CS626: Speech, NLP and the Web

POS Tagging Pushpak Bhattacharyya Computer Science and Engineering Department IIT Bombay Week of 17th August, 2020

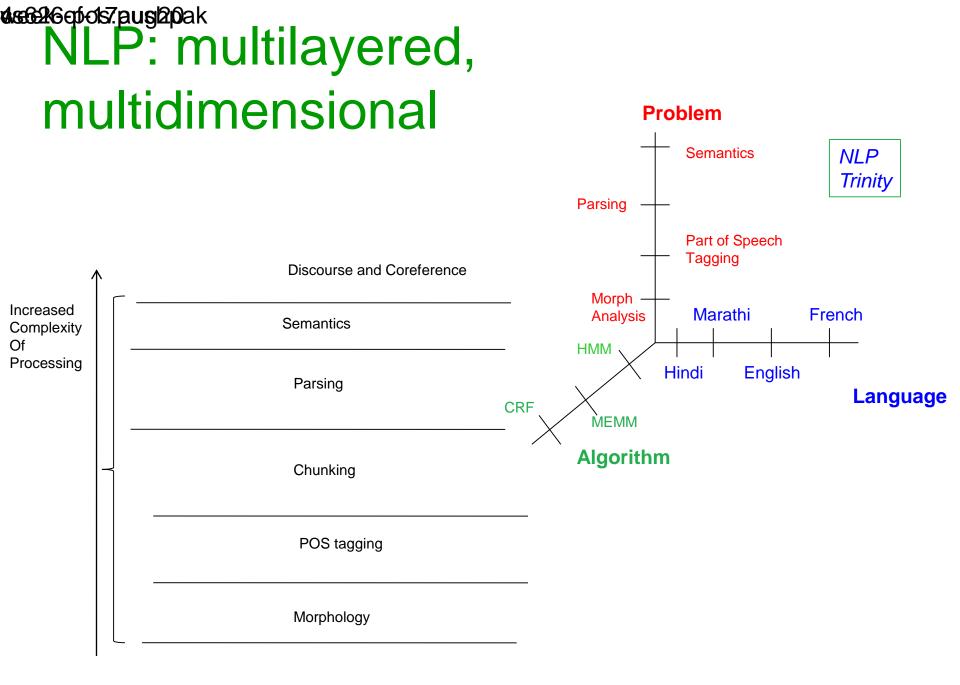
Part of Speech Tagging

Agenda

Rule Based POS Tagging

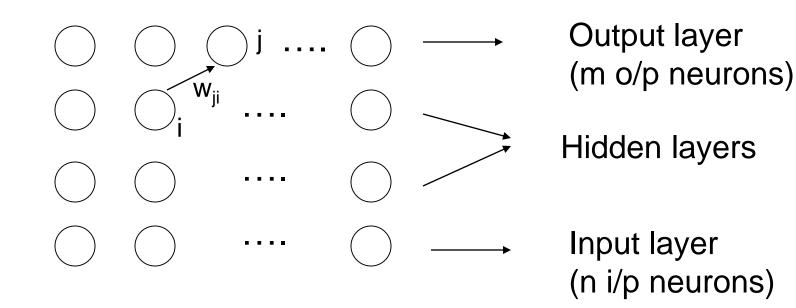
• Statistical ML based POS Tagging (*Hidden Markov Model, Support Vector Machine*)

 Neural (Deep Learning) based POS Tagging



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Multilayer neural net



- NLP pipeline $\leftarrow \rightarrow$ NN layers
- Discover bigger structures bottom up, starting from character?
- Words, POS, Parse, Sentence.

Subwords (for "jaauMgaa", जाऊंगा)

- Characters: "j+aa+u+M+g+aa"
- Morphemes: "jaa"+"uMgaa"
- Syllables: "jaa"+"uM"+"gaa"
- Orthographic syllables: "jaau"+"Mgaa"
- BPE (depends on corpora, statistically frequent patterns): both "jaa" and "uMgaa" are likely

NLP Layer

What a gripping movie was Three_Idiots!

What/WP a/DT gripping/JJ movie/NN was/VBD Three_Idiots/NNP !/!

```
Parse
(ROOT
 (FRAG
    (SBAR
      (WHNP
        (WP What))
        (S
           (NP
             (DT a)
             (JJ gripping)
             (NN movie)
           (VP
             (VBD was)
             (NP
             (NNP Three_idiots)))))
           (. !)
```

Universal dependencies

dobj(Three_Idiots-6, What-1) det(movie-4, a-2) amod(movie-4, gripping-3) nsubj(Dangal-6, movie-4) cop(Dangal-6, was-5) root(ROOT-0, Three_idiots-6) Beeeekeepos. pugl2pak

Part of Speech Tagging

Attach to each word a tag from
 Tag-Set

 Standard Tag-set : Penn Treebank (for English). Øsecentors. puglapak

POS ambiguity instances

best ADJ ADV NP V better ADJ ADV V DET

close ADV ADJ V N (*running close to the competitor, close escape, close the door, towards the close of the play*)

cut V N VN VD even ADV DET ADJ V grant NP N V hit V VD VN N lav ADJ V NP VD left VD ADJ N VN like CNJ V ADJ P near P ADV ADJ DET open ADJ V N ADV past N ADJ DET P present ADJ ADV V N read V VN VD NP right ADJ N DET ADV second NUM ADV DET N set VN V VD N that CNJ V WH DET

POS Ambiguity



2. He is gripping it firm.

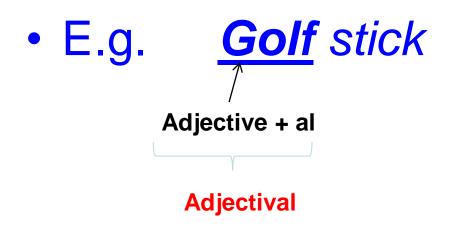
Verb

Linguistic fundamentals

- A word can have two roles
 - Grammatical role (Dictionary POS tag)
 - Functional role (Contextual POS tag)
 - E.g. <u>Golf</u> stick
- POS tag of "Golf"
 - Grammatical: Noun
 - Functional: Adjective (+ al)

The "al" rule!

 If a word has different functional POS tag than its grammatical pos then add "al" to the functional POS tag



Noun + al Verb + al Adjective + al Adverb + al

- = Nominal
- = Verbal
- = Adjectival
- = Adverbial

Dictionary meaning of "Golf" noun

- a game in which clubs with wooden or metal heads are used to hit a small, white ball into a number of holes, usually 9 or 18, in succession,
- situated at various distances over a course having natural or artificial obstacles, the object being to get the ball into each hole in as few strokes as possible.
- a word used in communications to represent the letter *G*.

Golf stick

verb

(used without object) to play golf. *We golfed the whole day in the weekend*

The "al" rule cntd.

