

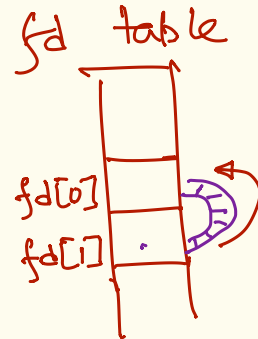
~ fork, exec, wait, open, close, read, write, lseek,
dup, dup2, pipe, getpid, getppid, waitpid, exit
signal, kill...

pipe

```
int fd[2];
```

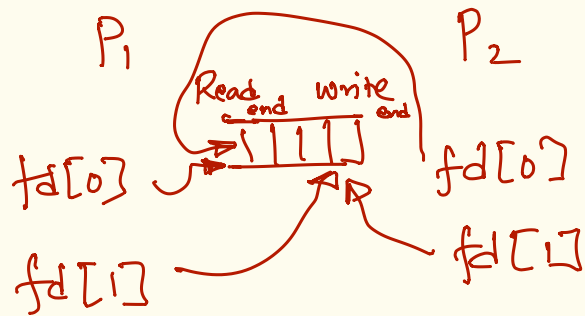
```
pipe(fd);
```

```
fork();
```



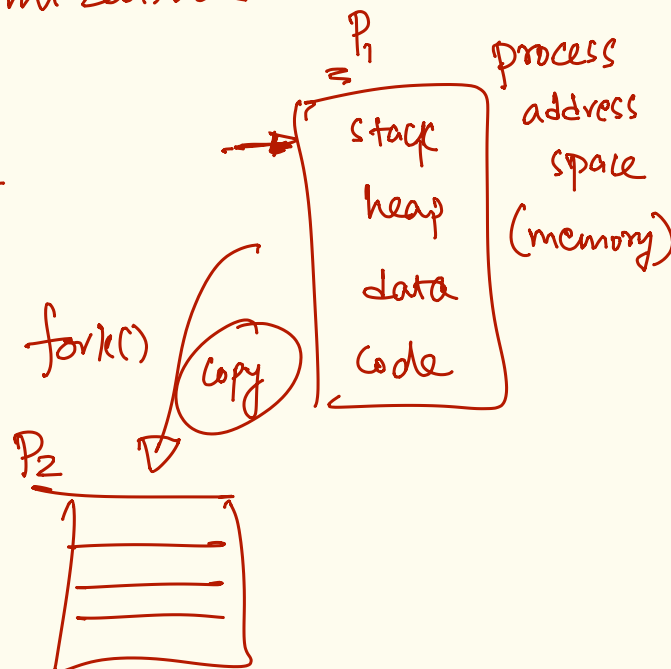
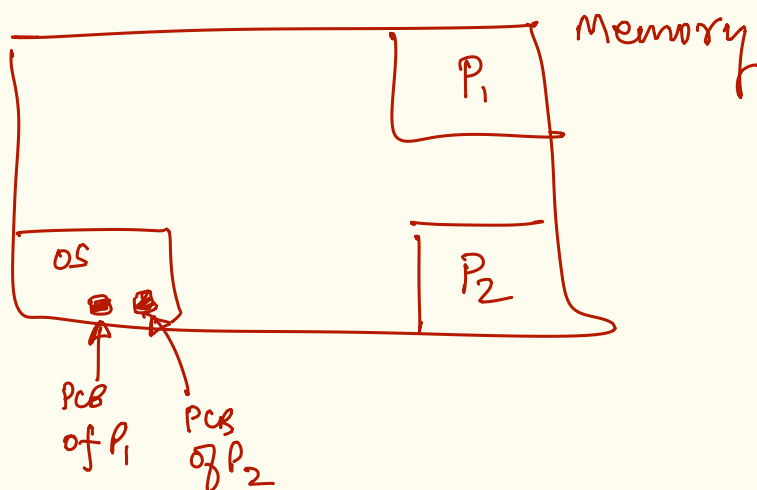
fd[0] ~ read end

fd[1] ~ write end



COW ~ copy-on-write.

~ fork/exec related optimization.



```
int a[1e7];
```

```
fork();
```

```
    P1 {  
    (*) a[0]++;  
    wait();  
    }
```

```
    P2 {  
    (*) a[0]++;  
    p = getpid();  
    a[p]++;  
    exit();  
    }
```

