

the experiments story

motivate. formulation. design. build. deploy. measure. reason. report

Q — question
A — accuracy
R — reproducible
C — completeness

① question

② setup

③ modality

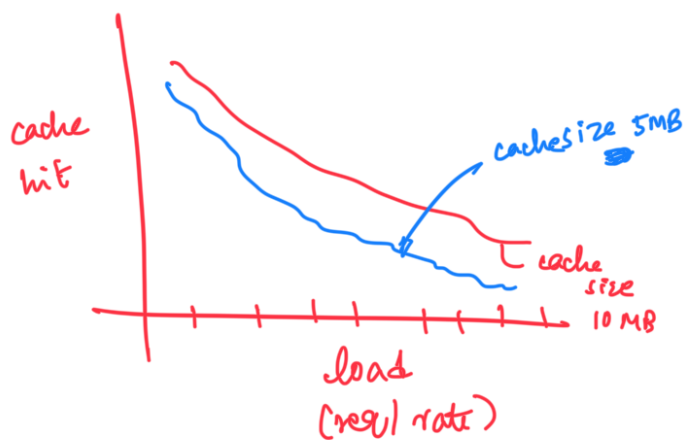
④ execution & reporting

⑧ setup

hardware
software
workloads

①
mimic/
representative
of "real"
conditions of
interest.

② reproducibility

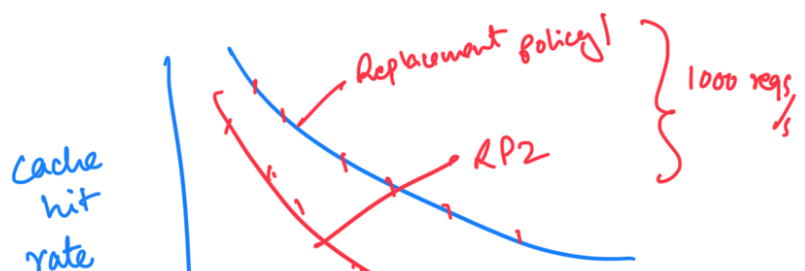
③ apples vs apples.caching system

- cache size

- cache replacement policy

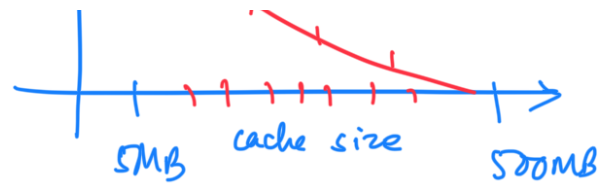
- object size distⁿ.- req. distⁿ.

- 10 blue to storage



③ modality

(how to setup the system for expⁿ).



(i) model

(ii) simulators

(iii) emulators

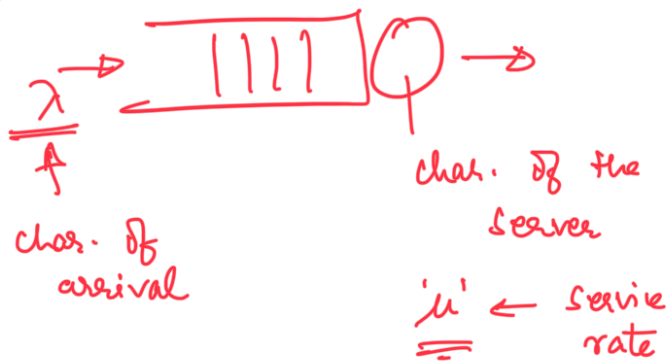
- analytical / theoretical representation of a system.

(iv) prototypes

(v) production systems.

- no physicality (program n/w)

eg: (i) queuing model



- expected probabilistic analysis

eg. what is expected queue length given λ & μ ?

(ii) setting up optimization formulations.

eg: LP — linear program

ILP — integer LP

objective fⁿ. min # servers for VMs

constraints.

$R_{ij} < C_{jk}$ = resource req. i of VMj should be less than capacity of resource

(iii) simulation

(ii) simulator

- ~ time / events management loop
- ~ keeping track of important system state.

on node K

- no "actual" work.

eg: webserver

- there need not be actual disk / web pages / HTTP responses

basic simulator loop

while (1) {

$e = \text{getNextEvent}(Q);$

$\text{processEvent}(e);$

}

dequeueing & possibly adding events to the queue
↓
ordered

is a queue of time-ordered items
event requests

is system logic + update to system state.