- Examples:
 - Nominal

adjective, hun-gri-er, hun-gri-est.

having a desire, craving, or need for food; feeling <u>hunger</u>. indicating, characteristic of, or characterized by hunger:

Many don't
 understand the
 problem of hungry.

He approached the table with a hungry look.

- Adverbial
 - Come quick.

- Verbal?

strongly or eagerly desirous. lacking needful or desirable elements; not fertile; poor:

hungry land.

marked by a scarcity of food: *The depression years were hungry times.*

Learning POS Tags

- Question
 - Is one instance of example enough for ML?
 - E.g. common example of "people"
 People → Noun

POS Ambiguity

But it can be verb as well
 People → Verb (to populate)

Answer

 We need at least as many instances as number of different labels #POS tags-1 to make decision.

Disambiguation of POS tag

• If no ambiguity, learn a table of words and its corresponding tags.

 If ambiguity, then look for the contextual information i.e. look-back or look-ahead.

Data for "present"

He gifted me the/a/this/that present_NN.

They **present_VB** innovative ideas.

He was **present_JJ** in the class.

Rules for disambiguating "present"

- For Present_NN (look-back)
 - If present is preceded by determiner (the/a) or demonstrative (this/that), then POS tag will be noun.
- Does this rule guarantee 100% precision and 100% recall?
 - False positive:
 - The present_ADJ case is not convincing.

Adjective preceded by "the"

- False negative:
 - **Present** foretells the future.

Noun but not preceded by "the"

Rules for disambiguating "present"

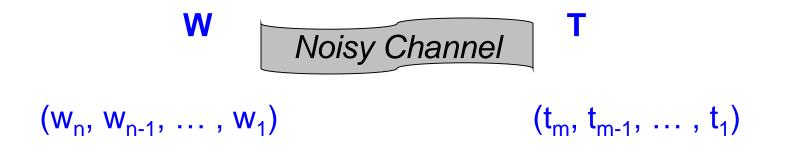
- For Present_NN (look-back and look ahead)
 - If present is preceded by determiner (the/a) or demonstrative (this/that) or followed by a verb, then POS tag will be noun.
 - E.g.
 - Present_NN will tell the future.
 - Present_NN fortells the future.
- Does this rule guarantee 100% precision and 100% recall?

Need for ML in POS tagging

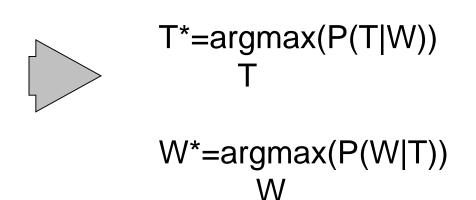
- Rules are challenged by new data
- Need a robust system.

- Machine learning based POS tagging:
 HMM (Accuracy increased by 10-20% against rule based systems)
 - Jelinek's work inspired from ASR

Noisy Channel Model



Sequence *W* is transformed into sequence *T*



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Mathematics of POS tagging

Argmax computation (1/2)

