

Practice Problems: Processes

1. Answer yes/no, and provide a brief explanation.

- (a) Can two processes that are not parent/child be concurrently executing the same program executable?
- (b) Can two running processes share the complete process image in physical memory (not just parts of it)?

Ans:

- (a) Yes, two processes can run the same program executable, which happens when we run the same executable from the terminal twice.
- (b) No. In general, each process has its own memory image.

2. Consider a process P1 that is executing on a Linux-like OS on a single core system. When P1 is executing, a disk interrupt occurs, causing P1 to go to kernel mode to service that interrupt. The interrupt delivers all the disk blocks that unblock a process P2 (which blocked earlier on the disk read). The interrupt service routine has completed execution fully, and the OS is just about to return back to the user mode of P1. At this point in time, what are the states (ready/running/blocked) of processes P1 and P2?

- (a) State of P1
- (b) State of P2

Ans:

(a) P1 is running (b) P2 is ready

3. Consider a process executing on a CPU. Give an example scenario that can cause the process to undergo:

- (a) A voluntary context switch.
- (b) An involuntary context switch.

Ans:

- (a) A blocking system call.
- (b) Timer interrupt that causes the process to be switched out.

4. Consider a parent process P that has forked a child process C. Now, P terminates while C is still running. Answer yes/no, and provide a brief explanation.

- (a) Will C immediately become a zombie?
- (b) Will P immediately become a zombie, until reaped by its parent?

Ans:

- (a) No, it will be adopted by init.
- (b) Yes.

5. A process in user mode cannot execute certain privileged hardware instructions. [T/F]

Ans: True, some instructions in every CPU's instruction set architecture can only be executed when the CPU is running in a privileged mode (e.g., ring 0 on Intel CPUs).

6. Consider the following CPU instructions found in modern CPU architectures like x86. For each instruction, state if you expect the instruction to be privileged or unprivileged, and justify your answer. For example, if your answer is "privileged", give a one sentence example of what would go wrong if this instruction were to be executable in an unprivileged mode. If your answer is "unprivileged", give a one sentence explanation of why it is safe/necessary to execute the instruction in unprivileged mode.

- (a) Instruction to write into the interrupt descriptor table register.
- (b) Instruction to write into a general purpose CPU register.

Ans:

- (a) Privileged, because a user process may misuse this ability to redirect interrupts of other processes.
- (b) Unprivileged, because this is a harmless operation that is done often by executing processes.

7. Which of the following C library functions do NOT directly correspond to (similarly named) system calls? That is, the implementations of which of these C library functions are NOT straightforward invocations of the underlying system call?

- (a) `system`, which executes a bash shell command.
- (b) `fork`, which creates a new child process.
- (c) `exit`, which terminates the current process.
- (d) `strlen`, which returns the length of a string.

Ans: (a), (d)

8. Which of the following actions by a running process will *always* result in a context switch of the running process, even in a non-preemptive kernel design?

- (a) Servicing a disk interrupt, that results in another blocked process being marked as ready/runnable.
- (b) A blocking system call.
- (c) The system call `exit`, to terminate the current process.
- (d) Servicing a timer interrupt.

Ans: (b), (c)

9. Consider two machines A and B of different architectures, running two different operating systems OS-A and OS-B. Both operating systems are POSIX compliant. The source code of an application that is written to run on machine A must always be rewritten to run on machine B. [T/F]

Ans: False. If the code is written using the POSIX API, it need not be rewritten for another POSIX compliant system.

10. Consider the scenario of the previous question. An application binary that has been compiled for machine A may have to be recompiled to execute correctly on machine B. [T/F]

Ans: True. Even if the code is POSIX compliant, the CPU instructions in the compiled executable are different across different CPU architectures.

11. A process makes a system call to read a packet from the network device, and blocks. The scheduler then context-switches this process out. Is this an example of a voluntary context switch or an involuntary context switch?

Ans: Voluntary context switch.

12. A context switch can occur only after processing a timer interrupt, but not after any other system call or interrupt. [T/F]

Ans: False, a context switch can also occur after a blocking system call for example.

