# CS 433 Automated Reasoning 2025

# Lecture 17: Thinking Integer

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IITB India

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# **Topic 17.1**

Linear integer arithmetic (LIA)



# Linear integer arithmetic (LIA)

Formulas with structure 
$$\Sigma = (\{+/2, 0, 1, \dots\}, \{ with a set of axioms$$

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Syntactically, looks very similar to rational arithmetic.

Note that the theory does not have multiplication.

However, one can simulate multiplication by constants in the theory.

### Example 17.1

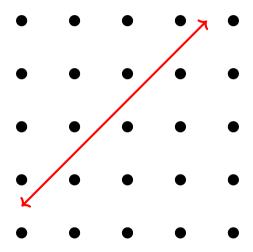
The following formulas are in the quantifier-free fragment of the theory (QF\_LIA), where x, y, and z are the integers.

$$x \ge 0 \lor y + z = 5$$

$$\rightarrow x < 300 \land x - z \neq 5$$

# Difference in reasoning

Integers are not dense. They are like a lattice in the space.

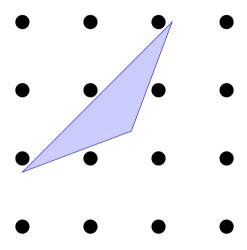


Subspaces may exist that do not contain any integer.

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# Polyhedrons without integers!

We may also have polyhedrons that do not contain integers.



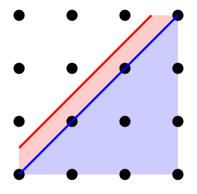
# Reasoning over integer

$$[\operatorname{Comb}] \frac{t_1 \leq 0 \quad t_2 \leq 0}{t_1 \lambda_1 + t_2 \lambda_2 - \lambda_3 \leq 0} \lambda_1, \lambda_2, \lambda_3 \geq 0$$

$$[DIV] \frac{a_1x_1 + \dots + a_nx_n \leq b}{\frac{a_1}{g}x_1 + \dots + \frac{a_n}{g}x_n \leq \left|\frac{b}{g}\right|} g = gcd(a_1, ..., a_n)$$

# Example: application of $\operatorname{D}_{\mathrm{IV}}$ rule

### Example 17.2



$$[Div] \frac{2x_1 + 2x_2 \le 1}{\frac{2}{2}x_1 + \frac{2}{2}x_2 \le \left|\frac{1}{2}\right|} 2 = \gcd(2, 2)$$

### Completeness

Are the two rules complete?

We will not do the full completeness. However, we will discuss key ideas when thinking integer.

# **Topic** 17.2

Greatest common divisor

# Euclid's method for computing gcd(x,y)

- 1. If x = 0, return y
- 2. If y = 0, return x
- 3. If x > y,  $x := x y \lfloor \frac{x}{y} \rfloor$  else  $y := y x \lfloor \frac{y}{x} \rfloor$
- 4. goto 1

#### Theorem 17.1

Euclid's method runs in polynomial time.

### Proof.

In each step one of x and y is reduced by half.

Bound on number of iterations:  $log_2(x) + log_2(y) + 1$ 

# **Topic** 17.3

Hermite normal form



# Find integer solution of equations

Consider a rational matrix A and vector b, find integral solution for x such that

$$Ax = b$$
.

# Hermite normal form (HNF)

#### Definition 17.1

A rational matrix is in Hermite normal form if it has the form  $[B\ 0]$ , where B is

- lower triangular,
- nonnegative matrix, and
- ▶ the unique maximum entry in each row is at diagonal.

#### Exercise 17.1

Are the following matrices in Hermite normal form?

$$\begin{bmatrix}
2 & 1 \\
0 & 1
\end{bmatrix}$$

$$\begin{bmatrix}
2 & 0 & 0 \\
1 & 2 & 0 \\
1 & -2 & 3
\end{bmatrix}$$

$$\begin{bmatrix}
2 & 0 & 0 & 0 \\
1 & 2 & 0 & 0 \\
1 & 1.5 & 3 & 0
\end{bmatrix}$$

$$\begin{bmatrix}
2 & 0 & 0 & 0 \\
2 & 2 & 0 & 0 \\
1 & 1 & 3 & 0
\end{bmatrix}$$

# Elementary unimodular column operations

#### Definition 17.2

The elementary unimodular column operations are

- exchanging two columns.
- $\triangleright$  multiplying a column by -1, and
- adding integral multiple of a column to another

Exercise 17.2 Can we get the following by applying a single operation on  $\begin{bmatrix} 2 & 3 & 6 \\ 2 & 1 & -3 \\ 1 & 1 & 3 \end{bmatrix}$ ?

$$\begin{bmatrix} 3 & 2 & 6 \\ 1 & 2 & -3 \\ 1 & 1 & 3 \end{bmatrix} \qquad \begin{bmatrix} 2 & 3 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & -3 \end{bmatrix} \qquad \begin{bmatrix} 0 & 3 & 6 \\ 3 & 1 & -3 \\ 0 & 1 & 3 \end{bmatrix} \qquad \begin{bmatrix} 2 & 3 & 8 \\ 2 & 1 & -1 \\ 1 & 1 & 4 \end{bmatrix}$$

Exercise 17.3

The elementary operations on A preserve integral satisfiability of Ax = b.

