

## Lecture 12: The Simplex Algorithm III

Lecturer: *Sundar Vishwanathan*  
COMPUTER SCIENCE & ENGINEERING

Scribe: *Prekshu Ajmera*  
INDIAN INSTITUTE OF TECHNOLOGY, BOMBAY

Let  $x_0$  be the current extreme point. From previous lectures we already know that:

- The directions of the neighboring extreme points of  $x_0$  are given by the columns of the matrix  $-A'^{-1}$
- We can write  $Ax_0 \leq b$  as

$$A'x_0 = b' \tag{1}$$

$$A''x_0 < b'' \tag{2}$$

where  $A'$  consists of  $n$  linearly independent rows(hyperplanes).

In this lecture we will give the stopping condition of the Simplex algorithm and prove the correctness of the algorithm.

### 1 Stopping Condition

*If all the neighboring extreme points of  $x_0$  have a cost  $\leq$  the cost of  $x_0$  then  $x_0$  is optimal and the algorithm stops at  $x_0$ .*

**Proof** First of all note that this is *not* the same as saying that  $x_0$  is local maximum and hence by a previously proved theorem, it is also a global maximum. This is so because we just know that the cost at  $x_0$  is maximum as compared to its *neighbours* - not compared to a small enough *neighbourhood* around it.

#### First Approach

Let us consider a small neighborhood  $N$  of  $x_0$ . Also, assume that we can write any point  $p \in N$  as a convex combination of all the neighboring extreme points of  $x_0$  i.e.

$$p = \sum_{i=0}^n \lambda_i x_i \quad ; \quad 0 \leq \lambda_i \leq 1, \Sigma \lambda_i = 1 \tag{3}$$

This is similar to taking a weighted average with  $\lambda_i$ s be the probabilities. Now we know that  $\forall i \ c^T x_i \leq c^T x_0$ . Hence,

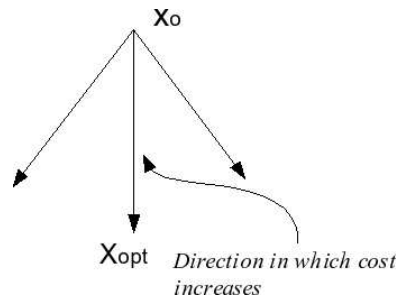
$$c^T p = c^T \left( \sum_{i=0}^n \lambda_i x_i \right) = \sum_{i=0}^n \lambda_i c^T x_i \leq c^T x_0 \left( \sum_{i=0}^n \lambda_i \right) = c^T x_0 \quad (4)$$

Thus,  $x_0$  is a local maximum and consequently a global maximum.

**To be shown :** (i)  $p = \sum \lambda_i x_i$  (ii) Starting criteria

## Second Approach

Assume that  $x_0$  is not an optimal point and there is some other point  $x_{opt}$  which is optimal. Thus, the cost increases along  $x_{opt} - x_0$ .



Now,  $x_0$  is an extreme point

$\Rightarrow A'$  has full rank

$\Rightarrow -A'^{-1}$  has full rank

$\Rightarrow n$  columns form a basis of the space

$\Rightarrow$  vector  $x_{opt} - x_0$  can be written as a linear combination of these columns. Hence,

$$x_{opt} - x_0 = \sum_i \beta_i ((-A'^{-1})^i) \quad (5)$$

Pre-multiplying with  $A'$  in the above equation, we get

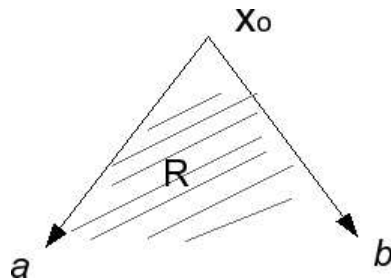
$$A' x_{opt} - A' x_0 = \sum_i \beta_i A' ((-A'^{-1})^i) \quad (6)$$

What can we say about  $\beta_i$  ?

Lets look at the following figure:

Any point in the region  $R$  can be written as  $a\beta_1 + b\beta_2$ . For feasibility,  $\beta_1$  and  $\beta_2$  have to be positive, otherwise we will be out of the region  $R$  ( $Ax \leq b$ ). Thus, intuitively it should be clear that  $\beta_i \geq 0$ .

More formal proof for  $\beta_i \geq 0$  will be given in the next lecture.



Now pre-multiplying with  $c^T$  in (5), we get

$$c^T x_{opt} - c^T x_0 = \sum_i \beta_i c^T ((-A'^{-1})^i) \quad (7)$$

Now,  $(-A'^{-1})^i = x_i - x_0$  where  $x_i$ 's are the neighboring extreme points of  $x_0$ . Since we have stopped at  $x_0$ ,  $\forall x_i$   $c^T x_i - c^T x_0 \leq 0$ . Also,  $\beta_j \geq 0$ . This implies that the R.H.S. of the above equation is  $\leq 0$ . Hence,

$$c^T x_{opt} - c^T x_0 \leq 0 \quad (8)$$

Thus, we find that cost decreases along  $x_{opt} - x_0$  which is a contradiction. So, our assumption was wrong and  $x_0$  is indeed an optimal point. Hence proved !