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Surfaces: Tensor Products

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Polynomials in 2 variables

Let $P^{m,n}[u, v]$ denote the vector space of all polynomials of degree at most m in u and n in v . Thus, for example,

$$3u^2v - v^3 \in P^{2,3}[u, v] \subset P^{3,3}[u, v]$$

The dimension of $P^{m,n}[u, v]$ is obviously $(m + 1)(n + 1)$ and the [Taylor basis](#) for it is the set:

$$\{u^i v^j | 0 \leq i \leq m, 0 \leq j \leq n\}$$

Just as polynomials in one variable served us to parametrize curves, these will serve us to parametrize surfaces.

Tensor-Product Bases

Actually, if $B = \{b_0(u), \dots, b_m(u)\}$ is a basis for $P^m[u]$ and $C = \{c_0(v), \dots, c_n(v)\}$ is a basis for $P^n[v]$ then:

$$B \otimes C = \{b_i(u)c_j(v) | 0 \leq i \leq m, 0 \leq j \leq n\}$$

is a basis for $P^{m,n}[u, v]$.

Question : Show that elements of $B \otimes C$ are linearly independent. Suppose that (as polynomials):

$$\sum_{i=0}^m \sum_{j=0}^n \alpha_{ij} b_i(u) c_j(v) = 0$$

Whence, for every u_0 , we construct the polynomial:

$$p(u_0, v) = \sum_{j=0}^n \left(\sum_{i=0}^m \alpha_{ij} b_i(u_0) \right) c_j(v)$$

We see that $p(u_0, v) = 0$ for all v , whence *every* coefficient of $p(u_0, v)$ must be zero. In other words, for all j and u_0 ,

$$\sum_{i=0}^m \alpha_{ij} b_i(u_0) = 0$$

Since, b_i 's are linearly independent, we are forced to conclude that $\alpha_{ij} = 0$ for all i and j .

□

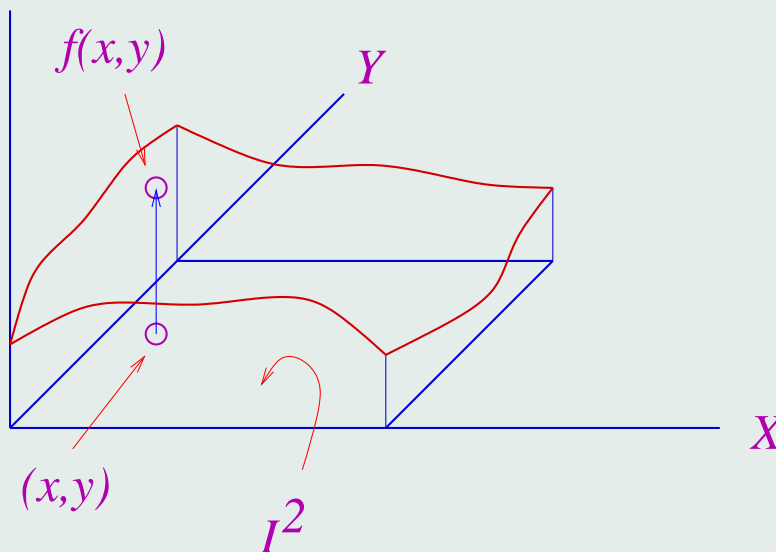
In particular we have the: **Bernstein Basis:**

$$\left\{ \binom{m}{i} u^i (1-u)^{m-i} \binom{n}{j} v^j (1-v)^{n-j} \mid 0 \leq i \leq m, 0 \leq j \leq n \right\}$$

We denote the typical basis element by $B_i^m(u) B_j^n(v)$.

Functions and the Approximation Problem

I will denote the interval $[0, 1]$ and I^2 the unit square $[0, 1] \times [0, 1]$. Let $f : I^2 \rightarrow \mathbb{R}$ be a function on the unit square.



Is there a polynomial approximation to f ?

The Bernstein-Weierstrass Approximation Theorem

Fix m and n , and form the data

$$S = \{f_{ij} = f(\frac{i}{m}, \frac{j}{n}) | 0 \leq i \leq m, 0 \leq j \leq n\}$$

We define the **Bernstein Approximation**

$$B^{m,n}(f)(u, v) = \sum_i \sum_j f_{ij} B_i^m(u) B_j^n(v)$$

Theorem: Let f be a function on I^2 , and let $\epsilon > 0$. Then there are m, n such that $|f(u, v) - B^{m,n}(f)(u, v)| < \epsilon$ for all $(u, v) \in I^2$.

