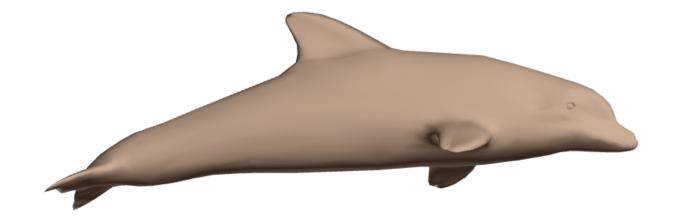


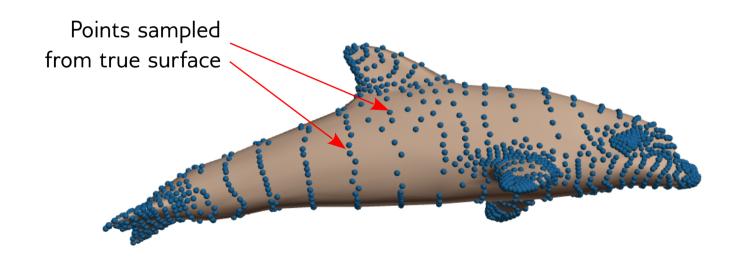
### Polygon Meshes

Siddhartha Chaudhuri, CS475/675, Fall 2016

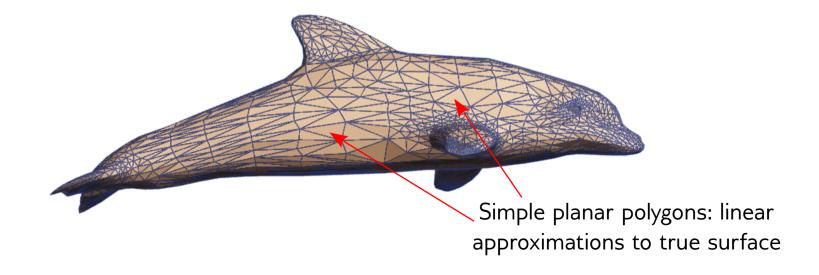
- Like a point cloud, it is a discrete sampling of a surface
- ... but, it adds simple polygons (no holes or self-intersections) as linear (flat) approximations of local regions of the actual underlying surface



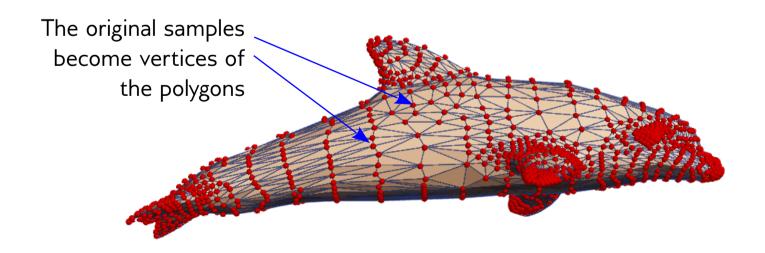
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- Like point clouds, meshes can have different resolutions

