

# Chapter 5

# Synchronous Sequential Logic

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#### **Outline**

- Sequential Circuits
- Latches
- Flip-Flops
- Analysis of Clocked Sequential Circuits
- State Reduction and Assignment
- Design Procedure



#### Sequential Circuits

- Consist of a combinational circuit to which storage elements are connected to form a feedback path
- State the state of the memory devices now, also called current state
- Next states and outputs are functions of inputs and present states of storage elements

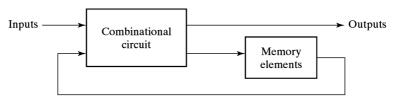
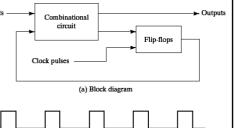


Fig. 5-1 Block Diagram of Sequential Circuit

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#### Two Types of Sequential Circuits

- Asynchronous sequential circuit
  - Depends upon the input signals at any instant of time and their change order
  - May have better performance but hard to design
- Synchronous sequential circuit
  - Defined from the knowledge of its signals at discrete instants of time
  - Much easier to design (preferred design style)
  - Synchronized by a periodic train of clock pulses



(b) Timing diagram of clock pulses



### **Memory Elements**

- Allow sequential logic design
- Latch a level-sensitive memory element
  - SR latches
  - D latches
- Flip-Flop an edge-triggered memory element
  - Master-slave flip-flop
  - Edge-triggered flip-flop
- RAM and ROM a mass memory element
  - Discussed in Chapter 7

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#### Latches

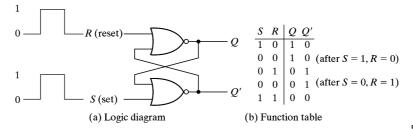
- The most basic types of flip-flops operate with signal levels
- The basic circuits from which all flip-flops are constructed
- Useful for storing binary information and for the design of asynchronous sequential circuits
  - Not practical for use in synchronous sequential circuits
  - Avoid to use latches as possible in synchronous sequential circuits to avoid design problems

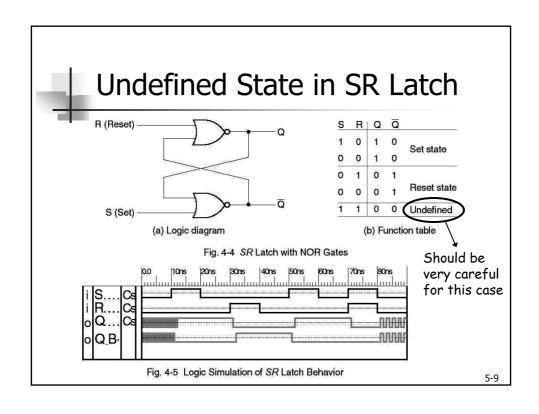
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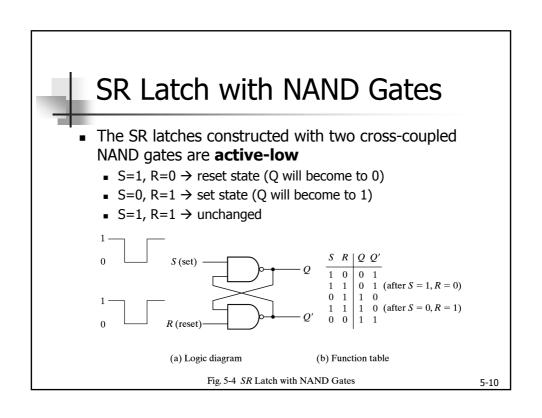


#### SR Latch

- A circuit with two cross-coupled NOR gates or two cross-coupled NAND gates
- Two useful states:
  - S=1,  $R=0 \rightarrow$  set state (Q will become to 1)
  - S=0,  $R=1 \rightarrow$  reset state (Q will become to 0)
- When S=0 and  $R=0 \rightarrow$  keep the current value

