

# Locking

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# Recap: Shared data access in threads

```
load counter → reg  
reg = reg + 1  
store reg → counter
```

- The C code “counter = counter + 1” is compiled into multiple instructions
  - Load counter variable from memory into register
  - Increment register
  - Store register back into memory of counter variable
- What happens when two threads run this line of code concurrently?
  - Counter is 0 initially
  - T1 loads counter into register, increment reg
  - Context switch, register (value 1) saved
  - T2 runs, loads counter 0 from memory
  - T2 increments register, stores to memory
  - T1 resumes, stores register value to counter
  - Counter value rewritten to 1 again
  - Final counter value is 1, expected value is 2

T1

```
load counter → reg  
reg = reg + 1  
(context switch, save reg)
```

```
(resume, restore reg)  
store reg → counter
```

T2

```
load counter → reg  
reg = reg + 1  
store reg → counter
```

# Recap: Race conditions, critical sections

- Incorrect execution of code due to concurrency is called **race condition**
  - Due to unfortunate timing of context switches, atomicity of data update violated
- Race conditions happen when we have **concurrent execution on shared data**
  - **Threads** sharing common data in memory image of user processes
  - Processes in kernel mode sharing **OS data structures**
- We require **mutual exclusion** on some parts of user or OS code
  - Concurrent execution by multiple threads/processes should not be permitted
- Parts of program that need to be executed with mutual exclusion for correct operation are called **critical sections**
  - Present in multi-threaded programs, OS code
- How to access critical sections with mutual exclusion? Using locks

# Using locks

- Locks are special variables that provide mutual exclusion
  - Provided by threading libraries
  - Can call **lock/acquire** and **unlock/release** functions on a lock
- When a thread T1 acquires a lock, another thread T2 cannot acquire same lock
  - Execution of T2 stops at the lock statement
  - T2 can proceed only after T1 releases the lock
- Acquire lock → critical section → release lock ensures mutual exclusion in critical section

```
int counter;
pthread_mutex_t m;

void start_fn() {

    for(int i=0; i < 1000; i++) {
        pthread_mutex_lock(&m)
        counter = counter + 1
        pthread_mutex_unlock(&m)
    }

    main() {
        counter = 0

        pthread_t t1, t2
        pthread_create(&t1,.., start_fn, ..)
        pthread_create(&t2, .., start_fn,..)

        pthread_join(t1, ..)
        pthread_join(t2, ..)

        print counter
    }
```

# How to implement a lock?

- Goals of a lock implementation
  - Mutual exclusion (obviously!)
  - Fairness: all threads should eventually get the lock, and no thread should starve
  - Low overhead: acquiring, releasing, and waiting for lock should not consume too many resources
- Implementation of locks are needed for both userspace programs (e.g., pthreads library) and kernel code
  - Separate implementations in user libraries and OS

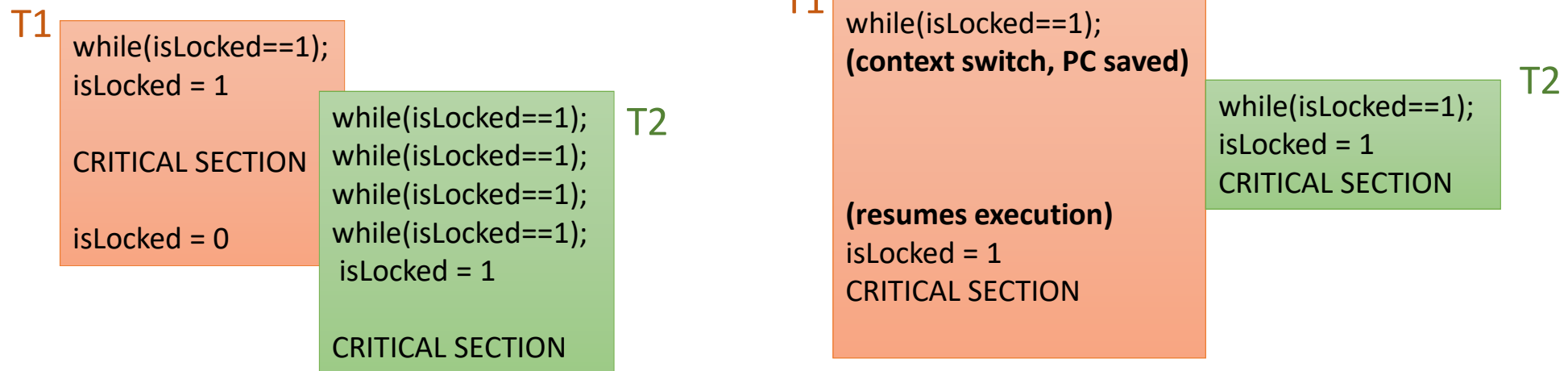
# Incorrect lock implementation

- Example of incorrect lock implementation
  - Use variable isLocked to indicate lock status (0 means lock is free, 1 indicates it is acquired)
  - To acquire lock, a thread waits as long as lock is busy, and then sets it to 1 (acquired)
  - One interleaving of executions (left) works while another (right) may not work

```
int isLocked = 0

void acquire_lock() {
    while(isLocked == 1); //wait
    isLocked = 1
}

void release_lock() {
    isLocked = 0
}
```