### There is a Hermite normal form

#### Theorem 17.2

Each rational matrix A of full row rank can be transformed into HNF by a sequence of elementary unimodular column operations.

### Proof.

Wlog A is an integer matrix. The transformation proceeds in two phases

**Phase 1:**we can transform to lower triangular matrix with positive diagonal.

Assume we have obtained  $\begin{bmatrix} B & 0 \\ C & D \end{bmatrix}$  where B is lower triangular matrix with positive diagonal.

Now we will apply the elementary operations on the columns of D to make top row zero except the first entry in the row.

### There is a Hermite normal form II

Proof. Let  $D = \begin{bmatrix} \delta_1 & \dots & \delta_k \\ \vdots & \vdots & \vdots \end{bmatrix}$ . We apply elementary operations to make the top row positive.

We maximally apply the following iteratively: If  $\delta_i \geq \delta_i > 0$ , we subtract column j in column i.

After finishing the above, exactly one column of D has positive entry at the top. We move the column to the first column.

Now we have larger lower triangular matrix with positive diagonal.

### Exercise 17.4

Why will the repeated operations terminate?

### There is a Hermite normal form III

Proof.

$$\begin{bmatrix} \beta_{11} & 0 & 0 & 0 & 0 \\ \vdots & \ddots & 0 & 0 & 0 \\ \vdots & \dots & \beta_{ii} & 0 & 0 \\ \vdots & \dots & \ddots & \ddots & 0 \\ \vdots & \dots & \dots & \beta_{nn} \end{bmatrix}$$

**Phase 2:**We can transform to  $0 \le \beta_{ij} < \beta_{ii}$ 

Now we apply column operations to bring non-diagonal entries in the range.

For each  $i \in 2..n$  and  $j \in 1..(i-1)$ , we subtract jth column by  $\lfloor \frac{\beta_{ij}}{\beta_{ii}} \rfloor$  times jth column.

The matrix is in HNF.

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## Example: HNF

Example 17.3
Consider integral matrix 
$$\begin{bmatrix} 2 & 3 & 6 \\ 2 & 1 & -3 \\ 1 & 1 & 3 \end{bmatrix}$$

Phase 1: Make top row lower triangular

Phase 1: Make middle row lower triangular

Phase 2: make non-diagonal nonnegative

# Topic 17.4

Condition of satisfiability



# Condition of satisfiability

#### Theorem 17.3

Ax = b has an integral solution x, iff

for each rational vector y, yA is integral  $\Rightarrow yb$  is an integer.

### Proof.

$$(\Rightarrow)$$

Let  $x_0$  be a solution. If yA is integral,  $yAx_0$  is an integer. Therefore, yb is an integer.

$$(\Leftarrow)$$

Assumption implies  $\forall y. \ yA = 0 \Rightarrow yb = 0. \text{(Why?)}$ 

Therefore, Ax = b has rational solutions and we can assume A is full rank.

# Condition of satisfiability II

### Proof(contd.)

Since the elementary operations do not affect the truth values of both sides, (Why?) we assume  $A = [B \ 0]$  is in HNF.

Since  $B^{-1}[B\ 0] = [I\ 0]$ , our assumption implies  $B^{-1}b$  is integral.

Since 
$$[B\ 0]\begin{bmatrix}B^{-1}b\\0\end{bmatrix}=b$$
,  $x:=\begin{bmatrix}B^{-1}b\\0\end{bmatrix}$  is a solution of  $Ax=b$ .



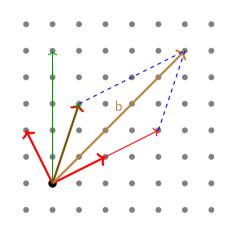
# Example: solving equation

### Example 17.4

Consider problem 
$$\begin{bmatrix} 2 & 1 & -1 \\ 1 & 3 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 5 \\ 5 \end{bmatrix}$$
.

HNF of 
$$\begin{bmatrix} 2 & 1 & -1 \\ 1 & 3 & 2 \end{bmatrix}$$
 is  $\begin{bmatrix} 1 & 0 & 0 \\ 3 & 5 & 0 \end{bmatrix}$ .

Solution of 
$$\begin{bmatrix} 1 & 0 & 0 \\ 3 & 5 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 5 \\ 5 \end{bmatrix} \text{ is } \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 5 \\ -2 \\ 0 \end{bmatrix}.$$



### Exercise 17.5

What is the solution in terms of the original  $x_1$ ,  $x_2$ , and  $x_3$ .