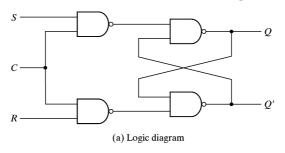








- Add an additional control input to determine when the state of the latch can be changed
- C=0: S and R are disabled (no change at outputs)
- C=1: S and R are active-high



C	S	R	Next state of Q
0	X	X	No change
1	0	0	No change
1	0	1	Q = 0; Reset state
1	1	0	Q = 1; set state
1	1	1	Indeterminate

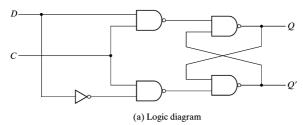
(b) Function table

Fig. 5-5 SR Latch with Control Input

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# D Latch

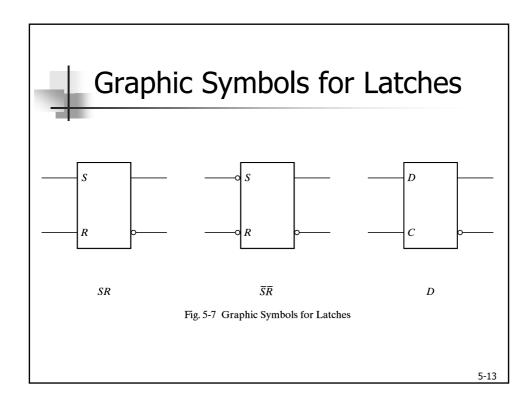
- D latch has only two inputs: D(data) and C(control)
  - Use the value of D to set the output value
  - Eliminate the indeterminate state in the SR latches
- The D input goes directly to the S input and its complement is applied to the R input
  - $\blacksquare$  D=1  $\rightarrow$  Q=1  $\rightarrow$  S=1, R=0



 $\begin{array}{c|c} C \ D & \text{Next state of } Q \\ \hline 0 \ X & \text{No change} \\ 1 \ 0 & Q = 0; \text{Reset state} \\ 1 \ 1 & Q = 1; \text{Set state} \\ \end{array}$ 

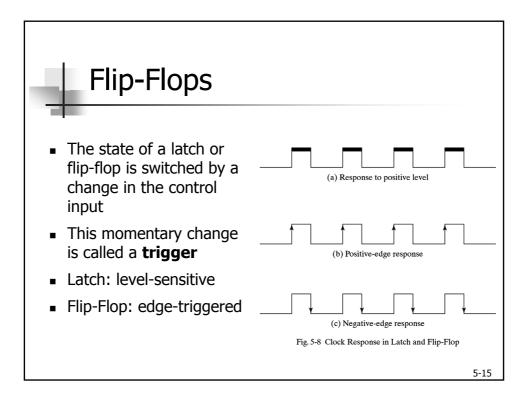
(b) Function table

Fig. 5-6 D Latch



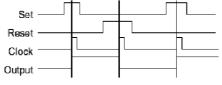
# Outline

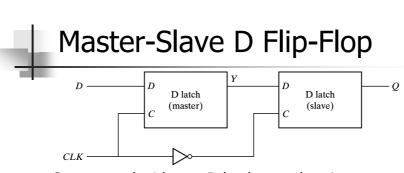
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# Latch vs. Flip-Flop

- Latch:
  - Change stored value under specific status of the control signals
  - Transparent for input signals when control signal is "on"
  - May cause combinational feedback loop and extra changes at the output
- Flip-Flop:
  - Can only change stored value by a momentary switch in value of the control signals
  - Cannot "see" the change of its output in the same clock pulse
  - Encounter fewer problems than using latches





- Constructed with two D latches and an inverter
- The first latch (master) is enabled when CLK=1
  - It reads the input changes but stops before the second one
- The second latch (slave) is enabled when CLK=0
  - Close the first latch to isolate the input changes
  - Deliver the final value at the moment just before CLK changes
- The circuit samples the D input and changes its output Q only at the **negative-edge** of the controlling clock

# Edge-Triggered D Flip-Flop

- If only SR latches are available, three latches are required
- Two latches are used for locking the two inputs (CLK & D)
- The final latch provides the output of the flip-flop

