

Proving Programs Correct by Abstract Interpretation

**Supratik Chakraborty
IIT Bombay**

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Program Analysis: An Example

```
int x = 0, y = 0, z;  
read(z);  
while ( f(x, z) > 0) {  
    if ( g(z, y) > 10) {  
        x = x + 1; y = y + 100;  
    }  
    else if ( h(z) > 20) {  
        if (x >= 4) {  
            x = x + 1; y = y + 1;  
        }  
    }  
}
```

IDEAS?

- Run test cases
- Get code analyzed by many people
- Convince yourself by ad-hoc reasoning

What is the relation between x and y on exiting while loop?

Program Verification: An Example

```
int x = 0, y = 0, z;  
read(z);  
while ( f(x, z) > 0) {  
    if ( g(z, y) > 10) {  
        x = x + 1; y = y + 100;  
    }  
    else if ( h(z) > 20) {  
        if (x >= 4) {  
            x = x + 1; y = y + 1;  
        }  
    }  
}
```

IDEAS?

- Run test cases
- Get code analyzed by many people
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INVARIANT or PROPERTY

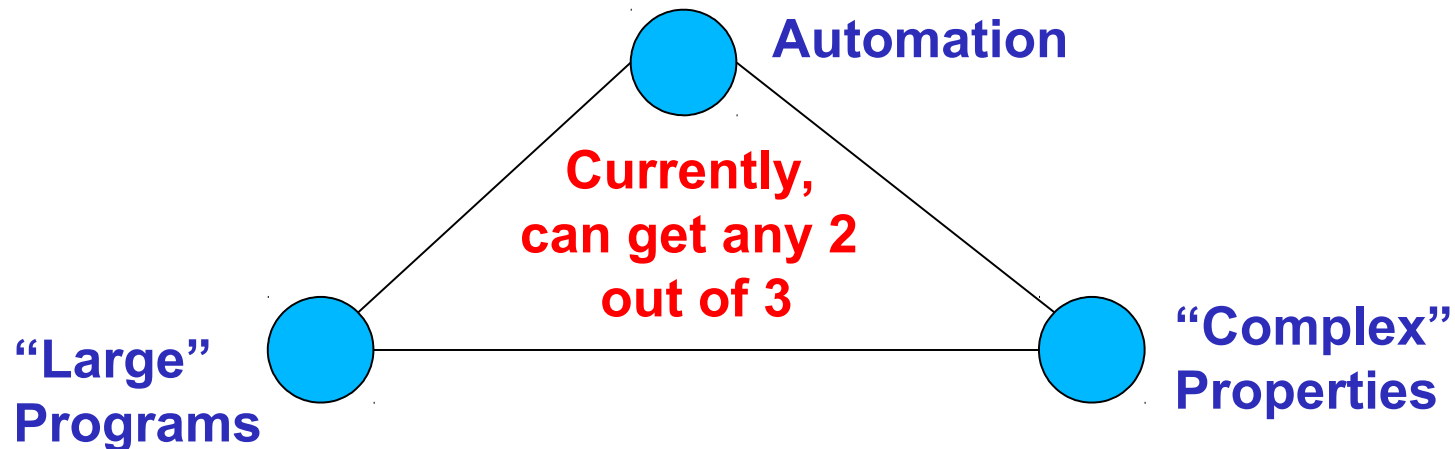
assert(x < 4 OR y >= 2);

Verification & Analysis: Close Cousins

- Both investigate relations between program variables at different program locations
- Verification: A (seemingly) special case of analysis
 - Yes/No questions
 - No simpler than program analysis
- Both problems **undecidable** (in general) for languages with loops, integer addition and subtraction
 - **Exact algorithm for program analysis/verification that works for all programs & properties: an impossibility**
 - But why care about arbitrary programs?

Hope for Real-Life Software

- Certain classes of analyses/property-checking of real-life software feasible in practice
 - Uses domain specific techniques, restrictions on program structure...
 - “Safety” properties of avionics software, device drivers, ...
- A practitioner’s perspective



Some Driving Factors

- Compiler design and optimizations
 - Since earliest days of compiler design
- Performance optimization
 - Renewed importance for embedded systems
- Testing, verification, validation
 - Increasingly important, given criticality of software
- Security and privacy concerns
- Distributed and concurrent applications
 - Human reasoning about all scenarios difficult

Successful Approaches in Practical Software Verification

- Use of sophisticated abstraction and refinement techniques
 - Domain specific as well as generic
- Use of constraint solvers
 - Propositional, quantified boolean formulas, first-order theories, ...
- Use of scalable symbolic reasoning techniques
 - Several variants of decision diagrams, combinations of decision diagrams & satisfiability solvers ...
- Incomplete techniques that scale to real programs

Focus of today's talk

Abstract Interpretation Framework

- Elegant **unifying framework** for several program analysis & verification techniques
- Several success stories
 - Checking properties of avionics code in Airbus
 - Checking properties of device drivers in Windows
 - Many other examples
 - Medical, transportation, communication ...
- But, **NOT a panacea**
- Often used in combination with other techniques

Sequential Program State

- Given sequential program P
 - State: information necessary to determine complete future behaviour
 - (pc, store, heap, call stack)
 - pc: program counter/location
 - store: map from program variables to values
 - heap: dynamically allocated/freed memory and pointer relations thereof
 - call stack: stack of call frames

Programs as State Transition Systems

➤ A simple program:

```
void func(int a, int b)
{ int x, y;
```

```
  L1: x = 0;
```

```
  L2: y = 1;
```

```
  L3: if (a >= b + 2)
```

```
    L4: a = y;
```

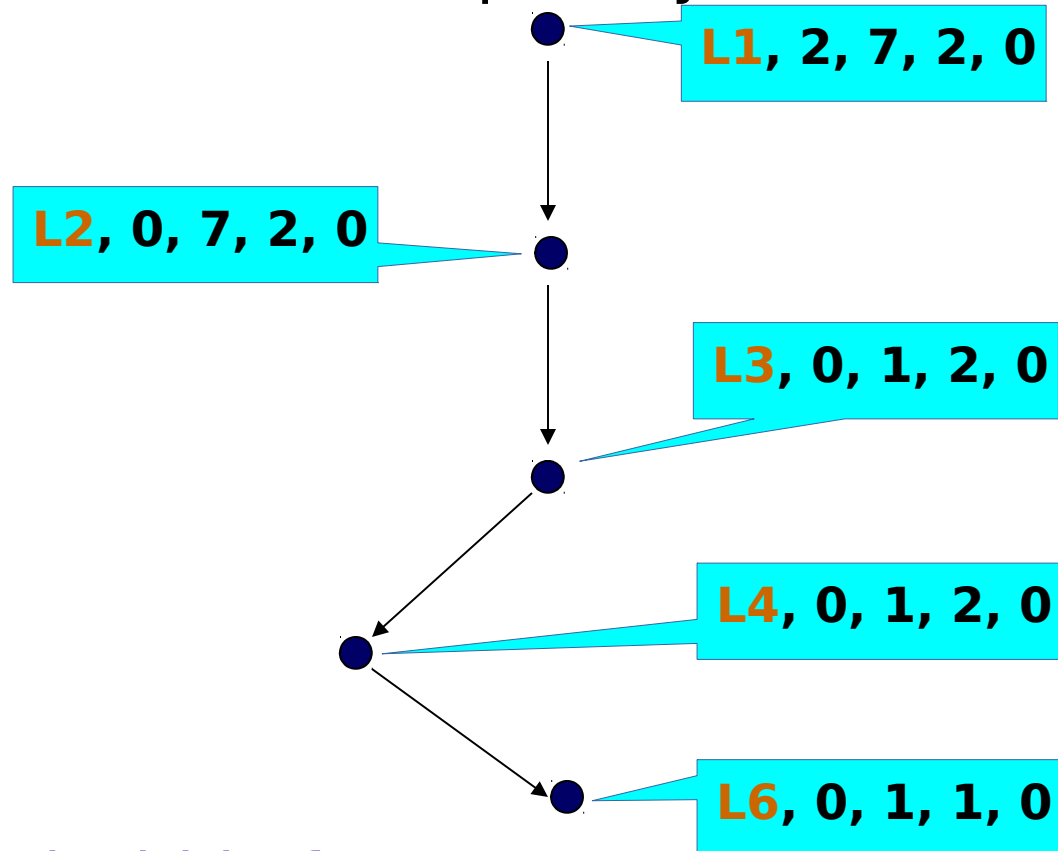
```
      else
```

```
    L5: b = x;
```

```
    L6: return;
```

```
}
```

State (pc, x, y, a, b)



State = (pc, store)

heap, stack unchanged within func

Programs as State Transition Systems

```
void func(int a, int b)
{ int x, y;
```

```
  L1: x = 0;
```

```
  L2: y = 1;
```

```
  L3: if (a >= b + 2)
```

```
    L4: a = y;
```

