Optimizing Multivariate Performance Measures for Learning Relation Extraction Models

Ganesh Ramakrishnan (joint work with) Gholamreza Haffari Ajay Nagesh

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Outline

Introduction

Preliminaries

Max-margin method for Optimizing Multi-variate Performance Measures

Experiments

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Xerox Corporation is an American multinational company headquartered in Norwalk, Connecticut. On May 21, 2009, it was announced that Ursula Burns would be the CEO of Xerox.

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Can we leverage already existing high quality databases (e.g. Freebase) to learn good relation extractors ?

Distant Supervision for Relation Extraction Mintz et al. (2009)

Knowledge base				
r	e ₁	e ₂		
BornIn	Barack Obama	U. S.		
PresidentOf	Barack Obama	U. S.		

Sentences

- Barack Obama was born in Honolulu, Hawaii, United States.
- Obama left United States this Saturday

for a UN summit in Geneva.

- President Obama defended his administrations' collection of phone records in the U.S.

Distant Supervision based Relation Extraction Mintz et al. (2009)

		Knowledge base	2	_
	r	e_1	e ₂	
	BornIn	Barack Obama	U. S.	
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Sentenc	es		Late	nt Label
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- <i>Obama</i> left United States this Saturday for a UN summit in Geneva.				none
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		4		◆문▶ ◆문▶ - 문

Multiple instance, multiple label Riedel et al. (2010); Hoffmann et al. (2011); Surdeanu et al. (2012)



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phone records in the U.S

Motivation

 In existing approaches, model parameters are often learnt by optimizing performance measures (e.g.: conditional log-likelihood, error rate)

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- In existing approaches, model parameters are often learnt by optimizing performance measures (e.g.: conditional log-likelihood, error rate)
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► Training Objective ⇔ Evaluation Measure

Motivation (cont.)

 Can we train better models by directly optimizing task specific performance measures while allowing latent variables to adapt their values

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Motivation (cont.)

- Can we train better models by directly optimizing task specific performance measures while allowing latent variables to adapt their values
- Further, can we provide a knob in the training algorithm to favor precision more than recall

- Our work: large margin method to learn parameters of models
 - That contain latent variables
 - Optimize performance measures that are non-linear (e.g. : F_{β})

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 Outline of our approach: Interleaves concave-convex procedure (CCCP) with dual decomposition

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- Outline of our approach: Interleaves concave-convex procedure (CCCP) with dual decomposition
 - CCCP : used to populate latent variables
 - Dual decomposition: factorizes the hard optimization problem (during training) into independent sub-problems
 - We present linear programming (LP) and local search methods to solve the sub-problems

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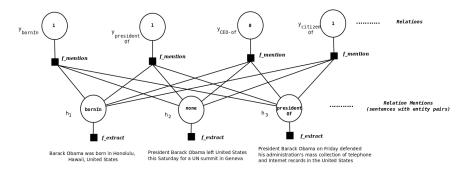


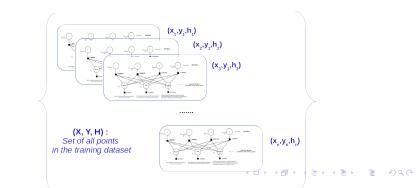
Figure: Graphical model instantiated for entity pair $\mathbf{x} := (Barack Obama, United States)$

Preliminaries



Preliminaries





Structured Prediction Learning

▶ Goal: To find $\mathbf{w} \in R^d$ that minimizes risk

$$R_{f_{\mathbf{w}}}^{\Delta} := \Delta \Big(\big(f_{\mathbf{w}}(\mathbf{x}_1), .., f_{\mathbf{w}}(\mathbf{x}_N) \big), \big(\mathbf{y}_1, .., \mathbf{y}_N \big) \Big)$$

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► Most large margin learning algorithms assume that loss is decomposable. So R[∆]_{f.} is simplified to,

$$R^{\Delta}_{f_{\mathbf{w}}} := \sum_{i=1}^{N} \delta(f_{\mathbf{w}}(\mathbf{x}), \mathbf{y})$$