$\text{addEvent}(e, Q);$
ordered addition



this based on a model profile

lookup table.

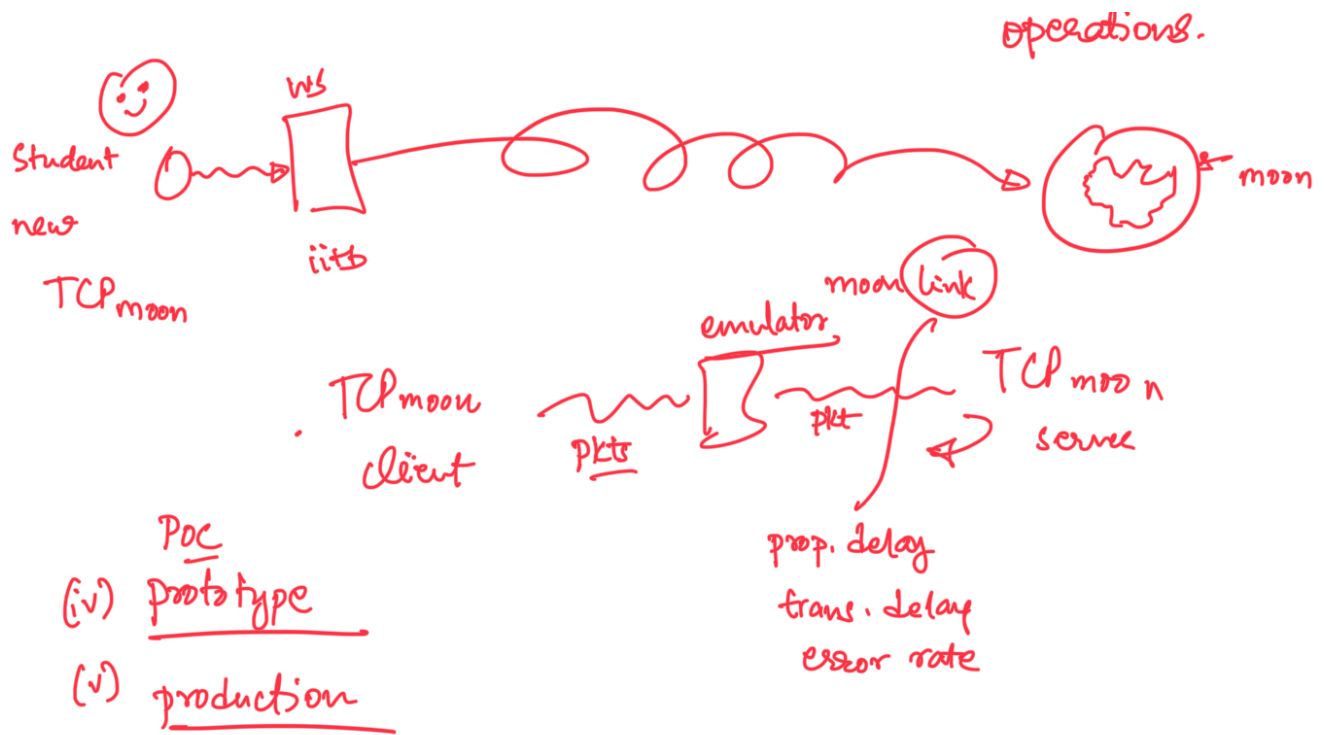
else {
cachemiss++;
 $t = \text{readDisk}();$
 $\text{addEvent}(e', Q, t);$
}

insert cache(e_0);

object
current time
service-time of disk 10
system state maintenance

(iii) emulators

~ emulate system behaviour via a set of different



② execution / types of expⁿ

~ types — correctness, comparison, causality,

~ independent parameters vs dependent variables
metrics



④ only one parameter should change across experiments.

instrumentation overheads.

~ overheads to measure system behaviours.

~ cannot overtly influence the system itself.



④ observations & inferences

- go back to QARC

- if question not answered or needs further analysis

go back to step 0.

⑤ representation

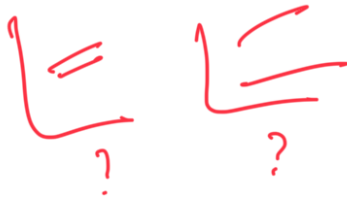
~ tables, figures, graphs

Cdf

pdf

Scatter plot.

3D



always start at $y=0$

