Introduction to Data Flow Analysis

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Part 1

About These Slides

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These slides constitute the lecture notes for CS618 Program Analysis course at IIT Bombay and have been made available as teaching material accompanying the book:

• Uday Khedker, Amitabha Sanyal, and Bageshri Karkare. Data Flow Analysis: Theory and Practice. CRC Press (Taylor and Francis Group). 2009.

Apart from the above book, some slides are based on the material from the following books

- A. V. Aho, M. Lam, R. Sethi, and J. D. Ullman. Compilers: Principles, Techniques, and Tools. Addison-Wesley. 2006.
- M. S. Hecht. Flow Analysis of Computer Programs. Elsevier North-Holland Inc. 1977.

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Motivating the Need of Program Analysis

- Some representative examples
 - Classical optimizations performed by compilers
 - Optimizing heap memory usage
- Course details, schedule, assessment policies etc.
- Program execution model and semantics

Classical Optimizations

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Intermediate Code

For the boxed source code

```
1. i = m - 1
```

2. i = n

3. t1 = 4 * n

4. t6 = a[t1]

5. v = t6

6. i = i + 1

7. t2 = 4 * i

8. t3 = a[t2]

9. if t3 < v goto 6

10. j = j - 1

11. t4 = 4 * i

12. t5 = a[t4]

13. if t5 > v goto 10

14. if i >= j goto 25

15. $t^2 = 4 * i$

16. t3 = a[t2]

17. x = t3

18. $t^2 = 4 * i$

19. t4 = 4 * i

20. t5 = a[t4]

21. a[t2] = t5

22. t4 = 4 * j

23. a[t4] = x

24. goto 6

25. t2 = 4 * i

26. t3 = a[t2]

27. x = t3

28. t2 = 4 * i

29. t1 = 4 * n30. t6 = a[t1]

31. a[t2] = t6

32. t1 = 4 * n

33. a[t1] = x

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Examples of Optimising Transformations (ALSU, 2006)

