

CS 433 Automated Reasoning 2022

Lecture 19: Theory of arrays

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Topic 19.1

Theory of arrays

Theory of arrays

The presence of arrays in programs is ubiquitous.

A solving engine needs to be able to reason over arrays.

Here we present an axiomatization of arrays, which has the following properties.

- ▶ arrays are accessible by function symbols $_{-}[_{-}]$ and *store*
- ▶ $_{-}[_{-}]$ and *store* can access an index at a time
- ▶ arrays have unbounded length

Commentary: This is a simplified view of arrays. It does not model length of arrays.

Many sorted FOL

FOL is often defined without sorts.

We need many sorted FOL to model arrays, indexes, and values.

In many sorted FOL, a model has a domain that is partitioned for values of each sort.

A term takes value only from its own sort.

Understanding *store* and $[-]$

- ▶ $[-]$ returns a value stored in an array at an index

$$[-] : Array \times Index \rightarrow Value$$

- ▶ *store* places a value at an index in an array and returns a modified array

$$store : Array \times Index \times Value \rightarrow Array$$

Array, *Index*, and *Elem* are disjoint parts of the domain of a model.

Commentary: Please leave your programmer's intuition behind. Here arrays are not mutable. A write on array does not modify the array, but produces a modified copy.

Axiom of theory of arrays (with extensionality)

Let $\mathbf{S}_A \triangleq (\{-[-]/2, store/3\}, \emptyset)$. Assuming $=$ is part of FOL syntax.

Definition 19.1

Theory of arrays[†] \mathcal{T}_A is defined by the following three axioms.

1. $\forall a \forall i \forall v. store(a, i, v)[i] = v$
2. $\forall a \forall i \forall j \forall v. i \neq j \Rightarrow store(a, i, v)[j] = a[j]$
3. $\forall a, b. \exists i. (a \neq b \Rightarrow a[i] \neq b[i])$

(extensionality axiom)

The theories that replace the 3rd axiom with some other axiom(s) are called non-extensional theory of arrays

[†] McCarthy, J.: Towards a mathematical science of computation. In: IFIP Congress. (1962) 21-28

Models for theory of arrays

A model m contains a set of indexes $Index_m$, a set of values $Value_m$, and a set of arrays $Array_m$. Constants take values from their respective sorts.

Exercise 19.1

Prove $|Array_m| = |Index_m \rightarrow Value_m|$ for model m .

Example 19.1

Consider the following satisfying model of formula $a[i] = a[j] \wedge i \neq j$:

Let $Index_m = \{1, 2\}$ and $Value_m = \{3, 8\}$ and $Array_m = \{a_1, a_2, a_3, a_4\}$

- ▶ $a_1[1]_m = 3, a_1[2]_m = 3,$
- ▶ $a_2[1]_m = 8, a_2[2]_m = 8$
- ▶ $a_3[1]_m = 3, a_3[2]_m = 8,$
- ▶ $a_4[1]_m = 8, a_4[2]_m = 3$

$store_m(a_1, 1, 3) = a_1, store_m(a_1, 1, 8) = a_4, store_m(a_4, 2, 8) = \dots, \dots,$

$i_m = 1, j_m = 2, a_m = a_1$

Decidability

Theory of arrays is undecidable.

However, quantifier-free (QF) fragment is decidable and its complexity is NP.

Example : checking sat in theory of arrays

Example 19.2

Consider the following QF_AX formula: $store(a, i, b[i]) = store(b, i, a[i]) \wedge a \neq b$

Apply axiom 3, $store(a, i, b[i]) = store(b, i, a[i]) \wedge a[j] \neq b[j]$

Due to congruence, $store(a, i, b[i])[j] = store(b, i, a[i])[j] \wedge a[j] \neq b[j]$

case $i = j$: Due to the axiom 1, $b[i] = a[i] \wedge a[j] \neq b[j] \leftarrow$ *Contradiction.*

case $i \neq j$: Due to the axiom 2, $a[j] = b[j] \wedge a[j] \neq b[j] \leftarrow$ *Contradiction.*

Therefore, the formula is unsat.

Exercise

Exercise 19.2

Show if the following formulas are sat or unsat

1. $a = b \wedge a[i] \neq b[i]$
2. $a = b \wedge a[i] \neq b[j]$
3. $store(store(a, j, y), i, x) \neq store(store(a, i, x), j, y) \wedge i \neq j$

Topic 19.2

A theory solver for \mathcal{T}_A

Theory solver for arrays

The key issues of checking sat of conjunction of \mathcal{T}_A literals are

- ▶ finding the set of the indices of interest
- ▶ finding the witness of disequality

Array solvers lazily/eagerly **add instantiations of the axioms** for relevant indices

Commentary: An eager solver instantiates axioms all possible relevant ways at pre-solving phase and solves using some EUF solver. A lazy solver instantiates on demand. And, there can be a combination of the two approaches.

