

General Data Flow Frameworks

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CS 618

General Frameworks: About These Slides

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Copyright

These slides constitute the lecture notes for CS618 Program Analysis course at IIT Bombay and have been made available as teaching material accompanying the book:

- Uday Khedker, Amitabha Sanyal, and Bageshri Karkare. *Data Flow Analysis: Theory and Practice*. CRC Press (Taylor and Francis Group). 2009.

Apart from the above book, some slides are based on the material from the following book

- M. S. Hecht. *Flow Analysis of Computer Programs*. Elsevier North-Holland Inc. 1977.

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Part 1

About These Slides

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General Frameworks: Outline

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Outline

- Modelling General Flows
- Constant Propagation
- Faint Variables Analysis
- Pointer Analyses
- Heap Reference Analysis



Modelling Flow Functions for General Flows

- General flow functions can be written as

$$f_n(X) = (X - \text{Kill}_n(X)) \cup \text{Gen}_n(X)$$

where Gen and Kill have constant and dependent parts

$$\text{Gen}_n(X) = \text{ConstGen}_n \cup \text{DepGen}_n(X)$$

$$\text{Kill}_n(X) = \text{ConstKill}_n \cup \text{DepKill}_n(X)$$

- The dependent parts take care of
 - ▶ dependence across different entities as well as
 - ▶ dependence on the value of the same entity in the argument X
- Bit vector frameworks are a special case

$$\text{DepGen}_n(X) = \text{DepKill}_n(X) = \emptyset$$

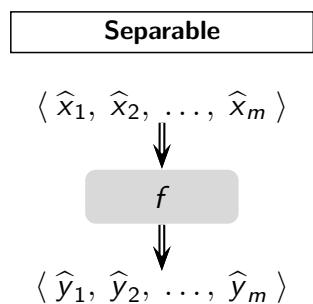
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Separability

$f : L \mapsto L$ is $\langle \hat{h}_1, \hat{h}_2, \dots, \hat{h}_m \rangle$ where \hat{h}_i computes the value of \hat{x}_i



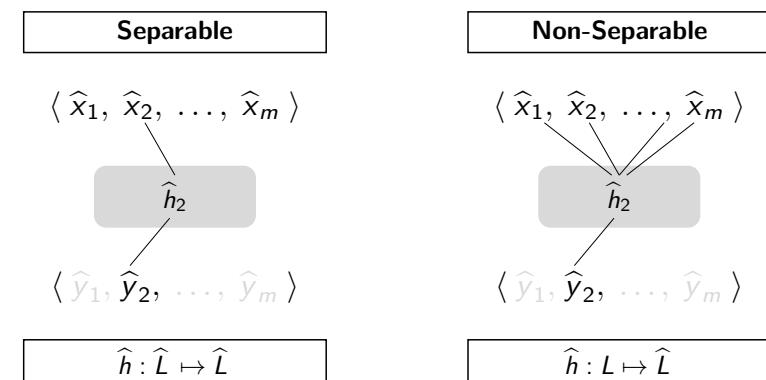
Example: All bit vector frameworks

Example: Constant Propagation



Separability

$f : L \mapsto L$ is $\langle \hat{h}_1, \hat{h}_2, \dots, \hat{h}_m \rangle$ where \hat{h}_i computes the value of \hat{x}_i



Example: All bit vector frameworks

Example: All bit vector frameworks

Example: Constant Propagation



Larger Values of Loop Closure Bounds

- Fast Frameworks \equiv 2-bounded frameworks (eg. bit vector frameworks)
Both these conditions must be satisfied
 - Separability*
Data flow values of different entities are independent
 - Constant or Identity Flow Functions*
Flow functions for an entity are either constant or identity
- Non-fast frameworks
At least one of the above conditions is violated

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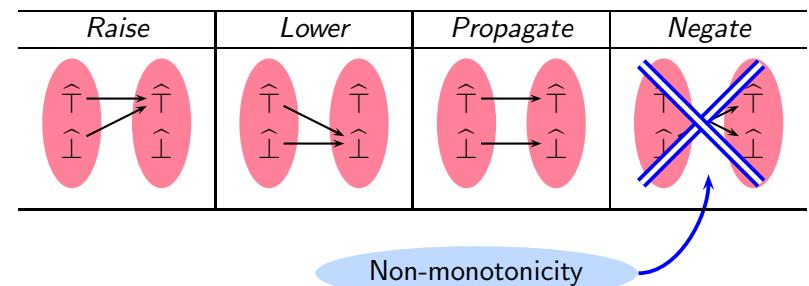


Part 3

Constant Propagation

Separability of Bit Vector Frameworks

- \hat{L} is $\{0, 1\}$, L is $\{0, 1\}^m$
- $\hat{\wedge}$ is either boolean AND or boolean OR
- $\hat{\top}$ and $\hat{\perp}$ are 0 or 1 depending on $\hat{\wedge}$.
- \hat{h} is a *bit function* and could be one of the following:



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General Frameworks: Constant Propagation

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Example of Constant Propagation

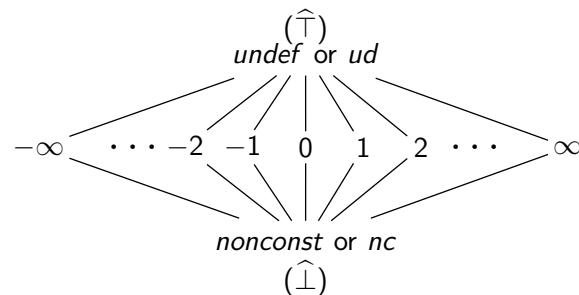
	MoP	MFP
n_1	$\langle \hat{\top}, \hat{\top}, \hat{\top}, \hat{\top} \rangle$	$\langle \hat{\top}, \hat{\top}, \hat{\top}, \hat{\top} \rangle$
	$\langle 1, 2, 3, \hat{\top} \rangle$	$\langle 1, 2, 3, \hat{\top} \rangle$
n_2	$\langle \hat{\perp}, \hat{\perp}, 3, 2 \rangle$	$\langle \hat{\perp}, \hat{\perp}, 3, \hat{\perp} \rangle$
	$\langle \hat{\perp}, \hat{\perp}, 3, 2 \rangle$	$\langle \hat{\perp}, \hat{\perp}, \hat{\perp}, \hat{\perp} \rangle$
n_3	$\langle \hat{\perp}, \hat{\perp}, 3, 2 \rangle$	$\langle \hat{\perp}, \hat{\perp}, \hat{\perp}, \hat{\perp} \rangle$
	$\langle 2, 1, 3, 2 \rangle$	$\langle 2, 1, 3, \hat{\perp} \rangle$

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Component Lattice for Integer Constant Propagation



- Overall lattice L is the product of \widehat{L} for all variables.
- \sqcap and $\widehat{\sqcap}$ get defined by \sqsubseteq and $\widehat{\sqsubseteq}$.

$\widehat{\sqcap}$	$\langle v, ud \rangle$	$\langle v, nc \rangle$	$\langle v, c_1 \rangle$
$\langle v, ud \rangle$	$\langle v, ud \rangle$	$\langle v, nc \rangle$	$\langle v, c_1 \rangle$
$\langle v, nc \rangle$	$\langle v, nc \rangle$	$\langle v, nc \rangle$	$\langle v, nc \rangle$
$\langle v, c_2 \rangle$	$\langle v, c_2 \rangle$	$\langle v, nc \rangle$	If $c_1 = c_2$ then $\langle v, c_1 \rangle$ else $\langle v, nc \rangle$



Defining Data Flow Equations for Constant Propagation

	$ConstGen_n$	$DepGen_n(X)$	$ConstKill_n$	$DepKill_n(X)$
$v = c, c \in \text{Const}$	$\{\langle v, c \rangle\}$	\emptyset	\emptyset	$\{\langle v, d \rangle \mid \langle v, d \rangle \in X\}$
$v = e, e \in \text{Expr}$	\emptyset	$\{\langle v, eval(e, X) \rangle\}$	\emptyset	$\{\langle v, d \rangle \mid \langle v, d \rangle \in X\}$
$read(v)$	$\{\langle v, nc \rangle\}$	\emptyset	\emptyset	$\{\langle v, d \rangle \mid \langle v, d \rangle \in X\}$
$other$	\emptyset	\emptyset	\emptyset	\emptyset

$eval(a_1 op a_2, X)$			
	$\langle a_1, ud \rangle \in X$	$\langle a_1, nc \rangle \in X$	$\langle a_1, c_1 \rangle \in X$
$\langle a_2, ud \rangle \in X$	ud	nc	ud
$\langle a_2, nc \rangle \in X$	nc	nc	nc
$\langle a_2, c_2 \rangle \in X$	ud	nc	$c_1 op c_2$



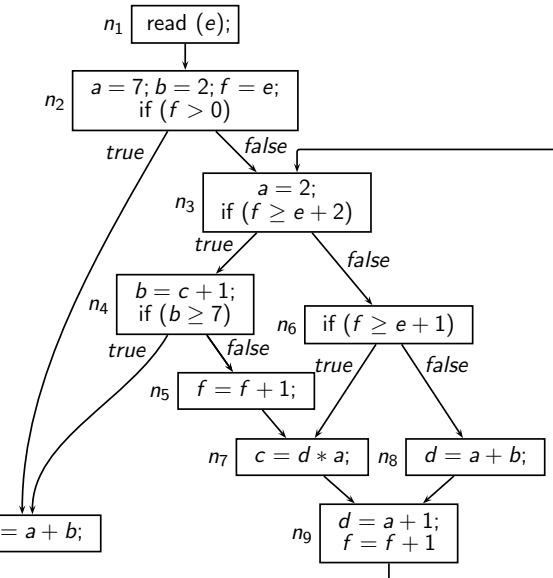
Flow Functions for Constant Propagation

- Flow function for $r = a_1 * a_2$

$mult$	$\langle a_1, ud \rangle$	$\langle a_1, nc \rangle$	$\langle a_1, c_1 \rangle$
$\langle a_2, ud \rangle$	$\langle r, ud \rangle$	$\langle r, nc \rangle$	$\langle r, ud \rangle$
$\langle a_2, nc \rangle$	$\langle r, nc \rangle$	$\langle r, nc \rangle$	$\langle r, nc \rangle$
$\langle a_2, c_2 \rangle$	$\langle r, ud \rangle$	$\langle r, nc \rangle$	$\langle r, (c_1 * c_2) \rangle$



Example Program for Constant Propagation



Result of Constant Propagation

	Iteration #1	Changes in iteration #2	Changes in iteration #3	Changes in iteration #4
In_{n_1}	$\top, \top, \top, \top, \top, \top$			
Out_{n_1}	$\top, \top, \top, \top, \perp, \top$			
In_{n_2}	$\top, \top, \top, \top, \perp, \top$			
Out_{n_2}	$7, 2, \top, \top, \perp, \top$			
In_{n_3}	$7, 2, \top, \top, \perp, \top$	$\hat{1}, 2, \hat{\top}, 3, \hat{\top}, \hat{\top}$	$\hat{1}, 2, 6, 3, \hat{\top}, \hat{\top}$	$\hat{1}, \hat{1}, 6, 3, \hat{\top}, \hat{\top}$
Out_{n_3}	$2, 2, \top, \top, \perp, \top$	$2, 2, \hat{\top}, 3, \hat{\top}, \hat{\top}$	$2, 2, 6, 3, \hat{\top}, \hat{\top}$	$2, \perp, 6, 3, \hat{\top}, \hat{\top}$
In_{n_4}	$2, 2, \top, \top, \perp, \top$	$2, 2, \hat{\top}, 3, \hat{\top}, \hat{\top}$	$2, 2, 6, 3, \hat{\top}, \hat{\top}$	$2, \perp, 6, 3, \hat{\top}, \hat{\top}$
Out_{n_4}	$2, \hat{\top}, \top, \top, \perp, \top$	$2, \hat{\top}, \top, 3, \hat{\top}, \hat{\top}$	$2, 7, 6, 3, \hat{\top}, \hat{\top}$	
In_{n_5}	$2, \hat{\top}, \top, \top, \perp, \top$	$2, \hat{\top}, \top, 3, \hat{\top}, \hat{\top}$	$2, 7, 6, 3, \hat{\top}, \hat{\top}$	
Out_{n_5}	$2, \hat{\top}, \top, \top, \perp, \top$	$2, \hat{\top}, \top, 3, \hat{\top}, \hat{\top}$	$2, 7, 6, 3, \hat{\top}, \hat{\top}$	
In_{n_6}	$2, 2, \top, \top, \perp, \top$	$2, 2, \hat{\top}, 3, \hat{\top}, \hat{\top}$	$2, 2, 6, 3, \hat{\top}, \hat{\top}$	$2, \perp, 6, 3, \hat{\top}, \hat{\top}$
Out_{n_6}	$2, 2, \top, \top, \perp, \top$	$2, 2, \hat{\top}, 3, \hat{\top}, \hat{\top}$	$2, 2, 6, 3, \hat{\top}, \hat{\top}$	$2, \perp, 6, 3, \hat{\top}, \hat{\top}$
In_{n_7}	$2, 2, \top, \top, \perp, \top$	$2, 2, \hat{\top}, 3, \hat{\top}, \hat{\top}$	$2, \perp, 6, 3, \hat{\top}, \hat{\top}$	
Out_{n_7}	$2, 2, \top, \top, \perp, \top$	$2, 2, 6, 3, \hat{\top}, \hat{\top}$	$2, \perp, 6, 3, \hat{\top}, \hat{\top}$	
In_{n_8}	$2, 2, \top, \top, \perp, \top$	$2, 2, \hat{\top}, 3, \hat{\top}, \hat{\top}$	$2, 2, 6, 3, \hat{\top}, \hat{\top}$	$2, \perp, 6, 3, \hat{\top}, \hat{\top}$
Out_{n_8}	$2, 2, \top, 4, \perp, \top$	$2, 2, \hat{\top}, 4, \perp, \top$	$2, 2, 6, 4, \perp, \top$	$2, \perp, 6, \perp, \top, \top$
In_{n_9}	$2, 2, \top, 4, \perp, \top$	$2, 2, 6, \perp, \top, \top$	$2, \perp, 6, \perp, \top, \top$	
Out_{n_9}	$2, 2, \top, 3, \perp, \top$	$2, 2, 6, 3, \perp, \top$	$2, \perp, 6, 3, \perp, \top$	
$In_{n_{10}}$	$\hat{1}, 2, \hat{\top}, \top, \perp, \top$	$\hat{1}, 2, \hat{\top}, 3, \hat{\top}, \hat{\top}$	$\hat{1}, \hat{1}, 6, 3, \perp, \top$	
$Out_{n_{10}}$	$\hat{1}, 2, \hat{\top}, \top, \perp, \top$	$\hat{1}, 2, \hat{\top}, 3, \hat{\top}, \hat{\top}$	$\hat{1}, \hat{1}, 6, 3, \perp, \top$	

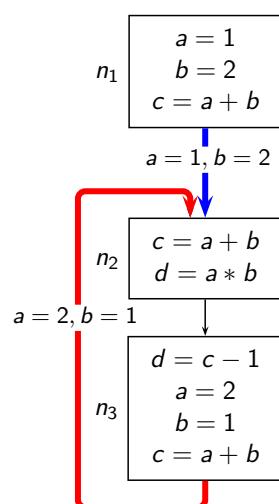
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Non-Distributivity of Constant Propagation



- $x = \langle 1, 2, 3, ? \rangle$ (Along $Out_{n_1} \rightarrow In_{n_2}$)
- $y = \langle 2, 1, 3, 2 \rangle$ (Along $Out_{n_3} \rightarrow In_{n_2}$)
- Function application before merging

$$\begin{aligned} f(x) \sqcap f(y) &= f(\langle 1, 2, 3, ? \rangle) \sqcap f(\langle 2, 1, 3, 2 \rangle) \\ &= \langle 1, 2, 3, 2 \rangle \sqcap \langle 2, 1, 3, 2 \rangle \\ &= \langle \hat{1}, \hat{1}, 3, 2 \rangle \end{aligned}$$

- Function application after merging

$$\begin{aligned} f(x \sqcap y) &= f(\langle 1, 2, 3, ? \rangle \sqcap \langle 2, 1, 3, 2 \rangle) \\ &= f(\langle \hat{1}, \hat{1}, 3, 2 \rangle) \\ &= \langle \hat{1}, \hat{1}, \hat{1}, \hat{1} \rangle \end{aligned}$$

- $f(x \sqcap y) \sqsubset f(x) \sqcap f(y)$

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Monotonicity of Constant Propagation

- Flow function $f_n(X) = (X - Kill_n(X)) \cup Gen_n(X)$ where

$$Gen_n(X) = ConstGen_n \cup DepGen_n(X)$$

$$Kill_n(X) = ConstKill_n \cup DepKill_n(X)$$

- $ConstGen_n$ and $ConstKill_n$ are trivially monotonic

- To show $X_1 \sqsubseteq X_2 \Rightarrow DepGen_n(X_1) \sqsubseteq DepGen_n(X_2)$ we need to show that $X_1 \sqsubseteq X_2 \Rightarrow eval(e, X_1) \sqsubseteq eval(e, X_2)$. This follows from definition of $eval(e, X)$.