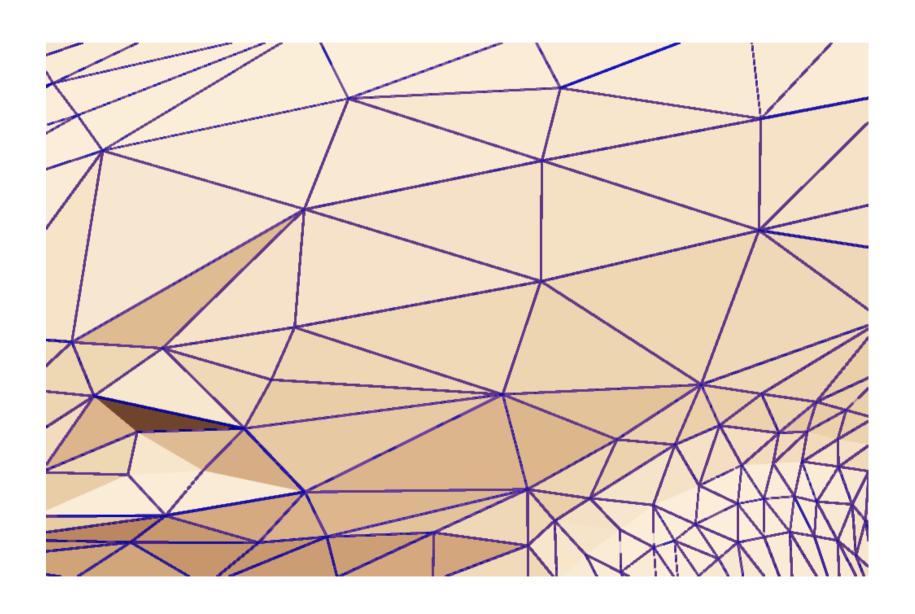
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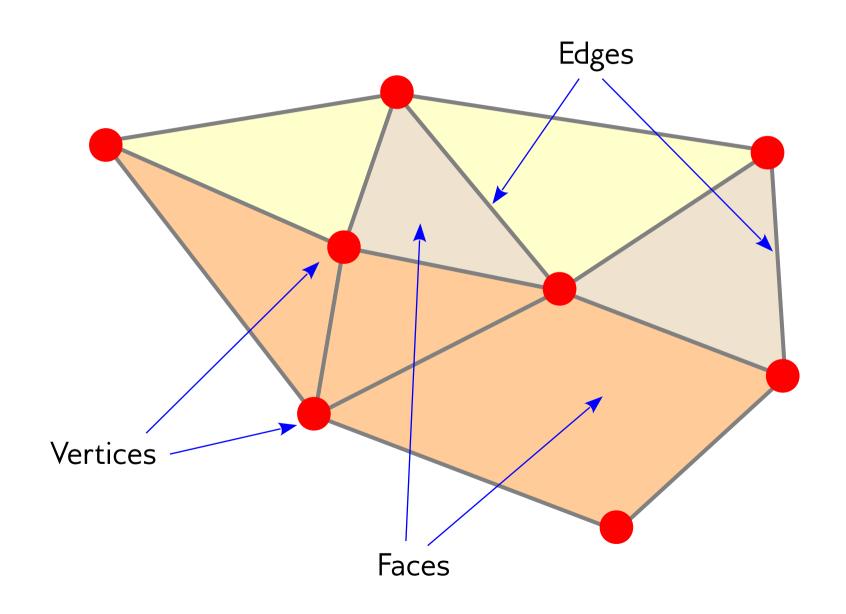
• ... at different places ("adaptive meshing")

