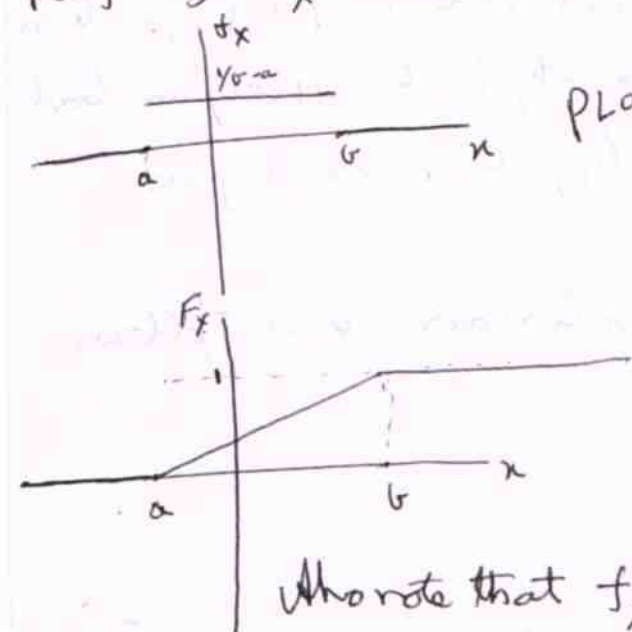
(ii) Unit-area: We have,  $1 = P_x(\mathbb{R}) = \int_{-\infty}^{\infty} f_x(x) dx$ . Hence the area under  $f_x$  must be unity.

Any function which satisfies these two conditions we called it a prob. density function (pdf). Let us look at some eg. of conts. r.v.

(conts.) Uniform R.V.

pdf:  $f_x(x) = \begin{cases} \frac{1}{b-a} & \forall x \in [a, b] \\ 0 & \forall x \notin [a, b] \end{cases}$ . Here  $a < b$  are two parameters.

It's trivial to check  $f_x$  is indeed a pdf. Now the plots of pdf &  $F_x$  are:



Note the relations (I), (II) from these plots. The points where  $F_x$  is not differentiable is exactly where  $f_x$  is discontinuous.

Observe that  $1/(b-a)$  can be  $> 1$ . So there is no reason to believe in general that  $f_x(x) \leq 1$ . (So  $f_x(x)$  need not be  $\leq 1$ )

Who note that  $f_x(a), f_x(b)$  ~~cannot be defined as any number~~ can be changed to arbitrary values without changing  $F_x$ !

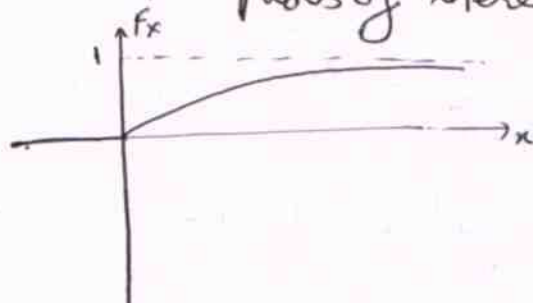
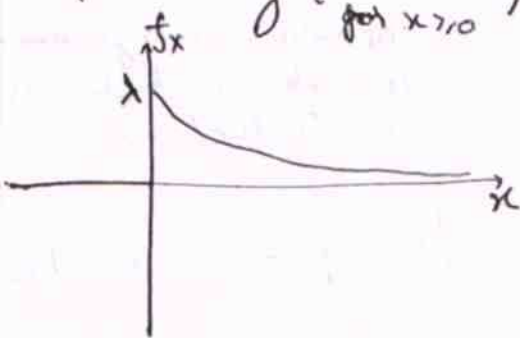
## Exponential R.V.

pdf:  $f_x(x) = \begin{cases} \lambda e^{-\lambda x} & x \geq 0 \\ 0 & x < 0 \end{cases}$   $\lambda > 0$  is a parameter

Again  $f_x(x) \geq 0$ . Also,  $\int_{-\infty}^{\infty} f_x(x) dx = \int_0^{\infty} \lambda e^{-\lambda x} dx = -e^{-\lambda x} \Big|_0^{\infty} = 1$ . Hence  $f_x(x)$  is a valid pdf.

Now,  $F_x(x) = \int_{-\infty}^x P_x((-\infty, x]) = \int_{-\infty}^x f_x(y) dy = \int_0^x \lambda e^{-\lambda y} dy = e^{-\lambda y} \Big|_0^x = 1 - e^{-\lambda x}$ .

$f_x(x)$  is an exponential decay function for  $x \geq 0$ , whereas  $F_x$  is a negative exp. decay (no convex) for  $x \geq 0$ . Here are the plots of these functions:



Now, similar to the geometric r.v. in discrete case, exponential r.v. satisfies the memory-less property:

TST  $P_x[X > x+y | X > y] = P[X > x] \quad \forall x, y \geq 0$ .

Proof:  $P[X > x] = 1 - F_x(x) = e^{-\lambda x} \quad \forall x \geq 0$ .

$$P[X > x+y | X > y] = \frac{P[X > x+y \cap X > y]}{P[X > y]} = \frac{P[X > x+y]}{P[X > y]} = \frac{e^{-\lambda(x+y)}}{e^{-\lambda y}} = e^{-\lambda x} = P[X > x]$$

→

One can show the converse also i.e. if  $X$  is a conts. r.v. which is non-negative and satisfies memory-less property then  $X$  MUST be exponential r.v.

Proof: From above proof we have that memory less property is same as:

$$P[X > x+y] = P[X > x] P[X > y] \quad \forall x, y \geq 0$$

Now use the fact that  $X$  is a r.v., this gives:

$$[1 - F_x(x+y)] = [1 - F_x(x)][1 - F_x(y)]$$

Note this does not say the events  $X > x, X > y$  are "independent" ⑤

Now call  $G_X(x) \equiv 1 - F_X(x)$ . We know that  $F_X(x)$  is a continuous function, hence  $G_X(x)$  is a conts. function which satisfies:

$$G_X(x+y) = G_X(x) G_X(y) \quad \forall x, y \geq 0. \quad \text{--- (1)}$$

Now,  $G_X\left(\frac{m}{n}\right) = G_X\left(\underbrace{\frac{1}{n} + \dots + \frac{1}{n}}_{m \text{ times}}\right) = G_X^n\left(\frac{1}{n}\right)$  ( $\because$  repeated application of (1))

Also, if  $m=n$ , we have  $G_X(1) = G_X^n\left(\frac{1}{n}\right) \Rightarrow G_X\left(\frac{1}{n}\right) = (G_X(1))^{1/n}$

Hence,  $G_X\left(\frac{m}{n}\right) = (G_X(1))^{m/n}$ .

So we proved that  $G_X$  is a power function for all rationals  $\frac{m}{n}$  ( $\geq 0$ ).  
By continuity of  $G_X$ ,  $G_X$  must be a power function for all reals ( $\geq 0$ )

$$\Rightarrow G_X(x) = (G_X(1))^x \quad \forall x \geq 0.$$

Now  $G_X(1) = P_X[X > 1]$ . Hence  $0 < G_X(1) < 1$ . Because of this

I can choose a  $\lambda > 0$  such that  $\lambda = -\log(G_X(1))$ .

$$\Rightarrow G_X(x) = e^{-\lambda x}, \quad \lambda > 0. \quad \forall x \geq 0.$$

$$\Rightarrow F_X(x) = 1 - e^{-\lambda x} \quad \forall x \geq 0 \quad (\lambda > 0). \text{ which is nothing but}$$

the distribution function of an exponential r.v. Hence proved.

Thus in non-negative conts. r.v., memory-less property is unique to Exponential r.v. Now, ~~we can~~ <sup>encouraged by this</sup>, we can apply exp. r.v. to model all cases (conts. versions) for which geometric r.v. was applicable. (Recall that geometric r.v. also is the only memoryless ~~discrete~~ <sup>discrete</sup> r.v.)

$\therefore$  Exponential r.v. can model waiting time for a successful event.

However care needs to be taken (as in case of geometric r.v.) that the physical situation make not support the memory-less property.

Ex. Suppose we model the time to failure of a T.V. by an exponential random variable. Then we will be saying an absurd ~~the~~ statement as follows:

"Let prob. of <sup>(new)</sup> T.V. working for 10 yrs. be 0.7. Then given that it already worked for 10 years, the prob. that it works for 10 more yrs. is again 0.7"

pdf:  $f_X(x) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2} \quad x \in \mathbb{R}$

Normal R.V.

Appears in many many applications. And needs no introduction.

$f_X$  is indeed non-negative. To show that  $f_X$  is a valid pdf, we need to show that:

$$I \equiv \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-x^2/2} dx = 1.$$

Proof: Consider the integral,

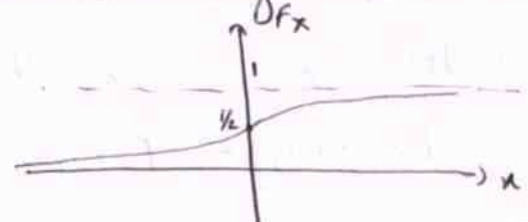
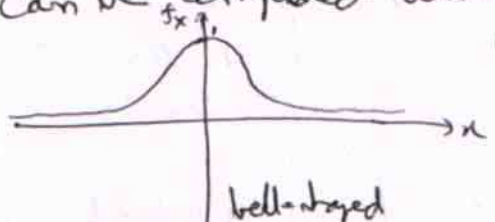
$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{1}{2\pi} e^{-(x^2+y^2)/2} dx dy = \int_{-\infty}^{\infty} \left[ \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-x^2/2} dx \right] \frac{1}{\sqrt{2\pi}} e^{-y^2/2} dy = I^2.$$

Now transform the integral in  $I^2$  using polar coordinates:

$$I^2 = \int_0^{2\pi} \int_0^{\infty} e^{-r^2/2} r dr \frac{1}{2\pi} d\theta = \int_0^{\infty} e^{-r^2/2} dr = -e^{-r^2/2} \Big|_0^{\infty} = 1$$

$\Rightarrow I = 1$  ~~because~~ ( $I \neq -1$  because  $I$  is integral of non-negative function).

Unfortunately  $F_X(x) = \int_{-\infty}^x \frac{1}{\sqrt{2\pi}} e^{-t^2/2} dt$  cannot be computed in closed form. However can be computed using numerical integration. Here are the graphs:



Consider the following random experiment: "Choose a random circle centered at origin and having radius between 0 & 1. Assume all radii are equally likely". Let the probability space for this expt. be  $\mathcal{P} = (\Omega, \mathcal{F}, P)$ .

Now, consider a random variable "R" defined on this probability space, which in words is "radius of the circle". In other words, R is a r.v. following uniform distribution between  $[0, 1]$ .

Consider another mapping from  $\mathcal{R}$  onto  $\mathcal{R}$ , which is "A": "area of the circle". ~~In this~~ Now Note that for each circle  $\omega \in \mathcal{R}$ , we have:

$$A(\omega) = \pi(R(\omega))^2.$$

~~Getting~~ Defining a new function  $g: \mathcal{R} \rightarrow \mathcal{R}$  such that  $g(x) = \pi x^2$ , it is easy to see that  $A = g \circ R$ , where 'o' denotes composition of functions. In other words,  $A(\omega) = g(R(\omega)) = \pi(R(\omega))^2$   $\forall \omega \in \mathcal{R}$ . We denote this as  $A = g(R)$  (abuse of notation?)

Now obvious questions are:

- (i) Given that R is a r.v., is  $A = g(R)$  ~~also~~ a "valid" r.v.?
- (ii) If no, what is the distribution of the new random variable A, which is defined in terms of ~~a r.v.~~ <sup>another</sup> r.v. R? (In particular, what is the distribution of the r.v. "Area of circle", given that "R: radius of circle" follows uniform distribution in  $[0, 1]$ ?)

In this lecture, we try to answer the above questions and in general, study the notion of "functions of R.V.s".

How, lets answer question (i):

The only thing we need to check is whether:

$$A^{-1}(B) \in \mathcal{F} \quad \forall B \in \mathcal{B}$$

$$\Leftrightarrow (g \circ R)^{-1}(B) \in \mathcal{F} \quad \forall B \in \mathcal{B}$$

$$\Leftrightarrow R^{-1}(g^{-1}(B)) \in \mathcal{F} \quad \forall B \in \mathcal{B}$$

Now suppose  $g^{-1}(B) \in \mathcal{B} \quad \forall B \in \mathcal{B}$ , then since  $R^{-1}(B) \in \mathcal{B} \quad \forall B \in \mathcal{B}$ , by the very fact that  $R$  is a n.v., we have that

(I)  $g^{-1}(B) \in \mathcal{B} \quad \forall B \in \mathcal{B}$  is sufficient for  $A$  being a valid n.v.

Now  $g: \mathbb{R} \rightarrow \mathbb{R}$ . One can show (not in this class) that if  $g$  is conts. then the above contd. is meet. In other words if  $g$  is conts. then  $A$  is assured to be n.v.

(In our case,  $g(x) = \pi x^2$ , so indeed  $A$  is a n.v.)  
Who note that contd. (I) itself implies that  $g$  is a valid n.v. with initial probability space as  $\mathbb{P}_{\mathbb{R}} = (\mathbb{R}, \mathcal{B}, P_{\mathbb{R}})$ !

So now we exploit this fact and attempt defining prob. wrt.  $A$  using  $P_{\mathbb{R}}$  (name things as we did in case of defining n.v.!) <sup>while</sup>

We define  $P_A(B) = P_{\mathbb{R}}(g^{-1}(B)) \quad \forall B \in \mathcal{B}$

~~It is easy to check~~ <sup>Note</sup> that  $P_A$  is a valid prob. function because  $g$  is itself a n.v. on  $\mathbb{P}_{\mathbb{R}}$  (as noted above).

To give an overall picture:

$$P = (\mathcal{R}, \mathcal{F}, P)$$

→ something like picking circles at random

$$P_X = (\mathcal{R}, \mathcal{B}, P_X)$$

→ X is something like "radius of circle"  
X is a r.v.

$$P_Y = (\mathcal{R}, \mathcal{B}, P_Y)$$

→ Y is something like "area of circle"  
g is like  $\pi r^2$   
g relates Y & X thru:  $Y = g(X)$ .

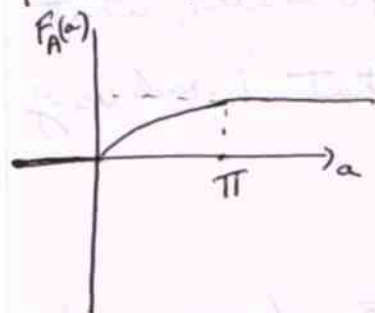
and the idea is to compute  $P_Y(B) \equiv P_X(g^{-1}(B))$  → this is already known!

Now lets answer the question "what is the distribution of "Area of circle" given radius follows uniform dist. between  $[0, 1]$ ?"

Let dist. function of A be  $F_A$  & that of R be  $F_R$ .

$$\begin{aligned} F_A(a) &= P[A \leq a] = P[g(R) \leq a] \\ &= P[\pi R^2 \leq a] \quad (= P_{\mathcal{R}}\{r \in \mathcal{R} \mid \pi r^2 \leq a\}) \\ &= P\left[-\frac{\sqrt{a}}{\sqrt{\pi}} \leq R \leq \frac{\sqrt{a}}{\sqrt{\pi}}\right] \quad a \geq 0 \end{aligned}$$

Here's the plot:

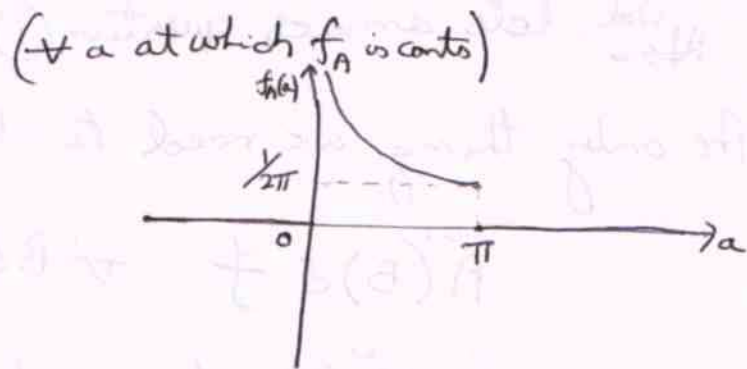


$$= \begin{cases} 0 & a < 0 \\ F_R\left(\frac{\sqrt{a}}{\sqrt{\pi}}\right) & a \geq 0 \quad (\because R \geq 0) \\ 0 & a < 0 \\ 0 & a < 0 \\ \frac{\sqrt{a}}{\sqrt{\pi}} & 0 \leq a < \pi \\ 1 & a \geq \pi \end{cases}$$



Now  $f_A(a) = \frac{dF_A(a)}{da}$

$$= \begin{cases} 0 & a < 0 \\ \frac{1}{2\sqrt{\pi a}} & 0 \leq a < \pi \\ 0 & a \geq \pi \end{cases}$$



Note that the distribution of "A: area of wheel" is nowhere near uniform distribution. Also, from the pdf it looks like the values near zero are "preferred" i.e. have more prob. density. This is also intuitive as R is uniform & more importantly  $\leq 1$ ! (By now, the Bertrand's Paradox also must be resolved!)

Note that the only trick is in writing the dist. function of  $Y=g(X)$  in terms of dist. function of X. The above example would have showed that ~~the~~ care in doing this really depends on ~~how~~ how "simple" is  $g^{-1}((-\infty, x])$  for any  $x \in \mathbb{R}$ .