Thus the 1-d situation has a complete 2-d analogue.

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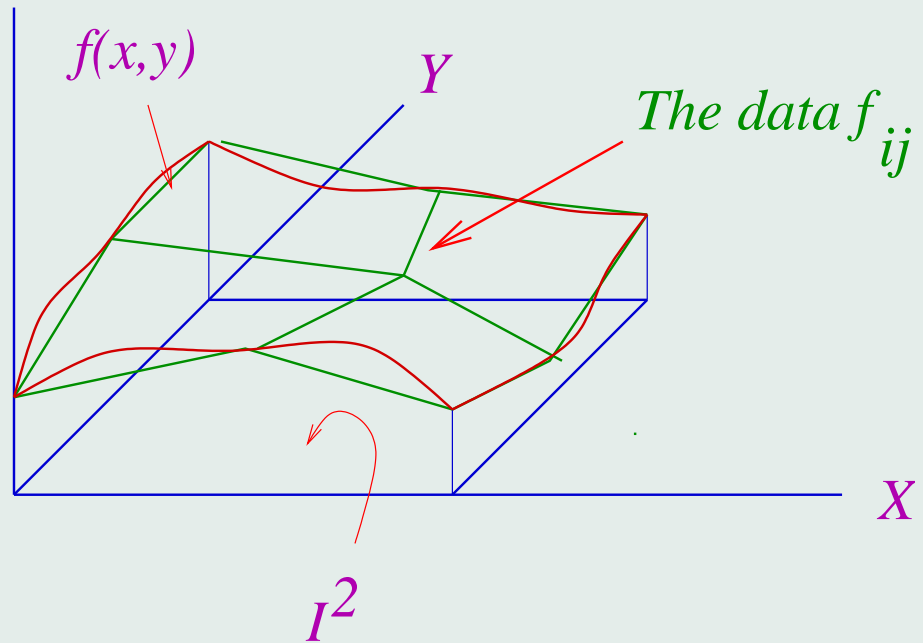
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The Picture



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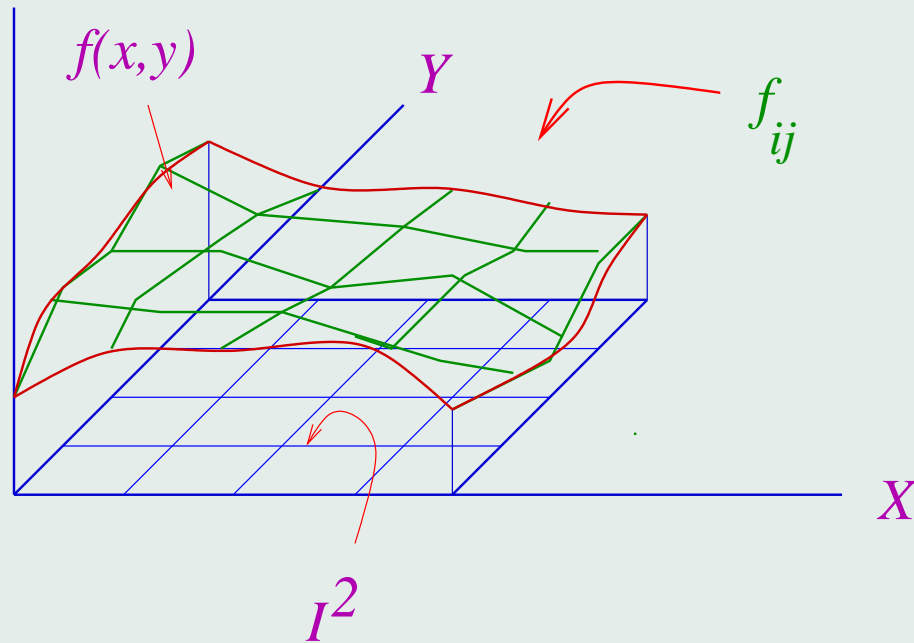
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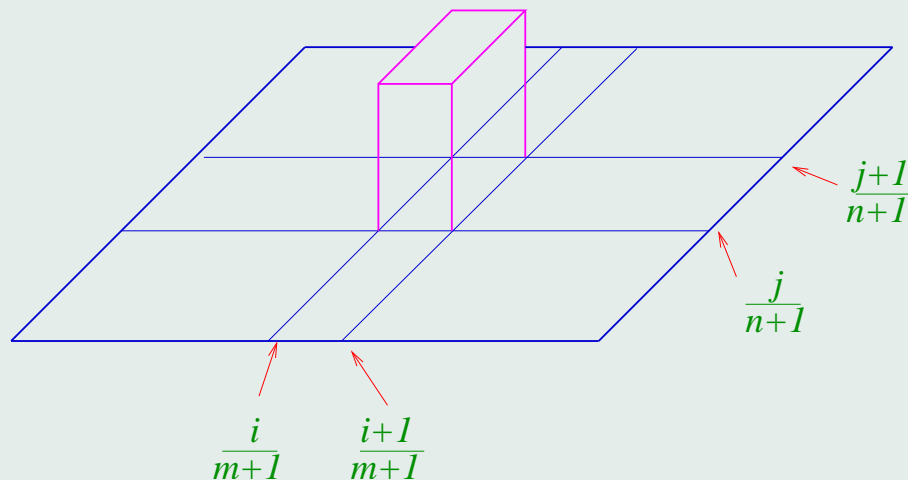
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The Finer Picture