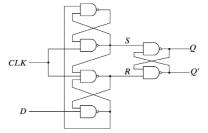
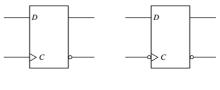


Fig. 5-10 D-Type Positive-Edge-Triggered Flip-Flop



(a) Positive-edg

(a) Negative-edge

Fig. 5-11 Graphic Symbol for Edge-Triggered D Flip-Flop



#### Setup & Hold Times

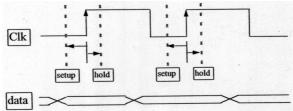
- The response time of a flip-flop to input changes must be taken into consideration
- Setup Time: The length of time that data must stabilize before the clock transition
  - The maximum data path is used to determine if the setup time is met
- Hold Time: The length of time that data must remain stable at the input pin after the active clock transition
  - The minimum data path is used to determine if hold time is met

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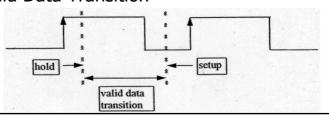


## Setup & Hold Times

Timing Diagram



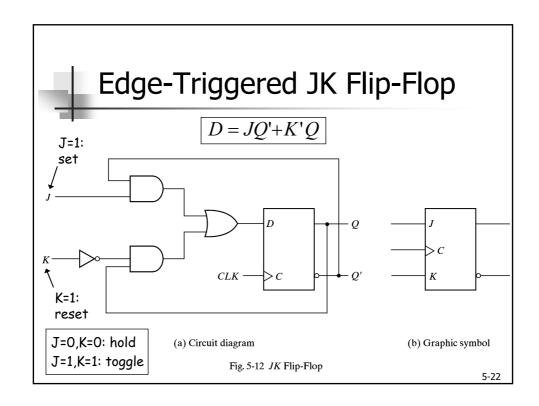
Valid Data Transition

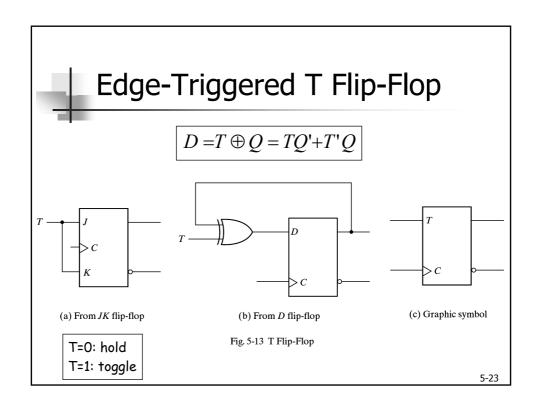


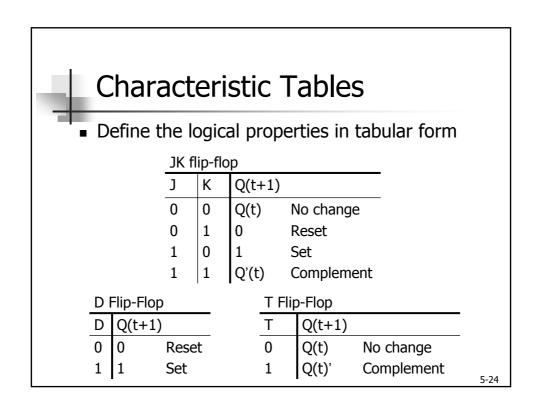


### Other Flip-Flops

- The most economical and efficient flip-flop is the edge-triggered D flip-flop
  - It requires the smallest number of gates
- Other types of flip-flops can be constructed by using the D flip-flop and external logic
  - JK flip-flop
  - T flip-flops
- Three major operations that can be performed with a flip-flop:
  - Set it to 1
  - Reset it to 0
  - Complement its output









#### **Characteristic Equations**

- Algebraically describe the next state
- Can be derived from characteristic tables
- D flip-flop:

$$Q(t+1) = D$$

■ JK flip-flop:

$$Q(t+1) = JQ'+K'Q$$

■ T flip-flop:

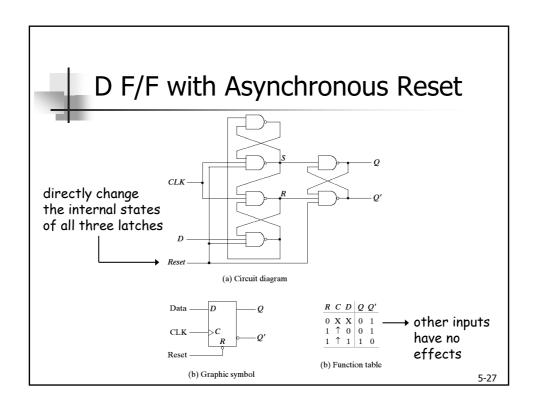
$$Q(t+1) = T \oplus Q = TQ' + T'Q$$

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#### **Direct Inputs**

- Force the flip-flop to a particular state immediately
  - Independent of clock signal
  - Have higher priority than any other inputs
  - Useful to bring all flip-flops from unknown into known state while power up
- The input that sets the flip-flop to 1 is called preset or direct set
- The input that clears the flip-flop to 0 is called **clear** or **direct reset**
- Also called **asynchronous** set/reset



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### Sequential Circuit Analysis

- The behavior of a clocked sequential circuit is determined from
  - The inputs
  - The outputs
  - The state of its flip-flops
- The outputs and the next state are both a function of the inputs and the present state
- To analyze a sequential circuit, we can use
  - State equations
  - State table
  - State diagram
  - Flip-Flop input equations

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### **State Equations**

- Specify the next state as a function of the present state and inputs
  - Also called transition equation
- Analyze the combinational part directly
- EX:

$$A(t+1) = A(t)x(t) + B(t)x(t)$$

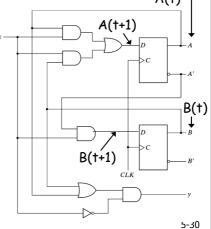
$$\implies$$
 A(t+1) = Ax + Bx

$$B(t+1) = A'(t) x(t)$$

$$\implies$$
 B(t+1) = A'x

$$y(t)=[A(t)+B(t)] x(t)$$

 $\implies$  y=(A+B)x'



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#### State Table

- Enumerate the time sequence of inputs, outputs, and flip-flop states
  - Also called transition table
  - Similar to list the truth table of state equations
- Consist of four sections
  - Present state, input, next state, and output
- A sequential circuit with m flip-flops and n inputs need 2<sup>m+n</sup> rows in the state table

1	sent ate	input	Next state		output
Α	В	Х	Α	В	У
0	0	0	0	0	0
0	0	1	0	1	0
0	1	0	0	0	1
0	1	1	1	1	0
1	0	0	0	0	1
1	0	1	1	0	0
1	1	0	0	0	1
1	1	1	1	0	0

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#### Second Form of State Table

- The state table has only three section: present state, next state, and output
- The input conditions are enumerated under next state and output sections

Pres	sent		Next	Output			
Sta	ate	X=	X=0 X=1			X=0	X=1
Α	В	Α	В	Α	В	Υ	Υ
0	0	0	0	0	1	0	0
0	1	0	0	1	1	1	0
1	0	0	0	1	0	1	0
1	1	0	0	1	0	1	0



#### State Diagram

- Graphically represent the information in a state table
  - Circle: a state (with its state value inside)
  - Directed lines: state transitions (with inputs/outputs above)
- Ex: starting from state 00
  - If the input is 0, it stays at state 00 with output=0
  - If the input is 1, it goes to state 01 with output=0
- The state table is easier to derive from a given logic diagram and state equations
- The state diagram is suitable for human interpretation

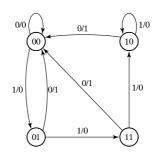


Fig. 5-16 State Diagram of the Circuit of Fig. 5-15

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### Flip-Flop Input Equations