Best tag sequence = T*

 $= \operatorname{argmax} P(T|W)$

 $= \operatorname{argmax} P(T)P(W|T)$ (by Baye's Theorem)

```
\begin{aligned} \mathsf{P}(\mathsf{T}) &= \mathsf{P}(t_0 = {}^{\wedge} t_1 t_2 \dots t_{n+1} = .) \\ &= \mathsf{P}(t_0) \mathsf{P}(t_1 | t_0) \mathsf{P}(t_2 | t_1 t_0) \mathsf{P}(t_3 | t_2 t_1 t_0) \dots \\ &\qquad \mathsf{P}(t_n | t_{n-1} t_{n-2} \dots t_0) \mathsf{P}(t_{n+1} | t_n t_{n-1} \dots t_0) \\ &= \mathsf{P}(t_0) \mathsf{P}(t_1 | t_0) \mathsf{P}(t_2 | t_1) \dots \mathsf{P}(t_n | t_{n-1}) \mathsf{P}(t_{n+1} | t_n) \\ &\qquad \mathsf{N} + 1 \\ &= \prod_{i = 0}^{n} \mathsf{P}(t_i | t_{i-1}) \end{aligned} Bigram Assumption
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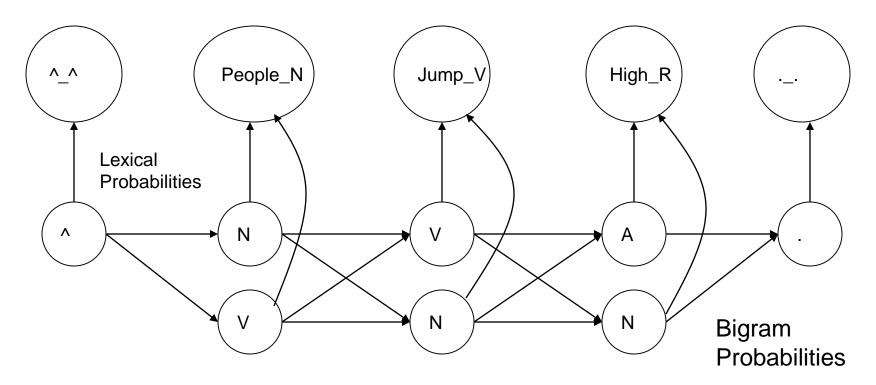
Argmax computation (2/2)

 $P(W|T) = P(w_0|t_0-t_{n+1})P(w_1|w_0t_0-t_{n+1})P(w_2|w_1w_0t_0-t_{n+1}) \dots P(w_n|w_0-w_{n-1}t_0-t_{n+1})P(w_{n+1}|w_0-w_nt_0-t_{n+1})$

Assumption: A word is determined completely by its tag. This is inspired by speech recognition

= $P(w_o|t_o)P(w_1|t_1) \dots P(w_{n+1}|t_{n+1})$ = $\prod_{i=0}^{n+1} P(w_i|t_i)$ = $\prod_{i=1}^{n+1} P(w_i|t_i)$ (Lexical Probability Assumption) 2562664057.pug20ak

Generative Model



This model is called Generative model. Here words are observed from tags as states. This is similar to HMM. 266246qtos7.pug/200ak

Typical POS tag steps

- Implementation of Viterbi Unigram, Bigram.
- Five Fold Evaluation.
- Per POS Accuracy.
- Confusion Matrix.

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Screen shot of typical Confusion Matrix

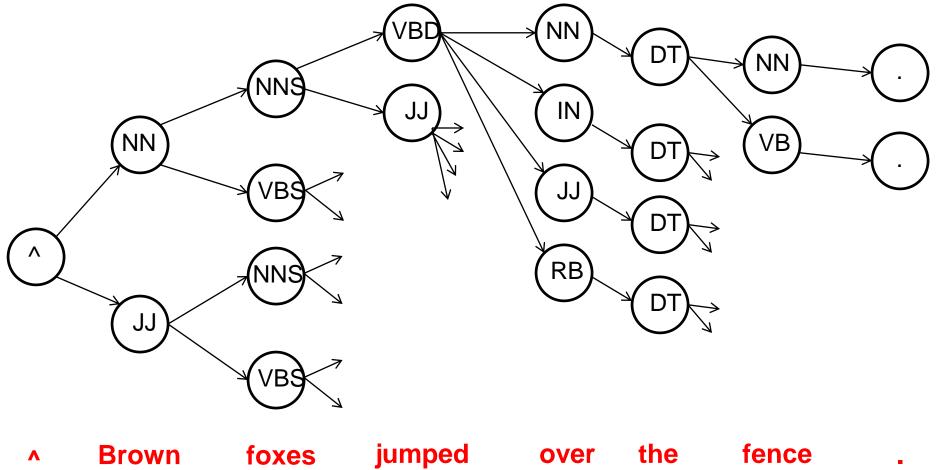
| | AJ0 | AJ0- AV0 | | | | AJ0- VVN | AJC | AJS | AT0 | | AV0- AJ0 | AVP |
|-------------|------|-------------|-----|---|---|-------------|-----|-----|------|------|-------------|-----|
| AJ0 | 2899 | | | | 3 | | 0 | | | | 27 | |
| AJ0- AV0 | 31 | 18 | 2 | 0 | 0 | 0 | 0 | O | 0 | 1 | 15 | 0 |
| AJ0- | | | | | | | | | | | | |
| NN1 AJ0- | 161 | 0 | 116 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 |
| VVD | 7 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| AJ0- VVG | 8 | 0 | 0 | 0 | 2 | 0 | 0 | 0 | 1 | 0 | 0 | 0 |
| AJ0- VVN | 8 | 0 | 0 | 3 | 0 | 2 | 0 | 0 | 1 | 0 | 0 | 0 |
| AJC | 2 | 0 | 0 | 0 | 0 | 0 | 69 | 0 | 0 | 11 | 0 | 0 |
| AJS | 6 | 0 | 0 | 0 | 0 | 0 | 0 | 38 | 0 | 2 | 0 | 0 |
| AT0 | 192 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 7000 | 13 | 0 | 0 |
| AV0 | 120 | 8 | 2 | 0 | 0 | 0 | 15 | 2 | 24 | 2444 | 29 | 11 |
| AV0- | 4.0 | _ | | 0 | 0 | 0 | 0 | 0 | | 40 | 00 | 0 |
| AJO | 10 | | | | 0 | | 0 | | | | | |
| AVP | 24 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 11 | 0 | 737 |

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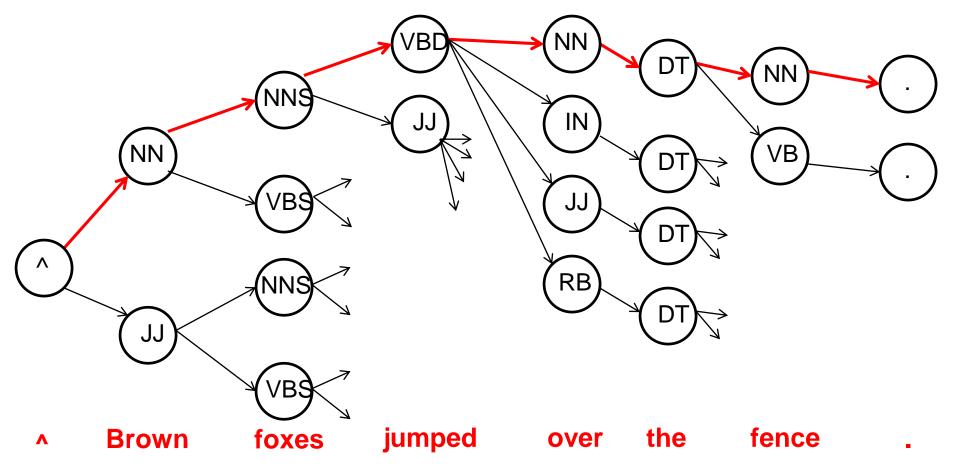
Computation of POS tags

DECODING

| W : | ^ | Brown | foxes | jumped | over | the | fence | |
|------------|---|-------|-------|--------|------|-----|-------|--|
| T: | ^ | JJ | NNS | VBD | NN | DT | NN | |
| | | NN | VBS | JJ | IN | | VB | |
| | | | | | JJ | | | |
| | | | | | RB | | | |



Λ



Probability of a path (e.g. Top most path) = P(T) * P(W|T)

P(^) . P(NN|^) . P(NNS|NN) . P(VBD|NNS) . P(NN|VBD) . P(DT|NN) . P(NN|DT) . P(.|NN) . P(.)

P(^|^) . P(brown|NN) . P(foxes|NNS) . P(jumped|VBD) . P(over|NN) . P(the|DT) . P(fence|NN) . P(.|.)

Questions?

- Where do tags come from?
 Tag set
- How to get probability values i.e. P(.)?
 Annotated corpora

After modeling of the problem, emphasis should be on the corpus

Computing P(.) values

