Computer Aided Geometric Design Introduction

Milind Sohoni Department of Computer Science and Engg. IIT Powai

Email:sohoni@cse.iitb.ac.in

Sources: www.cse.iitb.ac.in/sohoni

www.cse.iitb.ac.in/sohoni/gsslcourse

A Solid Modeling Fable

- Ahmedabad-Visual Design Office
- Kolhapur-Mechanical Design Office
- Saki Naka Die Manufacturer
- Lucknow- Soap manufacturer

Ahmedabad-Visual Design

- Input: A dream soap tablet
- Output:
- Sketches/Drawings
- Weights
- Packaging needs

Soaps



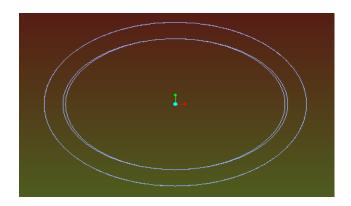


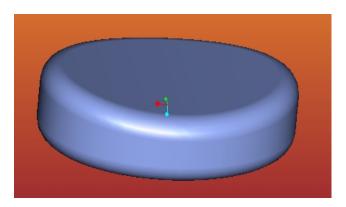
More Soaps



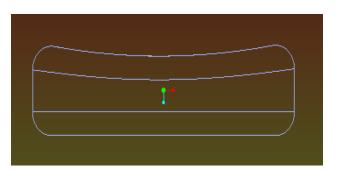


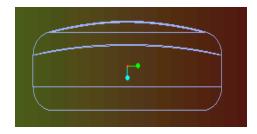
Ahmedabad (Contd.)





Top View



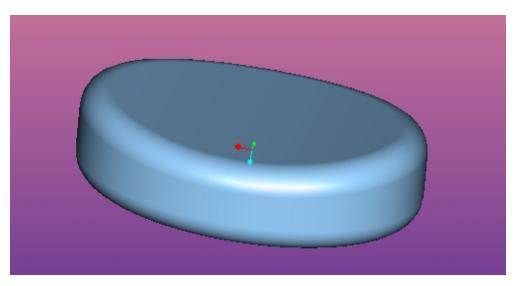


Side View

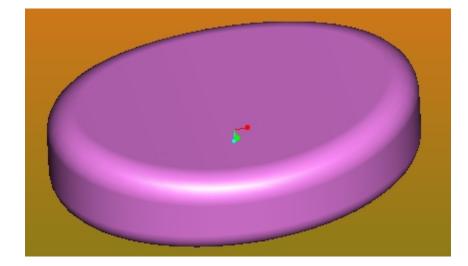
Front View

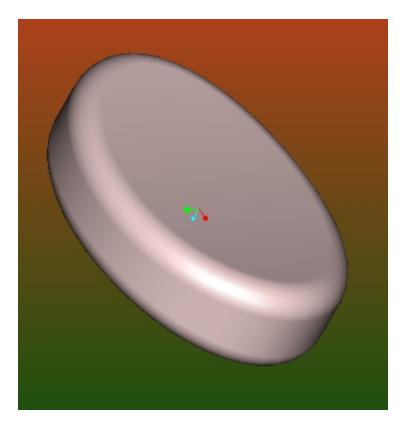
Kolhapur-ME Design Office

- Called an expert CARPENTER
- Produce a model (check volume etc.)
- Sample the model and produce a dataset



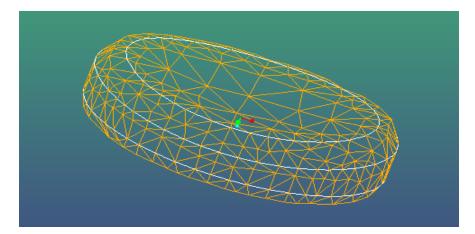
Kolhapur(contd.)