Leif Kobbelt

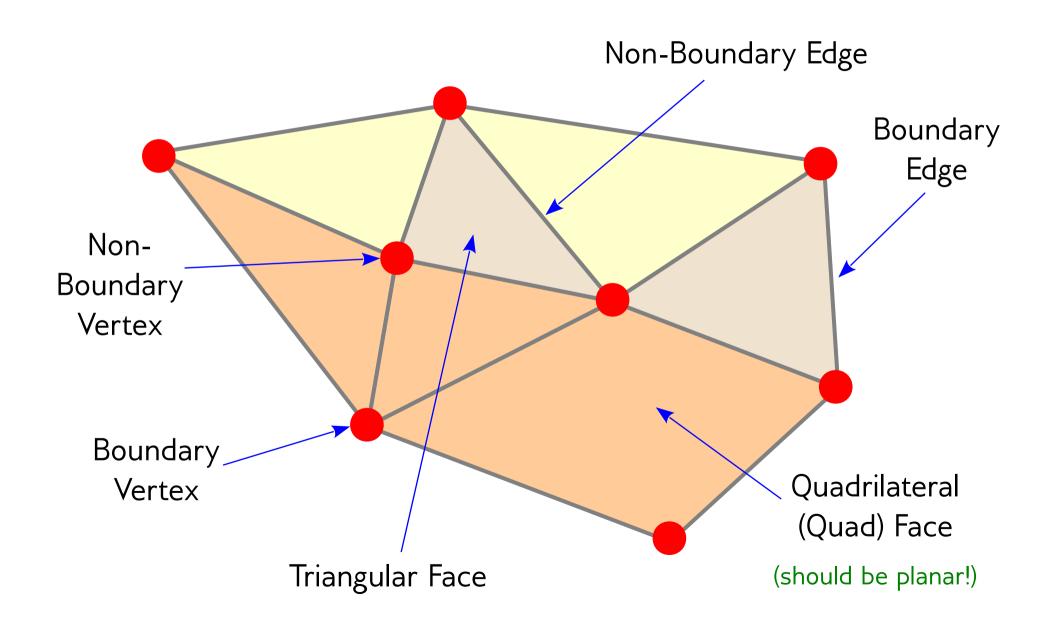
### Elements of a mesh



#### Elements of a mesh

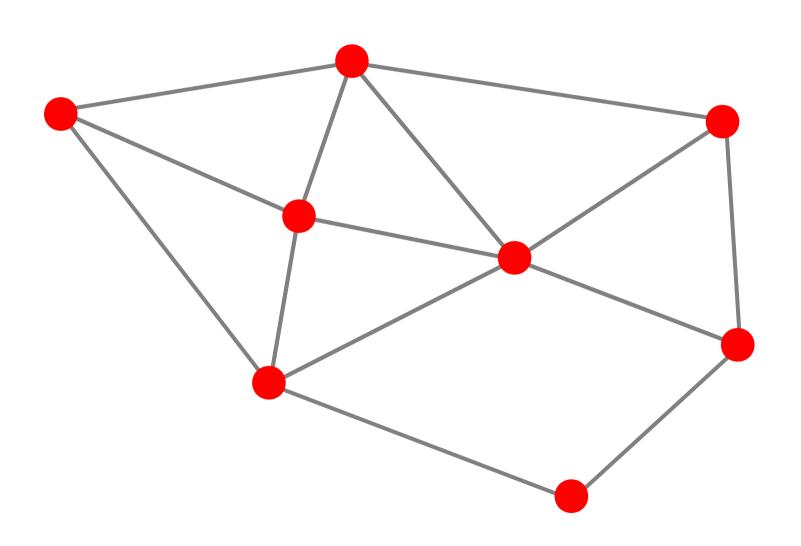


#### Elements of a mesh

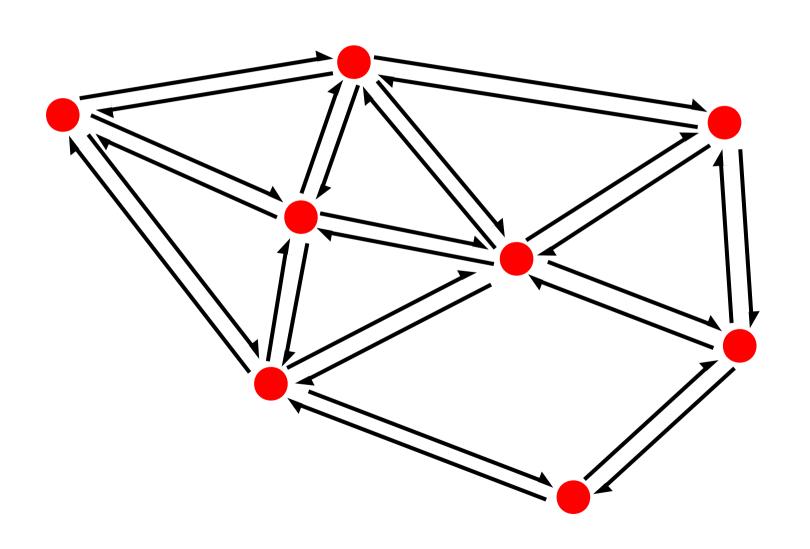


## A mesh is a graph

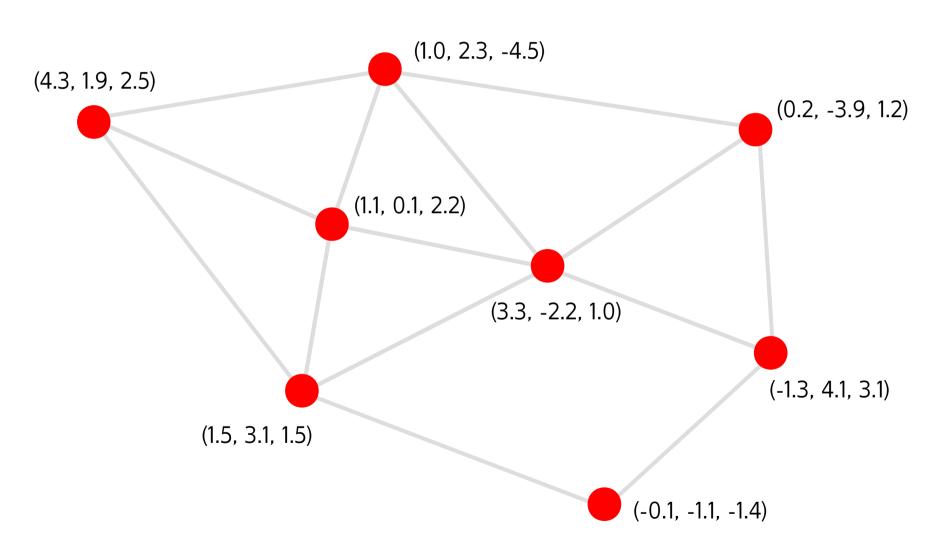
This cannot be stressed strongly enough!