Let us suppose annotated corpus has the following sentence

| I | have | а | brown | bag |
|-----|------|----|-------|-----|
| PRN | VB | DT | JJ | NN |

$$P(NN \mid JJ) = \frac{Number_of_times_JJ_followed_by_NN}{Number_of_times_JJ_appeared}$$

 $P(Brown | JJ) = \frac{Number_of_times_Brown_tagged_as_JJ}{Number_of_times_JJ_appeared}$

Why Ratios?

- This way of computing parameter probabilities: is this <u>correct</u>?
- What does "correct" mean?
- Is this principled?
- We are using Maximum Likelihood Estimate (<u>MLE</u>)
- Assumption: underlying distribution is multinomial

Explanation with coin tossing

- A coin is tossed 100 times, Head appears 40 times
- P(H)= 0.4
- Why?
- Because of maximum likelihood

N tosses, K Heads, parameter P(H)=p

- Construct Maximum Likelihood Expression
- Take log likelihood and take derivative
- Equate to 0 and Get p

$$L = p^{K} (1 - p)^{N - K}$$

$$\Rightarrow LL = \log(L) = K \log p + (N - K) \log(1 - p)$$

$$\Rightarrow \frac{d(LL)}{dp} = \frac{K}{p} - \frac{N - K}{1 - p}$$

$$\Rightarrow \frac{d(LL)}{dp} = 0 \quad gives \quad p = \frac{K}{N}$$

Exercise

- Following the process for finding the probability of Head from N tosses of coin yielding K Heads, prove that the transition probabilities can be found from MLE
- Most important: get the likelihood expression
- Use chapter 2 of the book

 Pushpak Bhattacharyya: Machine translation, CRC Press, Taylor & Francis Group, Boca Raton, USA, 2015, ISBN: 978-1-4398-9718-8

Next question?

- How to decode efficiently?
- E.g.
 - -T: Tags
 - -W:Words
 - Two special symbol: '^' and '.'

Find out number of paths in the tree given word sequence. Exponential *w.r.t.* number of wor

Number of path = Number of leaves in the tree.

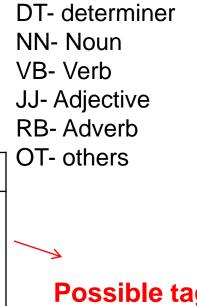
 $O(T^n)$



We do not need exponential work!

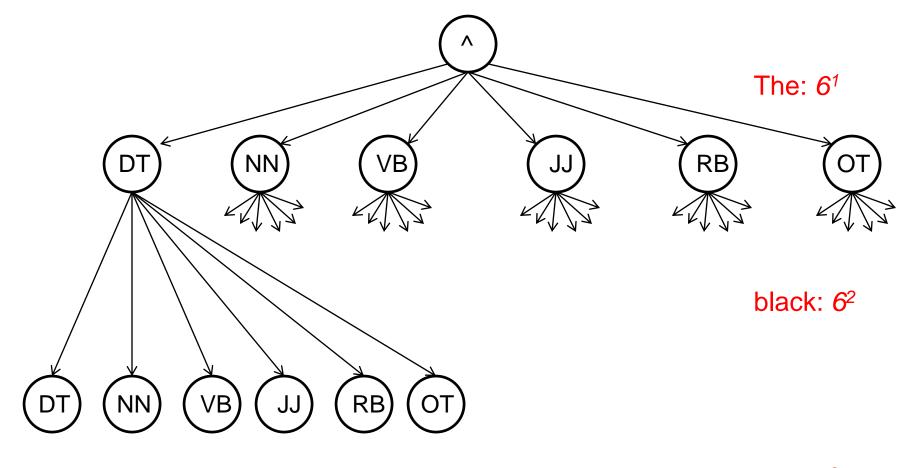
 Suppose our tags are – DT, NN, VB, JJ, RB and OT

• F a



| | | | | | RB- Adverb | |
|---|-----|-------|-----|-------|------------|---------------|
| ^ | The | black | dog | barks | - | OT- others |
| ^ | DT | DT | DT | DT | | |
| | NN | NN | NN | NN | | |
| | VB | VB | VB | VB | | Possible tags |
| | JJ | JJ | JJ | JJ | | |
| | RB | RB | RB | RB | | |
| | ОТ | ОТ | ОТ | ОТ | | |

So, 6⁴ possible path



dog: 6³

barks: 64

.: 64

Total 6⁴ paths

Now consider the paths that end in NN after seeing input "The black"

| ^ | The | black | |
|---|-----|-------|---|
| ^ | DT | NN | P(T).P(W T) = P(DT ^) . P(NN DT) . P(The DT) . P(Black NN) |
| ^ | NN | NN | <pre>P(T).P(W T) = P(NN ^) . P(NN NN) . P(The NN) . P(Black NN)</pre> |
| ^ | VB | NN | <i>P</i> (T) <i>.P</i> (W T) = <i>P</i> (VB ^) . <i>P</i> (NN VB) . <i>P</i> (The VB) . <i>P</i> (Black NN) |
| ^ | JJ | NN | <i>P</i> (T). <i>P</i> (W T) = <i>P</i> (JJ ^) . <i>P</i> (NN JJ) . <i>P</i> (The JJ) . <i>P</i> (Black NN) |
| ^ | RB | NN | P(T).P(W T) = P(RB ^) . P(NN RB) . P(The RB) . P(Black NN) |
| ^ | ОТ | NN | <i>P</i>(T).<i>P</i>(W T) = <i>P</i> (OT ^) . <i>P</i> (NN OT) . <i>P</i> (The OT) . <i>P</i> (Black NN) |
| ~ | 1 | 1 • , | $\mathbf{T}\mathbf{T}$ |

Complexity = $W_n * T$ For each tag, only path with highest probability value are retained, others are simply discarded.

Machine Translation v/s POS tagging!

- Similarity
 - POS
 - Every word in a sentence has one corresponding tag.
 - MT
 - Every word in a sentence has one (or more) corresponding translated word.
- Difference
 - Order: Order of translated word may change.
