

Advanced Tools from Modern Cryptography

Lecture 3
Secret-Sharing (ctd.)

Secret-Sharing

- Last time
 - (n,t) secret-sharing
 - (n,n) via additive secret-sharing
 - Shamir secret-sharing for general (n,t)
 - Shamir secret-sharing is a linear secret-sharing scheme

Linear Secret-Sharing

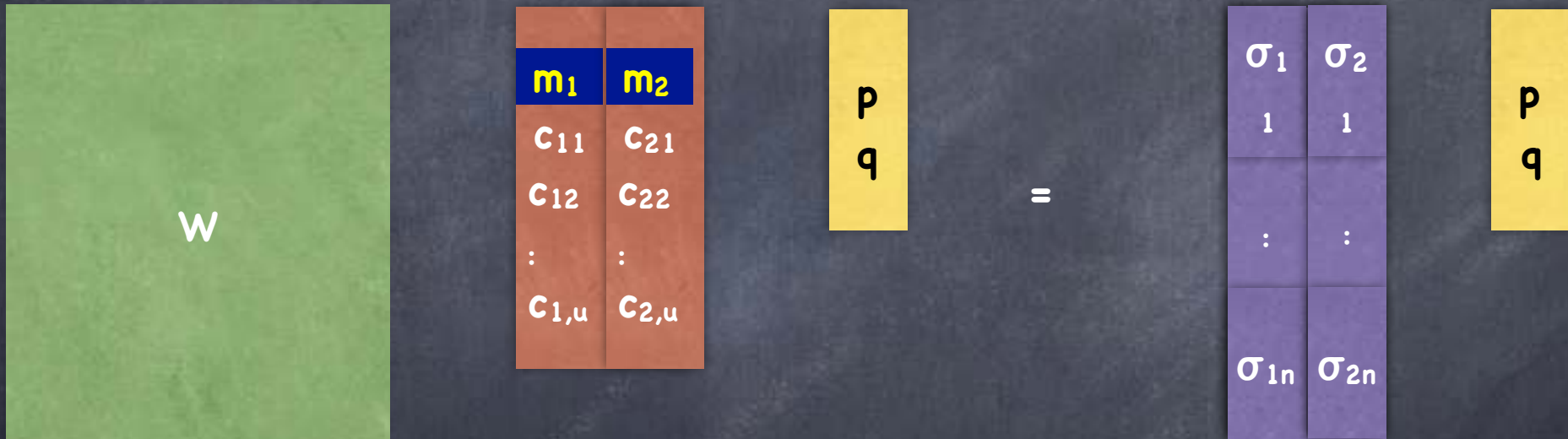
- Linear Secret-Sharing over a field: message and shares are field elements
- Reconstruction by a set $T \subseteq [n]$: solve $W_T \begin{bmatrix} M \\ r \end{bmatrix} = s_T$ for M



Linear Secret-Sharing:

Computing on Shares

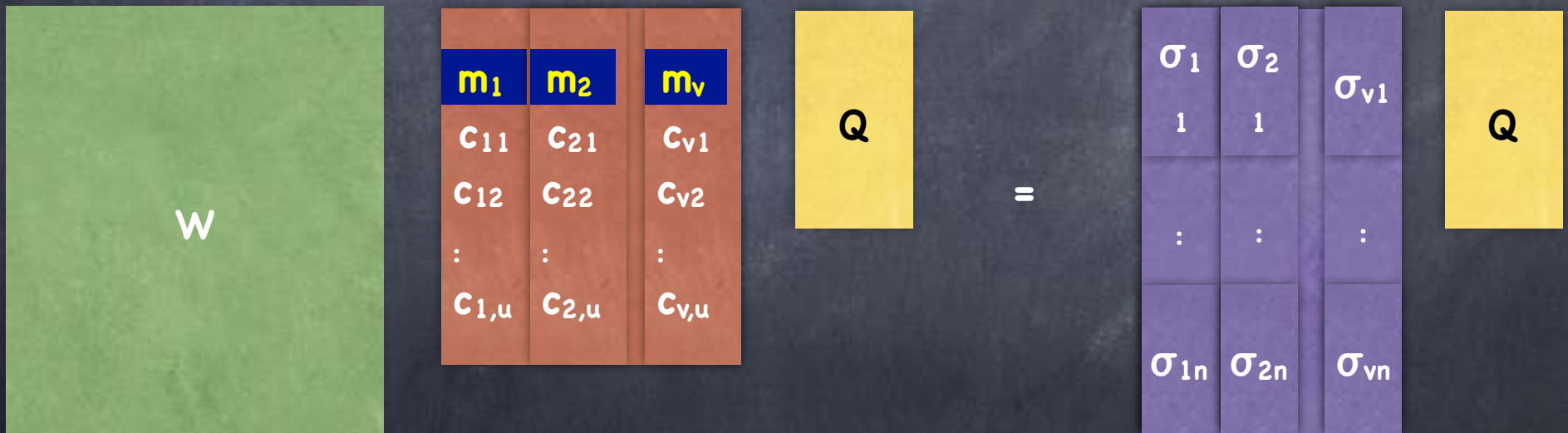
- Suppose two secrets m_1 and m_2 shared using the same secret-sharing scheme