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However, for non-decomposable loss functions like -F₁,
 Δ cannot be expressed in terms of δ

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Multi-variate Structured Prediction

In decomposable structure prediction task, our aim is to learn
 w ∈ ℝ^d such that for a new entity pair x, we can find:

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 Instead of learning a mapping function from an individual instance to its label, we learn a mapping from all instances to their labels

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$$f_{\mathbf{w}}(\mathbf{x}) := \arg \max_{\mathbf{y}} \max_{\mathbf{h}} \mathbf{w} \cdot \Phi(\mathbf{x}, \mathbf{h}, \mathbf{y})$$

- Instead of learning a mapping function from an individual instance to its label, we learn a mapping from all instances to their labels
- We define the best labeling using the following linear discriminant function

$$\mathbf{f}(\mathbf{X}) := \arg \max_{\mathbf{Y}' \in \mathcal{Y}} \max_{\mathbf{H} \in \mathcal{H}} \left\{ \mathbf{w} \cdot \Psi(\mathbf{X}, \mathbf{H}, \mathbf{Y}') \right\}$$

where $\Psi(\mathbf{X}, \mathbf{H}, \mathbf{Y}') := \sum_{i=1}^{N} \Phi(\mathbf{x}_i, \mathbf{h}_i, \mathbf{y}'_i)$

Training Objective

Based on margin re-scaling formulation of structured prediction problems, our training objective is:

$$\begin{split} & \min_{\mathbf{w}} \frac{1}{2} ||\mathbf{w}||_{2}^{2} + C \max_{\mathbf{y}_{1}',..,\mathbf{y}_{N}'} \left\{ \Delta \left((\mathbf{y}_{1},..,\mathbf{y}_{N}), (\mathbf{y}_{1}',..,\mathbf{y}_{N}') \right) \right. \\ & \left. + \sum_{i=1}^{N} \max_{\mathbf{h}} \mathbf{w} \cdot \Phi(\mathbf{x}_{i},\mathbf{h},\mathbf{y}_{i}') - \sum_{i=1}^{N} \max_{\mathbf{h}} \mathbf{w} \cdot \Phi(\mathbf{x}_{i},\mathbf{h},\mathbf{y}_{i}) \right\} \end{split}$$

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 The above objective is non-convex since it is the difference of two convex functions

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Convex-concave Procedure (CCCP)

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- Refer to Yuille and Rangarajan (2001) and Sriperumbudur and Lanckriet (2012)
- CCCP is a special example of Majorization-Minimization (class of) algorithm(s)
- Elaborate Convergence proof for constrained version by Sriperumbudur and Lanckriet (2012) using Zangwill's global convergence framework

$$\begin{array}{rcl}
 \operatorname{Training Objective} & \min_{\mathbf{w}} \frac{1}{2} ||\mathbf{w}||_{2}^{2} + C \max_{\mathbf{y}_{1}^{\prime}, \dots, \mathbf{y}_{N}^{\prime}} \left\{ \Delta \left((\mathbf{y}_{1}, \dots, \mathbf{y}_{N}), (\mathbf{y}_{1}^{\prime}, \dots, \mathbf{y}_{N}^{\prime}) \right) \\
\end{array} \\
 \overline{ \begin{array}{rcl} Algorithm 1 & \text{The Training Algorithm} \\
\hline & + \sum_{i=1}^{N} \max_{\mathbf{h}} \mathbf{w} \cdot \Phi(\mathbf{x}_{i}, \mathbf{h}, \mathbf{y}_{i}^{\prime}) - \sum_{i=1}^{N} \max_{\mathbf{h}} \mathbf{w} \cdot \Phi(\mathbf{x}_{i}, \mathbf{h}, \mathbf{y}_{i}) \right\} \\
\hline & 1: \text{ procedure OPT-LATENTSVM}(\mathbf{X}, \mathbf{Y}) \\
\hline & 2: & \text{Initialize } \mathbf{w}^{(0)} \text{ and set } t = 0 \\
\hline & 3: & \text{ repeat} \\
\hline & 4: & \text{ for } i := 1 & \text{ to } N & \text{ do} \\
\end{array}$$