A policy of axiom instantiations

Here we present the policy used in Z3 to add the instantiations.

- ▶ flattening of clauses
- ▶ solve flattened clauses using $\text{CDCL}(\mathcal{T}_{\text{EUF}})$
- ▶ time to time introduce new clauses due to instantiations.

L. Moura, N. Bjorner, Generalized, Efficient Array Decision Procedures. FMCAD09 (section 2-4)

Commentary: Here is another policy used in another solver:

M. Bofill and R. Nieuwenhuis, A Write-Based Solver for SAT Modulo the Theory of Arrays, FMCAD2008

Flattening

The solver maintains a set of definitions and a set of clauses.

$store$ terms are replaced by a fresh symbol and the definitions record the replacement.

Example 19.3

Consider clauses: $store(store(a, j, y), i, x) \neq store(store(a, i, x), j, y) \wedge i \neq j$

Flattened clauses: $u \neq v \wedge i \neq j$

Definition store: $u \triangleq store(u', i, x), u' \triangleq store(a, j, y), v \triangleq store(v', j, y), v' \triangleq store(a, i, y)$

Exercise 19.3

Translate the following in flattened clauses: $store(a, i, b[i]) = store(b, i, a[i]) \wedge a \neq b$

Commentary: The example is not chosen well. It has only unit clauses.

CDCL(\mathcal{T}_{EUF}) on flattened clauses

CDCL(\mathcal{T}_{EUF}) is iteratively applied on the flattened clauses as follows.

1. Run CDCL(\mathcal{T}_{EUF}) on the flattened clauses
2. If no assignment found then return unsat. Otherwise, \mathcal{T}_{EUF} has found equivalences that are compatible with the current clauses
3. Add relevant instantiations of array axioms due to the discovery of new equivalent classes
4. If no new instantiations added then return sat. Otherwise, goto 1

Commentary: CDCL assigns truth value to atoms and EUF solver translates the truth values into equivalence classes.

Relevant axiom instantiation

The following rules add new instantiations of the axioms in the clause set.
The instantiated clauses are flattened and added in $\text{CDCL}(\mathcal{T}_{\text{EUF}})$.

\sim denotes the discovered
equivalences in \mathcal{T}_{EUF}

$$\frac{a \triangleq \text{store}(b, i, v)}{a[i] = v}$$

$$\frac{a \triangleq \text{store}(b, i, -) \quad - \triangleq a'[j] \quad a \sim a'}{i = j \vee a[j] = b[j]}$$

$$\frac{a \triangleq \text{store}(b, i, -) \quad - \triangleq b'[j] \quad b \sim b'}{i = j \vee a[j] = b[j]}$$

$$\frac{a : \text{Array} \quad b : \text{Array}}{a = b \vee a[k_{a,b}] \neq b[k_{a,b}]}$$

Commentary: Reading the above rules: In the 2nd rule, if a is defined as above, a and a' are equivalent under current assignment, and a' is accessed at j then we instantiate the 2nd axiom involving indexes i and j , and arrays a and b

Soundness and completeness

The solver is sound because it only introduces the instantiations of axioms.

Theorem 19.1

The solver is complete

Proof sketch.

We need to show that only finite and all relevant instantiations are added.
If no conflict is discovered after saturation then we can construct a model.



Exercise 19.4

Fill the details in the above proof

- ▶ *Only finite instantiations are added*
- ▶ *Construct a model at saturation*

Optimizations

We may reduce the number of instantiations that are needed to be complete.

Here, we discuss three such optimizations.

- ▶ Instantiations for equivalent symbols are redundant
- ▶ Instantiate extensionality only if a disequality is discovered in EUF
- ▶ Instantiate 2nd axiom only if the concerning index is involved in the final model construction

Redundant Instantiations

If EUF solver has proven $i \sim i'$, $j \sim j'$, $a \sim a'$, and $b \sim b'$ then

$$i = j \vee a[j] = b[j] \quad \text{and} \quad i' = j' \vee a'[j'] = b'[j']$$

are mutually redundant instantiations.

We need to instantiate only one of the two.

Similarly, if EUF solver has proven $a \sim a'$, and $b \sim b'$ then

$$a = b \vee a[k_{a,b}] \neq b[k_{a,b}] \quad \text{and} \quad a' = b' \vee a'[k_{a',b'}] \neq b'[k_{a',b'}]$$

are mutually redundant instantiations.