 - Fertility: One word corresponds to many. Many to one also possible.

Complexity

- POS and HMM
 - Linear time complexity
- MT and Bean search
 - Exponential time complexity
 - Permutation of words produces exponential searc space
 - However, for related languages, MT is like POS tagging

Properties of related languages

1. Order preserving

2. Fertility ~ 1

3. Morphology preserving

| Hindi | Jaaunga | Hindi & Bengali |
|---------|---------|-----------------|
| Bengali | Jaabo | |
| English | Will go | Hindi & English |

Properties of related languages

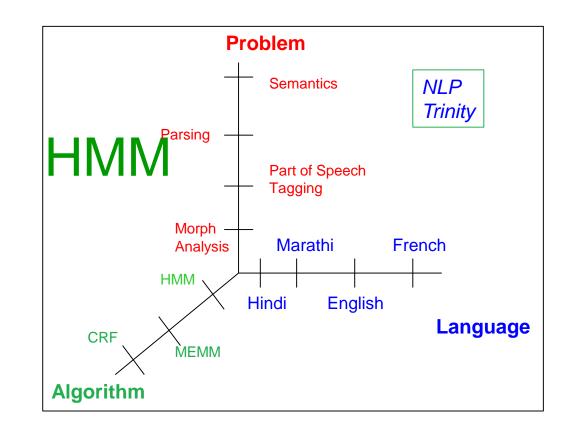
4. Syncretism: Suffix features should be similarly loaded

| Hindi | Main <i>jaaunga</i> | Hum jaayenge | Hindi & Bengali |
|---------|---------------------|--------------|-----------------|
| Bengali | Ami <i>jaabo</i> | Aamra jaabo | |

5. Idiomaticity: Literal translation should be high

| Hindi | Aap Kaise Ho? | Hindi & Bengali |
|---------|--------------------|-----------------|
| Bengali | Aapni Kemon Achen? | |
| English | How do you do? | Hindi & English |

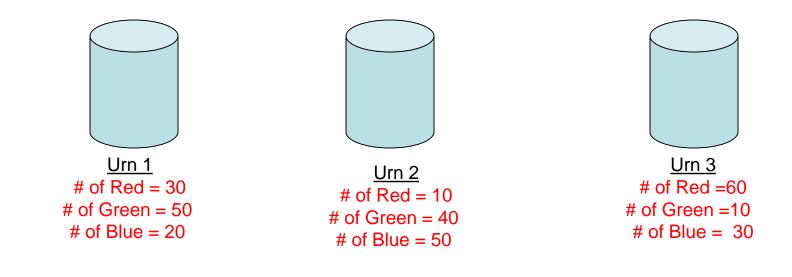
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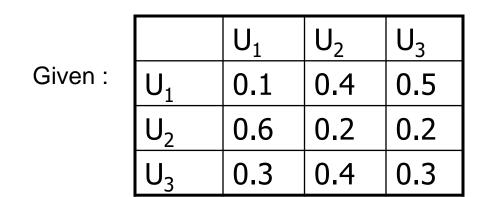
A Motivating Example

Colored Ball choosing



defetered and the second states and the seco

Example (contd.)



Transition probability table

G В R U₁ 0.3 0.5 0.2 and U_2 0.1 0.4 0.5 U₃ 0.3 0.6 0.1

Emission probability table

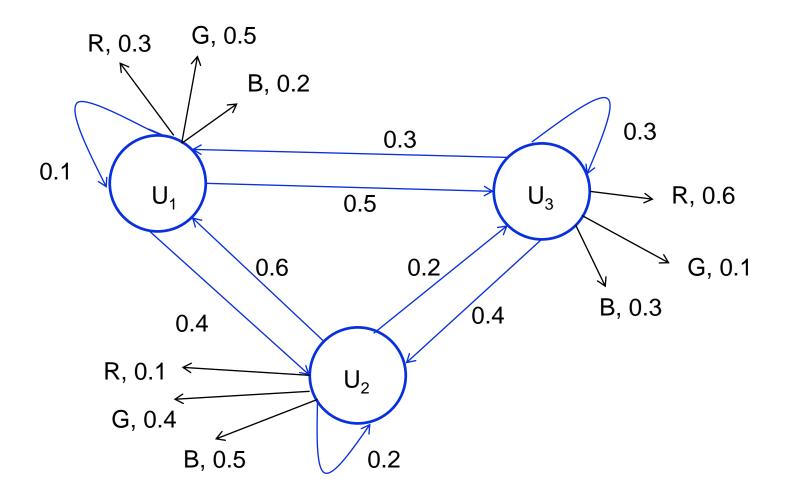
Observation : RRGGBRGR

State Sequence : ??

Not so Easily Computable.

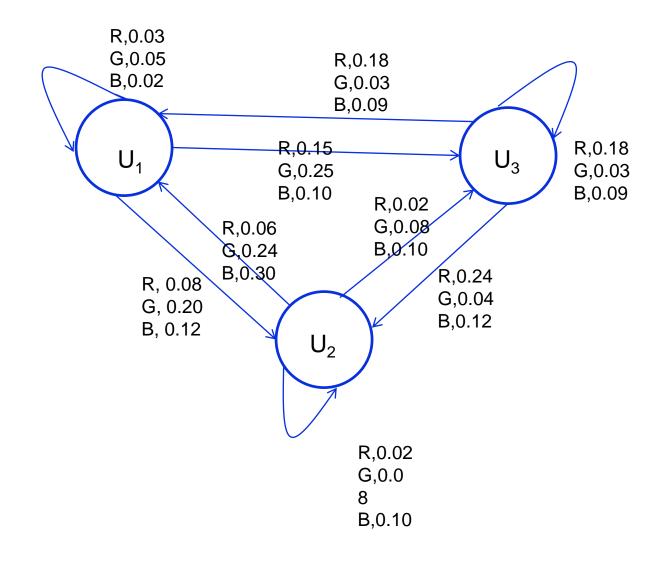
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Diagrammatic representation (1/2)



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Diagrammatic representation (2/2)



Classic problems with respect to HMM

 Given the observation sequence, find the possible state sequences- Viterbi
 Given the observation sequence, find its probability- forward/backward algorithm
 Given the observation sequence find the HMM prameters.- Baum-Welch algorithm

Illustration of Viterbi

- The "start" and "end" are important in a sequence.
- Subtrees get eliminated due to the Markov Assumption.

POS Tagset

- N(noun), V(verb), O(other) [simplified]
- ^ (start), . (end) [start & end states]

Illustration of Viterbi

Lexicon

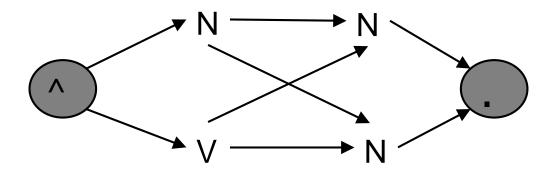
people: N, V laugh: N, V

- •
- •
- •

Corpora for Training

$$\begin{array}{c} & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & &$$

Inference



Partial sequence graph

| | ٨ | Ν | V | 0 | • |
|---|---|-----|-----|-----|-----|
| ^ | 0 | 0.6 | 0.2 | 0.2 | 0 |
| Ν | 0 | 0.1 | 0.4 | 0.3 | 0.2 |
| V | 0 | 0.3 | 0.1 | 0.3 | 0.3 |
| 0 | 0 | 0.3 | 0.2 | 0.3 | 0.2 |
| • | 1 | 0 | 0 | 0 | 0 |

This transition table will change from language to language due to language divergences.

Lexical Probability Table

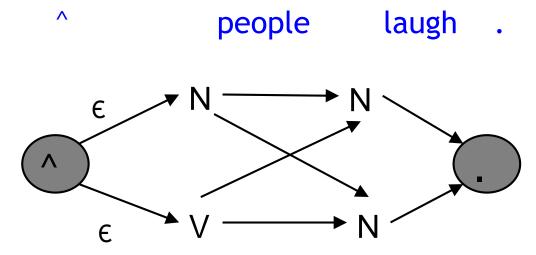
| | E | people | laugh | ••• | |
|---|---|--------------------|--------------------|-----|-----|
| ٨ | 1 | 0 | 0 | ••• | 0 |
| Ν | 0 | 1x10 ⁻³ | 1x10 ⁻⁵ | ••• | ••• |
| V | 0 | 1x10 ⁻⁶ | 1x10 ⁻³ | ••• | ••• |
| 0 | 0 | 0 | 0 | ••• | ••• |
| • | 1 | 0 | 0 | 0 | 0 |

Size of this table = # pos tags in tagset X vocabulary size

vocabulary size = # unique words in corpus

Inference

New Sentence:

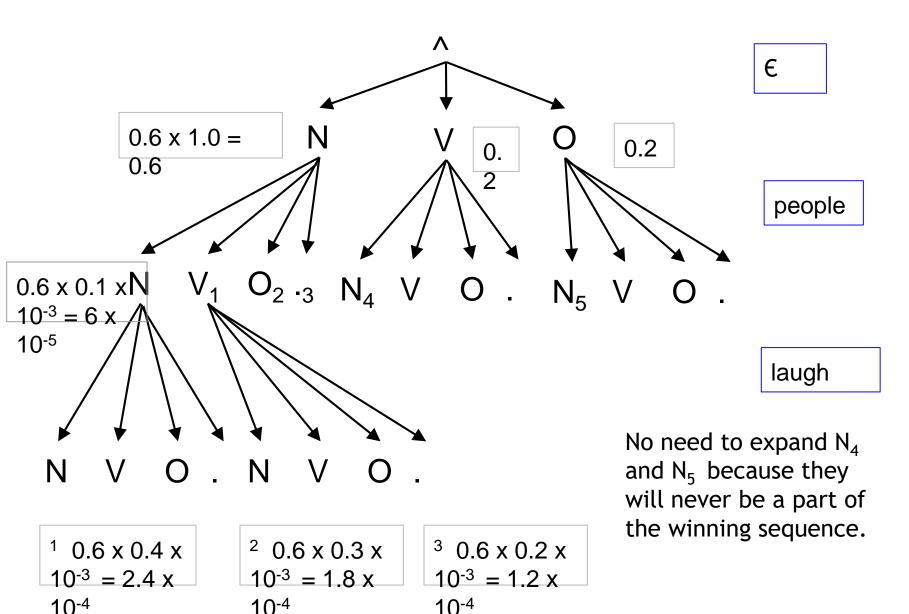


p(^ N N . | ^ people laugh .) = (0.6 x 0.1) x (0.1 x 1 x 10⁻³) x (0.2 x 1 x 10⁻⁵)

Computational Complexity