- To draw the logic diagram of a sequential circuit, we need
  - The type of flip-flops
  - A list of Boolean expressions of the combinational circuits
- The Boolean functions for the circuit that generates external outputs is called output equations
- The Boolean functions for the circuit that generates the inputs to flip-flops is flip-flop input equations
  - Sometimes called excitation equations
- The flip-flop input equations provide a convenient form for specifying the logic diagram of a sequential circuit

■ Ex: (Fig. 5-15)

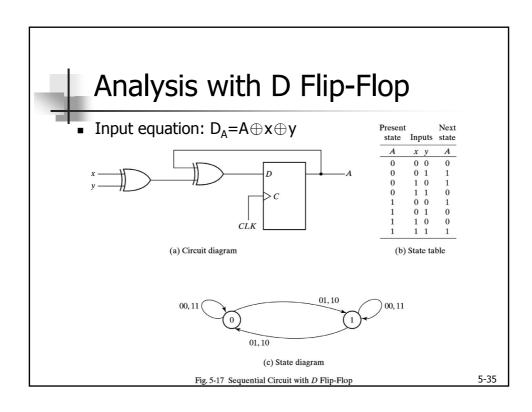
Input:

Output:

 $D_A = Ax + Bx$ 

y=(A+B)x'

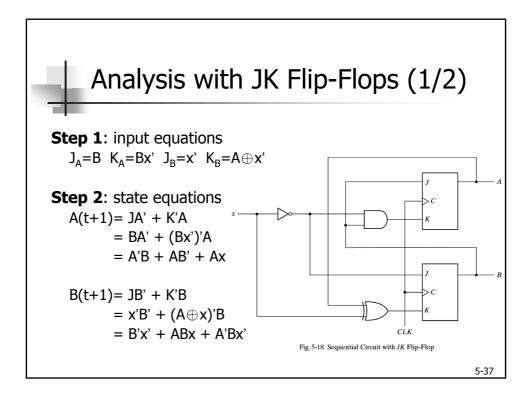
 $D_B = A'x$ 





### Analysis with Other Flip-Flops

- The sequential circuit using other flip-flops such as JK or T type can be analyzed as follows
  - Determine the flip-flop input equations in terms of the present state and input variables
  - List the binary values of each input equation
  - Use the corresponding flip-flop characteristic table to determine the next state values in the state table



# Analysis with JK Flip-Flops (2/2)

#### Step 3: state table

	esent tate	Input		ext ate		-	-Flop puts		
Α	В	Х	Α	В	J <sub>A</sub>	K <sub>A</sub>	J <sub>B</sub>	K <sub>B</sub>	
0	0	0	0	1	0	0	1	0	
0	0	1	0	0	0	0	0	1	
0	1	0	1	1	1	1	1	0	
0	1	1	1	0	1	0	0	1	
1	0	0	1	1	0	0	1	1	
1	0	1	1	0	0	0	0	0	
1	1	0	0	0	1	1	1	1	
1	1	1	1	1	1	0	0	0	