A C program and its optimizations

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```
void guicksort(int m, int n)
  int i, j, v, x;
   if (n \le m) return;
   i = m-1; j = n; v = a[n];
                                           /* v is the pivot */
                                   /* Move values smaller */
   while(1)
      do i = i + 1; while (a[i] < v); /* than v to the left of
      do j = j - 1; while (a[j] > v); /* the split point (sp) *
      if (i >= i) break;
                                       /\star and other values \star.
      x = a[i]; a[i] = a[i]; a[i] = x; /* to the right of sp *
   x = a[i]; a[i] = a[n]; a[n] = x; /* Move the pivot to sp *
   quicksort(m,i); quicksort(i+1,n); /* sort the partitions to *
        /* the left of sp and to the right of sp independently
```

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Intermediate Code: Observations

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- Multiple computations of expressions
- Simple control flow (conditional/unconditional goto) Yet undecipherable!
- Array address calculations



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Understanding Control Flow

- Identify maximal sequences of linear control flow
 ⇒ Basic Blocks
- No transfer into or out of basic blocks except the first and last statements

Control transfer into the block : only at the first statement. Control transfer out of the block : only at the last statement.

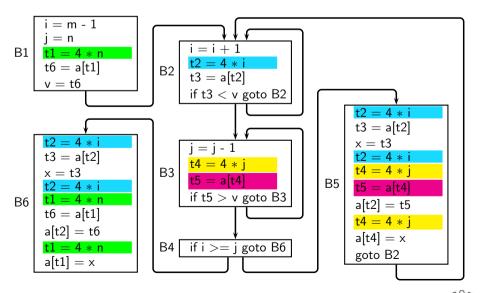
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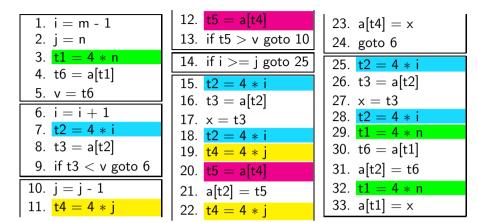
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Program Flow Graph



Intermediate Code with Basic Blocks



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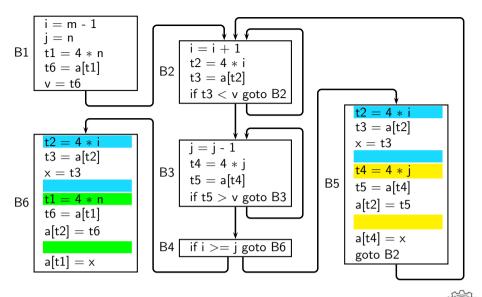
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Program Flow Graph: Observations

Nesting Level	Basic Blocks	No. of Statements
0	B1, B6	14
1	B4, B5	11
2	B2, B3	8



Local Common Subexpression Elimination



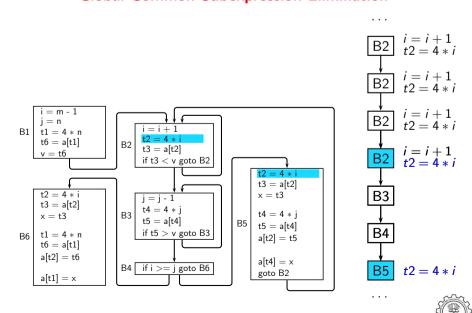
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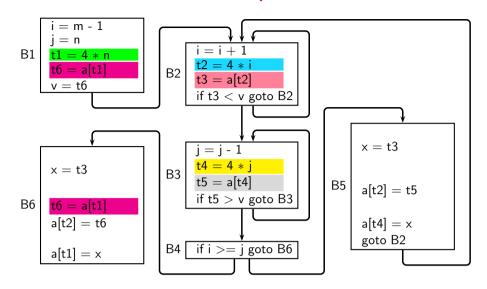
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Global Common Subexpression Elimination



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Global Common Subexpression Elimination



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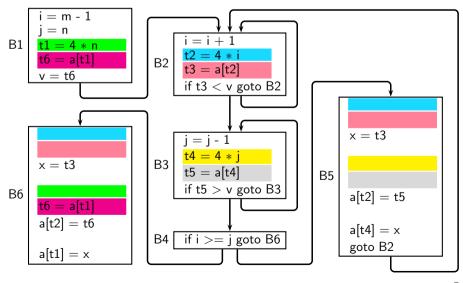
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Global Common Subexpression Elimination





Other Classical Optimizations

- Copy propagation
- Strength Reduction
- Elimination of Induction Variables
- Dead Code Elimination



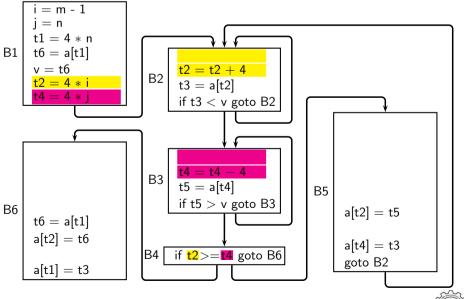
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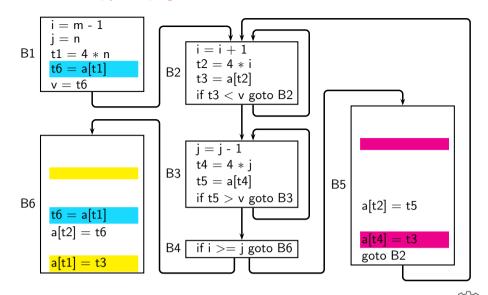
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Strength Reduction and Induction Variable Elimination



