

Knowledge Compilation for Boolean Functional Synthesis

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Boolean Functional Synthesis

Synthesizing Boolean functions from a relational specification.

Formal definition

Given Boolean relation $\varphi(x_1, \dots, x_n, y_1, \dots, y_m)$

- x_i *input* variables (vector X)
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 - Interesting as long as $\exists X \exists Y \varphi(X, Y) = 1$
 - $F(X)$ must give right value of Y for all X s.t. $\exists Y \varphi(X, Y) = 1$
 - $F(X)$ inconsequential for other X

A challenging example: Bounded Integer Factorization

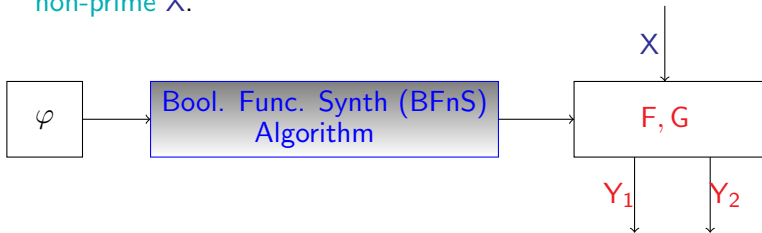
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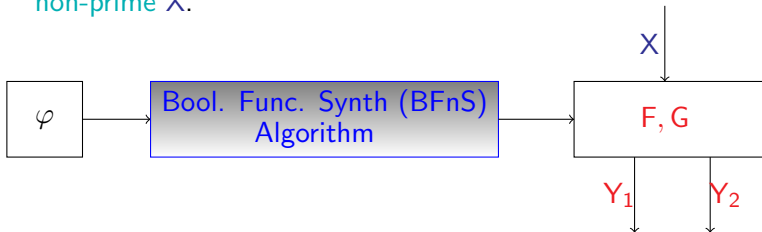
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- For every non-prime X , finds non-trivial factors
- From prime X , values of $F(X)$ and $G(X)$ inconsequential.
 - $\exists Y_1, Y_2 \varphi(X, Y_1, Y_2) = 0$ for such X .

Applications of Boolean Functional Synthesis

1. Cryptanalysis: Interesting but hard for synthesis!
2. Disjunctive decomposition of symbolic transition relations
[Trivedi et al'02]
3. Quantifier elimination, of course!
 - $\exists Y \varphi(X, Y) \equiv \varphi(X, F(X))$
4. Certifying QBF-SAT solvers
 - Nice survey of applications by Shukla et al'19
5. Reactive controller synthesis
 - Synthesizing moves to stay within winning region
6. Program synthesis
 - Combinatorial sketching [Solar-Lezama et al'06, Srivastava et al'13]
 - Complete functional synthesis [Kuncak et al'10]
7. Repair/partial synthesis of circuits [Fujita et al'13]

Existing Approaches

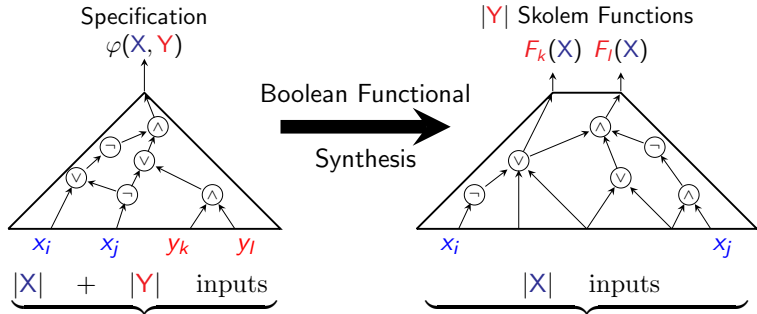
1. Closely related to most general Boolean unifiers
 - Boole'1847, Lowenheim'1908, Macii'98
2. Extract Sk. functions from proof of validity of $\forall X \exists Y \varphi(X, Y)$
 - Bendetti'05, Jussilla et al'07, Balabanov et al'12, Heule et al'14
3. Using templates: Solar-Lezama et al'06, Srivastava et al'13
4. Self-substitution + function composition: Jiang'09, Trivedi'03
5. Synthesis from special normal form representation of specification
 - From ROBDDs: Tronci'98, Kukula et al'00, Kuncak et al'10, Fried et al'16, Tabajara et al'17
 - From SynNNF: Akshay et al'09
6. Incremental determinization: Rabe et al'17,'18
7. Quantifier instantiation techniques in SMT solvers
 - Barrett et al'15, Bierre et al'17
8. Input/output component separation: C. et al'18
9. Guess/learn Skolem function candidate + check + repair
 - John et al'15, Akshay et al'17,'18,'20, Golia et al'20

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- Specification $\varphi(X, Y)$: $(|X| + |Y|)$ -input, 1-output circuit
 - Other forms (ROBDD/CNF/DNF ...) efficiently converted
- Desired Sk. fn. vector $F(X)$: $|X|$ -input, $|Y|$ -output circuit
 - No additional restrictions (ROBDD/CNF/DNF ...)



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 - Unless $\Pi_2^P = \Sigma_2^P$, there exist $\varphi(X, Y)$ for which Skolem function sizes are **super-polynomial** in $|\varphi|$.

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Efficient algorithms for Boolean functional synthesis unlikely

Some good news [CAV2018, FMCAD2019]

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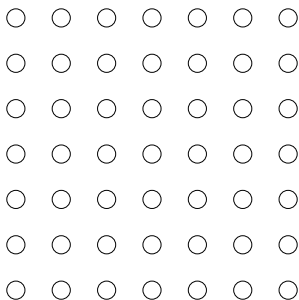
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 - Efficient synthesis doesn't require full capabilities of these stronger normal forms.