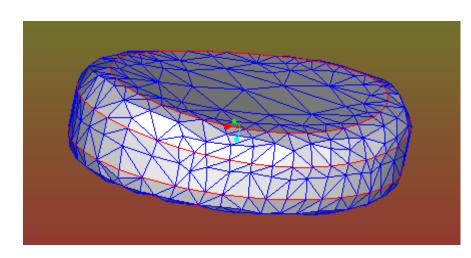




Kolhapur (contd.)

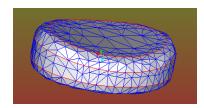
- Connect these samplepoints into a faceting
- Do mechanical analysis
- Send to Saki Naka

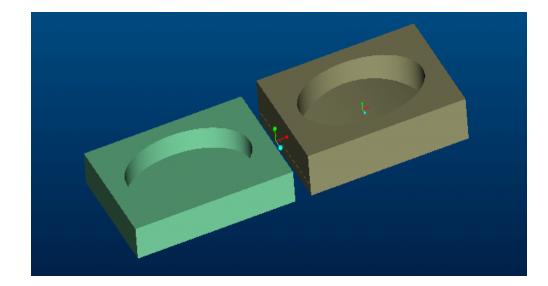




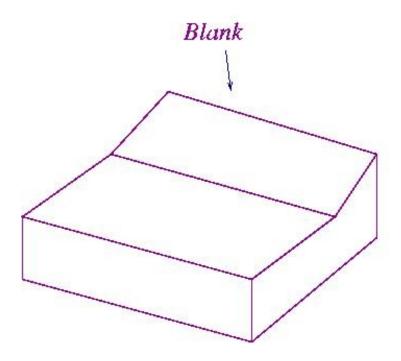
Saki Naka-Die Manufacturer

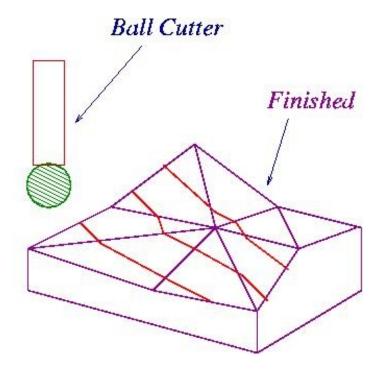
- Take the input faceted solid.
- Produce Tool Paths
- Produce Die





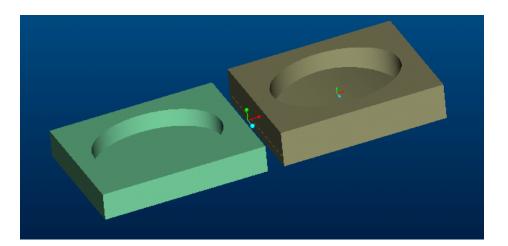
The Mechanics of it....

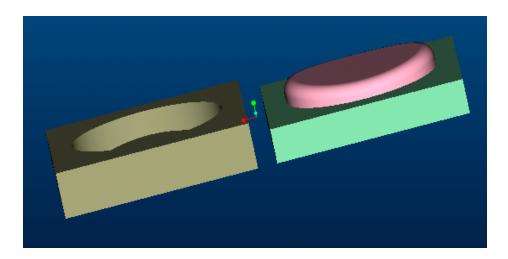




Lucknow-Soaps

- Use the die to manufacture soaps
- Package and transport to points of sale





Problems began...

- The die degraded in Lucknow
- The Carpenter died in Kolhapur
- Saki Naka upgraded its CNC machine
- The wooden model eroded

But

The Drawings were there!