13. A C program cannot directly invoke the OS system calls and must always use the C library for this purpose. [T/F]

Ans: False, it is cumbersome but possible to directly invoke system calls from user code.

14. A process undergoes a context switch every time it enters kernel mode from user mode. [T/F]

Ans: False, after finishing its job in kernel mode, the OS may sometimes decide to go back to the user mode of the same process, without switching to another process.

15. Consider a process P in xv6 that invokes the wait system call. Which of the following statements is/are true?

- (a) If P does not have any zombie children, then the wait system call returns immediately.
- (b) The wait system call always blocks process P and leads to a context switch.
- (c) If P has exactly one child process, and that child has not yet terminated, then the wait system call will cause process P to block.
- (d) If P has two or more zombie children, then the wait system call reaps all the zombie children of P and returns immediately.

Ans: (c)

16. Consider a process P which invokes the default wait system call. For each of the scenarios described below, state the expected behavior of the wait system call, i.e., whether the system call blocks P or if P returns immediately.

- (a) P has no children at all.

- (b) P has one child that is still running.
- (c) P has one child that has terminated and is a zombie.
- (d) P has two children, one of which is running and the other is a terminated zombie.

Ans:

- (a) Does not block
 - (b) Blocks
 - (c) Does not block
 - (d) Does not block
17. Consider the wait family of system calls (wait, waitpid etc.) provided by Linux. A parent process uses some variant of the wait system call to wait for a child that it has forked. Which of the following statements is always true when the parent invokes the system call?
- (a) The parent will always block.
 - (b) The parent will never block.
 - (c) The parent will always block if the child is still running.
 - (d) Whether the parent will block or not will depend on the system call variant and the options with which it is invoked.

Ans: (d)

18. Consider a simple linux shell implementing the command `sleep 100`. Which of the following is an accurate ordered list of system calls invoked by the shell from the time the user enters this command to the time the shell comes back and asks the user for the next input?
- (a) wait-exec-fork
 - (b) exec-wait-fork
 - (c) fork-exec-wait
 - (d) wait-fork-exec

Ans: (c)

19. Which of the following pieces of information in the PCB of a process are changed when the process invokes the exec system call?
- (a) Process identifier (PID)
 - (b) Page table entries
 - (c) The value of the program counter stored within the user space context on the kernel stack

Ans: (a) does not change. (b) and (c) change because the process gets a new memory image (and hence new page table entries pointing to the new image).

20. Which of the following pieces of information about the process are identical for a parent and the newly created child processes, immediately after the completion of the `fork` system call? Answer “identical” or “not identical”.

- (a) The process identifier.
- (b) The contents of the file descriptor table.

Ans: (a) is not identical, as every process has its own unique PID in the system. (b) is identical, as the child gets an exact copy of the parent's file descriptor table.

21. Consider a process P1 that forks P2, P2 forks P3, and P3 forks P4. P1 and P2 continue to execute while P3 terminates. Now, when P4 terminates, which process must wait for and reap P4?

Ans: init (orphan processes are reaped by init)

22. Consider a process P that executes the fork system call twice. That is, it runs code like this:

```
int ret1 = fork(); int ret2 = fork();
```

How many direct children of P (i.e., processes whose parent is P) and how many other descendants of P (i.e., processes who are not direct children of P, but whose grandparent or great grandparent or some such ancestor is P) are created by the above lines of code? You may assume that all fork system calls succeed.

- (a) Two direct children of P are created.
- (b) Four direct children of P are created.
- (c) No other descendant of P is created.
- (d) One other descendant of P is created.

Ans: (a), (d)

23. Consider the x86 instruction "int n" that is executed by the CPU to handle a trap. Which of the following statements is/are true?

- (a) This instruction is always invoked by privileged OS code.
- (b) This instruction causes the CPU to set its EIP to address value "n".
- (c) This instruction causes the CPU to lookup the Interrupt Descriptor Table (IDT) using the value "n" as an index.
- (d) This instruction is always executed by the CPU only in response to interrupts from external hardware, and never due to any code executed by the user.