Extensionality axiom only for disequalities

We only need to produce evidence that two arrays are disequal only if EUF finds such disequality

$$\frac{a : \text{Array} \quad b : \text{Array} \quad a \not\approx b}{a = b \vee a[k_{a,b}] \neq b[k_{a,b}]}$$

Restricted instantiation of the 2nd axiom

Definition 19.2

$b \in \text{nonlinear}$ if

1. $b \triangleq \text{store}(-, -, -)$ and there is another b' such that $b \sim b'$ and $b' \triangleq \text{store}(-, -, -)$
2. $a \triangleq \text{store}(b, -, -)$ and $a \in \text{nonlinear}$
3. $a \sim b$ and $a \in \text{nonlinear}$

We restrict the third instantiation rule as follows.

$$\frac{a \triangleq \text{store}(b, i, v) \quad w \triangleq b'[j] \quad b \sim b' \quad b \in \text{nonlinear}}{i = j \vee a[j] = b[j]}$$

Theorem 19.2

If $b \notin \text{nonlinear}$, value of index j has no effect in the model construction of a .

Topic 19.3

A decidable fragment of quantified arrays

Decidable fragments

Definition 19.3

*An undecidable class often has non-obvious sub-classes that are decidable, which are called **decidable fragments**.*

For example, QF_AX is a decidable fragment of AX.

Finding decidable fragments of various logics is an active area of research.

Now we will present a decidable fragment of AX called “array properties”, which allows some restricted form of quantifiers.

For ease of introducing core ideas, the fragment presented here is smaller than the original proposal in

Aaron R. Bradley, Zohar Manna, Henny B. Sipma: What's Decidable About Arrays? VMCAI 2006

Some notation

For formulas/terms F and G , we say

- ▶ $G \in F$ if G occurs in F and
- ▶ G is QF in F if $G \in F$ and no variable in $FV(G)$ is universally quantified in F

Array properties

Array properties fragment puts the following restrictions.

- ▶ *Index* = \mathbb{Z} .
- ▶ *Value* sort is part of some decidable theory \mathcal{T}_v .
- ▶ the formulas in the fragment are conjunctions of **array properties** that are defined next.

Array property

Definition 19.4

An *array property* is a formula that has the following shape.

$$\forall \vec{i}. (F_I(\vec{i}) \Rightarrow F_V(\vec{i}))$$

▶ there are other array, index, and value variables that are free

▶ $F_I(\vec{i}) \in \text{guard}$

$$\text{guard} ::= \text{guard} \vee \text{guard} \mid \text{guard} \wedge \text{guard} \mid \text{exp} \leq \text{exp} \mid \text{exp} = \text{exp}$$

$$\text{exp} ::= i \mid \text{pexp} \quad i \in \vec{i}$$

$$\text{pexp} ::= \mathbb{Z} \mid \mathbb{Z}j \mid \text{pexp} + \text{pexp} \quad j \notin \vec{i}$$

▶ $F_V(\vec{i})$ is a QF formula from \mathcal{T}_V . If $i \in \vec{i}$ and $i \in F_V$ then i only occurs as parameter of some array read and nested accesses are disallowed.

Example: array properties

Example 19.4

Are the following formulas array properties?

- ▶ $\forall i. a[i] = b[i]$ ✓
- ▶ $\forall i. a[i] = b[i + 1]$ ✗
- ▶ $\forall i. a[i] = b[j + 1]$ ✓
- ▶ $\forall i, j. i \leq j \Rightarrow a[i] \leq a[j]$ ✓
- ▶ $\forall i, j. i \leq j \Rightarrow a[a[i]] \leq a[j]$ ✗
- ▶ $\forall i, j. i \leq k + 1 \Rightarrow a[i] \leq a[j]$ ✓
- ▶ $\forall i, j. \neg(i \leq k + 1) \Rightarrow a[i] \leq a[j]$ ✗
- ▶ $\forall i, j. i \leq j + 1 \Rightarrow a[i] \leq a[j]$ ✗

Decision procedure: notation

For an array property F ,

Definition 19.5

The *read Set* R_F is $\{t \mid \lceil t \rceil \in F \wedge t \text{ is QF in } F\}$

Definition 19.6

The *bound Set* B_F is $\{t \mid (\forall \vec{i}. F_I(\vec{i}) \Rightarrow F_V(\vec{i})) \in F \wedge t \bowtie i \in F_I \wedge t \text{ is QF in } F\}$ where $\bowtie \in \{\leq, =, \geq\}$.