- To show $X_1 \sqsubseteq X_2 \Rightarrow (X_1 - DepKill_n(X_1)) \sqsubseteq (X_1 - DepKill_n(X_2))$ observe that $DepKill_n$ removes the pair corresponding to the variable modified in statement n . Data flow values of other variables remain unaffected.

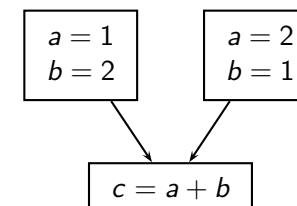
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Why is Constant Propagation Non-Distributive?

Possible combinations due to merging



$$\begin{array}{ccccccc} a = 1 & & a = 2 & & b = 1 & & b = 2 \\ & \searrow & & & \swarrow & & \\ & & c = a + b & & & & \end{array}$$

- Correct combination.

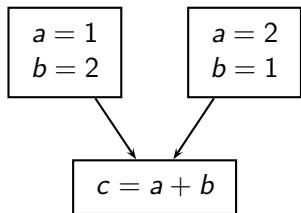
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Why is Constant Propagation Non-Distributive?

Possible combinations due to merging



$$\begin{array}{cccc} a = 1 & a = 2 & b = 1 & b = 2 \\ & \searrow & \swarrow & \\ & c = a + b = 3 & & \end{array}$$

- Correct combination.

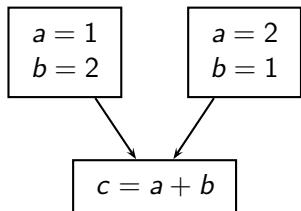
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Why is Constant Propagation Non-Distributive?

Possible combinations due to merging



$$\begin{array}{cccc} a = 1 & a = 2 & b = 1 & b = 2 \\ & \searrow & \swarrow & \\ & c = a + b = 4 & & \end{array}$$

- Wrong combination.
- Mutually exclusive information.
- No execution path along which this information holds.

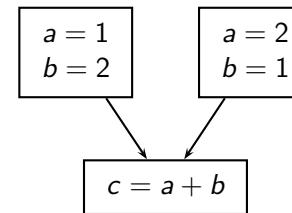
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Why is Constant Propagation Non-Distributive?

Possible combinations due to merging



$$\begin{array}{cccc} a = 1 & a = 2 & b = 1 & b = 2 \\ & \searrow & \swarrow & \\ & c = a + b = 2 & & \end{array}$$

- Wrong combination.
- Mutually exclusive information.
- No execution path along which this information holds.

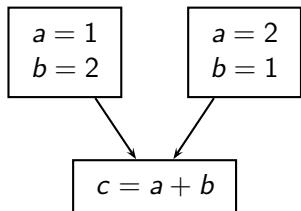
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Why is Constant Propagation Non-Distributive?

Possible combinations due to merging



$$\begin{array}{cccc} a = 1 & a = 2 & b = 1 & b = 2 \\ & \searrow & \swarrow & \\ & c = a + b = 4 & & \end{array}$$

- Wrong combination.
- Mutually exclusive information.
- No execution path along which this information holds.

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Boundedness of Constant Propagation

Summary flow function:
(data flow value at node 7)

$$f(\langle v_a, v_b, v_c \rangle) = \langle 1 \sqcap (v_b + 1), (v_c + 1), (v_a + 1) \rangle$$

$$f^0(\top) = \langle \hat{\top}, \hat{\top}, \hat{\top} \rangle$$

$$f^1(\top) = \langle 1, \hat{\top}, \hat{\top} \rangle$$

$$f^2(\top) = \langle 1, \hat{\top}, 2 \rangle$$

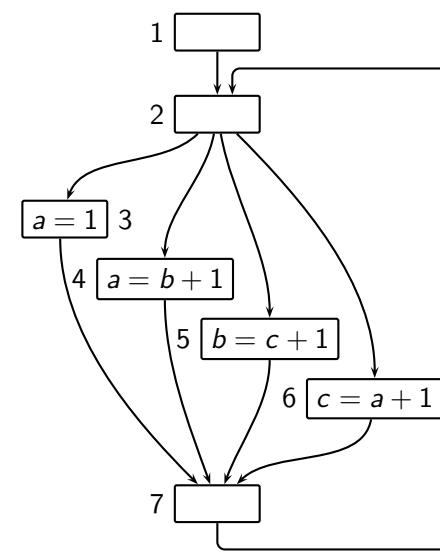
$$f^3(\top) = \langle 1, 3, 2 \rangle$$

$$f^4(\top) = \langle \perp, 3, 2 \rangle$$

$$f^5(\top) = \langle \perp, 3, \perp \rangle$$

$$f^6(\top) = \langle \perp, \perp, \perp \rangle$$

$$f^7(\top) = \langle \perp, \hat{\perp}, \hat{\perp} \rangle$$

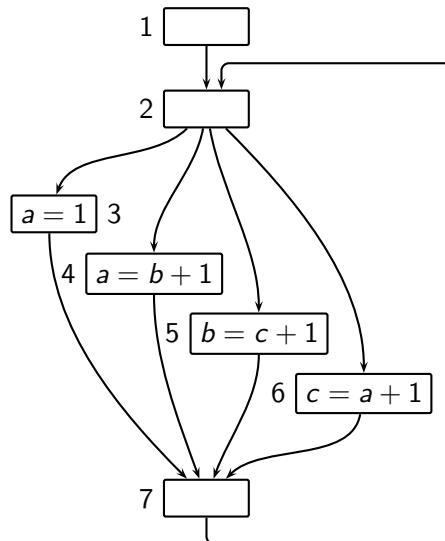


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Boundedness of Constant Propagation



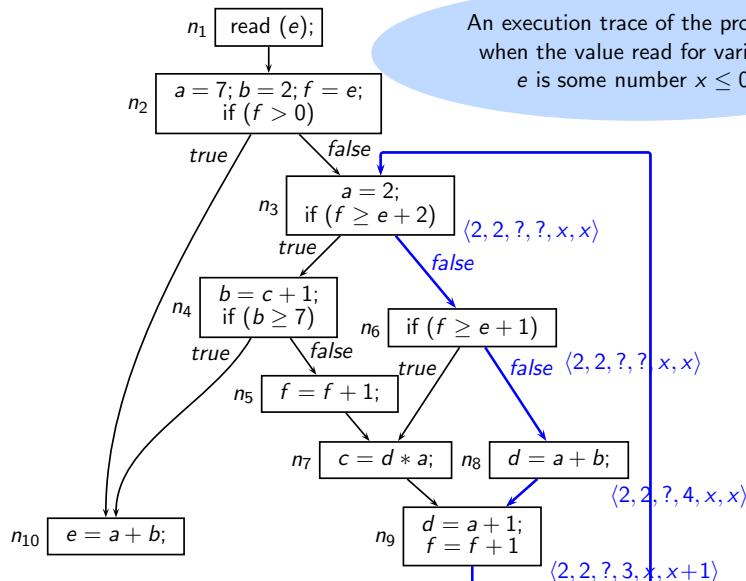
$$f^*(\top) = \bigcap_{i=0}^6 f^i(\top)$$

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Conditional Constant Propagation



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Boundedness of Constant Propagation

The moral of the story:

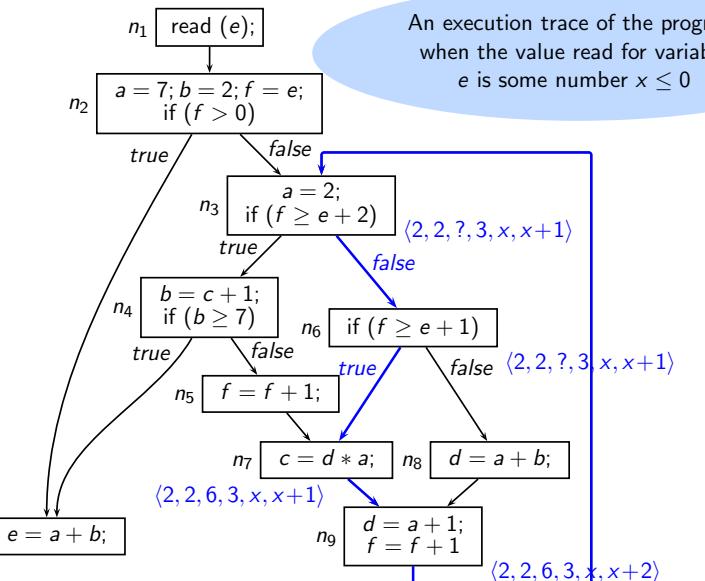
- The data flow value of every variable could change twice
- In the worst case, only one change may happen in every step of a function application
- Maximum number of steps: $2 \times |\mathbb{V}\text{ar}|$
- Boundedness parameter k is $(2 \times |\mathbb{V}\text{ar}|) + 1$

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Conditional Constant Propagation

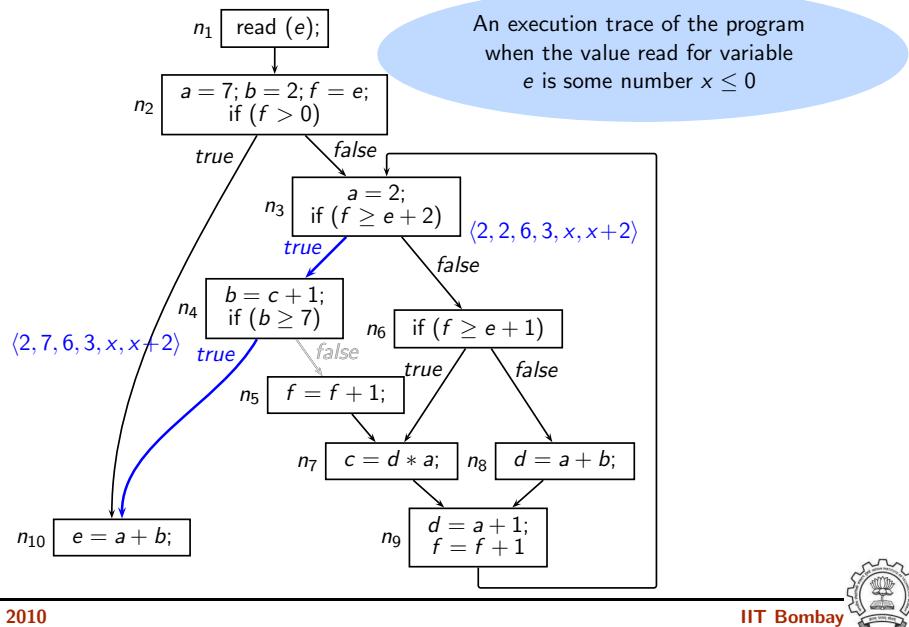


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Conditional Constant Propagation

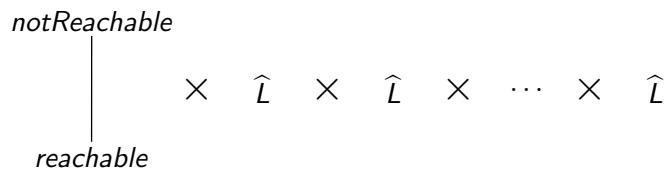


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Lattice for Conditional Constant Propagation



- Let $\langle s, X \rangle$ denote an augmented data flow value where $s \in \{reachable, notReachable\}$ and $X \in L$.
- If we can maintain the invariant $s = notReachable \Rightarrow X = \top$, then the meet can be defined as

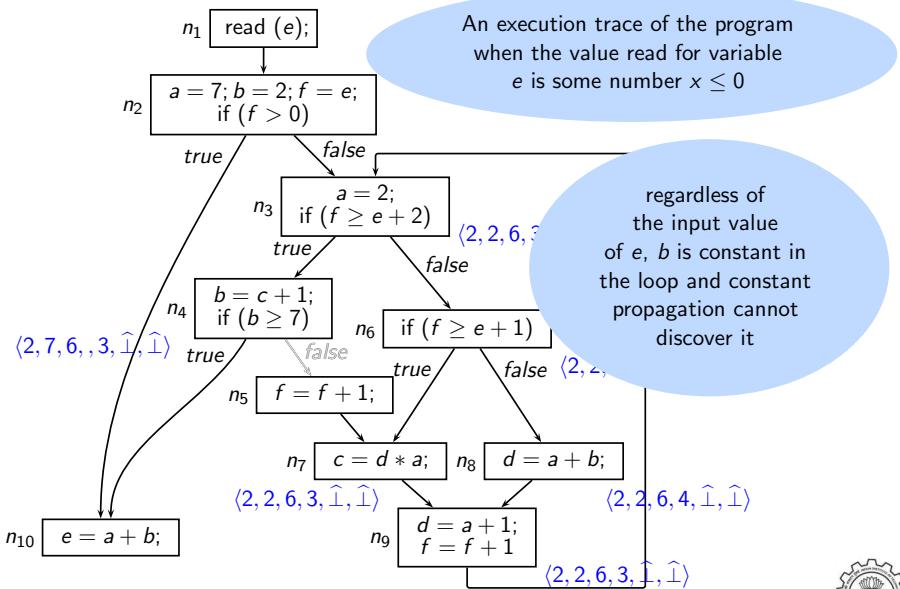
$$\langle s_1, X_1 \rangle \sqcap_c \langle s_2, X_2 \rangle = \langle s_1 \sqcap_c s_2, X_1 \sqcap X_2 \rangle$$

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Conditional Constant Propagation



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Data Flow Equations for Conditional Constant Propagation

$$In_n = \begin{cases} \langle reachable, BI \rangle & n \text{ is Start} \\ \bigcap_{p \in pred(n)} g_{p \rightarrow n}(Out_p) & \text{otherwise} \end{cases}$$

$$Out_n = \begin{cases} \langle reachable, f_n(X) \rangle & In_n = \langle reachable, X \rangle \\ \langle notReachable, \top \rangle & \text{otherwise} \end{cases}$$

$$g_{m \rightarrow n}(s, X) = \begin{cases} \langle notReachable, \top \rangle & evalCond(m, X) \neq undefined \text{ and} \\ & evalCond(m, X) \neq label(m \rightarrow n) \\ \langle s, X \rangle & \text{otherwise} \end{cases}$$

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Conditional Constant Propagation