**Topic 17.5** 

Lattice



### Lattice

#### Definition 17.3

A set S of  $\mathbb{R}^n$  is called additive group if

- **▶** 0 ∈ *S*
- ightharpoonup if  $x \in S$ , then  $-x \in S$ , and
- ▶ if  $x, y \in S$ , then  $x + y \in S$ .

#### Definition 17.4

A group S is generated by  $a_1,\ldots,a_m$  if  $S=\{\lambda_1a_1+\cdots+\lambda_ma_m|\lambda_1,\ldots,\lambda_m\in\mathbb{Z}\}$ 

#### Definition 17.5

A group S is called lattice if it can be generated by linearly independent  $a_1, \ldots, a_m$ . The vectors are called basis of S.

### Exercise 17.6

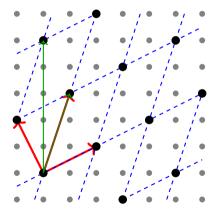
**@(1)(S)(0)** 

Prove: If A is obtained by applying elementary operations on B, the group generated by A and B are same.

# Example: HNF has same lattice

### Example 17.5

Consider our earlier matrix 
$$\begin{bmatrix} 2 & 1 & -1 \\ 1 & 3 & 2 \end{bmatrix}$$
 and its HNF  $\begin{bmatrix} 1 & 0 & 0 \\ 3 & 5 & 0 \end{bmatrix}$ 



### Exercise

#### Exercise 17.7

a) Give Hermite normal form of the following matrices.

$$\begin{bmatrix} 2 & 1 & 2 \\ -2 & -3 & 6 \end{bmatrix} \quad \begin{bmatrix} 6 & 3 & -9 \\ -3 & 8 & 4 \end{bmatrix}$$

- b) Consider the lattices generated by the columns of the above matrices in 2-D space. What fraction of the integral points are not on each of the lattices?
- c) If each of entry in the above matrices is multiplied by two, what would be the answers of (b).

# A generated group is a lattice

#### Theorem 17.4

If a group S is generated by  $a_1, ..., a_m$ , S is lattice.

# Proof.

Let  $a_1, ..., a_m$  be columns of A.

Wlog, let us suppose A is full row rank matrix.

We can convert A into HNF  $[B\ 0]$ .

Since columns of  $\boldsymbol{B}$  are linearly independent,  $\boldsymbol{S}$  is lattice.

### Exercise 17.8

Prove: If system Ax = b has an integral solution,  $B^{-1}b$  is integral.

## Hermite normal form is unique

#### Theorem 17.5

Let A and A' be rational matrices of full row rank, with HNFs  $[B\ 0]$  and  $[B'\ 0]$ , respectively. If columns of A and A' generate same lattice, iff B = B'.

### Proof.

 $(\Leftarrow)$  trivial.

$$(\Rightarrow)$$

Let lattice S be generated by columns of each A, B, A' and B'. Let  $B := (\beta_{ij})$  and  $B' := (\beta'_{ij})$ .

Consider i be the first row where B and B' are different. Let it be at ith column.

Let  $b_i$  and  $b'_i$  be the *j*th column of B and B' respectively.

# Hermite normal form is unique II

Wlog 
$$\beta_{ii} \geq \beta'_{ii}$$
.(Why?)

Therefore,  $b_j - b'_i \in S$ .  $b_j - b'_i$  has zeros in the first i - 1 entries.(Why?)

$$b_j - b_j'$$
 is integer combination of  $b_i, \ldots, b_{n\cdot(\mathsf{Why?})}$ 

Therefore, 
$$\beta_{ij} - \beta'_{ij}$$
 is integer multiple of  $\beta_{ii}$ .

Since  $0 \le \beta_{ii} < \beta_{ii}$  and  $0 \le \beta'_{ii} < \beta'_{ii}$ ,  $|\beta_{ii} - \beta'_{ii}| < \beta_{ii}$ . Contradiction.

### Exercise 17.9

Prove: a full row rank matrix A has a unique HNF.



## Exercise: Proof generation

#### Exercise 17.10

If there is no solution of Ax = b, how do we present the proof of unsatisfiability?

**Topic** 17.6

Hilbert basis



### Hilbert basis

### Definition 17.6

A finite set of vectors  $a_1, \ldots, a_m$  is Hilbert basis if each integral vector b in the cone generated by  $\{a_1, \ldots, a_m\}$  is nonnegative integral combination of  $a_1, \ldots, a_m$ .

### Example 17.6

Is the following an Hilbert basis?

$$\blacktriangleright \left\{ \begin{bmatrix} 2 \\ 2 \end{bmatrix} \right\}$$

$$\blacktriangleright \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$$

$$\blacktriangleright \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$$

$$\blacktriangleright \left\{ \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$$

### There is a Hilbert basis for each cone

#### Theorem 17.6

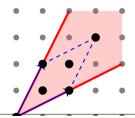
Each rational cone C is generated by an integral Hilbert basis.