The Unit Step

As before it is convenient to associate $B_i^m(u)B_j^n(v)$ with the 2-dimensional unit step function below. The ‘greville abscissa’ is obviously $(\frac{i}{m}, \frac{j}{n})$ which occurs within the support of the step.



As expected
$$\int_0^1 \int_0^1 B_i^m(u) B_j^n(v) du dv = \frac{1}{(m+1)(n+1)}.$$

The Control Polygon

We will now discard the function f .

Let S be an $m \times n$ matrix (in C++ notation, i.e., $[0 \dots m][0 \dots n]$) with entries in \mathbb{R} (or \mathbb{R}^3).

S is called the **Control Polygon**.

We define $S(u, v)$ as:

$$S(u, v) = \sum_i \sum_j S[i, j] B_i^m(u) B_j^n(v)$$

S will be called the **tensor-product** surface for the given control polygon.

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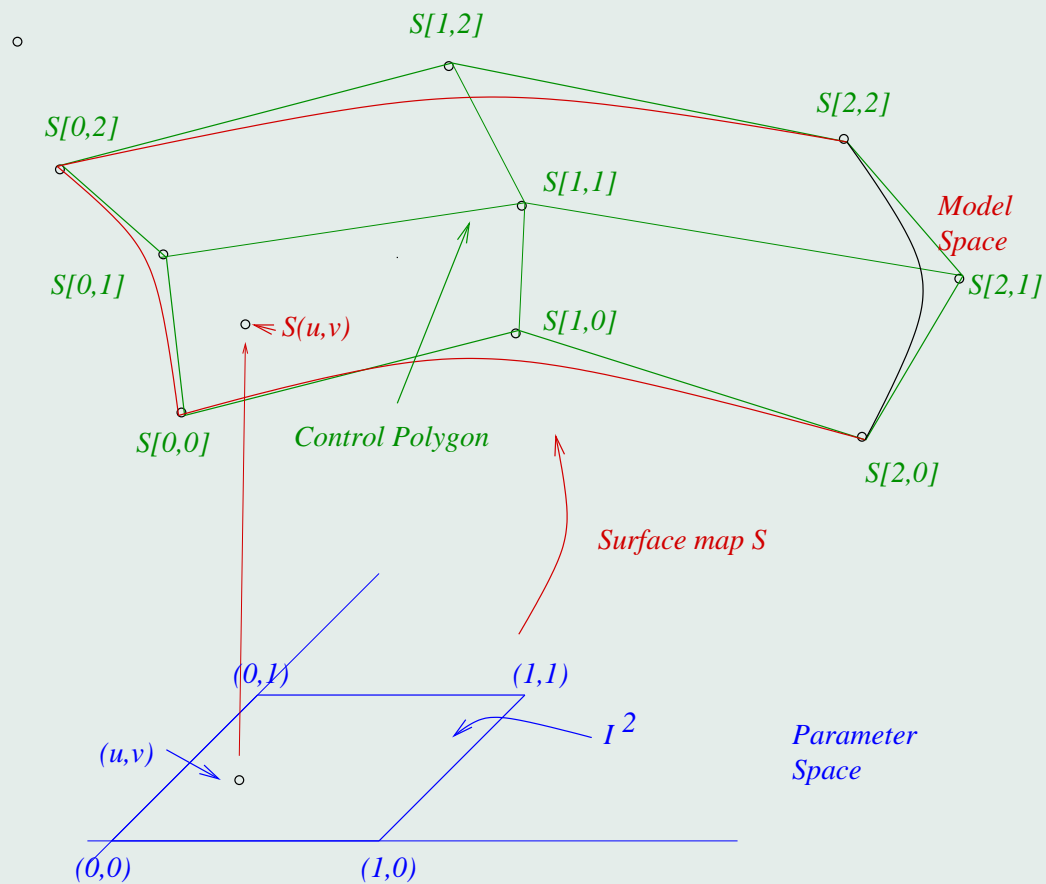
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An example



