

A Comparison of Some Methods for Direct 2D Reconstruction from Discrete Projections

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Introduction

- Tomographic acquisitions can be described as mathematical transforms
- Direct reconstruction methods aim to compute an accurate inverse for such transforms
- **Aim:** To obtain a high-fidelity image of the original object from a limited set of measurements by applying a suitable inversion technique

Experiment

- Comparison of three existing direct inversion techniques for sets of discrete projections:
 - Radon inverse-Radon
 - Least squared error method
 - Filtered back-projection for Mojette inversion



Original images used for testing reconstruction algorithms

Radon inverse-Radon Reconstruction

- Radon projections taken along set of angles
- Each angle equals $\tan^{-1}(\frac{p}{q})$ corresponding to the discrete angle (p, q) ; p and q being co-prime integers
- Reconstruction using Shepp-Logan filtered back-projection



Reconstruction by Radon i-Radon technique

Least Squared Error Reconstruction

- The Mojette back-projected image m and the original image im are related by [1]:

$$m_{p,q}(x, y) = im(x, y) * h_{p,q}(x, y)$$

* denotes convolution operator

– $h_{p,q}$: the PSF corresponding to the Mojette angle set (p, q) along which the projections are taken

- In frequency domain: $M(u, v) = IM(u, v) \cdot H(u, v)$
- $H(u, v)$ is estimated using a least squared error technique
- **Reconstruction Process:** Direct deconvolution of $H(u, v)$ with the Mojette back-projected image



Reconstruction by least squared error technique

Filtered Back-Projection Reconstruction

- $H_{p,q}(u, v)$ - regularized with a weighted filter
- **Reconstruction Process:** Direct deconvolution of the filtered Point Spread Function (PSF) with the Mojette back-projected image
- Equivalent to regularizing the back-projected image in the frequency domain and then taking the inverse Fourier transform
- Extremely low values (below a fixed threshold) in the FFT of the filtered PSF are replaced by the mean evaluated over neighborhoods of fixed size



Reconstruction by filtered back-projection technique

- This method performs better than the first two

Filtration

- The PSF filtration [2]

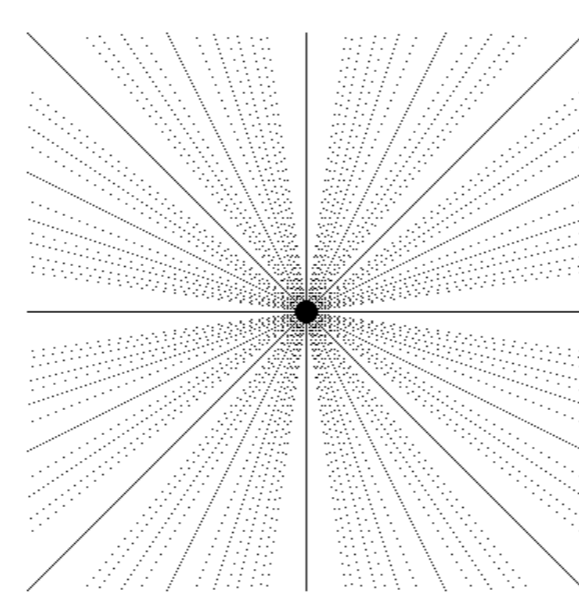
$$PSF_{\text{modified}} = \begin{cases} PSF \cdot wnp & K \geq 1 \\ PSF \cdot tnp & K < 1 \end{cases}$$

$$wnp = (wp * wn) * (D * D)$$

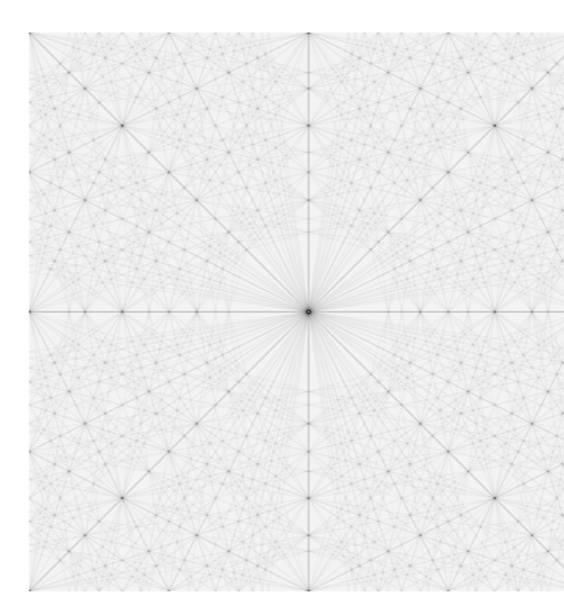
$$tnp = (wp * wn)$$

. \times denotes 'point-to-point' multiplication
* denotes 'cross-correlation'

