## Quadratic Optimization: Primal Active-Set Algorithm

Consider the quadratic optimization problem

minimize 
$$\frac{1}{2}\mathbf{x}^T Q \mathbf{x} + \mathbf{c}^T \mathbf{x} + \beta$$
  
subject to  $A \mathbf{x} > \mathbf{b}$  (1)

where  $Q \succ 0$ .

Below, we reproduce the primal active-set method (the motivation for each step was discussed in class) for optimization.

Step 1 Input a feasible point,  $\mathbf{x}^0$ , identify the active set  $\mathcal{I}^0$ , form matrix  $A_{\mathcal{I}^0}$ , and set k = 0. Step 2 Compute  $\mathbf{g}^k = Q\mathbf{x}^k + \mathbf{c}.$ Check the rank condition  $rank[A_{\mathcal{I}^k}^T \mathbf{g}^k] = rank[A_{\mathcal{I}^k}^T]$ . If it does not hold, go to Step 4. Step 3 Solve the system  $A_{\mathcal{I}^k}^T \hat{\lambda} = \mathbf{g}^k$ . If  $\hat{\lambda} \geq \mathbf{0}$ , output  $\mathbf{x}^k$  as the solution and stop; otherwise, remove the index that is associated with the most negative Lagrange multiplier (some  $\hat{\lambda}_t$ ) from  $\mathcal{I}^k$ . Step 4 Compute the value of  $\mathbf{d}^k$ : 
$$\begin{split} \mathbf{d}^k = & \underset{\mathbf{d}}{\operatorname{argmin}} & \frac{1}{2} \mathbf{d}^T Q \mathbf{d} + (\mathbf{g}^k)^T \mathbf{d} \\ & \text{subject to} & \mathbf{a}_i^T \mathbf{d} = 0 & \text{for } i \in \mathcal{I}^k \end{split}$$
(2)Step 5 Compute  $\alpha_k$ :  $\alpha_k = \min\left\{1, \min_{\substack{j \notin \mathcal{I}^k \\ \mathbf{a}^T d^k < 0}} \frac{\mathbf{a}_j^T \mathbf{x}^k - b_j}{-\mathbf{a}_j^T \mathbf{d}^k}\right\}$ (3)

Set 
$$\mathbf{x}^{k+1} = \mathbf{x}^k + \alpha_k \mathbf{d}^k$$
.  
**Step 6**  
If  $\alpha_k < 1$ , construct  $\mathcal{I}^{k+1}$  by adding the index that yields the minimum value of  $\alpha_k$  in (??). Otherwise, let  $\mathcal{I}^{k+1} = \mathcal{I}^k$ .  
**Step 7**  
Set  $k = k + 1$  and repeat from **Step 2**.

Figure 1: Optimization for the quadratic problem in (??) using Primal Activeset Method.