Some Observations

$$S(u, v) = \sum_i \sum_j S[i, j] B_i^m(u) B_j^n(v)$$

Lets evaluate $S(0, 0)$. Since $B_i^m(0) = 0$ unless $i = 0$ and $B_j^n(0) = 0$ unless $j = 0$, we have $S(0, 0) = S[0, 0]$. Similarly, we have the other ‘corner points’. Thus:

$$\begin{array}{lcl} S(0, 0) & = & S[0, 0] \\ S(1, 0) & = & S[m, 0] \\ S(0, 1) & = & S[0, n] \\ S(1, 1) & = & S[m, n] \end{array}$$

Boundary Curves

Next, let's look at $S(u, 0)$, which is the image of a boundary line of I^2 . Again, since on this curve $v = 0$, we have $B_j^n(0) = 0$ for $j \neq 0$. Thus the sum reduces to:

$$S(u, 0) = \sum_{i=0}^m S[i, 0] B_i^m(u)$$

This is clearly the **bezier curve** corresponding to the **first column** of S as its control points.

In general, we have:

$$\begin{array}{rcl} S(u, 0) & = & \sum_{i=0}^m S[i, 0] B_i^m(u) \\ S(u, 1) & = & \sum_{i=0}^m S[i, n] B_i^m(u) \\ S(0, v) & = & \sum_{j=0}^n S[0, j] B_j^n(v) \\ S(1, v) & = & \sum_{j=0}^n S[m, j] B_j^n(v) \end{array}$$

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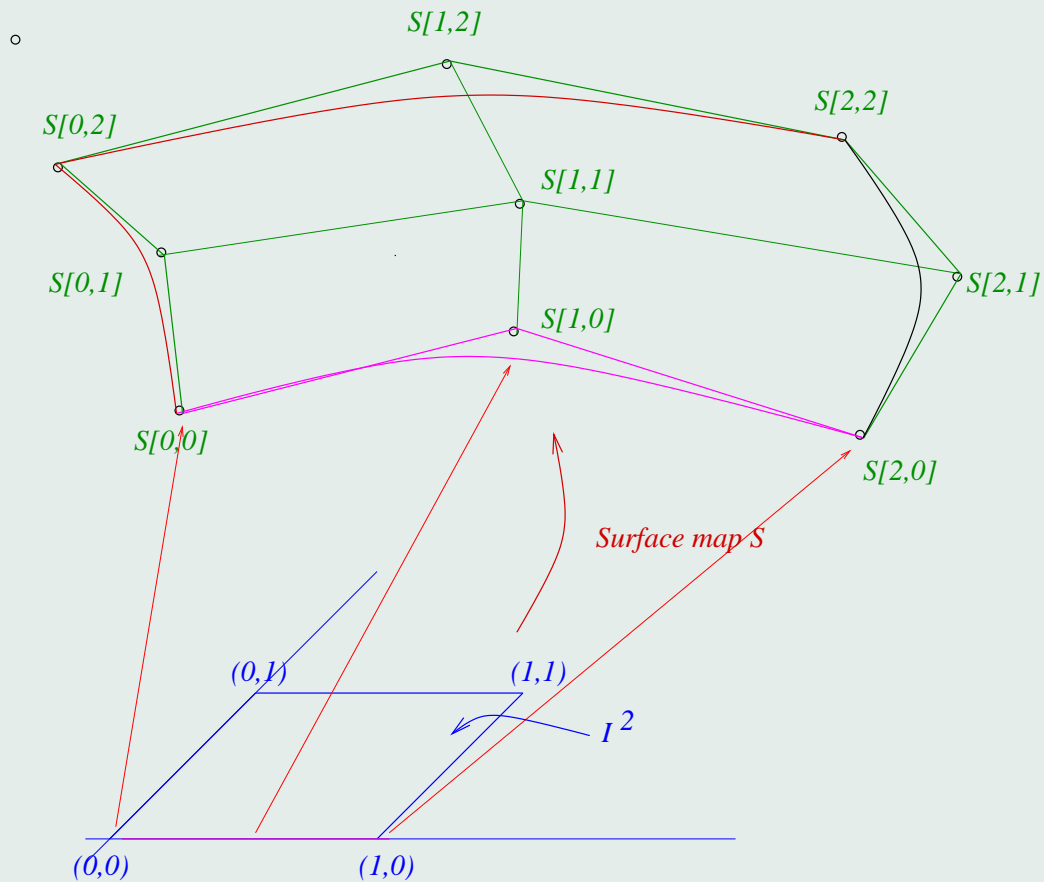
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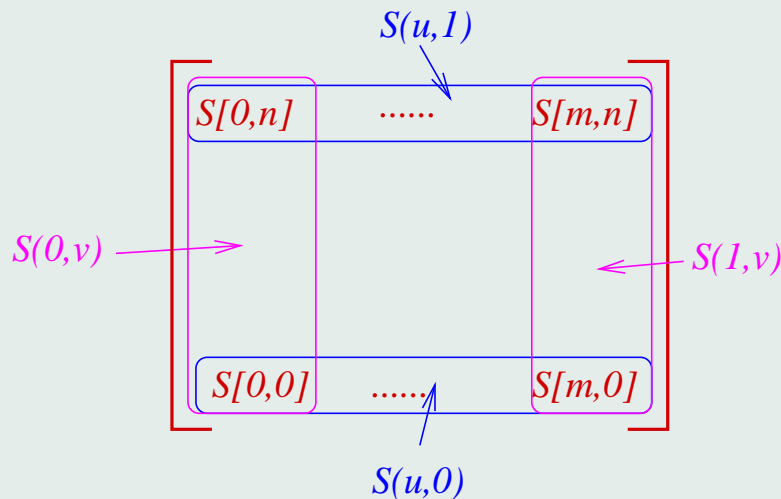
Pictorially



