

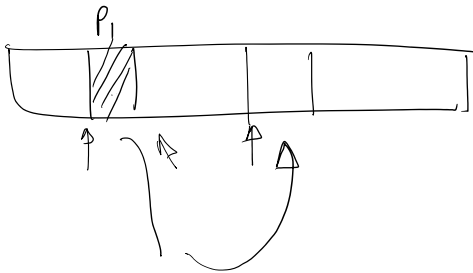
Lecture 16. Memory virtualization contd.

- design 0 : one-to-one v2p mapping
- design 1a. static relocation
- 1b. dynamic relocation (base + bound) regs.
- design 2. _____

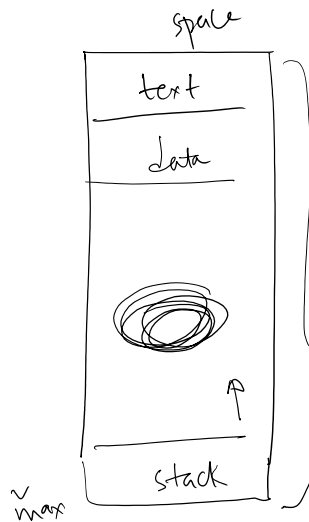
support the
address space
abstraction w/
an efficient
implementation
solⁿ.

* assumptions

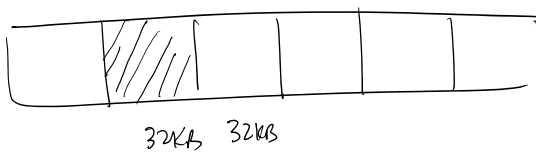
- VA size < PA size ✓
- all process have equal sizes ✓
- all processes get contiguous allocations ⊗ (virtual)



32-bit 4GB
16-bit: 4KB
32



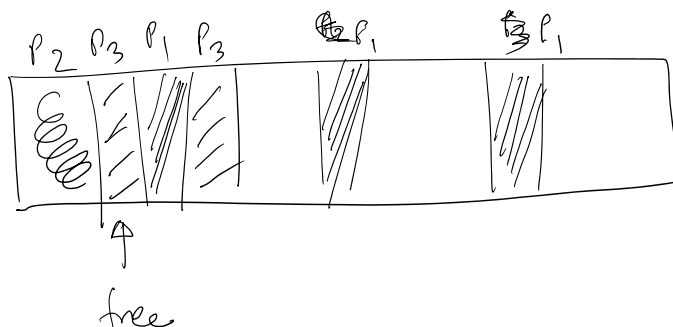
PA range



PA = (VA + base) — assumption that this address is valid & belongs to the process.

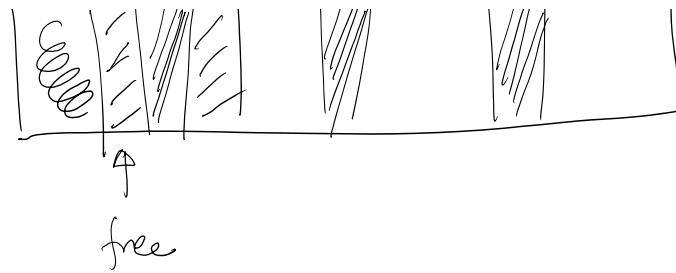
segmentation

PA range



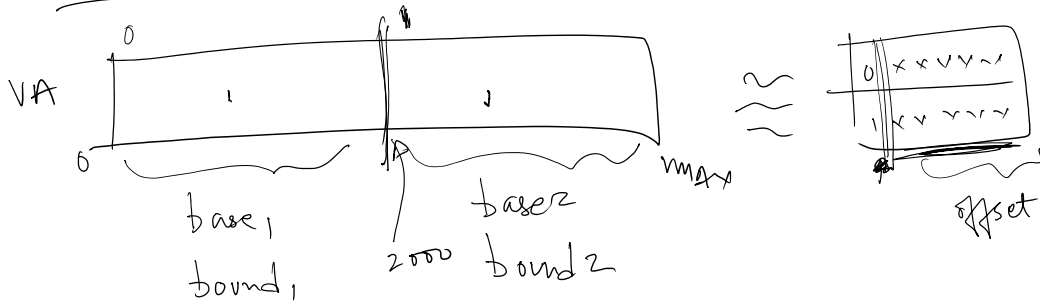
non-contiguous
imp.
for varying sized
programs!

range



imp. ^U
for varying sized
programs!

- use multiple base & bound regs.



$$PA = (VA + base) \sim \text{if } bound > VA$$

if $VA < bound1$

$$PA = VA + base1$$

else if $VA \leq bound2$

$$PA = VA + base2$$

X

Why, MMU

- needs to know which VA region
- know the base regs. & bound values.

$$VA = 2500$$



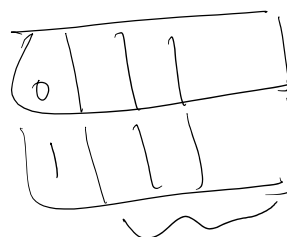
$$PA = \underline{1000} \quad ?$$

0 - 1999	VA1	b1 = 4000
<u>2000 - 3999</u>	VA2	b2 = 1000

simpler example.

mmu

+ lookup msb bit
+ select Base



4-bit



16 addresses



1 ← MSB

0

8 addr

8 addr

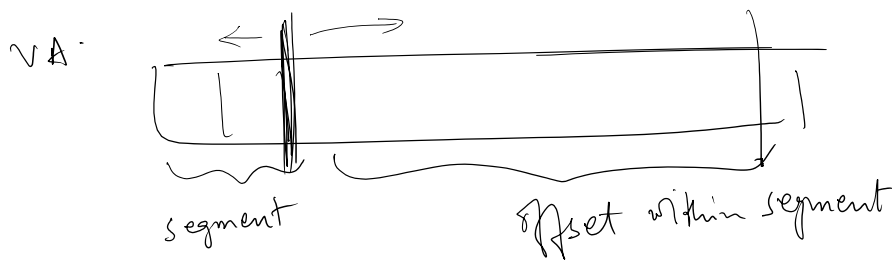
+ select Base
 + compute offset
 (base + offset)_r access for memory

segmentation

+ break / divide VA space into logical segments
 Continuous VA region

code segment
 data segment
 stack segment
 heap segment

} base & bound regs.



00 - CS
 01 - DS
 11 - SS
 10 - ES

choose a segment register

MMX

