CS 217: Artificial Intelligence and Machine Learning
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 Lecture 19: Two Player Competitive Games

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19.1 Two Player Competitive Game

Consider a two-player game in which there are 3 buckets (A, B, C) and each bucket contains two numbers as shown below.



Rules of the game are:

- Player 1(agent) picks the bucket
- Player 2 (opponent) picks a number from the "Selected" Bucket
- Player 1 (agent) utility will be the number picked by player 2

Now, let's construct the **game tree**



Consider two strategies of the opponent:

- 1. If the **opponent is stochastic**, i.e., the probability of choosing both left and right numbers in a bucket are the same (i.e., $\frac{1}{2}$).
 - If A is chosen, expected utility $=\frac{-50+50}{2}=0.$
 - If B is chosen, expected utility $=\frac{1+3}{2}=2$.
 - If C is chosen, expected utility $=\frac{-10+20}{2}=5.$

So in this case **agent picks bucket C**, to maximize it's utility.



2. If the opponent is a min player, i.e., the **opponent always chooses the minimum number from the bucket.**

In this case, the agent **picks Bucket B**, as $\operatorname{argmax}(-50, 1, -10) = 1$.



Note: Here, utility is given only to the agent. However, in some games, utility can be assigned to both the agent and the opponent. In such scenarios, the opponent not only tries to minimize the agent's score but also to maximize its own utility.

19.2 Two Player Zero Sum Games

Two-player zero-sum games are a type of mathematical game in which one player's gain is exactly balanced by the other player's loss. The total utility available in the game is constant; hence, the sum of the gains and losses of all players is zero. In these games, the interests of the players are completely opposed, meaning that one player's win is the other's loss.

Examples: Chess, tic-tac-toe, checkers

Lets start with some of the **basic terminologies** for 2-player zero sum games:

- Players: {Agent, Opponent}
- Starting State: S₀
- Actions(s): Possible actions at state 's'
- Player(s): Player who makes the move at state 's'
- Successor(s, a): Resulting state if action a is taken at state 's'
- isEnd(s): Is state an end state/ Flag to identify terminal state
- Utility(s): Agent's utility at the "end state"

Note:

- i) In Actions(s), Player(s), Successor(s, a), 's' is an intermediate state
- ii) Utility(s) is not defined in other (intermediate) states

Example: Chess

- Players: {White, Black}
- State: A board position (position of the chess pieces at a given time)
- Actions(s): All legal moves possible by Player(s)
- **Player**(s): Player who makes the move at state 's'
- Successor(s, a): Resulting state if action a is taken at state 's'
- isEnd(s): Whether 's' is a checkmate or a draw
- Utility function is defined as

 $\mathbf{Utility}(s) = \begin{cases} +M & \text{if white wins} \\ -M & \text{if black wins/white loses} \\ 0 & \text{if it is a draw} \end{cases}$

19.3 Constant Sum Game

Constant sum games are a type of game in game theory where the total payoff to all players remains the same regardless of the outcome of the game. In other words, the sum of gains and losses of all players is a constant value for every possible end-state of the game. These games are characterized by the fact that one player's gain (or loss) is exactly balanced by the losses (or gains) of the other player(s). Zero sum games are constant sum games with the constant as 0.

Example: 2 siblings (brother B and sister S) are given 2 chocolates from their mother and they have to divide the chocolates. The brother proposes to have some number of chocolates and the sister can either accept or reject the proposal.

 $Players = \{Brother, Sister\}$



Brother plays first and goes to one of the states n_2, n_3, n_4 . The **state** n_2 means he decides to keep both chocolates. The **state** n_3 means he decides to keep one and give his sister the other one. The **state** n_4 means he decides to give his sister both chocolates.

Then his sister chooses A_1 or R_1 if he chose n_2 ; A_2 or R_2 if he chose n_3 ; and A_3 or R_3

if he chose n_4 .

 A_1, A_2, A_3 are accepting states - Whatever her brother decided happens.