Convex-concave Procedure (CCCP)

Training Objective $\min_{\mathbf{w}} \frac{1}{2} ||\mathbf{w}||_2^2 + C \max_{\mathbf{y}',\dots,\mathbf{y}'_{t-1}} \left\{ \Delta \left((\mathbf{y}_1, \dots, \mathbf{y}_N), (\mathbf{y}'_1, \dots, \mathbf{y}'_N) \right) \right.$ $+\sum_{i=1}^{N}\max_{\mathbf{h}}\mathbf{w}\cdot\Phi(\mathbf{x}_{i},\mathbf{h},\mathbf{y}_{i}')-\sum_{i=1}^{N}\max_{\mathbf{h}}\mathbf{w}\cdot\Phi(\mathbf{x}_{i},\mathbf{h},\mathbf{y}_{i})\bigg\}$ Algorithm 1 The Training Algorithm 1: procedure OPT-LATENTSVM(X, Y) Initialize $\mathbf{w}^{(0)}$ and set t = 02: 3: repeat 4: for i := 1 to N do 5: $\mathbf{h}_{i}^{*} := \arg \max_{\mathbf{h}} \mathbf{w}^{(t)} \cdot \Phi(\mathbf{x}_{i}, \mathbf{h}, \mathbf{y}_{i})$ Convex Step: Given the best assignment of latent variables, 6: Solve for w (via cutting plane algorithm) 7. 8 until some stopping condition is met return $w^{(t)}$ 9:

Convex-concave Procedure (CCCP)

$$\begin{array}{rl} \textbf{Training Objective} & \min_{\mathbf{w}} \frac{1}{2} ||\mathbf{w}||_{2}^{2} + C \max_{\mathbf{y}_{1}^{\prime},...,\mathbf{y}_{N}^{\prime}} \left\{ \Delta \left((\mathbf{y}_{1},..,\mathbf{y}_{N}), (\mathbf{y}_{1}^{\prime},..,\mathbf{y}_{N}^{\prime}) \right) \\ \hline \textbf{Algorithm 1 The Training Algorithm} & + \sum_{i=1}^{N} \max_{\mathbf{h}} \mathbf{w} \cdot \Phi(\mathbf{x}_{i},\mathbf{h},\mathbf{y}_{i}^{\prime}) - \sum_{i=1}^{N} \max_{\mathbf{h}} \mathbf{w} \cdot \Phi(\mathbf{x}_{i},\mathbf{h},\mathbf{y}_{i}) \right\} \\ \hline \textbf{I: procedure OPT-LATENTSVM}(\mathbf{X}, \mathbf{Y}) \\ \textbf{2: Initialize } \mathbf{w}^{(0)} \text{ and set } t = 0 \\ \textbf{3: repeat} \\ \textbf{4: for } i := 1 \text{ to } N \text{ do} \\ \textbf{5: } \mathbf{h}_{i}^{*} := \arg\max_{\mathbf{h}} \mathbf{w}^{(t)} \cdot \Phi(\mathbf{x}_{i},\mathbf{h},\mathbf{y}_{i}) \\ & \text{ // Optimizing Eq 12} \\ \textbf{6: } \mathbf{w}^{(t+1)} := \text{optSVM}(\mathbf{X}, \mathbf{H}^{*}, \mathbf{Y}) \\ \textbf{7: } t := t + 1 \\ \textbf{8: until some stopping condition is met} \\ \textbf{9: return } \mathbf{w}^{(t)} \end{array}$$

Figure: CCCP Algorithm () () () () ()

Convex Step: Loss Augmented Inference

Convex step (via cutting plane) to find the best w

Convex Step: Loss Augmented Inference

- Convex step (via cutting plane) to find the best w
- Involves solving the following "loss-augmented inference"

$$\max_{\mathbf{y}'_1,...,\mathbf{y}'_N} \Delta \left((\mathbf{y}_1,..,\mathbf{y}_N), (\mathbf{y}'_1,..,\mathbf{y}'_N) \right) \\ + \sum_{i=1}^N \max_{\mathbf{h}} \mathbf{w} \cdot \Phi(\mathbf{x}_i,\mathbf{h},\mathbf{y}'_i)$$