Ans: (c)

24. Consider the following scheduling policy implemented by an OS, in which a user can set numerical priorities for processes running in the system. The OS scheduler maintains all ready processes in a strict priority queue. When the CPU is free, it extracts the ready process with the highest priority (breaking ties arbitrarily), and runs it until the process blocks or terminates. Which of the following statements is/are true about this scheduling policy?

- (a) This scheduler is an example of a non-preemptive scheduling policy.
- (b) This scheduling policy can result in the starvation of low priority processes.
- (c) This scheduling policy guarantees fairness across all active processes.
- (d) This scheduling policy guarantees lowest average turnaround time for all processes.

Ans: (a), (b)

25. Consider the following scheduling policy implemented by an OS. Every time a process is scheduled, the OS runs the process for a maximum of 10 milliseconds or until the process blocks or terminates itself before 10 milliseconds. Subsequently, the OS moves on to the next ready process in the list of processes in a round-robin fashion. Which of the following statements is/are true about this scheduling policy?
- (a) This policy cannot be efficiently implemented without hardware support for timer interrupts.
 - (b) This scheduler is an example of a non-preemptive scheduling policy.
 - (c) This scheduling policy can sometimes result in involuntary context switches.
 - (d) This scheduling policy prioritizes processes with shorter CPU burst times over processes that run for long durations.

Ans: (a), (c)

26. Consider a process P that needs to save its CPU execution context (values of some CPU registers) on some stack when it makes a function call or system call. Which of the following statements is/are true?
- (a) During a system call, when transitioning from user mode to kernel mode, the context of the process is saved on its kernel stack.
 - (b) During a function call in user mode, the context of the process is saved on its user stack.
 - (c) During a function call in kernel mode, the context of the process is saved on its user stack.
 - (d) During a function call in kernel mode, the context of the process is saved on its kernel stack.

Ans: (a), (b), (d)

27. For each of the events below, state whether the execution context of a running process P will be saved on the user stack of P or on the kernel stack.
- (a) P makes a function call in user mode. **Ans:** user stack
 - (b) P makes a function call in kernel mode. **Ans:** kernel stack
 - (c) P makes a system call and moves from user mode to kernel mode. **Ans:** kernel stack
 - (d) P is switched out by the CPU scheduler. **Ans:** kernel stack
28. Which of the following statements is/are true regarding how the trap instruction (e.g., `int n` in x86) is invoked when a trap occurs in a system?
- (a) When a user makes a system call, the trap instruction is invoked by the kernel code handling the system call
 - (b) When a user makes a system call, the trap instruction is invoked by userspace code (e.g., user program or a library)
 - (c) When an external I/O device raises an interrupt, the trap instruction is invoked by the device driver handling the interrupt
 - (d) When an external I/O device raises an interrupt signaling the completion of an I/O request, the trap instruction is invoked by the user process that raised the I/O request

Ans: (b)

29. Which of the following statements is/are true about a context switch?

- (a) A context switch from one process to another will happen every time a process moves from user mode to kernel mode
- (b) For preemptive schedulers, a trap of any kind always leads to a context switch
- (c) A context switch will always occur when a process has made a blocking system call, irrespective of whether the scheduler is preemptive or not
- (d) For non-preemptive schedulers, a process that is ready/willing to run will not be context switched out

Ans: (c), (d)

30. When a process makes a system call and runs kernel code:

- (a) How does the process obtain the address of the kernel instruction to jump to?
- (b) Where is the userspace context of the process (program counter and other registers) stored during the transition from user mode to kernel mode?

Ans:

(a) From IDT (interrupt descriptor table) (b) on kernel stack of process (which is linked from the PCB)

31. Which of the following operations by a process will definitely cause the process to move from user mode to kernel mode? Answer yes (if a change in mode happens) or no.

- (a) A process invokes a function in a userspace library.

Ans: no

- (b) A process invokes the `kill` system call to send a signal to another process.