### Proof.

Wlog, let  $b_1,...,b_m$  be a set of integral vectors that generate C.

Let  $a_1,...,a_t$  be all the integral vectors in  $\{\lambda_1b_1+\cdots+\lambda_mb_m|0\leq\lambda_1,\ldots,\lambda_m\leq 1\}$ .

### Example 17.7



Black dots are a.s.

### There is a Hilbert basis for each cone II

### Proof(contd.)

Claim:  $a_1, ..., a_t$  form a Hilbert basis

By definitions  $\{b_1,...b_m\} \subseteq \{a_1,...,a_t\}$ .

Consider integral vector  $c \in C$ . Therefore,  $c = \lambda_1 b_1 + \cdots + \lambda_m b_m$  for  $\lambda_i \geq 0$ .

$$c = (\lfloor \lambda_1 \rfloor b_1 + \dots + \lfloor \lambda_m \rfloor b_m) + \underbrace{((\lambda_1 - \lfloor \lambda_1 \rfloor) b_1 + \dots + (\lambda_m - \lfloor \lambda_m \rfloor) b_m)}_{\in \{a_1, \dots, a_t\} \text{ (Why?)}}$$

c is nonnegative integral combination of  $a_1, ..., a_t$ .

#### Exercise 17.11

Why the underbraced vector is integral?

# Uniqueness of Hilbert basis

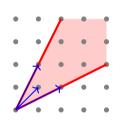
#### Theorem 17.7

Let C be a rational cone. If C has zero dimensional vertices, there is a unique minimal Hilbert basis for C.

### Proof.

Let H be a set of integral vectors defined as follows.  $a \in H$  iff

- ightharpoonup  $a \in C$ .
- ightharpoonup  $a \neq 0$ , and
- ightharpoonup a is not sum of any of the other two nonzero integral vectors in C.



#### Exercise 17.12

Show: *H* is subset of any Hilbert basis generating *C*.

# Uniqueness of Hilbert basis II

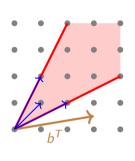
### Proof(contd.)

Claim: H is a Hilbert basis generating C.

Choose b such that bx > 0 for each  $x \in C$ . (Why exists?)

Choose  $c \in C$  such that c is not a nonnegative integral combination of H.

Let *bc* be smallest.



Since  $c \notin H$ ,  $c_1 + c_2 = c$  for some nonzero integral  $c_1, c_2 \in C$ .

Therefore,  $bc_1 < bc$  and  $bc_2 < bc$ .

Therefore,  $c_1$  and  $c_2$  are nonnegative integral combinations of H.

Therefore, c is nonnegative integral combination of H. Contradiction.

### Exercise 17.13

a. Why smallest bc? b. Show if C does not have zero dimensional vertices, H is not unique.

**Topic 17.7** 

**Problems** 



#### Finite infinite

#### Exercise 17.14

Consider formula F with single free variable in presburger arithmetic. Let  $S = \{k | \mathcal{T}_{\mathbb{Z}} \models F(k)\}$ .

- ▶ find a formula such that  $S \cap \mathbb{Z}^+$  is finite.
- ightharpoonup find a formula such that  $\mathbb{Z}^+ S$  is finite.

### **Topic 17.8**

Extra slides : Integer hull

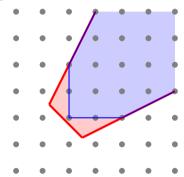


# Integer hull

Let P be a polyhedron.

#### Definition 17.7

Let  $P_I$  be the convex hull of integers in P.



Exercise 17.15

Show: for a polyhedral cone C,  $C = C_I$ . O(1) CS 433 Automated Reasoning 2025

### $P_I$ is a polyhedron

#### Theorem 17.8

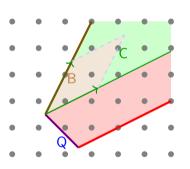
Let P be a rational polyhedron.  $P_I$  is also a polyhedron.

#### Proof.

Let Q + C, where Q is a polytope and C is the characteristic cone.

Let C be generated by integral vectors  $a_1, .... a_s$ . Let

$$B := \{\lambda_1 a_1 + \dots + \lambda_s a_s | 0 \le \lambda_1, \dots, \lambda_s \le 1\}.$$



### Exercise 17.16

Draw Q + B.

### $P_I$ is a polyhedron

#### Proof(contd.)

**Claim:** 
$$P_{I} = (Q + B)_{I} + C$$

Clearly  $(Q + B)_I \subseteq P_I$ . Therefore,  $(Q + B)_I + C \subseteq P_I + C \subseteq P_I + C_I \subseteq P_I$ .