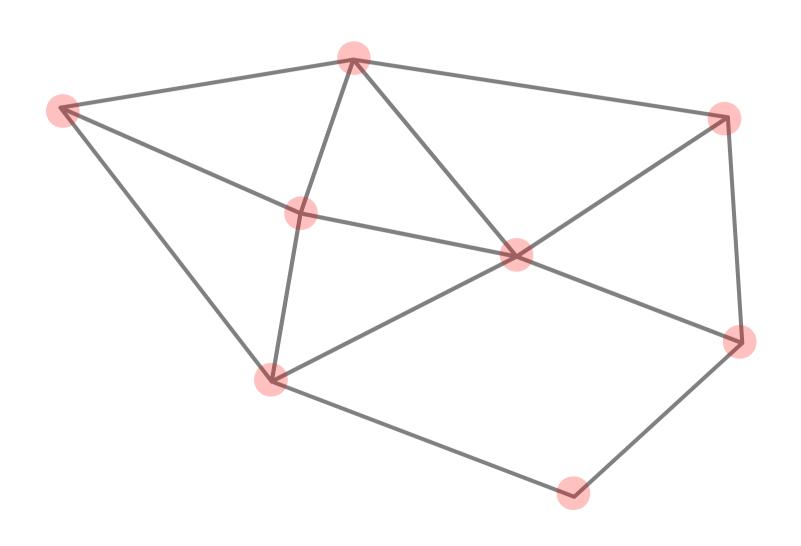
## A mesh is an undirected graph



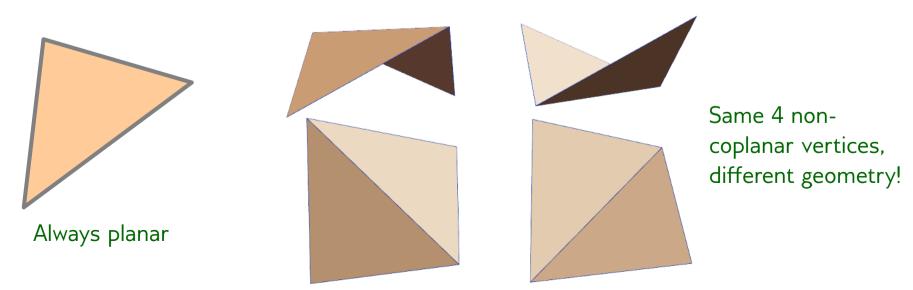
# The vertex positions capture the geometry of the surface



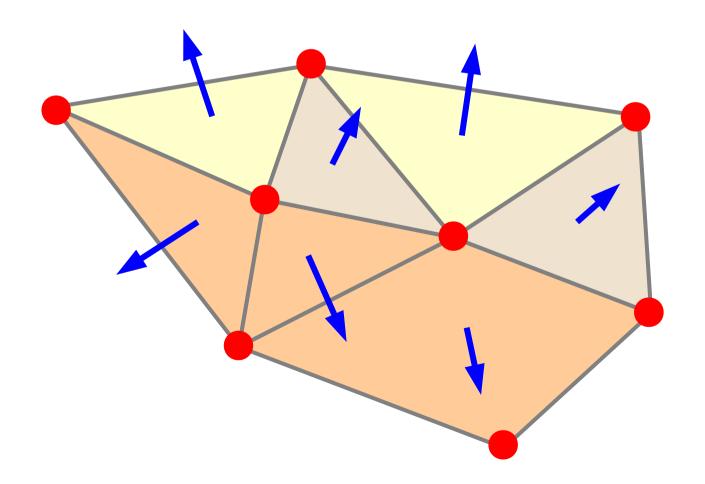
# The mesh connectivity captures the topology of the surface