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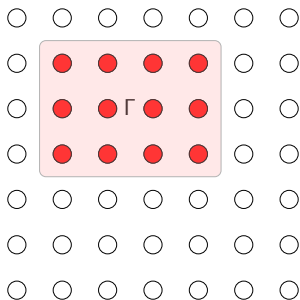
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— Set of all valuations of X .

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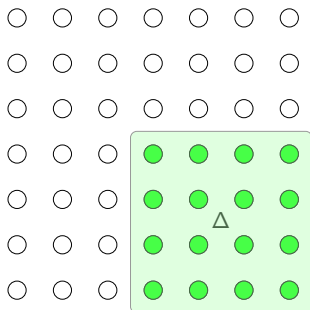
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E.g. If $\varphi \equiv (x_1 \vee y) \wedge (x_1 \vee x_2 \vee \neg y)$, then

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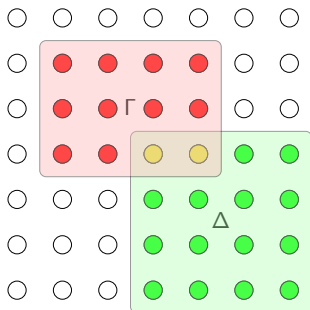
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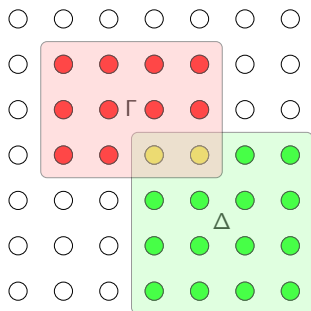
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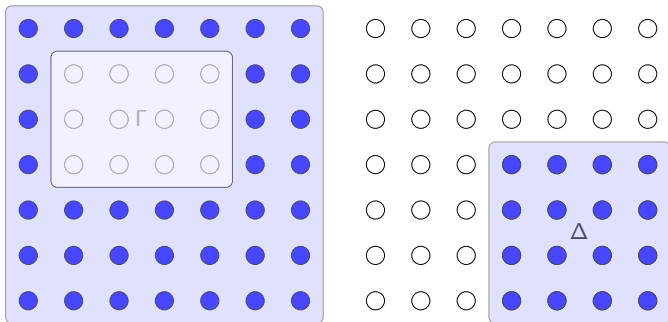
Lemma [Trivedi'03, Jiang'09, Fried et al'16]

Every Skolem function for y in φ must

- Evaluate to 1 in $(\Delta \setminus \Gamma)$ and to 0 in $(\Gamma \setminus \Delta)$
- Be an **interpolant** of $(\Delta \setminus \Gamma)$ and $(\Gamma \setminus \Delta)$

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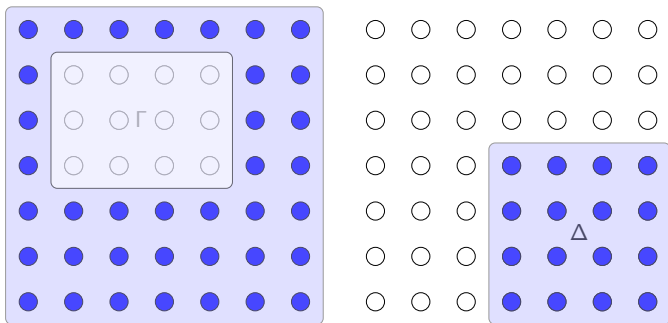


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- Synthesize $F_2(X)$ from $\varphi_1(X, y_2)$
 - Example: $\varphi_1(X, y_2) \equiv (x_1 \vee x_2 \vee \neg y_2)$

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How do we compute

$\exists [y_1, \dots, y_i] \varphi(X, [y_1, \dots, y_i], [F_{i+1}(X), \dots, F_m(X)])$ efficiently?

Synthesis from ROBDDs

- Tronci'98, Kukula et al'00, Kuncak et al'10, Fried et al'16, Tabajara et al'17
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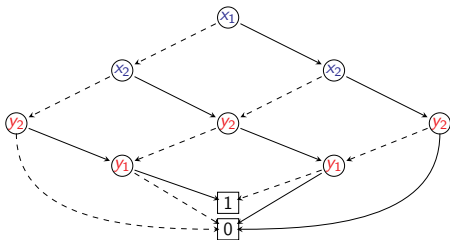
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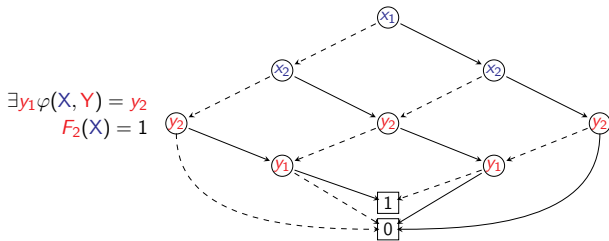
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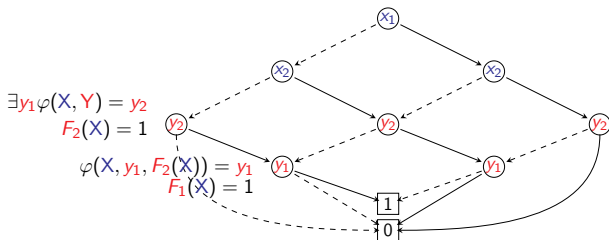
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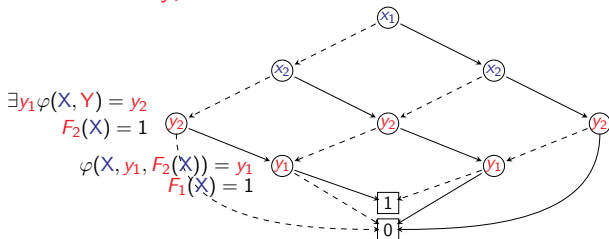
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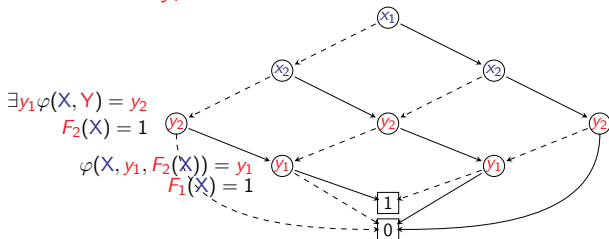
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- Spec ROBDD can be exp. larger with input-first ordering
 - $\varphi(X, Y) \equiv \bigwedge_{i=1}^n (x_i \Leftrightarrow y_i)$
 - Size $\Omega(2^n)$ with input-first ordering, $\Theta(n)$ with interleaved input-output ordering,