- Then for any $p, q \in \mathbb{F}$, shares of $p \cdot m_1 + q \cdot m_2$ can be computed locally by each party i as $\sigma_i = p \cdot \sigma_{1i} + q \cdot \sigma_{2i}$

Linear Secret-Sharing: Computing on Shares

- More generally, can compute shares of any linear transformation



Each row
computed locally

Switching Schemes

- Can move from any linear secret-sharing scheme W to any other linear secret-sharing scheme Z "securely"



- Given shares $(w_1, \dots, w_n) \leftarrow W.\text{Share}(m)$
- Share each w_i using scheme Z : $(\sigma_{i1}, \dots, \sigma_{in}) \leftarrow Z.\text{Share}(w_i)$
- Locally each party j reconstructs using scheme W :
 $z_j \leftarrow W.\text{Recon}(\sigma_{1j}, \dots, \sigma_{nj})$

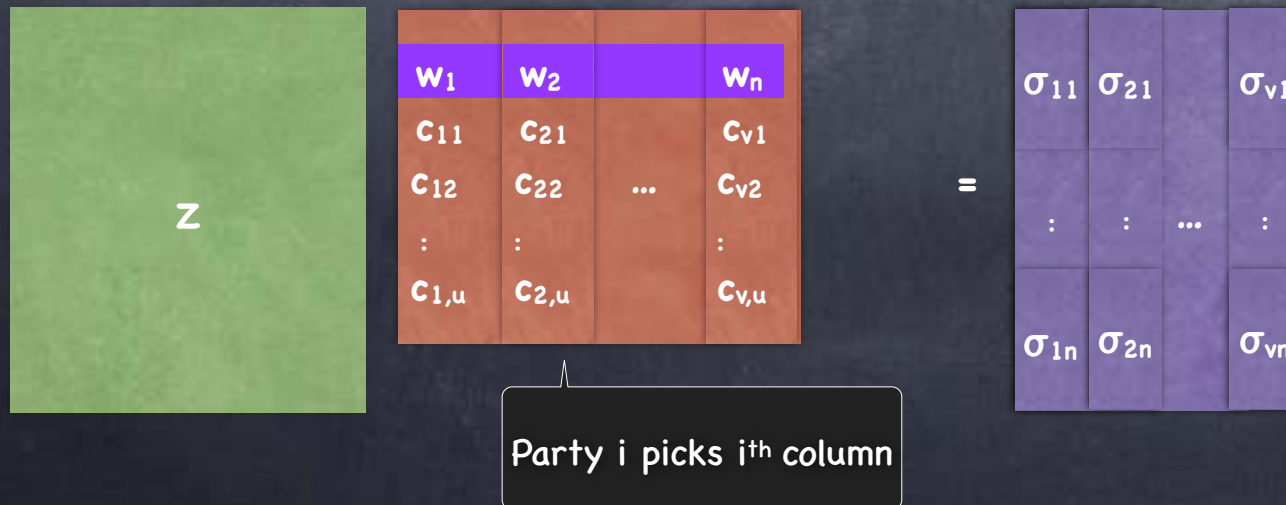


Switching Schemes

- Can move from any linear secret-sharing scheme W to any other linear secret-sharing scheme Z "securely"

$$\begin{bmatrix} R \end{bmatrix} \begin{bmatrix} w_1 \\ \vdots \\ w_n \end{bmatrix} = m$$