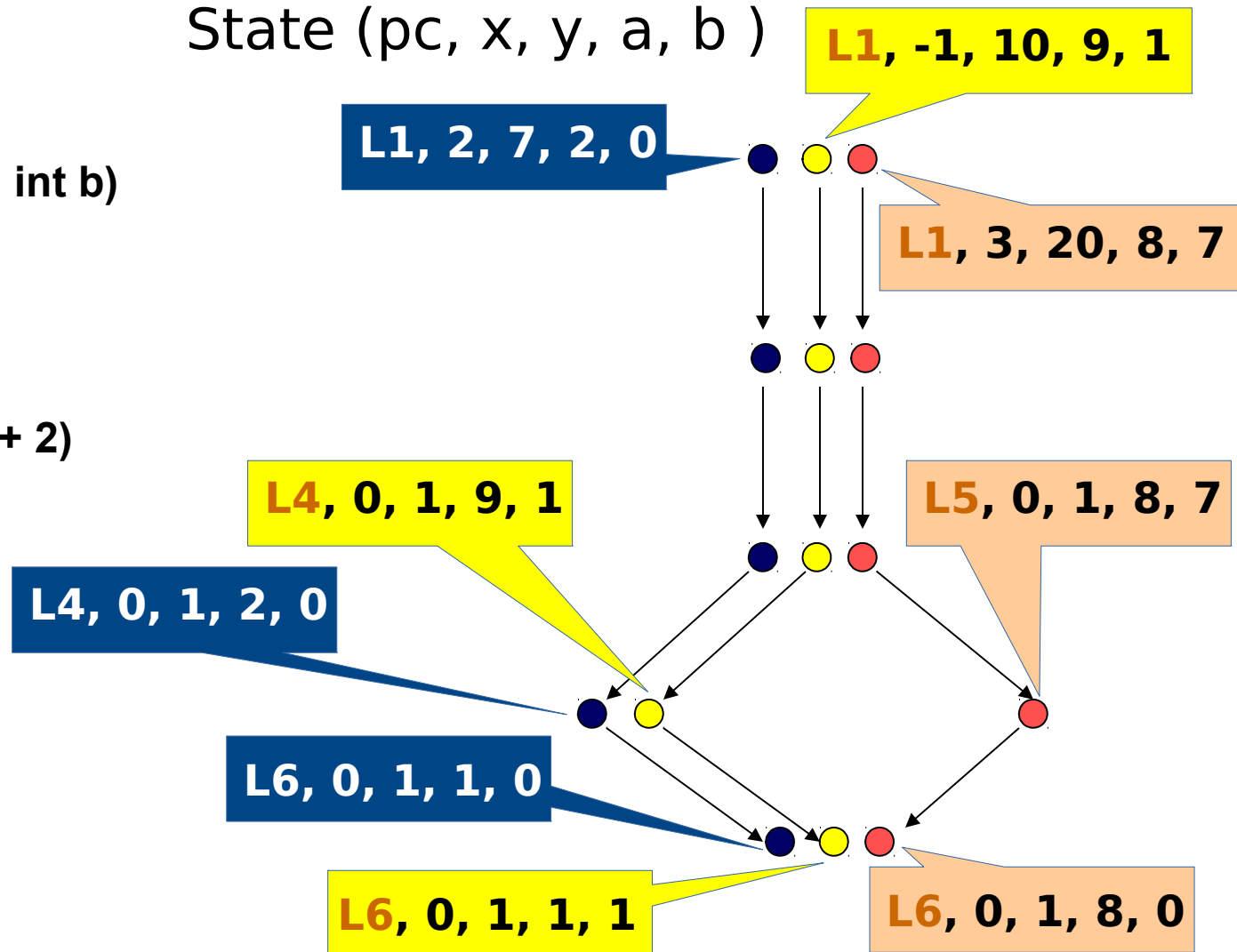
```
    else
```

```
    L5: b = x;
```

```
    L6: return;
```

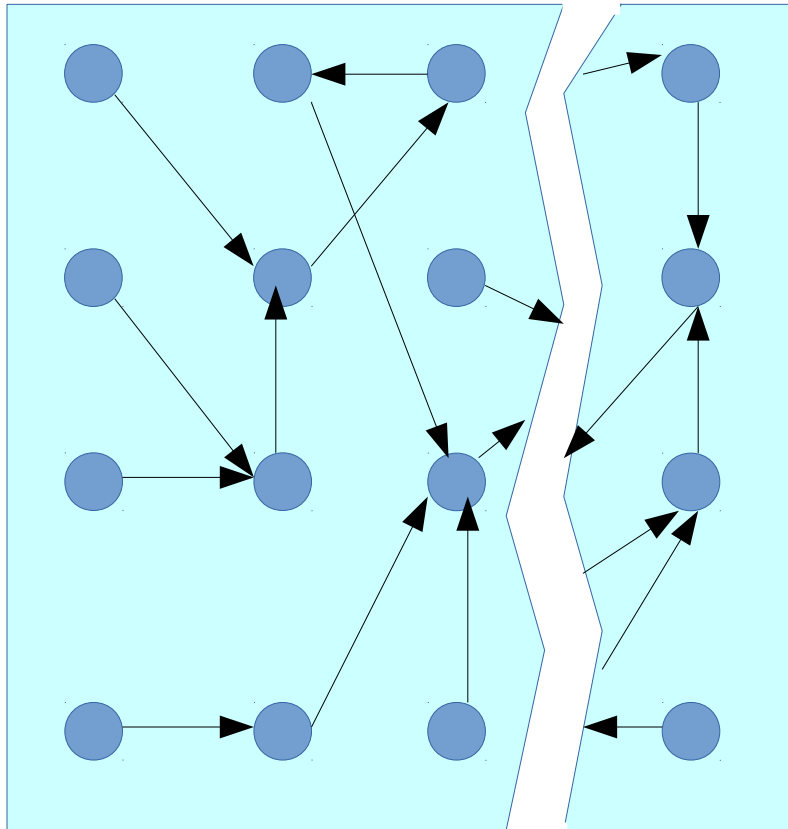
```
}
```

State (pc, x, y, a, b)



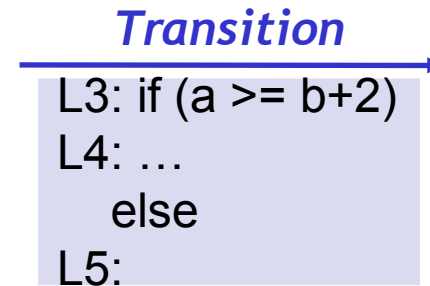
Programs as State Transition Systems

State: pc, x, y, a, b



(L3, 0, 1, 5, 2)

(L4, 0, 1, 5, 2)



```
void func(int a, int b)
{ int x, y;
```

```
  L1: x = 0;
```

```
  L2: y = 1;
```

```
  L3: if (a >= b + 2)
```

```
    L4: a = y;
```

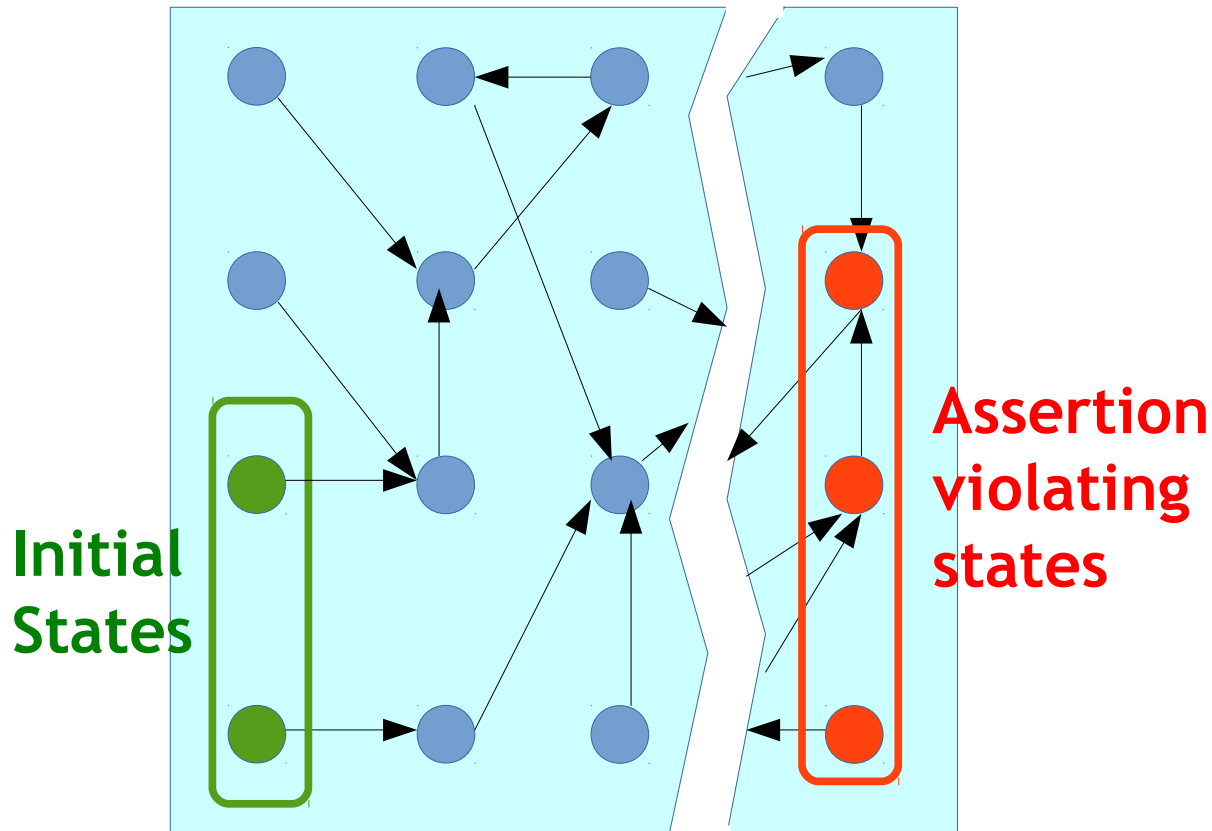
```
      else
```

```
    L5: b = x;
```

```
    L6: return;
```

```
  }
```

Assertion Checking as Reachability



Path from an initial to an assertion violating state ?