Going beyond Input-First Ordered ROBDDs

- ROBDDs have much more structure than we need.

Going beyond Input-First Ordered ROBDDs

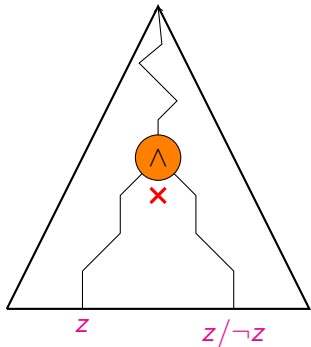
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Decomposable NNF (DNNF) and weak DNNF are better!

$\varphi(X, Y)$ in DNNF except on X

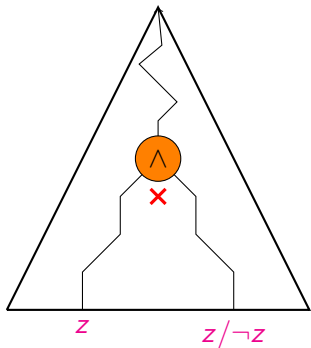


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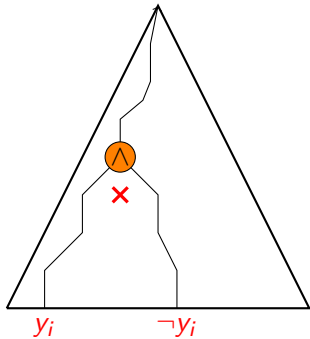
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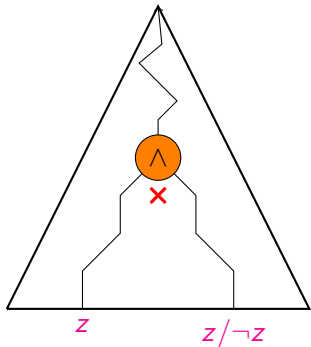
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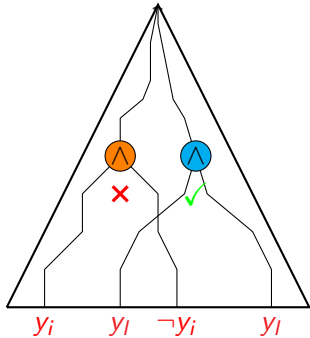
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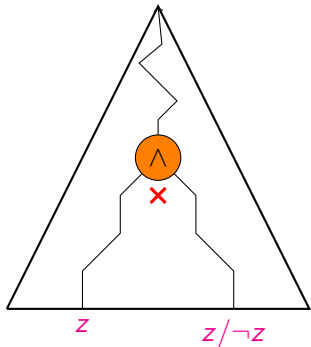
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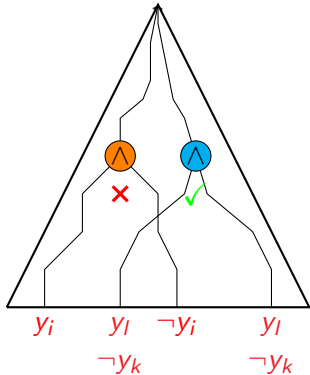
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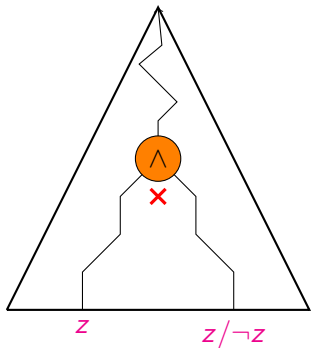
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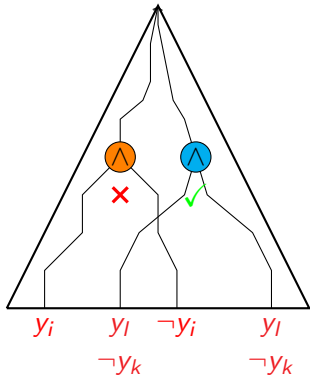
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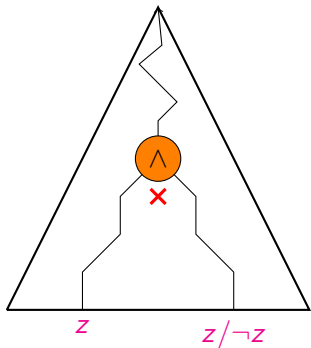
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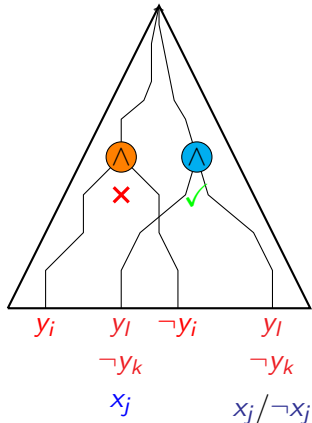
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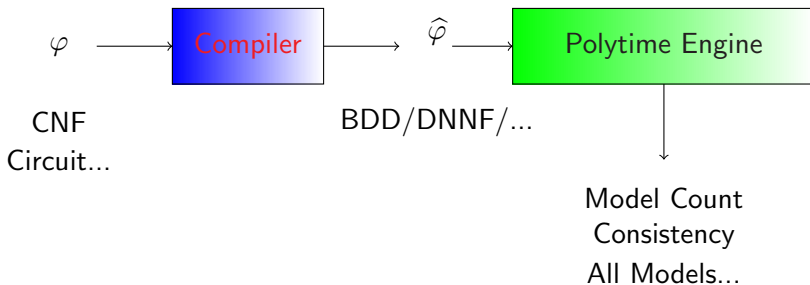
- **YES:** Super-polynomial time in worst-case
- **Practical performance promising!**

