

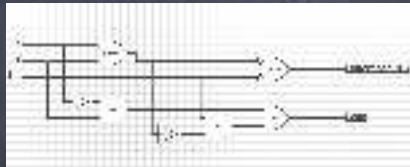
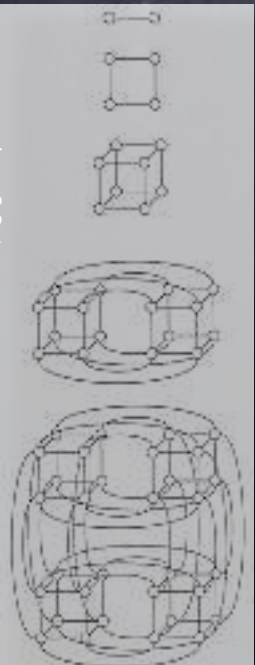
Graphs

Lecture 13

Graphs

- What is "connected" to what
- Many things we deal with in computer science are graphs
 - Networks: humans, communication, computation, transportation, knowledge

Courtesy: gigaflop.demon.co.uk



Courtesy: Microsoft Academic Search

Courtesy: cablemap.info



Courtesy: New Scientist



Courtesy: Digital Humanities Specialist @ Stanford

Simple Graphs

- A simple graph $G = (V, E)$, where
 - $E \subseteq \{ \{a, b\} \mid a, b \in V, a \neq b \}$
- V is the set of nodes E the set of edges
- V non-empty and finite (for us)
- Note: the “drawing” is not part of the graph, only the connectivity is

Simple Graphs

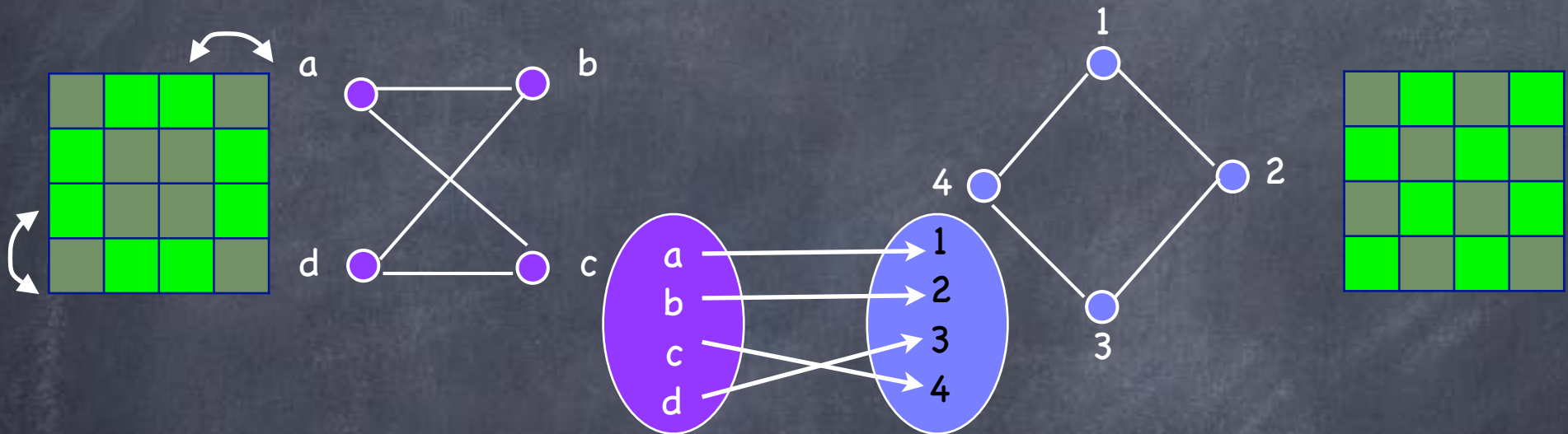
- Recall graphs for relations: directed graphs with self-loops
 - Each element in the domain forms a node
 - Each ordered pair (a,b) in the relation forms an edge
 - Edges of the form (a,a) are “self-loops”
- A simple graph is a symmetric, irreflexive relation
 - Symmetric: An undirected edge $\{a,b\}$ can be modelled as two directed edges (a,b) and (b,a)
 - Irreflexive: No self-loops
- In a “non-simple” graph, can allow more than one edge between any pair (multigraphs), or more generally, allow weights on edges (weighted graphs)

Examples

- **Complete graph K_n** : n nodes, with all possible edges between them
 - $E = \{ \{a,b\} \mid a,b \in V, a \neq b \}$
 - # edges, $|E| = n(n-1)/2$
- **Cycle C_n** : $V = \{ v_1, \dots, v_n \}$, $E = \{ \{v_i, v_j\} \mid j=i+1 \text{ or } (i=1 \text{ and } j=n) \}$
- **Bipartite graph** : $V = V_1 \cup V_2$, where $V_1 \cap V_2 = \emptyset$ (i.e., a partition), and no edge between two nodes in the same "part":
 $E \subseteq \{ \{a,b\} \mid a \in V_1, b \in V_2 \}$
 - e.g., C_n where n is even
- **Complete bipartite graph K_{n_1, n_2}** : Bipartite graph, with $|V_1|=n_1$, $|V_2|=n_2$ and $E = \{ \{a,b\} \mid a \in V_1, b \in V_2 \}$
 - # edges, $|E| = n_1 \cdot n_2$
- Later: **Hypercube, Trees**