Copy Propagation and Dead Code Elimination



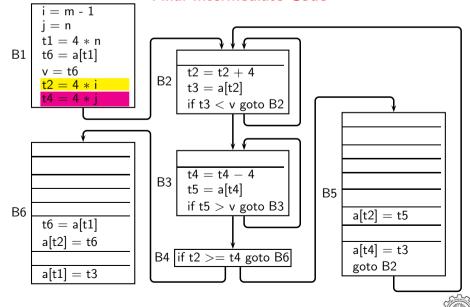
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Final Intermediate Code



Optimized Program Flow Graph

Nesting Level	No. of Statements		
	Original	Optimized	
0	14	10	
1	11	4	
2	8	6	

If we assume that a loop is executed 10 times, then the number of computations saved at run time

$$= (14-10) + (11-4) \times 10 + (8-6) \times 10^2 = 4 + 70 + 200 = 274$$

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Categories of Optimizing Transformations and Analyses

Code Motion Redundancy Elimination Control flow Optimization	Machine Independent	Flow Analysis (Data + Control)
Loop Transformations	Machine Dependent	Dependence Analysis (Data + Control)
Instruction Scheduling Register Allocation Peephole Optimization	Machine Dependent	Several Independent Techniques
Vectorization Parallelization	Machine Dependent	Dependence Analysis (Data + Control)

Observations

- Optimizations are transformations based on some information.
- Systematic analysis required for deriving the information.
- We have looked at data flow optimizations. Many control flow optimizations can also be performed.

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Conclusions

- Static analysis discovers useful information that represents all execution instances of the program being analysed
- This information can be used for a variety of applications such as
 - code optimization
 - verification and validation
 - reverse engineering
 - software engineering





Part 3

Optimizing Heap Memory Usage

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Managing Heap Memory

Decision 1: When to Allocate?

- Explicit. Specified in the programs. (eg. Imperative/OO languages)
- Implicit. Decided by the language processors. (eg. Declarative Languages)

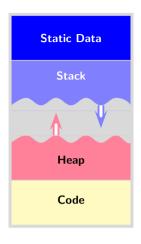
Decision 2: When to Deallocate?

- Explicit. Manual Memory Management (eg. C/C++)
- Implicit. Automatic Memory Management aka Garbage Collection (eg. Java/Declarative languages)

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Standard Memory Architecture of Programs



Heap allocation provides the flexibility of

• Variable Sizes. Data structures can grow or shrink as desired at runtime.

(Not bound to the declarations in program.)

 Variable Lifetimes. Data structures can be created and destroyed as desired at runtime.

(Not bound to the activations of procedures.)

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Predictability of Lifetimes

Memory	Run Time Change		Lifetime
Memory	Allocation	Deallocation	Liletiille
Code	None	None	Predictable
Static Data	None	None	Predictable
Stack	Predictable	Predictable	Predictable
Неар	Predictable	Unpredictable	Unpredictable

Predictability \Rightarrow Can be easily discovered by analysing the program text



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The Importance of Predictability