And Schematically

In terms of the control matrix, perhaps it is useful to use the *french notation* and number rows and columns from the bottom left corner. Then, we have:

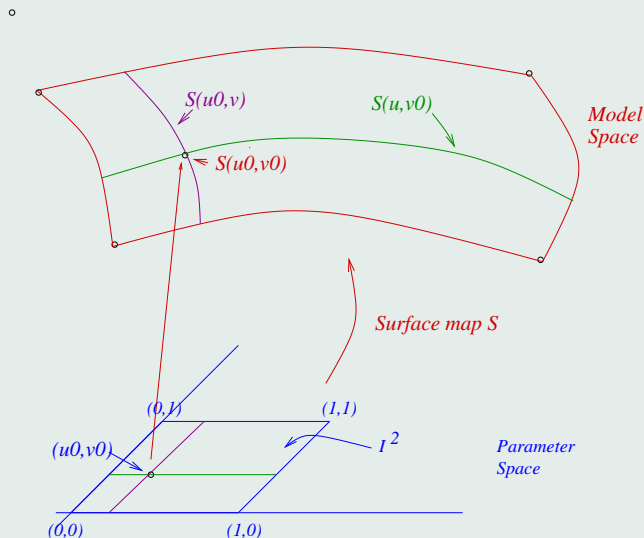
The Control Matrix S



Iso-parametric Lines

But what about general $S(u_0, v)$ for a fixed u_0 and $v \in [0, 1]$? Or $S[u, v_0]$ for a fixed v_0 but u ranging over $[0, 1]$?

These curves (in the model space) are called **iso-parametric** lines. Thus $S[u_0, v]$ is the iso-parametric line for $u = u_0$.



Iso-parametric Lines contd.

Lets evaluate $S(u_0, v)$. Re-arranging the sum $S(u, v)$, we see that:

$$S(u_0, v) = \sum_{j=0}^n \left[\sum_{i=0}^m S[i, j] B_i^m(u_0) \right] B_j^n(v)$$

We call $\sum_{i=0}^m S[i, j] B_i^m(u_0)$ as $S[u_0, j]$ and observe that $S(u_0, v)$ is a **bezier curve with control points $[S[u_0, 0], S[u_0, 1], \dots, S[u_0, n]]$.**

Also, note that *each* of these control points $S[u_0, j]$ is itself moving on a bezier curve parametrized by u .