This immediately hints on considering ~~g~~ <sup>cases</sup> where ~~g~~ where 'g' is monotonic; because if g is monotonic, then: ~~eq~~

$$\begin{aligned} g(x) \leq a & \\ \Leftrightarrow \begin{cases} x \leq g^{-1}(a) & \text{if } g \uparrow \text{ (monotonically increasing } g) \\ x \geq g^{-1}(a) & \text{if } g \downarrow \text{ ( " decreasing } g) \end{cases} \end{aligned}$$

The following result is immediate:

Result 1: If X is a r.v & g is conts, monotonic, then ~~the following~~ <sup>the following</sup> is true for the r.v  $Y=g(X)$ :

$$F_Y(y) = P[Y \leq y] = P[g(X) \leq y] = \begin{cases} P[X \leq g^{-1}(y)] & \text{if } g \uparrow \\ P[X \geq g^{-1}(y)] & \text{if } g \downarrow \end{cases}$$

$$F_Y(y) = \begin{cases} F_X(g'(y)) & \text{if } y \downarrow \\ 1 - F_X(g'(y)) + P[X = g'(y)] & \text{if } y \uparrow \end{cases}$$

Also, the following result is true:

Result 2: Suppose further that  $g$  is diff. &  $X$  is conts. r.v., then:

$$f_Y(y) = \frac{dF_Y(y)}{dy} \quad (+ y \text{ at which } f_Y \text{ is conts.})$$

$$= \begin{cases} \frac{d}{dy} F_X(g'(y)) & \text{if } y \uparrow \\ -\frac{d}{dy} F_X(g'(y)) & \text{if } y \downarrow \end{cases} \quad \begin{matrix} (\because X \text{ is conts.}) \\ P[X = g'(y)] = 0 \end{matrix}$$

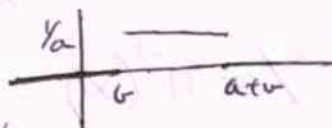
$$= \begin{cases} f_X(g'(y)) \frac{d g'(y)}{dy} & \text{if } y \uparrow \\ -f_X(g'(y)) \frac{d g'(y)}{dy} & \text{if } y \downarrow \end{cases} \quad (\because \text{chain rule})$$

$$f_Y(y) = f_X(g'(y)) \left| \frac{d g'(y)}{dy} \right|$$

One can apply these results to various  $g'$ . Let us take the case of  $g(x) = ax + b$  ( $a > 0$ ), which is a monotonically increasing diff. function.

$$Y = aX + b$$

(i)  $X$  is uniform between  $(0, 1)$   $\rightarrow f_Y(y) = f_X\left(\frac{y-b}{a}\right) \frac{1}{a} = \begin{cases} 0 & y < b \\ 1/a & b \leq y \leq a+b \\ 1 & y > a+b \end{cases}$



Again models "equally likely". So we can call  $Y$  as uniform distribution between  $[b, a+b]$ .

(ii)  $g)$   $X$  is Normal, then  $f_Y(y) = \frac{1}{a\sqrt{2\pi}} e^{-\frac{(y-b)^2}{2a^2}}$

(iii)  $X$  is uniform between  $[0, 1]$  &  $g = H^{-1}$ , where  $H$  is any distribution function of a continuous r.v.  
 Note that, indeed  $g$  is monotonically increasing (since  $H$  is dist. func.) & ~~and is not differentiable (at most points)~~ and  $g$  is also conts.

$$\text{From result 1, } F_Y(y) = F_X(g^{-1}(y)) = F_X(H(y)) = H(y) \quad \boxed{Y = H^{-1}(X)}$$

In other words, if  $Y = H^{-1}(X)$  where  $H$  is a dist. func., then dist. of  $Y$  is itself  $H$ ! This is way of generating <sup>our</sup> random ~~numbers~~ <sup>variables</sup> from a uniform r.v. itself. This <sup>can be</sup> used to generate random numbers with diff. distributions using random numbers from uniform distribution. This technique of random number generation is called "~~Gamma~~ Prob. Inverse" Technique.

However it may not be useful in practice always because  $H^{-1}$  may not be easily computable (for eg. for Normal dist.)

Here is an eg. where  $H^{-1}$  is has closed form solution:

Consider  $H$  as dist. of exponential r.v.

$$H(y) = 1 - e^{-\lambda y} \quad y \geq 0 \quad (\lambda > 0).$$

$$\text{Now } H^{-1}(x) = \frac{-1}{\lambda} \log(1-x)$$

$\therefore$  If one takes  $Y = H^{-1}(X) = \frac{-1}{\lambda} \log(1-X)$  &  $X$  is uniform between  $[0, 1]$ ,

$$\text{then } F_Y(y) = H(y) = 1 - e^{-\lambda y} \quad !$$

This lecture introduces the concept of expectation of a r.v. or expected value or mean value of a r.v. It is denoted as  $E[X]$  for a r.v.  $X$ .

Intuition: We know that <sup>independent</sup> one cannot predict which exact value a random variable takes. However ~~in practice one usually~~ talks about ~~one~~ <sup>one</sup> can talk about an average value or an expected value for the r.v. The ~~notion~~ <sup>concept</sup> of expected value will help us to relate to notions like "if we toss a <sup>fair</sup> coin repeatedly on an average we will see heads for half no. times" etc.

Here goes the definition:

$$E[X] = \sum_{x_i \in E} x_i f_x(x_i) \quad (\text{Discrete case})$$

$$= \int_{-\infty}^{\infty} x f_x(x) dx \quad (\text{Conts. case})$$

(I)

Note that,  $E[X]$  is <sup>either</sup> a series sum (probably infinite sum) of numbers which are not necessarily +ve or an improper integral over functions which are " " +ve. ~~One's analytical knowledge~~ In such cases, the value of sum/improper integral might depend on the way we compute them. For eg. consider the Cauchy ~~dist~~ r.v. defined in Assignment problem (7a). There we showed that if one computes  $\int_{-\infty}^{\infty} x f_x(x) dx$  by splitting it into  $\int_{-\infty}^0 x f_x(x) dx + \int_0^{\infty} x f_x(x) dx$ , then the value is undefined. Whereas if we compute it taking  $\int_{-\infty}^{\infty} x f_x(x) dx = \lim_{a \rightarrow \infty} \int_{-a}^a x f_x(x) dx = 0$ .

Hence one additionally puts the condition that  $E[X]$  is defined

(1)

if the corresponding sum/integral is absolutely convergent.

In other words, if  $\sum_{x_i \in E} |x_i| f_X(x_i)$  converges then  $E[X] = \sum_{x_i \in E} x_i f_X(x_i)$   
if  $\int_{-\infty}^{\infty} |x| f_X(x) dx$  converges then  $E[X] = \int_{-\infty}^{\infty} x f_X(x) dx$ .

Once a sum/integral is absolutely convergent many properties satisfied by "usual" sums/integrals also get satisfied. We will indicate these as and when they are used.

eg: Consider  $f_X(x) = \frac{1}{x^2}$ ,  $x \geq 1$ .

$$\text{Here } \int_{-\infty}^{\infty} x f_X(x) dx = \int_{-1}^{\infty} \frac{1}{x} dx = \infty.$$

In this case the improper integral is defined and is equal to  $\infty$  (unlike the case of Cauchy r.v., where integral itself was undefined!) However we may choose to consider whether to include the case  $E[X] = \infty$  as "well-defined" or not. For the purposes of this class we can choose  $E[X] = \infty$  as being "well-defined".

It is a straight-forward exercise to show that: (pls. do this exercise)

- (i)  $E[X] = np$  for binomial r.v. (iv)  $E[X] = 1/2$  for Uniform  $(0,1)$   
(ii)  $E[X] = 1/p$  for geometric r.v. (v)  $E[X] = 1/\lambda$  for exponential  
(iii)  $E[X] = \lambda$  for Poisson r.v. (vi)  $E[X] = 0$  for Normal r.v.

In all cases, note the intuition behind each value: (let success prob. be  $p$ )

- (i) Avg. no. of success in  $n$  trials is  $np$  (iv) Center of gravity of uniform rod is at midpoint  
(ii) Avg. no. trials needed for a success is  $1/p$  (v) ~~Avg. waiting time~~  $\lambda$  is the success rate  
(iii)  $\lambda$  is the avg. no. successes (vi) avg. error in measurements are zero. (2)

Now say  $Y = g(X)$ . One way to compute  $E[Y]$  is to use the defn (I) after computing the pmf/pdf of  $Y$ . Assignment prob. 9(G) shows this can be tedious (and unnecessary).

One can directly compute  $E[Y]$  using the distr. of  $X$  itself:

Theorem: If  $X$  is ~~discrete~~ discrete,  ~~$E[g(X)] = \sum_{x_i \in E} g(x_i) f_X(x_i)$~~

$$X \text{ is conts, } E[g(X)] = \int_{-\infty}^{\infty} g(x) f_X(x) dx$$

The proof is simple in the discrete case:

$$E[Y] = E[g(X)] = P \sum_{y_i} y_i f_X(y_i) \quad (\text{let } y_i \text{ be the values } Y \text{ takes on})$$

$$= \sum_{y_i} y_i P[g(X) = y_i]$$

$$= \sum_{y_i} y_i \sum_{x_i: g(x_i) = y_i} P[X = x_i]$$

$$= \sum_{y_i} \sum_{x_i: g(x_i) = y_i} g(x_i) \cancel{P[X = x_i]}^{f_X(x_i)}$$

$$= \sum_{x_i} g(x_i) f_X(x_i)$$

∴ We assume  $E[g(X)]$  whenever defined, the sum is absolutely convergent so order in which summation is done, does not matter!

Properties of  $E[X]$ : (we show them for conts r.v. but also true for discrete r.v.)

①  $E$  is a linear operator:  $E[aX + b] = aE[X] + b$

$$E[aX + b] = \int_{-\infty}^{\infty} (ax + b) f_X(x) dx = a \int_{-\infty}^{\infty} x f_X(x) dx + b \int_{-\infty}^{\infty} f_X(x) dx = aE[X] + b$$

$\underbrace{\int_{-\infty}^{\infty} (ax + b) f_X(x) dx}_{\text{by above thm.}} \quad \underbrace{\int_{-\infty}^{\infty} x f_X(x) dx}_{\substack{\text{abs. convergence of} \\ \text{improper integral \&} \\ \text{integral is linear} \\ \text{operator}}} \quad \underbrace{\int_{-\infty}^{\infty} f_X(x) dx}_{E[X]} \quad \underbrace{\int_{-\infty}^{\infty} f_X(x) dx}_1$

$$② \quad L \leq X \leq U \Rightarrow L \leq E[X] \leq U$$

$$P[L \leq X \leq U] = 1$$

Proof of

$$X \leq U \Rightarrow E[X] \leq U :$$

$$E[X] = \int_{-\infty}^{\infty} x f_X(x) dx \leq \int_{-\infty}^{\infty} U f_X(x) dx = U$$

abs. conv. of improper integral  
& monotonicity of integral  
prop.

||| by  $L \leq X \Rightarrow L \leq E[X]$ .  
here  $L \leq X \leq U \Rightarrow L \leq E[X] \leq U$   
Now its easy to prove:  
 $P[L \leq X \leq U] = 1 \Rightarrow L \leq E[X] \leq U$   
X is absolutely between [L, U]

③ "The best (optimal) constant value approximation of a r.v. X which minimizes the average squared error" in approximation is  $E[X]$

In other words  $E[X] = \underset{c}{\operatorname{argmin}} E[(X-c)^2]$

Proof  $\underset{c}{\operatorname{argmin}} E[(X-c)^2] = \underset{c}{\operatorname{argmin}} E[X^2 - 2cX + c^2]$   
 $= \underset{c}{\operatorname{argmin}} E[X^2] - 2cE[X] + c^2$   
 $= \underset{c}{\operatorname{argmin}} (c - E[X])^2 + E[X^2] - (E[X])^2$   
 $= E[X]$

repeated application of linearity property of E  
denoted by

Now, the minimized error is called as variance of X  $\hat{=}$   $\operatorname{var}(X)$ .

i.e.  $\operatorname{var}(X) = \min_c E[(X - \hat{E[X]})^2] = E[(X - E[X])^2]$   
 $= E[X^2] - (E[X])^2$  } by above proof

Now one can compute  $\operatorname{var}(X)$  of various r.v.s discussed in this course:

- i)  $\operatorname{var}(X) = np(1-p)$  for binomial
- ii)  $\operatorname{var}(X) = \frac{1-p}{p^2}$  for geometric
- iii)  $\operatorname{var}(X) = \lambda$  for Poisson
- iv)  $\operatorname{var}(X) = 1/3$  for U-jm [0,1]
- v)  $\operatorname{var}(X) = 1/\lambda^2$  for exponential r.v.
- vi)  $\operatorname{var}(X) = 1$  for Normal r.v.

## Properties of var(X):

① By the very definition of  $\text{var}(X)$  it is  $E$  of a non-negative RV (which is  $(X - E[X])^2$ ). Hence  $\text{var}(X) \geq 0$ .

$$\text{Now, } \text{var}(X) = E[(X - E[X])^2] = E[X^2] - (E[X])^2 \geq 0$$

$$\Rightarrow \underline{E[X^2] \geq (E[X])^2} \quad \text{--- (A)}$$

This is a very important inequality and is a specific case of the following inequality:

$$\underline{E[g(X)] \geq g(E[X])} \quad \forall g \text{ convex}$$

which is known as the Jensen's inequality. ( $g(x) = x^2$ )

(fundamental inequalities like AM  $\geq$  GM are special cases of this inequality)

$$\textcircled{2} \text{ var}(X+Y) = E[(X+Y - E[X+Y])^2] = E[(X - E[X])^2] = \text{var}(X)$$

$$\textcircled{3} \text{ var}(aX) = E[(aX - E[aX])^2] = E[a^2(X - E[X])^2] = a^2 \text{var}(X)$$

Variance is not a linear operator

Now let  $Y = \sigma X + \mu$  where  $X$  is a Normal RV. ( $\sigma, \mu$  are some numbers)

$$E[Y] = E[\sigma X + \mu] = \sigma E[X] + \mu = \mu \quad (\because E[X] = 0)$$

$$\text{var}(Y) = \text{var}(\sigma X + \mu) = \text{var}(\sigma X) = \sigma^2 \text{var}(X) = \sigma^2 \quad (\because \text{var}(X) = 1)$$

$$\text{We also know, } f_Y(y) = \frac{1}{\sqrt{2\pi} \sigma} e^{-\frac{(y-\mu)^2}{2\sigma^2}} \quad X \in \mathbb{R}.$$

This is our new defn of Normal (Gaussian) RV. with mean  $\mu$  & variance  $\sigma^2$ .

We call the case  $\mu = 0$  &  $\sigma^2 = 1$  as std. Normal RV.



Median of a r.v. is that number for which  $P\{X \leq M\} = \frac{1}{2}$ .

Assignment problem shows that

$$M = \underset{c}{\operatorname{argmin}} E[|X - c|]$$

In other words median is that value that minimizes the absolute error in approximating a r.v. by a constant.

Mode of a r.v. is the "most frequently taken value" of a r.v.

Let Mode of  $X$  be  $m$ . Mathematically,

$$m = \underset{c}{\operatorname{argmin}} E[1_{\{X \neq c\}}].$$

$$1_{\{X \neq c\}} = \begin{cases} 1 & \text{if } X \neq c \\ 0 & \text{if } X = c \end{cases}$$

mode minimizes the average number of times  $X$  does not take its value. In other words, maximizes the avg. no. times  $X$  takes the particular value.

$$\text{Now, } E[1_{\{X \neq c\}}] = 1 P[X \neq c] + 0 P[X = c] = P[X \neq c]$$

In discrete case,

$$m = \underset{c}{\operatorname{argmin}} P[X \neq c] = \underset{c}{\operatorname{argmax}} P[X = c]$$

i.e. Mode is the value with highest prob. of occurring.

Analogously for the conts. case we have  $m = \underset{c}{\operatorname{argmax}} f_X(c)$ .

For eg. std. Normal r.v. is "Unimodal" with 'm = 0'.  
(has one  $\operatorname{max} f_X(c)$ )

Each such peak in pdf/pmf is called mode (loosely).

Mean, median need not be values taken by  $X$ , whereas mode must be a value taken by  $X$ .

This lecture completes our discussion on single r.v.s by discussing concepts of generic moments, moment generating function and few important inequalities like Jensen's, Markov and Chebyshev's inequalities

### Moments & Moment Generating function

Encouraged by the relations of mean & variance etc. we now define some higher order moments of r.v. as follows:

$E[X^n]$  is called the  $n^{\text{th}}$  moment of  $X$  (1st moment is mean (center of gravity), second " is ~~moment~~ moment of inertia etc.)

$E[(X - E[X])^n]$  is called the  $n^{\text{th}}$  central moment of  $X$  ( $n=2$  is variance (central moment of inertia etc.))

$E[(X - a)^n]$  is the  $n^{\text{th}}$  generalized moment of  $X$  about 'a' (eg. moment of inertia abt some axis)

We can define the absolute value versions of these:

$E[|X|^n] \rightarrow n^{\text{th}}$  absolute moment

$E[|X - E[X]|^n] \rightarrow n^{\text{th}}$  absolute central moment

$E[|X - a|^n] \rightarrow n^{\text{th}}$  absolute moment about 'a'. and so on...

Now consider a function  $M_X$  defined as follows:

$$\underline{M_X(s) = E[e^{sX}]}$$

This function is known as the moment generating function (wherever it exists!)

Assuming  $E[e^{sX}]$  exists, (eg. of conts. case:)

$$\begin{aligned} M_X(s) &= \int_{-\infty}^{\infty} e^{sx} f_X(x) dx = \int_{-\infty}^{\infty} \left(1 + sx + \frac{s^2 x^2}{2!} + \dots\right) f_X(x) dx \quad \left. \begin{array}{l} \text{because of} \\ \text{abs. convergence of} \\ E[e^{sX}] \end{array} \right\} \\ &= \int_{-\infty}^{\infty} f_X(x) dx + s \int_{-\infty}^{\infty} x f_X(x) dx + \frac{s^2}{2!} \int_{-\infty}^{\infty} x^2 f_X(x) dx + \dots \end{aligned}$$

$$\Rightarrow M_X(s) = 1 + sE\{X\} + \frac{s^2}{2!} E\{X^2\} + \dots + \frac{s^n}{n!} E\{X^n\} + \dots \quad (2)$$

(This is why it is called as moment generating function!)

Also it is easy to see that  $\left. \frac{d}{ds} M_X(s) \right|_{s=0} = E\{X\}$

$$\left. \frac{d^2}{ds^2} M_X(s) \right|_{s=0} = E\{X^2\} \text{ and so on...}$$

In general,  $\left. \frac{d^n}{ds^n} M_X(s) \right|_{s=0} = E\{X^n\}$ .

In other words, mgf is a Maclaurin series with diff. given by

In general, mgf may not exist (for eg. take case of Cauchy distribution where we know first moment itself doesn't exist!). But whenever it exists, by the above relations all moments exist (and are finite).

However, the converse statement that if all moments exist then the mgf also exists may not be true in general.

(Take the log Normal dist defined as  $X \sim e^X$  where  $X$  is std. Normal and try!)  
 (You will notice that all moments exist but mgf does not.)