- Stack and static data offer a reasonable predictability.
 - ► Good (static) analysis techniques.
 - ► Allocation/deallocation/optimization handled very well by production quality language processors.
- Heap memory does not offer the same predictability.
 - ► Few or no (static) production quality analysis techniques.
 - ► Optimization ?

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Garbage Collection

■ Automatic Deallocation

- Retain active data structure.
 Deallocate inactive data structure.
- What is an Active Data Structure?

If an object does not have an access path, (i.e. it is unreachable) then its memory can be reclaimed.

What if an object has an access path, but is not accessed after the given program point?

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State of Art in Manual Deallocation

- Memory leaks
 10% to 20% of last development effort goes in plugging leaks
- Tool assisted manual plugging
 Purify, Electric Fence, RootCause, GlowCode, yakTest, Leak Tracer, BDW
 Garbage Collector, mtrace, memwatch, dmalloc etc.
- All leak detectors
 - ▶ are dynamic (and hence specific to execution instances)
 - generate massive reports to be perused by programmers
 - ▶ usually do not locate last use but only allocation escaping a call ⇒ At which program point should a leak be "plugged"?

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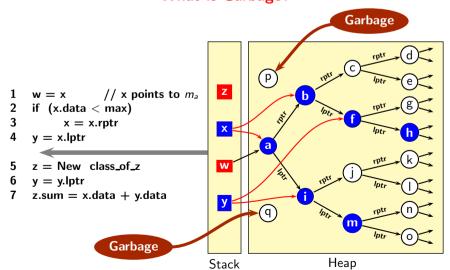
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What is Garbage?



All white nodes are unused and should be considered garbage



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Is Reachable Same as Live?

From www.memorymanagement.org/glossary

live (also known as alive, active): Memory(2) or an object is live if the program will read from it in future. The term is often used more broadly to mean reachable.

It is not possible, in general, for garbage collectors to determine exactly which objects are still live. Instead, they use some approximation to detect objects that are provably dead, such as those that are not reachable.

Similar terms: reachable. Opposites: dead. See also: undead.

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Intro to DFA: Optimizing Heap Memory Usage **Reachability and Liveness**

Comparison between different sets of objects:

Reachable ? Allocated

The objects that are not live must be reclaimed.

Is Reachable Same as Live?

• Not really. Most of us know that.

Even with the state of art of garbage collection, 24% to 76% unused memory remains unclaimed

• Yet we have no way of distinguishing.

Over a dozen reported approaches (since 1996), no real success.

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Reachability and Liveness

Comparison between different sets of objects:

Reachable

Allocated

The objects that are not live must be reclaimed.



Reachability and Liveness

Comparison between different sets of objects:

Reachable

Allocated

The objects that are not live must be reclaimed.

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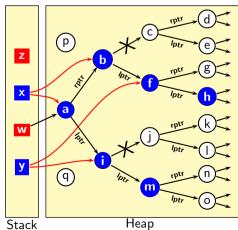
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Make the unused memory unreachable by setting references to NULL. (GC FAQ: http://www.iecc.com/gclist/GC-harder.html)



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Reachability and Liveness

Comparison between different sets of objects:

Live \subseteq Reachable \subseteq Allocated

The objects that are not live must be reclaimed.



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Cedar Mesa Folk Wisdom

- Most promising, simplest to understand, yet the hardest to implement.
- Which references should be set to NULL?
 - ▶ Most approaches rely on feedback from profiling.
 - ▶ No systematic and clean solution.



Distinguishing Between Reachable and Live

The state of art

- Eliminating objects reachable from root variables which are not live.
- Implemented in current Sun JVMs.
- Uses liveness data flow analysis of root variables (stack data).
- What about liveness of heap data?

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Liveness of Stack Data

1 $\mathbf{w} = \mathbf{x}$ // \mathbf{x} points to m_a

while (x.data < max)

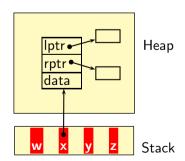
x = x.rptr

4 y = x.lptr

 $5 z = New class_of_z$

6 y = y.lptr

7 z.sum = x.data + y.data



What is the meaning of use of data?

Liveness of Stack Data

1 w = x // x points to m_a 2 while (x.data < max)

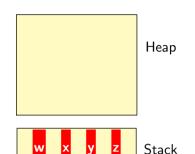
3 x = x.rptr

4 y = x.lptr

 $5 z = New class_of_z$

 $6 \quad y = y.lptr$

7 z.sum = x.data + y.data



if changed to while

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Liveness of Stack Data

1 w = x // x points to m_a

2 while (x.data < max)

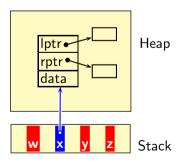
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 $6 \quad y = y.lptr$

7 z.sum = x.data + y.data



Reading x (Stack data)





Liveness of Stack Data

1 w = x // x points to m_a

2 while (x.data < max)

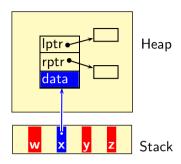
x = x.rptr

4 y = x.lptr

 $5 z = New class_of_z$

 $\hat{y} = y.lptr$

 $7 ext{ z.sum} = x.data + y.data$



Reading x.data (Heap data)



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Liveness of Stack Data

 $\mathbf{w} = \mathbf{x}$ // x points to m_a 2 while (x.data < max)

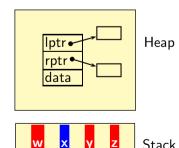
x = x.rptr

4 y = x.lptr

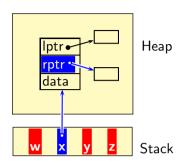
 $z = \text{New class_of_z}$

6 y = y.lptr

7 z.sum = x.data + y.data



w = x // x points to m_a
 while (x.data < max)
 x = x.rptr
 y = x.lptr
 z = New class_of_z
 y = y.lptr
 z.sum = x.data + y.data



Reading x.rptr (Heap data)

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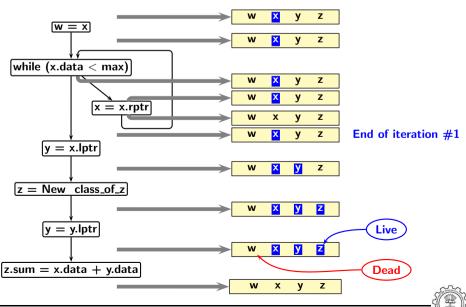
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Liveness of Stack Data