Perhaps, the matrix notation is more convenient to observe this. We see that:

$$S(u, v) = [B_n^n(v), \dots, B_0^n(v)] \begin{bmatrix} S[0, n] & \dots & S[m, n] \\ \vdots & & \vdots \\ S[0, 0] & \dots & S[m, 0] \end{bmatrix} \begin{bmatrix} B_0^m(u) \\ \vdots \\ B_m^m(u) \end{bmatrix}$$

This may be consicely written as $S(u, v) = B(v)SB(u)^T$. Consequently, forming the product as $S(u, v) = B(v)(SB(u)^T)$, we see that:

$$S(u_0, v) == [B_n^n(v), \dots, B_0^n(v)] \begin{bmatrix} S[u_0, n] \\ \vdots \\ S[u_0, 0] \end{bmatrix}$$

Also note that $\sum_i \sum_j B_i^m(u) B_j^n(v) = 1$ and thus $S(u, v)$ is a **convex combination** of the entries of S .

End Tangents and Normals

Given a map $S : I^2 \rightarrow \mathbb{R}^3$ as we have already determined the boundary $S(0, v)$, $S(u, 0)$, and so on. Other important data is the first-order data, viz., the tangents.

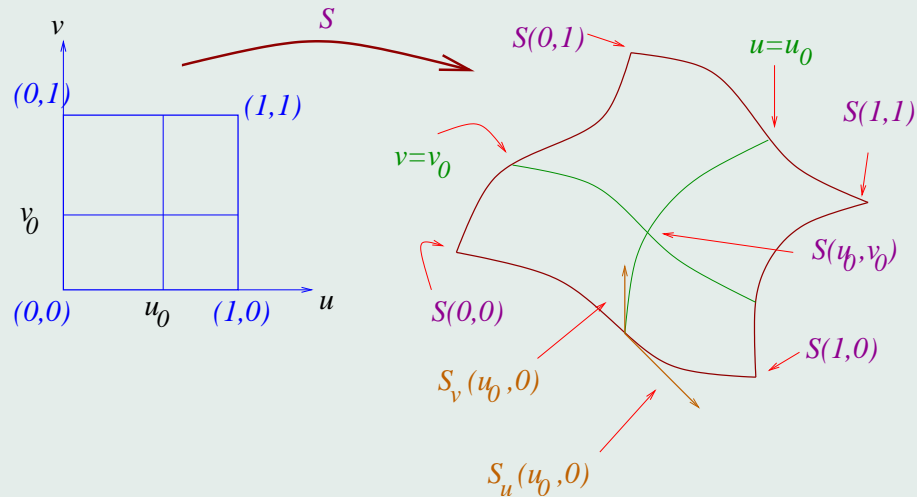
For convenience, let us consider the boundary point $S(u_0, 0)$. At any boundary point, we have **two** tangents to compute.

$$S_u(u_0, 0) = \lim_{u \rightarrow u_0} \frac{S(u, 0) - S(u_0, 0)}{u - u_0}$$

$$S_v(u_0, 0) = \lim_{v \rightarrow 0} \frac{S(u_0, v) - S(u_0, 0)}{v}$$

These two tangents are shown in the next picture.

An Example



The quantity $S_u(u_0, 0)$ is easily computed as the derivative of the boundary $S(u, 0) = \sum_{i=0}^m S[i, 0]B_i^m(u)$. We may thus use the curve-tangent law explained earlier to get:

$$S_u(u_0, 0) = m \left[\sum_{i=0}^{m-1} (S[i+1, 0] - S[i, 0]) B_i^{m-1}(u) \right]$$

$$S_v(u_0, v)$$

This quantity is a bit more delicate, since it is the tangent to the isoparametric curve $S(u_0, v)$ at $v = 0$.

We have seen that:

$$S(u_0, v) = \sum_{j=0}^n S[u_0, j] B_j^n(v)$$

where $S[u_0, j] = \sum_{i=0}^n S[i, j] B_i^m(u_0)$.