Wikipedia

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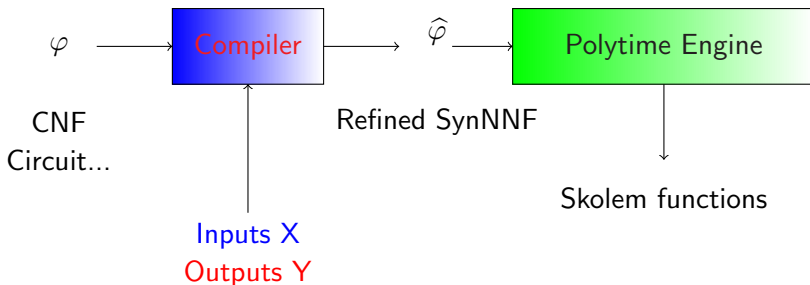


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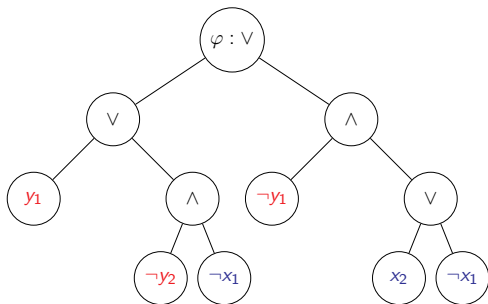


Towards a normal form for efficient synthesis

- Represent $\varphi(x_1, \dots, x_n, y_1, \dots, y_m)$ as NNF DAG
 - Boolean circuit, \wedge and \vee at internal nodes, \neg only at leaves

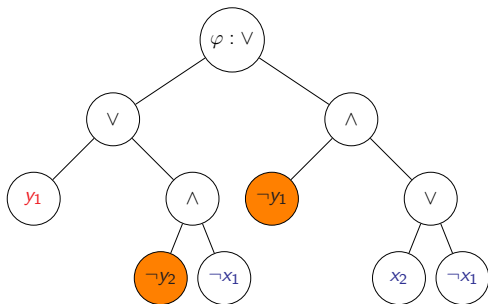
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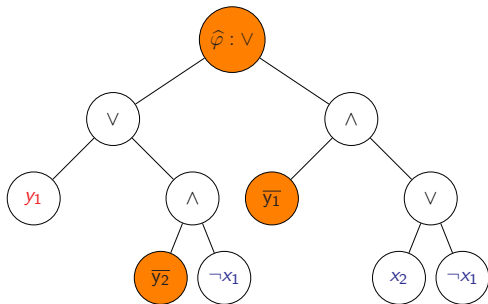
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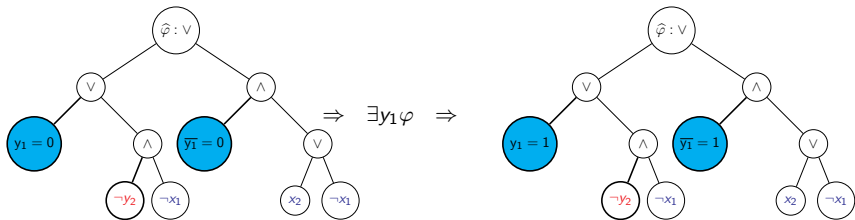
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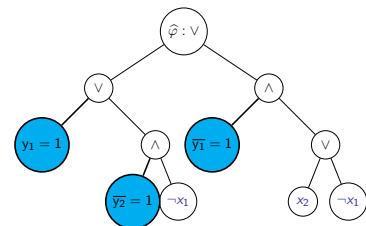
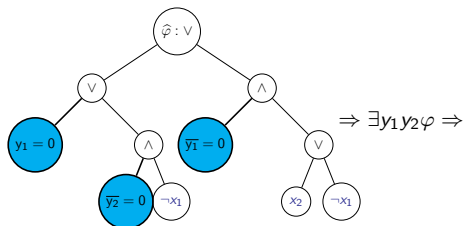


- **Positive form of specification:**
 $\hat{\varphi}(x_1, \dots, x_n, y_1, \dots, y_m, \overline{y_1}, \dots, \overline{y_m})$
 - Monotone w.r.t all y_i and $\overline{y_i}$