Step 4: state diagram

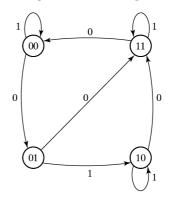
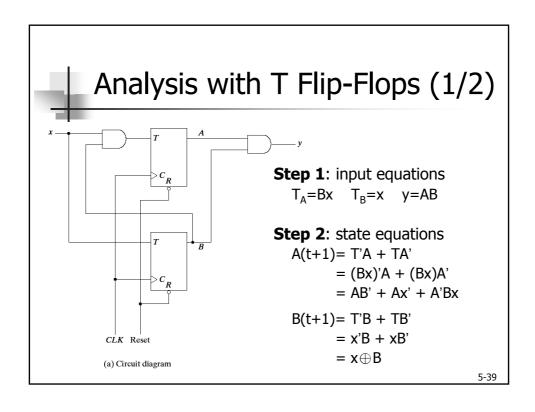
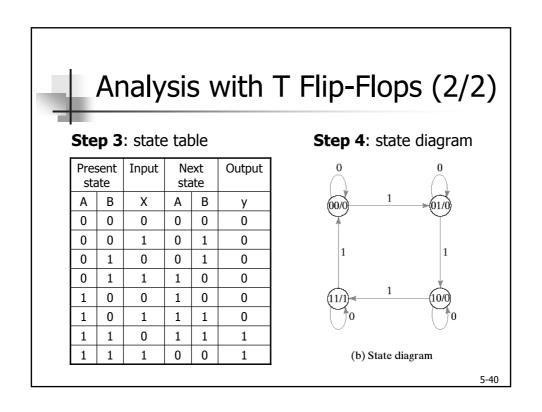
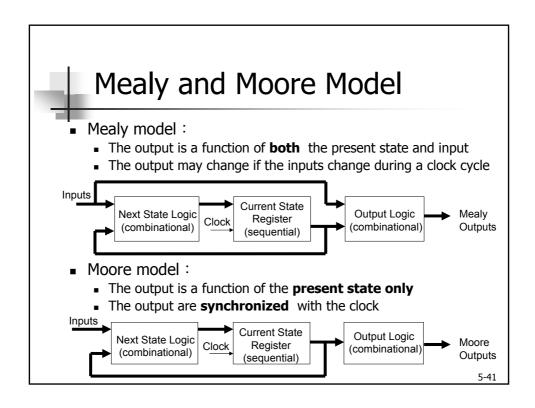


Fig. 5-19 State Diagram of the Circuit of Fig. 5-18







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#### **State Reduction**

- Reducing the number of states in a state table, while keeping the external input-output requirements unchanged
- Example:
  - Total 7 states
  - A sequence as follows

state	a	а	b	С	d	е	f	f	g	f	g	а
input	0	1	0	1	0	1	1	0	1	0	0	
output	0	0	0	0	0	1	1	0	1	0	0	

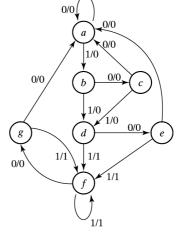


Fig. 5-22 State Diagram

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#### **State Reduction Rules**

 Two states are said to be equivalent if, for every possible inputs, they give exactly the same output and have equivalent next state

Present	Next	State	Output			
State	X=0	X=1	X=0	X=1		
a	a	b	0	0		
b	С	d	0	0		
С	a	d	0	0		
d	е	f	0	1		
e	а		0	1		
f	g	f	0	1		
g	а		0	1		

Present	Next	State	Output		
State			X=0	•	
a	а	b	0	0	
b	С	d	0	0	
С	a	d	0	0	
d	е	f	0	1	
е	a	f	0	1	
f	e	f	0	1	

delete state g and replaced with state e



#### **Further State Reduction**

- After the first reduction, we can see that state d and state f will have the same output and next state for both x=0 and x=1
  - Further reduce one state

Present		State	Output		
State	X=0	X=1	X=0	X=1	
а	a	b	0	0	
b	С	d	0	0	
С	a	d	0	0	
d	e	f	0	1	
е	a	f	0	1	
	е	f	0	1	

Present	Next		Output		
State	X=0	X=1	X=0	X=1	
a	а	b	0	0	
b	С	d	0	0	
С	a	d	0	0	
d	е	<b>a</b>	0	1	
е	a	<b>d</b>	0	1	

delete state f and replaced with state d

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# Reduced State Diagram

- After reduction, the circuit has only 5 states with same input/output requirements
- Original output sequence:

_												
state	а	a	b	С	d	е	f	f	g	f	g	а
input	0	1	0	1	0	1	1	0	1	0	0	
output	0	0	0	0	0	1	1	0	1	0	0	

• Reduced output sequence:

state	а	а	b	С	d	е	d	d	e	d	e	a
input	0	1	0	1	0	1	1	0	1	0	0	
output	0	0	0	0	0	1	1	0	1	0	0	