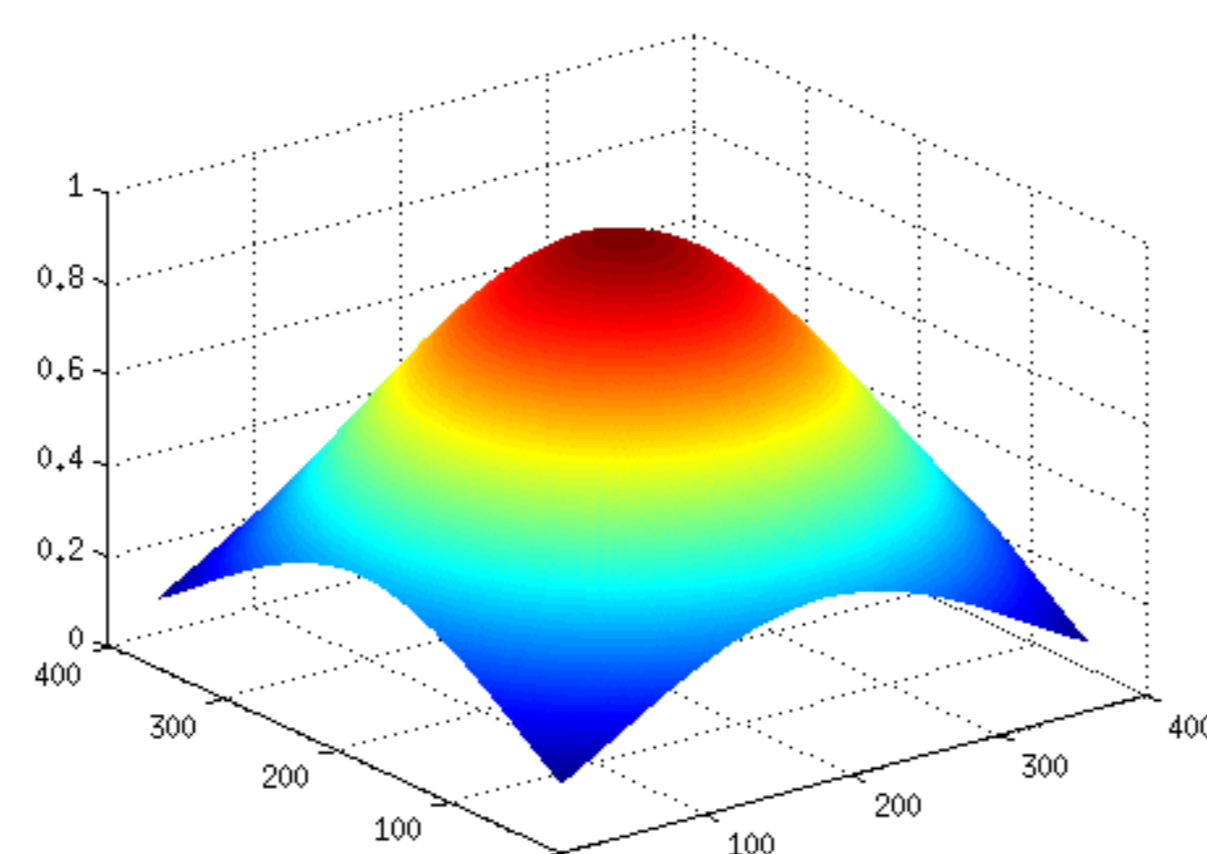
- wnp (the filter) is given by cross-correlation of the back-projected images wp and wn
- wp is given by back-projection of delta image along the set of angles that was used while taking measurements
- wn is given by back-projection of delta image along complementary set of angles
- D denotes the circular region of interest
- $K = k/N$; k being the Katz number given by: $k = 1 + \max(\sum_i |p_i|, \sum_i |q_i|)$ [3] and $N \times N$ being the dimension of the image.
- The Katz number is dependent on:
 - the number of views
 - the specific set of angles (p, q) chosen.