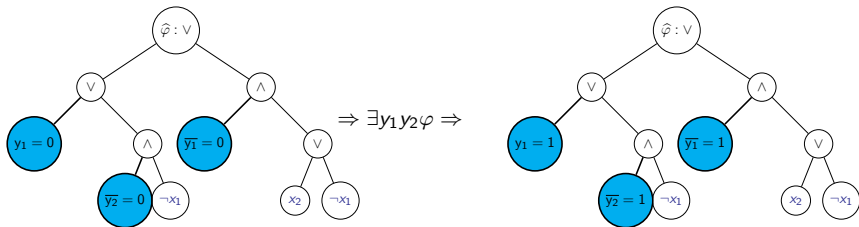
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- $\hat{\varphi}(x_1 \dots x_n, \overbrace{0 \dots 0}^i, y_{i+1} \dots y_m, \overbrace{0 \dots 0}^i, \neg y_{i+1} \dots \neg y_m) \Rightarrow \exists y_1 \dots y_i \varphi(\dots)$
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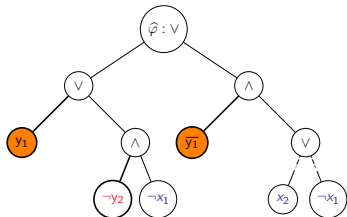
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$$[\hat{\varphi}]_1(x_1, x_2, y_1, y_2, \overline{y_1})$$

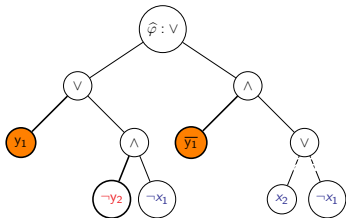
Iterated reducts of $\hat{\varphi}$

Given

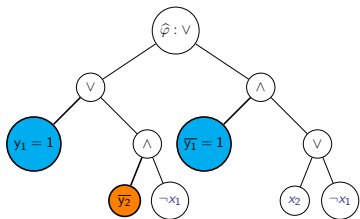
- Positive form of spec $\hat{\varphi}(x_1, \dots, x_n, y_1, \dots, y_m, \overline{y_1}, \dots, \overline{y_m})$
- Linear order of outputs $y_1 \prec \dots \prec y_m$

Define $[\hat{\varphi}]_i$ as

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$$[\hat{\varphi}]_2(x_1, x_2, y_2, \overline{y_2})$$

Iterated reducts and existential quantification

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- Inductively, $\exists y_1, \dots, y_i \varphi(X, Y) \Leftrightarrow [\widehat{\varphi}]_i |_{y_i=1, \overline{y_i}=1}$ iff $\neg \exists X, y_{i+1}, \dots, y_m ([\widehat{\varphi}]_i \Leftrightarrow y_i \wedge \overline{y_i})$.

SynNNF: A negation normal form for efficient synthesis

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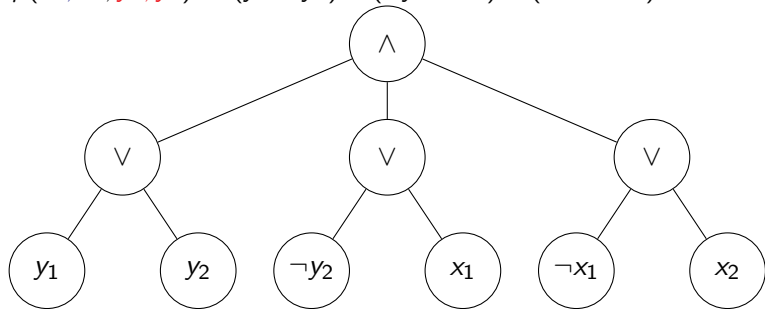
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Observations:

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- Reminiscent of Deterministic DNNF (dDNNF)
 - For every \vee node representing $\varphi_1 \vee \varphi_2$, require $\varphi_1 \wedge \varphi_2 = \perp$.

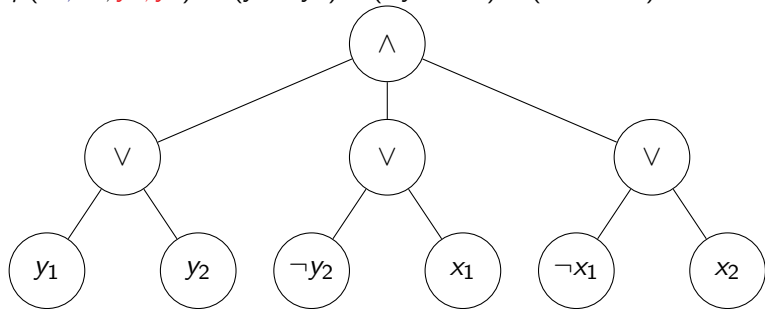
SynNNF: An Example

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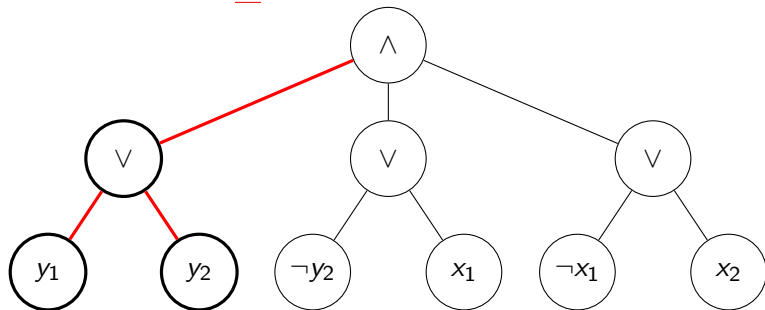


Representation of φ **not** in DNNF/wDNNF

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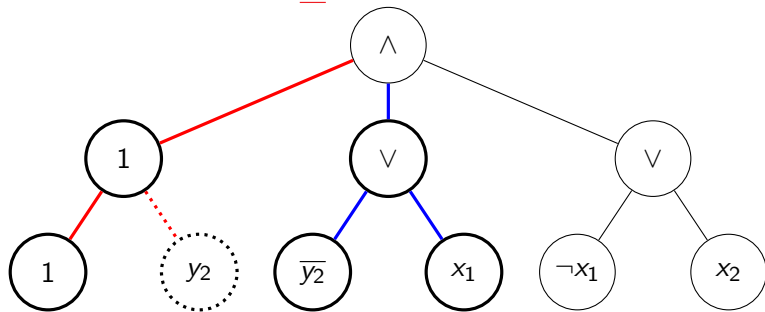
Output sequence: y_1 \prec y_2