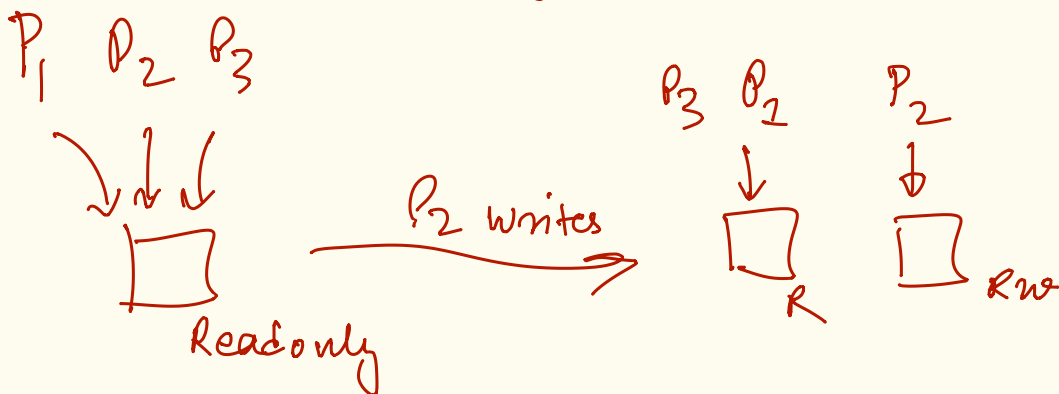
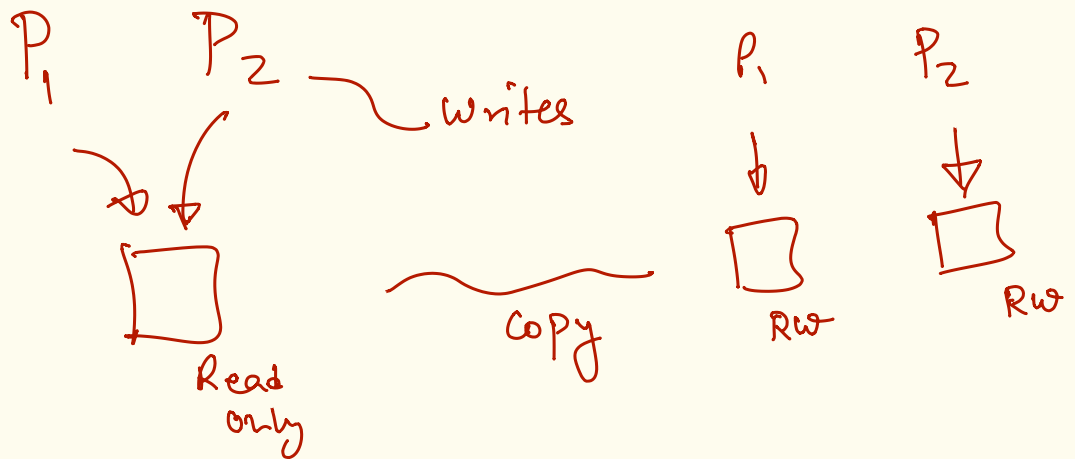
```
    mov eax, #mem  
    inc eax  
    mov #mem, eax
```

Cow

copy-on-write

~ share all memory regions on fork()

~ mark them read-only
on write to read-only region generates an interrupt (page fault)

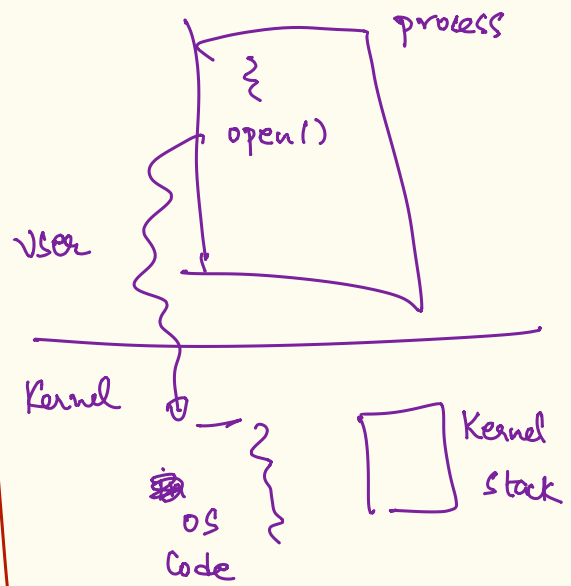
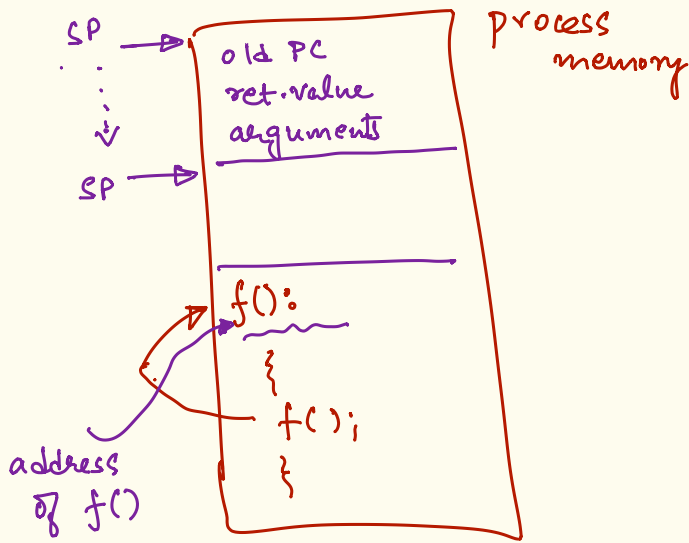


System calls

function calls

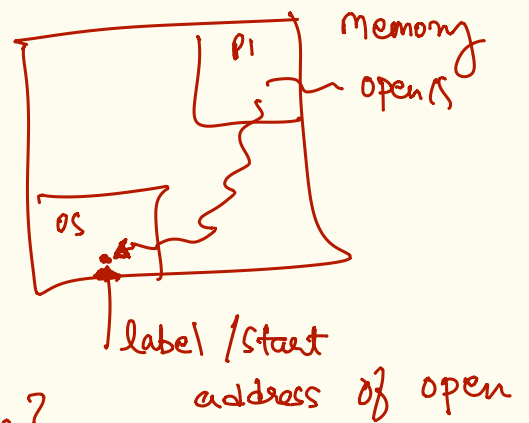
vs

system call



design of system calls

- how to invoke a system call?
- how to change privilege break?
- how to pass arguments & get return values?
- how to identify which system call?
- how to return from system call?
- how to handle context of calling process?



* Ans: Short ans: no ISA support $\Rightarrow$ no system call!

H/w assisted system call invocation:

① explicit s/w interrupt via an instruction

int 0x80 — x86 instruction
opcode ↗ ↖ argument (interrupt vector)

- switch CPU to PL=0
- saves context of user process on kernel stack
- switch to kernel stack
- jumps to an interrupt handler.