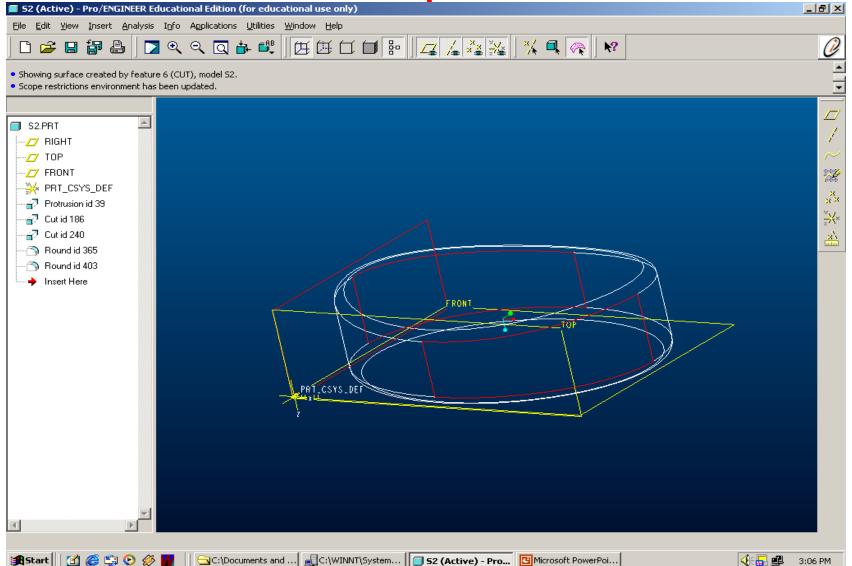
So Then....

• The same process was repeated but...

The shape was different!

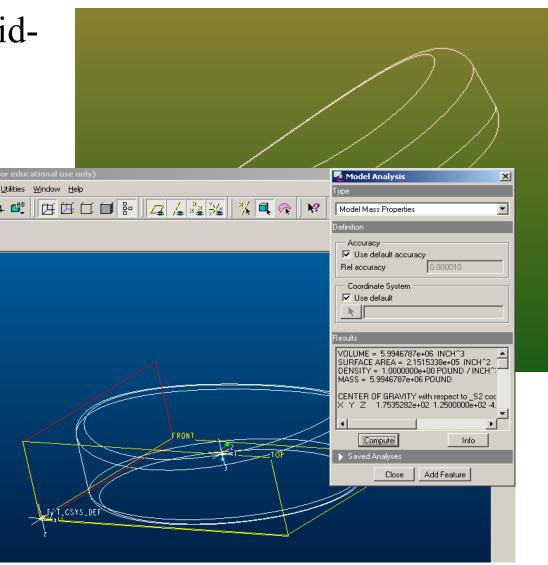
The customer was suspicious and sales dropped!!!

The Soap Alive !

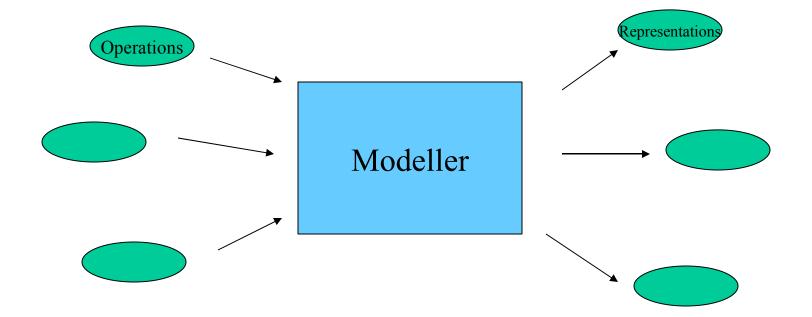


What was lacking was...

- A Reproducible Solid-Model.
- Surfaces defn
- Tactile/point sampling
- Volume computation
- Analysis