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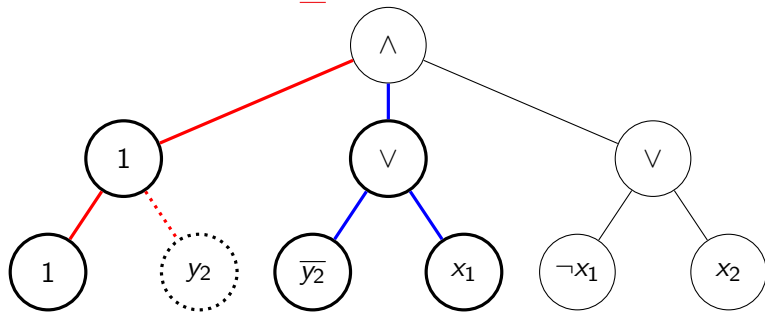
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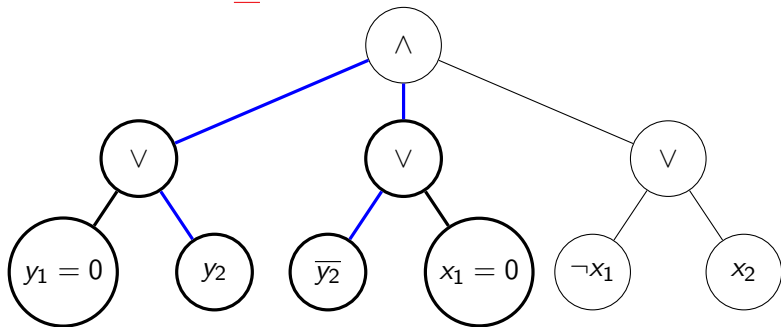


Representation of φ in SynNNF **w.r.t** $y_1 \prec \underline{y_2}$

Non-SynNNF: An Example

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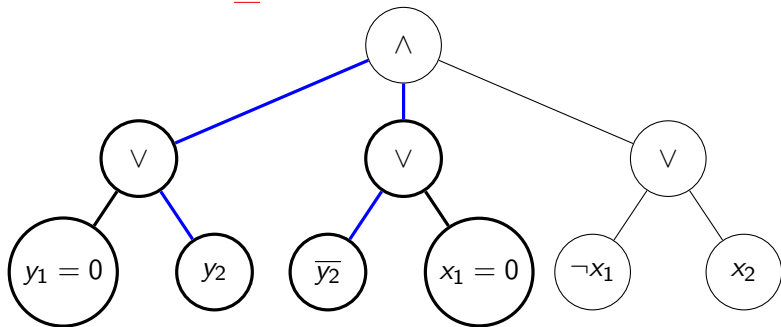
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Non-SynNNF: An Example

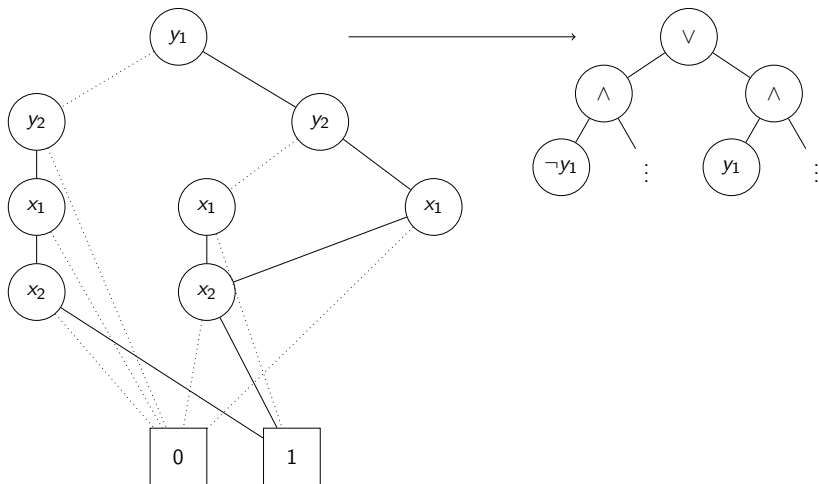
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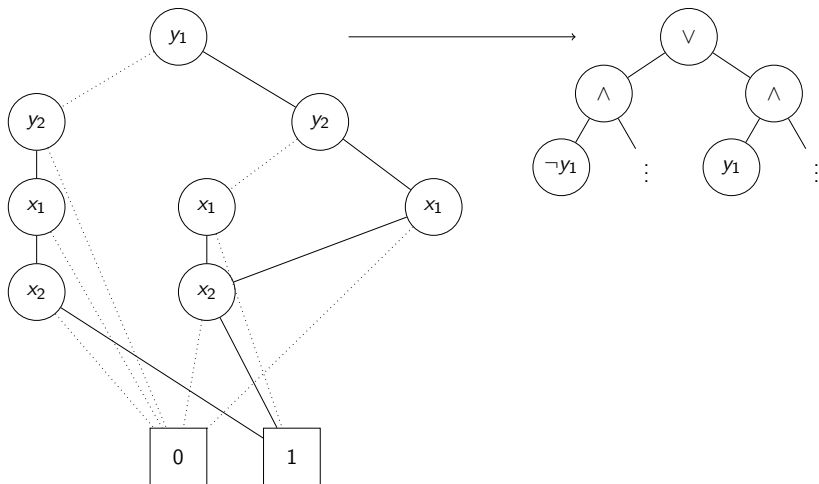


Representation of φ not in SynNNF **w.r.t** $y_2 \prec y_1$

BDD and SynNNF



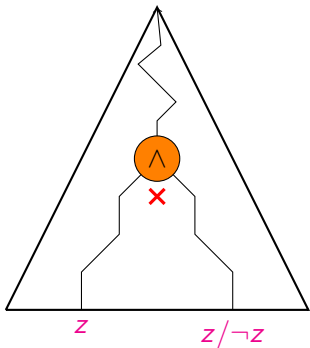
BDD and SynNNF



BDD \rightarrow SynNNF in linear time for any output order \prec and any BDD variable order.