(a)



(b)



(c)

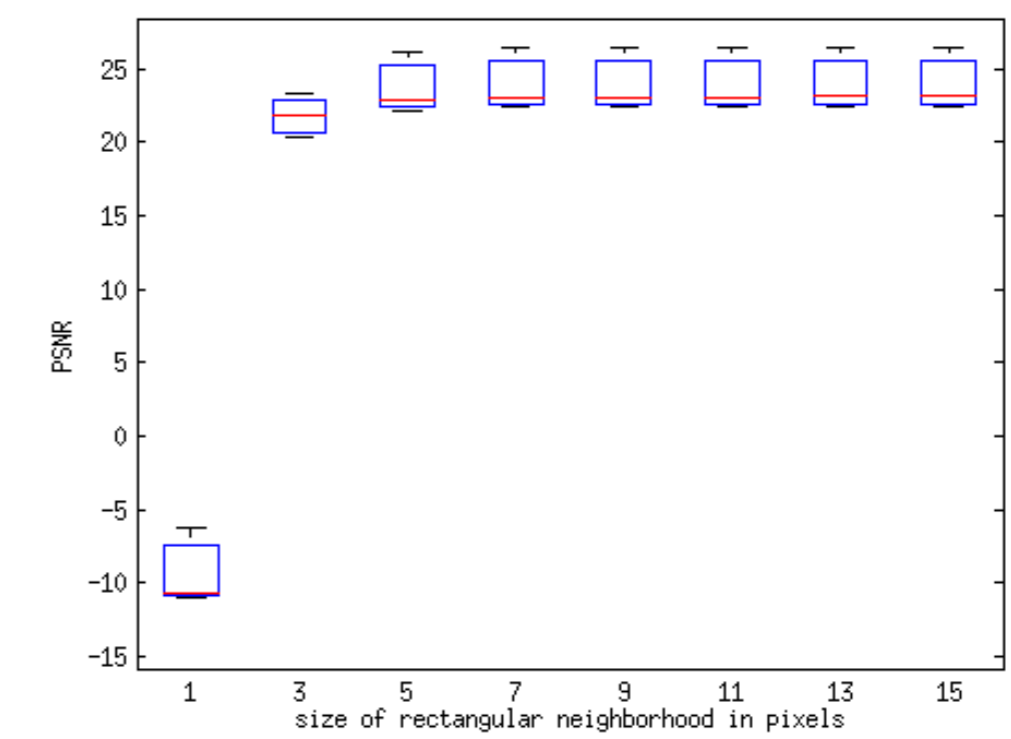
(a) Raw PSF (b) FFT of raw PSF (c) Filter

Analysis

- We observed the quality of reconstruction for different values of threshold

Analysis

- The sensitivity of image reconstructions to the selected value of the threshold is quite weak over a wide range of image sizes and Katz values.



Quality of reconstruction as the size of neighborhood over which mean is evaluated is varied