	Iteration #1	Changes in iteration #2	Changes in iteration #3
In_{n_1}	$R, \langle \top, \top, \top, \top, \top, \top \rangle$		
Out_{n_1}	$R, \langle \top, \top, \top, \top, \top, \top \rangle$		
In_{n_2}	$R, \langle \top, \top, \top, \top, \perp, \perp \rangle$		
Out_{n_2}	$R, \langle 7, 2, \top, \top, \perp, \perp \rangle$		
In_{n_3}	$R, \langle 7, 2, \top, \top, \perp, \perp \rangle$	$R, \langle \perp, 2, 6, 3, \top, \top \rangle$	$R, \langle \perp, 2, 6, 3, \top, \top \rangle$
Out_{n_3}	$R, \langle 2, 2, \top, \top, \perp, \perp \rangle$	$R, \langle 2, 2, 6, 3, \top, \top \rangle$	$R, \langle 2, 2, 6, 3, \top, \top \rangle$
In_{n_4}	$R, \langle 2, 2, \top, \top, \perp, \perp \rangle$	$R, \langle 2, 2, \top, 3, \top, \top \rangle$	$R, \langle 2, 2, 6, 3, \top, \top \rangle$
Out_{n_4}	$R, \langle 2, \top, \top, \top, \perp, \perp \rangle$	$R, \langle 2, \top, \top, 3, \top, \top \rangle$	$R, \langle 2, 7, 6, 3, \top, \top \rangle$
In_{n_5}	$R, \langle 2, \top, \top, \top, \perp, \perp \rangle$	$R, \langle 2, \top, \top, 3, \top, \top \rangle$	$N, T = \langle \top, \top, \top, \top, \top, \top \rangle$
Out_{n_5}	$R, \langle 2, \top, \top, \top, \perp, \perp \rangle$	$R, \langle 2, \top, \top, 3, \top, \top \rangle$	$N, T = \langle \top, \top, \top, \top, \top, \top \rangle$
In_{n_6}	$R, \langle 2, 2, \top, \top, \perp, \perp \rangle$	$R, \langle 2, 2, \top, 3, \top, \top \rangle$	$R, \langle 2, 2, 6, 3, \top, \top \rangle$
Out_{n_6}	$R, \langle 2, 2, \top, \top, \perp, \perp \rangle$	$R, \langle 2, 2, \top, 3, \top, \top \rangle$	$R, \langle 2, 2, 6, 3, \top, \top \rangle$
In_{n_7}	$R, \langle 2, 2, \top, \top, \perp, \perp \rangle$	$R, \langle 2, 2, \top, 3, \top, \top \rangle$	$R, \langle 2, 2, 6, 3, \top, \top \rangle$
Out_{n_7}	$R, \langle 2, 2, \top, \top, \perp, \perp \rangle$	$R, \langle 2, 2, 6, 3, \top, \top \rangle$	$R, \langle 2, 2, 6, 3, \top, \top \rangle$
In_{n_8}	$R, \langle 2, 2, \top, \top, \perp, \perp \rangle$	$R, \langle 2, 2, \top, 3, \top, \top \rangle$	$R, \langle 2, 2, 6, 3, \top, \top \rangle$
Out_{n_8}	$R, \langle 2, 2, \top, 4, \perp, \perp \rangle$	$R, \langle 2, 2, \top, 4, \perp, \perp \rangle$	$R, \langle 2, 2, 6, 4, \perp, \perp \rangle$
In_{n_9}	$R, \langle 2, 2, \top, 4, \perp, \perp \rangle$	$R, \langle 2, 2, 6, \perp, \perp, \perp \rangle$	$R, \langle 2, 2, 6, \perp, \perp, \perp \rangle$
Out_{n_9}	$R, \langle 2, 2, \top, 3, \perp, \perp \rangle$	$R, \langle 2, 2, 6, 3, \perp, \perp \rangle$	$R, \langle 2, 2, 6, 3, \perp, \perp \rangle$
$In_{n_{10}}$	$R, \langle \perp, 2, \top, \top, \perp, \perp \rangle$	$R, \langle \perp, 2, \top, 3, \perp, \perp \rangle$	$R, \langle \perp, \perp, 6, 3, \perp, \perp \rangle$
$Out_{n_{10}}$	$R, \langle \perp, 2, \top, \top, \perp, \perp \rangle$	$R, \langle \perp, 2, \top, 3, \perp, \perp \rangle$	$R, \langle \perp, \perp, 6, 3, \perp, \perp \rangle$



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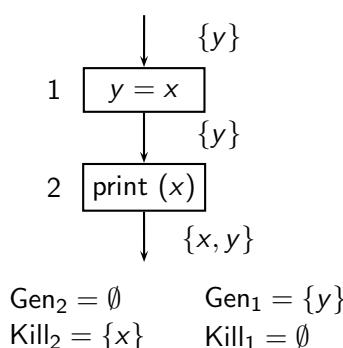
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Part 4

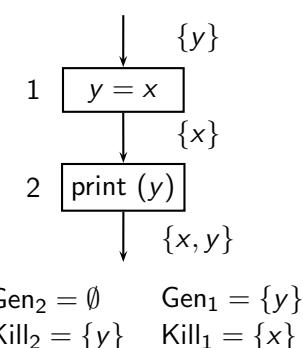
Faint Variables Analysis

Faint Variables Analysis

A variable is faint if it is dead or is used in computing faint variables.

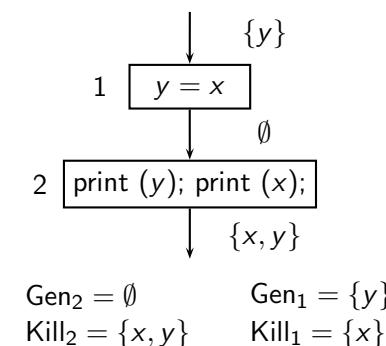


Faintness of x is killed by the print statement (i.e. x becomes live)



Faintness of x is killed by the assignment to y (i.e. x becomes live)

Faint Variables Analysis



Faintness of x is killed both by the print statement and by the assignment to y (i.e. x becomes live)

Data Flow Equations for Faint Variables Analysis

$$\begin{aligned} In_n &= f_n(Out_n) \\ Out_n &= \begin{cases} BI & n \text{ is End} \\ \bigcap_{s \in succ(n)} In_s & \text{otherwise} \end{cases} \end{aligned}$$

where,

$$\begin{aligned} f_n(X) &= (X - (ConstKill_n \cup DepKill_n(X))) \\ &\cup (ConstGen_n \cup DepGen_n(X)) \end{aligned}$$

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Why is $DepGen_n(X) = \emptyset$ in Faint Variables Analysis?

Faintness can only be generated by an assignment statement, a read statement, or BI.

Consider an assignment statement $x = e$ where $e \in \text{Expr}$

- If $x \notin Opd(e)$ then x becomes faint unconditionally.
Case covered by $ConstGen_n$.
- For the operands of e (including x if it is in $Opd(e)$)
 - ▶ If $x \notin X$ (i.e. x is not faint after the assignment), operands cannot be faint before the assignment.
 - ▶ If $x \in X$ (i.e. is faint after the assignment), faintness of operands depends on their uses after the assignment.
 - ▶ If they are faint after the assignment, they continue to remain faint.
 - ▶ If they are not faint after the assignment, they cannot become faint before the assignment.

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Flow Function Components for Faint Variables Analysis

	Statement		
	$x = e$, $e \in \text{Expr}$	$read(x)$ (assigning value from input)	$use(x)$ (not in assignment)
$ConstGen_n$	$x \notin Opd(e) \Rightarrow \{x\}$ $x \in Opd(e) \Rightarrow \emptyset$	$\{x\}$	\emptyset
$ConstKill_n$	\emptyset	\emptyset	$\{x\}$
$DepGen_n(X)$	\emptyset	\emptyset	\emptyset
$DepKill_n(X)$	$x \notin X \Rightarrow Opd(e) \cap \text{Var}$ $x \in X \Rightarrow \emptyset$	\emptyset	\emptyset

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Faint Variable Analysis

- What is \widehat{L} for faint variables analysis?
- Is faint variables analysis a bit vector framework?
- Is faint variables analysis distributive? Monotonic?

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Distributivity of Faint Variables Analysis

Prove that

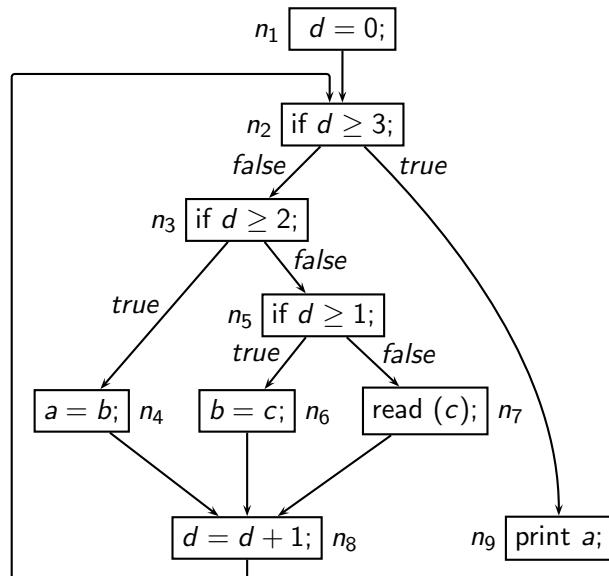
$$\forall X_1, X_2 \in L, f_n(X_1 \cap X_2) = f_n(X_1) \cap f_n(X_2)$$

- $ConstGen_n$, $DepGen_n$, and $ConstKill_n$ are trivially distributive.
Assume that $DepKill_n$ is \emptyset

$$f_n(X) = (X - ConstKill_n) \cup ConstGen_n \cup DepGen_n(X)$$

Since $DepGen_n(X) = \emptyset$, the flow function has only constant parts!

Example Program for Faint Variables Analysis



Distributivity of Faint Variables Analysis

To show that

$$(X_1 \cap X_2) - DepKill_n(X_1 \cap X_2) \\ = (X_1 - DepKill_n(X_1)) \cap (X_2 - DepKill_n(X_2))$$

- If n is an assignment statement $x = e$, and $x \notin X_1 \cap X_2$. Assume that x is neither in X_1 nor in X_2 .

$$(X_1 \cap X_2) - DepKill_n(X_1 \cap X_2) \\ = (X_1 \cap X_2) - (Opd(e) \cap \mathbb{Var}) \\ = (X_1 - (Opd(e) \cap \mathbb{Var})) \cap (X_2 - (Opd(e) \cap \mathbb{Var})) \\ = (X_1 - DepKill_n(X_1)) \cap (X_2 - DepKill_n(X_2))$$

What if x is in X_1 but not in X_2 ?

- In all other cases, $DepKill_n(X) = \emptyset$.

Result of Faint Variables Analysis

Node	Iteration #1		Changes in Iteration #2		Changes in Iteration #3		Changes in Iteration #4	
	Out _n	In _n	Out _n	In _n	Out _n	In _n	Out _n	In _n
n ₉	{a, b, c, d}	{b, c, d}						
n ₈	{a, b, c, d}	{a, b, c, d}	{b, c}	{b, c}	{c}	{c}	∅	∅
n ₇	{a, b, c, d}	{a, b, c, d}	{b, c}	{b, c}	{c}	{c}	∅	
n ₆	{a, b, c, d}	{a, b, c, d}	{b, c}	{b, c}	{c}	∅	∅	
n ₅	{a, b, c, d}	{a, b, c}	{b, c}	{b, c}	∅	∅		
n ₄	{a, b, c, d}	{a, b, c, d}	{b, c}	{a, c}	{c}		∅	∅
n ₃	{a, b, c}	{a, b, c}	{c}	{c}	∅	∅		
n ₂	{b, c}	{b, c}	{c}	{c}	∅	∅		
n ₁	{b, c}	{b, c, d}	{c}	{c, d}	∅	{d}		

Code Optimization In Presence of Pointers

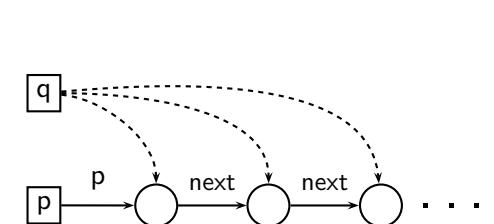
Part 5

Pointer Analyses

```

1. q = p;
2. while (...) {do {
3.     q = q->next;
4. }while (... )
5. p->data = r1;
6. print (q->data);
7. p->data = r2;
8. r4 = p->data + r3;

```



Program

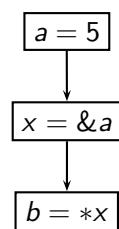
Memory graph at statement 5

- Is $p \rightarrow \text{data}$ live at the exit of line 5? Can we delete line 5?
- No, if p and q can be possibly aliased.
- Yes, if p and q are definitely not aliased.

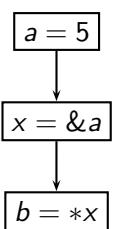
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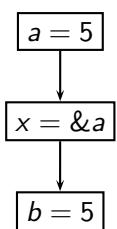
Code Optimization In Presence of Pointers



Original Program



Constant Propagation
without aliasing



Constant Propagation
with aliasing

The World of Pointer Analysis

Alias Analysis

Alias analysis
of reference
parameters,
fields of unions
array indices

Pointer Analysis

Alias analysis
of data pointers

Points-to
analysis of
data and
function
pointers

The Mathematics of Pointer Analysis

In the most general situation

- Alias analysis is undecidable.
Landi-Ryder [POPL 1991], Landi [LOPLAS 1992],
Ramalingam [TOPLAS 1994]
- Flow insensitive alias analysis is NP-hard
Horwitz [TOPLAS 1997]
- Points-to analysis is undecidable
Chakravarty [POPL 2003]

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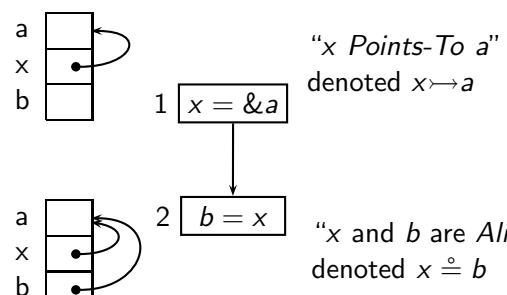


CS 618

General Frameworks: Pointer Analyses

37/98

Alias Information Vs. Points-To Information



- What about transitivity?
 - ▶ Points-To: No.
 - ▶ Alias: Depends.

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Motivation for a Good Science of Pointer Analysis

- To quote Hind [PASTE 2001]
 - ▶ Fortunately many approximations exist
 - ▶ Unfortunately too many approximations exist!
 - Pointer analysis enables not only precise data analysis but also precise control flow analysis.
 - Needs to scale to large programs.
 - Engineering of pointer analysis is much more dominant than the science of pointer analysis.
- ⇒ Results in many questionable perceptions.

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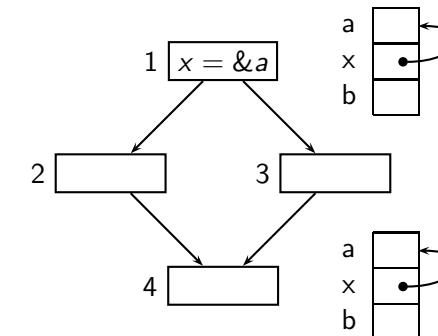


CS 618

General Frameworks: Pointer Analyses

38/98

Must Points-To Information

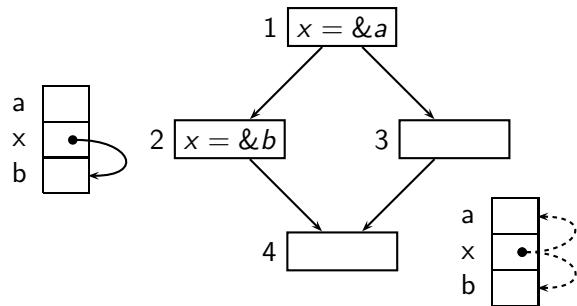


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May Points-To Information

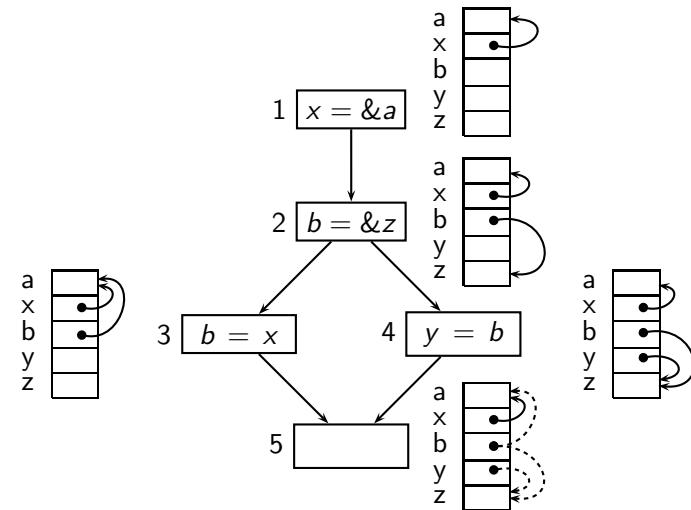


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May Alias Information

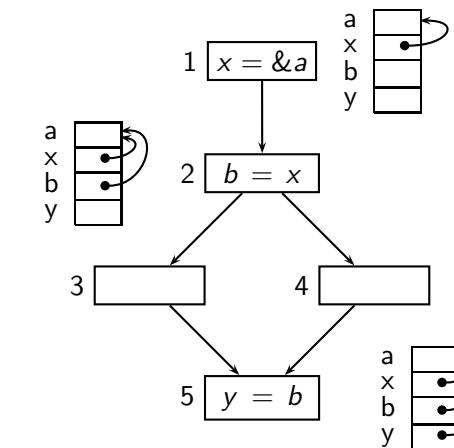

 $x \stackrel{\circ}{=} b \text{ and } b \stackrel{\circ}{=} y \not\Rightarrow x \stackrel{\circ}{=} y$