Graph Isomorphism

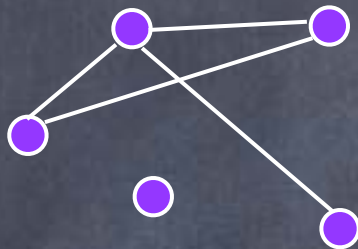
- $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ are isomorphic if there is a bijection $f: V_1 \rightarrow V_2$ such that $\{u, v\} \in E_1$ iff $\{f(u), f(v)\} \in E_2$



- Computational problem: check if two graphs (given as **adjacency matrices**) are isomorphic
 - Can rule out if certain "invariants" are not preserved (e.g. $|V|, |E|$)
- In general, no "efficient" algorithm known, when graph is large
 - Some believe no efficient algorithm exists!

Degree of a node

- Given a simple graph $G = (V, E)$, for each node $v \in V$, the degree of v is the number of edges incident on v



- Formally, $\text{deg}(v) = | \{ u : \{u, v\} \in E \} |$

Note: Definition restricted to simple graphs

- Counting** edges in two different ways: $2 \cdot |E| = \sum_{v \in V} \text{deg}(v)$
- Degree sequence: sorted list of degrees. (e.g.: 0,1,2,2,3)
- Degree sequence invariant under isomorphism



Question



ZBVY

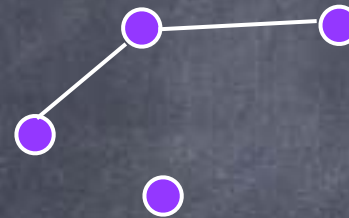
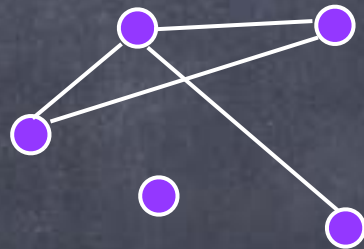
- A graph is said to be d-regular if all nodes have degree d . How many edges are there in a 3-regular graph with 6 nodes?

- A. Such a graph doesn't exist
- B. 18
- C. 12
- D. 9
- E. It depends on the graph

e.g., $K_{3,3}$
 $n \cdot d / 2$ (unless n & d odd)

Subgraphs

- A subgraph of $G = (V, E)$ is a graph $G' = (V', E')$ such that $V' \subseteq V$ and $E' \subseteq E$

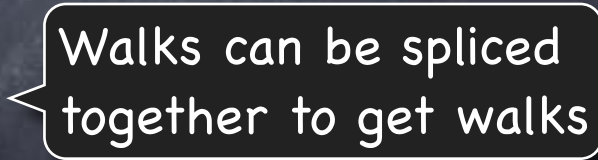


- To get a subgraph: Remove zero or more vertices, remove all edges incident on them, and further remove zero or more edges
 - Induced subgraph: omit the last step

Walks, Paths & Cycles

- A walk (of length k , $k \geq 0$) from node a to node b is a sequence of nodes (v_0, v_1, \dots, v_k) such that
 - $v_0 = a, v_k = b$
 - for all $i \in \{0, \dots, k-1\}$, the edge $\{v_i, v_{i+1}\} \in E$
- Length is the number of edges in a walk. Could be 0.
- If a walk has no node repeating, then it is called a path
- If a walk of length $k \geq 3$ has $v_0 = v_k$, but no other two nodes are equal, then it is called a cycle
 - Note: we require a cycle to be of length at least 3
- A graph is acyclic if it has no cycles (i.e., no C_k is a subgraph of G)

Connectivity

- Given a graph G , whether there is a path between two nodes u and v is an important question regarding G
 - u is said to be connected to v if there is such a path
 - Prove: u connected to v iff there is a walk from u to v
- Relation $\text{Connected}(u,v)$ is an equivalence relation
 - Reflexive, Symmetric and Transitive 
 - Equivalence classes of this relation are called the connected components of G

Prove via contradiction

Hence \exists walk
 $\rightarrow \exists$ path

Distance

In many applications, the edges on the graph will have "lengths". For us, typically all edges are of length 1.

- Shortest walk between nodes u and v is always a path
- Shortest path is of great interest in many applications
 - e.g., nodes correspond to locations on a map and edges are roads, optic fibers etc.
 - Also, graph can be used to model probabilistic processes, with shortest path indicating the most likely outcome
- Length of the shortest path between u and v is called the distance between u and v (∞ if no path)

$$\min_{W: u-v \text{ walk}} \text{Length}(W)$$

- Diameter is the largest distance in a graph (can be ∞)

$$\max_{u,v} \text{Distance}(u,v) = \max_{u,v} \min_{W: u-v \text{ walk}} \text{Length}(W)$$