- Given shares $(w_1, \dots, w_n) \leftarrow W.\text{Share}(m)$
- Share each w_i using scheme Z : $(\sigma_{i1}, \dots, \sigma_{in}) \leftarrow Z.\text{Share}(w_i)$
- Locally each party j reconstructs using scheme W :
 $z_j \leftarrow W.\text{Recon}(\sigma_{1j}, \dots, \sigma_{nj})$

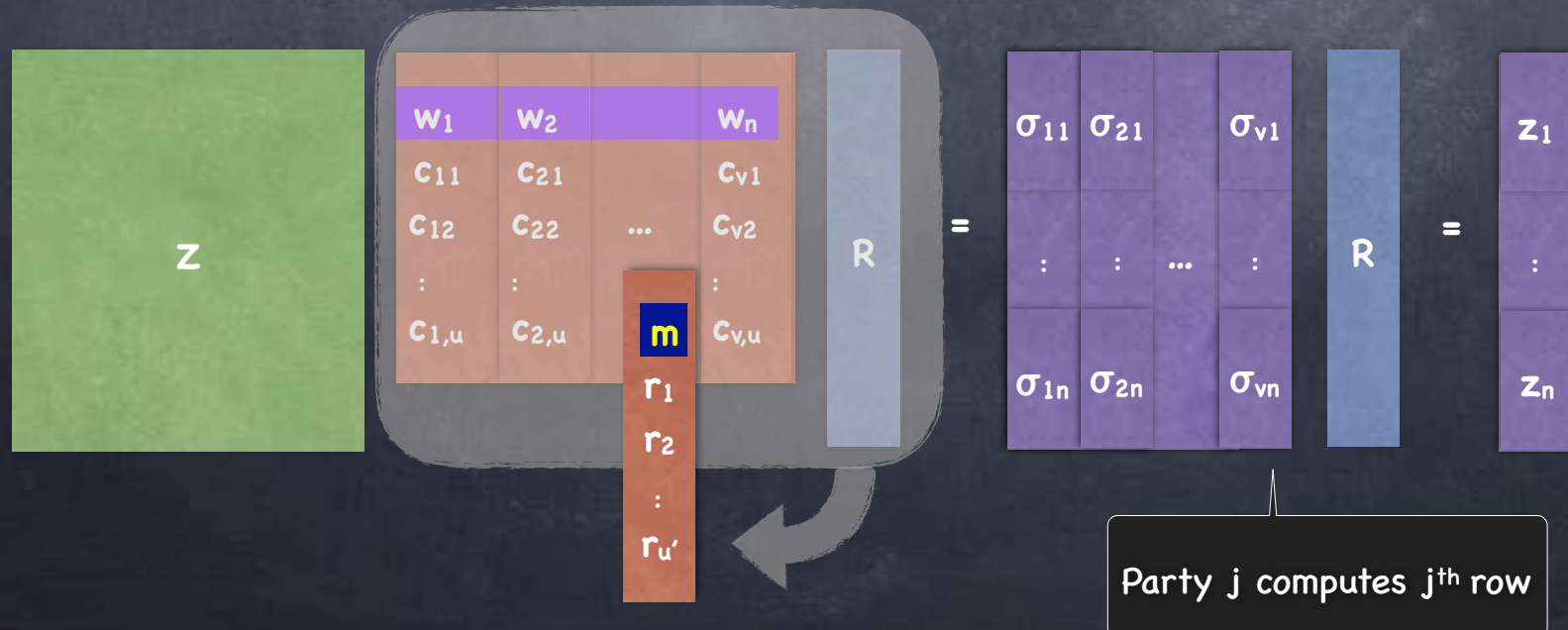


Switching Schemes

- Can move from any linear secret-sharing scheme W to any other linear secret-sharing scheme Z "securely"

$$\begin{bmatrix} & & \\ & R & \\ & & \end{bmatrix} \begin{bmatrix} w_1 \\ : \\ w_n \end{bmatrix} = \begin{bmatrix} m \end{bmatrix}$$

- Given shares $(w_1, \dots, w_n) \leftarrow W.\text{Share}(m)$
- Share each w_i using scheme Z : $(\sigma_{i1}, \dots, \sigma_{in}) \leftarrow Z.\text{Share}(w_i)$
- Locally each party j reconstructs using scheme W :
 $z_j \leftarrow W.\text{Recon}(\sigma_{1j}, \dots, \sigma_{nj})$



Switching Schemes

- Can move from any linear secret-sharing scheme W to any other linear secret-sharing scheme Z “securely”