The Solid-Modeller



The mechanical solid-modeller

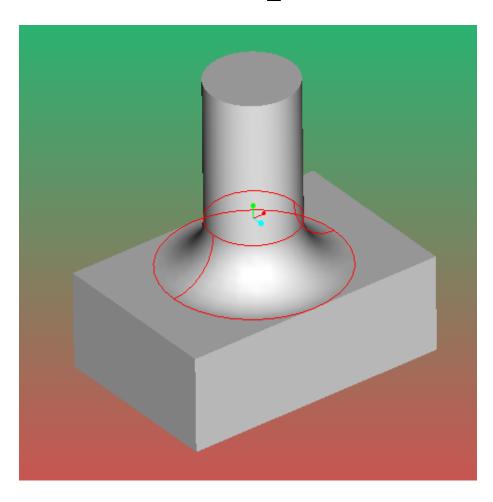
Operations

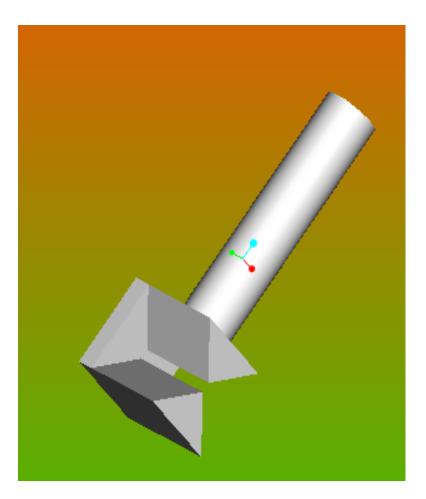
- Volume Unions/Intersections
- Extrude holes/bosses
- Ribs, fillets, blends etc.

Representation

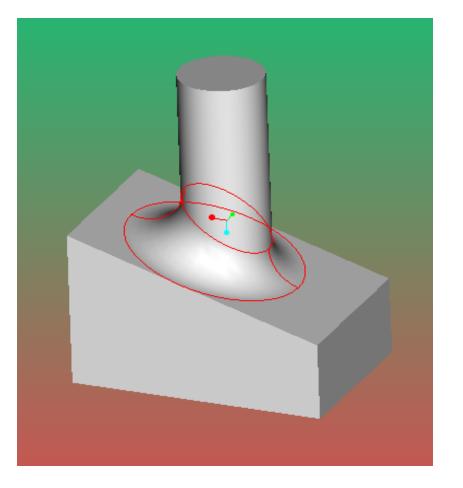
- Surfaces-*X*,*Y*,*Z* as functions in 2 parameters
- Edges –*x*,*y*,*z* as functions in 1 parameter