 R_1, R_2, R_3 are **rejecting states** - If she chooses one of these none of them get any chocolate irrespective of the decision made by her brother earlier.

The nodes in the last level signify the utility according to the brother.

The **state** 1 means he gets both chocolates.

The state $\frac{1}{2}$ means he gets both the chocolates.

The state $\tilde{0}$ means his sister gets both chocolates.

$$\mathbf{Utility}(s) = \begin{cases} \text{Gets both the chocolates} & \text{if end state is 1} \\ \text{Gets one chocolate} & \text{if end state is 1/2} \\ \text{Gets no chocolates} & \text{if end state is 0} \end{cases}$$
$$\mathbf{Actions}(s) = \begin{cases} \{1, \frac{1}{2}, 0\} & \text{when s} = n_1 \\ \{A_1, R_1\} & \text{when s} = n_2 \\ \{A_2, R_2\} & \text{when s} = n_3 \\ \{A_3, R_3\} & \text{when s} = n_4 \end{cases}$$

Note: The utility function is defined for the brother.

19.4 Strategy of a player

The strategy of a player is the action we must take, if we end up in any of the state. It can be deterministic, probabilistic and also random. Now, we study about different types of strategies.

19.4.1 Deterministic Strategies:

In deterministic strategies, the action of a player at a specific state is fixed and predetermined. For any given state S, the action chosen by player i is strategically fixed, denoted by $\pi_i(s)$, and it belongs to the set of all possible actions available at that state, provided player(s) = i i.e.,

 $\pi_i(s) \in \operatorname{actions}(s)$ if $\operatorname{player}(s) = i$

19.4.2 Randomized Strategies:

In contrast, randomized strategies incorporate probabilities into the decisionmaking process. For a state S, the strategy of the player for choosing an action is probabilistic. The strategy $\pi_i(s)$ assigns a probability to each possible action, meaning that $\pi_i(s)$ belongs to the set of all probability distributions over the set of actions available at state S, provided player(s) = i i.e.,

$$\pi_i(s) \in \Delta(\operatorname{actions}(s))$$
 if $\operatorname{player}(s) = i$

where $\Delta(A)$ denotes the set of all probability distributions over the set A, which in this context, is the set of actions available at state S.

Consider the above game of brother and sister sharing two chocolates, and at state n_1 , if the brother's strategy is stochastic,

$$\pi_B(n_1) = \left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right)$$

This implies that for the state n_1 , the brother's strategy assigns equal probabilities to each possible action (A, B, C). Specifically, each action (A, B, C) has a 1/3 chance of being chosen.

19.5 Games with partial information

Consider the game tree below:



Note: $\Pi_{agent}(s)[a]$ and $\Pi_{opponent}(s)[a]$ are probabilities that the agent and the opponent pick action 'a' respectively.

 \rightarrow If the opponent is stochastic but the player is a utility maximizer: Then the player is called a 'Max player'. Now the utility of the agent changes to

$$u_{agent}(s) = \begin{cases} utility(s) & \text{if isEnd(s)} \\ \max_{a \in actions(s)} u_{agent}(\operatorname{successor}(s, a)) & \text{if player(s)} = \operatorname{agent} \\ \sum_{a \in actions(s)} \prod_{opponent}(s)[a] u_{agent}(\operatorname{successor}(s, a)) & \text{if player(s)} = \operatorname{opponent} \end{cases}$$

 \rightarrow If the opponent is a utility minimizer:

Then the opponent is called a 'Min player'. Now the utility of the agent changes to