Let's compute mgf for Poisson r.v.:

$$M_X(s) = E\{e^{sX}\} = \sum_{k=0}^{\infty} e^{sk} e^{-\lambda} \frac{\lambda^k}{k!} = e^{-\lambda} \sum_{k=0}^{\infty} \frac{(e^s \lambda)^k}{k!} = e^{-\lambda} e^{e^s \lambda} = e^{e^s \lambda - \lambda}$$

mgf for std. Normal r.v.:

$$M_X(s) = E\{e^{sX}\} = \int_{-\infty}^{\infty} e^{sx} \frac{1}{\sqrt{2\pi}} e^{-x^2/2} dx = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{\frac{s^2}{2} - \frac{(s-x)^2}{2}} dx = \frac{e^{s^2/2}}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-t^2/2} dt$$

Completing quadratic

$$t = s - x = e^{-t^2/2}$$

$$\therefore M_X(s) = e^{s^2/2}$$

for std. Normal

$$\left( \because \int_{-\infty}^{\infty} \frac{e^{-t^2/2}}{\sqrt{2\pi}} dt = 1 \right)$$

mgf for Normal r.v.:  $Y = \sigma X + \mu$

$$M_Y(s) = E[e^{sY}] = E[e^{s(\sigma X + \mu)}] = E[e^{s\sigma X}] e^{s\mu} = e^{\frac{\sigma^2 s^2}{2}} e^{s\mu} = e^{s\mu + \frac{1}{2} s^2 \sigma^2}$$

$$\Rightarrow \boxed{M_Y(s) = e^{s\mu + \frac{1}{2} s^2 \sigma^2}} \quad \textcircled{I}$$

mgf of std. Normal

Apart from fact that mgf "generates" moments, there is an important application of it: mgf also characterize r.v! In other

words if somebody ~~proves~~ proves/asserts that a certain claim r.v has mgf for eg as  $e^{s\mu + \frac{1}{2} s^2 \sigma^2}$ , then certainly that claim r.v must be a Normal r.v.

Intuitively, here's the reason why mgf characterizes a r.v:

Take  $s = j\omega$  then mgf is nothing but the Fourier transform of  $f_X(x)$ !  $\rightarrow M_X(j\omega) = E[e^{j\omega X}] = \int_{-\infty}^{\infty} e^{j\omega x} f_X(x) dx$ . Hence characterizing  $f_X$  is equivalent to characterizing mgf's ]

Let's calculate  $n^{th}$  moment of a log-Normal r.v:  $Y = e^X$ ,  $X$  is Normal r.v.

$$E\{Y^n\} = E\{(e^X)^n\} = E\{e^{nX}\} = e^{n\mu + \frac{1}{2} n^2 \sigma^2}$$

by  $\textcircled{I}$

This shows that log-Normal has all moments! (but as said earlier doesn't have an mgf)

Jensen's Inequality

$$E[f(X)] \geq f(E[X]) \quad \text{for } X, f \text{ convex on } \mathbb{R}.$$

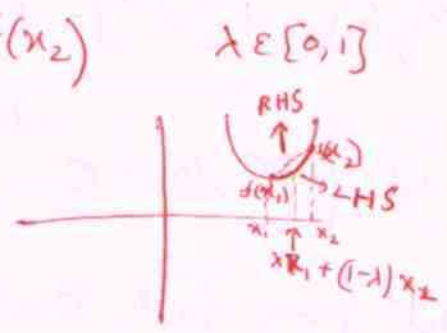
In assignment we saw a lengthy and restricted proof of this inequality following from the very defn. of a convex function. Now let's look at diff characterizations of a convex function which leads to a simple proof.

# Characterization of convex functions

→  $f(\lambda x_1 + (1-\lambda)x_2) \leq \lambda f(x_1) + (1-\lambda)f(x_2)$

This is the definition.

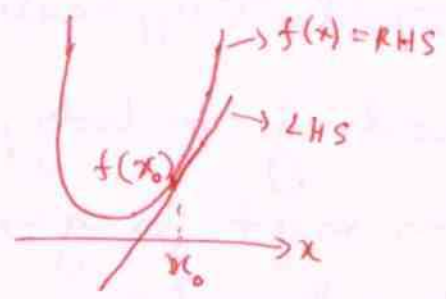
intuition →



→  $f(x) \geq f(x_0) + \frac{df(x_0)}{dx}(x-x_0)$

In words, the linear approx. at  $x_0$  always under-estimates the function

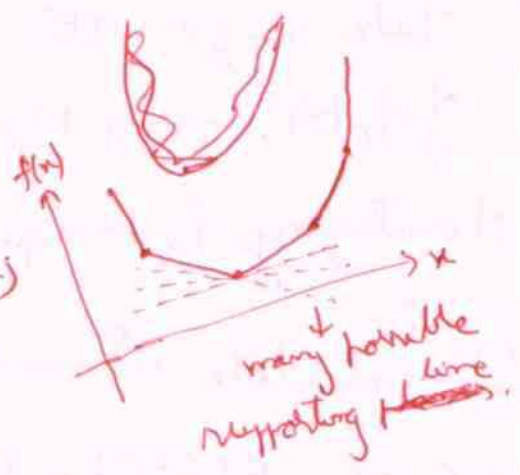
intuition →



But this view is limited to differentiable convex functions only.

→ Above intuition holds in all convex function (even though not differentiable)

i.e. at every pt. there is a supporting line



Mathematically,

$f$  is convex  $\Leftrightarrow \exists$  a  $\lambda(x)$  such that

$f(x) \geq f(x_0) + \lambda(x_0)(x-x_0) \quad \forall x \in \mathbb{R}$

This is the characterization which we use now:

$X$  is a r.v. → in other words a mapping from  $\Omega \rightarrow \mathbb{R}$ . Hence take  $x = X(\omega)$ .

Take  $x_0 = E[X]$ .

→  $f(X(\omega)) \geq f(E[X]) + \lambda(E[X])(X(\omega) - E[X]) \quad \forall \omega \in \Omega$

Now we saw that expectation maintains order relations

→  $E[f(X)] \geq E[f(E[X]) + \lambda(E[X])(X - E[X])]$   
 $= f(E[X]) + \lambda(E[X])(E[X] - E[X]) = f(E[X])$

Hence Proved.

## Applications of Jensen's inequality:

i) Take  $f(x) = -\log(x) \rightarrow$  convex. Take  $X$  as discrete rv taking values  $x_1, \dots, x_n$ .  
 $f(E[X]) \leq E[f(X)]$   $\neq$  Uniform distribution.  $\searrow \nearrow 0$

$$\Rightarrow -\log\left(\frac{x_1 + x_2 + \dots + x_n}{n}\right) \leq \frac{-\log(x_1) + \dots + -\log(x_n)}{n}$$
$$= -\frac{1}{n} \log(x_1 x_2 \dots x_n)$$
$$= -\log \sqrt[n]{x_1 x_2 \dots x_n}$$

$$\Rightarrow \frac{x_1 + x_2 + \dots + x_n}{n} \geq \sqrt[n]{x_1 x_2 \dots x_n} \quad (\because -\log \text{ is a monotonically decreasing function})$$

AM  $\geq$  GM.

So Jensen's inequality is a generalization of AM, GM inequality.

ii) TST  $|\mu - M| \leq \sigma$  ( $\mu$  is mean,  $\sigma$  is std. dev.,  $M$  is median).

$$|\mu - M| = |E[X] - M| = |E[X - M]| \leq E[|X - M|] = \cancel{E[\sqrt{(X - M)^2}]}$$

Jensen's Ineq. with  $|\cdot|$  as convex function!  $\downarrow$

$$= \min_c E[|X - c|] \rightarrow \text{we saw this in assignment}$$
$$\leq E[|X - c|] \quad \forall c \text{ in particular take } c = \mu = E[X]$$
$$= E[|X - E[X]|]$$
$$= E[\sqrt{(X - E[X])^2}] \leq \sqrt{E[(X - E[X])^2]} = \sigma$$

Jensen's Inequality with  $\sqrt{\cdot}$  as concave function!

Here Proved.

Occurs frequently in many places for eg: Information theory, Loss-entropy etc.

Till now we have been looking at random variables which take on real values. In other words, the range of r.v. was always  $\mathbb{R}$ .  
Now, we will generalize the notion of r.v.s to include ones taking on vectorial values i.e. r.v.s for which the range is  $\mathbb{R}^n$ , the  $n$ -dimensional Euclidean Space.

i.e. We define functions of the form  $X: \Omega \rightarrow \mathbb{R}^n$ . Such functions from some sample space to  $\mathbb{R}^n$  (with additional restrictions (as we shall see as we proceed)) are called as Multi-variate Random variables. Other names are random vector, multi-valued random variable etc...

Intuitively a (usual) random ~~vector~~<sup>variable</sup> quantifies outcomes in terms of numbers (scalars) whereas a ~~random vector~~<sup>multi-variate</sup> r.v. (m.r.v.) quantifies outcomes in terms of  $n$ -tuples (vectors). Once this view is clear, the applications where an m.r.v. can be employed are obvious: eg. whenever the outcome of a random experiment can be defined in terms of vectorial values rather than scalar values.

To give a ~~realistic~~<sup>realistic</sup> example, let us consider the random experiment where people in IITB are clinically examined for presence of Swine-Flu. Here it is immediate that each person's (or outcome in our case) ~~health~~<sup>health</sup> cannot be described by a single quantity such as temperature or cough etc., but can be described using a collection of all these data!

Let us run through this example:

(1)

Let  $\Omega$  be the set of all people (living) in IITB (say  $N$  of them).

~~Let~~ An event in  $\Omega$  is nothing but groups of people (take  $\mathcal{F} = 2^{\Omega}$ ).

Now define  $P(\{x_i\}) = \frac{1}{N} \forall x_i \in \Omega$  ( $x_i$  is the  $i^{\text{th}}$  person).

This gives a valid prob. space  $\mathbb{P} = (\Omega, \mathcal{F}, P)$ .

Now define a r.v.  $X_1$ , which is nothing but a 'thermometer'. (Thermometer takes input as a patient gives output as a number, specifically the body temperature of that patient). Let  $B_1$  be the set of all "high temperatures" i.e.  $B_1 = \{x \in \mathbb{R} / x \geq 103\}$

Now we saw, that,  $P_{X_1}(B_1) = P(X_1^{-1}(B_1)) = P(\underbrace{\{\omega \in \Omega / X_1(\omega) \geq 103\}}_{\text{set of all people with high temp.}})$

This gives us the induced prob. space  $\mathbb{P}_{X_1} = (\mathbb{R}, \mathcal{B}, P_{X_1})$ .

III) by ~~for~~ each symptom of swine flu (which is ~~of course~~ quantifiable as a number) we can represent it with a r.v.

Let  $X_1, X_2, \dots, X_{n-1}$  be r.v.s representing "clinical devices" quantifying each symptom of swine-flu disease. Now consider an expert doctor who looks at the diagnostic report of patient  $\omega$  (i.e. looks at  $X_1(\omega), \dots, X_{n-1}(\omega)$ ) and certifies presence of swine flu or not. ~~In other words,~~ Let  $X_n$  r.v. represent the expert doctor (again he takes as input a patient  $\omega \in \Omega$  & gives as output a number 1 (if swine-flu presence) or 0 (if normal patient)).

In other words  $X_n$  is the indicator function of presence of disease.

(Note that  $X_n$  depends "implicitly" on all  $X_1, \dots, X_{n-1}$ ).

Let  $B_n \in \mathcal{L}$  be an event of observing swine flu i.e.  $B_n = \{\omega \in \Omega / X_n(\omega) = 1\}$ .



Now let us define a m.d.v.  $X$  as follows:

$X: \Omega \rightarrow \mathbb{R}^n$  such that,

$$X(\omega) = (X_1(\omega), X_2(\omega), X_3(\omega), \dots, X_{n-1}(\omega), X_n(\omega)) \quad \forall \omega \in \Omega.$$

\* Note that intuitively  $X(\omega)$  is nothing but an analyzed diagnostic report of patient  $\omega$ .

Note that  $X$  (which is an m.d.v.) not only helps in representing a "complicated" outcomes like health of a person, but also helps in analyzing relationships between  $X_i, X_j$  ~~etc~~ <sup>d.v.s !!</sup>

~~Now let us see if there is a concept of induced probability~~

~~for a m.d.v.:~~ Let us see how do events in  $\mathbb{R}^n$  look like:

~~words to do that~~ An event in  $\mathbb{R}^n$  looks like:

$$B = B_1 \times B_2 \times \dots \times B_n \quad \text{where } B_i \in \mathcal{B} \quad \forall i$$

$$= \{ (x_1, x_2, \dots, x_n) \mid x_i \in B_i, B_i \in \mathcal{B} \}$$

In our medical eg:  $B$  is nothing but ~~high~~ temperature values in first coordinate, presence of nerve pain i.e. 1 in the last coordinate.

Now collection of all such events  $B$  in  $\mathbb{R}^n$  is the Borel- $\sigma$ -algebra in  $\mathbb{R}^n$ .

$$\mathcal{B}^n = \{ B \mid B = B_1 \times B_2 \times \dots \times B_n, B_i \in \mathcal{B} \quad \forall i \}$$

(Borel- $\sigma$ -algebra in  $\mathbb{R}^n$ )

Let us now see if there exists a concept of induced probability for a m.d.v.:

i.e. can we define  $P_X(B)$ ?

~~Following~~ Following a strategy similar to the case of (usual) d.v., we (3)  
have:

$$\begin{aligned}
P_X(B) &\equiv P(\{\omega \in \Omega \mid X(\omega) \in B\}) \xrightarrow{\text{Nothing but}} P(X^{-1}(B)) = P[X \in B] \\
&= P(\{\omega \in \Omega \mid (X_1(\omega), X_2(\omega), \dots, X_n(\omega)) \in B\}) \xrightarrow{\text{square bracket rotation}} B_1 \times B_2 \times \dots \times B_n \\
&= P(\{\omega \in \Omega \mid X_1(\omega) \in B_1, X_2(\omega) \in B_2, \dots, X_n(\omega) \in B_n\}) \\
&= P(\bigcap_{i=1}^n \{\omega \in \Omega \mid X_i(\omega) \in B_i\}) \xleftarrow{\text{Notation}} \textcircled{I} \\
&= P[X_1 \in B_1, X_2 \in B_2, \dots, X_n \in B_n]
\end{aligned}$$

In words, (in case of medical eg.)  $P_X(B)$  is nothing prob. of observing high temp (first coordinate),  $\dots$ , nerve flu (last coordinate).

~~$P_X(B)$~~   $P(\bigcap_{i=1}^n \{\omega \in \Omega \mid X_i(\omega) \in B_i\})$  is nothing but the prob. of a person having high temp.  $\dots$ , & having nerve flu. This is indeed intuitive. Since  $P$  models classical prob in our medical eg., this is exactly the "fraction of people in ITB having all symptoms of nerve-flu & also have nerve flu!". So in future classes, we will try to ~~answer for~~ <sup>look on this</sup> which questions like which symptoms are crucial for nerve-flu, how to predict presence of nerve flu given a raw diagnostic report (i.e. guess values of  $X_n$  given say values of  $X_1, \dots, X_{n-1}$ ) and so on & so forth!

Math. detail  
~~Prob. question:~~  
 Q: Why does  $\bigcap_{i \in I} \{\omega \in \Omega \mid X_i \in B_i\} \in \mathcal{F}$ ? (unless this happens my induced Prob. def. is invalid!)

A: I know each of  $\uparrow$  for fixed  $i \in I$  ( $\because X_i$  is a RV)  
 So intersection of them also  $\in \mathcal{F}$  ( $\because \mathcal{F}$  is a  $\sigma$ -algebra)

Now that we have correctly defined Induced prob. of a m.g.v., let us extend the concept of "distribution function" to an m.g.v.:

## Distribution functions of m.g.v.

In case of r.v. we defined  $F_X : \mathbb{R} \rightarrow \mathbb{R}$  such that

$$F_X(x) = P[X \leq x].$$

Now we will define in an analogous way for an m.g.v. (Note that range of m.g.v. is  $\mathbb{R}^n$ ):

$$F_X : \mathbb{R}^n \rightarrow \mathbb{R} \ni F_X(\underline{x}) = P[X \leq \underline{x}]$$

$\downarrow$   
 $\in \mathbb{R}^n$   
 $\rightarrow \underline{x} = (x_1, x_2, \dots, x_n)$

Using (I) we get:

$$F_X(\underline{x}) = P[X \leq \underline{x}] = P[X_1 \leq x_1, X_2 \leq x_2, \dots, X_n \leq x_n].$$

called the prob. dist. func. of m.g.v.  $X$  or it is also called as joint prob. dist. func. of  $X_1, X_2, \dots, X_n$  (in this case it is

represented as  $F_{X_1, X_2, \dots, X_n}(x_1, x_2, x_3, \dots, x_n)$ )

Now as in case of ~~m.g.v.~~ r.v. we can show the following 4 prop. for  $F_X$  of a m.g.v. also:

i)  $F_X(\underline{x}) \geq 0 \quad \forall \underline{x}$  (after all it's a prob.)

ii)  $F_X(\underline{\infty}) = P[X_1 \leq \infty, X_2 \leq \infty, \dots, X_n \leq \infty] = P[X \in \mathbb{R}^n] = P(\Omega) = 1.$

$F_X(\underline{-\infty}) = P[X_1 \leq -\infty, X_2 \leq -\infty, \dots, X_n \leq -\infty] = P(\emptyset) = 0.$

$\rightarrow$  represents vector with all values  $\infty/-\infty$ .

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This not only shows that  ~~$P\{X \in B\}$~~  prob. of events can be computed in terms of dist. function but also the extra cond.

$$\text{that } F_{X_1, X_2}(b_1, b_2) - F_{X_1, X_2}(a_1, b_2) - F_{X_1, X_2}(b_1, a_2) + F_{X_1, X_2}(a_1, a_2) \geq 0.$$

Now (II) ~~can be proved that (continguous) interval using the idea.~~ is a generalization of this to a  $n$ -dimensional case.

Now using set algebra we can show (not in this class) that  $P\{X \in B\}$  can be written in terms of  $F_X$ . So we from

$\mathbb{R}^n$   
now onwards characterize a m.r.v.  $X = [X_1, X_2, \dots, X_n]$  using  $(F_X \text{ or } F_{X_1, X_2, \dots, X_n})$  dist. function.