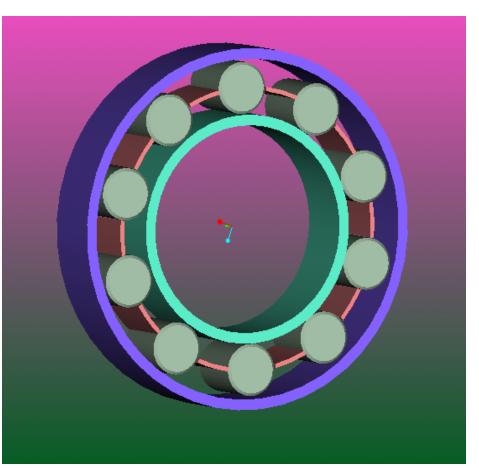
Examples of Solid Models





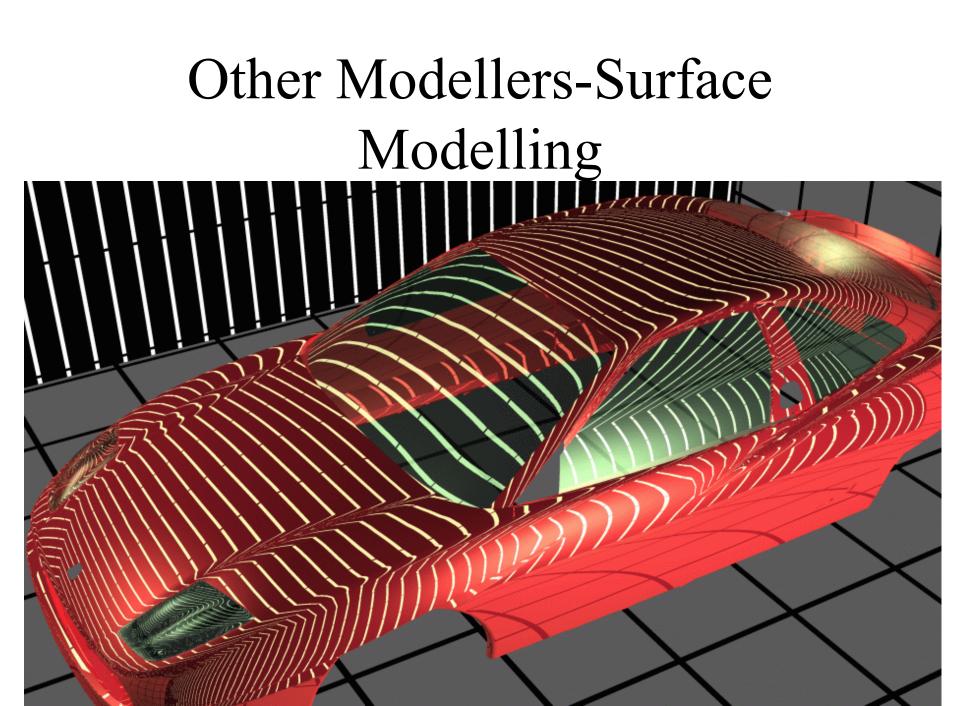
Even more examples



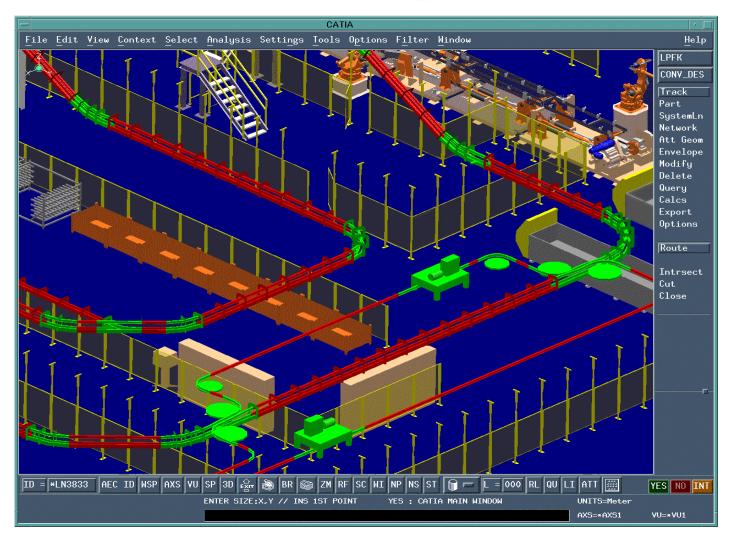


Slanted Torus

Bearing



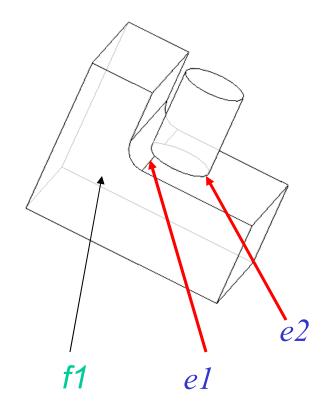
Chemical plants.



Chemical Plants (contd.)



Basic Solution: Represent each surface/edge by equations



e1: part of a line *X*=1+*t*; *Y*=*t*, *Z*=1.2+*t t* in [0,2.3]

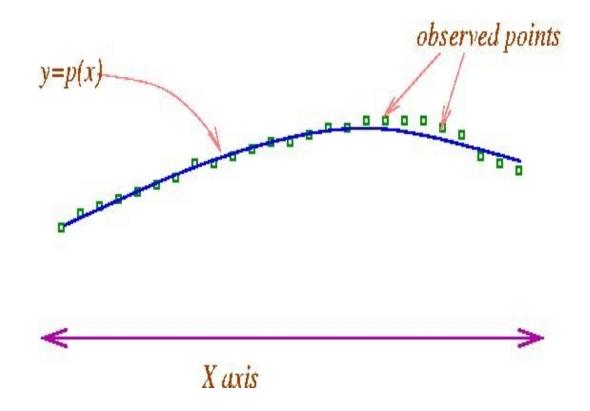
e2: part of a circle
X=1.2 +0.8 cos t
Y=0.8+0.8 sin t
Z=1.2
T in [-2.3,2.3]

f1: part of a plane *X*=*3*+2*u*-1.8*v Y*=*4*-2*u Z*=7 [*u*,*v*] in Box

A Basic Problem Construction of defining equations

- Given data points

 arrive at a curve approximating
 this point-set.
- Obtain the equation of this curve