Ans: yes

32. Consider the following events that happen during a context switch from (user mode of) process P to (user mode of) process Q, triggered by a timer interrupt that occurred when P was executing, in a Unix-like operating system design studied in class. Arrange the events in chronological order, starting from the earliest to the latest.

(A) The CPU program counter moves from the kernel address space of P to the kernel address space of Q.

(B) The CPU executing process P moves from user mode to kernel mode.

(C) The CPU stack pointer moves from the kernel stack of P to the kernel stack of Q.

(D) The CPU program counter moves from the kernel address space of Q to the user address space of Q.

(E) The OS scheduler code is invoked.

Ans:

B E C A D

33. Consider a system with two processes P and Q, running a Unix-like operating system as studied in class. Consider the following events that may happen when the OS is concurrently executing P and Q, while also handling interrupts.

- (A) The CPU program counter moves from pointing to kernel code in the kernel mode of process P to kernel code in the kernel mode of process Q.
- (B) The CPU stack pointer moves from the kernel stack of P to the kernel stack of Q.
- (C) The CPU executing process P moves from user mode of P to kernel mode of P.
- (D) The CPU executing process P moves from kernel mode of P to user mode of P.
- (E) The CPU executing process Q moves from the kernel mode of Q to the user mode of Q.
- (F) The interrupt handling code of the OS is invoked.
- (G) The OS scheduler code is invoked.

For each of the two scenarios below, list out the chronological order in which the events above occur. Note that all events need not occur in each question.

- (a) A timer interrupt occurs when P is executing. After processing the interrupt, the OS scheduler decides to return to process P.
- (b) A timer interrupt occurs when P is executing. After processing the interrupt, the OS scheduler decides to context switch to process Q, and the system ends up in the user mode of Q.

Ans:

- (a) C F G D
- (b) C F G B A E

34. In modern operating systems, the process of saving user context of a process on a trap is done jointly by hardware and software. The trap instruction saves a few registers like the program counter (PC) and stack pointer (SP) to some location (say, the kernel stack of the process), while the kernel's trap handling software code saves the other registers like general purpose registers. Which one of the following statements best describes the reason behind this division of work between the hardware and software?

Ans: _____

- (a) The CPU hardware cannot access the general purpose registers and hence cannot save them
- (b) The OS software does not have the privilege to read the PC and SP registers and hence cannot save them
- (c) The old values of the PC and SP would have changed by the time the OS code starts to run, so the OS software cannot save the PC and SP of user context
- (d) There is no real reason for this division of work, and it is simply a convention followed by system designers

Ans: c

35. Consider the following three processes that arrive in a system at the specified times, along with the duration of their CPU bursts. Process P1 arrives at time $t=0$, and has a CPU burst of 10 time units. P2 arrives at $t=2$, and has a CPU burst of 2 units. P3 arrives at $t=3$, and has a CPU burst of 3 units. Assume that the processes execute only once for the duration of their CPU burst, and terminate immediately. Calculate the time of completion of the three processes under each of the following scheduling policies. For each policy, you must state the completion time of all three processes, P1, P2, and P3. Assume there are no other processes in the scheduler's queue. For the preemptive policies, assume that a running process can be immediately preempted as soon as the new process arrives (if the policy should decide to preempt).
- (a) First Come First Serve
 - (b) Shortest Job First (non-preemptive)
 - (c) Shortest Remaining Time First (preemptive)
 - (d) Round robin (preemptive) with a time slice of (atmost) 5 units per process

Ans:

- (a) FCFS: P1 at 10, P2 at 12, P3 at 15
 - (b) SJF: same as above
 - (c) SRTF: P2 at 4, P3 at 7, P1 at 15
 - (d) RR: P2 at 7, P3 at 10, P1 at 15
36. Consider a system with a single CPU core and three processes A, B, C. Process A arrives at $t = 0$, and runs on the CPU for 10 time units before it finishes. Process B arrives at $t = 6$, and requires an initial CPU time of 3 units, after which it blocks to perform I/O for 3 time units. After returning from I/O wait, it executes for a further 5 units before terminating. Process C arrives at $t = 8$, and runs for 2 units of time on the CPU before terminating. For each of the scheduling policies below, calculate the time of completion of each of the three processes. Recall that only the size of the current CPU burst (excluding the time spent for waiting on I/O) is considered as the "job size" in these schedulers.
- (a) First Come First Serve (non-preemptive).
Ans: A=10, B=21, C=15. A finishes at 10 units. First run of B finishes at 13. C completes at 15. B restarts at 16 and finishes at 21.
 - (b) Shortest Job First (non-preemptive)
Ans: A=10, B=23, C=12. A finishes at 10 units. Note that the arrival of shorter jobs B and C does not preempt A. Next, C finishes at 12. First task of B finishes at 15, B blocks from 15 to 18, and finally completes at 23 units.
 - (c) Shortest Remaining Time First (preemptive)
Ans: A=15, B=20, C=11. A runs until 6 units. Then the first task of B runs until 9 units. Note that the arrival of C does not preempt B because it has a shorter remaining time. C completes at 11. B is not ready yet, so A runs for another 4 units and completes at 15. Note that the completion of B's I/O does not preempt A because A's remaining time is shorter. B finally restarts at 15 and completes at 20.

37. Consider three processes P1, P2 and P3 that arrive in a single-core system at times 0, 4 and 10 milliseconds. (Note: when we say a process arrives at time n , we mean that the process arrives after the n -th time unit has finished.) The CPU bursts of the processes are 8, 4 and 1 milliseconds respectively.

- (a) What are the turnaround times of P1, P2 and P3 (in milliseconds) if the CPU scheduler uses the pre-emptive shortest remaining time first policy?

Ans: 13, 4, 1 or 8, 9, 1 (depending on how you break ties of processes having the same remaining time)

- (b) Repeat the above question for the non-preemptive shortest job first policy.

Ans: 8, 8, 3

- (c) Repeat the above question for the non-preemptive FIFO policy.

Ans: 8, 8, 3

38. Consider the various CPU scheduling mechanisms and techniques used in modern schedulers.

- (a) Describe one technique by which a scheduler can give higher priority to I/O-bound processes with short CPU bursts over CPU-bound processes with longer CPU bursts, without the user explicitly having to specify the priorities or CPU burst durations to the scheduler.

Ans: Reducing priority of a process that uses up its time slice fully (indicating it is CPU bound)

- (b) Describe one technique by which a scheduler can ensure that high priority processes do not starve low priority processes indefinitely.

Ans: Resetting priority of processes periodically, or round robin.

39. Consider the following new scheduling policy proposed for an OS. For every process P_i in the scheduler's ready queue waiting to be scheduled, let c_i be the size of the average CPU burst of the process in the past, which the OS uses as an approximation for its current expected CPU burst. That is, the OS expects P_i to run approximately for c_i time duration if scheduled on the CPU. The OS will use some reasonable default values of c_i for processes running for the first time, where historical information is not available. For every process in the ready queue, the OS computes $f_i = \frac{1}{ac_i + b}$ where a and b are some non-zero positive constants. Every time the scheduler is invoked (during a voluntary or involuntary context switch), the OS picks the process with the highest value of f_i and runs it for a time quantum (until the timer interrupt goes off) or until the process voluntarily gives up the CPU, whichever happens first.

Answer yes/no for the questions below, with a one-sentence justification.

- (a) Does this policy prioritize I/O-bound processes over CPU-bound processes?

Ans: Yes. Because I/O bound processes have a small CPU burst and hence a higher f_i .

- (b) Does this policy schedule all processes for equal number of times?

Ans: No. Processes with smaller CPU bursts will get scheduled more number of times.

- (c) Can this policy cause starvation of some processes?

Ans: Yes. A CPU-bound process with a low priority can starve if higher priority I/O-bound processes keep arriving continuously.