DNNF, wDNNF and SynNMF

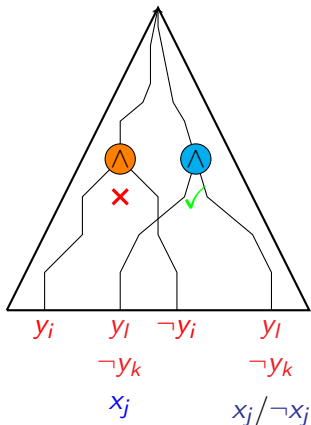
$\varphi(X, Y)$ in DNNF except on X



z is y_j

Disallowed paths

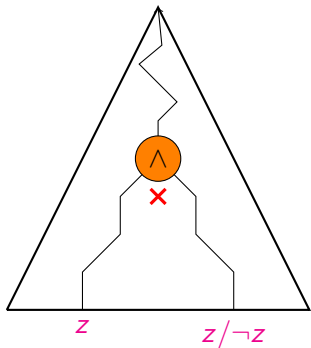
$\varphi(X, Y)$ in wDNNF except on X



(Dis)allowed paths

DNNF, wDNNF and SynNNF

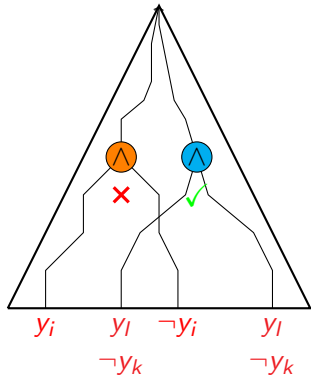
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(Dis)allowed paths

A specification in DNNF or wDNNF is already in SynNNF for any output order \prec .

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- Given φ , checking if φ is in SynNNF w.r.t. any (unspecified) order \prec is in Σ_2^P .

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NNF \sqsubset SynNNF \sqsubset DNNF \sqsubset dDNNF \sqsubset BDD

Operations with SynNNF

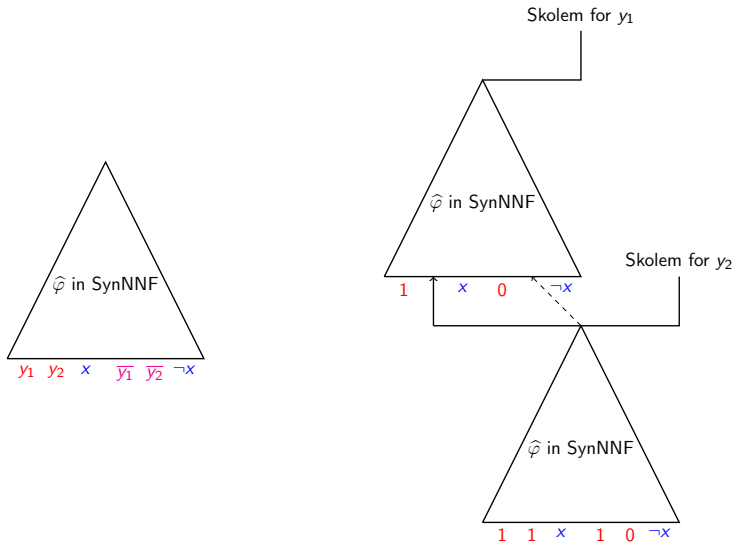
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- Computing $\varphi_1 \wedge \varphi_2$ in SynNNF in poly-time not possible unless $P = NP$
- Computing $\varphi_1 \vee \varphi_2$ in SynNNF in same ordering of Y takes constant time
- Existentially quantifying y_1, \dots, y_m takes linear time.
 - Quantifying subset of Y not possible in linear time in general.

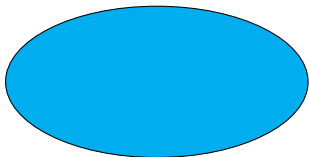
How does SynNNF help Skolem function synthesis?



Synthesis: $m \times |\varphi|$ circuit size, $\mathcal{O}(m^2)$ additional wires.