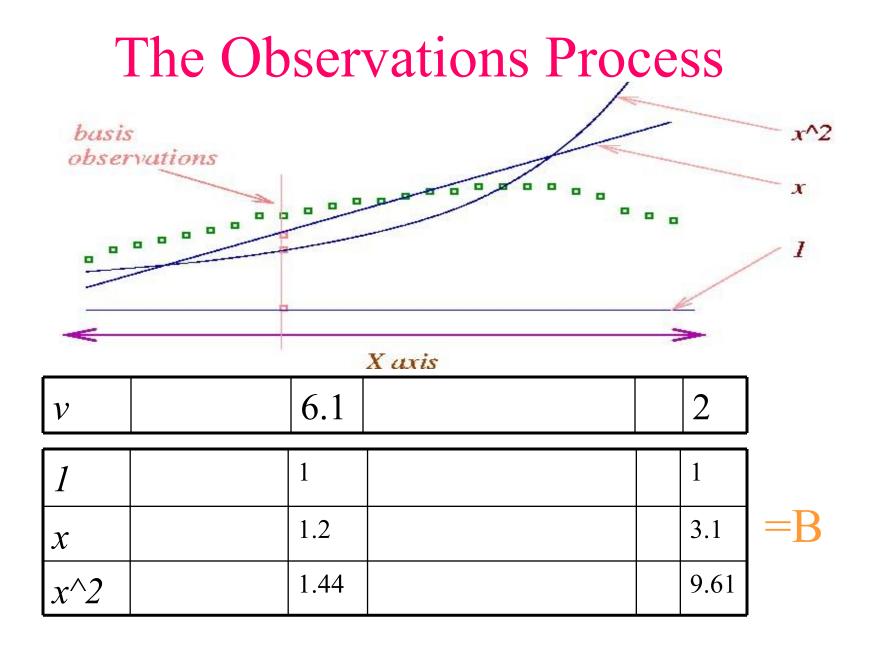


The Basic Process

- Choose a set of basis functions
- Observe these at the data points
- Get the best linear combination

In our case, Polynomials 1, x, x^2, x^3

 $P(x) = a0 + a1.x + a2.x^{2} + ...$



The Matrix Setting

We have

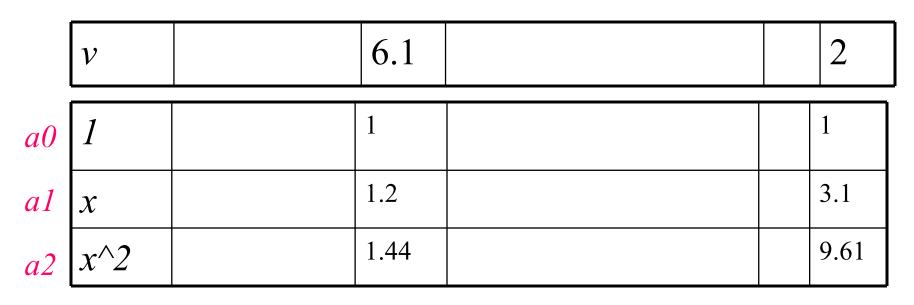
- The basis observations Matrix *B* which is 5-by-100
- The desired observations Matrix *v* which is 1-by-100

We want:

• *a* which is 1-by-5 so that aB is close to v

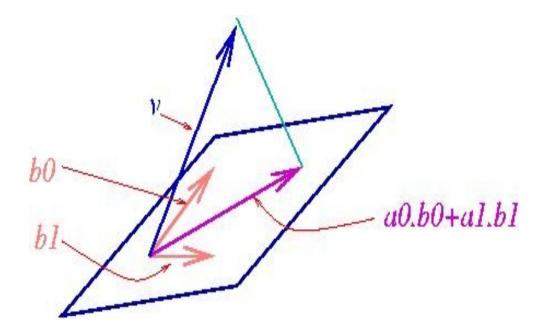


The minimization



Minimize least-square error (i.e. distance squared).
(6.1-a0.1-a1.1.2-a2.1.44)^2+...+(2-1.a0 - 3.1a1 - 9.61 a2)^2 +...
Thus, this is a quadratic function in the variables
a0,a1,a2,...
And is easily minimized.

A Picture



Essentially, projection of v onto the space spanned by the basis vectors

The calculation

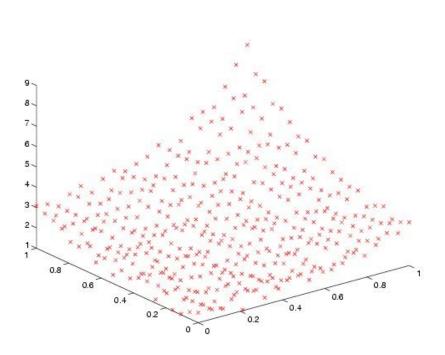
- How does one minimize
 1.1 a0^2 +3.7 a0 a1 +6.9 a1^2 ?
- Differentiate!

2.2 a0 + 3.7 a1 = 03.7 a0 + 13.8 a1 = 0

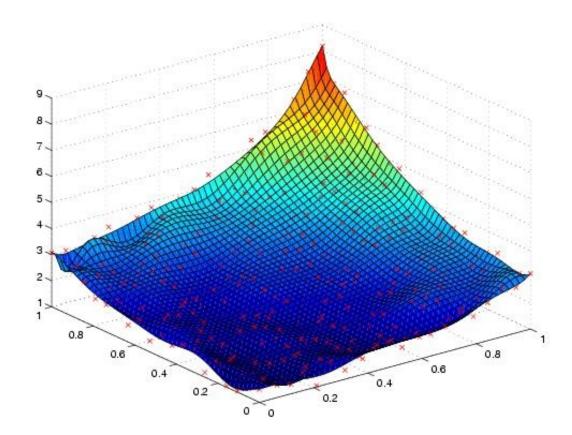
• Now *Solve* to get *a0,a1*

We did this and....

• So we did this for *surfaces* (very similar) and here are the pictures...



And the surface..



Unsatisfactory....

- Observation: the defect is because of *bad curvatures*, which is really *swings in double-derivatives!*
- So, how do we rectify this?
- We must ensure that if

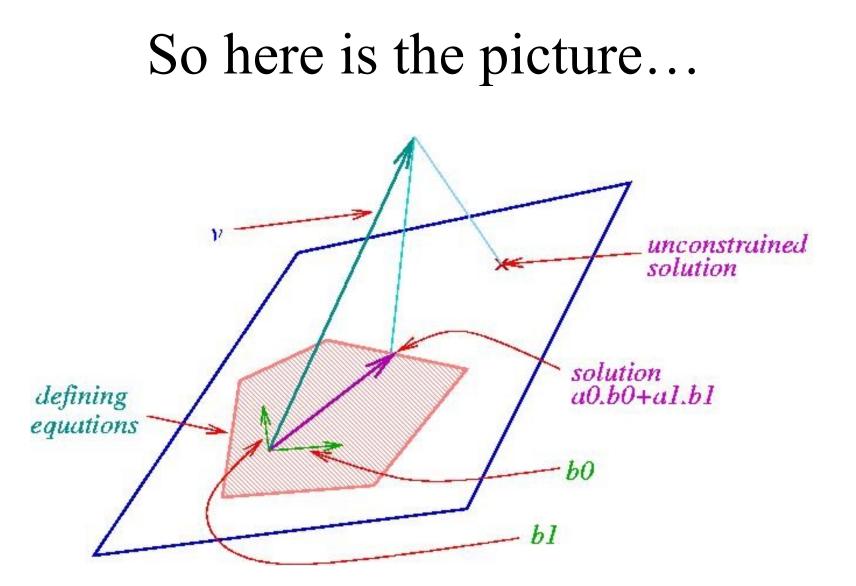
 $p(x) = a0 + a1.x + a2.x^2 + ...$ and q(x) = p''(x) then