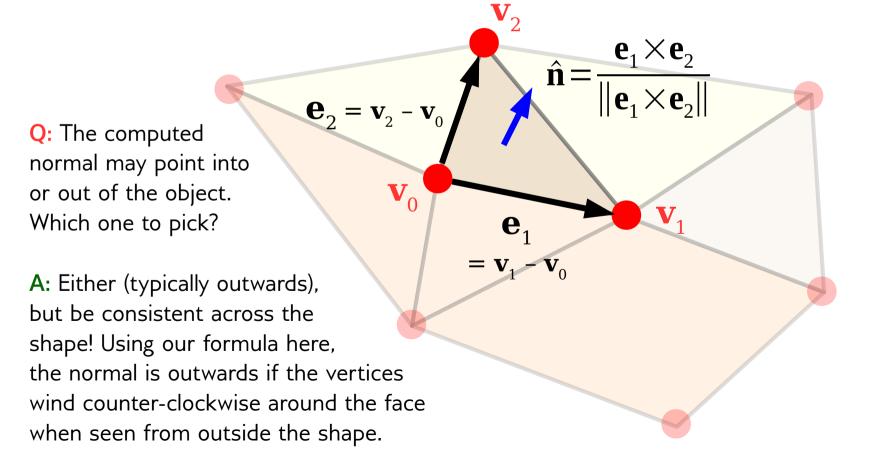
- Each polygon is (assumed to be) planar
  - Triangular faces are always planar
  - Quads and higher degree faces need not be
    - Ambiguity revealed by triangulation
  - Many mesh formats allow non-planar faces, but most algorithms assume planar faces. Caveat emptor.



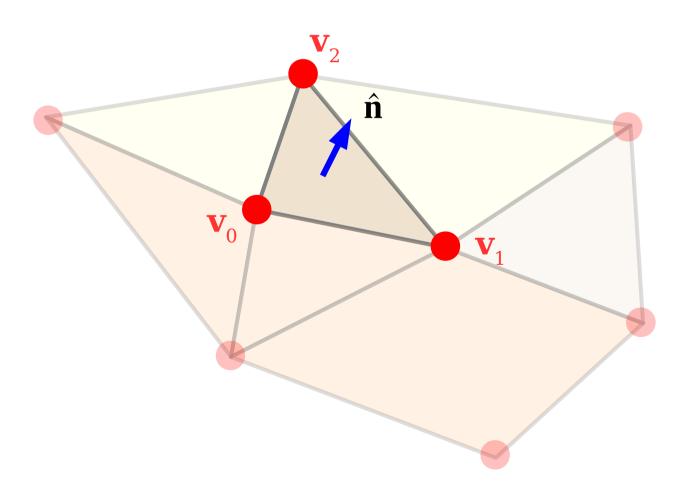
The plane of each polygon has an associated normal vector



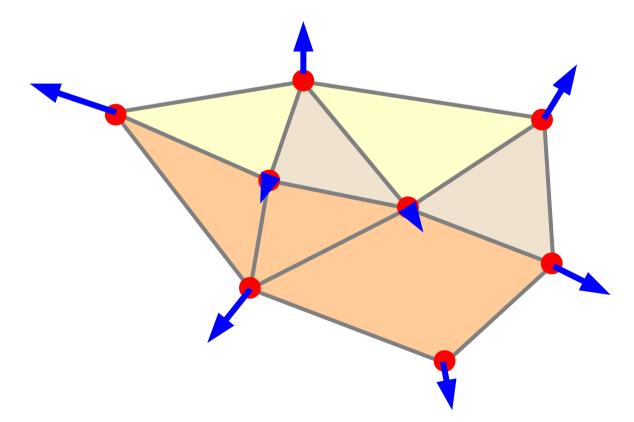
The plane of each polygon has an associated normal vector



• The plane of each polygon has an associated plane equation:  $\hat{\mathbf{n}} \cdot (\mathbf{p} - \mathbf{v}_0) = 0$ 

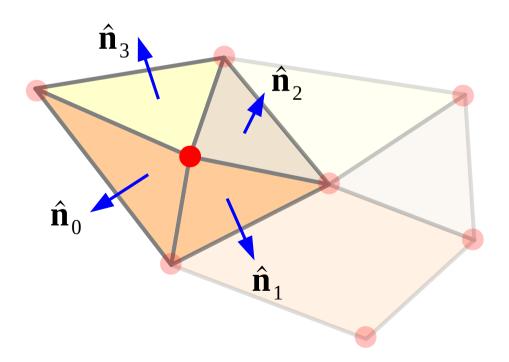


- We can also associate vertices with normals
  - Sometimes they come with the mesh (e.g. if they were estimated when the mesh was constructed from a point cloud)
  - Sometimes we have to estimate them



