

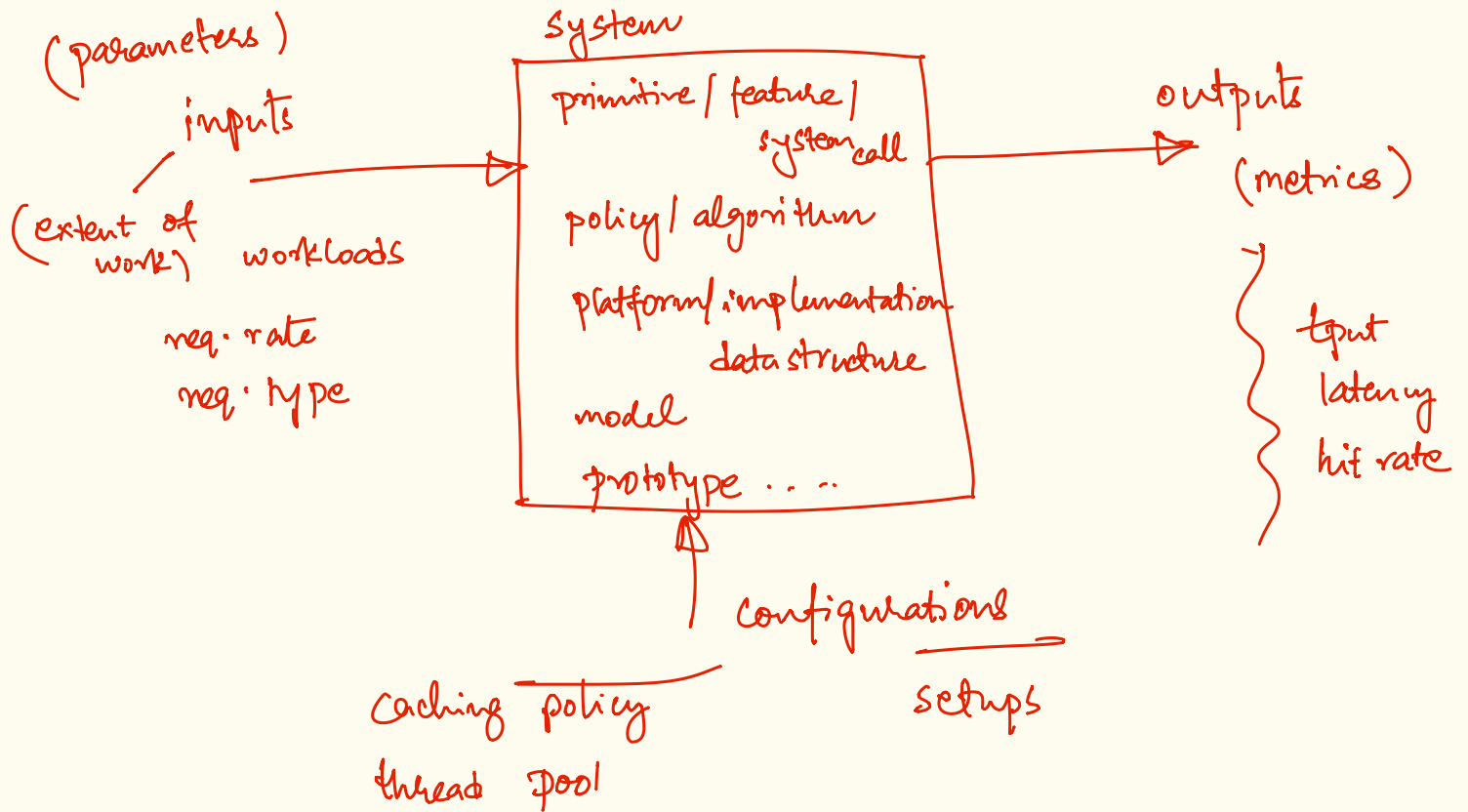
CS 6 95

the experiments story

motivation. formulation. design. build. deploy.