Lets look at the case where all  $X_i$ 's are discrete. Then we can define a p.m.f. mass function (p.m.f) for the m.r.v.  $X$ : (analogous to discrete r.v.'s case):

$$f_X(\underline{x}) = f_X(x_1, x_2, \dots, x_n) = f_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n) \\ \equiv P[X_1 = x_1, X_2 = x_2, \dots, X_n = x_n]$$

Now let  $E$  be the set of (discrete) values in  $\mathbb{R}^n$  taken by  $X$ , then following two properties of p.m.f are immediate:

$$f_X(\underline{x}) \geq 0 \quad (\because f_X \text{ is after } P \text{ all above})$$

$$\sum_{\underline{x} \in E} f_X(\underline{x}) = 1 \quad (\because P(\Omega) = 1)$$

Now again any function ~~satisfying~~  $f_X: \mathbb{R}^n \rightarrow \mathbb{R}$  satisfying

(7)

Here two properties is called a pmf. & also given a pmf, of  $X$ , dist. of  $X (F_X)$  is fixed and vice-versa. So we can characterize discrete m.v. using pmf. (from now onwards).

Let's look at an ex. of a discrete m.v. (which is a generalization of the binomial d.v.):

### Multinomial R.V.

Suppose we define the following  $f_X: \mathbb{R}^n \rightarrow \mathbb{R}_+$

$$f_X(\underline{x}) = P[X_1=x_1, X_2=x_2, \dots, X_n=x_n] = \frac{n!}{x_1! x_2! \dots x_n!} p_1^{x_1} p_2^{x_2} \dots p_n^{x_n} \quad \text{--- (III)}$$

$$\forall x_i \geq 0, \sum_{i=1}^n x_i = n$$

and  $(n, p_1, \dots, p_n)$  are parameters such that  $n \in \mathbb{N}$  and  $p_i \geq 0, \sum_{i=1}^n p_i = 1$ .

(It is an exercise to first check if this is a valid pmf!)

At first look this might look weird but consider the following <sup>random</sup> expt: Suppose I throw a die  $n$  times. In each throw I ~~ex~~ have ( $n=6$ ) outcomes. Suppose  $p_i$  is probability of seeing no. 'i' ( $i=1$  to  $6$ ). Now the answer to the question: "what is the prob. of seeing  $x_1$  1s,  $x_2$  2s,  $\dots$ ,  $x_6$  6s" is exactly given by (III)! (why?)

Now that we know some 'physical' interpretation of multinomial r.v. lets see (if at all) ~~are~~ what kind of r.v.'s are  $X_1, X_2, \dots, X_n$  individually?

In the die throwing case,  $X_i = \#$  ~~no~~ throws in which 'i' was observed

Now it is easy to see that  $X_i$  is a binomial r.v. with parameters  $(n, p_i)$ !

So  $X = [X_1, X_2, \dots, X_n]$  follows multinomial distribution then each of  $X_i$  ( $i=1$  to  $n$ ) follow binomial distri. (with diff. parameters)

Now ~~we can~~ compute prob like

$$P[X_i = x_i] \quad \text{using the pmf of } X_i$$

But note that  $P[X_1 = x_1, \dots, X_n = x_n]$  (which is nothing but the joint pmf of  $X_1, X_2, \dots, X_n$ ), cannot be computed merely from the knowledge of  $P[X_i = x_i]$ 's. (at most you can give bounds on joint pmf using inequalities like Berjeroni's inequality you proved in the assigns.)

However the pmf of  $X_i$  can be computed given the pmf of  $X$  (i.e. the joint pmf of  $X_i$ 's):

$$\sum_{\substack{x_2, x_3, \dots, x_n \\ \Rightarrow x_i \geq 0, \sum_{i=1}^n x_i = n}} f_X(x_1, x_2, \dots, x_n) = f_{X_i}(x_i)$$

$\uparrow$  fixed all varied for all allowed values

no ~~pmf~~ specifying joint pmf is a "richer" information! (than specifying pmf of  $X_i$ 's alone)

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(iii) " $F_X$  is right cont. &  $f_X$  has left limit"

(we don't show this here)

Missing Page 6  
from Lecture - 10

(iv) Monotonicity: (but in all variables)

$$\begin{aligned}
 & F_X(x_1 + \Delta x_1, x_2 + \Delta x_2, \dots, x_n + \Delta x_n) - F_X(x_1, x_2, \dots, x_n) \\
 & \quad \downarrow \geq 0 \quad \quad \downarrow \geq 0 \quad \quad \downarrow \geq 0 \\
 & = P[X_1 \leq x_1 + \Delta x_1, \dots, X_n \leq x_n + \Delta x_n] \\
 & \quad - P[X_1 \leq x_1, \dots, X_n \leq x_n] \\
 & = P[x_1 \leq X_1 \leq x_1 + \Delta x_1, \dots, x_n \leq X_n \leq x_n + \Delta x_n] \\
 & \geq 0 \quad (\because \text{it is a prob. of some event}).
 \end{aligned}$$

→ All this all prop. are analogous to those in case of n.v.

But in case of m. n.v. an extra condition needs to be satisfied:

(v)

$$\begin{aligned}
 & F_X(x_1 + \epsilon_1, x_2 + \epsilon_2, \dots, x_n + \epsilon_n) = \sum_i F_X(x_1 + \epsilon_1, \dots, x_i, \dots, x_n + \epsilon_n) \\
 & + \sum_i \sum_{j > i} F_X(x_1 + \epsilon_1, \dots, x_i, x_{i+1} + \epsilon_{i+1}, \dots, x_j, x_{j+1} + \epsilon_{j+1}, \dots, x_n + \epsilon_n)
 \end{aligned}$$

II

(-1)<sup>n</sup>  $F_X(x_1, x_2, \dots, x_n) \geq 0 \quad \forall x_i, \epsilon_i > 0.$

✶ We can get an intuition for this by looking at a n.v. taking values ~~for~~ in  $\mathbb{R}^2$ :

Let  $X = [X_1, X_2]$  Let  $F_{X_1, X_2}(x_1, x_2)$  be the disjoint prob. dist. function at  $(x_1, x_2)$ .

Now suppose I want to compute

$$0 \leq P[a_1 \leq X_1 \leq b_1, a_2 \leq X_2 \leq b_2] \text{ (in terms of)} \quad \text{then:}$$

$$= F_{X_1, X_2}(b_1, b_2) - F_{X_1, X_2}(a_1, b_2) - F_{X_1, X_2}(b_1, a_2) + F_{X_1, X_2}(a_1, a_2)$$

(how we get this was explained in class)

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## Lecture-11

Let  $X = [X_1, X_2, \dots, X_n]$  be a m.r.v.  $X$  is called a continuous m.r.v. (or equivalently  $X_1, X_2, \dots, X_n$  are said to be "jointly continuous" m.r.v.) iff there exists a function  $f_X: \mathbb{R}^n \rightarrow \mathbb{R}$  such that:

$$P[X \in B] = \int_B f_X(\underline{x}) d\underline{x} \quad \forall B \in \mathcal{B}^n$$

multidimensional  
integral

Such a function  $f_X$  is called the prob. density function of  $X$  or joint prob. density function of  $X_1, X_2, \dots, X_n$ .

For eg. if  $n=2$ ,  $P[X \in B] = \iint_B f_{X_1, X_2}(x_1, x_2) dx_1 dx_2$ .

Now take  $B = \{(a_1, a_2, \dots, a_n) \mid a_i \in (-\infty, x_i]\}$

$$\Rightarrow P[X_1 \leq x_1, X_2 \leq x_2, \dots, X_n \leq x_n] = \int_{-\infty}^{x_1} \int_{-\infty}^{x_2} \dots \int_{-\infty}^{x_n} f_X(x_1, x_2, \dots, x_n) dx_1 dx_2 \dots dx_n$$

$\downarrow$   
 $F_X(x_1, x_2, \dots, x_n)$

Hence  $F_X$  is fixed if  $f_X$  is known. ~~One can show the converse also is true~~  
Also we have:

$$\frac{\partial^n F_X(x_1, x_2, \dots, x_n)}{\partial x_1 \partial x_2 \dots \partial x_n} = f_X(x_1, x_2, \dots, x_n) \quad (\text{provided } f_X \text{ is continuous})$$

As in case of 1-d r.v., the values of  $f_X$  (where  $f_X$  is discontin.) does'nt matter (they do not account for the area). One can show that (again, not here) that such points are "few", so we can make the statement ~~for~~ "given  $f_X$ , we have  $F_X$  fixed and vice-versa".

So from now on we characterize  $X$  by  $f_X$  (pdf)



Now let's look at some properties of  $f_x$ :

we have, (i)  $1 = P(\omega) = P[X \in \mathbb{R}^n] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \dots \int_{-\infty}^{\infty} f_x(x_1, x_2, \dots, x_n) dx_1 dx_2 \dots dx_n$

(ii) we can show  $f_x(x_1, x_2, \dots, x_n) \geq 0 \forall x \in \mathbb{R}^n$ . Recall that an analogous statement in case of i.v. followed from "monotonicity property of  $F_x$ ". Here it follows from the "①" prop. of  $F_x$  which in 2-d case is illustrated below:

We know,  $F_{X_1, X_2}(b_1, b_2) - F_{X_1, X_2}(a_1, b_2) - F_{X_1, X_2}(b_1, a_2) + F_{X_1, X_2}(a_1, a_2) \geq 0$

$\Leftrightarrow \int_{-\infty}^{b_1} \int_{-\infty}^{b_2} f_x(x_1, x_2) dx_1 dx_2 - \int_{-\infty}^{a_1} \int_{-\infty}^{b_2} f_x(x_1, x_2) dx_1 dx_2 - \int_{-\infty}^{b_1} \int_{-\infty}^{a_2} f_x(x_1, x_2) dx_1 dx_2 + \int_{-\infty}^{a_1} \int_{-\infty}^{a_2} f_x(x_1, x_2) dx_1 dx_2 \geq 0$   $\forall a_1 \leq b_1, a_2 \leq b_2$

$\Leftrightarrow \int_{a_1}^{b_1} \int_{-\infty}^{b_2} f_x(x_1, x_2) dx_1 dx_2 - \int_{a_1}^{b_1} \int_{-\infty}^{a_2} f_x(x_1, x_2) dx_1 dx_2 \geq 0$   $\forall a_1 \leq b_1, a_2 \leq b_2$

$\Leftrightarrow \int_{a_1}^{b_1} \int_{a_2}^{b_2} f_x(x_1, x_2) dx_1 dx_2 \geq 0 \forall a_1 \leq b_1, a_2 \leq b_2 \Leftrightarrow f_x(x) \geq 0 \forall x$

Hence, p.d.f is any function that satisfies:

(i)  $f_x(x) \geq 0 \forall x$

(ii)  $\int_{-\infty}^{\infty} f_x(x) dx = 1$

Now let's look at a particular case eg. of a conts. m.i.v.:

$f_x(x) = \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2} x^T x} \forall x \in \mathbb{R}^n$  (I)

First lets check if it is pdf?

$f_x$  is indeed non-negative. Only non-trivial thing to verify is if it integrates to unity:

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \dots \int_{-\infty}^{\infty} \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2} \sum_{i=1}^n x_i^2} dx_1 dx_2 \dots dx_n$$

$$= \underbrace{\prod_{i=1}^n \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2} x_i^2} dx_i}_{\text{(each of integral is 1)}} = 1$$

Now,  $F_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n) = \int_{-\infty}^{x_1} \int_{-\infty}^{x_2} \dots \int_{-\infty}^{x_n} \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2} \sum_{i=1}^n x_i^2} dx_1 dx_2 \dots dx_n$

$$= \left( \int_{-\infty}^{x_1} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2} x_1^2} dx_1 \right) \dots \left( \int_{-\infty}^{x_n} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2} x_n^2} dx_n \right)$$

$$= F_{X_1}(x_1) F_{X_2}(x_2) \dots F_{X_n}(x_n)$$

each is the distribution function of the std. Normal r.v.'s !!

Here are two things to note about  $\textcircled{I}$ :

- $\textcircled{i}$  Its distribution func. is product of dist. func. of individual r.v.'s (later on we will see that such r.v.'s are called as independent r.v.'s)
- $\textcircled{ii}$  ~~Dist. func.~~ Dist. func. of each individual r.v. is the std. Normal dist.

Now both in case of discrete and conts. r.v., we saw that the distribution functions or pmfs or pdfs of individual r.v.'s can be obtained from their joint-distribution. This leads to the notion of  $M$  marginal distributions:

Now  $F_{X_1, X_2}$  From now onwards to simplify the notation we will consider collections of two r.v.'s. However keep in mind that the analogous results do hold in the generic  $n$ -d case also.

So from now onwards consider two r.v.  $X, Y$ ,  $F_{XY}$  is the joint dist. function of  $X$  and  $Y$ .

$$\text{Now, } F_X(x) = P[X \leq x] = P[X \leq x, Y \leq \infty] = F_{XY}(x, \infty) \quad \forall x$$

$$\text{Similarly, } F_Y(y) = F_{XY}(\infty, y) \quad \forall y.$$

The dist. functions of  $X/Y$  are also known as the marginal dist. of  $X/Y$  w.r.t the joint dist. function of  $X$  and  $Y$ .

Now if  $X, Y$  are discrete,

$$f_X(x) = P[X=x] = \sum_{\forall y} P[X=x, Y=y] = \sum_{\forall y} f_{XY}(x, y) \quad \forall x$$

$$\text{Similarly } f_Y(y) = \sum_{\forall x} f_{XY}(x, y) \quad \forall y$$

Again  $f_X, f_Y$  are known as the marginal pmfs of  $X$  and  $Y$  w.r.t. to the joint pmf of  $X, Y$  i.e.  $f_{XY}$ .

Now suppose  $X, Y$  are jointly conts:

$$\Rightarrow F_{XY}(x, y) = \int_{-\infty}^x \int_{-\infty}^y f_{XY}(x', y') dx' dy'$$

$$\text{Now } F_{XY}(x, \infty) = \int_{-\infty}^x \int_{-\infty}^{\infty} f_{XY}(x', y') dy' dx'$$

$$\text{Also, } F_X(x) = \int_{-\infty}^x f_X(x') dx'$$

Ⓜ

Since the pdf is fixed (except at "few" points) given the dist. func., we have that  $f_X(x) = \int_{-\infty}^{\infty} f_{XY}(x, y) dy$  from Ⓜ

$$\text{III by } f_Y(y) = \int_{-\infty}^{\infty} f_{XY}(x', y) dx'$$

Again  $f_X, f_Y$  are known as the marginal pdfs of  $X, Y$  w.r.t. to the joint-pdf of  $X$  and  $Y$  i.e.  $f_{XY}$ .

Now, it is easy to see that in example Ⓜ, the following holds:

$$f_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n) = f_{X_1}(x_1) f_{X_2}(x_2) \dots f_{X_n}(x_n)$$

$\downarrow \quad \downarrow \quad \downarrow$   
 each is pdf of  
 std. Normal.

Now lets run through the calculation of marginal pdfs using a toy-example:

$$\text{Let } f_{XY}(x, y) = \begin{cases} 24xy & \text{if } 0 < x, 0 < y, 0 < x+y < 1 \\ 0 & \text{otherwise} \end{cases}$$

be the joint pdf of  $X$  and  $Y$ . Let us compute the marginals: Ⓟ

$$f_x(x) = \int_{-\infty}^{\infty} f_{xy}(x, y) dy$$

$$= \begin{cases} \int_0^{1-x} 24xy \, dy & \text{if } x \in [0, 1] \\ 0 & \text{otherwise} \end{cases}$$

(we know that  $0 < x, 0 < y$   
 $0 < x+y < 1$ )

$$= \begin{cases} 12x(1-x)^2 & x \in [0, 1] \\ 0 & \text{otherwise} \end{cases}$$

Since expression of  $f_{xy}$  is symmetric in terms of  $x, y$ , we will get that

$$f_y(y) = \begin{cases} 12y(1-y)^2 & y \in [0, 1] \\ 0 & \text{otherwise} \end{cases}$$

$$\text{Also, } \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{xy}(x, y) dx dy = \int_{-\infty}^{\infty} f_x(x) dx = \int_0^1 12x(1-x)^2 dx$$

$$= \int_0^1 12x^2(1-x) dx = 4x^3 - 3x^4 \Big|_0^1 = 1$$

This verifies that both the marginals and in turn the joint pdf are indeed "valid" pdfs!

Now <sup>recall</sup> ~~suppose~~ the example of "swine-flu" analysis done in a previous lecture. Suppose I've want to evaluate the truth in the statement that ~~the~~ <sup>the</sup> given "symptoms of swine-flu are indeed good indicators of presence of disease". To answer such question we would (may) consider the set of all ppl. who have the symptoms and then look at frac. of ppl. in that set who also have high swine-flu. (if this value is high, then symptoms are indeed indicators). In other words, we need to ask questions abt. probabilities ~~considering the~~ <sup>as if the original</sup> ~~reduced~~  $\Omega$  is thinned to the set of all people having the symptoms.

As we explained in one of the early lectures, ~~such~~ conditional probability is a mechanism which facilitates this "thinning of  $\Omega$ ".

Def:  $\rightarrow$  lets now look at <sup>the</sup> concept of cond. prob. measure, defined in terms of <sup>usual</sup> conditional prob. <sup>measures</sup>.

Consider two discrete RVs  $X, Y$  with joint pmf given by  $f_{XY}$ . Suppose

$f_Y(y_i) = P[Y=y_i] \neq 0$  for some fixed value of  $y_i$ . Now define a new prob. mass function:

$$f_{X/Y}(x_i/y_i) = \frac{f_{XY}(x_i, y_i)}{f_Y(y_i)}$$

$\forall x_i \rightarrow$  values which random variable  $X$  takes.

notation for conditional probability mass function of  $X$  given  $Y=y_i$

First of all, lets check if (this) is a valid pmf?

First of all it's a ratio of values of pmf so audience is  $\geq 0$ . Secondly,

$$\sum_{\neq x_i} f_{X|Y}(x_i/y_i) = \sum_{\neq x_i} \frac{f_{XY}(x_i, y_i)}{f_Y(y_i)} = \frac{\sum_{\neq x_i} f_{XY}(x_i, y_i)}{f_Y(y_i)} = \frac{f_Y(y_i)}{f_Y(y_i)} = 1$$

margin pmf  
definition.

Now for each value of  $y_i$  such that  $f_Y(y_i) \neq 0$ , we can define a different pmf. Hence we have a family of pmf. derived from the joint pmf of  $X, Y$ .

Note that,  $f_{X|Y}(x_i/y_i) = \frac{f_{XY}(x_i, y_i)}{f_Y(y_i)} = \frac{P[X=x_i, Y=y_i]}{P[Y=y_i]} = P[X=x_i | Y=y_i]$

defn. of cond.  
prob. of over events  
which is familiar to  
all of us.