Let integral vector  $p \in P$  such that p = q + c for some  $q \in Q$  and  $c \in C$ .

Let 
$$c = \lambda_1 a_1 + \cdots + \lambda_s a_s$$
 for  $\lambda_i \geq 0$ .

Let 
$$c' = |\lambda_1| a_1 + \cdots + |\lambda_s| a_s \in C$$
.

Therefore  $(c - c') \in B$  and q + (c - c') is integral.

$$q + (c - c') \in (Q + B)_I$$
. Hence,  $P_I \subseteq (Q + B)_I + C$ .

 $P_I$  is polyhedron and can be represented by some  $Ax \leq b$ .

### **Topic 17.9**

Extra slides: Total duality integrality



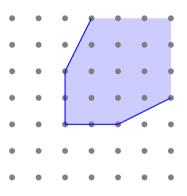
### Integral

#### Definition 17.8

A polyhedron P is integral if all faces of P have integral vectors.

Faces include any thing that is facing exterior

- Vertices (minimal face)
- Edges
- Many dimensional surfaces



### Some properties of faces

- ▶ Faces are obtained by converting one or more inequalities to equality.
- Faces are polyhedron themselves.
- ► Faces have subfaces
- ▶ There are minimal dimensional faces.
- All minimal dimensional faces
  - must have same dimension.
  - are affine spaces, and
  - are translation of each other.

# Condition for being integral

The hyperplanes that are "touching" P

Theorem 17.9

A rational polyhedron P is integral, iff each supporting hyperplane of P has integral vectors.

# Proof

<u>@(1)(S)(0)</u>

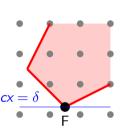
 $(\Rightarrow)$  trivial.

$$(\Leftarrow)$$
 Assume ¬LHS. We prove ¬RHS.

Let  $P = \{x | Ax \le b\}$  for integral A and b. and

of 
$$Ax < b$$
, without integral vectors.

 $F = \{x | A'x = b'\}$  be a minimal face of P, where  $A'x \le b'$  is a subsystem



Due to theorem 17.3, there is a y such that yA' is integral and yb' is not.

We add positive integers to components of v to make it positive.

Still yA' is integral and yb' is not. Let c = yA' and  $\delta = yb'$ .

Clearly,  $cx = \delta$  has no integral vectors.

Since 
$$F \subset cx = \delta$$
 and  $P \subseteq cx < \delta_{(Why?)}$ ,  $cx = \delta$  is a supporting hyperplane.

### Total duality integrality(TDI)

#### Definition 17.9

A rational system Ax < b is totally dual integral if the minimum in the LP-duality equation

$$\max\{cx|Ax\leq b\}=\min\{yb|y\geq 0 \land yA=c\}$$

has an integral optimum y for each integral c for which the minimum is finite.

#### Example 17.8

max reaches optima at the corner of the red polyhedron. if c is in the green cone.

TDI says that integral c is nonnegative integral combination of  $a_1$  and  $a_2$ .

Therefore,  $a_1$  and  $a_2$  form an Hilbert basis.

#### Exercise 17.17

Prove: If Ax < b is TDI, and  $Ax < b \Rightarrow ax < \beta$ ,  $Ax < b \land ax < \beta$  is a TDI. CS 433 Automated Reasoning 2025

### TDI has integral optimum solutions

#### Theorem 17.10

If  $Ax \le b$  is TDI and b is integral,  $\{x | Ax \le b\}$  is integral.

#### Proof.

Let c be an integral row vector such that  $max\{cx|Ax \leq b\}$  is finite.

Since  $Ax \le b$  is TDI and b is integral,  $min\{yb|y \ge 0 \land yA = c\}$  is integer. (Why?)  $\delta = max\{cx|Ax \le b\}$  is integer.

Let  $H = \{x | cx = \delta\}$ . H is a supporting hyperplane.

Let  $H = \{x | cx = \delta\}$ . H is a supporting hyperplane. Wlog, we assume gcd(c) = 1. Therefore,  $cx = \delta$  has integer solutions.

Due to theorem 17.9,  $\{x|Ax \le b\}$  is integral.

#### Exercise 17.18

Let  $Ax \le b$  be TDI. If b and c are integral, and  $max\{cx|Ax \le b\}$  is finite, the max achieves optima at integral x.

### A face of TDI-system is TDI-system

#### Theorem 17.11

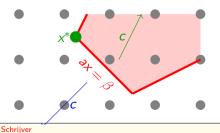
Let  $Ax \leq b \land ax \leq \beta$  be TDI. Then,  $Ax \leq b \land ax = \beta$  is also TDI.

#### Proof.

Let c be an integral vector, with

$$\max\{cx|Ax \leq b \land ax = \beta\} = \min\{yb + (\lambda - \mu)\beta|y, \lambda, \mu \geq 0 \land yA + (\lambda - \mu)a = c\}.$$

Let  $x^*$ ,  $y^*$ ,  $\lambda^*$  and  $\mu^*$  attain the optima.