	<u>measure</u>	<u>infer</u>	report.
	observe	reason	repeat

└───────────┘
empirical action



⑧ meta-point / (guiding principles for an experiment)

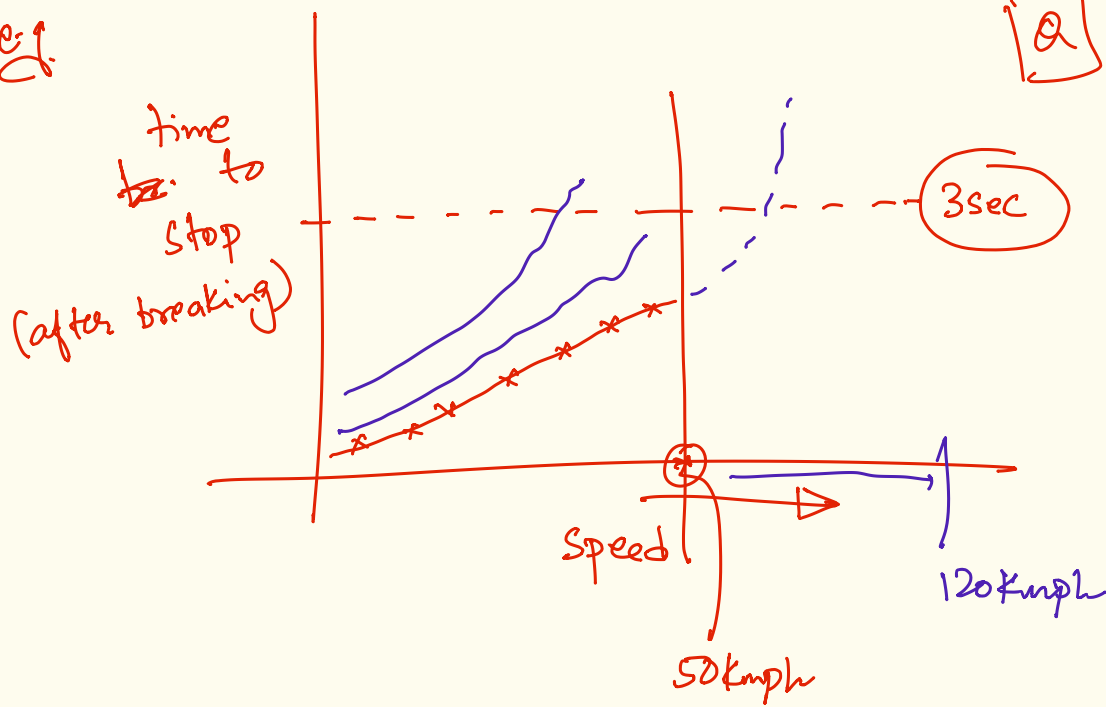
Q ~ question ~ no question, no experiment!
why is an experiment needed?

$A \sim$ accuracy $\leadsto$ infer ~~the~~ correct findings

$R \sim$ repeatability $\rightarrow$ can redo experiments for validation & comparison.

$C \sim$ completeness $\sim$ coverage of the parameter space

eg.



Q

does a vehicle stop in 3 seconds after breaking?

① types of experiments / questions?

- establish motivation
- hypothesis testing / correctness
- performance - cost tradeoff study
- sensitivity analysis / performance characterization
- comparison
- best case - worst case scenarios.

②

setup

hardware

software

workloads

solⁿ. setup, config & inputs

~ system : "realistic" / ~~realistic~~ representative
Setup

~ workloads ~ how to generate work for the system?

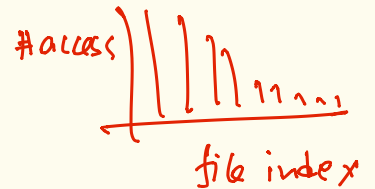
(i) synthetic benchmark

- custom program to generate work based on ~~input~~ configs. } probability distribution of the system.