Absence of path: System cannot exhibit error

Presence of path: System can exhibit error

What happens with procedure calls/returns?

State Space: How large is it?

- State = (pc, store, heap, call stack)
 - pc: finite valued
 - store: finite if all variables have finite types
 - Every program statement effects a state transition
 - enum {wait, critical, noncritical} pr_state (finite)
 - int a, b, c (infinite)
 - bool *p, *q (infinite)
 - heap: unbounded in general
 - call stack: unbounded in general
- **Bad news: State space infinite in general**

Dealing with State Space Size

- Infinite state space
 - Difficult to represent using state transition diagram
 - Can we still do some reasoning?
- Solution: Use of abstraction
 - Naive view
 - Bunch sets of states together “intelligently”
 - Don't talk of individual states, talk of a representation of a set of states
 - Transitions between state set representations
 - Granularity of reasoning shifted
 - Extremely powerful general technique
 - Allows reasoning about large/infinite state spaces

Concrete states


Abstract states

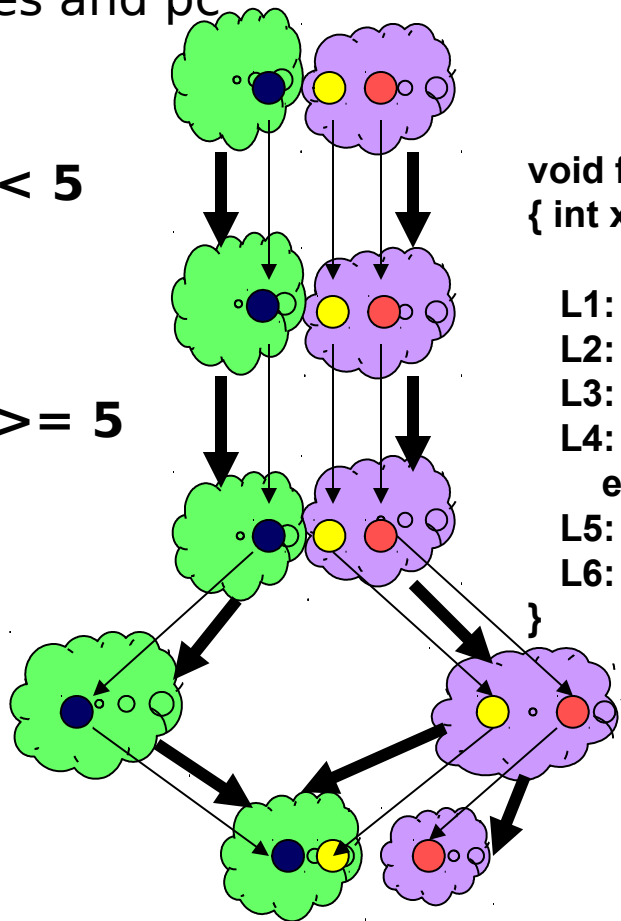
Simple Abstractions

Group states according to values of variables and pc

State: pc, x, y, a, b

 $a < 5$

 $a \geq 5$



```
void func(int a, int b)
{ int x, y;
```

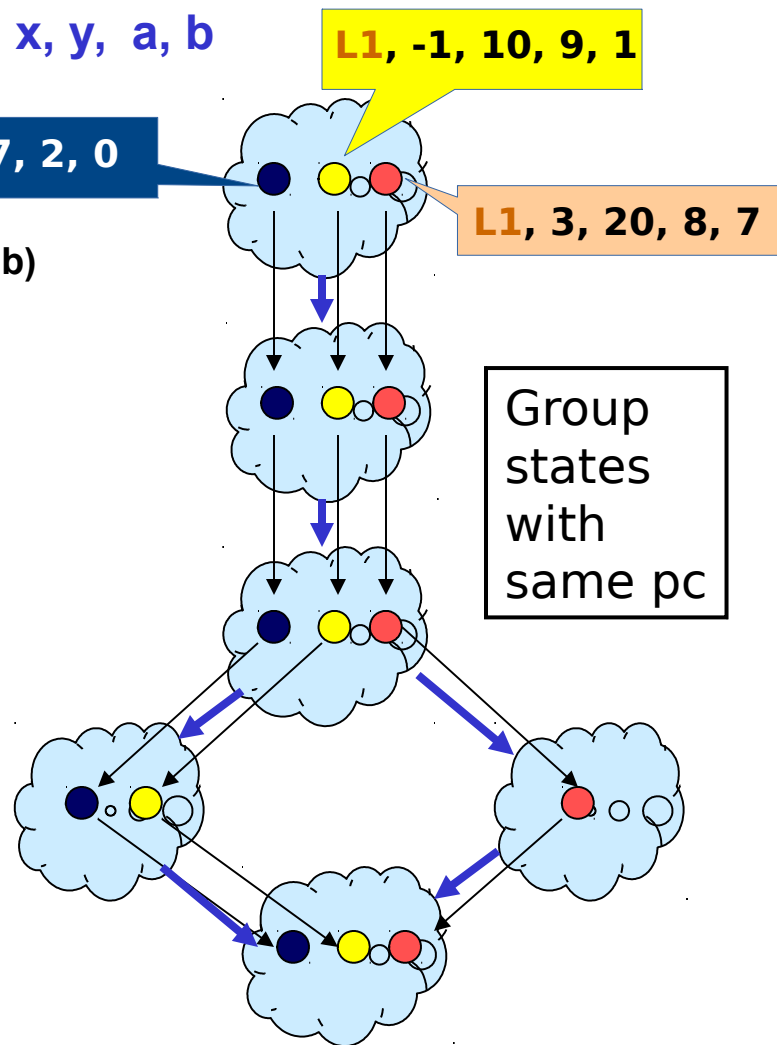
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L1: x = 0;
L2: y = 1;
L3: if (a >= b + 2)
L4:   a = y;
      else
L5:   b = x;
L6: return;
```

L1, 2, 7, 2, 0

L1, -1, 10, 9, 1

L1, 3, 20, 8, 7


Group states with same pc

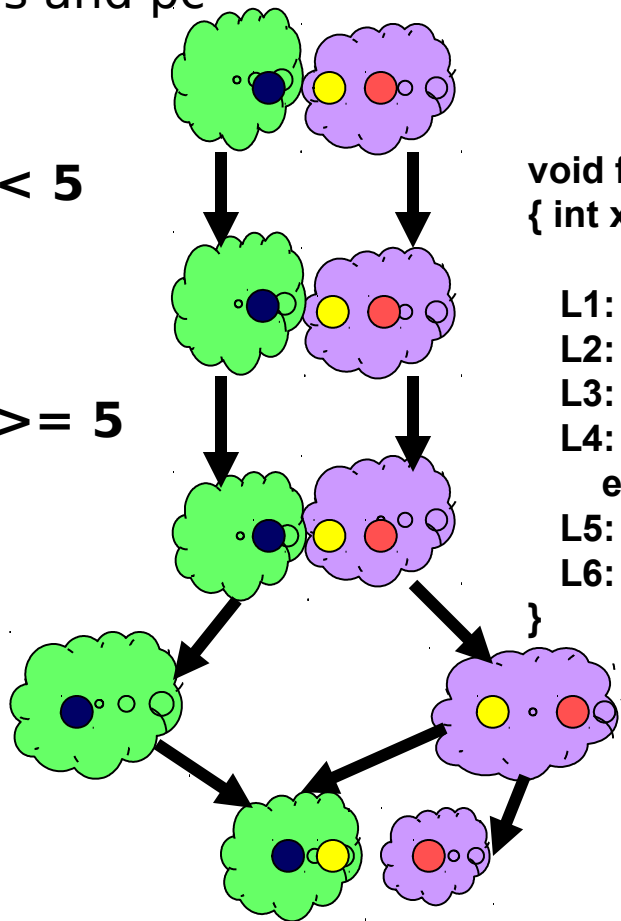


Programs as State Set Transformers

Group states according to values of variables and pc

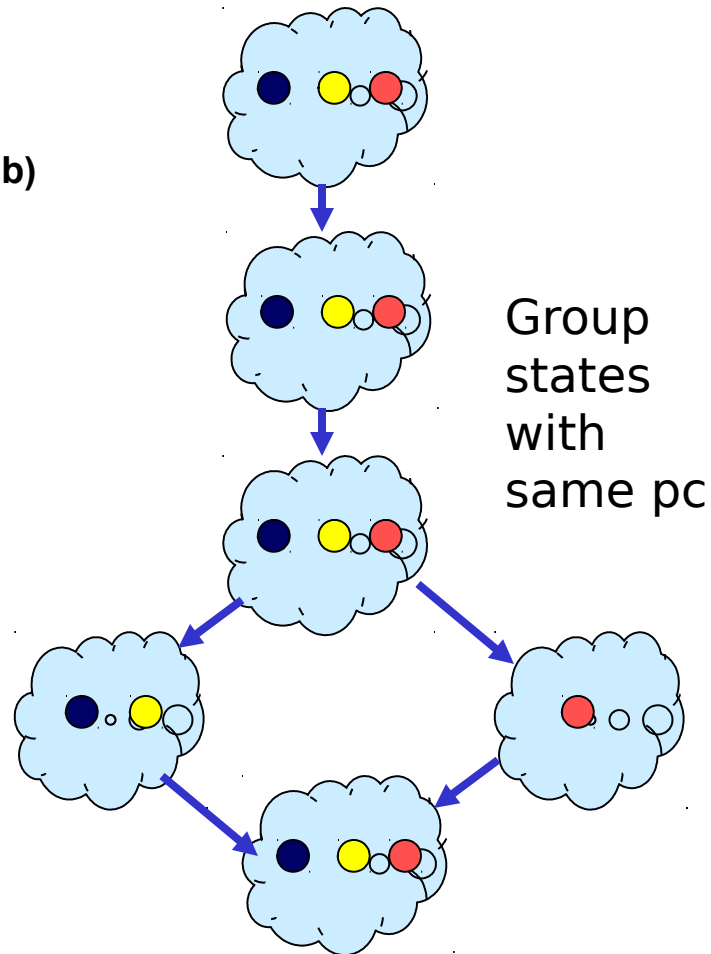
 $a < 5$

 $a \geq 5$



