Lecture 29 synchronization

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- spin locks, non-blocking locks (spinning), mutex
  - mutex → 0/1 condition non-spinning lock.

- condition variables
  - variables → used to index blocked processes
  - condition → decide block/runnable state of processes

- if (condition) // not favourable
      wait (variable)
      sleep

  if (work done)
      change condition
      ~~wakeup~~
      signal (variable)
      wakeup

```
mutex_lock (mutex * m)
{
    spinlock (m->s);
    while (m->L)
        sleep (m->id, m->s);
    m->L = 1;
    spin unlock (m->s);
}
```

```
mutex_unlock (mutex * m)
{
    spin lock (m->s);
    m->L = 0;
    wakeup (m->id);
    spin unlock (m->s);
}
```

```
struct mutex {
    int L;       // lock
    int id;      // variable
    spinlock s;
}
```

```
sleep (m->id, m->s) {
    add toqueue (m->id, currproc);      (looking xv6)
        ⇓
      state = BLOCKED
    spinunlock (m->s);
    scheduler ();   // get of the CPU
    spin lock (m->s);
}
```

```
wakeup (m->id)
{
    lock;
    remove from queue (m->id);
        ↓
      set state to READY
    unlock;
}
```

ptable.lock — serialize the PCB list / state

producer - consumer

bufsize = current size of produced elements.

```
producer () {
```

```
consumer () {
```

```
producer() {

    spinlock(S);

    bufsize++;

    wakeup(NOBUF);

    spinunlock(S);

}
```

```
consumer() {

    spinlock(S);

    while (if) (bufsize == 0)
        sleep(NOBUF, S);

    bufsize--;

    spinlock(S);

}
```