Two possibilities:

1. 
$$\lambda * - \mu * > 0$$

2. 
$$\lambda * -\mu * < 0$$

The second case can be handled by rotating c. No need of cases.

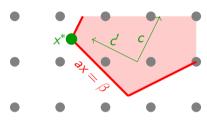
Commentary: Theorem 22.2 in Schrijver

# A face of TDI-system is TDI-system II

#### Proof(contd.)

Let c' = c + Na for some integer N such that  $N \ge \mu *$  and Na is integral.

Removes negative a component from c



Then optima  $max\{c'x|Ax \le b \land ax \le \beta\} = min\{yb + \lambda\beta|y, \lambda \ge 0 \land yA + \lambda a = c'\}$  is finite because

- $\triangleright$   $x := x^*$  satisfies  $Ax < b \land ax < \beta$
- $\triangleright$   $y := y^*$ , and  $\lambda := \lambda^* + N \mu^*$  satisfies  $y, \lambda \ge 0 \land vA + \lambda a = c'$ .

### A face of TDI-system is TDI-system III

#### Proof(contd.)

Since  $Ax \leq b \land ax \leq \beta$  is TDI, the minimum in the above is attained by integral solution, say  $y_0, \lambda_0$ . Therefore,  $y_0b + \lambda_0\beta \leq y^*b + (\lambda^* + N - \mu^*)\beta$ .

**Claim:**  $y = y_0, \lambda = \lambda_0, \ \mu = N$  also attains minimum in  $\max\{cx|Ax \leq b \land ax = \beta\} = \min\{yb + (\lambda - \mu)\beta|y, \lambda, \mu \geq 0 \land yA + (\lambda - \mu)a = c\}.$ 

Since  $y_0b + \lambda_0\beta \le y^*b + (\lambda^* + N - \mu^*)\beta$ , after moving  $N\beta$  rhs to lhs

$$y_0b + (\lambda_0 - N)\beta \le y^*b + (\lambda^* - \mu^*)\beta$$

Since  $y = y^*, \lambda = \lambda^*, \mu = \mu^*$  attains the minimum, therefore  $y = y_0, \lambda = \lambda_0, \mu = N$  attains the minimum.

#### Hilbert basis and TDI

An inequality  $ax \le \delta$  of  $Ax \le b$  is active in F if  $F \Rightarrow ax = \delta$ 

#### Theorem 17.12

Let  $Ax \le b$  be TDI iff, for each face F of  $\{x | Ax \le b\}$ , the inequalities of  $Ax \le b$  that are active in F form a Hilbert basis.

## Proof.

$$(\Rightarrow)$$

<u>@(1)(S)(0)</u>

Let  $a_1 \leq \delta_1, \ldots, a_t \leq \delta_t$  be active on F.

Choose an integral vector c in the cone of  $\{a_1,..,a_t\}$ .

The maximum attained in the following

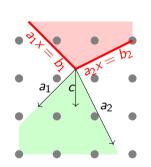
$$\max\{cx|Ax\leq b\}=\min\{yb|y\geq 0 \land yA=c\}$$



Since  $Ax \le b$  is TDI, the minimum is achieved by integral y.

Due to complementary slackness, the components of y for non-active rows is 0.

Hence c is nonnegative integral combination of  $a_1, ... a_t$ .



#### Hilbert basis and TDI

### Proof(contd.)

$$(\Leftarrow)$$

Let c be an integral row vector for which the following is finite.

$$\max\{cx|Ax \le b\} = \min\{yb|y \ge 0 \land yA = c\}$$

Consider the largest F such that all x in F attain the maximum. (Why?)

Let  $a_1 \leq \delta_1, \ldots, a_t \leq \delta_t$  be active on F.

c must be in the cone of  $a_1, ..., a_t$ .

Since they form an Hilbert basis  $c = \lambda_1 a_1 + \cdots + \lambda_t a_t$  for  $\lambda_1, ..., \lambda_t \geq 0$ .

By zero padding, we can construct integral y such that yA = c and yb = yAx = cx for each x in F.

Therefore, y achives the minimum. Therefore,  $Ax \le b$  is TDI.

#### Exercise 17.19

Why we need largest face F?

# There is a TDI-system for each polyhedron

#### Theorem 17.13

For each rational polyhedron P, there is a TDI-system  $Ax \leq b$  with A integral matrix and rational vector b such that  $P = \{x | Ax \leq b\}$ .

### Proof.

Consider a minimal face F of P. Let  $C_F$  be the cone of vectors c such that  $max\{cx|x \in P\}$  is attained by  $x \in F$ 

Let  $a_1, \ldots, a_t$  be integral Hilbert basis of  $C_F$ . Let  $x_0 \in F$ . Therefore, for  $1 \le i \le t$ ,  $P \Rightarrow a_i x \le a_i x_0$ .