```
void func(int a, int b)
{ int x, y;
```

```
L1: x = 0;
L2: y = 1;
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L4:   a = y;
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L6: return;
```

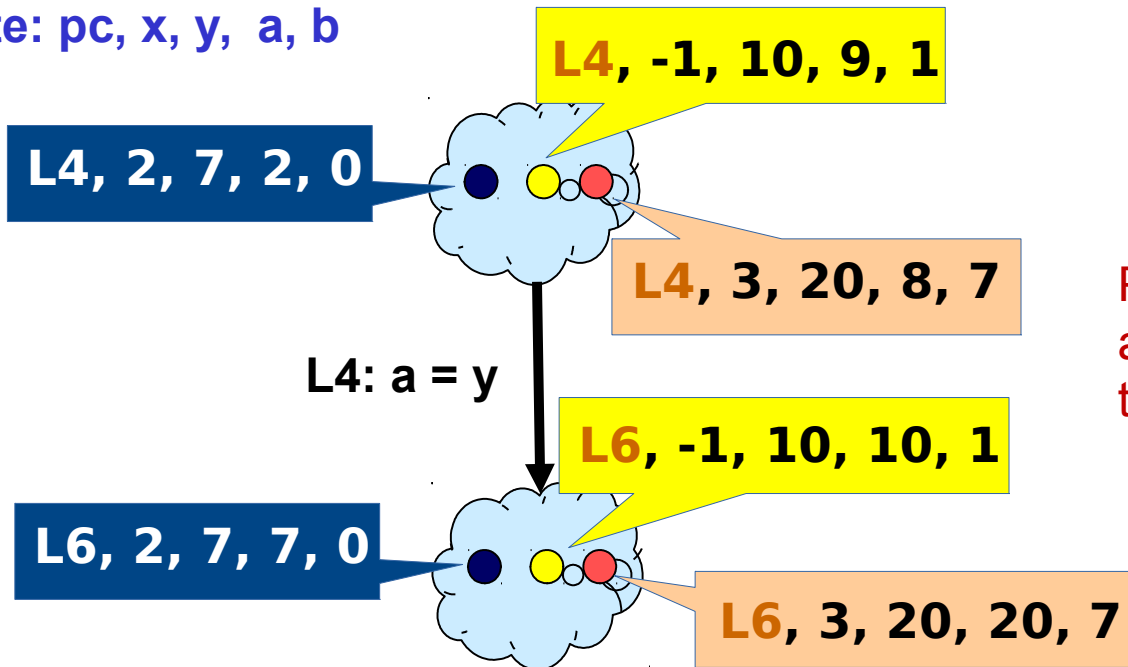


Group states with same pc

Programs as Abstr State Transformers

- Recall: Set of (potentially infinite) concrete states is an abstract state
- **Think of program as abstract state transformer**

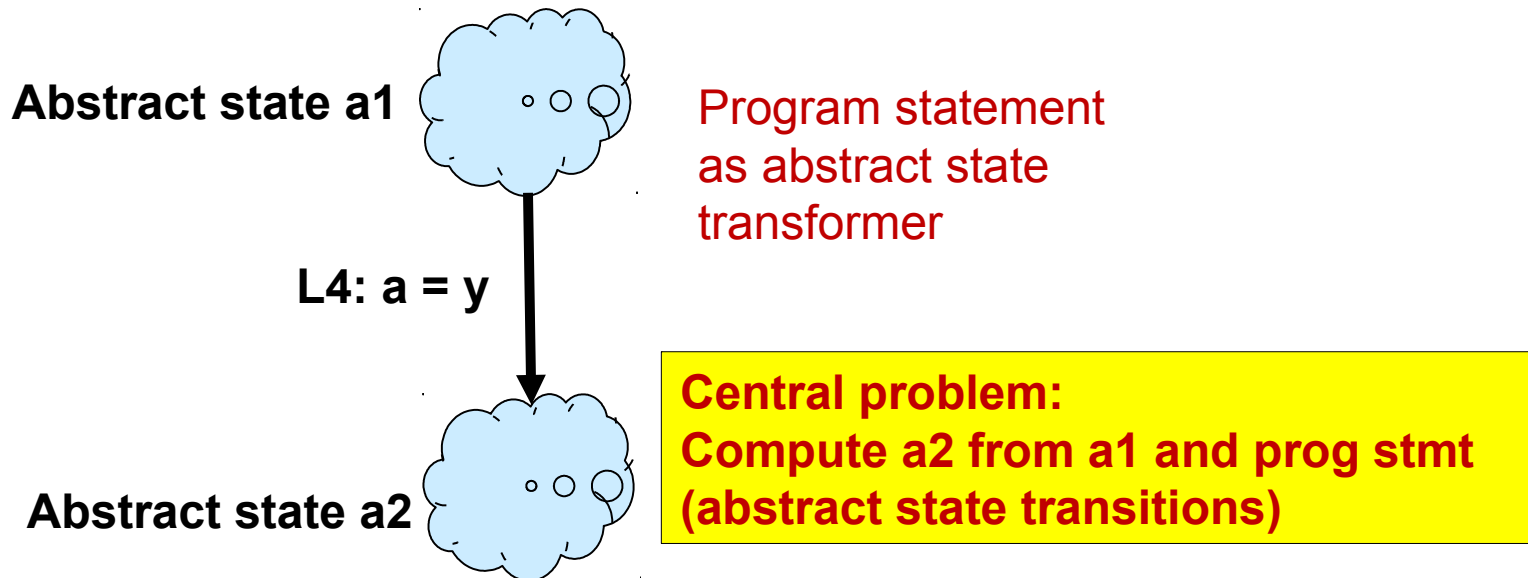
State: pc, x, y, a, b



Program statement
as concrete state
transformer

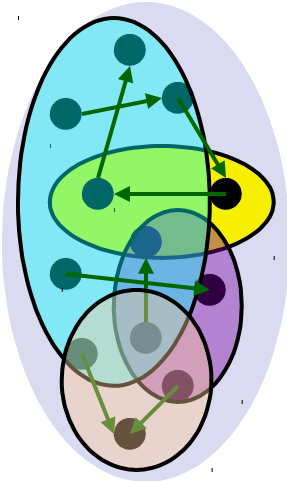
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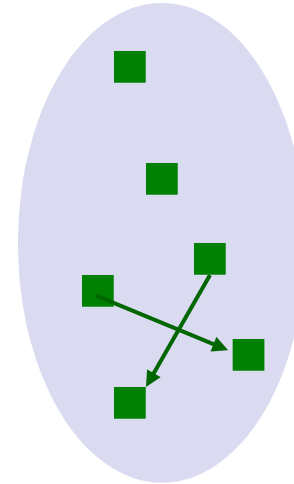


A Generic View of Abstraction

Set of concrete states



Set of abstract states



Abstraction (α)



Concretization (γ)

- Every subset of concrete states mapped to unique abstract state
- Desirable to capture containment relations
- Transitions between state sets (abstract states)

Mathematical Foundations of Abstract Interpretation

➤ Set of concrete states: S

▪ Concrete lattice $\mathbf{C} = (\wp(S), \subseteq, \cup, \cap, S, \emptyset)$

Powerset of S

Partial order

Least upper bound

Greatest lower bound

Bottom element

Top element

Mathematical Foundations of Abstract Interpretation

- Abstract lattice $\mathbf{A} = (\mathcal{A}, \sqsubseteq, \sqcup, \sqcap, \top, \perp)$
-
- Abstraction function $\alpha : \wp(S) \rightarrow \mathcal{A}$
 - Monotone: $S_1 \subseteq S_2 \Rightarrow \alpha(S_1) \sqsubseteq \alpha(S_2)$ for all $S_1, S_2 \subseteq S$
 - $\alpha(S) = \top, \quad \alpha(\emptyset) = \perp$