# Hardware atomic instructions

- Need a way to check a variable and set its value atomically
  - No context switch between checking lock variable and setting it
  - But user programs have no control over context switches
- Solution: use **hardware atomic instructions**
- Example: **test-and-set** hardware atomic instruction
  - Two arguments: address of variable and new value to set
  - Writes new value into a variable and returns old value in one single step
  - Entire logic implemented in hardware, runs in one single step

```
1      int TestAndSet(int *old_ptr, int new) {
2          int old = *old_ptr; // fetch old value at old_ptr
3          *old_ptr = new;      // store 'new' into old_ptr
4          return old;          // return the old value
5      }
```

# Lock implementation using test-and-set

- Simple lock can be implemented using test-and-set instruction
  - isLocked variable indicates lock status (0=free, 1=acquired)
  - If test-and-set(&isLocked, 1) returns 1, it means lock is not free, wait
  - If test-and-set(&isLocked, 1) returns 0, lock was free and was acquired, done!
- No further race conditions possible with this lock implementation
  - All modern lock implementations based on such hardware instructions
  - Software based locking algorithms do not work well in modern systems

```
int isLocked = 0

void acquire_lock() {
    while(test-and-set(&isLocked, 1) == 1); //wait
    //return, lock is acquired
}
```



```
1  typedef struct __lock_t {
2      int flag;
3  } lock_t;
4
5  void init(lock_t *lock) {
6      // 0 indicates that lock is available, 1 that it is held
7      lock->flag = 0;
8  }
9
10 void lock(lock_t *lock) {
11     while (TestAndSet(&lock->flag, 1) == 1)
12         ; // spin-wait (do nothing)
13 }
14
15 void unlock(lock_t *lock) {
16     lock->flag = 0;
17 }
```

**Figure 28.3: A Simple Spin Lock Using Test-and-set**

## Another instruction: compare-and-swap

- Another example: **compare-and-swap** (CAS) hardware atomic instruction
  - Three arguments: address of variable, expected old value, new value
  - If variable has expected old value, then write new value and return true; else do not change variable and return false

```
1  int CompareAndSwap(int *ptr, int expected, int new) {
2      int actual = *ptr;
3      if (actual == expected)
4          *ptr = new;
5      return actual;
6  }
```

Figure 28.4: **Compare-and-swap**

# Lock using CAS

- Lock implementation using compare-and-swap
  - If compare-and-swap(&isLocked, 0, 1) returns false, it means lock is busy, wait
  - If compare-and-swap(&isLocked, 0, 1) returns true, it means old value of lock was 0 and was changed to 1, so lock has been acquired, done!

```
int isLocked = 0

void acquire_lock() {
    while(compare-and-swap(&isLocked, 0, 1) == false); //wait
}
```

# Evaluating spinlock implementations

- Correctness: does it lead to mutual exclusion correctly?
- Fairness: are all waiting threads treated fairly? Can we guarantee that every waiting thread will get its turn?
  - The implementations we saw here do not guarantee it
- Performance: overheads of having threads spin for lock
  - Single core system: what happens when thread holding lock is context switched out and other threads that are scheduled continue to spin for lock?
  - Problem less severe in multicore system. Why? (Thread holding lock can finish while other threads are spinning)

# Spinlock vs. sleeping mutex

- Simple lock implementation seen here is a **spinlock**
  - If thread T1 has acquired lock, and thread T2 also wants lock, then T2 will keep spinning in a while loop till lock is free
- Another implementation option: thread can go to sleep (be blocked) while waiting for lock, saving CPU cycles
  - OS blocks waiting thread, context switch to another thread/process
  - Such locks are called **(sleeping) mutex**
- Threading libraries provide APIs for both spinlocks and sleeping mutex
  - Better to use spinlock if locks are expected to be held for short time, avoid context switch overhead
  - Better to use sleeping mutex if critical sections are long

# Guidelines for using locks

- When writing multithreaded programs, careful **locking discipline**
  - Protect each shared data structure with one lock
  - Locks can be **coarse-grained** (one big fat lock) or **fine-grained** (many smaller locks)
  - Any thread wanting to access shared data must acquire corresponding lock before access, release lock after access
- If using third-party libraries in multi-threaded programs, check the documentation to see if the library is **thread-safe**
  - Thread-safe implementations work correctly with concurrent access

# Guidelines for using locks

- Good practice to acquire locks for both **reading and writing data**
  - Why locks for reading? We do not want to read incorrect data while another thread is concurrently updating the data
  - Some libraries provide separate locks for reading and writing, allowing multiple threads to concurrently read data if no other thread is writing
- Good practice to minimize use of locks, use only when needed
  - Why? Use of locks serializes thread access, removes gains due to parallelism
  - Example of minimizing lock usage: instead of each thread updating shared global counter, let each thread update a local counter, and periodically update global counter

```

1  typedef struct __counter_t {
2      int          value;
3      pthread_mutex_t lock;
4  } counter_t;
5
6  void init(counter_t *c) {
7      c->value = 0;
8      Pthread_mutex_init(&c->lock, NULL);
9  }
10
11 void increment(counter_t *c) {
12     Pthread_mutex_lock(&c->lock);
13     c->value++;
14     Pthread_mutex_unlock(&c->lock);
15 }
16
17 void decrement(counter_t *c) {
18     Pthread_mutex_lock(&c->lock);
19     c->value--;
20     Pthread_mutex_unlock(&c->lock);
21 }
22
23 int get(counter_t *c) {
24     Pthread_mutex_lock(&c->lock);
25     int rc = c->value;
26     Pthread_mutex_unlock(&c->lock);
27     return rc;
28 }

```

**Figure 29.2: A Counter With Locks**