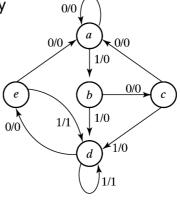


Fig. 5-23 Reduced State Diagram



# Implication Chart Method (1/3)

■ Step 1: build the implication chart

Present	Next S	Present	
State	X = 0	1	Output
a	d	c	0
b	f	h	0
c	e	d	1
d	a	e	0
e	c	a	1
f	f	b	1
g	b	h	0
h	c	g	1

b	d-f c-h	<b>←</b>	. a≡l	b ift	f d =	€f ar	nd c	≡h		
С	X	X	<b>←</b>	b≠c	sin	ce o	utpu	ıts	diff	er
d	များ များ	a-f e-h	X							
е	X	X	a-d	X						
f	X	X	e-f b-d	X	c-f a-b					
g	b-d c-h	b-f	X	a-b e-h	X	X				
h	X	X	c-e d-g	X	a-g	c-f b-g	X			
	а	b	С	d	е	f	g			

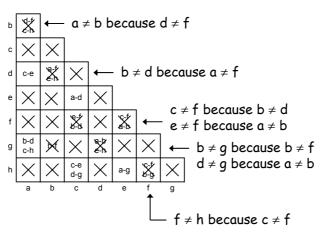
\*For details, see "Fundamentals of Logic Design", 4th Ed., by C. H. Roth, Jr.

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### Implication Chart Method (2/3)

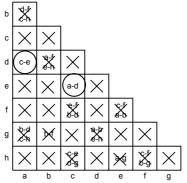
■ Step 2: delete the node with unsatisfied conditions





### Implication Chart Method (3/3)

■ Step 3: repeat Step 2 until equivalent states found



Present	Next S	Present	
State	X = 0	1	Output
a	a	c	0
b	f	h	0
c	c	a	1
f	f	b	1
g	b	h	0
h	c	g	1

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#### State Assignment

- Assign coded binary values to the states for physical implementation
- For a circuit with m states, the codes must contain n bits where 2<sup>n</sup> >= m
- Unused states are treated as don't care conditions during the design

Assign	Assignment:						
a = 000	d = 011						
b = 001	e = 100						
c = 010							

- Don't cares can help to obtain a simpler circuit
- There are many possible state assignments
  - Have large impacts on the final circuit size

Present	Next	State	Output		
State	X=0	X=1	X=0	X=1	
000	000	001	0	0	
001	010	011	0	0	
010	000	011	0	0	
011	100	011	0	1	
100	000	011	0	1	
				E E0	



### Popular State Assignments

- Binary: assign the states in binary order
  - Typical method without other considerations
- Gray code: assign the states by gray code
  - Lower power consumption during state transitions (if in order)
- One-hot: assign a specific flip-flop for each state
  - Simplify the circuit design but may have larger hardware cost

State	Assignment 1	Assignment 2	Assignment 3
	Binary	Gray code	One-hot
а	000	000	00001
b	001	001	00010
С	010	011	00100
d	011	010	01000
е	100	110	10000

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#### Design Procedure

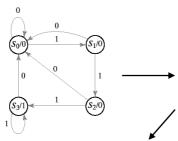
- Design procedure of synchronous sequential circuits:
  - Derive a state diagram for the circuit from specifications
  - Reduce the number of states if necessary
  - Assign binary values to the states
  - Obtain the binary-coded state table
  - Choose the type of flip-flop to be used
  - Derive the simplified flip-flop input equations and output equations
  - Draw the logic diagram
- Step 4 to 7 can be automated
  - Use HDL synthesis tools

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## Synthesis Using D Flip-Flops