- Concretization function $\gamma : \mathcal{A} \rightarrow \wp(S)$
 - Monotone: $a_1 \sqsubseteq a_2 \Rightarrow \gamma(a_1) \subseteq \gamma(a_2)$ for all $a_1, a_2 \in \mathcal{A}$
 - $\gamma(\top) = S, \quad \gamma(\perp) = \emptyset$

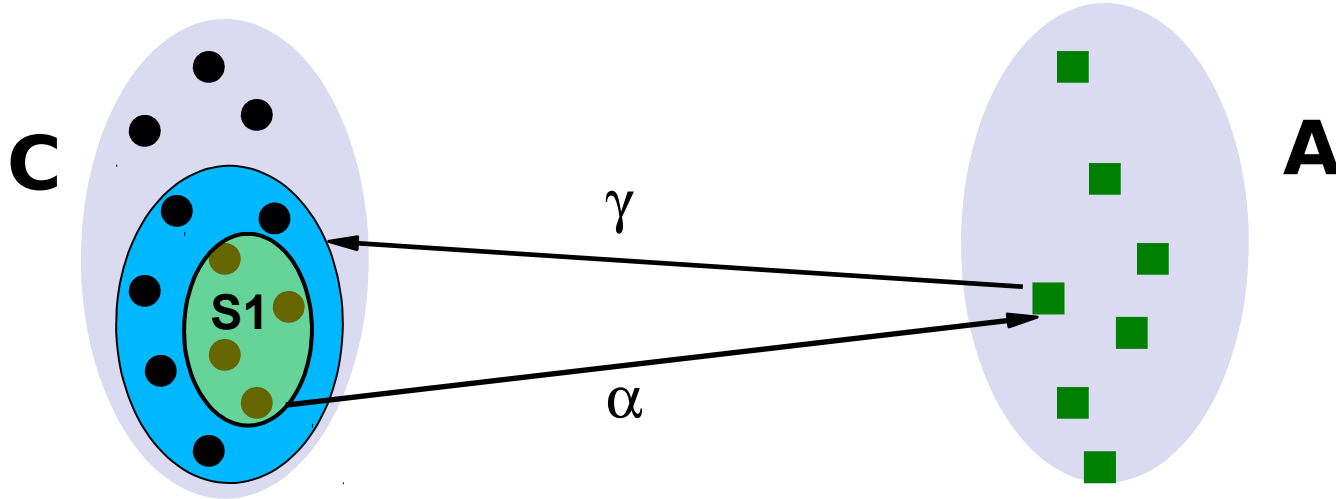
Mathematical Foundations of Abstract Interpretation

➤ α and γ form a ***Galois connection***

· First view: $S_1 \subseteq \gamma(\alpha(S_1))$ for all $S_1 \subseteq S$

Set of concrete states

Set of abstract states



Mathematical Foundations of Abstract Interpretation

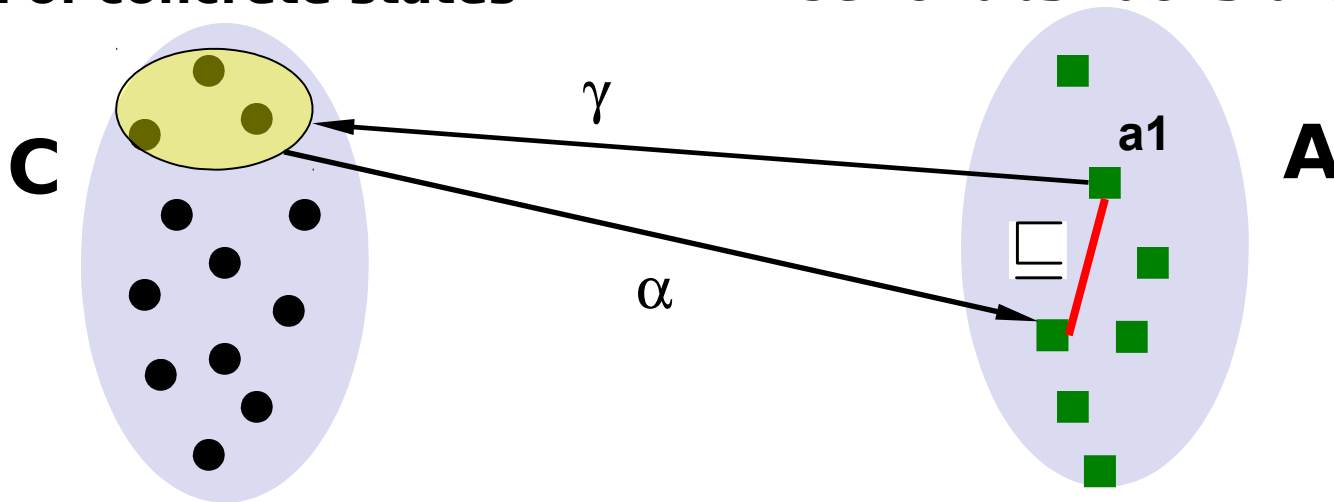
➤ α and γ form a ***Galois connection***

· First view: $S_1 \subseteq \gamma(\alpha(S_1))$ for all $S_1 \subseteq S$

$\alpha(\gamma(a_1)) \sqsubseteq a_1$ for all $a_1 \in \mathcal{A}$

Set of concrete states

Set of abstract states



Mathematical Foundations of Abstract Interpretation

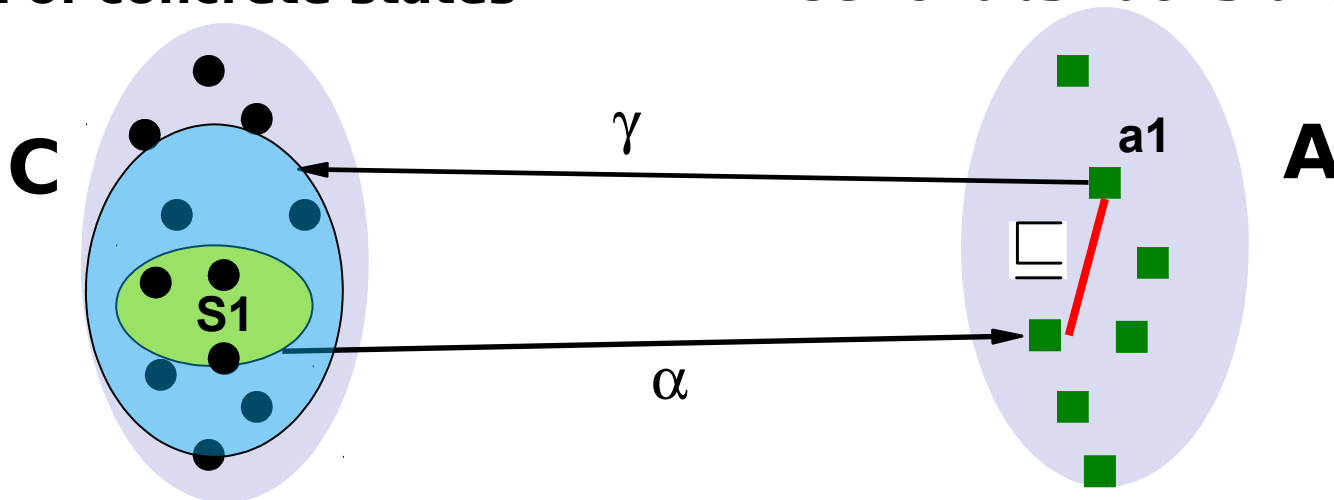
➤ α and γ form a **Galois connection**

▪ Second (equivalent) view:

$$\alpha(S_1) \sqsubseteq a_1 \Leftrightarrow S_1 \subseteq \gamma(a_1) \text{ for all } S_1 \subseteq S, a_1 \in \mathcal{A}$$

Set of concrete states

Set of abstract states

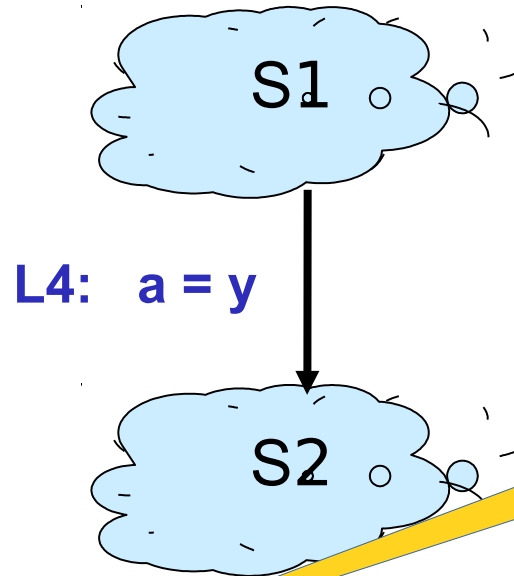


Computing Abstract State Transformers

- Concrete state set transformer function

- Example:

$S1 = \{ (L4, x, y, a, b) \mid \dots \}$: set of concr. states



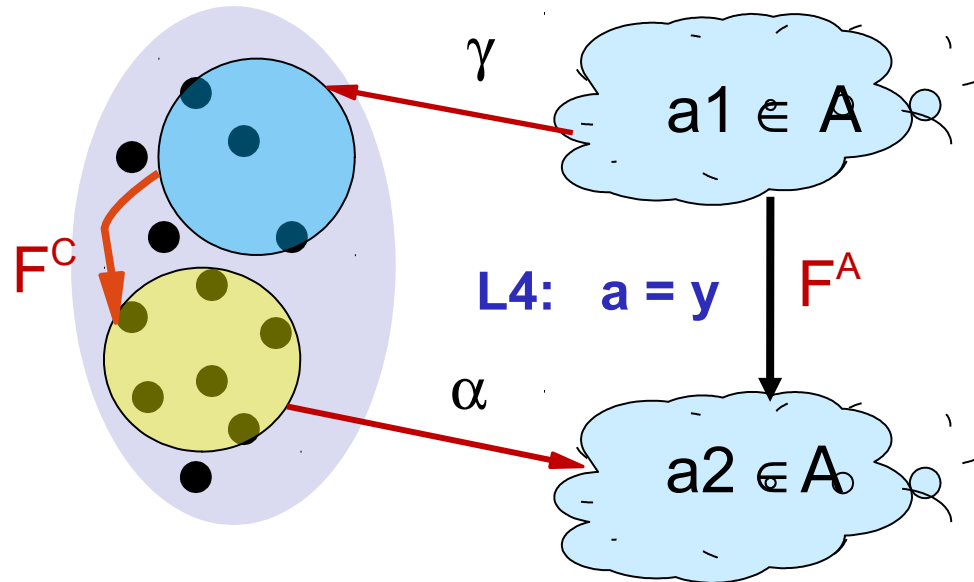
Monotone concrete state set transformer function for stmt at L4

$S2 = \{ (L6, x, y, a', b) \mid \exists (L4, x, y, a, b) \in S1 \wedge a' = y \}$
 $= F^C(S1)$: set of concrete states

Computing Abstract State Transformers