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Must Alias Information


 $x \stackrel{\circ}{=} b \text{ and } b \stackrel{\circ}{=} y \Rightarrow x \stackrel{\circ}{=} y$

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A Comparison of Points-To and Alias Relations

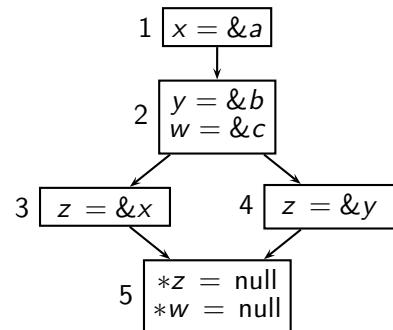
Asgn.	Memory	Points-to	Aliases
$*x = y$	Before	Existing $x \rightarrow u$ New Direct $y \rightarrow z$	Existing $*x \stackrel{\circ}{=} u$ $*y \stackrel{\circ}{=} z$
	After	New $u \rightarrow z$	New Direct $*x \stackrel{\circ}{=} y$ $y \stackrel{\circ}{=} u$
			New Indirect $*u \stackrel{\circ}{=} z$ $*x \stackrel{\circ}{=} z$
$*x = *y$	Before	Existing $x \rightarrow v$ New Direct $y \rightarrow z$ New Indirect $z \rightarrow u$	Existing $*x \stackrel{\circ}{=} v$ $*y \stackrel{\circ}{=} z$ $*z \stackrel{\circ}{=} u$ $*x \stackrel{\circ}{=} y$
	After	New $v \rightarrow u$	New Direct $*x \stackrel{\circ}{=} z$ $*x \stackrel{\circ}{=} y$ $v \stackrel{\circ}{=} z$ $v \stackrel{\circ}{=} y$
			New Indirect $*x \stackrel{\circ}{=} u$ $*v \stackrel{\circ}{=} u$

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Strong and Weak Updates



Weak update: Modification of x or y due to $*z$ in block 5

Strong update: Modification of c due to $*w$ in block 5

How is this concept related to May/Must nature of information?



What About Heap Data?

- Compile time entities, abstract entities, or summarized entities
- Three options:
 - ▶ Represent all heap locations by a single abstract heap location
 - ▶ Represent all heap locations of a particular type by a single abstract heap location
 - ▶ Represent all heap locations allocated at a given memory allocation site by a single abstract heap location
- Summarization: Usually based on the length of pointer expression
- No clean and elegant solution exists

Left and Right Locations in Pointer Assignments

For an assignment statement $lhs_n = rhs_n$

- Left Locations

Left Locations		
lhs_n	$ConstLeftL_n$	$DepLeftL_n(X)$
x	$\{x\}$	\emptyset
$*x$	\emptyset	$\{y \mid (x \rightarrow y) \in X\}$

- Right Locations

Right Locations		
rhs_n	$ConstRightL_n$	$DepRightL_n(X)$
x	\emptyset	$\{y \mid (x \rightarrow y) \in X\}$
$*x$	\emptyset	$\{z \mid \{x \rightarrow y, y \rightarrow z\} \subseteq X\}$
$\&x$	$\{x\}$	\emptyset

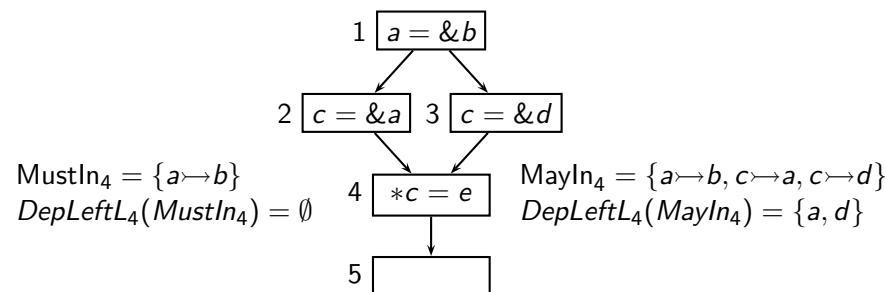


Gen and Kill Components

$$\begin{aligned}
 ConstGen_n &= \{x \rightarrow y \mid x \in ConstLeftL_n, y \in ConstRightL_n\} \\
 DepGen_n(X) &= \{x \rightarrow y \mid (x \in ConstLeftL_n, y \in DepRightL_n(X)), \text{ or } \\
 &\quad (x \in DepLeftL_n(X), y \in ConstRightL_n), \text{ or } \\
 &\quad (x \in DepLeftL_n(X), y \in DepRightL_n(X))\} \\
 ConstKill_n &= \{x \rightarrow y \mid x \in ConstLeftL_n\} \\
 DepKill_n(X) &= \{x \rightarrow y \mid x \in DepLeftL_n(X)\}
 \end{aligned}$$



DepKill(X) in May and Must Points-To Analysis



- $a \rightarrow b$ at block 5 along path 1, 3, 4, 5 but not along path 1, 2, 4, 5.
- $a \rightarrow b \in \text{MayIn}_5$ but $a \rightarrow b \notin \text{MustIn}_5$
- If DepKill_n for MayOut_4 is defined in terms of MayIn_4 then $a \rightarrow b \notin \text{MayOut}_4$ because a is in $\text{DepLeftL}_4(\text{MayIn}_4)$
- If DepKill_4 for MustOut_4 is defined in terms of MustIn_4 then $a \rightarrow b \in \text{MustOut}_4$ because a is not in $\text{DepLeftL}_4(\text{MustIn}_4)$



Data Flow Equations for Points-To Analysis

$$\begin{aligned} \text{MayIn}_n &= \begin{cases} BI & n \text{ is Start} \\ \bigcup_{p \in \text{pred}(n)} \text{MayOut}_n & \text{otherwise} \end{cases} \\ \text{MayOut}_n &= f_n(\text{MayIn}_n, \text{MustIn}_n) \\ \text{MustIn}_n &= \begin{cases} BI & n \text{ is Start} \\ \bigcap_{p \in \text{pred}(n)} \text{MustOut}_n & \text{otherwise} \end{cases} \\ \text{MustOut}_n &= f_n(\text{MustIn}_n, \text{MayIn}_n) \end{aligned}$$

$$f_n(X_1, X_2) = (X_1 - \text{Kill}_n(X_2)) \cup \text{Gen}_n(X_1)$$



DepKill(X) in May and Must Points-To Analysis

- May Points-To analysis
 - A points-to pair should be removed only if it must be removed along all paths
 - $\text{DepKill}(X)$ should remove only strong updates
 - X should be Must Points-To information
- Must Points-To analysis
 - A points-to pair should be removed if it can be removed along some path
 - $\text{DepKill}(X)$ should remove all weak updates
 - X should be May Points-To information
- Must Points-To \subseteq May Points-To



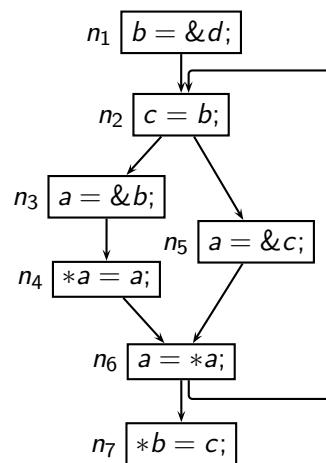
Approximating May and Must Alias and Points-To Information

- May Alias: Every pointer variable is aliased to every pointer variable.
- Must Alias: Every pointer variable is aliased only to itself.
- May Points-To: Every pointer variable points to every location.
- Must Points-To: No pointer variable points to any location.
- Both May and Must analyses need not be performed.

In every case, the approximation uses the \perp element of the lattice.



Example Program for Points-To Analysis



- Variables and points-to sets:

$$\text{Var} = \{a, b, c, d\}$$

$$\mathbb{U} = \{a \rightarrow a, a \rightarrow b, a \rightarrow c, a \rightarrow d, b \rightarrow a, b \rightarrow b, b \rightarrow d, b \rightarrow d, c \rightarrow a, c \rightarrow b, c \rightarrow c, c \rightarrow d, d \rightarrow a, d \rightarrow b, d \rightarrow c, d \rightarrow d\}$$

- $L_{may} = \langle 2^{\mathbb{U}}, \supseteq \rangle$, $\top_{may} = \emptyset, \perp_{may} = \mathbb{U}$

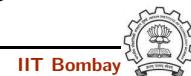
- $L_{must} = \widehat{L}_a \times \widehat{L}_b \times \widehat{L}_c \times \widehat{L}_d$

The component lattice \widehat{L}_a is:

$$\{a \rightarrow a, a \rightarrow b, a \rightarrow c, a \rightarrow d\}$$

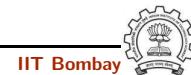
```

graph TD
    a1[a → a] --> a2[a → b]
    a1 --> a3[a → c]
    a1 --> a4[a → d]
    a2 --> a5[a → a]
    a2 --> a6[a → b]
    a3 --> a5
    a3 --> a7[a → c]
    a4 --> a5
    a4 --> a8[a → d]
    a5 --> a9[∅]
    a6 --> a9
    a7 --> a9
    a8 --> a9
  
```



Result of Pointer Analysis

	Iteration #1	Changes in Iteration #2	Changes in Iteration #3
$MayIn_{n_4}$	{a → b, b → d, c → d}	{a → b, b → b, b → d, c → b, c → d}	
$MustIn_{n_4}$	{a → b, b → d, c → d}	{a → b}	
$MayOut_{n_4}$	{a → b, b → d, c → d}	{a → b, b → b, c → b, c → d}	
$MustOut_{n_4}$	{a → b, b → d, c → d}	{a → b, b → b}	
$MayIn_{n_5}$	{b → d, c → d}	{a → b, a → d, b → b, b → d, c → b, c → d}	
$MustIn_{n_5}$	{b → d, c → d}	∅	
$MayOut_{n_5}$	{a → c, b → d, c → d}	{a → c, b → b, b → d, c → b, c → d}	
$MustOut_{n_5}$	{a → c, b → d, c → d}	{a → c}	



Result of Pointer Analysis

	Iteration #1	Changes in Iteration #2	Changes in Iteration #3
$MayIn_{n_1}$	∅		
$MustIn_{n_1}$	∅		
$MayOut_{n_1}$	{b → d}		
$MustOut_{n_1}$	{b → d}		
$MayIn_{n_2}$	{b → d}	{a → b, a → d, b → b, b → d, c → d}	{a → b, a → d, b → b, b → d, c → b, c → d}
$MustIn_{n_2}$	{b → d}	∅	
$MayOut_{n_2}$	{b → d, c → d}	{a → b, a → d, b → b, b → d, c → b, c → d}	
$MustOut_{n_2}$	{b → d, c → d}	∅	
$MayIn_{n_3}$	{b → d, c → d}	{a → b, a → d, b → b, b → d, c → b, c → d}	
$MustIn_{n_3}$	{b → d, c → d}	∅	
$MayOut_{n_3}$	{a → b, b → d, c → d}	{a → b, b → b, b → d, c → b, c → d}	
$MustOut_{n_3}$	{a → b, b → d, c → d}	{a → b}	



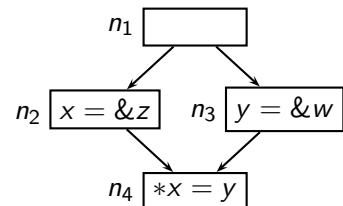
Result of Pointer Analysis

	Iteration #1	Changes in Iteration #2	Changes in Iteration #3
$MayIn_{n_6}$	{a → b, a → c, b → b, b → d, c → b, c → d}	{a → b, a → c, b → b, b → d, c → b, c → d}	
$MustIn_{n_6}$	{c → d}	∅	
$MayOut_{n_6}$	{a → b, a → d, b → b, b → d, c → d}	{a → b, a → d, b → b, b → d, c → b, c → d}	
$MustOut_{n_6}$	{c → d}	∅	
$MayIn_{n_7}$	{a → b, a → d, b → b, b → d, c → b, c → d}	{a → b, a → d, b → b, b → d, c → b, c → d}	
$MustIn_{n_7}$	{c → d}	∅	
$MayOut_{n_7}$	{a → b, a → d, b → b, b → d, c → b, c → d, d → b, d → d}	{a → b, a → d, b → b, b → d, c → b, c → d, d → b, d → d}	
$MustOut_{n_7}$	{c → d}	∅	



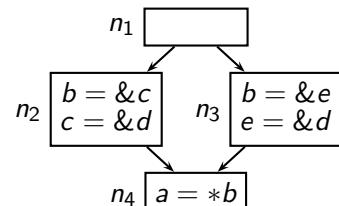
Non-Distributivity of Points-To Analysis

May Points-To



$z \rightarrow w$ is spurious

Must Points-To



$a \rightarrow d$ is missing

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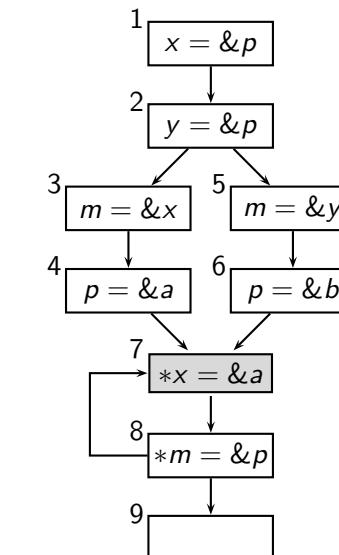
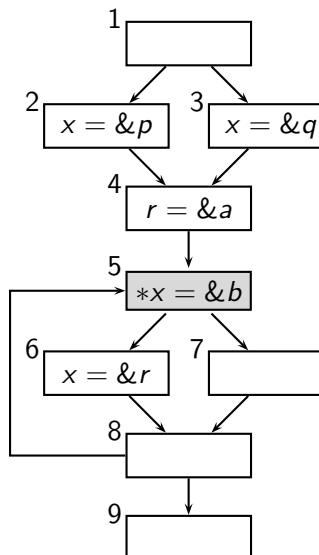
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Part 6

Heap Reference Analysis

Tutorial Problems for May and Must Points-To Analysis



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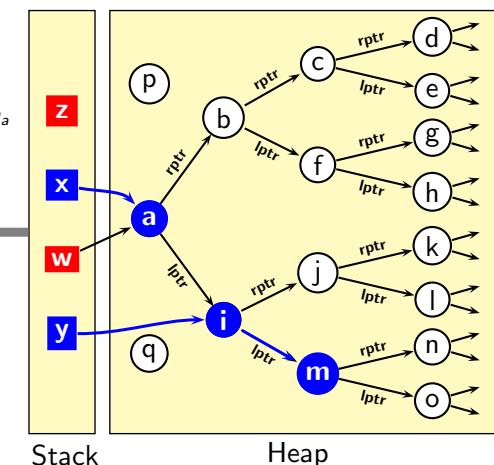


Motivating Example for Heap Liveness Analysis

If the while loop is not executed even once.

```

1 w = x      // x points to m_a
2 while (x.data < max)
3   x = x.rptr
4   y = x.lptr
5   z = New_class_of_z
6   y = y.lptr
7   z.sum = x.data + y.data
  
```



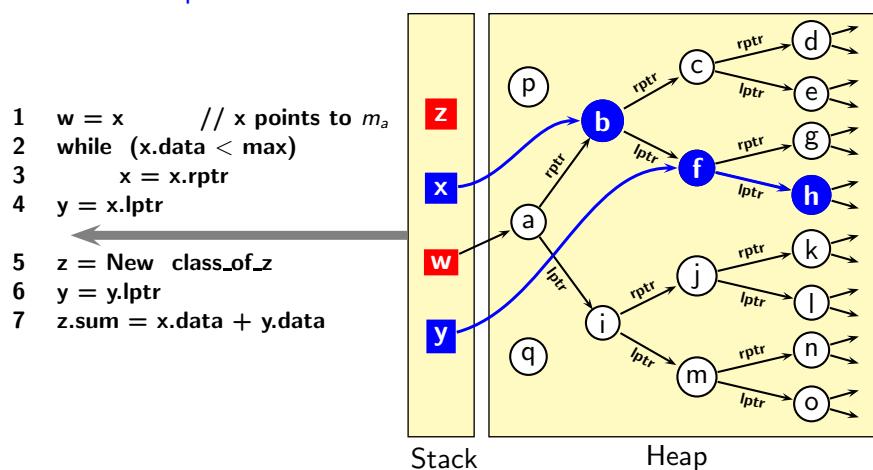
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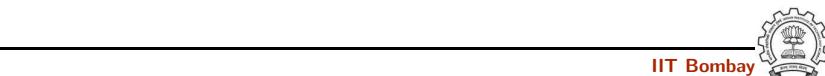
Motivating Example for Heap Liveness Analysis

If the `while` loop is executed once.