Let  $A_F = \{a_1x \leq a_1x_0, ..., a_tx \leq a_tx_0\}.$ 

Let  $Ax \le b$  be union of inequalities  $A_F$  for each minimal F.  $Ax \le b$  defines  $P_{(Why?)}$  and is TDI due to theorem 17.12.

Exercise 17.20

a. Why we need minimal face F?

### Topic 17.10

Extra slides: cutting planes

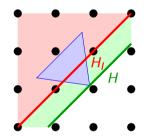


## Cutting half spaces

Let  $H = \{x | cx \le \beta\}$  be half space, where gcd(c) = 1.

#### Definition 17.10

For a polyhedron P. Let  $P' = \bigcap_{P \Longrightarrow H} H_I$ 



Clearly, 
$$P \supseteq P' \supseteq P'' \dots \supseteq P^t \supseteq \dots \supseteq P_I$$
.

We will show that the chain will saturate in finite steps.

#### Exercise 17.21

Give a *P* such that the saturation takes take multiple steps.

### TDI-systems quickly finds P'

#### Theorem 17.14

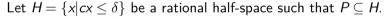
Let  $Ax \le b$  be TDI and A is integral. Let  $P = \{x | Ax \le b\}$ .  $P' = \{x | Ax \le \lfloor b \rfloor\}$ 

If 
$$P = \emptyset$$
, trivial.(Why?)

Let us assume 
$$P \neq \emptyset$$
.

Clearly, 
$$P' \subseteq \{x | Ax \le \lfloor b \rfloor\}$$
.(Why?)

Claim: 
$$P' \supseteq \{x | Ax \leq \lfloor b \rfloor \}$$



Wlog we assume 
$$gcd(c) = 1$$
. Then,  $H_I = \{x | cx \le \lfloor \delta \rfloor \}$ . We have  $\delta > \max\{cx | Ax \le b\} = \min\{vb | v > 0 \land vA = c\}$ .

Since 
$$Ax < b$$
 is TDI, the above min is attained by an integral  $y_0$ .

Chose 
$$x$$
 such that  $Ax \leq \lfloor b \rfloor$ . Therefore,  $cx = y_0 Ax \leq y_0 \lfloor b \rfloor \leq \lfloor y_0 b \rfloor \leq \lfloor \delta \rfloor$ .

So 
$$\{x|Ax \leq \lfloor b \rfloor\} \subseteq H_I$$
.  
As this is true for each rational half-space, the claim holds.

### P' carries over to faces

#### Theorem 17.15

Let F be face of a rational polyhedron P. Then  $F' = P' \cap F$ 

### Proof.

Let  $P = \{x | Ax \le b\}$ , with A integral and  $Ax \le b$  TDI.

Let  $F = \{x | Ax \le b \land ax = \beta\}$  for integral a and  $\beta$  and  $P \Rightarrow ax \le \beta$ .(Why?)

Since  $Ax \le b \land ax \le \beta$  is  $TDI_{(Why?)}$ ,  $Ax \le b \land ax = \beta$  is TDI.

Therefore,

$$P' \cap F = \{x | Ax \leq \lfloor b \rfloor \land ax = \beta\} = \{x | Ax \leq \lfloor b \rfloor \land ax \leq \lfloor \beta \rfloor \land ax \geq \lfloor \beta \rfloor\} = F'$$



$$P^t = P_I$$

#### Theorem 17 16

For each rational polyhedron P, there exists a number t such that  $P^t = P_I$ .

### Proof.

Hence.

We apply induction over dimension d of P.

The case  $P = \emptyset$  and d = 0 are trivial.

case: Let us suppose affine. Hull(P) has no integers.

$$P' \subset \{x | cx < |\delta| \land cx > \lceil \delta \rceil\} = \emptyset.$$

Therefore, there is integral vector c and non-integer  $\delta$  such that *affine.Hull(P)*  $\subseteq \{x|cx = \delta\}$ .

$$F \subseteq \{x \mid cx \leq \lfloor b \rfloor \land cx \geq \lfloor b \rfloor\} = \emptyset$$

Commentary: Theorem 23.2 in Schrijver

Therefore,  $P' = P_I$ .

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$$P^t = P_I$$
 II

### Proof(contd).

**case:** Let us suppose *affine*. *Hull*(*P*) has integers.

If affine.Hull(P) is not full dimensional, we project it to lower dimensions using Hermite Normal form and apply induction hypothesis.(How?)

, ,

Therefore, we may assume affine. Hull(P) is full dimensional.

Due to theorem ??, we know  $P_I = \{x | Ax \le b'\}$  and  $P = \{x | Ax \le b\}$ .