- Abstract state transformer function
 - Example:

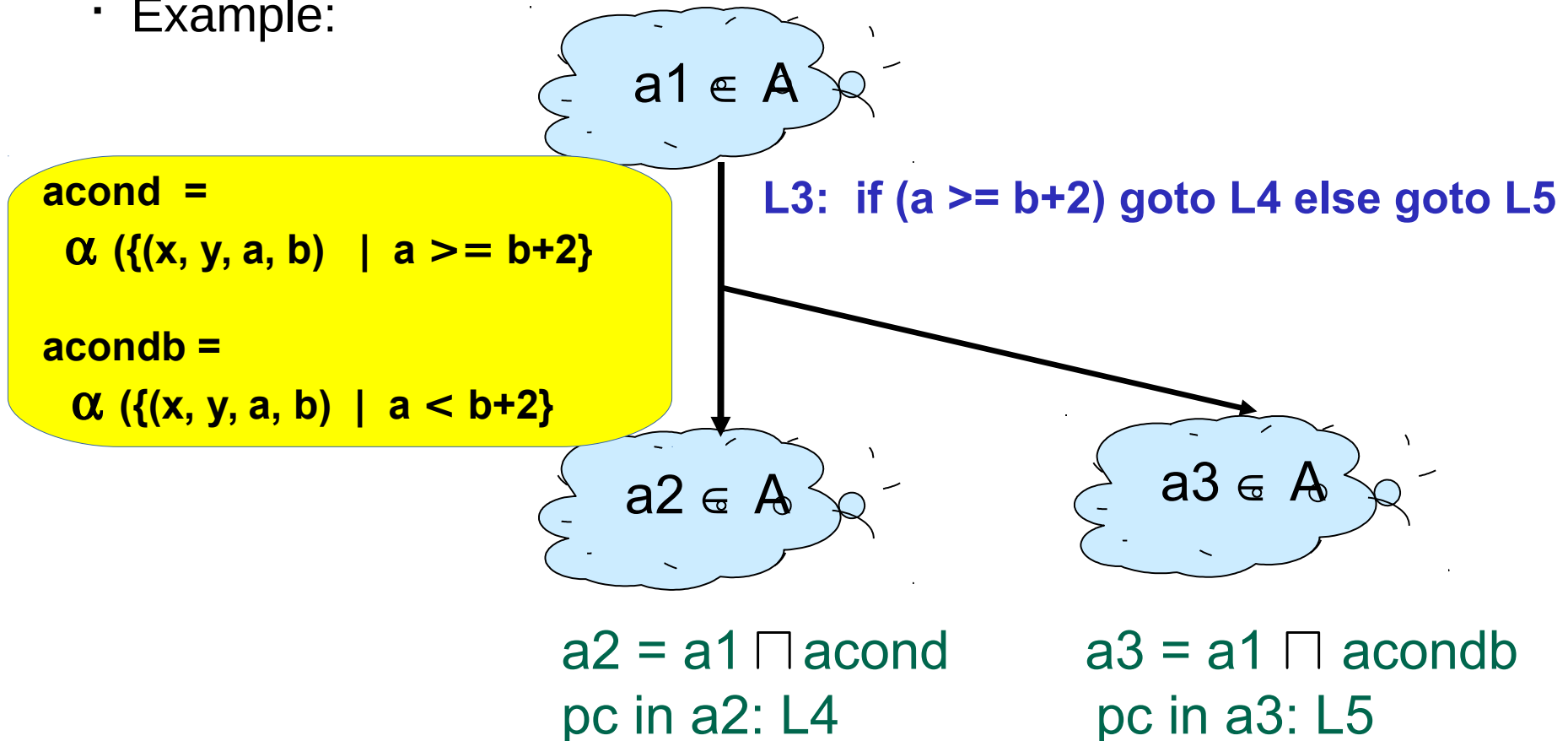
Set of concrete states



$a2 = \alpha(F^C (\gamma (a1)))$ ideally, but $F^A(a1) \sqsupseteq \alpha(F^C (\gamma (a1)))$ often used

Computing Abstract State Transformers

- Abstract state transformer for if-then-else
 - Example:



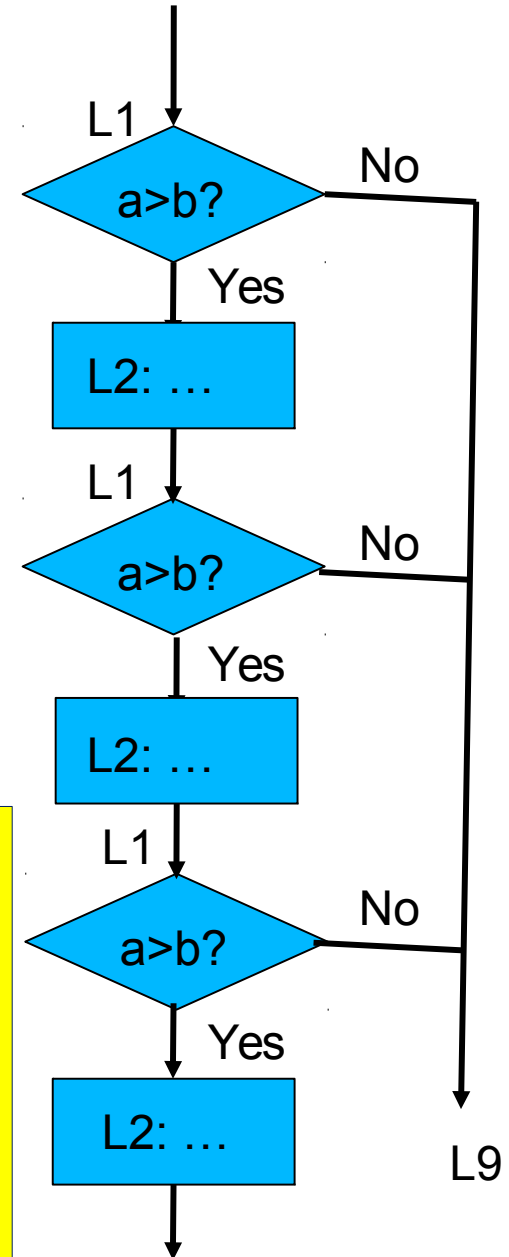
Dealing with Loops

- Example:
L1 : while (a > b) do
 L2: <loop body>
L9: end while

Given

F^A : abstr state transformer of loop body,
a : abstr state at L1 the first time L1 is reached

What is the abstract loop invariant at L1?



Dealing with Loops

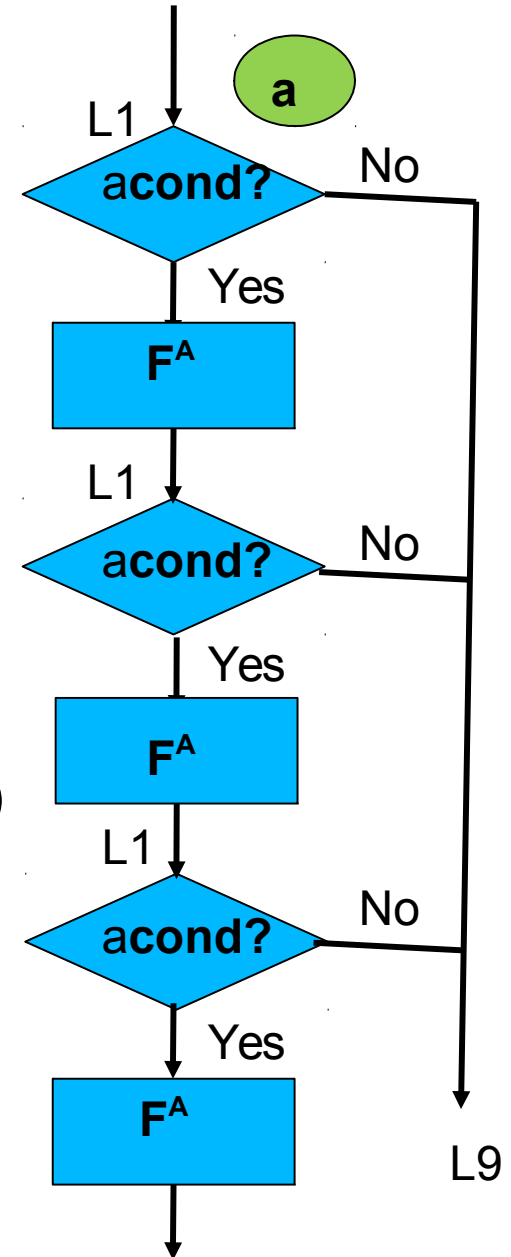
Given

F^A : abstr state transformer of loop body,
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What is the abstract loop invariant at L1?

$acond = \alpha (\{s \mid s \text{ is a concrete state with } a > b \})$

Current view of abstract loop invariant



Dealing with Loops

Given

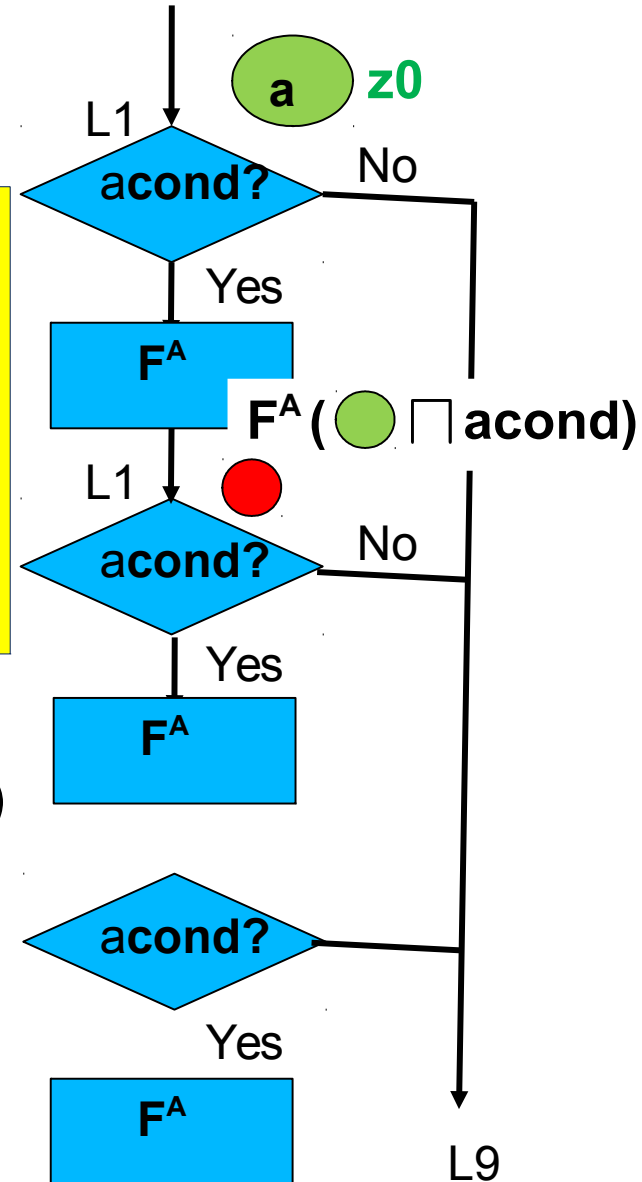
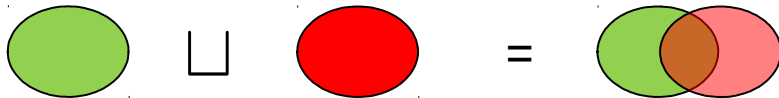
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Dealing with Loops

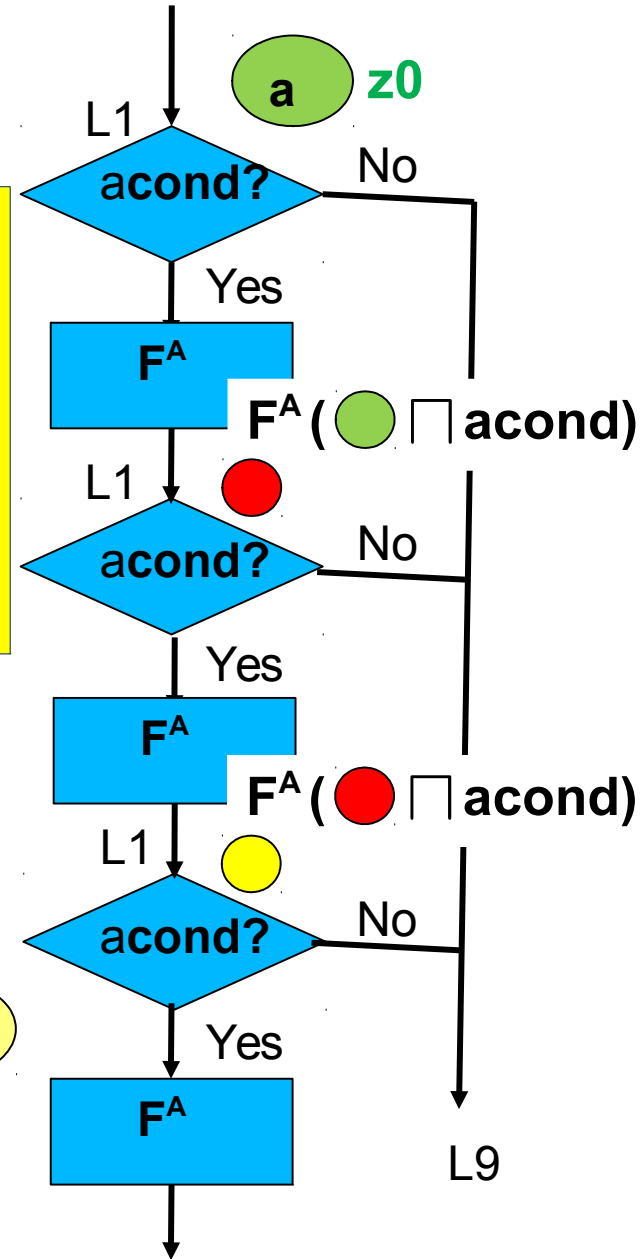
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Dealing with Loops

Given

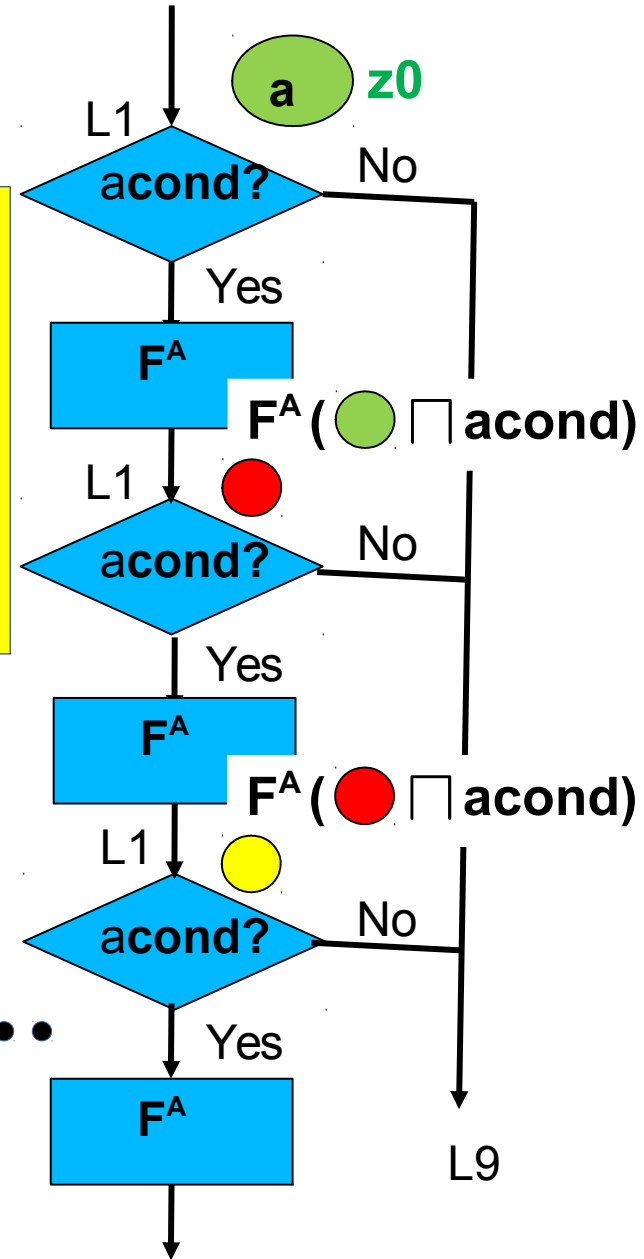
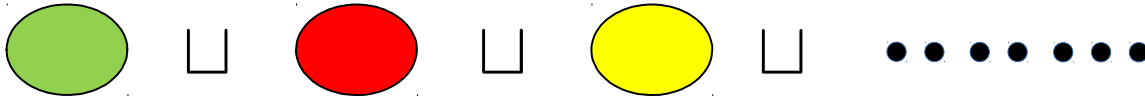
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Abstract loop invariant



Dealing with Loops

Given

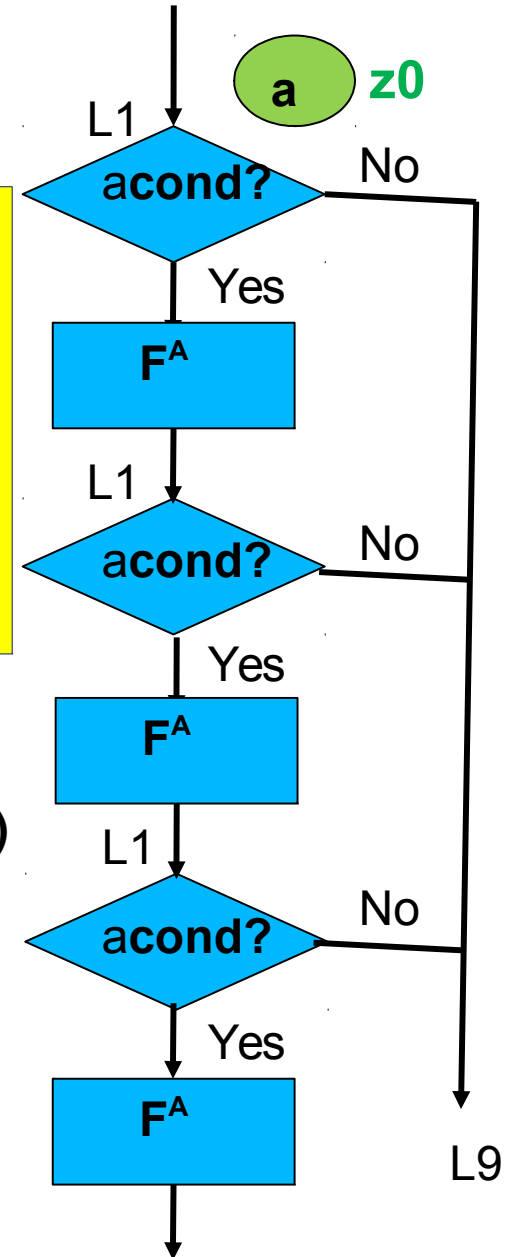
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What is the abstract loop invariant at L1?

$acond = \alpha (\{s \mid s \text{ is a concrete state with } a > b \})$

Loop invariant at L1 is limit of the sequence:

$z0 = a$



Dealing with Loops

Given

F^A : abstr state transformer of loop body,
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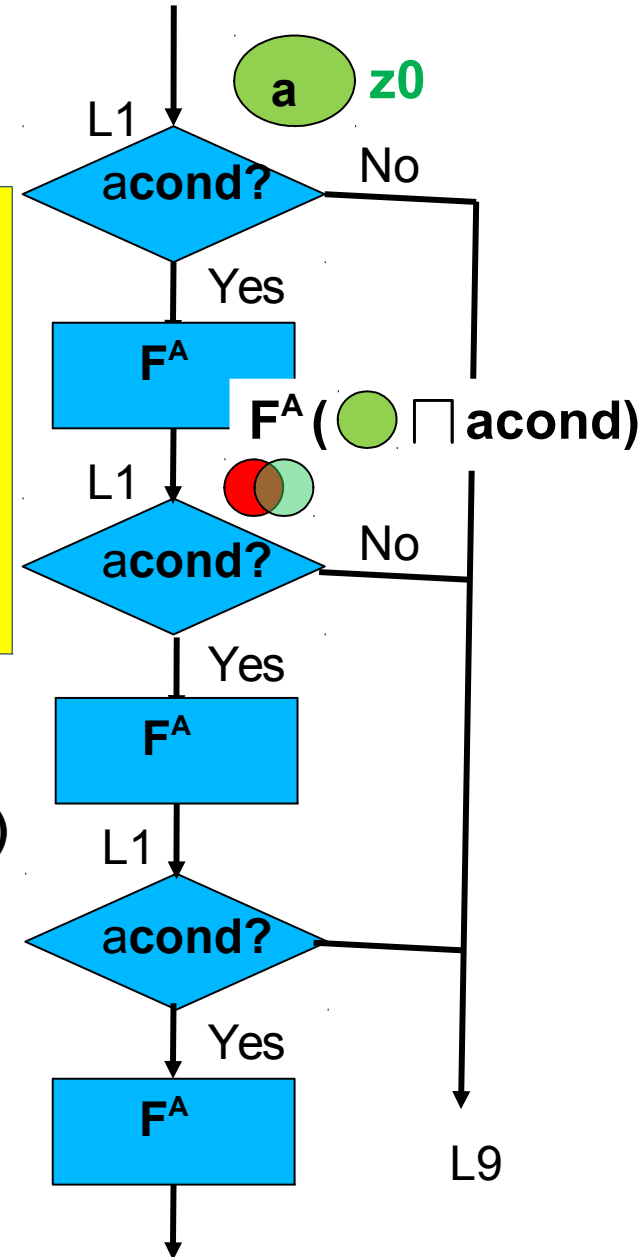
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Loop invariant at L1 is limit of the sequence:

$z0 = a$

$z1 = a \sqcup F^A (z0 \sqcap acond)$



Dealing with Loops

Given

F^A : abstr state transformer of loop body,
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What is the abstract loop invariant at L1?

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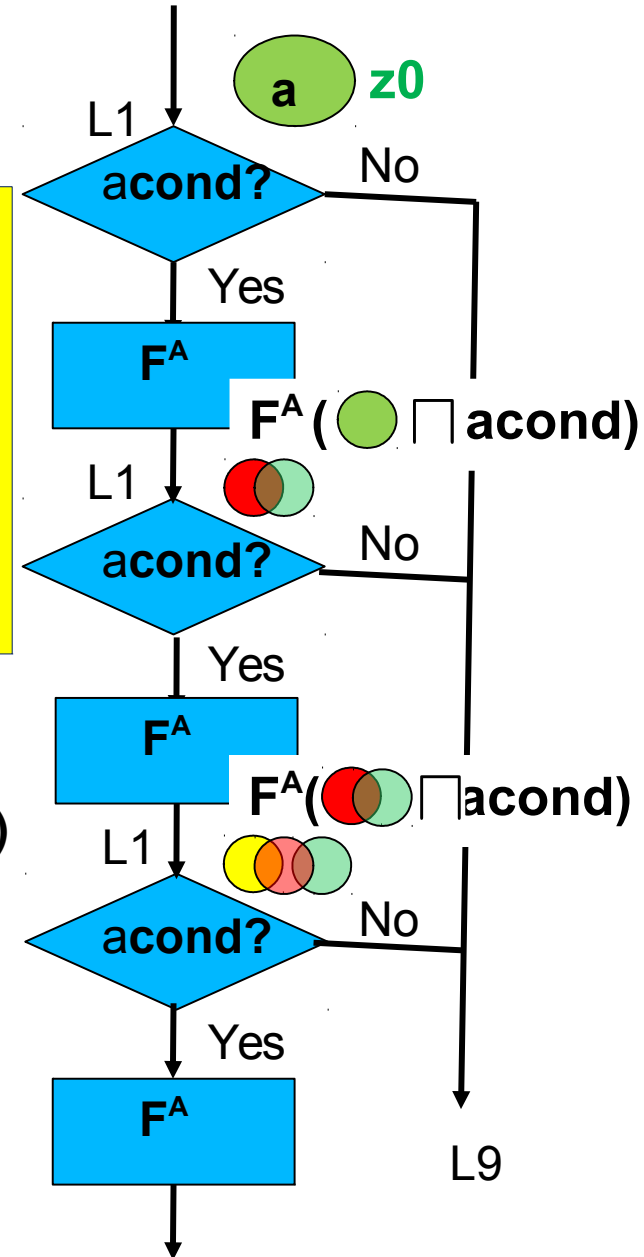
Loop invariant at L1 is limit of the sequence:

$$z_0 = a$$

$$z_1 = a \sqcup F^A (z_0 \sqcap acond)$$

.....

$$z_{i+1} = a \sqcup F^A (z_i \sqcap acond)$$



Dealing with loops

- Loop invariant at L1 is limit of the sequence:
 - $z_0 = a, \dots, z_{i+1} = a \sqcup F^A(z_i \sqcap a \text{cond})$
 - The **limit exists** and is the **least fixpoint** of $g: \mathcal{A} \rightarrow \mathcal{A}$ where $g(z) = a \sqcup F^A(z \sqcap a \text{cond})$
- **Difficult to compute** if A has infinite ascending chains
- Use an extrapolation (**widen**) operator **r**
 - $w_0 = z_0$, and $w_{i+1} = w_i \nabla z_{i+1}$ for all $i \geq 0$
 - By definition of ∇ ,
 - Sequence of w_i 's stationary after finitely many i 's
 - Stationary value w^* overapproximates limit of sequence of z_i 's
 - **Theory of abstract interpretation guarantees that $\gamma(w^*)$ overapproximates loop invariant at L1**

Putting It All Together

- Given a program P and an assertion φ at location L
 - Choose an abstract lattice (domain) A with a ∇ operator