40. Consider the following C program. Assume there are no syntax errors and the program executes correctly. Assume the fork system calls succeed. What is the output printed to the screen when we execute the below program?

```
void main(argc, argv) {  
  
    for(int i = 0; i < 4; i++) {  
        int ret = fork();  
        if(ret == 0)  
            printf("child %d\n", i);  
    }  
}
```

Ans: The statement “child i” is printed 2^i times for $i=0$ to 3

41. Consider a parent process P that has forked a child process C in the program below.

```
int a = 5;  
int fd = open(...) //opening a file  
int ret = fork();  
if(ret > 0) {  
    close(fd);  
    a = 6;  
    ...  
}  
else if(ret == 0) {  
    printf("a=%d\n", a);  
    read(fd, something);  
}
```

After the new process is forked, suppose that the parent process is scheduled first, before the child process. Once the parent resumes after fork, it closes the file descriptor and changes the value of a variable as shown above. Assume that the child process is scheduled for the first time only after the parent completes these two changes.

- (a) What is the value of the variable a as printed in the child process, when it is scheduled next? Explain.
- (b) Will the attempt to read from the file descriptor succeed in the child? Explain.

Ans:

- (a) 5. The value is only changed in the parent.
- (b) Yes, the file is only closed in the parent.

42. Consider the following pseudocode. Assume all system calls succeed and there are no other errors in the code.

```

int ret1 = fork(); //fork1
int ret2 = fork(); //fork2
int ret3 = fork(); //fork3
wait();
wait();
wait();

```

Let us call the original parent process in this program as P. Draw/describe a family tree of P and all its descendents (children, grand children, and so on) that are spawned during the execution of this program. Your tree should be rooted at P. Show the spawned descendents as nodes in the tree, and connect processes related by the parent-child relationship with an arrow from parent to child. Give names containing a number for descendents, where child processes created by fork "i" above should have numbers like "i1", "i2", and so on. For example, child processes created by fork3 above should have names C31, C32, and so on.

Ans: P has three children, one in each fork statement: C11, C21, C31. C11 has two children in the second and third fork statements: C22, C32. C21 and C22 also have a child each in the third fork statement: C33 and C34.

43. Consider a parent process that has forked a child in the code snippet below.

```

int count = 0;
ret = fork();
if(ret == 0) {
printf("count in child=%d\n", count);
}
else {
count = 1;
}

```

The parent executes the statement "count = 1" before the child executes for the first time. Now, what is the value of count printed by the code above?

Ans: 0 (the child has its own copy of the variable)

44. Consider the following sample code from a simple shell program.

```

command = read_from_user();
int rc = fork();
if(rc == 0) { //child
    exec(command);
}
else { //parent
    wait();
}

```

Now, suppose the shell wishes to redirect the output of the command not to STDOUT but to a file "foo.txt". Show how you would modify the above code to achieve this output redirection. You can indicate your changes next to the code above.

Ans:

Modify the child code as follows.

```
close(STDOUT_FILENO)
open("foo.txt")
exec(command)
```

45. What is the output of the following code snippet? You are given that the `exec` system call in the child does not succeed.

```
int ret = fork();
if(ret==0) {
    exec(some_binary_that_does_not_exec);
    printf("`child\n`");
}
else {
    wait();
    printf("`parent\n`");
}
```

Ans:

```
child
parent
```

46. Consider the following code snippet, where a parent process forks a child process. The child performs one task during its lifetime, while the parent performs two different tasks.

```
int ret = fork();
if(ret == 0) { do_child_task(); }
else { do_parent_task1();
       do_parent_task2(); }
```

With the way the code is written right now, the user has no control over the order in which the parent and child tasks execute, because the scheduling of the processes is done by the OS. Below are given two possible orderings of the tasks that the user wishes to enforce. For each part, briefly describe how you will modify the code given above to ensure the required ordering of tasks. You may write your answer in English or using pseudocode.

Note that you cannot change the OS scheduling mechanism in any way to solve this question. If a process is scheduled by the OS before you want its task to execute, you must use mechanisms like system calls and IPC techniques available to you in userspace to delay the execution of the task till a suitable time.

- (a) We want the parent to start execution of both its tasks only after the child process has finished its task and has terminated.