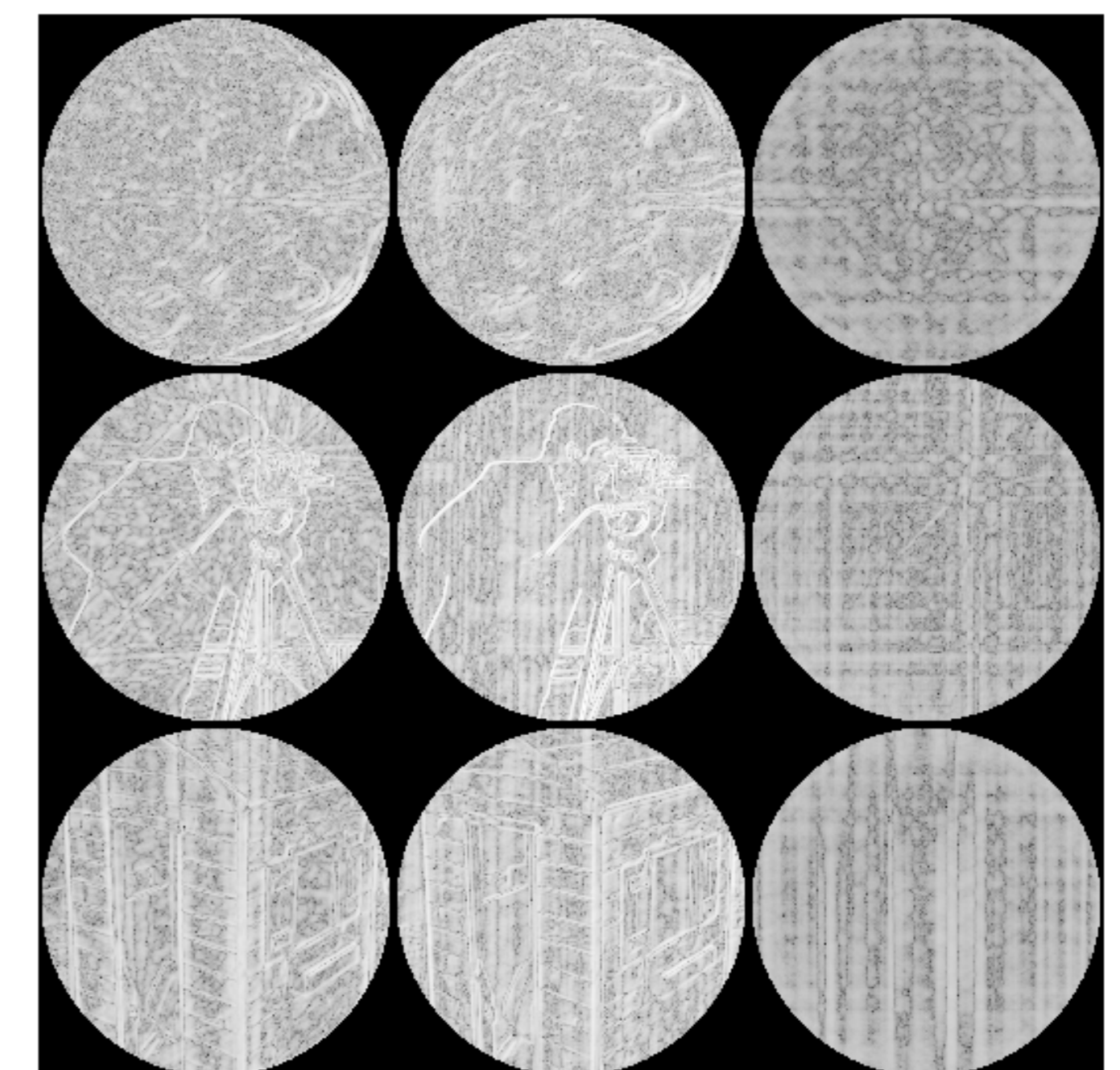
Katz ratio	Image size: 179x179			Image size: 89x89			Image size: 43x43		
	# shortest angles	Peak PSNR	fval	# shortest angles	Peak PSNR	fval	# shortest angles	Peak PSNR	fval
0.46	33	16.6	13	21	18.13	8	13	17.65	8
0.7	44	20.52	16	28	21.36	10	17	20.12	7
0.88	52	22.39	15	32	22.26	11	20	22.2	8
1.10	60	23.58	14	38	23.63	11	24	23.36	7
1.30	64	24.24	15	42	24.69	11	25	24.34	8
1.75	81	26.51	13	50	26.75	10	31	26.44	9

Table 1: Variation of optimal threshold (fval) with image size and Katz ratio

Comparison and Inferences

- The reconstruction errors in filtered back-projection method are least dependent on the image structure and orientation

Method 1 Method 2 Method 3



Absolute error (in log scale) on applying different reconstruction techniques using the shortest 200 projection angles

- The optimal threshold is slightly dependent on image size [larger sized PSF \Rightarrow higher frequency content \Rightarrow requirement of relatively higher threshold]
- **Future Work:** Modify the filter such that there is no need for a final threshold

References

- [1] Guédon, J.: The Mojette Transform: Theory and Applications. ISTE, Wiley (2009)
- [2] Svalbe, I., Kingston, A., Normand, N., Der Sarkissian, H.: Back-projection filtration inversion of discrete projections. In Barucci, E., Frosini, A., Rinaldi, S., eds.: Discrete Geometry for Computer Imagery. Volume 8668 of LNCS. (2014) 238–249
- [3] Katz, M.: Questions of Uniqueness and Resolution in Reconstruction from Projections. Volume 26 of Lecture Notes in Biomathematics. (1978)