Automated reasoning 2016

Lecture 5: Proof generation

Instructor: Ashutosh Gupta

TIFR, India

Compile date: 2016-04-26



Where are we and where are we going?

I assume, you have seen

- CDCL (or DPLL)
- $CDCL(\mathcal{T})$ (or $DPLL(\mathcal{T})$)
- Theory of equality with uninterpreted functions(T_{EUF})
- Theory of linear rational arithmetic (T_{LRA})

We will see

▶ proof generation in CDCL(T) with T_{LRA}/T_{EUF}



Topic 5.1

Resolution proofs for propositional logic



Resolution Proofs

A resolution proof rule is

$$\frac{p \lor C \quad \neg p \lor D}{C \lor D}$$

We say p is a pivot that produced $C \vee D$.

Example 5.1 Suppose $F = (p \lor q) \land (\neg p \lor q) \land (\neg q \lor r) \land \neg r$



Exercise 5.1

Prove the following generalized proof rule

$$\frac{\ell_1 \vee C_1 \quad \dots \quad \ell_k \vee C_k \quad \neg \ell_1 \vee \dots \vee \neg \ell_k \vee D}{C_1 \vee \dots \vee C_k \vee D}$$



Implication graph for conflict graph



Reading proofs from implication graphs

► For each learned clause we assign a resolution proof that proves that the learned clause is implied by the clauses in the solver so far.

We demonstrate the process using an example.



Resolution proofs for conflict clauses

Example 5.4 (contd.)



The above is a resolution proof of the conflict clause.

One more issue:

There may be a leaf of the above proof that is a conflict clause in itself.

- ▶ In the case, there must be a resolution proof for the conflict clause.
- ▶ We "stitch" that proof on top of the above proof .



$\mathsf{CDCL}(\mathcal{T})$ with proof generation

Algorithm 5.1: CDCL(T)

```
Input: CNF F, boolean encoder e
ADDCLAUSES(e(F)); m := UNITPROPAGATION();dl := 0;dstack := \lambda x.0;proofs = \lambda C.C;
do
     // backtracking
     while \exists x \{x \mapsto 0, x \mapsto 1\} \subseteq m do
          (C, dl, proof) := ANALYZECONFLICT(m, proofs); proofs(C) := proof;
          if C = \emptyset then return unsat(proof);
          m.resize(dstack(dl)); ADDCLAUSES({C}); m := UNITPROPAGATION();
        Boolean decision
     if m is partial then
          dstack(dl) := m.size();
         dl := dl + 1; m := DECIDE(); m := UNITPROPAGATION();
                                                    We also need proofs of Cs from the theory
     // Theory propagation
     if \forall x \{x \mapsto 0, x \mapsto 1\} \not\subseteq m then
                                                    solvers
          (Cs, dl', proofs') := \text{THEORYDEDUCTION}(\wedge e^{-1}(m));
          if dl' < dl then \{dl = dl'; m.resize(dstack(dl)); \};
          proofs := proofs \cup proofs'; ADDCLAUSES(e(Cs)); m := UNITPROPAGATION();
while m is partial or \exists x \{x \mapsto 0, x \mapsto 1\} \subset m;
```

return sat

Topic 5.2

Proofs in SAT solvers



Issues in generation proofs in SAT solvers or any solver

Proof format vs. checking

- > Detailed proofs require non-trivial work from solvers, causing overhead.
- Missing details in proofs imply expensive proof checkers.

Proof minimization

- Problems of moderate size may have very large proofs
- Proofs often have redundancies
- It is wise to minimize proofs before dumping it out



Proof formats in SAT solvers

SAT solvers typically return two kinds of proofs

- List of learned clauses (low overhead)
- Resolution proofs (detailed)



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Proof checking

A proof is a proof only if an independent checker can checker it efficiently.

To check a learned clauses proof, we need to check the following things

- 1. Unit propagation on the input+learned clauses leads to conflict
- 2. Each learned clause is implied by the preceding+input clauses

Exercise 5.2

a. Give procedure for the 2nd step in the above proof checking

b. Give procedure for checking resolution proofs as presented in the the previous slide



Proof minimization

- > There are several kinds of redundancies that may occur in proofs.
- ▶ We may apply several passes to minimize for each kind
- A minimization pass should preferably be a linear-time algorithm

Here we present one such case.



