

Lecture 22: Using LP techniques to design algorithms for combinatorial problems

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1 Integer Linear Programs

An *Integer Linear Program* is a linear program where the variables are constrained to take integer values only. An ILP is formulated as

$$\begin{aligned} \max \quad & c^T x \\ & Ax \leq b \\ & x_i \text{ is integral } \forall i. \end{aligned}$$

2 Recap of primal, dual and complementary slackness

Recapitulate that for an LP

$$\begin{aligned} \max \quad & c^T x \\ & Ax \leq b \end{aligned}$$

the dual is

$$\begin{aligned} \min \quad & y^T b \\ & A^T y = c \end{aligned}$$

Complementary slackness implies that the optimums of the primal and dual coincide i.e. $c^T x_o = (y_o)^T b$ and where $y_{oi} > 0$ in the dual $A_i x_o = b_i$ in the primal and vice versa.

3 Formulation Of Minimum Spanning Tree as an ILP

A *spanning tree* is a subgraph of a connected, undirectional graph that connects all vertices and is a tree. The minimum spanning tree is a spanning tree with minimum cost or sum of weight of edges part of the tree. The corresponding ILP may be formulated taking as variables x_e , one for each edge where a value of 1 for x_e indicates that the edge is part of the tree and value of zero indicates that the edge is not part of the spanning tree. The cost then is $\sum x_e c_e$ where c_e is the weight of the edge. The ILP formulation then is

$$\min c^T x = \sum x_e c_e$$

Constraints :

$$\begin{aligned} & \forall \text{ partitions } \pi \\ & \sum_{e \text{ crosses } \pi} x_e \geq \#(\pi) - 1 \\ & 0 \leq x_e \leq 1 \\ & x_e \text{ is integral} \end{aligned}$$

where $\#(\pi)$ is the number of parts in the partition π . The first constraint basically represents that the graph is connected.

Now we drop the integral constraint and write the dual of the resulting LP. The dual is

$$\begin{aligned} & \max \left(\sum_{\pi} y_{\pi} (\#(\pi) - 1) \right) \\ & \forall e : \sum_{e \text{ crosses } \pi} y_{\pi} \leq c_e \\ & y_{\pi} \geq 0 \end{aligned}$$