- e.g: read:write ratio
object size distribution



- iorzone, dbench, rubis, fio, ...

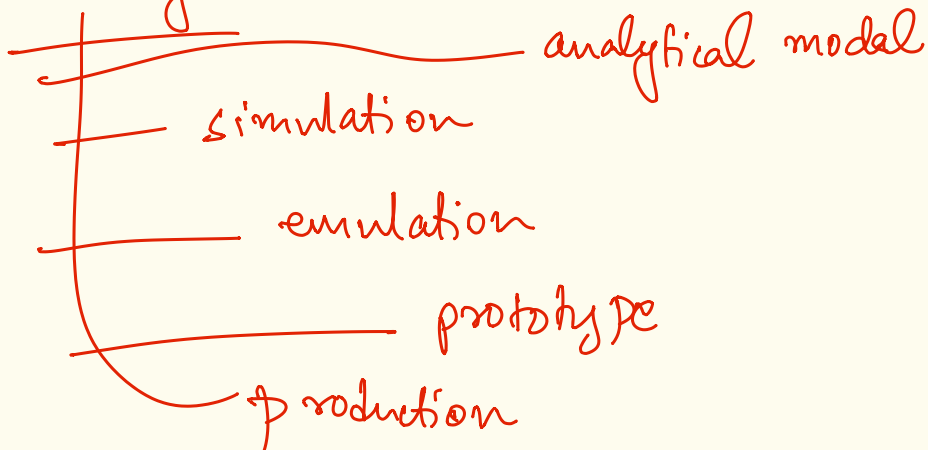


(ii) trace driven logging & replay
record

(iii) real workloads on production systems.

(2) Execution of experiments

(i) modality → how will the system be implemented?



~ analytical model

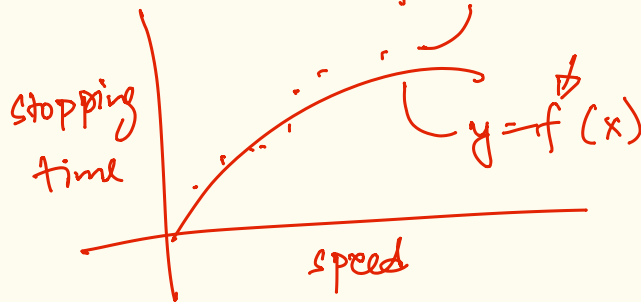
+ mathematical representation of the main components of the solⁿ.

- e.g: queuing model



$$y = f(x)$$

↑
 f^n encodes behavior of system



(ii) simulation ~ all s/w solⁿ.

~ objects / interactions are not "real" components.

e.g: cache simulator

- no objects created / stored for caching.

- only manipulate "state" of cache (size, object list)

- no malloc / write to disk etc.

- process / procedure is true

e.g. eviction policy

~ do not account for real interactions

+ impⁿ. envs

~ non-deterministic parallelism

trgs:

+ quick / main-comp^{on}te analysis

+ system is complicated / large

basic loop of a simulator

~ priority queue ~ prioritized by the time an event occurs

while (1) {

$e = \text{getNextEvent}(Q);$

$\text{processEvent}(e, Q);$

}

$\text{addEvent}(e, Q) \{$

$t = \text{timeEvent}(e);$

$\text{addQueue}(e, t, Q);$

}

on cache miss

read object from disk

- simulate disk access latency

~ e : disk read completion

t : time from disk

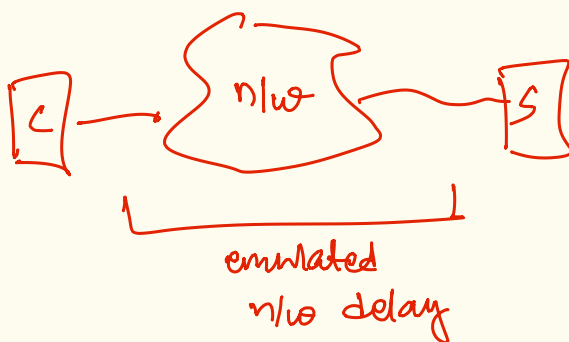
↑

from a model

$$y = f(x)$$

(ii) emulation

~ emulating behaviour of some components of a system.