Ans: Parent does `wait()` until child finishes, and then starts its tasks.

- (b) We want the child process to execute its task after the parent process has finished its first task, but before it runs its second task. The parent must not execute its second task until the child has completed its task and has terminated.

Ans: Many solutions are possible. Parent and child share two pipes (or a socket). Parent writes to one pipe after completing task 1 and child blocks on this pipe read before starting its task. Child writes to pipe 2 after finishing its task, and parent blocks on this pipe read before starting its second task. (Or parent can use wait to block for child termination, like in previous part.)

47. What are the possible outputs printed from this program shown below? You may assume that the program runs on a modern Linux-like OS. You may ignore any output generated from “some_executable”. You must consider all possible scenarios of the system calls succeeding as well as failing. In your answer, clearly list down all the possible scenarios, and the output of the program in each of these scenarios.

```
int ret = fork();
if(ret == 0) {
    printf("`Hello1\n'");
    exec("`some_executable'");
    printf("`Hello2\n'");
} else if(ret > 0) {
    wait();
    printf("`Hello3\n'");
} else {
    printf("`Hello4\n'");
}
```

Ans: Case I: fork and exec succeed. Hello1, Hello3 are printed. Case II: fork succeeds but exec fails. Hello1, Hello2, Hello3 are printed. Case III: fork fails. Hello4 is printed.

48. Consider the following sample code from a simple shell program.

```
int rc1 = fork();
if(rc1 == 0) {
    exec(cmd1);
}
else {
    int rc2 = fork();
    if(rc2 == 0) {
        exec(cmd2);
    }
    else {
        wait();
        wait();
    }
}
```

- (a) In the code shown above, do the two commands `cmd1` and `cmd2` execute serially (one after the other) or in parallel? **Ans:** parallel.
- (b) Indicate how you would modify the code above to change the mode of execution from serial to parallel or vice versa. That is, if you answered “serial” in part (a), then you must change the code to execute the commands in parallel, and vice versa. Indicate your changes next to the code snippet above. **Ans:** move the first wait to before second fork.
49. Consider the following code snippet running on a modern Linux operating systems (with a reasonable preemptive scheduling policy as studied in class). Assume that there are no other interfering processes in the system. Note that the executable “good_long_executable” runs for 100 seconds, prints the line “Hello from good executable” to screen, and terminates. On the other hand, the file “bad_executable” does not exist and will cause the `exec` system call to fail.

```
int ret1 = fork();
if(ret1 == 0) { //Child 1
    printf("Child 1 started\n");
    exec("good_long_executable");
    printf("Child 1 finished\n");
}
else { //Parent
    int ret2 == fork();
    if(ret2 == 0) { //Child 2
        sleep(10); //Sleeping allows child 1 to begin execution
        printf("Child 2 started\n");
        exec("bad_executable");
        printf("Child 2 finished\n");
    } //end of Child 2
    else { //Parent
        wait();
        printf("Child reaped\n");
        wait();
        printf("Parent finished\n");
    }
}
```

Write down the output of the above program.

Ans:

Child 1 started
Child 2 started
(Some error message from the wrong executable)
Child 2 finished
Child reaped
Hello from good executable
Parent finished

50. What is the output printed by the following snippet of pseudocode? If you think there is more than one possible answer depending on the execution order of the processes, then you must list all possible outputs.

```
int fd[2];
pipe(fd);
int rc = fork();
if(rc == 0) { //child
    close(fd[1]);
    printf("`child1\n'");
    read(fd[0], bufc, bufc_size);
    printf("`child2\n'");
}
else { //parent
    close(fd[0]);
    printf("`parent1\n'");
    write(fd[1], bufp, bufp_size);
    wait();
    printf("`parent2\n'");
}
```

Ans: If child scheduled before parent: child1, parent1, child2, parent 2. If parent scheduled before child, parent1, child1, child2, parent2.