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Convex Step: Loss Augmented Inference

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 We employ dual decomposition to decouple the two terms and efficiently find an approximate solution

Dual Decomposition

$$\max_{\mathbf{y}'_1,..,\mathbf{y}'_N} \quad \Delta\left((\mathbf{y}_1,..,\mathbf{y}_N),(\mathbf{y}'_1,..,\mathbf{y}'_N)\right) \\ + \sum_{i=1}^N \max_{\mathbf{h}} \mathbf{w} \cdot \Phi(\mathbf{x}_i,\mathbf{h},\mathbf{y}'_i)$$

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Dual Decomposition

$$\max_{\mathbf{y}_{1}',...,\mathbf{y}_{N}'} \Delta\left((\mathbf{y}_{1},...,\mathbf{y}_{N}),(\mathbf{y}_{1}',...,\mathbf{y}_{N}')\right) \\ + \sum_{i=1}^{N} \max_{\mathbf{h}} \mathbf{w} \cdot \Phi(\mathbf{x}_{i},\mathbf{h},\mathbf{y}_{i}') \\ \sum_{\mathbf{y}_{1}',...,\mathbf{y}_{N}''} \Delta\left((\mathbf{y}_{1},...,\mathbf{y}_{N}),(\mathbf{y}_{1}',...,\mathbf{y}_{N}')\right) + \sum_{i=1}^{N} \max_{\mathbf{h}} \mathbf{w} \cdot \Phi(\mathbf{x}_{i},\mathbf{h},\mathbf{y}_{i}'') \\ + \sum_{i=1}^{N} \max_{\mathbf{h}} \mathbf{w} \cdot \Phi(\mathbf{x}_{i},\mathbf{h},\mathbf{y}_{i}'')$$
subject to
$$\forall i \in \{1,...,N\}, \forall \ell \in \{1,...,L\}, \quad y_{i,\ell}' = y_{i,\ell}''$$
Two Independent Sub-problems

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Dual Decomposition (cont.)

 After forming lagrangian, the dual objective function is derived as:

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Dual Decomposition (cont.)

 After forming lagrangian, the dual objective function is derived as:

- Since L(Λ) is an upper-bound on the original loss-augmented inference, we find the tightest upper-bound as an approximate solution: min_Λ L(Λ)
- This is solved via sub-gradient descent method

Optimization of the Dual - Multivariate Loss

$$\mathbf{Y}_{*}^{'} := \arg\max_{\mathbf{Y}^{'}} \Delta(\mathbf{Y},\mathbf{Y}^{'}) + \sum_{i} \sum_{\ell} \lambda_{i}^{(t-1)}(\ell) y_{i,\ell}^{'}$$

Optimization of the Dual - Multivariate Loss

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▶ Optimizing the multivariate loss is also a hard problem since we have search over entire space of Y' ∈ 𝔅 (exponential)

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- ▶ Optimizing the multivariate loss is also a hard problem since we have search over entire space of Y' ∈ 𝔅 (exponential)
- ► However, loss term can be expressed in terms of aggregate statistics over Y' (false positives (FPs) and false negatives (FNs))
- Since FPs and FNs are integral it can take finite values which can be represented on a two-dimensional grid and efficiently searched via a local search algorithm

Local Search Algorithm

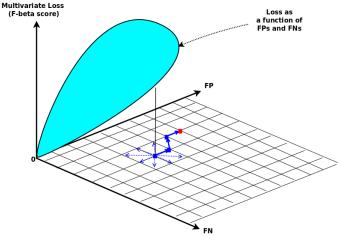


Figure: Local Search Algorithm : An Illustration

Optimization of the Dual - Model Lagrangian

$$\mathbf{Y}_{*}^{''} := \arg \max_{\mathbf{Y}^{''}} \sum_{i=1}^{N} \max_{\mathbf{h}} \mathbf{w} \cdot \Phi(\mathbf{x}_{i}, \mathbf{h}, \mathbf{y}_{i}^{\,''}) \\ - \sum_{i} \sum_{\ell} \lambda_{i}^{(t-1)}(\ell) y_{i,\ell}^{''}$$

