Design and Engineering of Computer Systems

Lecture 8: Threads

Mythili Vutukuru IIT Bombay

What are threads?

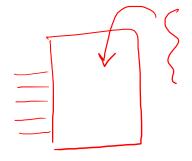
- A process may want to run multiple copies of itself
 - If one copy blocks due to blocking system call, another copy can still run
 - Multiple copies can run in parallel on multiple CPU cores
- Example: a web server should handle multiple requests at a time
- One option: have multiple processes running the same program
 - Disadvantage: too much memory consumed by identical memory images
- Better option: use threads = light weight processes
- A process can create multiple threads (default: single thread)
 - Multiple threads share same memory image of process, saves memory
 - Threads run independently on same code (if one blocks, another can still run)
 - Threads can run in parallel on multiple cores at same time

Understanding threads

- Multiple threads of a process share the same code, global/static variables allocated at compile time, and heap
- Threads execute independently on the process code
 - Each thread has its own separate CPU context
 - Each thread's PC is pointing to different instructions
- As a result, each thread has a separate stack
 - Each thread calls functions independently, has to store context separately
- Inside the OS, each thread has its separate thread control block (TCB), context stored in TCB when not running
 - TCBs of threads belonging to same process share some common information of the PCB (e.g., details of memory image, I/O connections)

Stack 1 Stack 2

POSIX threads



- In Linux, POSIX threads (pthreads) library allows creation of multiple threads in a process
- Each thread is given a <u>start function</u> where its execution begins
 - Threads execute independently from parent after creation/
 - Parent can wait for threads to finish (optional)
- Threads created with pthreads treated as separate entities by OS scheduler, can run concurrently on same CPU core, or in parallel on multiple cores
 - Kernel-level threads (OS is aware of them)
- Several such threading libraries exist
 - Not all threading libraries guarantee independent scheduling at the OS level, may exist only for ease of programming for user (user-level threads)

```
void f1()
void f2() {
main()
  pthread_t t1, t2
  pthread_create(&t1, .(, f1).
  pthread_create(&t2), (., f2)
  pthread_join(t1, ..)
  pthread_join(t2,..)
```

Shared data access

- Threads of a program share global/static variables and heap data
- What happens when threads concurrently access shared data?
- Example: two threads created, each increments shared counter 1000 times
 - We expect final counter value to be 2000
 - In reality: value slightly smaller than 2000
- Concurrent access of shared data is tricky!

```
int counter;
void start fn() {
  for(int i=0; i < 1000; i++)
    counter = counter + 1
main() {
  counter = 0
  pthread t t1, t2
  pthread_create(&t1,.., start_fn, ..)
  pthread_create(&t2, .., start_fn,..)
  pthread join(t1, ..)
  pthread_join(t2, ..)
  print counter
```

Understanding shared data access

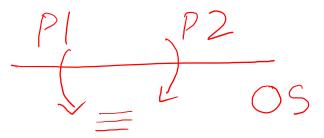
- The C code "counter = counter + 1" is compiled into multiple instructions
 - Load counter variable from memory into register
 - Increment register
 - Store register back into memory of counter variable
- What happens when two threads run this line of code concurrently?
 - Counter is 0 initially
 - T1 loads counter into register, increment reg
 - Context switch, register (value 1) saved
 - T2 runs, loads counter 0 from memory
 - T2 increments register, stores to memory
 - T1 resumes, stores register value to counter
 - Counter value rewritten to 1 again
 - Final counter value is 1, expected value is 2

```
load counter → reg
reg = reg + 1
(context switch, save reg)

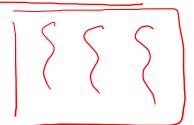
load counter → reg
reg = reg + 1
store reg → counter

(resume, restore reg)
store reg → counter
```

Race conditions, critical sections



- Incorrect execution of code due to concurrency is called race condition
 - Due to unfortunate timing of context switches, atomicity of data update violated
 - Not just counters, can happen with any data structures
 - User code cannot disable interrupts or context switches
- Race conditions happen when we have concurrent execution on shared data
 - Threads sharing common data in memory image
 - Processes in kernel mode sharing OS data structures
 - (Single-threaded processes in user mode do not share any data)
- We require <u>mutual exclusion</u> on some parts of code
 - Concurrent execution by multiple threads should not be permitted
- Parts of program that need to be executed with mutual exclusion for correct operation are called <u>critical sections</u>
 - Present in multi-threaded programs, OS code