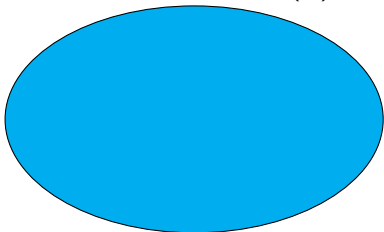
Refinement w.r.t. synthesis

Values of X s.t. $\exists Y \varphi(X, Y)$



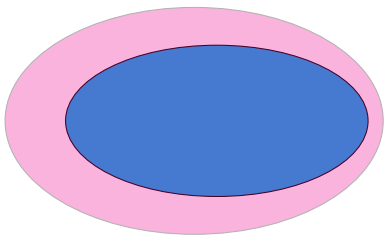
Given spec: $\varphi(X, Y)$

Skolem functions $F(X)$



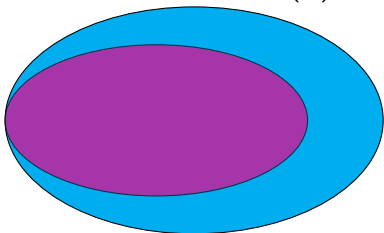
Refinement w.r.t. synthesis

Values of X s.t. $\exists Y \varphi(X, Y)$



Given spec: $\varphi(X, Y)$

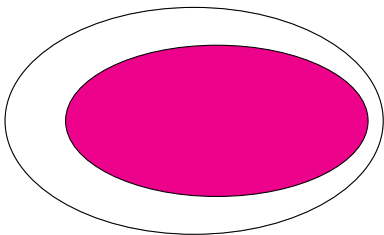
Skolem functions $F(X)$



Refined spec: $\tilde{\varphi}(X, Y)$

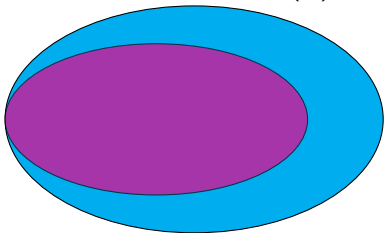
$$\tilde{\varphi} \preceq_{\text{syn}} \varphi$$

Values of X s.t. $\exists Y \varphi(X, Y)$



Given spec: $\varphi(X, Y)$

Skolem functions $F(X)$



Strongly
Refined spec: $\tilde{\varphi}(X, Y)$

$$\tilde{\varphi} \models_{syn}^* \varphi$$

Lemma

If $\tilde{\varphi}(X, Y) \preceq_{syn} \varphi(X, Y)$, every Skolem function vector for Y in $\tilde{\varphi}$ is also a Skolem function vector for Y in φ .

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Example: $(y_2 \wedge y_1) \preceq_{syn}$

$$((\neg y_1 \vee y_2 \vee x_1) \wedge (y_1 \vee \neg y_2) \wedge (y_1 \vee \neg x_1) \wedge (y_2 \vee x_2))$$

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- 3 If $\bigwedge_{y_i \in Y} (F|_{y_i=0} \Leftrightarrow F|_{y_i=1})$, then $1 \preceq_{syn} F$ and $F|_{Y=a} \preceq_{syn}^* F$, where a is any vector in $\{0, 1\}^m$.

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- 4 If F is positive (resp. negative) unate in $y_i \in Y$, then $y_i \wedge F|_{y_i=1}$ (resp. $\neg y_i \wedge F|_{y_i=0}$) $\preceq_{syn}^* F$. pause
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 - 2 Let $\tilde{F}_1 \preceq_{syn} F_1$ and $\tilde{F}_2 \preceq_{syn} F_2$. If the output supports of F_1 and F_2 , and similarly of \tilde{F}_1 and \tilde{F}_2 , are disjoint, then $(\tilde{F}_1 \wedge \tilde{F}_2) \preceq_{syn} (F_1 \wedge F_2)$. If, in addition, $\tilde{F}_1 \preceq_{syn}^* F_1$ and $\tilde{F}_2 \preceq_{syn}^* F_2$, then $(\tilde{F}_1 \wedge \tilde{F}_2) \preceq_{syn}^* (F_1 \wedge F_2)$.

Putting it all together

Tool C2Syn:

- Input: φ in CNF (or AIG)
 - Output: Refined $\tilde{\varphi}$ in SynNNF
- Branches only on output variables
 - Aggressively tries to refine whenever possible
 - Details in our FMCAD 2019 paper

Experimental Results

Comparison of run-time with

- CADET [Rabe et al 2016]
- BFSS [Akshay et al 2018]
- BDD [BDD pipeline of BFSS]

Benchmarks: QBFEVAL 2018 and Factorization (408 total)

Benchmarks (Total)	Compiled By C2Syn			BDD compilation	Total in SynNNF
	Stage I	Stage II	Total		
QBFEVAL (402)	103	83	186	153	283
FA.QD (6)	0	6	6	6	6

Table: Compilation into SynNNF

Experimental Results

Bench mark	C2Syn vs CADET		C2Syn vs BFSS		C2Syn \ (CADET \cup BFSS)
	C2Syn \ CADET	CADET \ C2Syn	C2Syn \ BFSS	BFSS \ C2Syn	
QBFEVAL	78	105	83	78	75
FA.QD	2	0	3	0	2

Table: Comparison Results of C2Syn

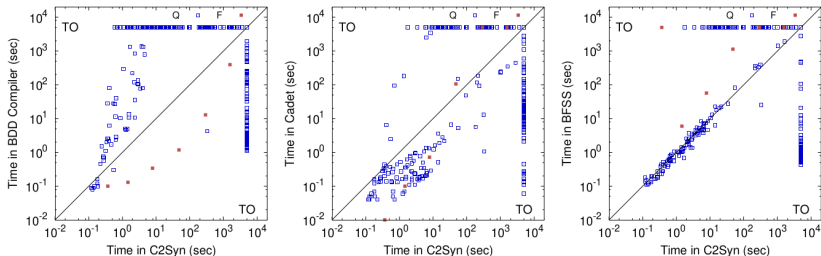


Fig. 1: Time comparisons: C2Syn vs BDD^{BFSS} , CADET, BFSS

Conclusion

- SynNNF: A new normal form for polynomial-time synthesis
- Refinement w.r.t. synthesis useful in practice
 - Formalization of folklore
 - CNF \rightarrow Refined SynNNF much more efficient than CNF \rightarrow SynNNF
- Experimental results with preliminary implementation show promise
- It appears that SynNNF can be further weakened to achieve poly-time synthesis
 - Ongoing work