- If we have to get the probability of each sequence and then find maximum among them, we would run into exponential number of computations.
- If |s| = #states (tags + ^ + .) and |o| = length of sentence (words + ^ + .) Then, #sequences = s^{|o|-2}
- But, a large number of partial computations can be reused using Dynamic Programming.

Dynamic Programming



Computational Complexity

- Retain only those N / V / O nodes which ends in the highest sequence probability.
- Now, complexity reduces from |s|^{|o|} to
 |s|.|o|
- Here, we followed the Markov assumption of order 1.

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Points to ponder wrt HMM and Viterbi

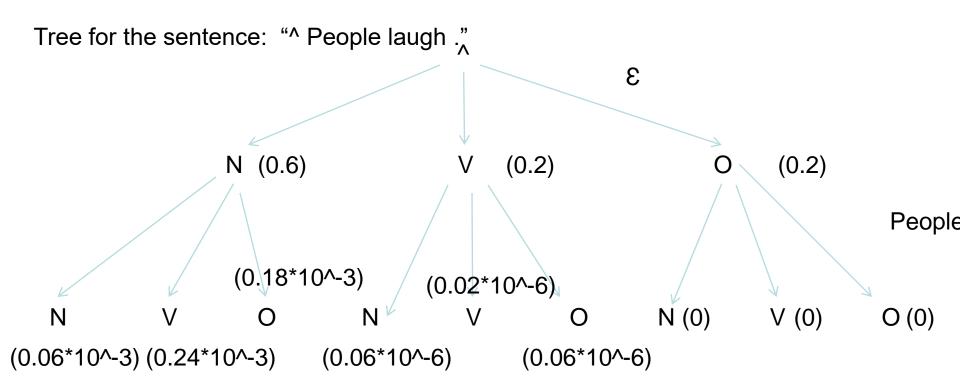
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Viterbi Algorithm

- Start with the start state.
- Keep advancing sequences that are "maximum" amongst all those ending in the same state

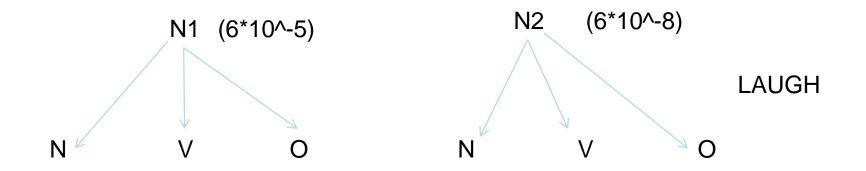
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Viterbi Algorithm



Claim: We do not need to draw all the subtrees in the algorithm

Viterbi phenomenon (Markov process)



Next step all the probabilities will be multiplied by identical probability (lexical and transition). So children of N2 will have probability less than the children of N1.

What does P(A|B) mean?

- P(A|B)=P(B|A)If P(A)=P(B)
- P(A|B) means??
 - Causality?? B causes A??
 - Sequentiality?? A follows B?

Back to the Urn Example

A =

- Here :
 - S = {U1, U2, U3} - V = { R,G,B}
- For observation: $- O = \{o_1 \dots o_n\}$
- And State sequence $-Q = \{q_1 \dots q_n\}$ B=

•
$$\pi i \mathbf{S}_i = P(q_1 = U_i)$$

| | U ₁ | U ₂ | U ₃ |
|----------------|----------------|----------------|----------------|
| U ₁ | 0.1 | 0.4 | 0.5 |
| U ₂ | 0.6 | 0.2 | 0.2 |
| U ₃ | 0.3 | 0.4 | 0.3 |
| | R | G | В |
| U ₁ | 0.3 | 0.5 | 0.2 |
| U ₂ | 0.1 | 0.4 | 0.5 |
| U ₃ | 0.6 | 0.1 | 0.3 |

Observations and states

- $S_i = U_1/U_2/U_3$; A particular state
- S: State sequence
- O: Observation sequence

S* = "best" possible state (urn) sequence

Goal: Maximize P(S*|O) by choosing "best" S

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Goal

 Maximize P(S|O) where S is the State Sequence and O is the Observation Sequence

$$S^* = \arg\max_{S} (P(S \mid O))$$

False Start

 O_1 O_2 O_3 O_4 O_5 O_6 O_8 O_7 R G B R G OBS: R G R S_3 S_4 S_5 S_6 S_2 S_7 S_8 State: S₁

 $P(S \mid O) = P(S_{1-8} \mid O_{1-8})$ $P(S \mid O) = P(S_1 \mid O) \cdot P(S_2 \mid S_1, O) \cdot P(S_3 \mid S_{1-2}, O) \cdot \dots \cdot P(S_8 \mid S_{1-7}, O)$

By Markov Assumption (a state depends only on the previous state)

 $P(S \mid O) = P(S_1 \mid O).P(S_2 \mid S_1, O).P(S_3 \mid S_2, O)...P(S_8 \mid S_7, O)$

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Baye's Theorem

$P(A \mid B) = P(A).P(B \mid A) / P(B)$

P(A) -: Prior P(B|A) -: Likelihood

 $\operatorname{arg\,max}_{S} P(S \mid O) = \operatorname{arg\,max}_{S} P(S) \cdot P(O \mid S)$

State Transitions Probability

$$P(S) = P(S_{1-8})$$

$$P(S) = P(S_1).P(S_2 | S_1).P(S_3 | S_{1-2}).P(S_4 | S_{1-3})...P(S_8 | S_{1-7})$$

By Markov Assumption (k=1)

 $P(S) = P(S_1).P(S_2 | S_1).P(S_3 | S_2).P(S_4 | S_3)...P(S_8 | S_7)$

Observation Sequence probability

 $P(O | S) = P(O_1 | S_{1-8}) \cdot P(O_2 | O_1, S_{1-8}) \cdot P(O_3 | O_{1-2}, S_{1-8}) \cdot \cdot \cdot P(O_8 | O_{1-7}, S_{1-8})$

Assumption that ball drawn depends only on the Urn chosen

 $P(O | S) = P(O_1 | S_1) . P(O_2 | S_2) . P(O_3 | S_3) ... P(O_8 | S_8)$