Let  $ax \leq \beta'$  in  $Ax \leq b'$ , and there is a corresponding  $ax \leq \beta$  in  $Ax \leq b$ .

Let 
$$H = \{x | ax \leq \beta'\}$$
.



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$$P^t = P_I$$
 III

### Proof(contd.)

**Claim:**  $P^s \subseteq H$  for some s

Let us suppose for each s, we have  $P^s \nsubseteq H$ .

Therefore, there is an integer  $\beta''$  and an integer r such that  $\beta' < \beta'' \le \lfloor \beta \rfloor$ .

$$\{x|ax \leq \beta'' - 1\} \not\supseteq P^s \subseteq \{x|ax \leq \beta''\}$$
 for each  $s \geq r$ 

Let 
$$F = P^r \cap \{x | ax = \beta''\}$$
.

Due to dim(F) < dim(P), F does not contain any integer(Why?), and induction hypothesis,  $F^u = \emptyset$ 

for some *u*. Therefore.

$$\emptyset = F^{u} = P^{(r+u)} \cap F = P^{(r+u)} \cap \{x | ax = \beta''\}$$

### Cutting plane proofs

Let  $Ax \le b$  be a system of inequalities, and let  $cx \le \delta$  be an inequality.

#### Definition 17.11

A sequence of inequalities  $c_1x \leq \delta_1, \ldots, c_mx \leq \delta_m$  is a cutting plane proof of  $cx \leq \delta$  from  $Ax \leq b$  if

- $ightharpoonup c_m = c, \ \delta_m = \delta,$
- $ightharpoonup c_1, ..., c_m$  are integral,
- $\triangleright$   $c_i = \Lambda A + \lambda_1 c_1 + \cdots + \lambda_{i-1} c_{i-1}$ , and
- $\delta_i > |\Lambda \delta + \lambda_1 \delta_1 + \dots + \lambda_{i-1} \delta_{i-1}|$ , where  $\Lambda, \lambda_1, \dots, \lambda_{i-1} > 0$ .

*m* is the length of the proof.

# Cutting plane proofs always exist

#### Theorem 17.17

Let  $P = \{x | Ax \le b\}$  be a nonempty rational polyhedron.

- ▶ If  $P_I \neq \emptyset$  and  $P_I \Rightarrow cx \leq \delta$ , then there is a cutting plane proof of  $cx \leq \delta$  from  $Ax \leq b$ .
- ▶ If  $P_I = \emptyset$ , then there is a cutting plane proof of  $0 \le -1$  from  $Ax \le b$ .

#### Proof.

Let t be such that  $P^t = P_I$ .

For each  $i \ge 1$ , there is a system  $A_i \times \le b_i$  that defines  $P^i$  such that

- ▶ For each  $\alpha x \leq \beta$  in  $A_i x \leq b_i$ , there is  $yA_{i-1} = \alpha$  and  $\beta = \lfloor yb_{i-1} \rfloor$ .
- ►  $A_0 = A$  and  $b_0 = b$ .

. . .

## Cutting plane proofs always exist

#### Proof(contd.)

If  $P_l \neq \emptyset$  and  $P_l \Rightarrow cx \leq \delta$ , due to the Farkas lemma (affine form)  $yA_t = c$  and  $\delta \geq yb_t$ . Therefore, the following is the cutting proof of  $cx \leq b$  from  $Ax \leq b$ ,

$$A_1x \leq b_1, \ldots, A_tx \leq b_t, cx \leq b.$$

If  $P_I = \emptyset$ , then  $yA_t = 0$  and  $yb_t = -1$  for some  $y \ge 0$ .

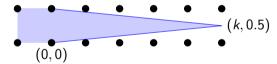
Therefore, the following is the cutting proof of  $0 \le -1$  from  $Ax \le b$ .

$$A_1x \le b_1, \ldots, A_tx \le b_t, 0x \le -1.$$

### Length of cutting plane proofs

The number of cutting planes depends on the size of numbers!

The following will trigger at least k cuts.



Topic 17.11

**Problems** 



## Find a TDI-system

#### Exercise 17.22

Write a program that takes an integral system  $Ax \le b$  as input, and finds a TDI-system that also defines polyhedron  $\{x | Ax \le b\}$ .

- ► All groups will implement the program in C++
- ▶ Please feel free to consult any literature to implement the procedure efficiently but refrain from using high level libraries.
- Each group will submit 30 random inputs in the following format
  - ▲ 2 3 First row defines the size of matrix A [row\_size] [column\_size]
  - 1 3 4
  - Afterwards rows of integral A are written one after another
    - Afterwards b indicates the start of vector b.
      - Afterwards b indicates the start of vector b.
      - Afterwards entries of b are listed.

#### **Evaluation:**

- We will pool submitted inputs and run all the submissions on the inputs
- ► The marks will be decided on the correctness of the submissions, their relative performances, and size of the found TDI-systems

# End of Lecture 17