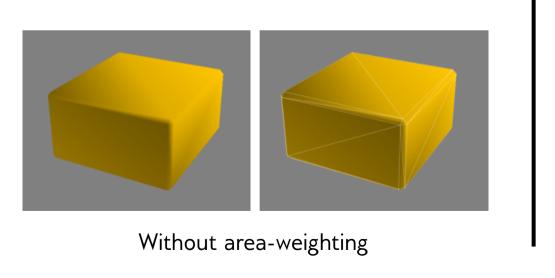
### Estimating vertex normals

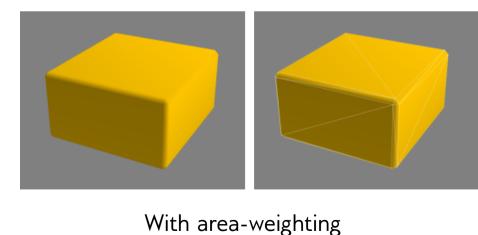
• Simplest: Add up the normals of adjacent faces and unitize



### Estimating vertex normals

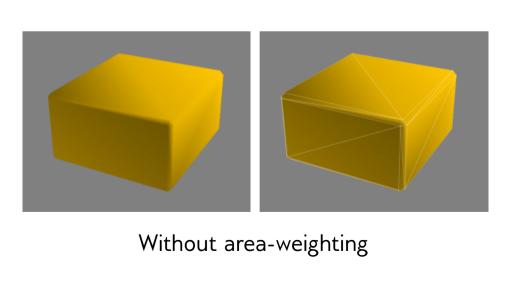
- Simplest: Add up the normals of adjacent faces and unitize
- Simple and usually a bit better: Add up the normals of adjacent faces, weighted by face areas

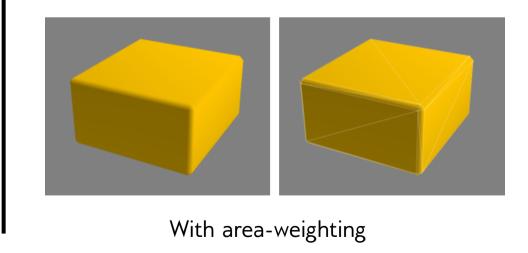




### Estimating vertex normals

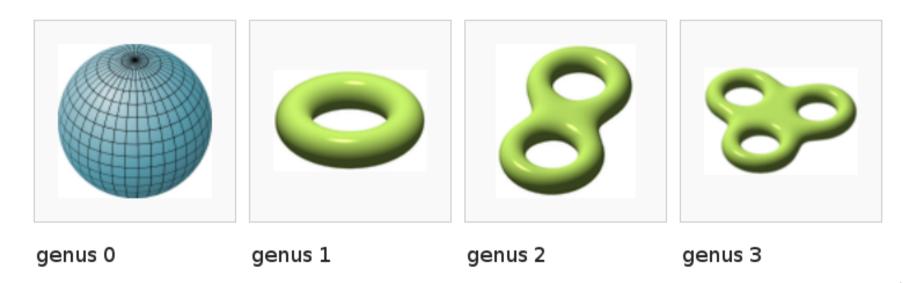
- Simplest: Add up the normals of adjacent faces and unitize
- Simple and usually a bit better: Add up the normals of adjacent faces, weighted by face areas
- Complex: Detect sharp edges





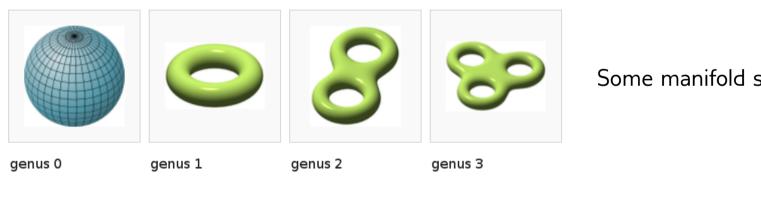
### Mesh Topology

- Topology (loosely): The structure of a shape ignoring any measurements of distance, angle etc
  - i.e. the properties invariant to bending, twisting, folding, stretching... (but not tearing)
- E.g. Genus: The number of handles in a shape

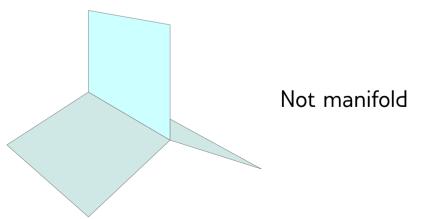


### Mesh Topology

 Manifold: A topological space that is locally Euclidean (neighborhood has the topology of the unit ball)



Some manifold shapes



Manifold structure of a surface is approximated by its mesh connectivity