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The Moral of the Story

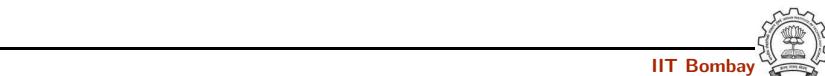
- Mappings between access expressions and l-values keep changing
- This is a *rule* for heap data
For stack and static data, it is an *exception*!
- Static analysis of programs has made significant progress for stack and static data.

What about heap data?

- Given two access expressions at a program point, do they have the same l-value?
- Given the same access expression at two program points, does it have the same l-value?

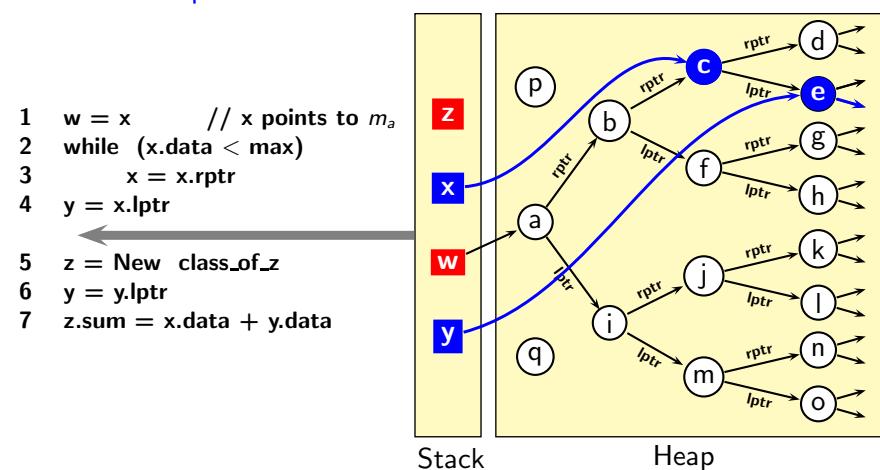
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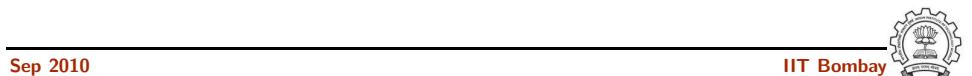
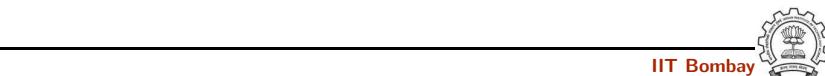
Motivating Example for Heap Liveness Analysis

If the `while` loop is executed twice.



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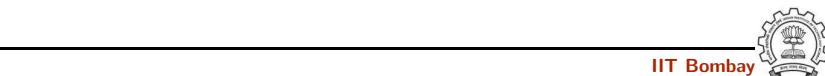
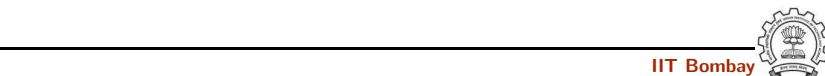


Our Solution

<pre> 1 w = x 2 while (x.data < max) 3 x = x.rptr 4 y = x.lptr 5 z = New class_of_z 6 y = y.lptr 7 z.sum = x.data + y.data </pre>	<pre> y = z = null w = null x.rptr = x.lptr.rptr = null x.lptr.lptr.lptr = null x.lptr.lptr.rptr = null x.lptr = y.rptr = null y.lptr = y.rptr.rptr = null z.lptr = z.rptr = null y.lptr = y.rptr = null x = y = z = null </pre>
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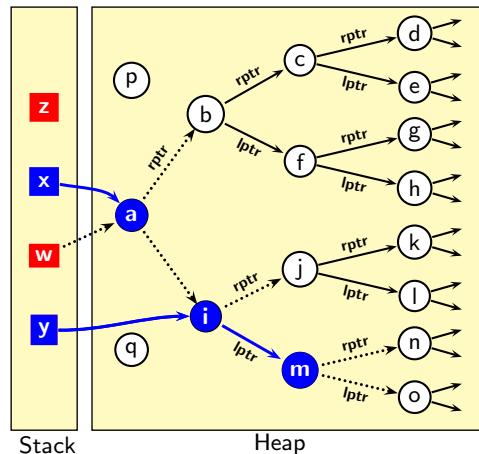
Our Solution

```

y = z = null
1 w = x
w = null
2 while (x.data < max)
{   x.lptr = null
3   x = x.rptr
}
x.rptr = x.lptr.rptr = null
x.lptr.lptr.lptr = null
x.lptr.lptr.rptr = null
4 y = x.lptr
x.lptr = y.rptr = null
y.lptr = y.rptr.rptr = null
5 z = New class_of_z
z.lptr = z.rptr = null
6 y = y.lptr
y.lptr = y.rptr = null
7 z.sum = x.data + y.data
x = y = z = null

```

While loop is not executed even once



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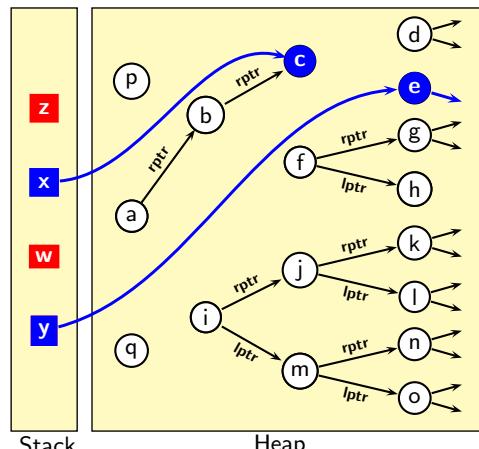
Our Solution

```

y = z = null
1 w = x
w = null
2 while (x.data < max)
{   x.lptr = null
3   x = x.rptr
}
x.rptr = x.lptr.rptr = null
x.lptr.lptr.lptr = null
x.lptr.lptr.rptr = null
4 y = x.lptr
x.lptr = y.rptr = null
y.lptr = y.rptr.rptr = null
5 z = New class_of_z
z.lptr = z.rptr = null
6 y = y.lptr
y.lptr = y.rptr = null
7 z.sum = x.data + y.data
x = y = z = null

```

While loop is executed twice



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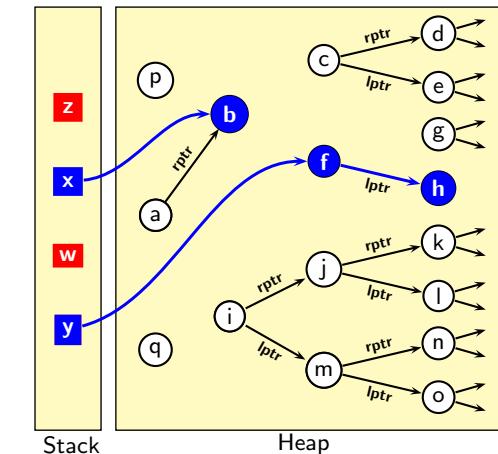
Our Solution

```

y = z = null
1 w = x
w = null
2 while (x.data < max)
{   x.lptr = null
3   x = x.rptr
}
x.rptr = x.lptr.rptr = null
x.lptr.lptr.lptr = null
x.lptr.lptr.rptr = null
4 y = x.lptr
x.lptr = y.rptr = null
y.lptr = y.rptr.rptr = null
5 z = New class_of_z
z.lptr = z.rptr = null
6 y = y.lptr
y.lptr = y.rptr = null
7 z.sum = x.data + y.data
x = y = z = null

```

While loop is executed once



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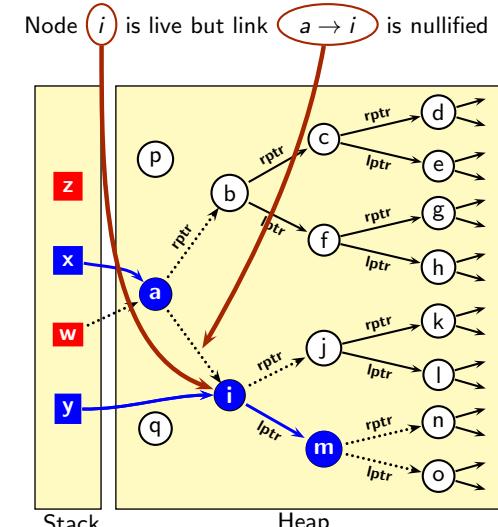


Some Observations

```

y = z = null
1 w = x
w = null
2 while (x.data < max)
{   x.lptr = null
3   x = x.rptr
}
x.rptr = x.lptr.rptr = null
x.lptr.lptr.lptr = null
x.lptr.lptr.rptr = null
4 y = x.lptr
x.lptr = y.rptr = null
y.lptr = y.rptr.rptr = null
5 z = New class_of_z
z.lptr = z.rptr = null
6 y = y.lptr
y.lptr = y.rptr = null
7 z.sum = x.data + y.data
x = y = z = null

```



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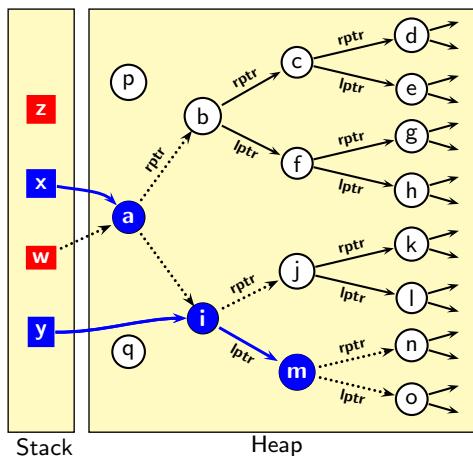


Some Observations

```

y = z = null
1 w = x
w = null
2 while (x.data < max)
{   x.lptr = null
3   x = x.rptr
}   x.rptr = x.lptr.rptr = null
x.lptr.lptr.lptr = null
x.lptr.lptr.rptr = null
4 y = x.lptr
x.lptr = y.rptr = null
y.lptr.lptr = y.lptr.rptr = null
5 z = New class_of_z
z.lptr = z.rptr = null
6 y = y.lptr
y.lptr = y.rptr = null
7 z.sum = x.data + y.data
x = y = z = null
    
```

New access expressions are created.
Can they cause exceptions?



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Assumptions

For simplicity of exposition

- Java model of heap access
 - Root variables are on stack and represent references to memory in heap.
 - Root variables cannot be pointed to by any reference.
- Simple extensions for C++
 - Root variables can be pointed to by other pointers.
 - Pointer arithmetic is not handled.

An Overview of Heap Reference Analysis

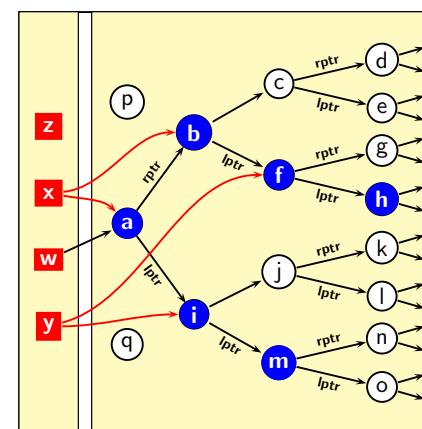
- A reference (called a *link*) can be represented by an *access path*.
Eg. “ $x \rightarrow \text{lptr} \rightarrow \text{rptr}$ ”
- A link may be accessed in multiple ways
- Setting links to null
 - Alias Analysis.** Identify all possible ways of accessing a link
 - Liveness Analysis.** For each program point, identify “dead” links (i.e. links which are not accessed after that program point)
 - Availability and Anticipability Analyses.** Dead links should be reachable for making null assignment.
 - Code Transformation.** Set “dead” links to null

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Key Idea #1 : Access Paths Denote Links



- Root variables : x, y, z
- Field names : rptr, lptr
- Access path : $x \rightarrow \text{rptr} \rightarrow \text{lptr}$
Semantically, sequence of “links”
- Frontier : name of the last link
- Live access path : If the link corresponding to its frontier is used in future

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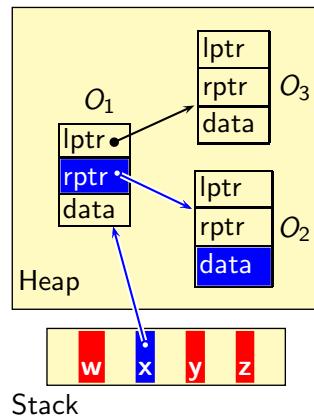


What Makes a Link Live?

Assuming that a statement is the last statement in the program, if nullifying a link **read** in the statement can change the semantics of the program, then the link is live.

Reading a link for accessing the contents of the corresponding target object:

Example	Objects read	Live access paths
<code>sum = x.rptr.data</code>	x, O_1, O_2	$x, x \rightarrow rptr$
<code>if (x.rptr.data < sum)</code>	x, O_1, O_2	$x, x \rightarrow rptr$



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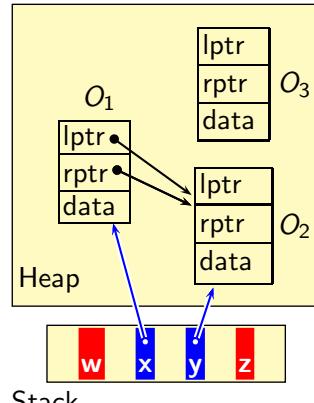


What Makes a Link Live?

Assuming that a statement is the last statement in the program, if nullifying a link **read** in the statement can change the semantics of the program, then the link is live.

Reading a link for copying the contents of the corresponding target object:

Example	Objects read	Live access paths
<code>y = x.rptr</code>	x, O_1	x
<code>x.lptr = y</code>	x, O_1, y	x



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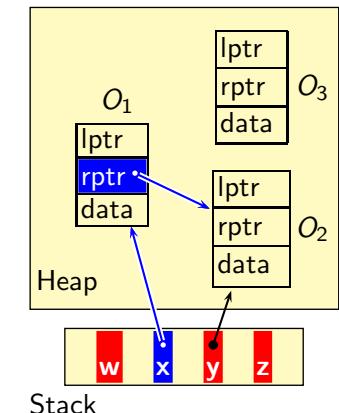


What Makes a Link Live?

Assuming that a statement is the last statement in the program, if nullifying a link **read** in the statement can change the semantics of the program, then the link is live.

Reading a link for copying the contents of the corresponding target object:

Example	Objects read	Live access paths
<code>y = x.rptr</code>	x, O_1	x



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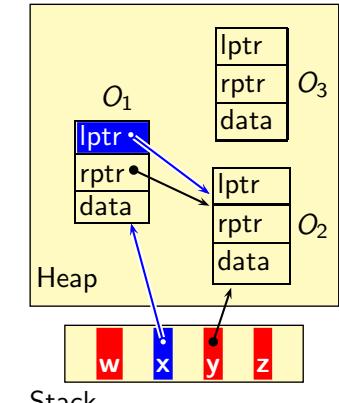


What Makes a Link Live?

Assuming that a statement is the last statement in the program, if nullifying a link **read** in the statement can change the semantics of the program, then the link is live.

