

$$F \text{ measure} := \frac{2 P_r + R_e}{P_r + R_e}$$

$$P_r = \text{Precision} = \frac{\# \text{ True positives}}{\# \text{ True positives} + \# \text{ False Positives}} = \frac{TP}{TP + FP}$$

$$R_e = \text{Recall} = \frac{TP}{TP + FN}$$

$$\frac{1}{F_\beta} = \left( \frac{\beta}{P_r} + \frac{1}{R_e} \right) \frac{1}{2}$$

if  $\beta > 1$  then you favour  
Recall  
& o/w Precision

$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|_2^2 + C \max_{y'_1, \dots, y'_N} \left\{ \Delta \left( (y_1, \dots, y_N), (y'_1, \dots, y'_N) \right) + \sum_{i=1}^N \max_{\mathbf{h}} \mathbf{w} \cdot \Phi(\mathbf{x}_i, \mathbf{h}, y'_i) - \sum_{i=1}^N \max_{\mathbf{h}} \mathbf{w} \cdot \Phi(\mathbf{x}_i, \mathbf{h}, y_i) \right\}$$

$\min_{\mathbf{w}}$

$$\sum_{i=1}^N \max_{\mathbf{h}} \mathbf{w}^T \cdot \phi(\mathbf{x}_i, \mathbf{h}, y_i)$$

convex  $:-g_2(\mathbf{w})$

convex  $:-g_1(\mathbf{w})$

$g_1(\mathbf{w}) - g_2(\mathbf{w})$  s.t.  $g_1$  &  $g_2$  are both convex

Necessary conditions for optimality of  $O(w) = g_1(w) - g_2(w)$

$$\nabla O(\hat{w}) = \nabla g_1(\hat{w}) - \nabla g_2(\hat{w}) = 0$$

$$\nabla g_1(w^{t+1}) = \nabla g_2(w^t) \quad t = \text{iteration number} \dots$$

(set up our fix point iteration)

$$w^{t+1} = \min_w \left( \underbrace{g_1(w) - w^T \nabla g_2(w^t)} \right)$$

More generally Majorization

minimization techniques  
do the following . . .

$\min_w O(w)$  - - - . considers  $T(w, w')$  s.t

$$O(w) \leq T(w, w') \quad \forall w'$$

$$\& O(w) = T(w, w)$$

$w_0$  - - initialized

$$w_{k+1} = \min_w T(w, w_k)$$

$$k = k + 1$$

Majorization  
algos - - -

minimization

Intuition behind convergence:

To prove:  $O(w^{t+1}) \leq O(w^t)$

$$g_1(w^{t+1}) - g_2(w^{t+1})$$

$$\leq$$

$$g_1(w^t) - g_2(w^t)$$

Rearranging

$$g_1(w^{t+1}) - g_1(w^t) \leq g_2(w^{t+1}) - g_2(w^t)$$

$$\begin{aligned} \nabla g_1(w^{t+1}) \\ = \nabla g_2(w^t) \end{aligned}$$

$$g_i(x') \geq g_i(x) + (x' - x)^T \nabla g_i(x)$$

for  $i = 1 \text{ \& } 2$

using

for  $g_1$ ,  $x = w^{t+1}$  &  $x' = w^t$

for  $g_2$ ,  $x = w^t$  &  $x' = w^{t+1}$