- Given shares $(w_1, \dots, w_n) \leftarrow W.\text{Share}(m)$
- Share each w_i using scheme Z : $(\sigma_{i1}, \dots, \sigma_{in}) \leftarrow Z.\text{Share}(w_i)$
- Locally each party j reconstructs using scheme W :
 $z_j \leftarrow W.\text{Recon}(\sigma_{1j}, \dots, \sigma_{nj})$

- Note that if a set of parties $T \subseteq [n]$ is allowed to learn the secret by either W or Z , then T learns m from either the shares it started with or the ones it ended up with
- Claim: If $T \subseteq [n]$ is not allowed to learn the secret by both W and Z , then T learns nothing about m from this process

• Exercise

More General Access Structures

- Idea: For arbitrary monotonic access structure \mathcal{A} , there is a “basis” \mathcal{B} of minimal sets in \mathcal{A} . For each S in \mathcal{B} generate an $(|S|, |S|)$ sharing, and distribute them to the members of S .

- Works, but very “inefficient”

$$|\mathcal{B}| = \binom{n}{t}$$

- How big is \mathcal{B} ? (Say when \mathcal{A} is a threshold access structure)

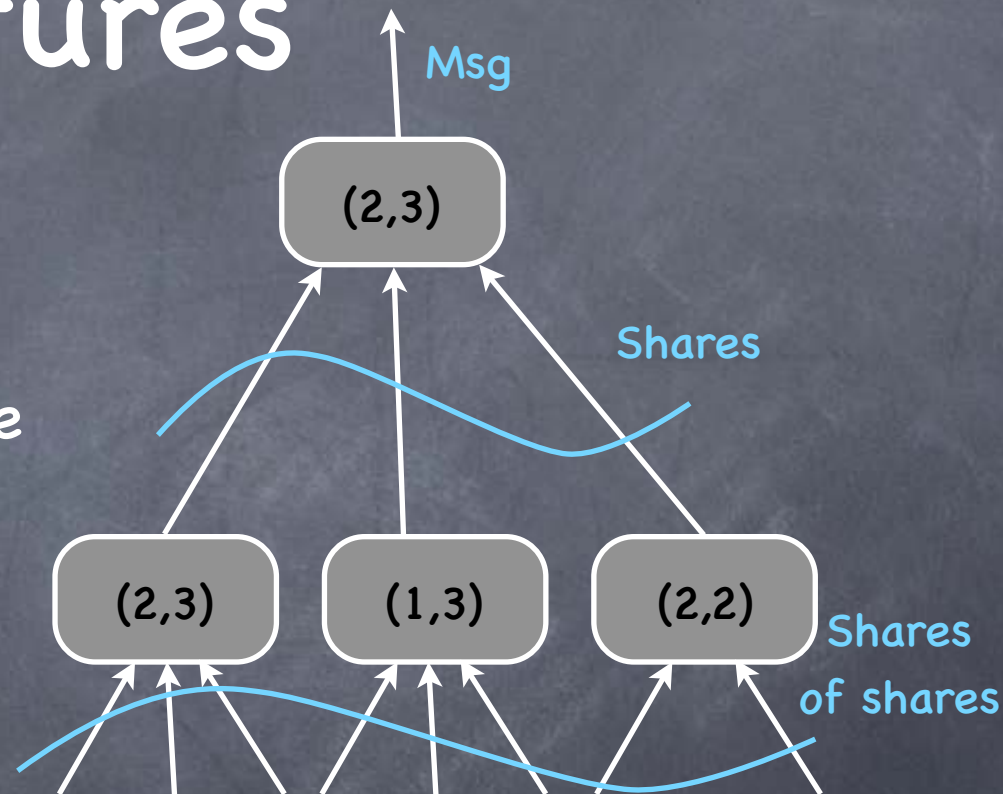
- Total share complexity = $\sum_{S \in \mathcal{B}} |S|$ field elements. (Compare with Shamir's scheme: n field elements in all.)

$$t \cdot \binom{n}{t}$$

- More efficient schemes known for large classes of access structures

More General Access Structures

- A simple generalization of threshold access structures
- A threshold tree to specify the access structure
- Can realize by recursively threshold secret-sharing the shares
- Note: linear secret-sharing
- Fact: Access structures that admit linear secret-sharing are those which can be specified using “monotone span programs”