Reading a link for comparing the address of the corresponding target object:

Example	Objects read	Live access paths
<code>if (x.lptr == null)</code>	x, O_1	$x, x \rightarrow lptr$



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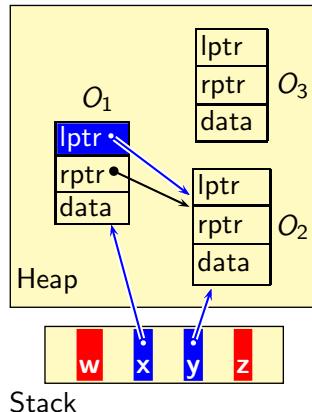


What Makes a Link Live?

Assuming that a statement is the last statement in the program, if nullifying a link **read** in the statement can change the semantics of the program, then the link is live.

Reading a link for comparing the address of the corresponding target object:

Example	Objects read	Live access paths
<code>if (x.lptr == null)</code>	x, O_1	$x, x \rightarrow lptr$
<code>if (y == x.lptr)</code>	x, O_1, y	$x, x \rightarrow lptr, y$

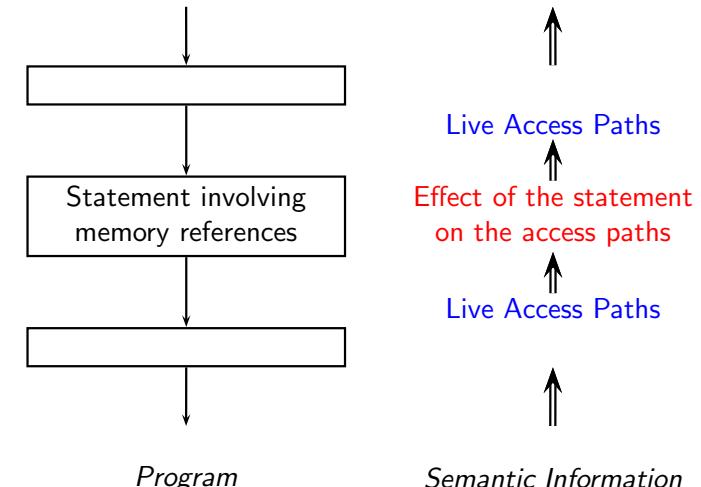


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Liveness Analysis

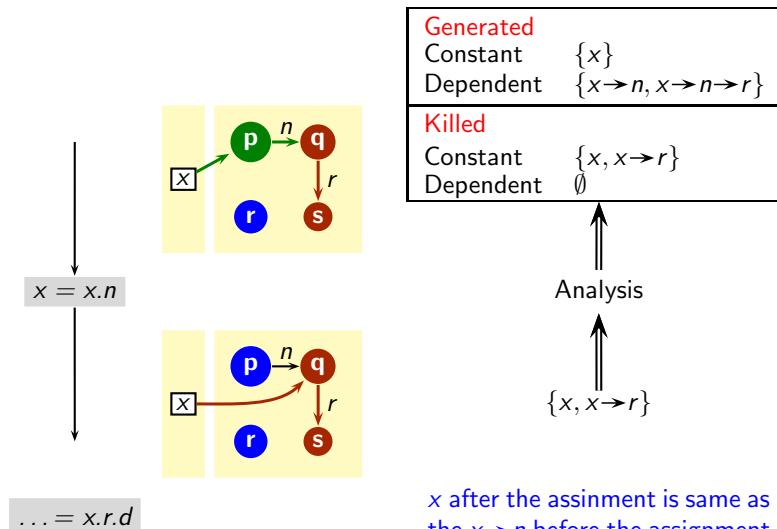


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General Frameworks: Heap Reference Analysis

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Key Idea #2 : Transfer of Access Paths

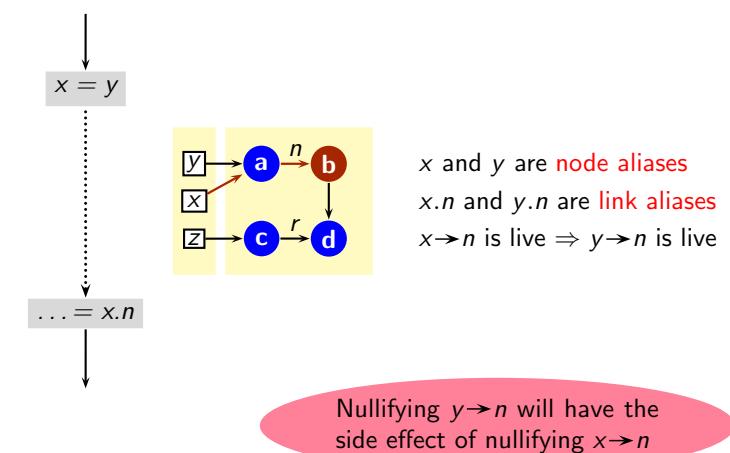


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Key Idea #3 : Liveness Closure Under Link Aliasing

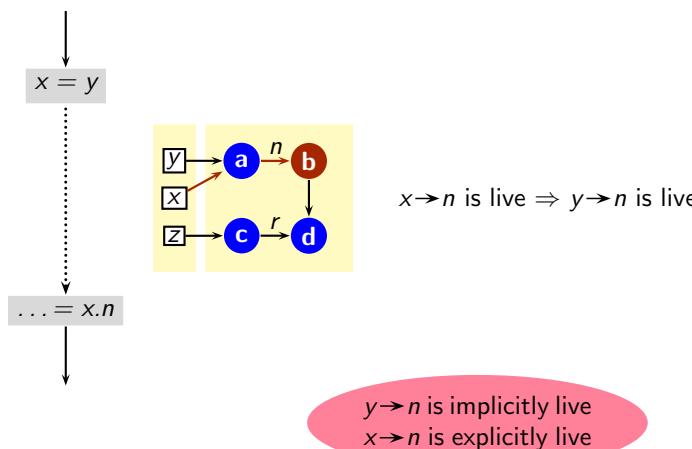


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Explicit and Implicit Liveness



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Notation for Defining Flow Functions for Explicit Liveness

$$\begin{aligned} \text{base}(\rho_x) &= \text{longest proper prefix of } \rho_x \\ \text{prefixes}(\rho_x) &= \{\rho'_x \mid \rho'_x \text{ is a prefix of } \rho_x\} \\ \text{summary}(S) &= \{\rho_x \rightarrow * \mid \rho_x \in S\} \end{aligned}$$

ρ_x	$\text{frontier}(\rho_x)$	$\text{base}(\rho_x)$	$\text{prefixes}(\rho_x)$	$\text{summary}(\{\rho_x\})$
$x \rightarrow n \rightarrow r$	r	$x \rightarrow n$	$\{x, x \rightarrow n, x \rightarrow n \rightarrow r\}$	$\{x \rightarrow n \rightarrow r \rightarrow *\}$
$x \rightarrow r \rightarrow n$	n	$x \rightarrow r$	$\{x, x \rightarrow r, x \rightarrow r \rightarrow n\}$	$\{x \rightarrow r \rightarrow n \rightarrow *\}$
$x \rightarrow n$	n	x	$\{x, x \rightarrow n\}$	$\{x \rightarrow n \rightarrow *\}$
$x \rightarrow r$	r	x	$\{x, x \rightarrow r\}$	$\{x \rightarrow r \rightarrow *\}$
x	x	\mathcal{E}	$\{x\}$	$\{x \rightarrow *\}$

empty access path

0 or more occurrences of any field name

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Key Idea #4: Explicit Liveness Covers Entire Heap Usage

- Explicit Liveness at p
Liveness purely due to the program beyond p .
The effect of execution before p is not incorporated.
- Implicit Liveness at p
Access paths that become live under link alias closure.
 - ▶ The set of implicitly live access paths may not be prefix closed.
 - ▶ These *paths* are not accessed, their frontiers are accessed through some other access path

Every live link in the heap is the Frontier of some explicitly live access path.

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Flow Functions for Explicit Liveness Analysis

Statement	ConstKill	$\text{DepKill}(X)$	ConstGen	$\text{DepGen}(X)$
$\text{Use } \alpha_y$	\emptyset	\emptyset	$\text{prefixes}(\text{base}(\rho_y))$	\emptyset
$\text{Use } \alpha_y.d$	\emptyset	\emptyset	$\text{prefixes}(\rho_y)$	\emptyset
$\alpha_x = \text{new }$	$\{\rho_x \rightarrow *\}$	\emptyset	$\text{prefixes}(\text{base}(\rho_x))$	\emptyset
$\alpha_x = \text{Null}$	$\{\rho_x \rightarrow *\}$	\emptyset	$\text{prefixes}(\text{base}(\rho_x))$	\emptyset
$\alpha_x = \alpha_y$	$\{\rho_x \rightarrow *\}$	\emptyset	$\text{prefixes}(\text{base}(\rho_x)) \cup \text{prefixes}(\text{base}(\rho_y))$	$\{\rho_y \rightarrow \sigma \mid \rho_x \rightarrow \sigma \in X\}$
End	\emptyset	\emptyset	$\text{summary}(\text{Globals})$	\emptyset
other	\emptyset	\emptyset	\emptyset	\emptyset

access expression

corresponding access path

End of procedure

Transfer

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Flow Functions for Handling Procedure Calls in Computing Explicit Liveness

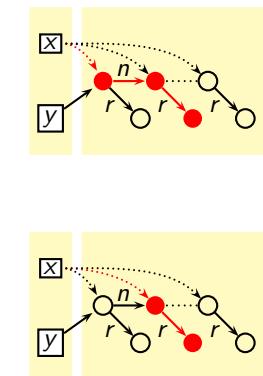
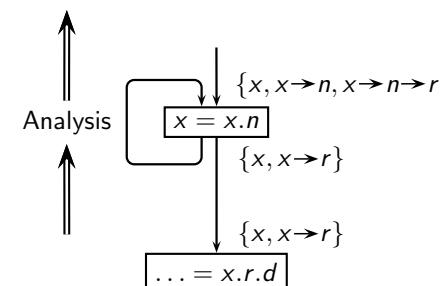
Statement	<i>ConstKill</i>	<i>DepKill(X)</i>	<i>ConstGen</i>	<i>DepGen(X)</i>
$\alpha_x = f(\alpha_y)$	$\{\rho_x \rightarrow *\}$	\emptyset	$\text{prefixes}(\text{base}(\rho_x)) \cup \text{prefixes}(\text{base}(\rho_y)) \cup \text{summary}(\{\rho_y\} \cup \text{Globals})$	\emptyset
<i>return</i> α_y	\emptyset	\emptyset	$\text{prefixes}(\text{base}(\rho_y)) \cup \text{summary}(\{\rho_y\})$	\emptyset

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Computing Explicit Liveness Using Sets of Access Paths



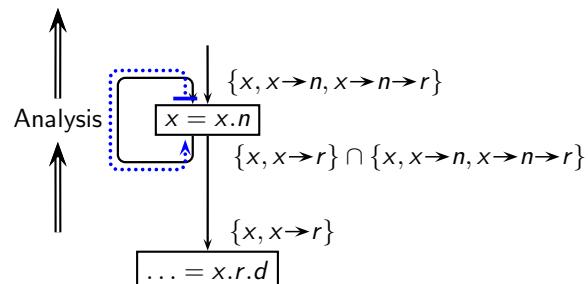
CS 618

General Frameworks: Heap Reference Analysis

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Computing Explicit Liveness Using Sets of Access Paths

Anticipability of Heap References: An *All Paths* problem

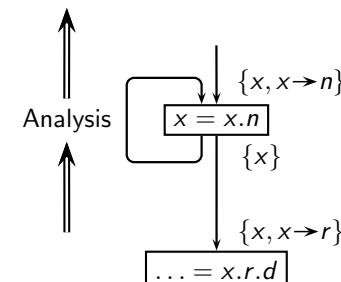


CS 618

General Frameworks: Heap Reference Analysis

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Computing Explicit Liveness Using Sets of Access Paths



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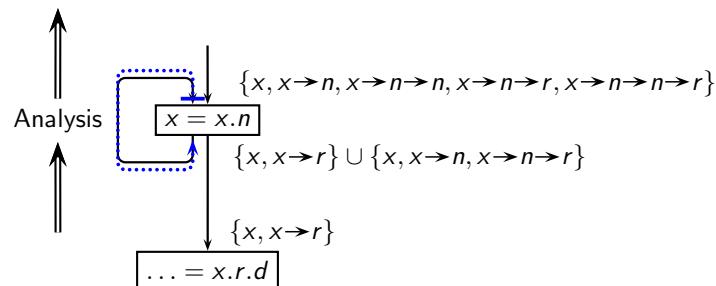
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Computing Explicit Liveness Using Sets of Access Paths

Liveness of Heap References: An *Any Path* problem

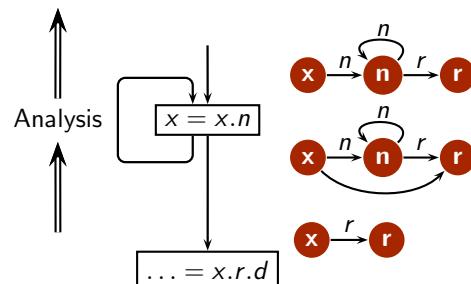


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Key Idea #5: Using Graphs as Data Flow Values



Finite Number of Bounded Structures

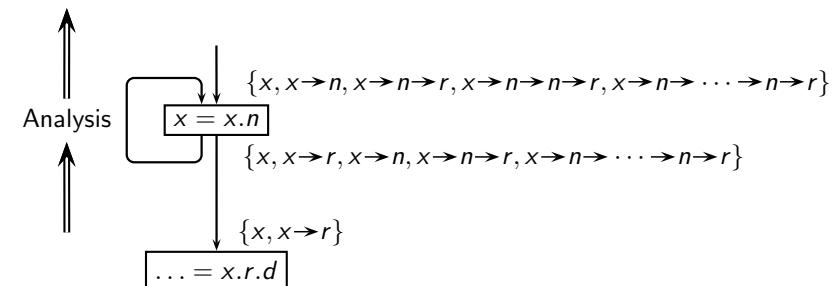
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Computing Explicit Liveness Using Sets of Access Paths

Liveness of Heap References: An *Any Path* problem

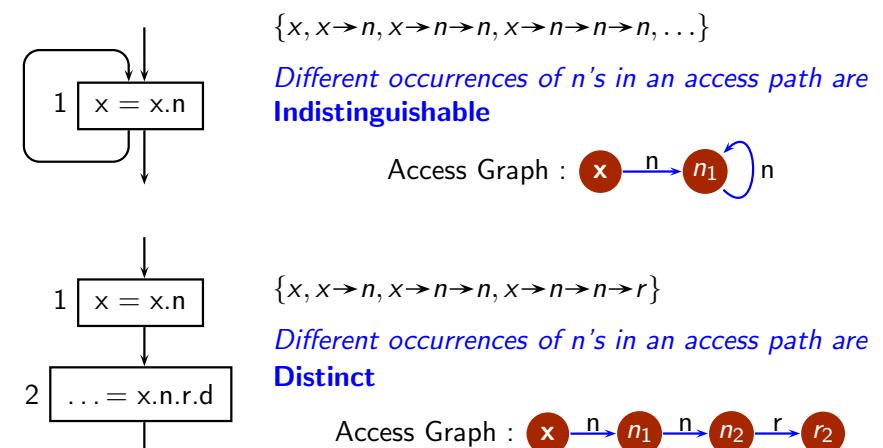


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Key Idea #6 : Include Program Point in Graphs

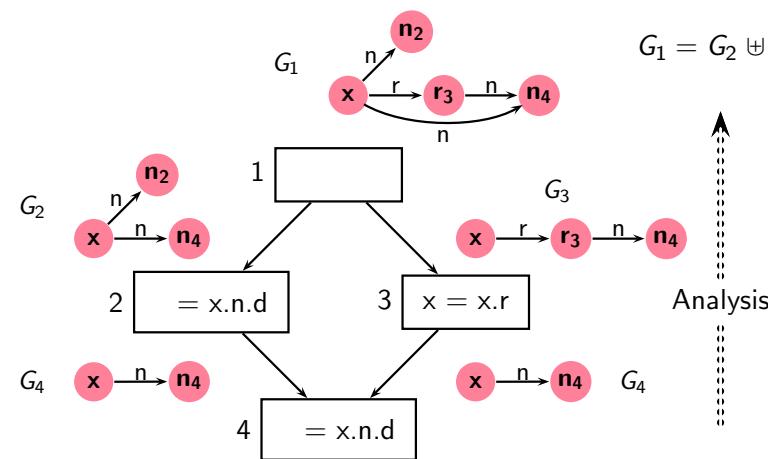


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Inclusion of Program Point Facilitates Summarization