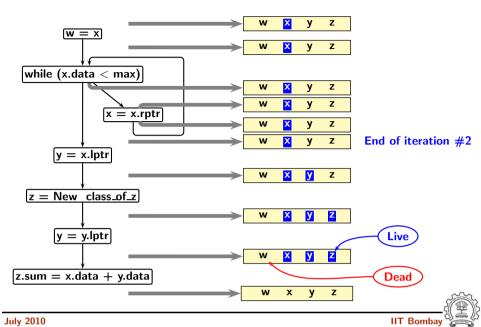
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Liveness of Stack Data



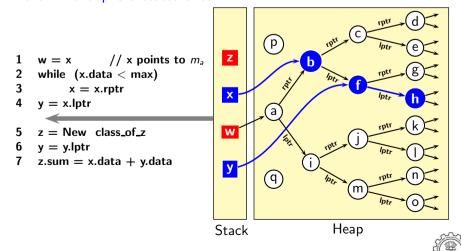
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Applying Cedar Mesa Folk Wisdom to Heap Data

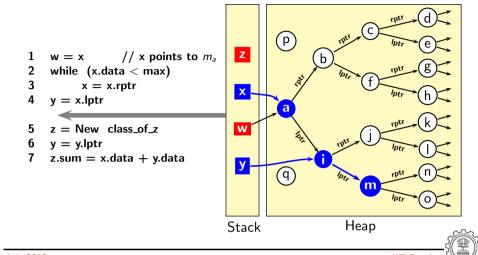
Liveness Analysis of Heap Data If the while loop is executed once.



Applying Cedar Mesa Folk Wisdom to Heap Data

Liveness Analysis of Heap Data

If the while loop is not executed even once.



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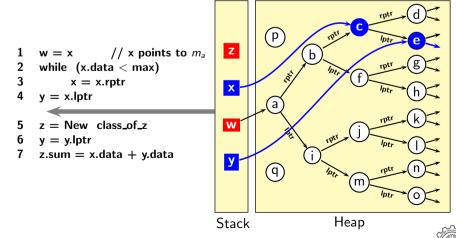
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Applying Cedar Mesa Folk Wisdom to Heap Data

Liveness Analysis of Heap Data
If the while loop is executed twice.



The Moral of the Story

- Mappings between access expressions and I-values keep changing
- This is a *rule* for heap data For stack and static data, it is an exception!
- Static analysis of programs has made significant progress for stack and static data.

What about heap data?

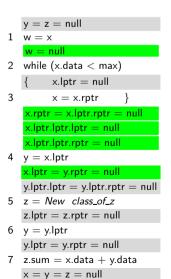
- Given two access expressions at a program point, do they have the same I-value?
- Given the same access expression at two program points, does it have the same I-value?



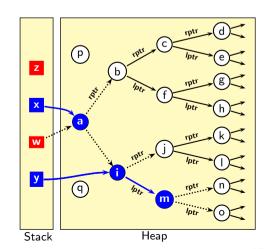
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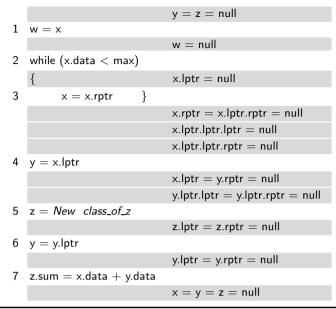
Our Solution



While loop is not executed even once



Our Solution



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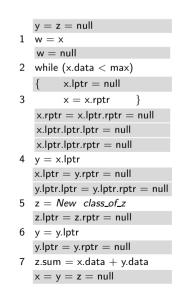
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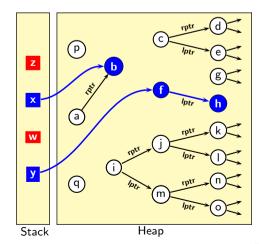
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Our Solution



While loop is executed once







y = z = null $1 \quad w = x$ w = null

2 while (x.data < max)

x.lptr = null

x = x.rptrx.rptr = x.lptr.rptr = nullx.lptr.lptr.lptr = null

x.lptr.lptr.rptr = null4 y = x.lptr

x.lptr = y.rptr = nully.lptr.lptr = y.lptr.rptr = null

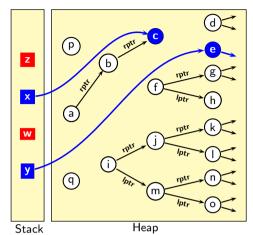
5 $z = New class_of_z$ z.lptr = z.rptr = null

6 y = y.lptr

y.lptr = y.rptr = null

7 z.sum = x.data + y.datax = y = z = null

While loop is executed twice





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Some Observations

y = z = null $1 \quad \mathsf{w} = \mathsf{x}$ w = null2 while (x.data < max) x.lptr = nullx = x.rptrx.rptr = x.lptr.rptr = nullx.lptr.lptr.lptr = nullx.lptr.lptr.rptr = null4 y = x.lptrx.lptr = y.rptr = nully.lptr.lptr = y.lptr.rptr = null

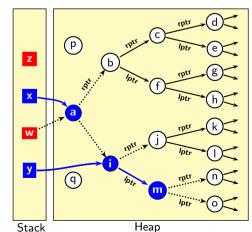
5 $z = New class_of_z$ z.lptr = z.rptr = null

y.lptr = y.rptr = null

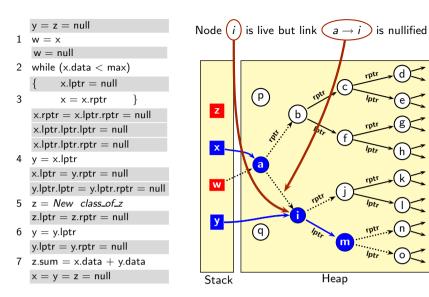
7 z.sum = x.data + y.datax = y = z = null

6 y = y.lptr

New access expressions are created. Can they cause exceptions?

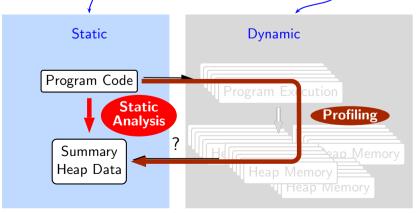






BTW, What is Static Analysis of Heap?





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