(iii) prototype

(iv) production

(b) process of experimentation

independent
(parameters)

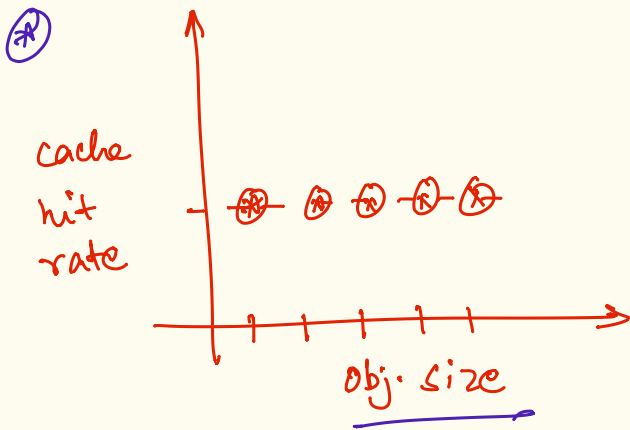
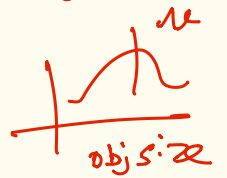
vs

dependent
(metrics)

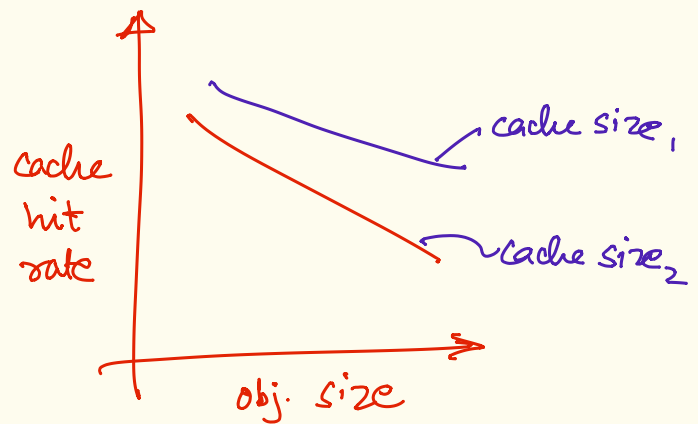
varied

measured

~ across experiments only (single) the parameter under study should be changed.



~ cache size was also
changed per exp^r.
~ object size



cache size
is constant

⑧ workload pattern/sequence has to
be identical / expectation.

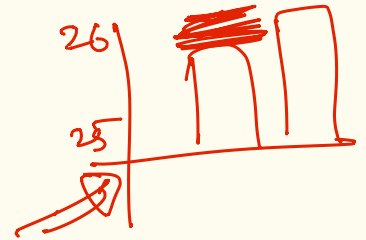
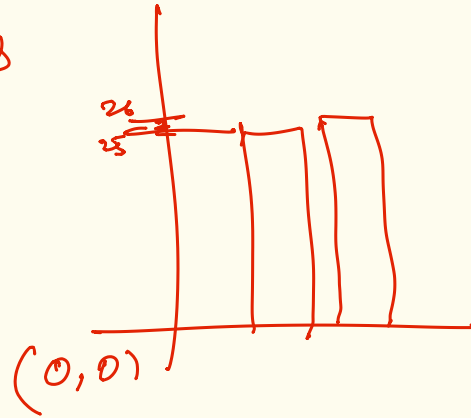
⑧ instrumentation overheads.

~ does measurement affect the system
behaviour

④

observations & inferences via
representations

├ tables
└ graphs



revisit QARC & repeat.