 $P(S \mid O) = P(S).P(O \mid S)$

 $P(S | O) = P(S_1).P(S_2 | S_1).P(S_3 | S_2).P(S_4 | S_3)...P(S_8 | S_7).$

 $P(O_1 | S_1).P(O_2 | S_2).P(O_3 | S_3)...P(O_8 | S_8)$

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Grouping terms

| $O_0 O_1$ | O ₂ | O ₃ | O_4 | O_5 | O_6 | O ₇ | O ₈ |
|------------------|----------------|----------------|-------|-------|-------|----------------|-------------------------------|
| Obs: ε R | R | G | G | В | R | G | R |
| State: $S_0 S_1$ | S_2 | S_3 | S_4 | S_5 | S_6 | S ₇ | S ₈ S ₉ |

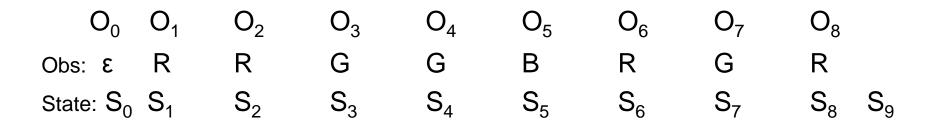
P(S).P(O|S)

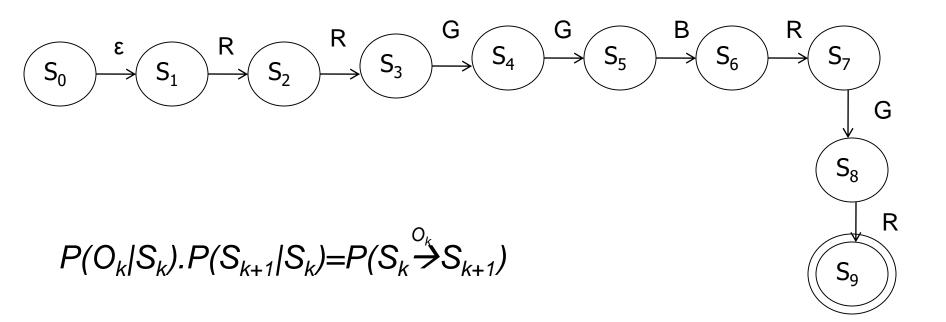
 $= [P(O_0|S_0).P(S_1|S_0)].$ $[P(O_1|S_1). P(S_2|S_1)].$ $[P(O_2|S_2). P(S_3|S_2)].$ $[P(O_3|S_3).P(S_4|S_3)].$ $[P(O_4|S_4).P(S_5|S_4)].$ $[P(O_5|S_5).P(S_6|S_5)].$ $[P(O_6|S_6).P(S_7|S_6)].$ $[P(O_7|S_7).P(S_8|S_7)].$ $[P(O_8|S_8).P(S_9|S_8)].$ We introduce the states S_0 and S_9 as initial and final states respectively.

- After S_8 the next state is S₉ with probability 1, i.e., P(S₉|S₈)=1
- O_0 is ϵ -transition

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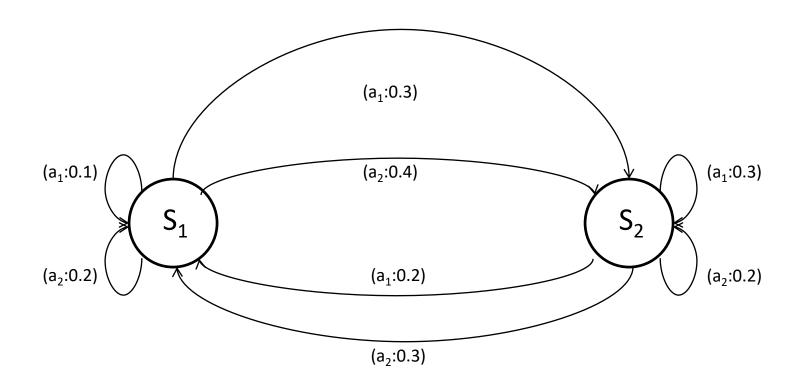
Introducing useful notation





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Probabilistic FSM

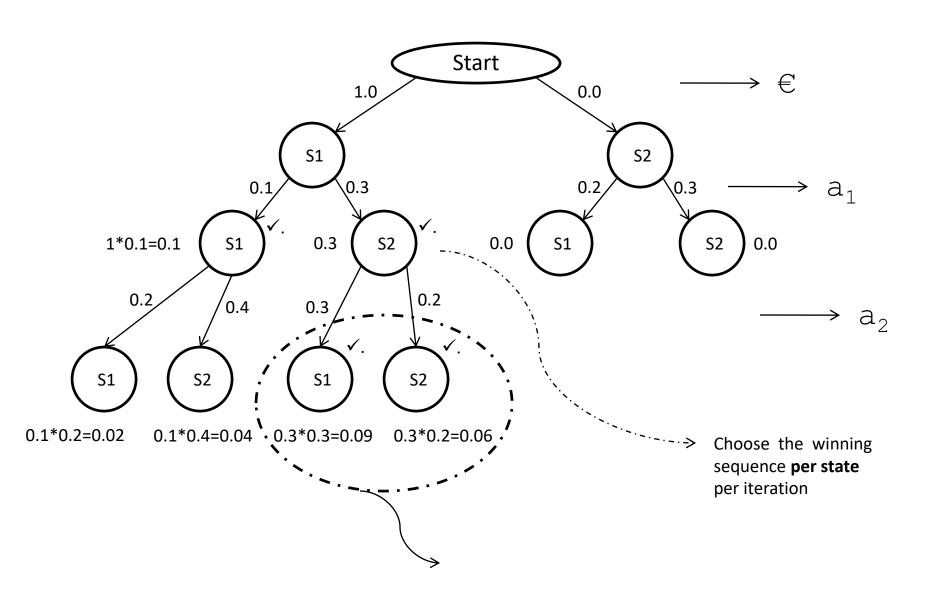


The question here is:

"what is the most likely state sequence given the output sequence seen"

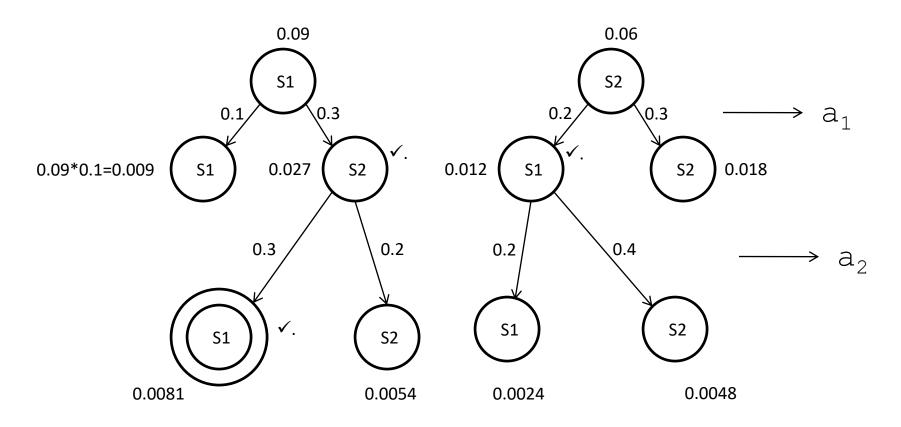
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Developing the tree

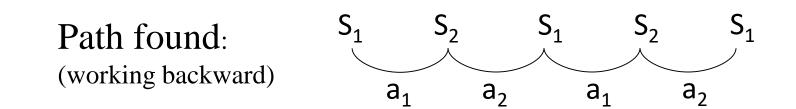


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Tree structure contd...



The problem being addressed by this tree is $S^* = \arg \max_{s} P(S \mid a_1 - a_2 - a_1 - a_2, \mu)$ a1-a2-a1-a2 is the output sequence and μ the model or the machine 7666246q40157.pug/210ak



Problem statement: Find the best possible sequence $S^* = \arg \max P(S \mid O, \mu)$ S where, $S \rightarrow$ State Seq, $O \rightarrow$ Output Seq, $\mu \rightarrow$ Model or Machine Model or Machine = $\{S_0, S, A, T\}$ Start symbol State collection Alphabet Transitions set

T is defined as $P(S_i \xrightarrow{a_k} S_j) \quad \forall_{i, j, k}$

Tabular representation of the tree

| Latest symbol observed Ending state | € | a ₁ | a ₂ | a ₁ | a ₂ |
|---|-----|--|-------------------------|------------------------|-----------------------------|
| S ₁ | 1.0 | (1.0*0.1,0.0*0.2) =(0.1 ,0.0) | (0.02, 0.09) | (0.009, 0.012) | (0.0024, 0.0081) |
| S ₂ | 0.0 | (1.0*0.3,0.0*0.3) =(0.3 ,0.0) | (0.04, 0.06) | (0.027 ,0.018) | (0.0048,0.005 4) |

Note: Every cell records the winning probability ending in that state Final winner

The bold faced values in each cell shows the sequence probability ending in that state. Going backward from final winner sequence which ends in state S_2 (indicated By the 2nd tuple), we recover the sequence.

Algorithm

(following James Alan, Natural Language Understanding (2nd edition), Benjamin Cummins (pub.), 1995

Given:

- 1. The HMM, which means:
 - a. Start State: S₁
 - b. Alphabet: $A = \{a_1, a_2, ..., a_p\}$
 - c. Set of States: $S = \{S_1, S_2, \dots, S_n\}$
 - d. Transition probability which is equal to $P(S_i \xrightarrow{a_k} S_j) \quad \forall_{i, j, k}$ $P(S_j, a_k \mid S_i)$
- 2. The output string $a_1a_2...a_T$

To find:

The most likely sequence of states $C_1C_2...C_T$ which produces the given output sequence, *i.e.*, $C_1C_2...C_T = \arg \max_{\alpha} [P(C | a_1, a_2, ...a_T, \mu]]$

1. Initialization