Using locks

- Locks are special variables that provide mutual exclusion
 - Provided by threading libraries
 - Can call lock/acquire and unlock/release functions on a lock
- When a thread T1 acquires a lock, another thread T2 cannot acquire same lock
 - Execution of T2 stops at the lock statement
 - T2 can proceed only after T1 releases the lock
- Acquire lock → critical section → release lock ensures mutual exclusion in critical section

```
int counter;
pthread_mutex_t m
void start_fn() {
  for(int i=0; i < 1000; i++)
    pthread_mutex_lock(&m) —
    counter = counter + 1
    pthread_mutex_unlock(&m)
main() {
  counter = 0
  pthread_t t1, t2
  pthread_create(&t1).., start_fn,..)
  pthread_create(&t2, .., start_fn,..)
  pthread join(t1, ..)
  pthread_join(t2, ..)
  print counter
```

Implementing locks

- What is happening inside the lock/unlock functions? How are locks implemented?
- Example of incorrect lock implementation
 - Use bool isLocked to indicate lock status
 - To acquire lock, a thread waits until lock is free and then proceeds to acquire it

```
while(isLocked);
isLocked = true

CRITICAL SECTION

while(isLocked);
while(isLocked);
while(isLocked);
while(isLocked);
isLocked = false

CRITICAL SECTION

CRITICAL SECTION
```

```
bool isLocked = false
              void acquire_lock() {
                while(isLocked); //wait
              isLocked = true
              void release_lock() {
                 isLocked = false
while(isLocked);
(context switch, PC saved)
                                                    T2
                            while(isLocked);
                            isLocked = true
                            CRITICAL SECTION
(resumes execution)
isLocked = true
CRITICAL SECTION
```

Hardware atomic instructions

- Need a way to check a variable and set its value atomically
 - No context switch between checking lock variable to be free and setting it to be true
 - But user programs have no control over context switches
- Solution: use hardware atomic instructions
- Example: test-and-set sets value of variable and returns old value
- Simple lock can be implemented using test-and-set instruction
 - If test-and-set(isLocked, true) returns true, it means lock is held by someone, wait
 - If test-and-set(isLocked, true) returns false, lock was free and has been acquired
- Single CPU instruction is both checking lock to be free and setting it to be true atomically, cannot be interrupted in between

```
bool isLocked = false

void acquire_lock() {
   while(test-and-set(isLocked, true) == true); //wait
}
```

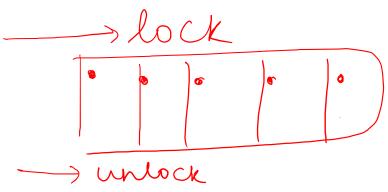
false true

Spinlock vs. sleeping mutex

while (...);

- Simple lock implementation seen here is a spinlock
 - If thread T1 has acquired lock, and thread T2 also wants lock, then T2 will keep spinning in a while loop till lock is free
- Another implementation option: thread can go to sleep (be blocked) while waiting for lock, saving CPU cycles
 - OS blocks waiting thread, context switch to another thread/process
 - Such locks are called (sleeping) mutex
- Threading libraries provide APIs for both spinlocks and sleeping mutex.
 - Better to use spinlock if locks are expected to be held for short time, avoid context switch overhead
 - Better to use sleeping mutex if critical sections are long

Guidelines for using locks



- When writing multithreaded programs, careful locking discipline
 - Protect each shared data structure with one lock
 - Locks can be coarse-grained (one big fat lock) or fine-grained (many smaller locks)
 - Any thread wanting to access shared data must acquire corresponding lock before access, release lock after access
- Good practice to acquire locks for both reading and writing data
 - Why locks for reading? We do not want to read incorrect data while another thread
 is concurrently updating the data
 - Some libraries provide separate locks for reading and writing, allowing multiple threads to concurrently read data if no other thread is writing
- If using third-party libraries in multi-threaded programs, check if the library is thread-safe
 - Thread-safe implementations work correctly with concurrent access

Summary

- In today's lecture:
 - Threads for concurrency and parallelism
 - Race conditions, critical sections
 - Locks: usage and implementation
 - Hardware atomic instructions
- Try to write simple multi-threaded programs, observe race conditions, and fix them using locks
 - Pthreads API is simple and easy to use