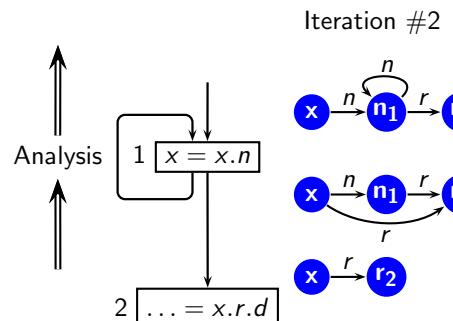


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Inclusion of Program Point Facilitates Summarization

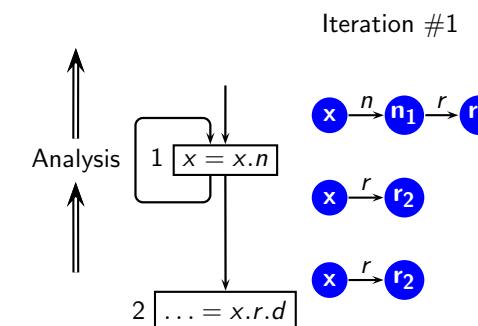


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Inclusion of Program Point Facilitates Summarization

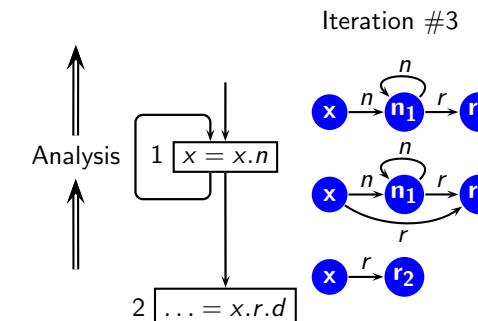


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Inclusion of Program Point Facilitates Summarization

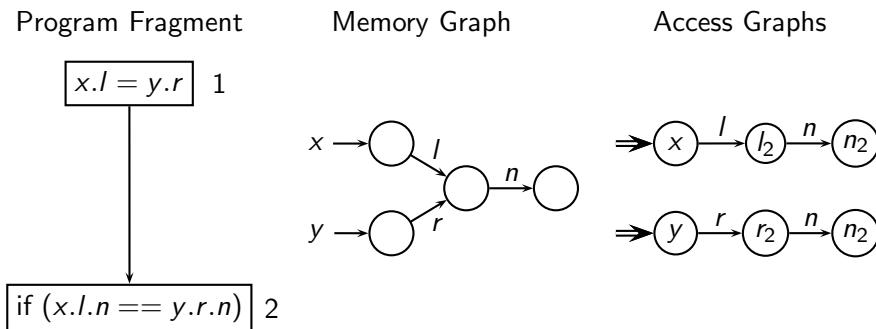


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Access Graph and Memory Graph



- Memory Graph: Nodes represent locations and edges represent links (i.e. pointers).
- Access Graphs: Nodes represent dereference of links at particular statements. Memory locations are implicit.

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Access Graph Operations

- Union. $G \uplus G'$
- Path Removal.
 $G \ominus \rho$ removes those access paths in G which have ρ as a prefix.
- Factorization (/).
- Extension.

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Lattice of Access Graphs

- Finite number of nodes in an access graph for a variable
- \uplus induces a partial order on access graphs
 - \Rightarrow a finite (and hence complete) lattice
 - \Rightarrow All standard results of classical data flow analysis can be extended to this analysis.

Termination and boundedness, convergence on MFP, complexity etc.

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Semantics of Access Graph Operations

- $P(G, M)$ is the set of paths in graph G terminating on nodes in M . For graph G_i , M_i is the set of all nodes in G_i .
- S is the set of remainder graphs and $P(S, M_s)$ is the set of all paths in all remainder graphs in S .

Operation	Access Paths
Union $G_3 = G_1 \uplus G_2$	$P(G_3, M_3) \supseteq P(G_1, M_1) \cup P(G_2, M_2)$
Path Removal $G_2 = G_1 \ominus \rho$	$P(G_2, M_2) \supseteq P(G_1, M_1) - \{\rho \rightarrow \sigma \mid \rho \rightarrow \sigma \in P(G_1, M_1)\}$
Factorization $S = G_1 / (G_2, M)$	$P(S, M_s) = \{\sigma \mid \rho' \rightarrow \sigma \in P(G_1, M_1), \rho' \in P(G_2, M)\}$
Extension $G_2 = (G_1, M) \# \emptyset$	$P(G_2, M_2) = \emptyset$
Extension $G_2 = (G_1, M) \# S$	$P(G_2, M_2) \supseteq P(G_1, M_1) \cup \{\rho \rightarrow \sigma \mid \rho \in P(G_1, M), \sigma \in P(S, M_s)\}$

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Semantics of Access Graph Operations

- $P(G, M)$ is the set of paths in graph G terminating on nodes in M . For graph G_i , M_i is the set of all nodes in G_i .
- S is the set of remainder graphs and $P(S, M_s)$ is the set of all paths in all remainder graphs in S .

Operation	Access Paths
Union	$G_3 = G_1 \uplus G_2$
Path Removal	$P(G_2, M_2) \supseteq P(G_1, M_1) - \{p \rightarrow \sigma \mid p \rightarrow \sigma \in P(G_1, M_1)\}$
Factorization	$S = G_1 / (G_2, M)$
Extension	$G_2 = (G_1, M) \# \emptyset$ $G_2 = (G_1, M) \# S$

σ represents remainder

ρ' represents quotient



Access Graph Operations: Examples

Program	Access Graphs			Remainder Graphs
1 x = x.l	$g_1 \Rightarrow x$	$g_2 \Rightarrow x \rightarrow r_2$	$g_3 \Rightarrow x \rightarrow l_1$	$rg_1 \Rightarrow r_2$
2 y = x.r.d	$g_4 \Rightarrow x \rightarrow l_1 \rightarrow r_2$	$g_5 \Rightarrow x \rightarrow l_1 \rightarrow r_2$	$g_6 \Rightarrow x \rightarrow l_1 \rightarrow r_2$	$rg_2 \Rightarrow l_1 \rightarrow r_2$
Union	Path Removal	Factorisation	Extension	
$g_3 \uplus g_4 = g_4$	$g_6 \ominus x \rightarrow l = g_2$	$g_2 / (g_1, \{x\}) = \{rg_1\}$		
$g_2 \uplus g_4 = g_5$	$g_5 \ominus x = \mathcal{E}_G$	$g_5 / (g_1, \{x\}) = \{rg_1, rg_2\}$		
$g_5 \uplus g_4 = g_5$	$g_4 \ominus x \rightarrow r = g_4$	$(g_3, \{l_1\}) \# \{rg_1, rg_2\} = g_6$		
$g_5 \uplus g_6 = g_6$	$g_5 / (g_2, \{r_2\}) = \{\epsilon_{RG}\}$	$(g_2, \{r_2\}) \# \{\epsilon_{RG}\} = g_2$		
		$(g_2, \{r_2\}) \# \emptyset = \mathcal{E}_G$		

Remainder is empty

Quotient is empty



Access Graph Operations: Examples

Program	Access Graphs			Remainder Graphs
1 x = x.l	$g_1 \Rightarrow x$	$g_2 \Rightarrow x \rightarrow r_2$	$g_3 \Rightarrow x \rightarrow l_1$	$rg_1 \Rightarrow r_2$
2 y = x.r.d	$g_4 \Rightarrow x \rightarrow l_1 \rightarrow r_2$	$g_5 \Rightarrow x \rightarrow l_1 \rightarrow r_2$	$g_6 \Rightarrow x \rightarrow l_1 \rightarrow r_2$	$rg_2 \Rightarrow l_1 \rightarrow r_2$

Union	Path Removal	Factorisation	Extension
$g_3 \uplus g_4 = g_4$	$g_6 \ominus x \rightarrow l = g_2$	$g_2 / (g_1, \{x\}) = \{rg_1\}$	$(g_3, \{l_1\}) \# \{rg_1\} = g_4$
$g_2 \uplus g_4 = g_5$	$g_5 \ominus x = \mathcal{E}_G$	$g_5 / (g_1, \{x\}) = \{rg_1, rg_2\}$	$(g_3, \{x, l_1\}) \# \{rg_1, rg_2\} = g_6$
$g_5 \uplus g_4 = g_5$	$g_4 \ominus x \rightarrow r = g_4$	$g_4 / (g_2, \{r_2\}) = \{\epsilon_{RG}\}$	$(g_2, \{r_2\}) \# \{\epsilon_{RG}\} = g_2$
$g_5 \uplus g_6 = g_6$	$g_4 \ominus x \rightarrow l = g_1$	$g_4 / (g_2, \{r_2\}) = \emptyset$	$(g_2, \{r_2\}) \# \emptyset = \mathcal{E}_G$



Data Flow Equations for Heap Liveness Analysis

Computing Liveness Access Graph for variable v by incorporating the effect of statement n .

$$\begin{aligned}
 ELIn_n(v) &= (ELOut_n(v) \ominus ELKillPath_n(v)) \uplus ELGen_n(v) \\
 ELOut_n(v) &= \begin{cases} makeGraph(v \rightarrow *) & n = End, v \in Globals \\ \mathcal{E}_G & n = End, v \notin Globals \\ \biguplus_{s \in succ(n)} ELIn_s(v) & \text{otherwise} \end{cases} \\
 ELGen_n(v) &= ELConstGen_n(v) \uplus ELDepGen_n(v)
 \end{aligned}$$

(Note: This notation is slightly different from the notation in the book.)

Flow Functions for Explicit Liveness Analysis

Access Paths \Rightarrow

	$Use \alpha_x.d$	$\alpha_x = \alpha_y$
$ConstKill_n$	\emptyset	$\{\rho_x \rightarrow *\}$
$ConstGen_n$	$prefixes(\rho_x)$	$prefixes(base(\rho_x)) \cup prefixes(base(\rho_y))$
$DepGen_n(X)$	\emptyset	$\{\rho_y \rightarrow \sigma \mid \rho_x \rightarrow \sigma \in X\}$

Access Graphs \Downarrow

$$G_x = makeGraph(\rho_x) \quad G_x^B = makeGraph(base(\rho_x)) \\ G_y = makeGraph(\rho_y) \quad G_y^B = makeGraph(base(\rho_y))$$

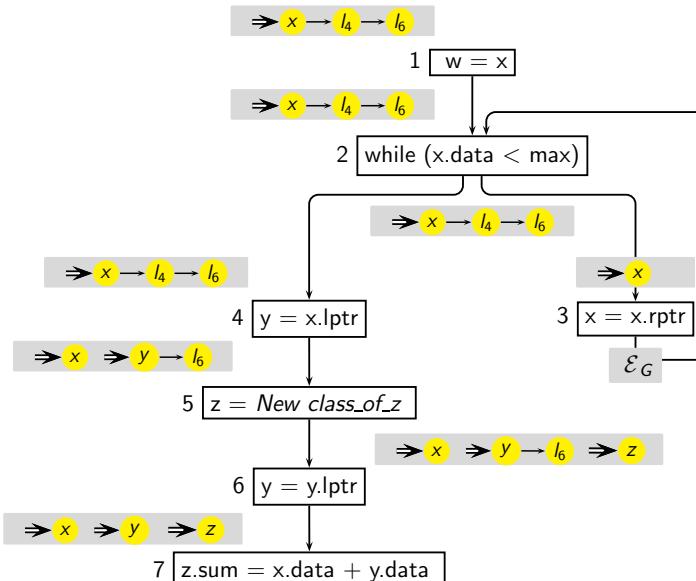
	$Use \alpha_x.d$	$Use \alpha_x$	$\alpha_x = \alpha_y$	$\alpha_x = Null, \alpha_x = New$
$ELKillPath_n(x)$	\mathcal{E}	\mathcal{E}	ρ_x	ρ_x
$ELKillPath_n(y)$	\mathcal{E}	\mathcal{E}	\mathcal{E}	\mathcal{E}
$ELConstGen_n(x)$	G_x	G_x^B	G_x^B	G_x^B
$ELConstGen_n(y)$	\mathcal{E}_G	\mathcal{E}_G	G_y^B	\mathcal{E}_G
$ELDepGen_n(x)(X)$	\mathcal{E}_G	\mathcal{E}_G	\mathcal{E}_G	\mathcal{E}_G
$ELDepGen_n(y)(X)$	\mathcal{E}_G	\mathcal{E}_G	$(G_y, M_y) \# (X / (G_x, M_x))$	\mathcal{E}_G

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Liveness Analysis of Example Program: 1st Iteration



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Flow Functions for Explicit Liveness Analysis

Access Paths \Rightarrow

	$Use \alpha_x.d$	$\alpha_x = \alpha_y$
$ConstKill_n$	\emptyset	$\{\rho_x \rightarrow *\}$
$ConstGen_n$	$prefixes(\rho_x)$	$prefixes(base(\rho_x)) \cup prefixes(base(\rho_y))$
$DepGen_n(X)$	\emptyset	$\{\rho_y \rightarrow \sigma \mid \rho_x \rightarrow \sigma \in X\}$

Access Graphs \Downarrow

$$G_x = makeGraph(\rho_x) \quad G_x^B = makeGraph(base(\rho_x)) \\ G_y = makeGraph(\rho_y) \quad G_y^B = makeGraph(base(\rho_y))$$

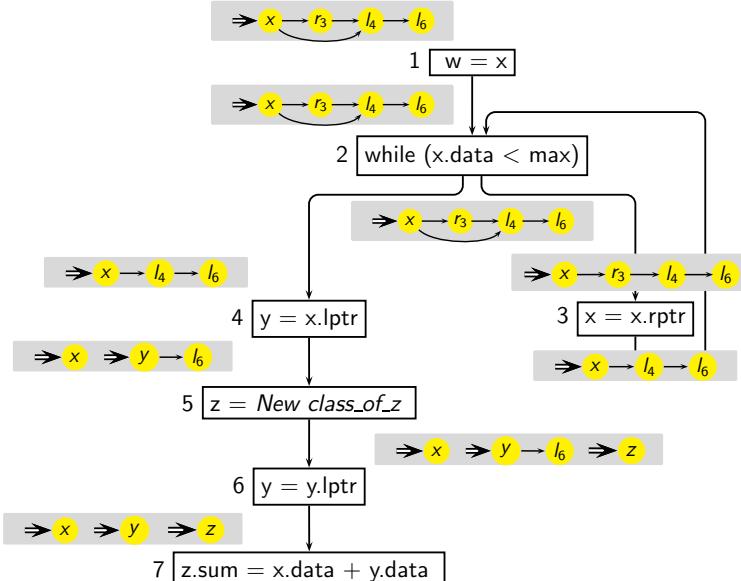
	$Use \alpha_x.d$	$Use \alpha_x$	$\alpha_x = \alpha_y$	$\alpha_x = Null, \alpha_x = New$
$ELKillPath_n(x)$	\mathcal{E}	\mathcal{E}	ρ_x	ρ_x
$ELKillPath_n(y)$	\mathcal{E}	\mathcal{E}	\mathcal{E}	\mathcal{E}
$ELConstGen_n(x)$	G_x	G_x^B	G_x^B	G_x^B
$ELConstGen_n(y)$	\mathcal{E}_G	\mathcal{E}_G	G_y^B	\mathcal{E}_G
$ELDepGen_n(x)(X)$	\mathcal{E}_G	\mathcal{E}_G	\mathcal{E}_G	\mathcal{E}_G
$ELDepGen_n(y)(X)$	\mathcal{E}_G	\mathcal{E}_G	$(G_y, M_y) \# (X / (G_x, M_x))$	\mathcal{E}_G

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Liveness Analysis of Example Program: 2nd Iteration

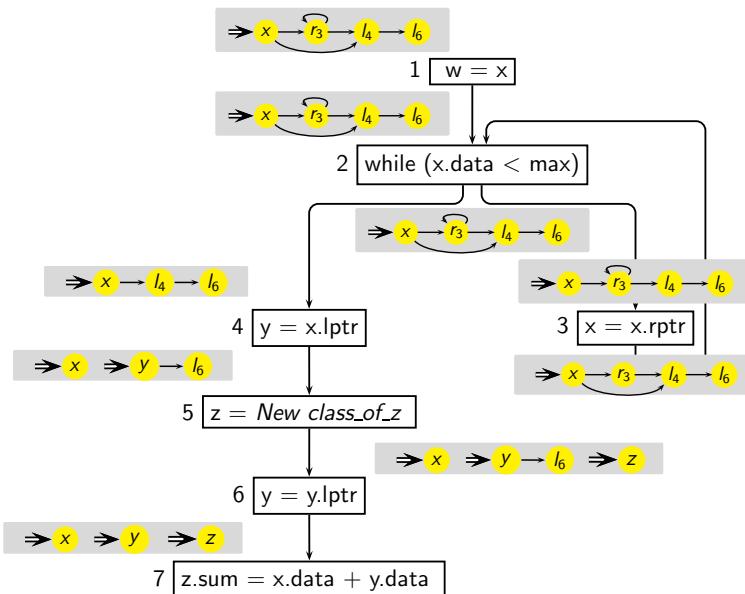


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Liveness Analysis of Example Program: 3rd Iteration



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Which Access Paths Can be Nullified?