In other words, the conditional pmf is defined in terms of cond. prob. over events.

Now once we have a <sup>cond.</sup> pmf we can also define conditional distribution function:  $F_{X|Y}$

$$F_{X|Y}(x_0/y_i) = \sum_{\neq x_i \leq x_0} f_{X|Y}(x_i/y_i) = \sum_{\neq x_i \leq x_0} P[X=x_i | Y=y_i] = P[X \leq x_0 | Y=y_i]$$

Let's try to put down the cond. prob. for a toy example:

(Note that, instead we could have started by defining cond. distr. ~~and~~ later discovered the name defn. of cond. pmf!) (2)

Consider the ~~the~~ usual prob. space associated with tossing of a coin (with prob. of getting ahead =  $p$ ) for  $n$  times (independent & independent Bernoulli trials).  $\hookrightarrow$  may ( $n > 2$ )

Now define two r.v.s

$X$ : trial at which first head appears ( $X$  takes values 1 to  $n$ )  
 $Y$ : no. of heads in the  $n$  tosses ( $Y$  takes values 0 to  $n$ )

Note that  $X$  is not a valid r.v. as per the defn. since there is "no trial id" which handles the case of all tails in  $n$  tosses. As a collecting factor lets ~~also~~ include a dummy value (may "0") which  $X$  takes on to represent the case of all tails.

Here is the marginal pmf of  $X$ :

$$f_X(x_i) = \begin{cases} (1-p)^n & x_i = 0 \\ (1-p)^{x_i-1} p & x_i = 1 \text{ to } n \\ 0 & \text{otherwise} \end{cases}$$

$x_i = 0$  (dummy value representing all tails)

$x_i = 1 \text{ to } n$   
otherwise

$\rightarrow$  Now this is a valid pmf

marginal pmf of  $Y$ :  $\rightarrow$  Binomial r.v.

$$f_Y(y_i) = \binom{n}{y_i} p^{y_i} (1-p)^{n-y_i} \quad y_i = 0 \text{ to } n.$$

~~joint pmf of~~ lets write down the conditional prob. mass function of  $X/Y = i$

a  $i=0$ :  $f_{X/Y}(x_i/0) = \begin{cases} 1 & \text{if } x_i = 0 \\ 0 & \text{otherwise} \end{cases} \rightarrow \text{valid pmf}$

b  $i=1$ :  $f_{X/Y}(x_i/1) = \begin{cases} \frac{f_{XY}(x_i, 1)}{f_Y(1)} = \frac{(1-p)^{x_i-1} p}{\binom{n}{1} p (1-p)^{n-1}} = \frac{1}{n} & \text{if } x_i = 1 \text{ to } n \\ 0 & \text{otherwise} \end{cases}$



$$\textcircled{c} \underline{i=2} : f_{X|Y}(x_i|2) = \begin{cases} \frac{{}^{n-x_i}C_1 p^2 (1-p)^{n-2}}{{}^n C_2 p^2 (1-p)^{n-2}} & \text{if } x_i = 1 \text{ to } n-1 \\ 0 & \text{otherwise} \end{cases}$$

of  $x_i = 1 \text{ to } n-1$   
 otherwise

~~Now we have already put down values of joint pmf for few~~

In the process of writing down the cond. <sup>pmf</sup> we have also put down the joint pmf for ~~the~~ few value pair of  $(x_i, y_i)$ .

In the next lecture we will look at the case of cond. prob. for jointly conts. r.v. etc.

# Lecture Notes 13

① 01-01-01

Suppose  $X, Y$  are jointly conts. r.v. Now we want to define notion of ray cond. dist. and cond. pdf (if possible), moreover using the familiar notion of cond. prob. over events (which is very familiar to us). Now pdf has "no direct link" with prob. So maybe it's better to start ~~from~~ by defining cond. distr. function using cond. prob. over events.

Suppose we attempt the following:  $F_{X|Y}(x/y) = P\{X \leq x / Y = y\}$   
*note this was the defn for discrete r.v. case.*

We are bound to fail since  $P\{Y=y\} = 0 \forall y$ . The work around is to define as follows: (which intuitively means the same!)

$$\begin{aligned} F_{X|Y}(x/y) &= \lim_{\Delta y \rightarrow 0} P[X \leq x / y \leq Y \leq y + \Delta y] \rightarrow \text{(this is the definition we go with)} \\ &= \lim_{\Delta y \rightarrow 0} \frac{P\{X \leq x, y \leq Y \leq y + \Delta y\}}{P\{y \leq Y \leq y + \Delta y\}} \rightarrow \text{(familiar notion of cond. prob. over events)} \\ &= \lim_{\Delta y \rightarrow 0} \frac{\int_{-\infty}^x \int_y^{y+\Delta y} f_{XY}(x', y') dy' dx'}{\int_y^{y+\Delta y} f_Y(y') dy'} \rightarrow \text{(since } X, Y \text{ are jointly conts.) there } \exists \text{ a pdf} \\ &= \lim_{\Delta y \rightarrow 0} \frac{\int_{-\infty}^x f_{XY}(x', y) \Delta y dx'}{f_Y(y) \Delta y} \rightarrow \text{(over small intervals we assume pdf doesn't change) so area is height } \times \text{ interval length} \end{aligned}$$

$$\Rightarrow F_{X|Y}(x|y) = \frac{\int_{-\infty}^x f_{XY}(x', y) dx'}{f_Y(y)} = \int_{-\infty}^x \left[ \frac{f_{XY}(x', y)}{f_Y(y)} \right] dx'$$

↓  
this must be cond. pdf!!

$$\Rightarrow f_{X|Y}(x|y) = \frac{f_{XY}(x, y)}{f_Y(y)}$$

(Conditional pdf)

→ Note the similarity in the expression even in the discrete case!

↓  
Now for this defn. is first of all valid iff  $y$  is such that  $f_Y(y) \neq 0$ . (i.e. prob. density of  $Y$  at  $y$  is non-zero).

Now ~~suppose~~ ~~if~~ let us check if for a fixed  $y$ , the  $f_{X|Y}$  is indeed a pdf or not. (This check will complete the defn.)

(i) firstly  $f_{X|Y}$  is  $\geq 0$ .

(ii) 
$$\int_{-\infty}^{\infty} f_{X|Y}(x|y) dx = \int_{-\infty}^{\infty} \frac{f_{XY}(x, y)}{f_Y(y)} dx = \frac{\int_{-\infty}^{\infty} f_{XY}(x, y) dx}{f_Y(y)} = \frac{f_Y(y)}{f_Y(y)} = 1$$

Hence for a fixed value of  $y$  such that  $f_Y(y) \neq 0$ ,  $f_{X|Y}$  is indeed a pdf and with different values of  $y$  (satisfying  $f_Y(y) \neq 0$ ) we get different pdf's!

Let look at an eg. given in one of prev. lectures:

eg 1  $f_{xy}(x,y) = \begin{cases} 24xy & x > 0, y > 0, x+y < 1 \\ 0 & \text{otherwise} \end{cases}$

We already saw that

$$f_x(x) = \int_{-\infty}^{\infty} f_{xy}(x,y) dy = \begin{cases} 12x(1-x)^2 & 0 < x < 1 \\ 0 & \text{otherwise} \end{cases}$$

$$f_y(y) = \begin{cases} 12y(1-y)^2 & 0 < y < 1 \\ 0 & \text{otherwise} \end{cases}$$

Now lets compute

$$f_{x/y}(x/y) = \begin{cases} \frac{24xy}{12y(1-y)^2} = \frac{2x}{(1-y)^2} & \text{if } 0 < x < 1-y \\ 0 & \text{otherwise} \end{cases}$$

↓  
for some  $y \in (0,1)$   
where I am  
sure  $f_y(y) \neq 0$

(It is an easy exercise to check if ↑ is valid pdf)

For eg.  $f_{x/y}(x/0.25) = \begin{cases} \frac{32x}{9} & 0 < x < 0.75 \\ 0 & \text{otherwise} \end{cases}$

$$f_{x/y}(x/0.75) = \begin{cases} 32x & 0 < x < 0.25 \\ 0 & \text{otherwise} \end{cases}$$

So we can get a family of pdf using different values of  $y \in (0,1)$ .

Now lets take <sup>another</sup> eg of a jointly contin pdf we saw in last class

$$-\frac{1}{2} \sum_{i=1}^n x_i^2$$

$$f_X(x) = f_{x_1, x_2, \dots, x_n}(x_1, x_2, \dots, x_n) = \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2} \sum_{i=1}^n x_i^2} \quad x \in \mathbb{R}^n$$

We also say that each of  $x_1, x_2, \dots, x_n$  are i.i.d. Normal dist.

$$(ii) F_{x_1, x_2, \dots, x_n}(x_1, x_2, \dots, x_n) = F_{x_1}(x_1) F_{x_2}(x_2) \dots F_{x_n}(x_n)$$

(why?)



$$f_{x_1, x_2, \dots, x_n}(x_1, x_2, \dots, x_n) = f_{x_1}(x_1) f_{x_2}(x_2) \dots f_{x_n}(x_n)$$

Now lets take  $n=2$ , then calculate

$$f_{x_1, x_2}(x_1, x_2) = \frac{f_{x_1}(x_1) f_{x_2}(x_2)}{f_{x_2}(x_2)} = f_{x_1}(x_1)$$

In other words knowledge abt.  $x_2$  is not effect pdf of  $x_1$ !

Similar  
This notion was discussed while discussing notion of independent events!

Let's formalize this notion of independence:

Independence of r.v.s

$X, Y$  are said to be independent

$\Leftrightarrow \forall B_1, B_2 \in \mathcal{B}$  it happens that: (I)

$$P[X \in B_1, Y \in B_2] = P[X \in B_1] P[Y \in B_2]$$

in other words the events

$$\{X \in B_1\} \text{ \& \} \{Y \in B_2\}$$

$$\{ \omega \in \Omega / X(\omega) \in B_1 \} \text{ \& \} \{ \omega \in \Omega / Y(\omega) \in B_2 \}$$

are independent

Now let's choose  $B_1 = (-\infty, u]$  &  $B_2 = (-\infty, y]$

(5)

then  $\textcircled{I} \Rightarrow \underline{F_{XY}(x, y) = F_X(x) F_Y(y)}$

(the converse is also true & beyond scope of this course)

→ This means the joint that factorizes into marginals or in case of independent rvs the marginals completely determine the joint-dent!!

→ Now if  $X, Y$  are discrete rvs, then:

Take  $B_1 = \{x\}, B_2 = \{y\}$   $\textcircled{I} \Rightarrow \underline{f_{XY}(x, y) = f_X(x) f_Y(y)}$

→ If  $X, Y$  are jointly cont. rvs, then we anyway have:

$$F_{XY}(x, y) = F_X(x) F_Y(y)$$

$$\Rightarrow \frac{\partial F_{XY}(x, y)}{\partial y} = F_X(x) \frac{dF_Y(y)}{dy} = F_X(x) f_Y(y)$$

$$\Rightarrow \frac{\partial^2 F_{XY}(x, y)}{\partial x \partial y} = \frac{d}{dx} F_X(x) f_Y(y) = f_X(x) f_Y(y)$$

$$\Rightarrow \underline{f_{XY}(x, y) = f_X(x) f_Y(y)}$$

So joint functions, pmf, pdf's factorize!!

~~We can extend~~  
Also for independent rvs:  $f_{X|Y}(x|y) = \frac{f_{XY}(x, y)}{f_Y(y)} = \frac{f_X(x) f_Y(y)}{f_Y(y)} = f_X(x)$   
Conditional = marginal!

The notion of independence of r.v.'s can be extended to any  $X_1, X_2, \dots, X_n$ :

We say  $X_1, \dots, X_n$  are independent if for all sub-collections  $X_i, \dots, X_j$  are independent (in other words  $X_i, X_j$  are independent,  $X_i, X_j, X_k$  are independent, no on  $\dots$ ) and  $F_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n)$  factorizes into marginals.  
(So there are  $2^n - n - 1$  conditions to be checked!)

again one of the conditions is  $F_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n)$   
$$= F_{X_1}(x_1) F_{X_2}(x_2) \dots F_{X_n}(x_n).$$

Note that the r.v.'s in eq 1 are not independent and those in eq 2 are independent r.v.'s!

Moreover the r.v.'s in eq 2 are also identically distributed

In other words, each of the  $X_1, X_2, \dots, X_n$  has the name Ntd. Normal distribution.

Such a collection of r.v.'s which are independent and identically distributed are called as iid r.v.s.

Let's look at a quick eg:

eg Suppose  $X, Y$  are iid. & conts. r.v.'s.

Calculate  $P[X > Y]$ .

Intuitive answer is:

$$P[\text{~~IR~~}] 1 = P\{(X, Y) \in \mathbb{R}^2\} = P[X > Y \cup X < Y \cup X = Y]$$
$$= P[X > Y] + P[X < Y] + P[X = Y]$$

each are mutually  
exclusive events

$$\downarrow$$

~~$P[X = X, Y = X]$~~

$\downarrow$  zero  
since  $X, Y$  are  
conts. r.v.'s!  
(since they

Now there is no reason to believe  $X > Y$  or  $Y < X$   
are independent & imitations of same distr. butions) so  $P[X > Y]$   
must be equal to  $P[Y < X]$

$$\Rightarrow P[X > Y] = 1/2$$

may all are iid.

IIIth argument shows  $P\{X_1 > X_2 > \dots > X_n\} = \frac{1}{n!}$

because this is just one ordering  
among all  $n!$  orderings!!

Now lets look at a more rigorous answer and we  
will be seeing that our intuition is right!

$$P[X > Y] = \int_{-\infty}^{\infty} \int_{-\infty}^x f_{XY}(x, y) dy dx = \int_{-\infty}^{\infty} \int_{-\infty}^x f_X(x) f_Y(y) dy dx$$

$\downarrow$   
 $X, Y$  are independent



$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_x(x) f_x(y) dy dx \quad (\because x, y \text{ are identically distributed})$$

$$= \int_{-\infty}^{\infty} f_x(x) \left[ \int_{-\infty}^{\infty} f_x(y) dy \right] dx \rightarrow F_x(x)$$

$$= \int_{-\infty}^{\infty} f_x(x) F_x(x) dx$$

(two ways of computing it)

(by parts method)

$$= F_x(x) F_x(x) \Big|_{-\infty}^{\infty} - \int_{-\infty}^{\infty} F_x(x) f_x(x) dx$$

$$\Rightarrow \int_{-\infty}^{\infty} f_x(x) F_x(x) dx = \frac{F_x(x) F_x(x) \Big|_{-\infty}^{\infty}}{2}$$

$$= \frac{1}{2}$$

(substitution method)

Put  $u \rightarrow F_x(x)$

$$= \int_0^1 F_x(x) dF_x(x) = \frac{F_x(x)^2}{2} \Big|_0^1 = \frac{1}{2}$$

## BAYE'S Theorem (extension to r.v.)

Let  $X, Y$  are discrete/jointly cont. r.v's

Let  $f_{xy}, f_x, f_y$  represent their joint & marginal pmf/pdf. (whichever is the case)

We know:

$$f_{X|Y}(x/y) = \frac{f_{xy}(x, y)}{f_y(y)} \Rightarrow f_{xy}(x, y) = f_{X|Y}(x/y) f_y(y)$$

$$\text{also, } f_{Y|X}(y/x) = \frac{f_{xy}(x, y)}{f_x(x)} = \frac{f_{X|Y}(x/y) f_y(y)}{f_x(x)}$$

Now if  $X, Y$  are discrete r.v.s, then:

$$f_X(x) = \sum_{y'} f_{XY}(x, y') = \sum_{y'} f_{X|Y}(x/y') f_Y(y')$$

Now substituting back we get:

$$f_{Y|X}(y/x) = \frac{f_{X|Y}(x/y) f_Y(y)}{\sum_{y'} f_{X|Y}(x/y') f_Y(y')} \quad \left. \begin{array}{l} \text{Bayes' theorem} \\ \text{for} \\ \text{discrete r.v.s.} \end{array} \right\}$$

If  $X, Y$  are jointly conts., then:

$$f_X(x) = \int_{-\infty}^{\infty} f_{XY}(x, y') dy' = \int_{-\infty}^{\infty} f_{X|Y}(x/y') f_Y(y') dy'$$

Substituting back we get:

$$f_{Y|X}(y/x) = \frac{f_{X|Y}(x/y) f_Y(y)}{\int_{-\infty}^{\infty} f_{X|Y}(x/y') f_Y(y') dy'} \quad \left. \begin{array}{l} \text{Bayes' theorem} \\ \text{for} \\ \text{jointly conts. r.v.s.} \end{array} \right\}$$

The advantage is that without knowing joint pmf or joint pdf we are able to calculate cond. probs on one side using cond. probs on the other side i.e.  $f_{X|Y}$  and of course we also are using  $f_Y(y)$  or  $f_X(x)$  i.e. marginals.   
  $\downarrow f_{Y|X}$    
  $\therefore$  Use whenever joint-pmf/pdf is difficult to compute !!   
 (unnecessary)

This lecture begins with some applications of Bayes' theorem.

eg! Suppose we are told that a person picks up a coin at random from a set of  $m$  coins. It is also given to us ~~that~~ that the prob. of picking the  $i^{\text{th}}$  coin is  $q_i$  (i.e.  $q_i \geq 0$ ,  $\sum_{i=1}^m q_i = 1$ ). Now just given this information suppose we are asked to guess what coin was picked up by the person, intuitively our answer would be  $\arg \max q_i$ , i.e. the coin which has the maximum prob. of ~~being~~ picked. Note that we are using ~~no~~ absolutely no information regarding the particular coin picked ~~but~~ <sup>up</sup> but some "generic" information ~~about~~ about  $q_i$ .

Now suppose the person is generous to reveal some partial information regarding the coin in his hand and then asks us to guess. ~~For~~ ~~if~~ ~~the~~ In particular, suppose he reveals the number of heads he got by tossing the coin in his hand for  $n$  times and he also reveals the prob. of getting heads with each of the coin (i.e.  $p_i \geq 0$ ,  $p_i \leq 1$ ,  $i=1$  to  $m$ ).