q(x) >= 0 for all x

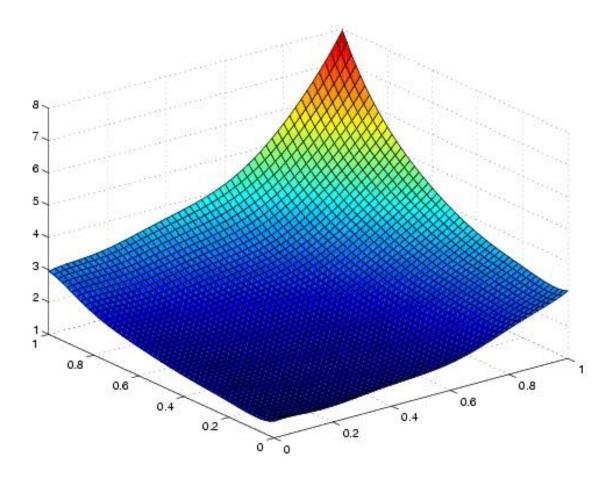
What does this mean?

 $q(x)=2.a2+6.a3.x+12.a4.x^2+...$ Thus q(1)>=0, q(2)>=0 means 2.a2+6.a3+12.a4>=02.a2+12.a3+48.a4>=0

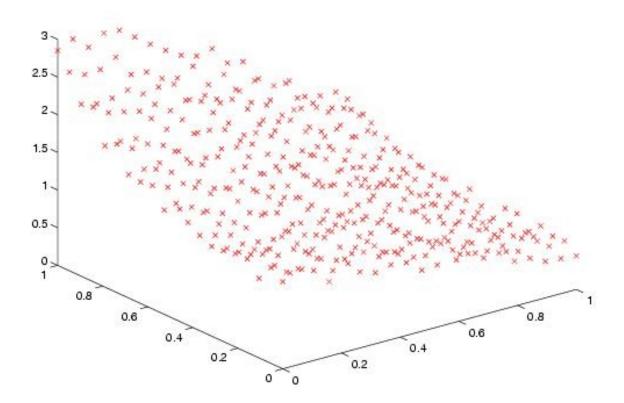
• Whence, we need to pose some *linear inequalities* on the variables *a0,a1,a2,...*



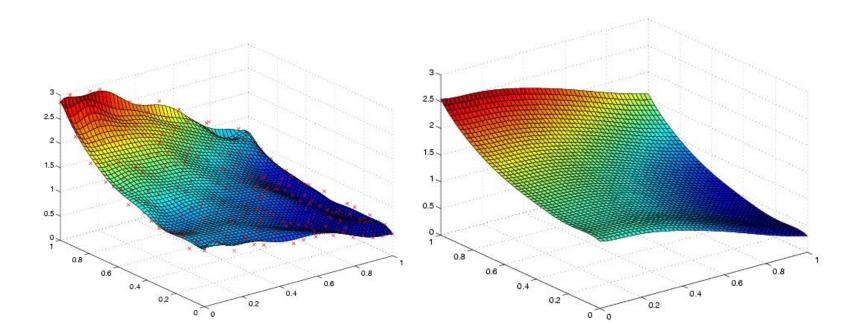
The smooth picture



Another example



The rough and the smooth



Summary

- The Solid Modeler
- Boundary Representation
- Polynomials and Splines
- Operations
- Optimization
- Curvatures and Basic differential geometry
- Genus

Softwares

MATLAB ProEngineer