 $u_{agent}(s) = \begin{cases} utility(s) & if \text{ isEnd(s)} \\ \max_{a \in actions(s)} u_{agent}(\operatorname{successor}(s, a)) & if \text{ player(s)} = \operatorname{agent} \\ \min_{a \in actions(s)} u_{agent}(\operatorname{successor}(s, a)) & if \text{ player(s)} = \operatorname{opponent} \end{cases}$

$$\begin{split} \mathbf{Q} &: \text{Is } \Pi^{\max \min}_{\text{agent}} \text{ the optimal strategy when } \Pi^{\text{stochastic}}_{\text{opponent}} ? \\ \mathbf{A} &: \text{No, we don't have an optimal policy, rather we have an equilibrium } (\Pi^{\max \min}_{\text{agent}} , \Pi^{\min}_{\text{opponent}}). \end{split}$$

 \mathbf{Q} : Is ($\Pi_{agent}^{stochastic}$, $\Pi_{opponent}^{stochastic}$) an equilibrium ? \mathbf{A} : No.

19.6 Subgame and Subgame Perfection



A subgame at 'S' is a restriction of the game at the subtree rooted at 'S' where isEnd(s) is false.

Here, **Player 1** is a utility maximizer (**Max Player**) i.e. plays to maximize his utility. Hence if player(s) = player 1, the utility of Player 1 changes to, $u_1(s) = \max_{a \in actions(s)} u_1(successor(s, a))$

Player 2 is the utility minimiser (**Min Player**) i.e. plays to minimize his utility. Hence if player(s) = player 2, the utility of Player 1 changes to, $u_1(s) = \min_{a \in actions(s)} u_1(\operatorname{successor}(s, a))$

Let us look at the subgame at node n_4 :



In this subgame, it's Player 1's turn and he is a max player.

Player 1 (max player) should **pick** 'G' here so as to get '2' (> 1, that he would have got by choosing 'H'). We are done solving this subgame.

Similarly using the result of the subgame at n_4 , we can solve the subgame at n_3 , and this way we move to the upper levels.

Let us take a look at the **subgame at** n_3 :



In this subgame, it's Player 2's turn and he is a min player. Therefore, he should **pick 'F'** so that player 1 gets '2' (from n_4 , instead of getting '5' by picking 'E').

Let us look at the **subgame at** n_2 :



In this subgame, it's Player 2's turn and he is a min player. Therefore, he should **pick 'C'** so that player 1 gets '3' (instead of getting '8' by picking 'D').

Now, let us take a look at the **subgame at** n_1 :



In this subgame, it's Player 1's turn.

Player 1 (max player) should **pick 'A'** here to get '3' (> 2, that he would have got by choosing 'B'). Therefore, the **final utility of the Player 1 = 3**

Subgame Perfect Equilibrium is an equilibrium at every subgame/subtree. The **summary of solving the above game** is:

- Player 1 will choose 'H' in the subgame at n_4
- Player 2 will choose 'F' in the subgame at n_3
- player 2 will choose 'C' in the subgame at n_2
- player 1 will choose 'A' in the subgame at n_1

19.7 Backward Induction

```
function BackInd(s):
    if isEnd(s):
        return u_{agent}, \phi
                                    // empty set as we don't have any action here
    if player(s) = agent:
                                                // try to maximize utility
        bestUtility = -\infty
        for all a \in actions(s) do:
             utilityAtChild, bestAvector \leftarrow BackInd(succ(s,a))
             if utilityAtChild > bestUtility:
                 bestUtility = utilityAtChild
                 bestAvector = append(a, bestAvector)
    if player(s) = opponent:
                                                // try to minimize utility
        bestUtility = \infty
        for all a \in actions(s) do:
             utilityAtChild, bestAvector \leftarrow BackInd(succ(s,a))
             if utilityAtChild < bestUtility:
                 bestUtility = utilityAtChild
                 bestAvector = append(a, bestAvector)
    return bestUtility, action_vector(bestAvector)
```

We can apply Backward induction on small games like Tic-tac-toe. But can apply it to Chess, Go, Checkers, etc.? We can, but the game tree is huge.

Checkers game tree ~ 10^{20} nodes Chess game tree ~ 10^{40} nodes Go game tree ~ 10^{170} nodes Checkers was solved in 2007 after 18 years of computation and the optimal solution was a Draw.