Now, ~~the~~ a little bit of thinking will show that ~~the~~ given the partial information, we can come up with a better guess. (Think abt two extreme cases where all  $q_i$  are same &  $q_i$  highly distinct)

Let us formalize our ideas: define two RVs (2)

$X$ : # heads in  $n$  tosses (with the coin picked up)  $\rightarrow E \in \{0, 1, 2, \dots, n\}$

$Y$ : id of the coin picked up  $\rightarrow E \in \{1, 2, \dots, m\}$

Now ~~this~~ pmf of  $Y$  is given:  $f_Y(y) = \begin{cases} q_y & y \in \{1, 2, \dots, m\} \\ 0 & \text{otherwise} \end{cases}$

~~Since this is an information given prior to the <sup>partial</sup> information regarding the coin ~~picked up~~, this information is~~

Also, the following cond. pmf is given:

$$f_{X|Y}(x|y) = \begin{cases} \binom{n}{x} p_y^x (1-p_y)^{n-x} & x \in \{0, 1, \dots, n\} \\ 0 & \text{otherwise} \end{cases}$$

Now we wish to calculate the prob. that the coin picked up is  $y$  given that there were  $x$  heads:

$$f_{Y|X}(y|x) = \frac{f_{X|Y}(x|y) f_Y(y)}{\sum_{y'} f_{X|Y}(x|y') f_Y(y')} \quad (\because \text{Bayes theorem})$$

$$= \frac{\binom{n}{x} p_y^x (1-p_y)^{n-x} q_y}{\sum_{y'} \binom{n}{x} p_{y'}^x (1-p_{y'})^{n-x} q_{y'}}$$

Now given a 'n' by the person, for different values of y we can calculate this quantity. Again (intuitively) the guess is to pick the coin which maximizes  $f_{y/x}$ !

Note that if all  $p_y = \frac{1}{m}$  (for  $y=1$  to  $m$ ), then  $f_{y/x}$  is same as  $f_y$  (and our guess wouldnt change!) In other words, if all coins have same prob. of getting heads, the partial information regarding the coin picked up does not give any ~~more~~ <sup>additional</sup> insight to it!  
→ i.e. no. heads in 'n' tosses

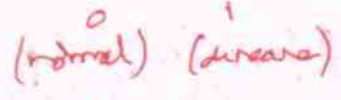
Since  $f_{y/x}$  is prob. of ~~picking~~ <sup>a coin being</sup> picked after looking at the partial information about X, it is usually called as posterior prob. &  $f_y$  is called as prior probability. (The same idea is extensively used in prob. model known as ~~Hidden Markov Model~~ <sup>Hidden Markov model (HMM)</sup> which are ~~the~~ <sup>state of the art</sup> models for automated speech recognition systems!)

Hence the idea of cond. prob. & Bayes' theorem have far reaching consequences.

Now lets look at another eg. illustrating the utility of the Bayes' theorem. The reader is encouraged to see at every step the analogy between these two examples.

eg 2 Suppose  $X$  represents the diagnostic report of a patient <sup>in words</sup> (4)

(for the sake of simplicity assume it represents the body temp. of the patient) and suppose  $Y$  represents whether he has a disease or not.



Now ~~required~~ <sup>(again)</sup> the task is to predict (guess) whether a patient has disease or not! Assume the following information is given:

(i)  $f_Y$  (pmf) is given. (This is the pri of information). In ~~words~~ <sup>words</sup>, the fraction of normal & diseased people in a population is given. (I)

(ii)  $f_{X|Y}$  (pdf) is given. In words, the body temp. distribution of normal as well as of patients with disease are given. Note that  $X|Y$  is a conts. r.v.  $\Rightarrow F_{X|Y}(x/y) \equiv P\{X \leq x|Y=y\} = \int_{-\infty}^x f_{X|Y}(x'/y) dx'$ .

Again we ~~need~~ <sup>wish</sup> to compute  $f_{Y|X}$  (pmf) which ~~is~~ <sup>is words</sup> is the prob. of the patient is normal or has disease given his diagnostic report (body temp.)

Before this ~~supposed~~ let us answer a simpler question "what is  $f_X(x)$ ?" In words, ~~the~~ what is the body temp. dist. of the entire population? Since we have not assumed anything thing abt  $X$ , <sup>conts. or discrete</sup> let us compute its dist. function:

$$F_X(x) = P[X \leq x] = \sum_{\forall y} P[X \leq x, Y=y]$$

(∵ marginal funda)

$$= \sum_{\forall y} P[X \leq x | Y=y] P\{Y=y\}$$

(∵ cond. prob.)

$$= \sum_{\forall y} F_{X|Y}(x|y) f_Y(y)$$

(∵ def. of cond. dist.)

$$= \sum_{\forall y} \int_{-\infty}^x f_{X|Y}(x'|y) f_Y(y) dx'$$

(∵  $X|Y$  is a cont. rv)

$$= \int_{-\infty}^x \left[ \sum_{\forall y} f_{X|Y}(x'|y) f_Y(y) \right] dx'$$

(∵ interchange  $\int$  &  $\sum$ )

$$\Rightarrow f_X(x) = \sum_{\forall y} f_{X|Y}(x|y) f_Y(y)$$

(∵ def. of pdf)

Recall that this resembles the total prob. rule (for the case where  $X, Y$  are both discrete). However note that  $f_X$  and  $f_{X|Y}$  are pdfs and  $f_Y$  is a pmf. Also, it looks like

$f_X$  is a convex combination of conditional pdfs ( $f_{X|Y}$ ).

In other words it looks like  $X$  is a mixture of two kinds of ~~random vars~~ ( $X|Y=0, X|Y=1$  here!).  $f_X$  is also sometimes called as

mixture density.  $f_Y$  are called as mixing prob. &

~~$f_{X|Y}$~~  as class conditional density!

Models satisfying (i) & (ii) in (I) here are called as "Mixture Models".

Now lets try to compute:

$$f_{Y|X}(y/x) \equiv \lim_{\Delta x \downarrow 0} P[Y=y / X \in [x, x+\Delta x]]$$

(III to defn. in case of  $X, Y$  conts rvs.)

↓  
pmf for fixed  $x$   
such that  $f_X(x) \neq 0$

$$= \lim_{\Delta x \downarrow 0} \frac{P[x \leq X \leq x+\Delta x, Y=y]}{P[x \leq X \leq x+\Delta x]}$$

$$= \lim_{\Delta x \downarrow 0} \frac{P[x \leq X \leq x+\Delta x / Y=y] P\{Y=y\}}{P[x \leq X \leq x+\Delta x]}$$

$$= \lim_{\Delta x \downarrow 0} \frac{\int_x^{x+\Delta x} f_{X|Y}(x'/y) dx' f_Y(y)}{\int_x^{x+\Delta x} f_X(x') dx'}$$

(∵  $X, Y$  and therefore  $X'$  are conts rvs.)

$$= \lim_{\Delta x \downarrow 0} \frac{f_{X|Y}(x/y) \Delta x f_Y(y)}{f_X(x) \Delta x}$$

$$\Rightarrow f_{Y|X}(y/x) = \frac{f_{X|Y}(x/y) f_Y(y)}{f_X(x)} = \frac{f_{X|Y}(x/y) f_Y(y)}{\sum_{y'} f_{X|Y}(x/y') f_Y(y')}$$

Again, this looks like Baye's theorem in case of  $X, Y$  both discrete rvs! But here  $f_{Y|X}$  and  $f_Y$  are ~~pdfs~~ pmfs whereas

$f_{X|Y}$  is a pdf!

Again  $f_{Y|X}$  is posterior pmf (pmf after looking at partial information i.e. diagnostic report of the patient)  
 $f_Y$  is simply the prior information.



In general, there are two ways to guess: ⑦

$$\operatorname{argmax}_y f_y(y)$$

$y$  that  
→ maximizes the prior  
prob. (without looking at  
the particular patient!)

$$\operatorname{argmax}_y f_{y|x}(y/x)$$

→ given diagnostic report  $x$   
of patient guess his  
status of health

max. prior prob.

max. posterior prob. → it is easy to reason out this  
gives a better guess.

→  
Suppose we want to design a chair which withstands the  
weight of people who sit on it as well as is not built from  
too costly or heavy (storing) material! One way is to design it  
for the heaviest person on earth. But this is too pessimistic  
and will lead to a chair perhaps too heavy to even move :)  
On the other hand we want chair to be 'robust' enough  
to handle heavy people.

one way to put this is ~~to~~ to design chair such  
that it withstands the weight of any '100' random  
people who sit on it. i.e. design for:  
d in'

$$M = \max \{X_1, X_2, X_3, \dots, X_n\}$$

Here  $X_1, \dots, X_n$  represents weights of 'n' people. It is easy to see that they are i.i.d. r.v.s (why??).

Also note that  $M$  is a r.v. and is in fact a function of collection of r.v.s  $X_1, \dots, X_n$ !

Let compute the df of  $M$ :

$$\begin{aligned}
 F_M(x) &= P\{M \leq x\} = P\{\max\{X_1, X_2, \dots, X_n\} \leq x\} \\
 &= P\{X_1 \leq x, X_2 \leq x, \dots, X_n \leq x\} \\
 &= P\{X_1 \leq x\} P\{X_2 \leq x\} \dots P\{X_n \leq x\} \quad (\because \text{they are independent}) \\
 &= F_{X_1}(x) F_{X_2}(x) \dots F_{X_n}(x) \\
 &= (F(x))^n \quad (\text{Here } F \text{ is the common dist. function of all the identically distributed r.v.s } X_1, \dots, X_n)
 \end{aligned}$$

$$\Rightarrow f_M(x) = n(F(x))^{n-1} f(x)$$

(Here  $f$  is the common pdf of  $X_1, \dots, X_n$ )

In words  $F(x)$  ~~represent~~ <sup>represent</sup> the dist. of body weight among humans!

!!! by one can consider:

$N = \min\{X_1, X_2, \dots, X_n\}$ .  $N$  is another function of collections of r.v.s. ①

$$\begin{aligned}F_N(x) &= P\{N \leq x\} = P\{\min\{X_1, X_2, \dots, X_n\} \leq x\} \\&= 1 - P\{\min\{X_1, X_2, \dots, X_n\} > x\} \\&= 1 - P\{X_1 > x, X_2 > x, \dots, X_n > x\} \\&= 1 - (1 - F(x))^n \quad (\text{again by iid})\end{aligned}$$

$$\Rightarrow f_N(x) = n(1 - F(x))^{n-1} f(x).$$

Now one can consider the joint dist. of collection of  $M, N$  r.v.s which are in turn function of collections of r.v.s!

$$\begin{aligned}F_{MN}(x, y) &= P\{M \leq x, N \leq y\} \\&= P\{M \leq x\} - P\{M \leq x, N > y\} \\&= (F(x))^n - P\{y < X_1 \leq x, y < X_2 \leq x, \dots, y < X_n \leq x\} \\&= (F(x))^n - (F(x) - F(y))^n \quad (\because \text{iid arguments})\end{aligned}$$

In future classes we will look into more eg. of functions of r.v.s.

This lecture formalizes the notion of function of multivariate r.v.s. (in other words functions of collections of r.v.s).

Suppose  $X_1, X_2, \dots, X_n$  are r.v.s defined on  $\mathbb{P} = (\Omega, \mathcal{F}, P)$ . Also,  $g: \mathbb{R}^n \rightarrow \mathbb{R}$  is given. Consider a new function  $Z: \Omega \rightarrow \mathbb{R}$  defined as

$$Z(\omega) = g(X_1(\omega), X_2(\omega), \dots, X_n(\omega)) \quad \forall \omega \in \Omega.$$

The shorthand representation of  $\downarrow$  is  $Z = g(X_1, X_2, \dots, X_n)$ .

Now  $Z$  is indeed a function from  $\Omega \rightarrow \mathbb{R}$ , so it is a r.v. if:

$$Z^{-1}(B) \in \mathcal{F} \quad \forall B \in \mathcal{B}.$$

i.e.

$$\left\{ \omega \in \Omega / g(X_1(\omega), X_2(\omega), \dots, X_n(\omega)) \in B \right\} \in \mathcal{F} \quad \forall B \in \mathcal{B}.$$

Consider the condition  $\underline{g^{-1}(B)} \in \mathcal{B}^n$   $\forall B \in \mathcal{B}$  in other words  $g^{-1}(B) = B_1 \times B_2 \times \dots \times B_n$  each  $B_i \in \mathcal{B}$ .

It is easy to see that  $Z^{-1}(B) = \prod_{i=1}^n \left\{ \omega \in \Omega / X_i(\omega) \in B_i \right\} \in \mathcal{F}$

Hence  $g^{-1}(B) \in \mathcal{B}^n$  is the condition on  $g$  which makes  $Z$  a valid r.v. since each  $X_i$  is a valid r.v.!

Again (not in this class) we can show that if  $g$  is a continuous function then  $Z = g(X_1, \dots, X_n)$  is also a valid r.v.

Let's consider an example:

(here  $g(x, y) = x + y$ )

eg 1  $Z = X + Y$

Suppose joint pdf of  $X, Y$  is known. Compute  $f_z$ .

$$F_z(z) = P\{Z \leq z\} = P\{X + Y \leq z\}$$
$$= \int_{-\infty}^{\infty} \int_{-\infty}^{z-x} f_{XY}(x, y) dy dx$$

$$\text{Now } f_z(z) = \frac{dF_z(z)}{dz} = \int_{-\infty}^{\infty} \frac{d}{dz} \int_{-\infty}^{z-x} f_{XY}(x, y) dy dx$$
$$= \int_{-\infty}^{\infty} f_{XY}(x, z-x) dx$$

Assume now that  $X, Y$  are independent r.v.s.

$$\Rightarrow f_z(z) = \int_{-\infty}^{\infty} f_X(x) f_Y(z-x) dx \quad \left. \begin{array}{l} \text{nothing but} \\ \text{convolution of } f_X, f_Y \text{ at } z \end{array} \right\}$$
$$\equiv f_X(z) * f_Y(z)$$

Hence, pdf of sum of two r.v.s is the convolution of the individual pdfs!

Lets now take the special case  $f_X(x) = f_Y(x) = \begin{cases} 1/2 & -1 < x < 1 \\ 0 & \text{otherwise} \end{cases}$

In other words we are assuming  $X, Y$  are both  $\sim U[-1, 1]$  (uniform r.v.s in  $[-1, 1]$ ).

$$f_z(z) = f_x(z) * f_y(z)$$

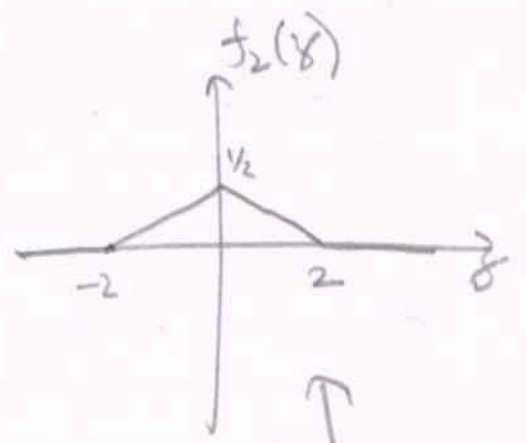
(X, Y are iid and are uniform r.v. in (-1, 1))

$$= \int_{-\infty}^{\infty} f_x(x) f_y(z-x) dx$$

$$= \begin{cases} 0 & z \leq -2 \\ \int_{-1}^{z+1} \frac{1}{4} dx & -2 < z \leq 0 \\ \int_{z-1}^1 \frac{1}{4} dx & 0 < z \leq 2 \\ 0 & z > 2 \end{cases}$$

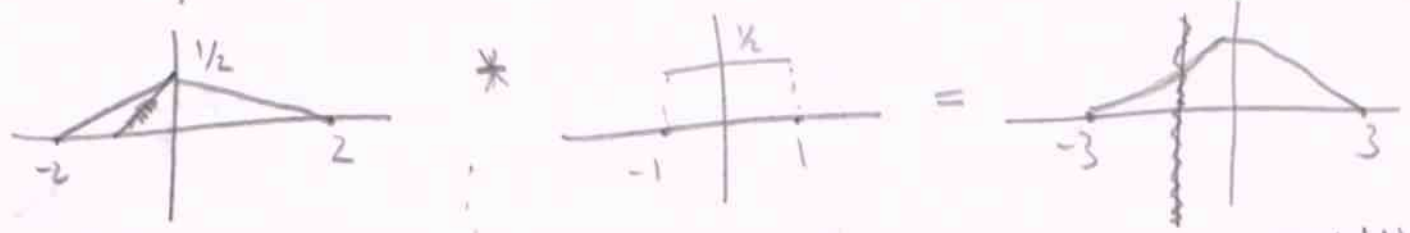
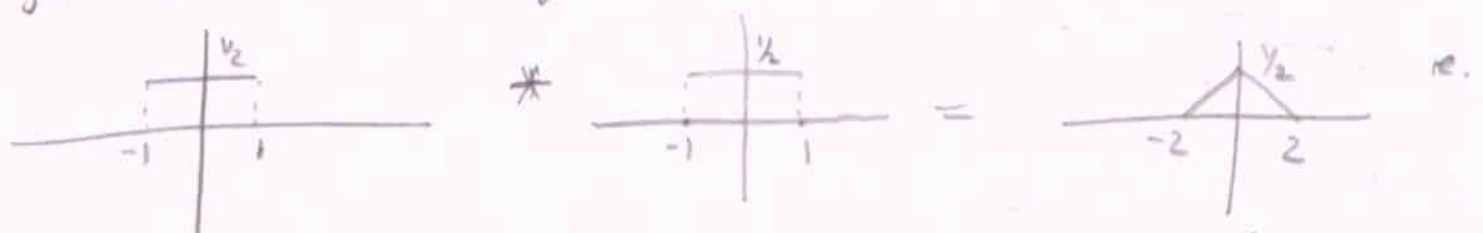
$f_x(x)$  and  $f_y(z-x)$  are non-zero iff  
 $-1 < x < 1$   
 $-1 < z-x < 1$   
 i.e.  $-1 < x < 1$   
 $z-1 < x < z+1$

$$= \begin{cases} 0 & z \leq -2 \\ \frac{z+2}{4} & -2 < z \leq 0 \\ \frac{2-z}{4} & 0 < z \leq 2 \\ 0 & z > 2 \end{cases}$$



So sum of two iid  $U[-1, 1]$  r.v.s is not  $U[-1, 1]$  but (in fact).

||| by we can sum three, four, ... iid r.v.s which are  $U[-1, 1]$ :



(infinite sum)

= Std. Normal r.v.!

This is an intuition for a special case of Central Limit Theorem.

(The sum of infinite iid rvs all  $U[-1,1]$  is converging to std. Normal r.v.)

eg 2  $\rightarrow$  Let  $X, Y$  be iid and ~~std~~<sup>be</sup> Normal rvs.

by above argument: ~~if~~  $Z = X + Y$  has the pdf as convolution of pdfs of  $X, Y$ . It is a well-known result that convolution of any two Gaussian functions is a Gaussian function.