Definition 19.7

For an array property F , *index set* $I_F = B_F \cup R_F$

Decision procedure for array properties

1. Replace writes by 1st and 2nd axioms of arrays

$$F[\text{store}(a, t, v)] \rightsquigarrow F[b] \wedge b[t] = v \wedge \forall i. (i \neq t \Rightarrow a[i] = b[i])$$

We will call the **transformed formula** F' .

Remains in array
property fragment

2. Replace universal quantifiers by index sets

$$F'[(\forall \vec{i}. F_I(\vec{i}) \Rightarrow F_V(\vec{i}))] \rightsquigarrow F'[\bigwedge_{\vec{t} \in I_{F'}^{len(\vec{i})}} (F_I(\vec{t}) \Rightarrow F_V(\vec{t}))]$$

We will call the **transformed formula** F'' .

no universal
quantifiers

3. F'' is in QF fragment of $\mathcal{T}_A + \mathcal{T}_{\mathbb{Z}} + \mathcal{T}_V$. We solve it using a decision procedure for the theory combination. We have not covered theory combination yet!!

Exercise 19.5

Extend this procedure for the boolean combinations of array properties.

Example: solving array properties

Example 19.5

Consider:

$$x < y \wedge k + 1 < \ell \wedge b = \text{store}(a, \ell, x) \wedge c = \text{store}(a, k, y) \wedge \\ \forall i, j. (k \leq i \leq j \leq \ell \Rightarrow b[i] \leq b[j]) \wedge \forall i, j. (k \leq i \leq j \leq \ell \Rightarrow c[i] \leq c[j])$$

After removing stores:

$$x < y \wedge k + 1 < \ell \wedge \\ b[\ell] = x \wedge \forall i. (\ell + 1 \leq i \vee i \leq \ell - 1) \Rightarrow b[i] = a[i] \wedge \\ c[k] = y \wedge \forall i. (k + 1 \leq i \vee i \leq k - 1) \Rightarrow c[i] = a[i] \wedge \\ \forall i, j. (k \leq i \leq j \leq \ell \Rightarrow b[i] \leq b[j]) \wedge \\ \forall i, j. (k \leq i \leq j \leq \ell \Rightarrow c[i] \leq c[j])$$

Exercise 19.6

The index set for the above formula includes expression $k - 1$. Instantiate the last quantified

Commentary: Removing stores may introduce new arrays. The above example is simple enough and we need not introduce new arrays.

Formula for term $k - 1$.

Example: solving array properties(contd.)

Index set $I = \{k - 1, k, k + 1, \ell - 1, \ell, \ell + 1\}$

We instantiate each universal quantifier 6 times.

Therefore, 84 quantifier-free clauses are added.

Let us consider only the following instantiations of the quantifiers:

$$x < y \wedge k + 1 < \ell \wedge b[\ell] = x \wedge c[k] = y \wedge$$

$$(\ell + 1 \leq k + 1 \vee k + 1 \leq \ell - 1) \Rightarrow b[k + 1] = a[k + 1] \wedge$$

$$(k + 1 \leq k + 1 \vee k + 1 \leq k - 1) \Rightarrow c[k + 1] = a[k + 1] \wedge$$

$$k \leq k \leq k + 1 \leq \ell \Rightarrow c[k] \leq c[k + 1] \wedge$$

$$k \leq k + 1 \leq \ell \leq \ell \Rightarrow b[k + 1] \leq b[\ell] \wedge \dots (\text{many more})$$

Since all the above mentioned guards are true,

$$x < y = c[k] \leq c[k + 1] = a[k + 1] = b[k + 1] \leq b[\ell] = x$$

Contradiction.

Why are finite instantiations sufficient for checking sat of \forall quantifiers?

Correctness

Theorem 19.3

If F is sat iff F' is sat

Proof.

This step only explicates theory axioms. Trivially holds. □

Theorem 19.4

If F' is sat iff F'' is sat

Proof.

Since F'' is finite instantiations of F' , if F'' is unsat then F' is unsat.

Now we show that if $m'' \models F''$ then we can construct a model m' for F' .

Let $I_{F'} = \{t^1, \dots, t^\ell\}$. Wlog, we assume $t_{m''}^1 \leq \dots \leq t_{m''}^\ell$

Correctness (contd.)

Proof(contd.)

Observation:

m'' assigns values to all non-array variables of F' .

In arrays, m'' assigns values only at indexes $I_{F'}$. (why?)