```
SEQSCORE(1,1)=1.0
BACKPTR(1,1)=0
For(i=2 to N) do
SEQSCORE(i,1)=0.0
[expressing the fact that first state is S_1]
```

2. Iteration

For(t=2 to T) do For(i=1 to N) do SEQSCORE(i,t) = Max_(j=1,N)

 $[SEQSCORE(j,(t-1)) * P(Sj \xrightarrow{a_k} Si)]$

BACKPTR(I,t) = index *j* that gives the MAX above

3. Seq. Identification

```
C(T) = i that maximizes SEQSCORE(i,T)
For i from (T-1) to 1 do
C(i) = BACKPTR[C(i+1),(i+1)]
```

Optimizations possible:

- 1. BACKPTR can be 1*T
- 2. SEQSCORE can be T*2

Homework:- Compare this with A*, Beam Search [Homework] Reason for this comparison:

Both of them work for finding and recovering sequence

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Reading List

<u>https://www.nltk.org/book/ch05.html</u>

• **TNT** (<u>http://www.aclweb.org/anthology-new/A/A00/A00-1031.pdf</u>)

 Hindi POS Tagger built by IIT
 Bombay (<u>http://www.cse.iitb.ac.in/pb/papers/ACL-2006-</u> Hindi-POS-Tagging.pdf)

Assignment Discussion

Build a POS Tagger (due date: 5th September, 2020)

- Using
 - -HMM
 - -SVM
 - Bi-LSTM

Training corpora (Brown Copus)
 <u>http://www.nltk.org/nltk_data/</u>

Project Discussion

Different Areas of NLP

Questions from Mohith

1. You mentioned about "ellipsis" during the lecture. In NLP, does "ellipsis" refer to the computational problem that arises due to

skipping a few words in a sentence, or the whole act of skipping words is itself termed as ellipsis?

- Ans: whole act; "where do you live?"- "Delhi" and "your friend?_{ellipsis}"- "Mumbai"

2. You mentioned about shallow/deep parsing. Was this in the context of dependency/constituency parsing? That is, can I say that dependency parser does shallow parsing and constituency parser does deep parsing, or some other similar relations exist between them?

 both constituency and dependency are "deep" parsing tasks; pos tagging, chunking [(the_DT blue_JJ sky_NN)_{chunk} was (vast_JJ and_CONJ deep_JJ)_{chunk}]

Questions from Mohith

3. In the Learning POS Tags slide, it is mentioned, "We need at least as many instances as number of different labels #POS tags-1 to make decision". That means, corresponding to every tag(except one) we are giving one example to the learning algorithm. If the algorithm encounters a previously unseen example, give it the last tag. I just wanted to know if my understanding is correct here.

-Ans: Correct; give the remaining tag if none of the tags from the training data is applicable

Mohith

Besides my doubts, I have also solved the first homework question that you had provided in the class. Could you please let me know if my answers are correct?

- Question 1: Example of Verbal, Answer: "Could you please google this topic?". Here "google" is a noun, but in this context it is being used as a verb. Therefore "google" would be tagged as a "Verbal"
- -Ans: No, dictionary definition of "google" includes verb also

I haven't got an example for the second question of finding false positive/negative for rules of "present"

-Ans: The rule is "*If present is preceded by determiner* (*the/a*) or demonstrative (*this/that*) or followed by a verb, *then POS tag will be noun*." Still fails for "The present situation is comfortable"