 - Compute abstract invariant at each location of P
 - If abstract invariant at L is a_L , check if $\gamma(a_L)$ satisfies φ
 - The theory of abstract interpretation guarantees that
$$\gamma(a_L) \supseteq \text{concrete invariant at } l$$

**Bird's eye-view of program verification by
abstract interpretation**

A Simple Abstract Domain

Interval Abstract Domain

- Simplest domain for analyzing numerical programs
- Represent values of each variable separately using intervals
- Example:

L0: $x = 0$; $y = 0$;

L1: while ($x < 100$) do

 L2: $x = x + 1$;

 L3: $y = y + 1$;

L4: end while

If the program terminates, does x have the value 100 on termination?

Interval Abstract Domain

- Abstract states: pairs of intervals (one for each of x, y)
 - $[-10, 7], (-1, 20]$
 - \sqsubseteq relation: Inclusion of intervals
 - $[-10, 7], (-1, 20] \sqsubseteq [-20, 9], (-1, +\infty)$
 - \sqcup and \sqcap : union and intersection of intervals
 - $[a, b] \nabla_x [c, d] = [e, f]$, where
 - $e = a$ if $c \geq a$, and $e = -\infty$ otherwise
 - $f = b$ if $d \leq b$, and $f = +\infty$ otherwise
 - ∇_y similarly defined, and ∇ is simply (∇_x, ∇_y)
 - \perp is empty interval of x and y
 - \top is $(-\infty, +\infty), (-\infty, +\infty)$

Analyzing our Program

L0: $x = 0$; $y = 0$;

L1: while ($x < 100$) do

 L2: $x = x + 1$;

 L3: $y = y + 1$;

L4: end while

Some Concluding Remarks

- Abstract interpretation: a fundamental technique for analysis of programs
- Choice of right abstraction crucial
- Often getting the right abstraction to begin with is very hard
 - Need automatic refinement techniques
- Very active area of research
-