Constructing m' :

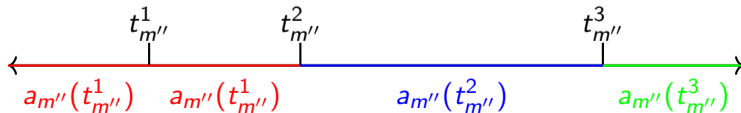
We copy assignment of non-array variables from m'' to m' .

Let a be an array appearing in F' . We construct $a_{m'}$ as follows.

For each $j \in \mathbb{Z}$,

$$a_{m'}(j) \triangleq a_{m''}(t_{m''}^k)$$

where $k = \max\{1\} \cup \{j \mid t_{m''}^j \leq j\}$.



Correctness (contd.)

Proof(contd.)

claim: $m' \models F'$

Consider $\forall \vec{i}. F_I(\vec{i}) \Rightarrow F_V(\vec{i}) \in F'$.

Let $\vec{v} \in \mathbb{Z}^n$, where $n = \text{len}(i)$.

Choose $\vec{u} \triangleq (t_{m''}^{j_1}, \dots, t_{m''}^{j_n})$ and $\vec{w} \triangleq (t_{m''}^{j_1+1}, \dots, t_{m''}^{j_n+1})$ such that $\vec{u} \leq \vec{v} < \vec{w}$.

Since $m'' \models F''$, $m''[\vec{i} \rightarrow \vec{u}] \models F_I(\vec{i}) \Rightarrow F_V(\vec{i})$.

\vec{v} is inside a hyper-cube defined by corners \vec{u} and \vec{w}

Case $m''[\vec{i} \rightarrow \vec{u}] \models F_I(\vec{i})$:

Therefore, $m''[\vec{i} \rightarrow \vec{u}] \models F_V(\vec{i})$.

Therefore, $m''[\vec{i} \rightarrow \vec{v}] \models F_V(\vec{i})$._(why?)

Therefore, $m''[\vec{i} \rightarrow \vec{v}] \models F_I(\vec{i}) \Rightarrow F_V(\vec{i})$.

...

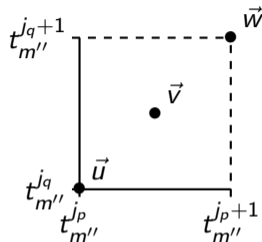
Commentary: This proof divides quantified space into finite parts and chooses a representative such that if it satisfies the formula then all in the partition satisfy the formula.

Correctness (contd.)

Case $m''[\vec{i} \rightarrow \vec{u}] \not\models F_I(\vec{i})$:

For $i_p, i_q \in \vec{i}$, there are three kinds of atoms in F_I .

- ▶ $i_p \leq t^r$
- ▶ $t^r \leq i_p$
- ▶ $i_p \leq i_q$



If an atom is false in $m''[\vec{i} \rightarrow \vec{u}]$ then it is false in $m''[\vec{i} \rightarrow \vec{v}]$. (why?)

Since F_I is **positive** boolean combination of the atoms, $m''[\vec{i} \rightarrow \vec{v}] \not\models F_I(\vec{i})$.

Therefore, $m''[\vec{i} \rightarrow \vec{v}] \models F_I(\vec{i}) \Rightarrow F_V(\vec{i})$.

Exercise 19.7

Some ranges of \vec{i} are missing in the above argument. Complete the proof.

Commentary: Note that if any atom is true at \vec{u} then it can become false at \vec{v} .

Topic 19.4

Problems

Swap

Exercise 19.8

Prove the following formula unsatisfiable using the axioms of the theory of arrays

$$\text{store}(a, i, b[i]) = \text{store}(b, i, a[i]) \wedge a \neq b$$

Prove sorting

Exercise 19.9

Give a model that satisfies the following formula:

$$\forall i, j. (i < j \Rightarrow a[i] = b[i]) \Rightarrow \forall i. a[i] = b[i + 1]$$

Can we also prove?

$$\forall i. a[i] = b[i + 1] \Rightarrow \forall i, j. (i < j \Rightarrow a[i] = b[i])$$

Model generation

Exercise 19.10

Give a model that satisfies the following formula:

$$\text{store}(\text{store}(b, i_0, b[i_1]), i_1, b[i_0]) = \text{store}(\text{store}(b, i_1, b[i_1]), i_1, b[i_1])$$

Run Z3

Exercise 19.11

Run Z3 in proof producing mode on the following example:

$$\text{store}(\text{store}(a, j, y), i, x) \neq \text{store}(\text{store}(a, i, x), j, y) \wedge i \neq j$$

explain the proof of unsatisfiability produced by Z3.

Note that: In smt-lib format select denotes $[-]$.

End of Lecture 19