51. What is the output of the following program? Only relevant code snippets are shown, and you may assume that the code compiles and executes successfully.

```
int a = 2;
while(a > 0) {
    int ret = fork();
    if(ret == 0) {
        a++;
        printf("a=%d\n", a);
    }
    else {
        wait(NULL);
        a--;
    }
}
```

Ans: The code goes into an infinite while+fork loop, as every child that is forked will execute the same code with a higher value of “a” and hence the while loop never terminates. There will be an infinite number of child processes that will print a=3,4,5, and so on, until either fork fails or the system exhausts some other resource.

52. What is the output of the following program? Only relevant code snippets are shown, and you may assume that the code compiles and executes successfully.

```
int a = 2;
while(a > 0) {
    int ret = fork();
    if(ret == 0) {
        a++;
        printf("a=%d\n", a);
        execl("/bin/ls", "/bin/ls", NULL);
    }
    else {
        wait(NULL);
        a--;
    }
}
```

Ans:

```
a=3
<output of ls>
a=2
<output of ls>
```

53. Consider the program shown below, with two fork system calls. When the first fork runs, Parent P (PID: 8268) forks C1 (PID: 8269). When the second fork runs, P forks C2 (PID: 8270), and C1 forks C3 (PID: 8271). The program below prints 4 lines. Write down these 4 lines (which may be printed in any order) in the space next to the question.

```
int main() {
    int ret1 = fork();
    int ret2 = fork();
    printf("%d %d\n", ret1, ret2);
    wait(NULL);
    wait(NULL);
}
```

Ans: P prints "8269 8270", C1 prints "0 8271", C2 prints "8269 0", C3 prints "0 0"

54. What are the outputs of the program shown below?

```
int x = 3;
void main() {
    while(x > 0) {
        int ret = fork();
```

```

    if(ret == 0) {
        printf("x = %d\n", x);
    }
    else wait(NULL);
    x--;
} }

```

Ans: 3 is printed once, 2 twice, 1 four times

55. What are the outputs of the program shown below? Note that the program below invokes the exec system call with itself as the argument. That is, “a.out” refers to the executable of the program shown below itself.

```

int x = 3;
void main() {
    while(x > 0) {
        int ret = fork();
        if(ret == 0) {
            printf("x = %d\n", x);
            x--;
            execl("./a.out", "a.out", "", 0);
        }
        else wait(NULL);
    } }

```

Ans: Endless loop of x=3

56. Consider an application that is composed of one master process and multiple worker processes that are forked off the master at the start of application execution. All processes have access to a pool of shared memory pages, and have permissions to read and write from it. This shared memory region (also called the request buffer) is used as follows: the master process receives incoming requests from clients over the network, and writes the requests into the shared request buffer. The worker processes must read the request from the request buffer, process it, and write the response back into the same region of the buffer. Once the response has been generated, the server must reply back to the client. The server and worker processes are single-threaded, and the server uses event-driven I/O to communicate over the network with the clients (you must not make these processes multi threaded). You may assume that the request and the response are of the same size, and multiple such requests or responses can be accommodated in the request buffer. You may also assume that processing every request takes similar amount of CPU time at the worker threads. Using this design idea as a starting point, describe the communication and synchronization mechanisms that must be used between the server and worker processes, in order to let the server correctly delegate requests and obtain responses from the worker processes. Your design must ensure that every request placed in the request buffer is processed by one and only one worker thread. You must also ensure that the system is efficient (e.g., no request should be kept waiting if some worker is free) and fair (e.g., all workers share the load almost equally). While you can use any IPC mechanism of your choice, ensure that your system design is practical enough to be

implementable in a modern multicore system running an OS like Linux. You need not write any code, and a clear, concise and precise description in English should suffice.

Ans: Several possible solutions exist. The main thing to keep in mind is that the server should be able to assign a certain request in the buffer to a worker, and the worker must be able to notify completion. For example, the master can use pipes or sockets or message queues with each worker. When it places a request in the shared memory, it can send the position of the request to one of the workers. Workers listen for this signal from the master, process the request, write the response, and send a message back to the master that it is done. The master monitors the pipes/sockets of all workers, and assigns the next request once the previous one is done.