Redundent resolutions

The process of resolution removes a literal in each step until none is left. In a step, the pivot literal is removed and others may be introduced.

Definition 5.1

if a pivot is repeated in a derivation path to \perp , then the earlier resolution is redundant in the path.

Example 5.6

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Consider the following resolution proof:



Removing redundant resolution

By rewiring the proof, we may remove the redundant node v.

One of the parent of v will be wired to the children of v. Example 5.7



After rewiring we may need to update clauses in some proof nodes.

Exercise 5.3

Which parent to choose?



Detecting redundant resolution - expansion set Definition 5.2

For a proof node v, expansion set $\rho(v)$ is the set of literals such that $\ell \in \rho(v)$ iff ℓ will be removed in all paths to \perp . ρ is defined as follows.

$$\rho(\mathbf{v}) = \begin{cases} \emptyset & \mathbf{v} = \bot \\ \bigcap_{\mathbf{v}' \in children(\mathbf{v})} \rho(\mathbf{v}') \cup \{rlit(\mathbf{v}, \mathbf{v}')\} - \{\neg rlit(\mathbf{v}, \mathbf{v}')\} & otherwise \end{cases}$$

where rlit(v, v') is the literal involved on the edge (v, v'). Exercise 5.4 $a \lor b \neg a \lor b$ Calculate $\rho(v)$ for each node: $a \lor \neg c \qquad a \lor c \qquad \neg a$ $\neg c \qquad c \qquad \downarrow$



Detecting redundant resolution (contd.)

Theorem 5.1

If pivot(v) or $\neg pivot(v) \in \rho(v)$ then v is redundant.

Exercise 5.5

- a. What is the complexity of computing ρ ?
- b. Prove $\rho(\mathbf{v}) \supseteq$ literals in \mathbf{v}
- c. Given the above observation suggest an heuristic optimization.



Topic 5.3

Proofs from theory solvers



Each theory needs to have its own proof rules and instrumentation of the employed decision procedure to obtain proofs.

Here, we will look at two examples

- Theory of linear rational arithmetic (T_{LRA})
- Theory of equality with uninterpreted functions(\mathcal{T}_{EUF})



Proof generation in \mathcal{T}_{LRA}

In the theory of LRA, atoms are linear constraints over rational variables.

The following is the only proof rule for the theory.

$$\frac{a_1x \leq b_1 \quad a_1x \leq b_1}{(\lambda_1a_1 + \lambda_2a_2)x \leq (\lambda_1b_1 + \lambda_2b_2)}\lambda_1, \lambda_2 \geq 0$$

Example 5.8
Consider:
$$3x_1 \le -6 \land x_1 - 3x_2 \le 1 \land x_1 + x_2 \le 2$$

$$\frac{3x_1 \le -6}{\frac{x_1 - 3x_2 \le 1 \quad x_1 + x_2 \le 2}{4x_1 \le 7}} \lambda_1 = 1, \lambda_2 = 3$$

$$\lambda_1 = 4/3, \lambda_2 = 1$$



LRA solver

There are many decision procedures for solving LRA.

We will present proof generation via Fourier-Motzkin algorithm for solving LRA.



Proof generation from Fourier-Motzkin

Observation:

- Fourier-Motzkin proceeds by replacing inequalities by other inequalities
- incoming inequalities are positive linear combination of old inequalities
- We may instrument Fourier-Motzkin to keep the record and produce proof if input is found to be unsat

Example 5.9

In the previous example,

$$\frac{-x_1 + x_2 + 2x_3 \le 0 \quad x_1 - x_3 \le 0}{x_2 + x_3 \le 0} \quad \frac{-x_1 + x_2 + 2x_3 \le 0 \quad x_1 - x_2 \le 0}{x_3 \le 0} - x_3 \le -1$$



End of Lecture 5