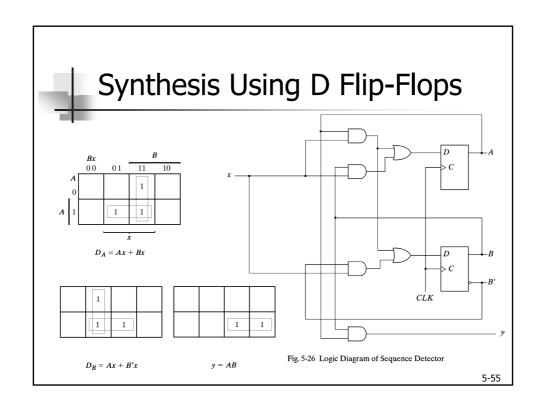
Ex: design a circuit that detects 3 or more consecutive 1's at inputs



$$A(t+1) = D_A(A, B, x) = \sum (3,5,7)$$
  
$$B(t+1) = D_B(A, B, x) = \sum (1,5,7)$$

$y(A,B,x) = \sum_{i=1}^{n} x_i dx_i$	(6,7)
--------------------------------------	-------

	sent ate	Input	Next state		Output	
Α	В	Х	Α	В	у	
0	0	0	0	0	0	
0	0	1	0	1	0	
0	1	0	0	0	0	
0	1	1	1	0	0	
1	0	0	0	0	0	
1	0	1	1	1	0	
1	1	0	0	0	1	
1	1	1	1	1	1	





#### **Excitation Tables**

- Record the flip-flop input conditions that will cause the required transition in STG
  - Equal to next state equations for D flip-flop
- For JK flip-flop:
  - J=0, K=X: no change (JK=00) or set to zero (JK=01)
  - J=1, K=X: toggle (JK=11) or set to one (JK=10)
  - J=X, K=1: toggle (JK=11) or set to zero (JK=01)
  - J=X, K=0: no change (JK=00) or set to one (JK=10)

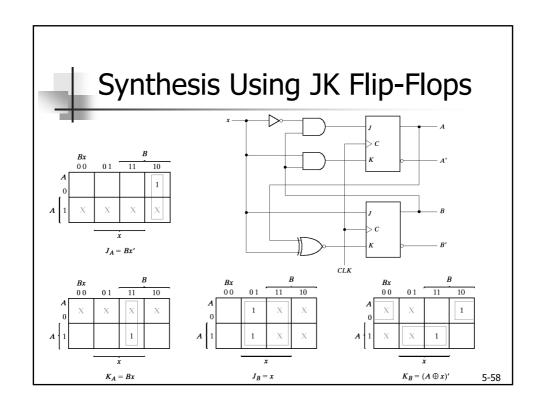
JK F/F	Q(t)	Q(t+1)	J	K	Q(t)	Q(t+1)	T	Т
F/F	0	0	0	Х	0	0	0	F/F
	0	1	1	Χ	0	1	1	
	1	0	Χ	1	1	0	1	
	1	1	Χ	0	1	1	0	F F6
								5-56



# Synthesis Using JK Flip-Flops

- Derive the state table with the excitation inputs
- Other design procedures are the same

	sent ate	Input	Next State			Flip-Flop Inputs				
Α	В	X	Α	A B		$J_A$	$K_A$	$J_{B}$	K <sub>B</sub>	
0	0	0	0	0		0	Χ	0	X	
0	0	1	0	1		0	Χ	1	Χ	
0	1	0	1	0		1	Χ	Χ	1	
0	1	1	0	1		0	Χ	Χ	0	
1	0	0	1	0		Χ	0	0	Χ	
1	0	1	1	1		Χ	0	1	Χ	
1	1	0	1	1		Χ	0	Χ	0	
1	1	1	0	0		Χ	1	Χ	1	





# Synthesis Using T Flip-Flops

- Derive the state table with the excitation inputs
- Other design procedures are the same

3-bit binary counter
(000)
(001) (111)
(010) (110)
100
(10)

Pre	sent S	state	Next State			Flip-Flop Inputs		
A2	A1	Α0	A2	A1	Α0	T <sub>A2</sub>	T <sub>A1</sub>	T <sub>A0</sub>
0	0	0	0	0	1	0	0	1
0	0	1	0	1	0	0	1	1
0	1	0	0	1	1	0	0	1
0	1	1	1	0	0	1	1	1
1	0	0	1	0	1	0	0	1
1	0	1	1	1	0	0	1	1
1	1	0	1	1	1	0	0	1
1	1	1	0	0	0	1	1	1