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 This problem is as difficult as the MAP inference in the underlying graphical model (NP-hard for loopy graphs)

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Optimization of the Dual - Model Lagrangian

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We use ILP formulations (relaxed to LP) to solve this

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Experimental Setup

 Dataset: We used the benchmark dataset created by Riedel et. al. (2010)

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Experimental Setup

- Dataset: We used the benchmark dataset created by Riedel et. al. (2010)
- Baseline: Hoffmann et. al.'s (2011) state-of-the-art distantly supervised relation extractor

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Experimental Setup

- Dataset: We used the benchmark dataset created by Riedel et. al. (2010)
- Baseline: Hoffmann et. al.'s (2011) state-of-the-art distantly supervised relation extractor
- Our approaches:
 - Max-margin which optimizes simple decomposable (Hamming) loss
 - Max-margin which optimizes non-decomposable $-F_{\beta}$ loss

$$egin{aligned} \mathcal{F}_eta := rac{1}{rac{eta}{ ext{Precision}} + rac{1-eta}{ ext{Recall}}} \end{aligned}$$

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Training on sub-samples of data

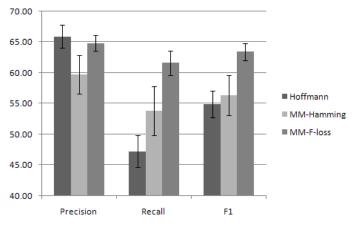


Figure: Experiments on 10% Riedel datasets.

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Tuning towards Precision/Recall

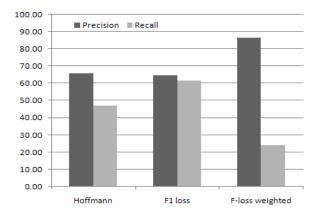


Figure: Weighting of Precision and Recall ($\beta = 0.833$)

Accuracies on the entire dataset

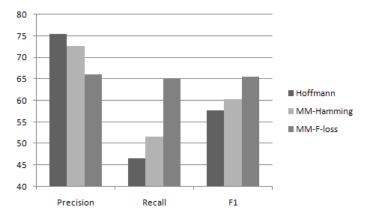


Figure: Overall accuracies Riedel dataset

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Outline

Introduction

Preliminaries

Max-margin method for Optimizing Multi-variate Performance Measures

Experiments

Conclusion

 Described a novel max-margin approach to optimize non-linear performance measures, such as F_β, in distant supervision of information extraction models

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- Described a novel max-margin approach to optimize non-linear performance measures, such as F_β, in distant supervision of information extraction models
- Our approach is general and can be applied to other latent variable models in NLP

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- Described a novel max-margin approach to optimize non-linear performance measures, such as F_β, in distant supervision of information extraction models
- Our approach is general and can be applied to other latent variable models in NLP
- Our approach involves solving the hard-optimization problem in learning by interleaving Concave-Convex Procedure with dual decomposition

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 Under several conditions, we have shown our technique outperforms very strong baselines, and results in up to 8.5% improvement in F₁-score

- Under several conditions, we have shown our technique outperforms very strong baselines, and results in up to 8.5% improvement in F₁-score
- For future work:
 - Maximize other performance measures, such as area under the curve, for information extraction models
 - Explore our approach for other latent variable models in NLP, such as those in machine translation

Acknowledgements

 National ICT Australia (NICTA) for their generous funding, as part of the Machine Learning Collaborative Research Projects.

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 Xerox Research Centre India (XRCI) for their generous student travel grant. Optimizing Multivariate Performance Measures for Learning Relation Extraction Models Conclusion



Thank You!

Code present at : https://github.com/ajaynagesh/lsvm_relationextraction

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