Can be safely dereferenced

Consider link aliases at p

- Consider extensions of accessible paths for nullification.

Let ρ be accessible at p (i.e. available or anticipable)
for each reference field f of the object pointed to by ρ

if $\rho \rightarrow f$ is not live at p then

Insert $\rho \rightarrow f = \text{null}$ at p subject to profitability

- For simple access paths, ρ is empty and f is the root variable name.

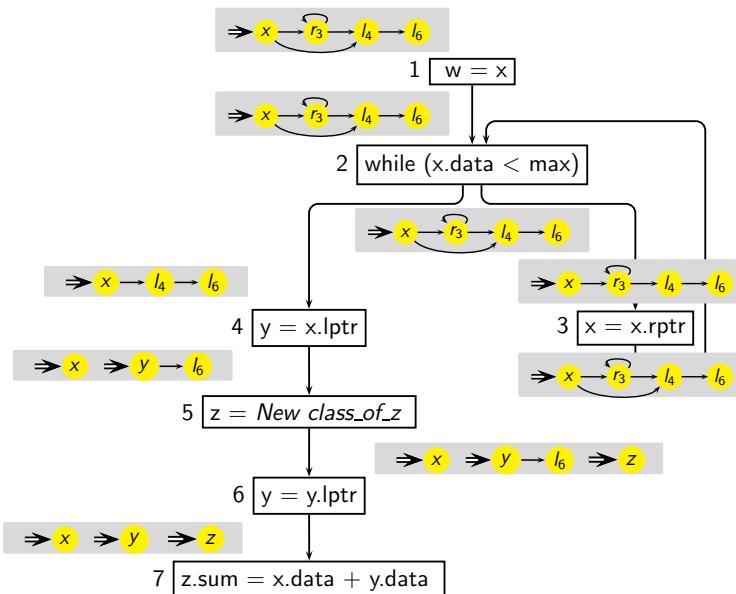
Cannot be hoisted and
is not redefined at p

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Liveness Analysis of Example Program: 4th Iteration



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Availability and Anticipability Analyses

- ρ is **available** at program point p if the target of each prefix of ρ is guaranteed to be created along every control flow path reaching p .
- ρ is **anticipable** at program point p if the target of each prefix of ρ is guaranteed to be dereferenced along every control flow path starting at p .
- Finiteness.
 - An anticipable (available) access path must be anticipable (available) along every paths. Thus unbounded paths arising out of loops cannot be anticipable (available).
 - Due to "every control flow path nature", computation of anticipable and available access paths uses \cap as the confluence. Thus the sets are bounded.

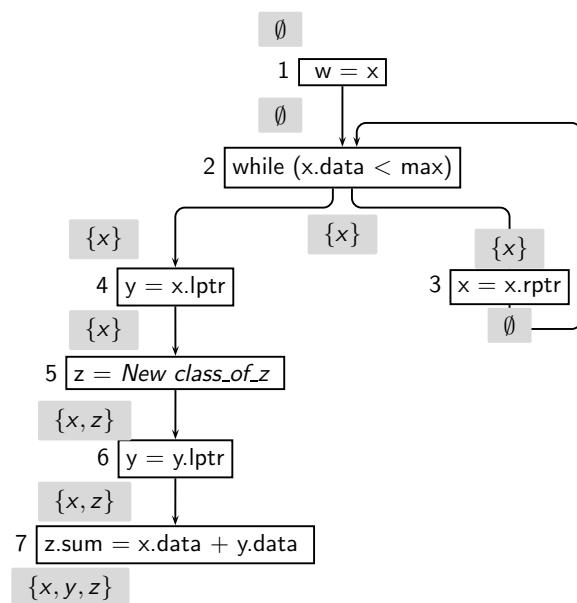
⇒ No need of access graphs.

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Availability Analysis of Example Program

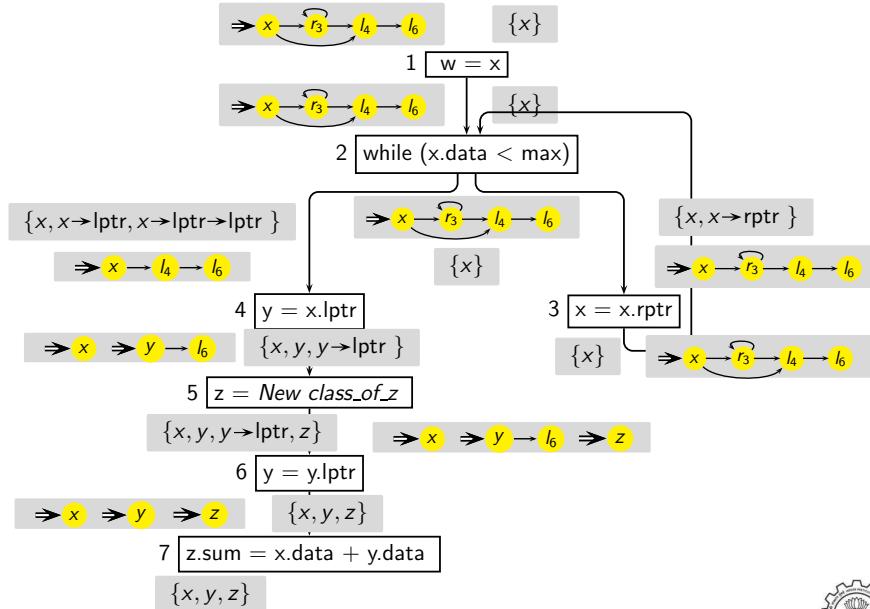


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Live and Accessible Paths

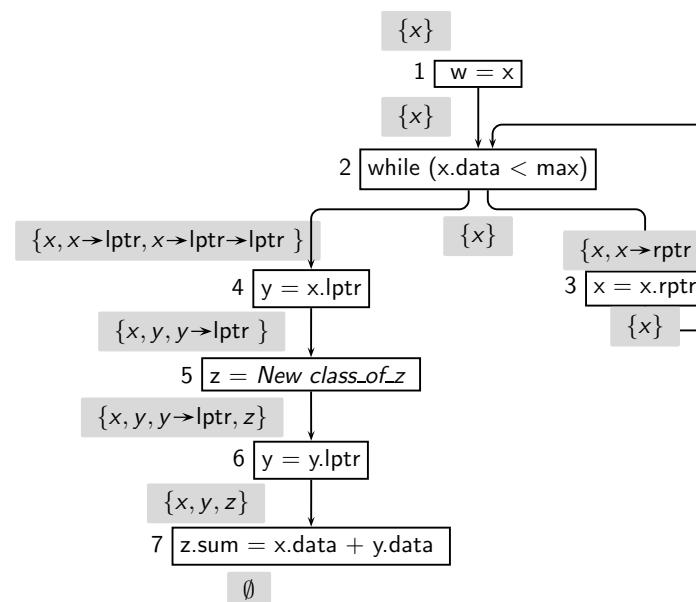


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Anticipability Analysis of Example Program

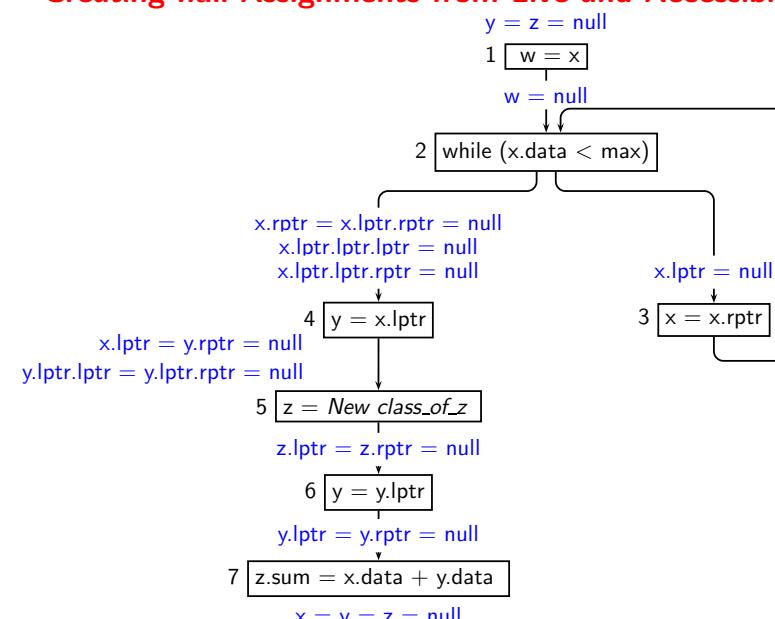


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Creating null Assignments from Live and Accessible Paths



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The Resulting Program

```

y = z = null
1 w = x
w = null
2 while (x.data < max)
{
    x.lptr = null
3   x = x.rptr
    x.rptr = x.lptr.rptr = null
    x.lptr.lptr.lptr = null
    x.lptr.lptr.rptr = null
4   y = x.lptr
    x.lptr = y.rptr = null
    y.lptr.lptr = y.lptr.rptr = null
5   z = New class.of.z
    z.lptr = z.rptr = null
6   y = y.lptr
    y.lptr = y.rptr = null
7   z.sum = x.data + y.data
    x = y = z = null

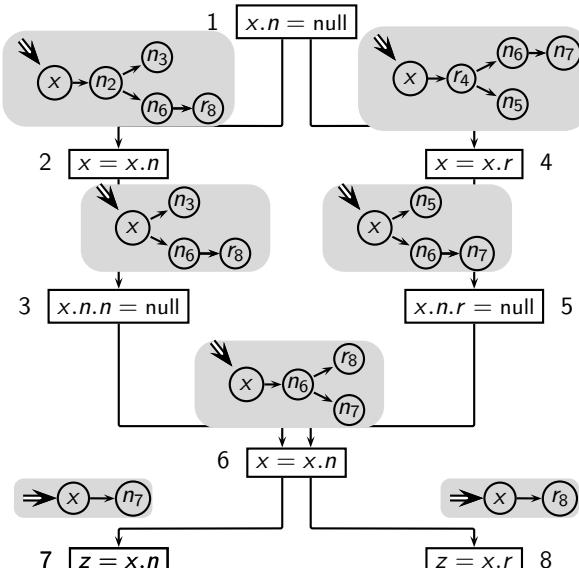
```



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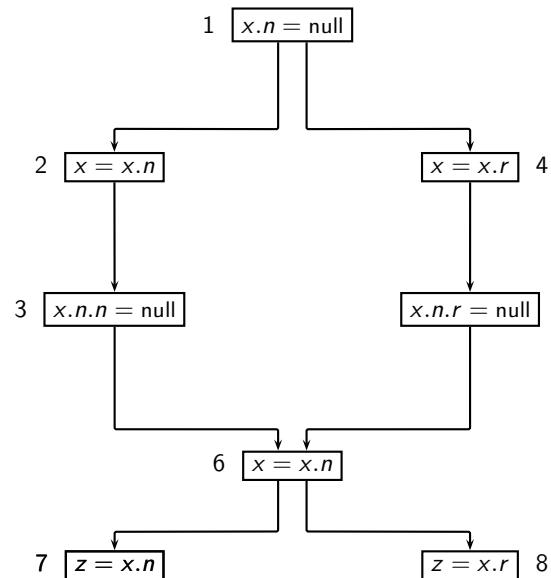
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Non-Distributivity of Explicit Liveness Analysis



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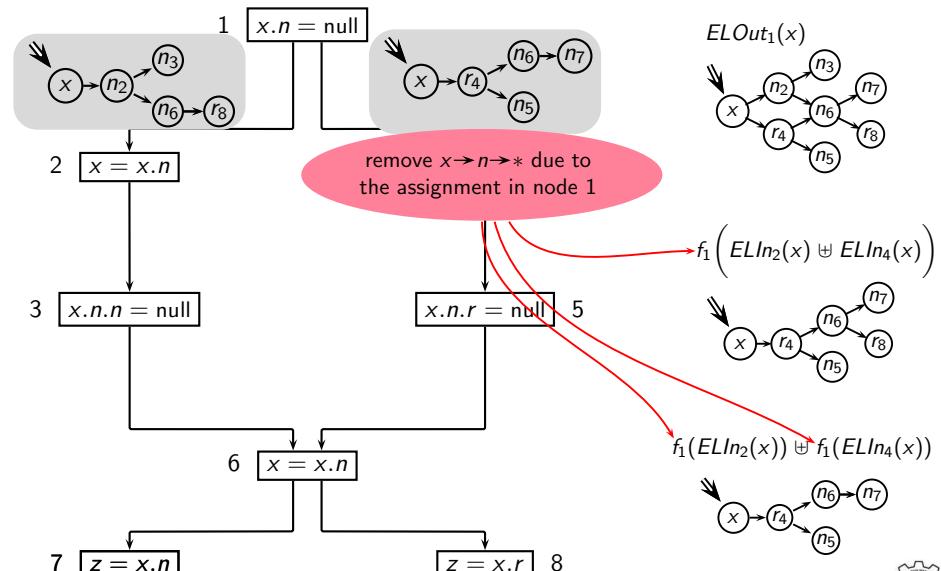
Non-Distributivity of Explicit Liveness Analysis



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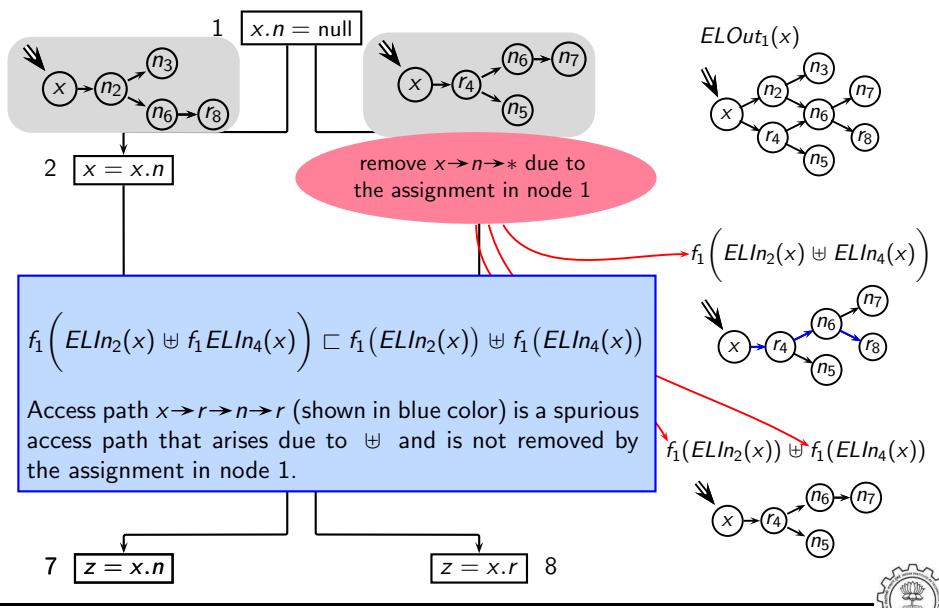
Non-Distributivity of Explicit Liveness Analysis



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Non-Distributivity of Explicit Liveness Analysis



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Issues Not Covered in These Slides

- Precision of information
 - ▶ Cyclic Data Structures
 - ▶ Eliminating Redundant null Assignments
- Properties of Data Flow Analysis:
Monotonicity, Boundedness, Complexity
- Interprocedural Analysis
- Extensions for C/C++

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