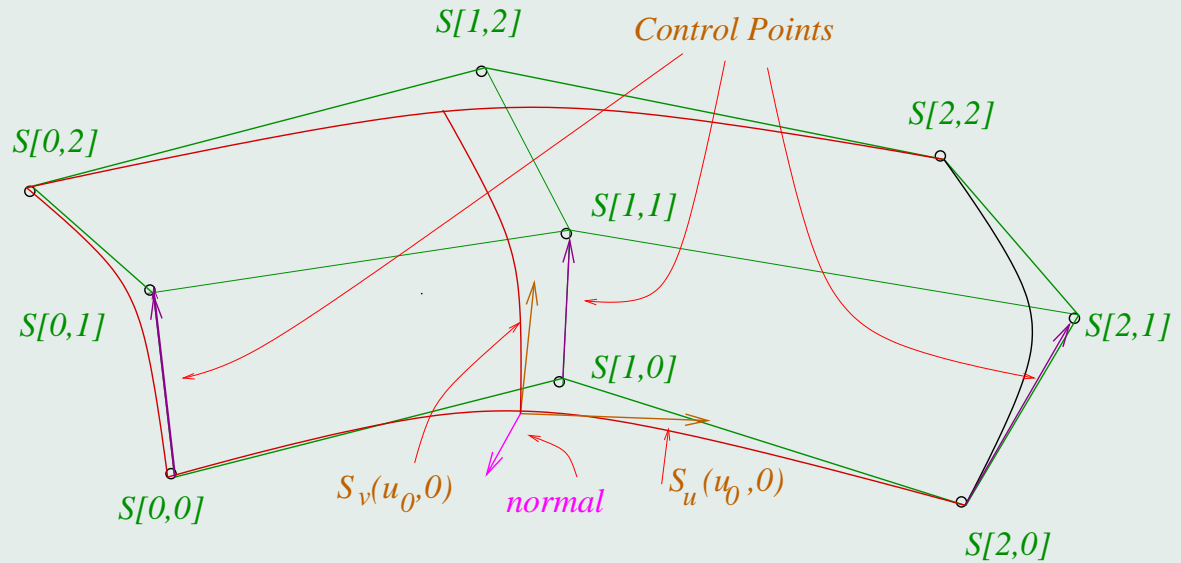
Thus $S_v(u_0, 0)$, the end-tangent to this curve, is $m(S[u_0, 1] - S[u_0, 0])$.

Back-substituting, we get:

$$\begin{aligned} S_v(u_0, 0) &= m \left[\sum_{i=0}^n S[i, 1] B_i^m(u_0) - \sum_{i=0}^n S[i, 0] B_i^m(u_0) \right] \\ &= m \left[\sum_{i=0}^n (S[i, 1] - S[i, 0]) B_i^m(u_0) \right] \end{aligned}$$

Thus $S_v(u_0, 0)$ is also a bezier with control points $[S[1, 0] - S[0, 0], S[1, 1] - S[1, 0], \dots, S[m, 1] - S[m, 0]]$.

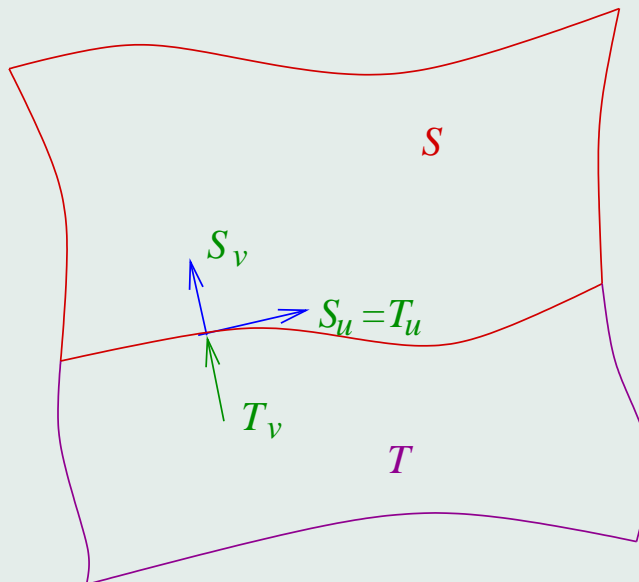
Pictorially



The **normal** at that point is given by the **cross-product** $S_v \times S_u$.

Splicing

Consider Two surfaces given by control points S and T . We would like to have them meet at a common boundary, and **smoothly**. Thus for example, we require $S(u, 0) = T(u, 1)$ for all $u \in [0, 1]$. Furthermore, we require that the normals match too.