Using this result we can say  $Z$  is again a Normal r.v.!

(we will see a generic result of this kind later)

(A Gaussian function is any function of the form:

$$f(x) = a e^{-\frac{(x-\mu)^2}{c^2}} \quad a, c > 0. \text{ Note that the}$$

Normal r.v. has a pdf as a Gaussian func. Hence Normal r.v. are also known as Gaussian r.v.s!)

eg 3  $Z = \frac{X}{Y}$ .

$$F_Z(z) = P\{Z \leq z\} = P\left\{\frac{X}{Y} \leq z\right\}$$

$$= P\{X \leq zY, Y > 0\} + P\{X > zY, Y < 0\}$$
$$= \int_0^{\infty} \int_{-\infty}^{zy} f_{X,Y}(x,y) dx dy + \int_{-\infty}^0 \int_{zy}^{\infty} f_{X,Y}(x,y) dx dy$$

$$\begin{aligned} \Rightarrow f_z(z) &= \frac{dF_z(z)}{dz} = \int_{-\infty}^{\infty} \frac{d}{dz} \int_{-\infty}^z f_{xy}(x,y) dx dy + \int_{-\infty}^0 \frac{d}{dz} \int_{zy}^0 f_{xy}(x,y) dx dy \\ &= \int_{-\infty}^{\infty} y f_{xy}(zy, y) dy + \int_{-\infty}^0 -y f_{xy}(zy, y) dy \\ &= \int_{-\infty}^{\infty} |y| f_{xy}(zy, y) dy \end{aligned}$$

→ Now lets take  $x, y$  as iid and std. Normal rvs.

$$\begin{aligned} \text{then } f_z(z) &= \int_{-\infty}^{\infty} |y| \frac{1}{\sqrt{\pi}} e^{-\frac{1}{2}zy^2} \frac{1}{\sqrt{\pi}} e^{-\frac{1}{2}y^2} dy = \frac{1}{\pi} \int_{-\infty}^{\infty} y e^{-\frac{(z^2+1)y^2}{2}} dy \\ &= \frac{1}{\pi} \left[ \frac{e^{-\frac{(z^2+1)y^2}{2}}}{-\frac{(z^2+1)}{2}} \right]_{-\infty}^{\infty} \\ &= \frac{1}{\pi(1+z^2)} \end{aligned}$$

∴  $Z$  is a Cauchy rv!

→ Now, Consider the collection of rvs  $Z_1, Z_2, \dots, Z_n$  each of which are ~~joint~~ <sup>in turn</sup> ~~independent~~ ~~probability~~ functions of the rvs:  $X_1, X_2, \dots, X_n$ .

i.e. Consider

$$\begin{aligned} Z_1 &= g_1(X_1, X_2, \dots, X_n) \\ Z_2 &= g_2(X_1, X_2, \dots, X_n) \\ &\vdots \\ Z_n &= g_n(X_1, X_2, \dots, X_n) \end{aligned}$$



we already saw that each  $Z_i$  is a r.v. (from the name initial IP). Here the collection of  $\{Z_1, Z_2, \dots, Z_n\}$  is indeed a valid multivariate r.v. Here we can talk about its dist. fnc. & equivalently, the joint distribution of  $Z_1, Z_2, \dots, Z_n$  which are collections of functions of  $X_1, X_2, \dots, X_n$  r.v.s.

$$F_Z(\underline{z}) = F_{Z_1, Z_2, \dots, Z_n}(z_1, z_2, z_3, \dots, z_n)$$

$$= P[Z \leq \underline{z}]$$

$$= P[Z \in B] \quad \text{where } B = (-\infty, z_1] \times (-\infty, z_2] \times \dots \times (-\infty, z_n]$$

Now  $Z = \underline{g}(X)$  where  $\underline{g}: \mathbb{R}^n \rightarrow \mathbb{R}^n$

$$\underline{g}(x_1, x_2, \dots, x_n) = (g_1(x_1, x_2, \dots, x_n), g_2(x_1, \dots, x_n), \dots, g_n(x_1, \dots, x_n))$$

$$\Rightarrow F_Z(\underline{z}) = P[\underline{g}(X) \in B]$$

$$= P[X \in \underline{g}^{-1}(B)]$$

$$= \iiint_{\underline{g}^{-1}(B)} f_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n) dx_1 dx_2 \dots dx_n$$

Now suppose ~~we do the follow~~ that  $g$  is invertible:

$$\Rightarrow \exists h \ni x = h(z).$$

Also suppose  $g, h$  are continuously differentiable.

Then

$$F_Z(z) = \iint \dots \int_{g^{-1}(z)} f_{x_1, x_2, \dots, x_n}(x_1, x_2, \dots, x_n) dx_1 dx_2 \dots dx_n$$

$$= \iint \dots \int_D f_{x_1, \dots, x_n}(h_1(z_1, \dots, z_n), h_2(z_1, \dots, z_n), \dots, h_n(z_1, \dots, z_n)) |J| dz_1 dz_2 \dots dz_n$$

$$\Rightarrow f_Z(z) = f_{x_1, \dots, x_n}(h_1(z_1, \dots, z_n), \dots, h_n(z_1, \dots, z_n)) |J|$$

↖ abs. value of the Jacobian.

$$|J| = \text{abs. of det. of } \begin{bmatrix} \frac{\partial h_1}{\partial z_1} & \dots & \frac{\partial h_1}{\partial z_n} \\ \vdots & & \vdots \\ \frac{\partial h_n}{\partial z_1} & \dots & \frac{\partial h_n}{\partial z_n} \end{bmatrix}$$

We will see an explanation in the next lecture.

We will continue the discussion at end previous lecture (now restricting ourselves to 2-d case):

Consider two rvs:  $Z_1 = g_1(x_1, x_2)$   $g_1: \mathbb{R}^2 \rightarrow \mathbb{R}$

$Z_2 = g_2(x_1, x_2)$   $g_2: \mathbb{R}^2 \rightarrow \mathbb{R}$

Let  $Z$  be the multivariate rv representing  $Z_1, Z_2$   
 $X$  " " " "  $X_1, X_2$

Also let,  $\underline{g}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be defined as  $\underline{g}(x, y) = (g_1(x, y), g_2(x, y))$

It is easy to see that  $Z = \underline{g}(X)$ .

Now assume:

(i)  $\underline{g}$  is invertible ( $\underline{g}$  is bijection). Let  $\underline{h} = \underline{g}^{-1}$ .

it is easy to see  $X = \underline{h}(Z)$ . Also let  $\underline{h}(z_1, z_2) = (h_1(z_1, z_2), h_2(z_1, z_2))$

(ii) Assume  $\underline{g}, \underline{h}$  are continuously differentiable.

~~Let~~ (iii) Assume  $Z, X$  are conts. (multivariate) rvs.

We wish to write down the joint pdf of  $Z_1, Z_2$  (i.e. pdf of  $Z$ ) in terms of joint-pdf of  $X_1, X_2$  (i.e. pdf of  $X$ ). To this end:

$$F_Z(\underline{z}) = P[Z \leq \underline{z}]$$

$$= P[Z \in B]$$

$$\text{where } B = (-\infty, z_1] \times (-\infty, z_2].$$

(i)

$$\Rightarrow F_2(\underline{y}) = P[\underline{g}(X) \in B]$$

$$= P[X \in \underline{h}(B)]$$

$$= \iint_{\underline{h}(B)} f_{X_1, X_2}(x_1, x_2) dx_1 dx_2 \quad \textcircled{I}$$

Now suppose I do change of dummy variables  $x_1, x_2$  in the double integral:

$$x_1 = h_1(\gamma_1, \gamma_2)$$

$$x_2 = h_2(\gamma_1, \gamma_2)$$

$$\left( \begin{array}{l} \text{remember that} \\ h_1 = g_1^{-1} \\ h_2 = g_2^{-1} \end{array} \right)$$

Now  $(x_1, x_2) \in \underline{h}(B)$  from the integral limits

$$\Rightarrow (h_1(\gamma_1, \gamma_2), h_2(\gamma_1, \gamma_2)) \in \underline{h}(B)$$

$$\Rightarrow \underline{h}(\gamma_1, \gamma_2) \in \underline{h}(B) \Rightarrow (\gamma_1, \gamma_2) \in B \quad \textcircled{II}$$

Now in order to proceed with change of variables I need to figure out how elementary area in  $\gamma_1, \gamma_2$  coordinate looks like! Before doing that say elementary area is  $|J| d\gamma_1 d\gamma_2$  (we will later know what is  $|J|$ )

$$\text{Then: } F_2(\underline{y}) = \iint_{\underline{h}(B)} f_{X_1, X_2}(h_1(\gamma_1, \gamma_2), h_2(\gamma_1, \gamma_2)) |J| d\gamma_1 d\gamma_2$$

from  $\textcircled{II}$

$\leftarrow B$

$\rightarrow$  must be  $f_{\gamma_1, \gamma_2}$  !! (why?)  $\textcircled{2}$

Since dist. of  $Z$  can be computed by integrating a function (over relevant  $z$ -interval), that same function must be the pdf of  $Z$ !

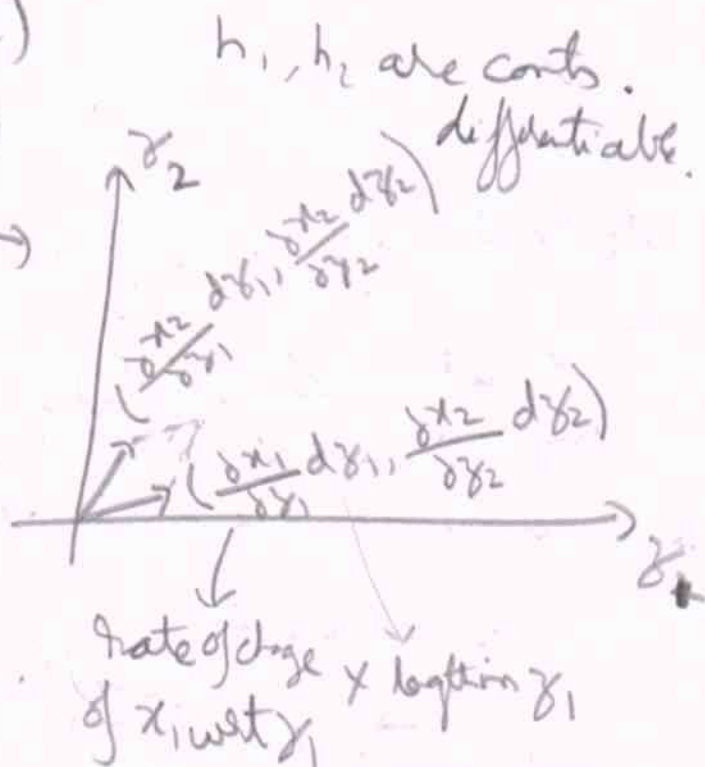
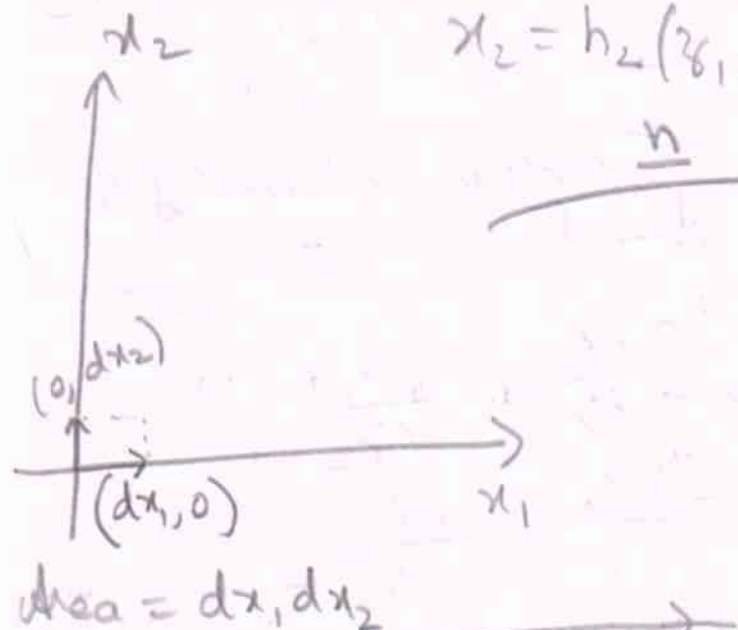
$$\Rightarrow \int_{z_1, z_2} f_{z_1, z_2}(z_1, z_2) = \int_{x_1, x_2} f_{x_1, x_2}(h_1(z_1, z_2), h_2(z_1, z_2)) |J|$$

Hence we are successful in the derivation. Now let us see how  $|J|$  can be computed as:

### Change of Variables in Multiple integrals

$$x_1 = h_1(z_1, z_2)$$

$$x_2 = h_2(z_1, z_2)$$



Area in  $z_1, z_2$  coordinates is area of parallelogram (for which we know the vectors of sides!)

Area of 11gm is nothing but cross-product of the vectors of bare sides:

$$\begin{aligned} \text{Area vector} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial x_1}{\partial z_1} dz_1 & \frac{\partial x_2}{\partial z_2} dz_2 & 0 \\ \frac{\partial x_2}{\partial z_1} dz_1 & \frac{\partial x_2}{\partial z_2} dz_2 & 0 \end{vmatrix} \\ &= \left( \frac{\partial x_1}{\partial z_1} dz_1 \frac{\partial x_2}{\partial z_2} dz_2 - \frac{\partial x_2}{\partial z_2} dz_2 \frac{\partial x_2}{\partial z_1} dz_1 \right) \hat{k} \\ \text{Area} &= \left| \begin{matrix} \nearrow \\ \nearrow \end{matrix} \right| = \left| \frac{\partial x_1}{\partial z_1} \frac{\partial x_2}{\partial z_2} - \frac{\partial x_2}{\partial z_1} \frac{\partial x_1}{\partial z_2} \right| dz_1 dz_2 \end{aligned}$$

Note that,

$|J|$  is also abs. of det. of  $\rightarrow$  is called Jacobian and denoted by  $|J|$

$\begin{bmatrix} \frac{\partial x_1}{\partial z_1} & \frac{\partial x_1}{\partial z_2} \\ \frac{\partial x_2}{\partial z_1} & \frac{\partial x_2}{\partial z_2} \end{bmatrix}$   
 Called as Jacobian matrix

In n-dimensional case:

$$\text{Jacobian matrix} = \begin{bmatrix} \frac{\partial x_1}{\partial z_1} & \frac{\partial x_1}{\partial z_2} & \dots & \frac{\partial x_1}{\partial z_n} \\ \frac{\partial x_2}{\partial z_1} & \frac{\partial x_2}{\partial z_2} & \dots & \frac{\partial x_2}{\partial z_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial x_n}{\partial z_1} & \frac{\partial x_n}{\partial z_2} & \dots & \frac{\partial x_n}{\partial z_n} \end{bmatrix}$$

Lets take an eg and work out details:

Q1 Let  $Z_1 = X + Y$   
 $Z_2 = X - Y$  joint pdf of  $X, Y$  is given

Compute joint pdf of  $Z_1, Z_2$ .

We know,  $f_{Z_1, Z_2}(z_1, z_2) = \int_{X, Y} f_{X, Y}(h_1(z_1, z_2), h_2(z_1, z_2)) |J|$

<sup>first</sup> we ~~just~~ need to figure out what are  $h_1, h_2$ :  
i.e. express  $X, Y$  in terms of  $Z_1, Z_2$ :

$$X = \frac{Z_1 + Z_2}{2}$$

$$Y = \frac{Z_1 - Z_2}{2}$$

$$\Rightarrow h_1(z_1, z_2) = \frac{z_1 + z_2}{2}$$

$$h_2(z_1, z_2) = \frac{z_1 - z_2}{2}$$

$$\text{Now } |J| = \text{abs} \begin{vmatrix} \frac{\partial(\frac{z_1 + z_2}{2})}{\partial z_1} & \frac{\partial(\frac{z_1 + z_2}{2})}{\partial z_2} \\ \frac{\partial(\frac{z_1 - z_2}{2})}{\partial z_1} & \frac{\partial(\frac{z_1 - z_2}{2})}{\partial z_2} \end{vmatrix}$$

$$= \text{abs} \begin{vmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{vmatrix} = \frac{1}{2}$$

$$\Rightarrow \underline{\underline{f_{z_1, z_2}(z_1, z_2) = \frac{1}{2} f_{xy}\left(\frac{z_1+z_2}{2}, \frac{z_1-z_2}{2}\right)}}$$

Now lets compute marginal  $z_1$ :

$$f_{z_1}(z_1) = \int_{-\infty}^{\infty} \frac{1}{2} f_{xy}\left(\frac{z_1+z_2}{2}, \frac{z_1-z_2}{2}\right) dz_2$$

$$= \int_{-\infty}^{\infty} f_{xy}(t, z_1-t) dt \quad \left(\text{put } t = \frac{z_1+z_2}{2}\right)$$

↳ This expression is familiar from prev. lecture.

This shows we are consistent.

→

eg 2

$$z_1 = x/y$$

$$z_2 = y$$

again  $x = z_1 z_2$

$$y = z_2$$

$$\left( \begin{array}{l} \text{i.e.} \\ h_1(z_1, z_2) = z_1 z_2 \\ h_2(z_1, z_2) = z_2 \end{array} \right)$$

$$|J| = \text{abs.} \begin{vmatrix} z_2 & z_1 \\ 0 & 1 \end{vmatrix} = |z_2|$$

$$\Rightarrow f_{z_1, z_2}(z_1, z_2) = |z_2| f_{xy}(z_1 z_2, z_2)$$



Now again  $\infty$

$$f_{z_1}(z_1) = \int_{-\infty}^{\infty} |z_2| f_{xy}(z_1, z_2, z_2) dz_2$$

This expression is also familiar from prev. lecture!

## EXPECTATIONS

Now lets return to the topic of expectations.

Consider  $Z = g(x, y)$

we know  $Z$  is a r.v.

So we know:  $E[Z] = \begin{cases} \int_{-\infty}^{\infty} z f_z(z) dz & \text{if } Z \text{ is continuous} \\ \sum_{x_i} z_i f_z(x_i) & \text{if } Z \text{ is discrete r.v.} \end{cases}$

But one can also show:

Theorem:  $E[Z] = E[g(x, y)] = \begin{cases} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y) f_{xy}(x, y) dx dy \\ \sum_{x_i} \sum_{y_i} g(x_i, y_i) f_{xy}(x_i, y_i) \end{cases}$

Recall that we proved a similar theorem for  $Z = g(x)$  also.