Efficiency

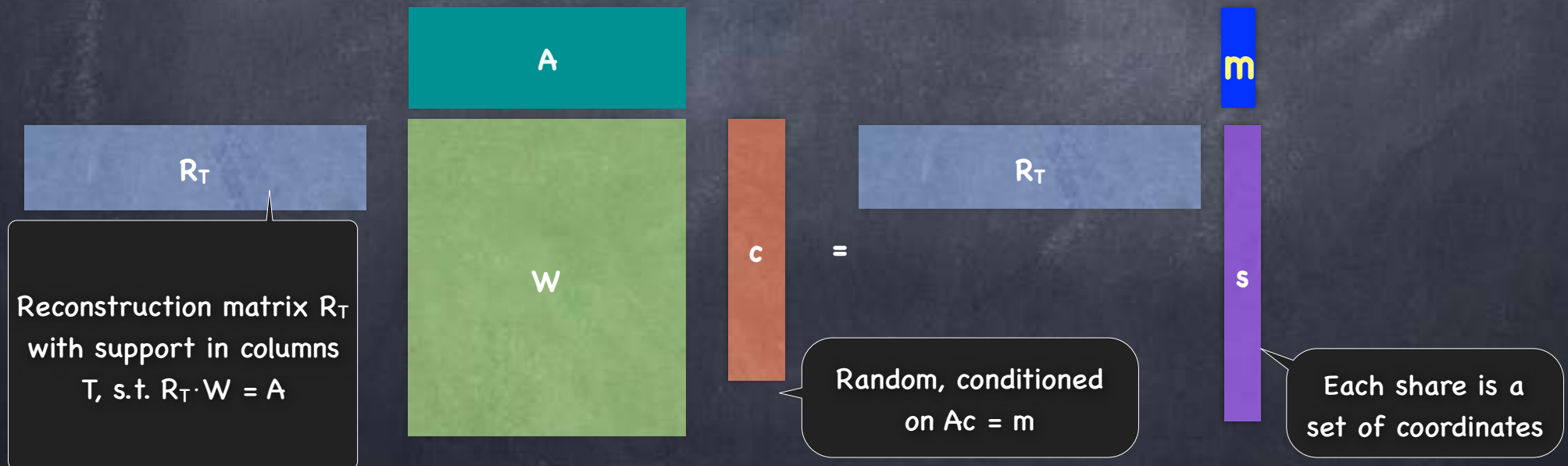
- Main measure: size of the shares (say, total of all shares)
 - Shamir's: each share is as big as the secret (a single field element)
 - Naïve scheme for arbitrary monotonic access structure: if a party is in N sets in \mathcal{B} , N basic shares
 - N can be exponential in n (as \mathcal{B} can have exponentially many sets)
 - **Share size must be at least as big as the secret:** "last share" in a minimal authorized set should contain all the information about the secret
 - Ideal: if all shares are only this big (e.g. Shamir's scheme)
 - Not all access structures have ideal schemes
 - Non-linear schemes can be more efficient than linear schemes

A More General Formulation

- Access structure consists of a monotonically “increasing” family \mathcal{A} (allowed to learn), and a monotonically “decreasing” family \mathcal{F} (forbidden from learning), with $\mathcal{A} \cap \mathcal{F} = \emptyset$
 - $T \in \mathcal{A} \Rightarrow \forall S \supseteq T, S \in \mathcal{A}$. $T \in \mathcal{F} \Rightarrow \forall S \subseteq T, S \in \mathcal{F}$.
 - For $T \notin \mathcal{A} \cup \mathcal{F}$, no requirements of secrecy or learning the message
- E.g., Ramp secret-sharing scheme: $\mathcal{A} = \{ S \subseteq [n] \mid |S| \geq t \}$ and $\mathcal{F} = \{ S \subseteq [n] \mid |S| \leq s \}$, where $s < t$
 - When $s = t-1$, a threshold secret-sharing scheme

Packed Secret-Sharing

- Shamir's scheme can be generalized to a ramp scheme, such that longer secrets can be shared with the same share size
- $m_j = f(z_j)$ and $s_i = f(a_i)$ where $\{z_1, \dots, z_k\} \cap \{a_1, \dots, a_n\} = \emptyset$ and f has degree $t-1$ (t being the reconstruction threshold)
- Access structure: $\mathcal{A} = \{S : |S| \geq t\}$ and $\mathcal{F} = \{S : |S| \leq t-k\}$



- $T \in \mathcal{A}$ if A spanned by W_T , and $T \in \mathcal{F}$ if every row of A independent of W_T