# Lecture 06 - Convex Optimization and Regression 

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## Agenda

- Definition of Convex Sets and Functions
- Example of Convex Set
- Example of Convex Function
- Theorem related to Convex Functions
- Overfitting
- Convex Optimization Problems
- Next Lecture


## Definition of Convex Sets and Convex Functions

Definition of convex sets and convex functions (Cite : Definition 32 and 35)[1]


Figure: Examples of a convex set (a) and a non-convex set (b) Cite: http://cs229.stanford.edu/section/cs229-cvxopt.pdf

A set $C$ is convex if, for any $x, y \in C$ and $\theta \in \Re$ and $0 \leq \theta \leq 1$,

$$
\begin{equation*}
\theta x+(1-\theta) x \in C \tag{1}
\end{equation*}
$$

## Example of a Convex Set

To prove : Verify that a hyperplane is a convex set.

## Proof

- A Hyperplane $\mathcal{H}$ is defined as $\left\{\mathbf{x} \mid \mathbf{a}^{T} \mathbf{x}=b, \mathbf{a} \neq \mathbf{0}\right\}$
- Let $\mathbf{x}$ and $\mathbf{y}$ be vectors that belong to the hyperplane
- Since they belong to the hyperplane, $\mathbf{a}^{T} \mathbf{x}=b$ and $\mathbf{a}^{T} \mathbf{y}=b$
- In order to prove the convexity of the set we must show that:

$$
\begin{equation*}
\theta \mathbf{x}+(1-\theta) \mathbf{y} \in \mathcal{H}, \text { where } \theta \in[0,1] \tag{2}
\end{equation*}
$$

- In particular, it will belong to the hyperplane if it's true that:

$$
\begin{align*}
\mathbf{a}^{T}(\theta \mathbf{x}+(1-\theta) \mathbf{y}) & =b  \tag{3}\\
\Longrightarrow \mathbf{a}^{T} \theta \mathbf{x}+\mathbf{a}^{T}(1-\theta) \mathbf{y} & =b  \tag{4}\\
\Longrightarrow \theta \mathbf{a}^{T} \mathbf{x}+(1-\theta) \mathbf{a}^{T} \mathbf{y} & =b \tag{5}
\end{align*}
$$

- And, we also have $\mathbf{a}^{T} \mathbf{x}=b$ and $\mathbf{a}^{T} \mathbf{y}=b$. Hence $\theta b+(1-\theta) b=b$. [Hence Proved] So a hyperplane is a convex set.


## Definition of Convex Sets and Convex Functions



Figure: A sample convex function

$$
\begin{equation*}
\therefore f(\theta \mathbf{x}+(1-\theta) \mathbf{y}) \leq \theta f(\mathbf{x})+(1-\theta) f(\mathbf{y}) \tag{6}
\end{equation*}
$$

## Example of a Convex Function

Q. $\mathrm{Is}\|\phi \mathbf{w}-\mathbf{y}\|^{2}$ convex?
A.

- To check this, we have (Cite : Theorem 75) ${ }^{1}$. Is this practical?
- Instead, we would use (Cite : Theorem 79) ${ }^{2}$ to check for the convexity of our function
- So the condition that has our focus is -
$\nabla^{2} f\left(\mathbf{w}^{*}\right)$ is positive semi-definite, if $\forall \mathbf{x} \neq 0, \mathbf{x}^{T} \nabla^{2} f\left(\mathbf{w}^{*}\right) \mathbf{x} \geq 0$
- We have,

$$
\begin{equation*}
\nabla^{2} f(\mathbf{w})=2 \phi^{T} \phi \tag{7}
\end{equation*}
$$

- So, $\|\phi \mathbf{w}-\mathbf{y}\|^{2}$ is convex, since the domain for $\mathbf{w}$ is $\mathbb{R}^{n}$ and is convex
${ }^{1}$ cs709/notes/BasicsOfConvexOptimization.pdf
${ }^{2}$ cs709/notes/BasicsOfConvexOptimization.pdf


## Strict Convexity

Q. When is $f(\mathbf{x})$ (strictly) convex?

A1. Iff $f(\theta \mathbf{x}+(1-\theta) \mathbf{y}) \leq(<) \theta f(\mathbf{x})+(1-\theta) f(\mathbf{y})$ for all $\theta \in[0,1]$ and for all $\mathbf{x}, \mathbf{y} \in d m n(f)$
A2. OR Iff $\nabla^{2} f(\mathbf{x})$ is positive semi-definite (definite) for all $\mathbf{x} \in d m n(f)$

## Strict Convexity

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A2. OR Iff $\nabla^{2} f(\mathbf{x})$ is positive semi-definite (definite) for all $\mathbf{x} \in d m n(f)$
Q. Is $\|\phi \mathbf{w}-\mathbf{y}\|^{2}$ strictly convex?
A. Iff $\phi$ has full column rank.

To prove: If a function is convex, any point of local minima $\equiv$ point of global minima
Proof - (Cite : Theorem 69) ${ }^{3}$
${ }^{3}$ cs709/notes/BasicsOfConvexOptimization.pdf

## Theorem

To prove : If a function is strictly convex, it has a unique point of global minima
Proof - (Cite : Theorem 70) ${ }^{4}$
Since $\|\phi \mathbf{w}-\mathbf{y}\|^{2}$ is strictly convex for linearly independent $\phi$,

$$
\begin{equation*}
\nabla f\left(\mathbf{w}^{*}\right)=0 \text { for } \mathbf{w}^{*}=\left(\phi^{T} \phi\right)^{-1} \phi^{T} \mathbf{y} \tag{9}
\end{equation*}
$$

Thus, $\mathbf{w}^{*}$ is a point of global minimum. One can also find a solution to $\left(\phi^{T} \phi \mathbf{w}=\phi^{T} \mathbf{y}\right)$ by Gauss elimination.

[^0]
## Redundant $\phi$ and Overfitting

- What do you expect in experiments if $\phi$ had redundancy?


## Example of linearly correlated features

- Example where $\phi$ doesn't have a full column rank,

$$
\phi=\left[\begin{array}{cccc}
x_{1} & x_{1}^{2} & x_{1}^{2} & x_{1}^{3}  \tag{10}\\
x_{2} & x_{2}^{2} & x_{2}^{2} & x_{2}^{3} \\
\vdots & \vdots & \vdots & \vdots \\
x_{n} & x_{n}^{2} & x_{n}^{2} & x_{n}^{3}
\end{array}\right]
$$

- This is the simplest form of linear correlation of features.


## Redundant $\phi$ and Overfitting



Figure: train-RMS and test-RMS values vs t (degree of polynomial) graph

- Too many bends ( $\mathrm{t}=9$ onwards) in curve $\equiv$ high values of some $w_{i}$ s
- Train and test errors differ significantly


[^0]:    ${ }^{4}$ cs709/notes/BasicsOfConvexOptimization.pdf