(7)

(7)

Again like prev. time we will show <sup>this</sup> only for the discrete case:

Proof:  $E[z] = \sum_{\neq z_i} z_i f_z(z_i)$

$$= \sum_{\neq z_i} z_i \sum_{\substack{(x_i, y_i): \\ g(x_i, y_i) = z_i}} f_{xy}(x_i, y_i)$$

$$= \sum_{\neq z_i} \sum_{(x_i, y_i): g(x_i, y_i) = z_i} g(x_i, y_i) f_{xy}(x_i, y_i)$$

$$= \sum_{\neq (x_i, y_i)} g(x_i, y_i) f_{xy}(x_i, y_i)$$

if  $E[z]$  exists then series sum is abs. convergent so it doesn't matter in which order we take the sum!

In summary, we know how to compute Expectation of function of two (d.i.g. general 'n') r.v.s!

In this lecture we will proceed with discussion of expectation in case of collections of r.v.s.

We already showed that:

$$E[g(x,y)] = \begin{cases} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y) f_{x,y}(x,y) dx dy & (\text{if } x,y \text{ are jointly conts}) \\ \sum_{\forall x_i} \sum_{\forall y_i} g(x_i, y_i) f_{x,y}(x_i, y_i) & (\text{if } x,y \text{ are discrete r.v.s}) \end{cases}$$

~~Let~~ (All derivations from now on (unless specified explicitly) take care of  $x, y$  jointly conts. and give results on expectation using integrals, however the generic results do hold off for discrete r.v.s case also).

Consider  $Z = g(x,y) = x+y$

$$\begin{aligned} E[Z] &= E\{x+y\} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x+y) f_{x,y}(x,y) dx dy \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x f_{x,y}(x,y) dy dx + \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} y f_{x,y}(x,y) dx dy \\ &= \int_{-\infty}^{\infty} x \left[ \int_{-\infty}^{\infty} f_{x,y}(x,y) dy \right] dx + \int_{-\infty}^{\infty} y \left[ \int_{-\infty}^{\infty} f_{x,y}(x,y) dx \right] dy \\ &= \int_{-\infty}^{\infty} x f_x(x) dx + \int_{-\infty}^{\infty} y f_y(y) dy \\ &= E\{x\} + E\{y\} \end{aligned}$$

In general,  $E\{x_1 + \dots + x_n\} = \sum_{i=1}^n E\{x_i\}$ .

i.e. ~~Sum~~ Expectation of sum of rvs = sum of expectation of rvs  
(Note that we did NOT assume these rvs are independent) (I)

~~eg1~~ ~~Let~~  $X_i =$  indicator of success <sup>at  $i^{\text{th}}$  trial among</sup>  ~~$n$~~  <sup>independent and identical</sup> ~~Bernoulli~~ Bernoulli trials.

i.e. each  $X_i$  is a (independent) Bernoulli rv with  $P\{X_i=1\}=p$   
 $P\{X_i=0\}=1-p$

$$\text{Now } E\{X_i\} = 1 P\{X_i=1\} + 0 P\{X_i=0\} = p$$

Consider the rv  $X = X_1 + X_2 + \dots + X_n$ . In words,  $X$  is no. successes <sup>in</sup>  $n$  iid Bernoulli trials. Of course  $X$  follows a binomial distribution with parameters  $(n, p)$ .

Let compute  $E\{X\}$  using (I):

$$E\{X\} = \sum_{i=1}^n E\{X_i\} = \sum_{i=1}^n p = np \rightarrow \text{we know this is } E\{X\} \text{ of binomial rv}$$

eg2 Let  $X_i =$  indicator of change at  $i^{\text{th}}$  <sup>interval</sup> ~~interval~~ between two consec. <sup>(gap)</sup> ~~gaps~~   
tosses in  $n$  independent coin tosses of the same coin.

We have already seen that  $P\{X_i=1\} = 2p(1-p)$

$$\Rightarrow E\{X_i\} = P\{X_i=1\} = 2p(1-p)$$

Now consider  $X = X_1 + X_2 + \dots + X_{n-1}$ . In words,  $X$  is the number of changes in  $n$  tosses!

$$\Rightarrow E\{X\} = \sum_{i=1}^n E\{X_i\} = 2(n-1)p(1-p).$$

(Note that here  $X_i$  are not independent Bernoulli rvs, so  $X$  is not binomial distributed. However the expectation matches to that of a binomial rv!)

Now nothing particular about  $g(x, y) = x + y$ , this linearity prop. of  $E$  is ~~inferred~~ <sup>followed</sup> from the linearity prop. of integrals and summations. So in general one has:

eg

$$\textcircled{I} \text{ Consider } g(x, y, z) = \sum_{i=1}^l a_i f_i(x, y, z) + \sum_{i=1}^m b_i g_i(x, z) + \sum_{i=1}^n c_i h_i(x) + d$$

linear combinations of functions of  $x, y, z$ .

It is easy to see that:

$$E\{g(x, y, z)\} = \sum_{i=1}^l a_i E\{f_i(x, y, z)\} + \sum_{i=1}^m b_i E\{g_i(x, z)\} + \sum_{i=1}^n c_i E\{h_i(x)\} + d$$

to compute we will need joint dist. of  $x, y, z$

to compute we need joint dist. of  $x, z$

we need only dist. of  $x$ .

(Also this can be further generalized to functions over  $n$  r.v.s)

This is the linearity property of Expectation.

One can show another property of Expectation:

Suppose  $X, Y$  are independent r.v.s. Then:

$$E[g(x)h(y)] = E[g(x)]E[h(y)] \quad \textcircled{II}$$

Proof

$$\text{LHS} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x)h(y) f_{xy}(x, y) dx dy = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x)h(y) f_x(x) f_y(y) dx dy$$

$$= \left( \int_{-\infty}^{\infty} g(x) f_x(x) dx \right) \left( \int_{-\infty}^{\infty} h(y) f_y(y) dy \right) = \text{RHS.}$$

LHS involves double integral/summation whereas RHS involves two single integrals/summations. So it is useful observation.

Also, in general, we can show if  $X, Y$  are independent then  $g(X), h(Y)$  are also independent (provided  $g(X), h(Y)$  are well defined rvs!)

Proof:  $g(X), h(Y)$  are independent rvs

$\Leftrightarrow [g(X) \in B_1], [h(Y) \in B_2]$  are independent events  $\forall B_1, B_2 \in \mathcal{B}$

$\Leftrightarrow [X \in g^{-1}(B_1)], [Y \in h^{-1}(B_2)]$  " "

but  $g^{-1}(B_1)$  and  $h^{-1}(B_2)$  are not  $\sigma$ -algebras!

which is true since  $X, Y$  are themselves independent rvs!

### Moments of bivariate rvs

While discussing rvs we defined moments, absolute moments etc.

Now we can extend these definitions:

$$\mu_{m,n} = E[X^m Y^n] \rightarrow m, n \text{th moment of } X, Y$$

(this is some function of  $x, y$  hence we can compute its expectation!)

eg  $\mu_{1,0} = E\{X\} = \mu_X, \mu_{0,1} = E\{Y\} = \mu_Y, \mu_{1,1} = E\{XY\} \equiv \mu_{XY}$   
no on...

Similarly, one can extend the concept of central moments:

$$\sigma_{m,n} = E[(X - E\{X\})^m (Y - E\{Y\})^n] \rightarrow m, n^{\text{th}} \text{ central moment of } X, Y.$$

eg  $\sigma_{10} = 0 = \sigma_{01}$ ,  $\sigma_{20} = \text{var}(X) = \sigma_X^2$ ,  $\sigma_{02} = \text{var}(Y) = \sigma_Y^2$ ,

$$\sigma_{11} = E[(X - E\{X\})(Y - E\{Y\})] \equiv \text{Cov}(X, Y)$$

↓ symbol  
new definition

$\sigma_{11}$  is called as covariance of  $X, Y$ . (of course  $\text{Cov}(X, Y) = \text{Cov}(Y, X)$ ).

$\text{Cov}(X, Y)$  has none connection with the notion of "how correlated two rvs  $X, Y$  are". Lets explore this connection now:

(i) Suppose  $X, Y$  are independent. Then we can show  $\text{Cov}(X, Y) = 0$

Proof:  $\text{Cov}(X, Y) = E[(X - E\{X\})(Y - E\{Y\})]$

$$= E\left\{ \left[ (XY + E\{X\}E\{Y\} - XE\{Y\} - YE\{X\}) \right] \right\}$$

$$= E[XY] - E\{X\}E\{Y\} \rightarrow \text{linearity prop. of } E$$

$$= E\{X\}E\{Y\} - E\{X\}E\{Y\} \rightarrow \because X, Y \text{ are independent (by II)}$$

$$= 0$$

So  $X, Y$  are independent  $\Rightarrow \text{Cov}(X, Y) = 0$

However  $\text{Cov}(X, Y) = 0 \not\Rightarrow X, Y$  are independent.

Here is the counter eg:

Consider  $Y = X^2$  and  $X$  is such that  $E\{X\} = E\{X^3\} = 0$ .

Note that  $Y, X$  are surely dependent (not independent!)

However, for this eg:  $\text{Cov}(X, Y) = \text{Cov}(X, X^2)$

$$= E[X^3] - E[X]E[X^2] = 0$$

So  $\text{Cov}(X, Y) = 0 \not\Rightarrow X, Y$  are independent.

(Note that an eg. of  $X$  such that  $E[X] = E[X^3] = 0$  is the std. Normal r.v. In fact in assignment you showed that all odd moments of a std. Normal r.v. are zero.) Also you showed that  $Y = X^2$  has Chi-square distribution if  $X$  is std. Normal)

→ For  $X, Y$  Normal r.v. such that  $\text{Cov}(X, Y) = 0$  it turns out that ~~indeed  $X, Y$  are independent~~ it turns out that indeed  $X, Y$  are independent! So Normal r.v.'s are an exception! and the converse holds!!

We may say  $X, Y$  are uncorrelated if  $\text{Cov}(X, Y) = 0$ .

(Uncorrelated is true in some sense weaker cond. than independence)

In fact we can quantify the "correlation" between two r.v.'s using what is known as the correlation coefficient defined as

$$\rho_{XY} = \frac{\text{Cov}(X, Y)}{\sigma_X \sigma_Y}$$

One of course  $\rho_{XY} = 0 \Rightarrow \text{Cov}(X, Y) = 0 \Rightarrow X, Y$  are uncorrelated

Also one can show that:

$|\rho_{XY}| \leq 1$  &  $\rho_{XY} = \pm 1$  implies "perfect" correlation in the sense that  $X, Y$  are linearly dependent!



Proof: TST  $|\rho_{xy}| \leq 1$

i.e. TST  $(\rho_{xy})^2 \leq 1$

i.e. TST  $(\text{cov}(X, Y))^2 \leq \sigma_x^2 \sigma_y^2$

i.e. TST  $(E[(X - E\{X\})(Y - E\{Y\})])^2 \leq E[(X - E\{X\})^2] E[(Y - E\{Y\})^2]$

(lets put  $X' = X - E\{X\}$ ,  $Y' = Y - E\{Y\}$ )

i.e. TST  $(E[X'Y'])^2 \leq E[X'^2] E[Y'^2]$  (III)

→ This is known as Cauchy-Schwartz inequality

This inequality also appears in linear algebra (vector spaces) and is a fundamental inequality. In fact this being satisfied in (III) form motivates the study of vector spaces of r.v.s!!

→ Here is some intuition:

+ Suppose there exists some vector space in which inner product is given by  $E[X'Y']$  i.e.  $\langle v_1, v_2 \rangle = E[X'Y']$

It is easy to see,  $\langle v_1, v_1 \rangle = E[X'^2]$

$\langle v_2, v_2 \rangle = E[Y'^2]$

but we know that  $(\langle v_1, v_2 \rangle)^2 \leq \langle v_1, v_1 \rangle \langle v_2, v_2 \rangle$

↓  
 $\Rightarrow (\|v_1\| \|v_2\| \cos \theta)^2 \leq \|v_1\|^2 \|v_2\|^2$

→  $|\cos \theta| \leq 1$  which is true of course.

So (III) is extension of Cauchy-Schwartz inequality in case of Euclidean vectors!

Proof of (III) is simple (& typical whenever Cauchy-Schwarz appears!)

Proof Consider  $E[(aX + Y)^2]$ . We know it is  $\geq 0$ .

$$\Rightarrow a^2 E[X^2] + 2a E[X'Y] + E[Y^2] \geq 0$$

$$\Leftrightarrow (E[X'Y])^2 \leq E[X^2] E[Y^2]$$

(discriminant  $\leq 0$ )

Also note that  $\rightarrow$  strict equality appears if and only if  $aX + Y = 0$  i.e.  $X, Y$  are linearly dependent!  
(with prob. 1)

This proves ~~the~~ overall claim that  $|\rho_{XY}| \leq 1$  &

$$\rho_{XY} = \begin{cases} 0 & \text{is case where } X, Y \text{ are uncorrelated} \\ \pm 1 & \text{is case of "highest" correlation} \\ & \text{i.e. } X, Y \text{ are linearly related!} \end{cases}$$

Now go back to the example of wine flu. We want to know which of symptoms  $X_1, X_2, \dots, X_n$  is most important symptom that characterizes  $Y$  (presence of wine flu or not).

$\rightarrow$  (one answer) Compute  $|\rho_{X_1 Y}|, |\rho_{X_2 Y}|, \dots, |\rho_{X_n Y}|$

whichever symptom has max  $\uparrow$  we can say it has "highest correlation" with disease and we can hence declare it to be the most important symptom for the disease!

Now let's compute  $\text{var}(Z)$  where  $Z = X + Y$ , in terms of  $\text{var}$  &  $\text{cov}$  of  $X, Y$ :

$$\begin{aligned}\text{var}(Z) &= \text{var}(X+Y) = E\{(X+Y - E[X+Y])^2\} \\ &= E\{((X - E[X]) + (Y - E[Y]))^2\} \\ &= E\{(X - E[X])^2\} + E\{(Y - E[Y])^2\} + 2E\{(X - E[X])(Y - E[Y])\} \\ &= \text{var}(X) + \text{var}(Y) + 2\text{Cov}(X, Y).\end{aligned}$$

Note that  $\text{var}(X+Y) = \text{var}(X) + \text{var}(Y) + 2\text{Cov}(X, Y)$  can be written in the following (and) way:

~~$\text{var}(X+Y)$~~

→ Apart from this sometimes "vectorial" versions of mean & variance are defined. Here's the motivation:

Suppose we want to find  $E[a^T X]$ .  $a^T X = \sum_{i=1}^n a_i X_i$ .   
  $X$  is an  $n$ -dimensional multivariate r.v.

$$E[a^T X] = E\left[\sum_{i=1}^n a_i X_i\right] = \sum_{i=1}^n a_i E[X_i] \rightarrow \text{by linearity prop. of } E.$$

$$= a^T E[X]$$

new notation  $E[X] = \begin{bmatrix} E[X_1] \\ \vdots \\ E[X_n] \end{bmatrix}$

This  $E[X]$  (exp. of multivariate r.v.) is nothing but the vector of expectations of the individual r.v.s. This is also sometimes called as the 'mean vector' of the multivariate r.v.  $X$ .

Now suppose we wish to find  $\text{var}(a^T X)$ :

$$\begin{aligned}\text{var}(a^T X) &= E[(a^T X - E[a^T X])^2] = E[(a^T X - a^T E[X])^2] \\ &= E[a^T (X - E[X]) a^T (X - E[X])]\end{aligned}$$

since transpose of a number is the number itself we get

$$\text{var}(a^T X) = E \left[ a^T \underbrace{(X - E\{X\})(X - E\{X\})^T}_{n \times n \text{ matrix}} a \right]$$

by linearity prop. of  $E$  we can show  $\rightarrow = a^T \Sigma a$  where

$\Sigma$  is called as the covariance matrix whose entries are given by  $\Sigma_{ij} = \text{Cov}(X_i, X_j)$   
 $\downarrow$   $i, j$   $^{\text{th}}$  element of the covariance matrix.

$\rightarrow$  for a 2-d case we can go through the steps easily:

$$\text{var}(a_1 X_1 + a_2 X_2) = E \left[ (a_1 X_1 + a_2 X_2 - E[a_1 X_1 + a_2 X_2])^2 \right]$$

$$= a_1^2 \text{var}(X_1) + a_2^2 \text{var}(X_2) + 2 a_1 a_2 \text{Cov}(X_1, X_2)$$

(By repeated appl. of linearity prop. of  $E$ , similar to (IV))

$$\rightarrow = [a_1 \ a_2] \begin{bmatrix} \text{var}(X_1) & \text{Cov}(X_1, X_2) \\ \text{Cov}(X_1, X_2) & \text{var}(X_2) \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$$

$$= a^T \Sigma a$$

$\rightarrow$  Here sometimes instead of talking about moments and central moments of collections of r.v.s, people talk abt mean vector and covariance matrix of the corresponding multivariate r.v.

# CONDITIONAL EXPECTATION

Suppose  $X, Y$  are two random variables. Now in all cases

- (i)  $X, Y$  are discrete (ii)  $X, Y$  are jointly conts (iii) one of them is conts. other is discrete,

we defined  $f_{X/Y}(x/y) \rightarrow$  either conditional pmf of conditional pdf given  $Y=y$  ~~or~~  $\downarrow$  if  $X$  is discrete  $\downarrow$  if  $X$  is conts.

Now the r.v for which  $\uparrow$  is the pmf or pdf is denoted by:

$$Z = X/Y=y$$

We already now that  $Z$  exactly takes those values which  $X$  takes and its pmf/pdf ~~is~~ given by  $f_{X/Y}(x/y)$ .

Since  $Z$  is a random variable we can talk about its expectation:

$$E[Z] = E[X/Y=y] = \begin{cases} \int_{-\infty}^{\infty} x f_{X/Y}(x/y) dx & \text{if } X \text{ is conts r.v.} \\ \sum_{x=x_i} x_i f_{X/Y}(x_i/y) & \text{if } X \text{ is discrete r.v.} \end{cases}$$

This is called as conditional expectation of  $X$  given that  $Y=y$ .

$\rightarrow$  Now we can further extend this concept:

$$X, Y \text{ are r.v \& may } Z = g(x, y)$$

we can talk abt.  $f_{X/Z}(x/z)$  i.e.  $f_{X/g(x,y)}(x/z)$

and in turn talk abt.  $E[X/g(x,y)=z]$  and so on.....