The conditions

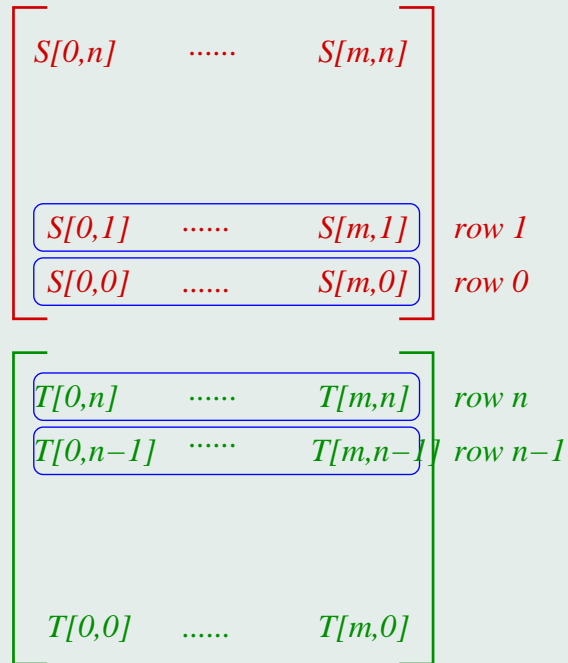
The condition $S(u, 0) = T(u, 1)$ is easily satisfied by having the **bottom** row of S match the **top** row of T .

This will also ensure that $S_u = T_u$ since both are tangents to the same curve.

Lets examine the normal condition next. $S_u \times S_v \equiv T_u \times T_v$, is achieved if we force S_v to be a multiple of T_v . This is forced by fixing a multiple, say α and requiring that:

$$S[i, 1] - S[i, 0] = \alpha(T[i, n] - T[i, n - 1])$$

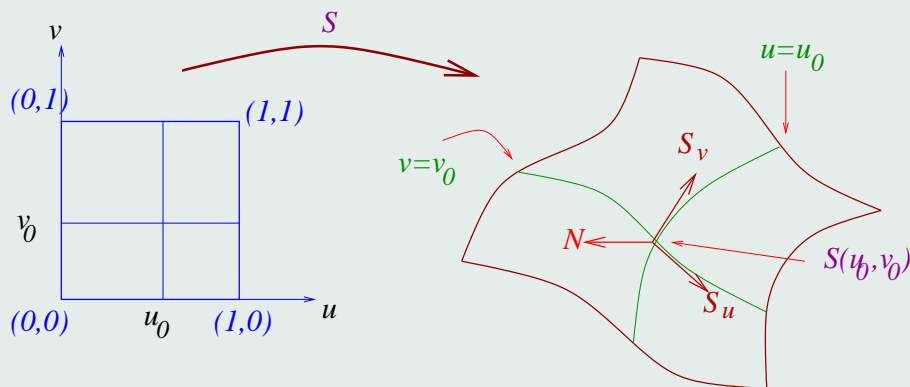
Schematically



$$\begin{aligned} \text{row } 0 &= \text{row } n \\ \text{row } 0 - \text{row } 1 &= \\ &\text{row } n - \text{row } n-1 \end{aligned}$$

The Normal System

A surface, if part of a solid, has at *every* point, an **outward normal**. Thus, given a (u_0, v_0) we are now faced with specifying *uniformly* an outward normal at $S(u_0, v_0)$!



Consider the figure above. At the point $S(u_0, v_0)$, we have the two tangents S_u and S_v . Let $N = S_u \times S_v$. Clearly the outward normal at $S(u_0, v_0)$ must be **either N or $-N$** .

The Sign of the Normal

We claim that if the outward normal at $S(u_0, v_0)$ is, say, $-N = -(S_u \times S_v)$, then it is so at **every** u, v ^a.

Thus *all* that needs to be stored is a **sign** $\in \{+1, -1\}$. The normal at any point $S(u, v)$ is given by

$$\text{sign} \cdot (S_u \times S_v)$$

Proof: Let $U(u, v)$ be the unit outward normal which exists! Clearly, $U(u, v)$ is a smooth function on the surface.

Let $M(u, v) = \text{sign} \cdot \frac{S_u \times S_v}{|S_u \times S_v|}$. We see that (i) $M(u, v)$ is a smooth function on u, v , and (ii) $M(u, v)$ is normal at $S(u, v)$.

^aprovided $S_u \times S_v$ is never zero

Continued

Thus at all points (u, v) , the vectors $M(u, v)$ and $U(u, v)$ are **collinear**.
Now the proof goes in the following 3 steps:

- Since both are unit, we have $M(u, v)/U(u, v) \in \pm 1$.
- Since both U and M are smooth and unit, $M(u, v)/U(u, v)$ must be **uniformly** either $+1$ or -1 .
- But we know that at (u_0, v_0) it is $+1$ and thus $M(u, v) = U(u, v)$.



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Things NOT covered

1. Surface Re-construction
2. Subdivision, Evaluation, Degree Elevation
3. Special Surfaces such as Coons-Patch
4. Tangent Planes, Gauss Map and Curvature