

# *Pointer Analysis*

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These slides constitute the lecture notes for CS618 Program Analysis course at IIT Bombay and have been made available as teaching material accompanying the book:

- Uday Khedker, Amitabha Sanyal, and Bageshri Karkare. *Data Flow Analysis: Theory and Practice*. CRC Press (Taylor and Francis Group). 2009.

(Indian edition published by Ane Books in 2013)

Apart from the above book, some slides are based on the material from the following book

- M. S. Hecht. *Flow Analysis of Computer Programs*. Elsevier North-Holland Inc. 1977.

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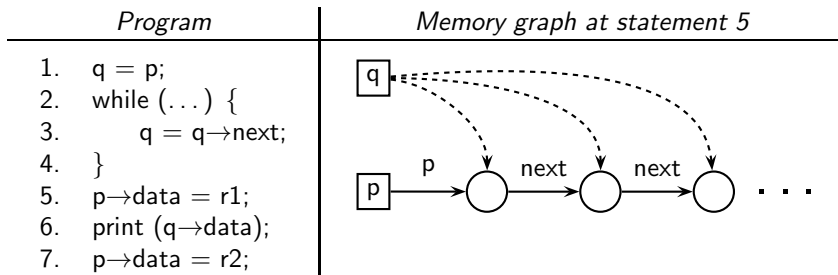


# An Outline of Pointer Analysis Coverage

- The larger perspective
- IR for Points-to Analysis
- Flow-Insensitive Points-to Analysis
- Flow-Sensitive Points-to Analysis



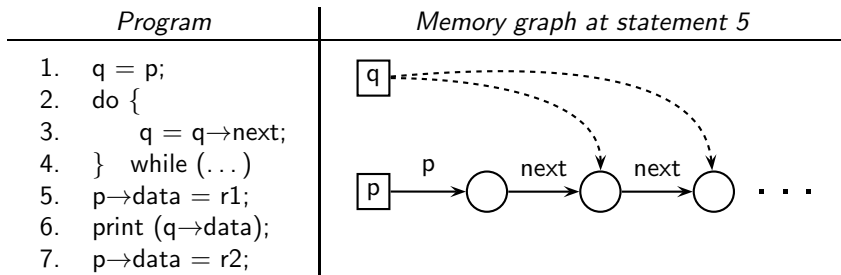
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- Is  $p \rightarrow \text{data}$  live at the exit of line 5? Can we delete line 5?



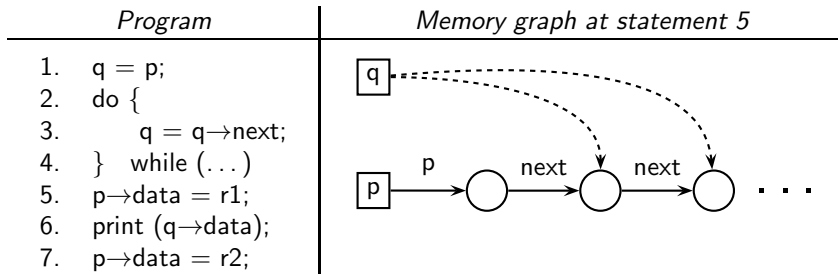
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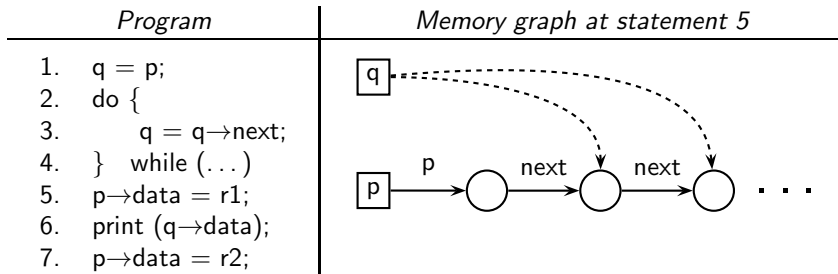
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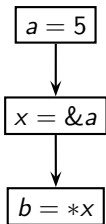
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- We cannot delete line 5 if  $p$  and  $q$  can be possibly aliased (while loop or do-while loop with a circular list)
- We can delete line 5 if  $p$  and  $q$  are definitely not aliased (do-while loop without a circular list)



## Code Optimization In Presence of Pointers (2)

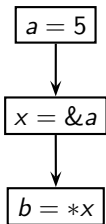


Original Program

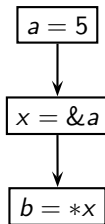




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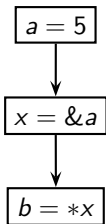
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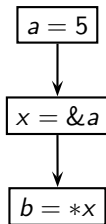
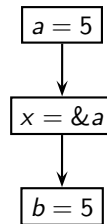
Constant Propagation  
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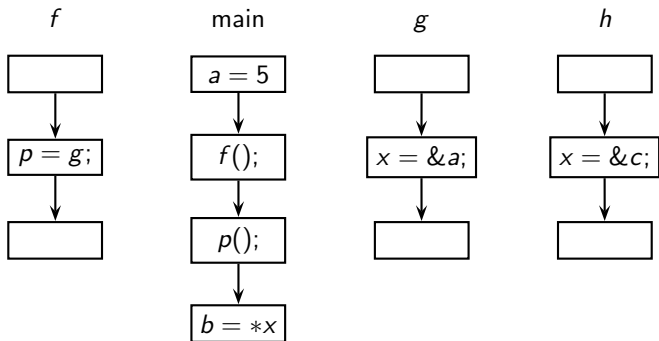
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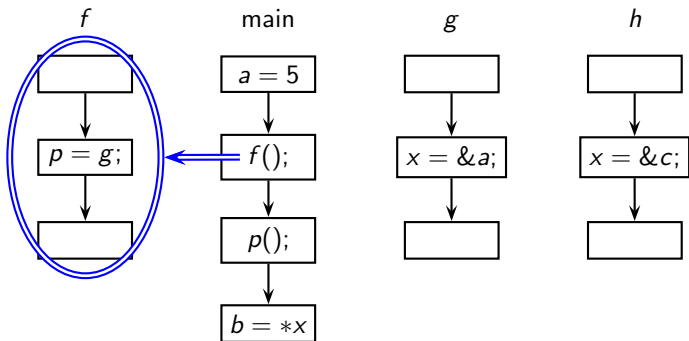
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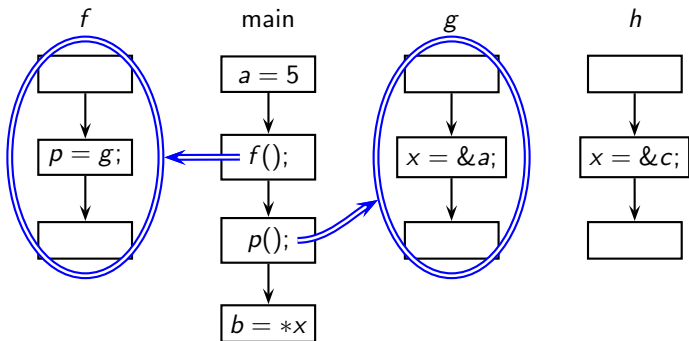
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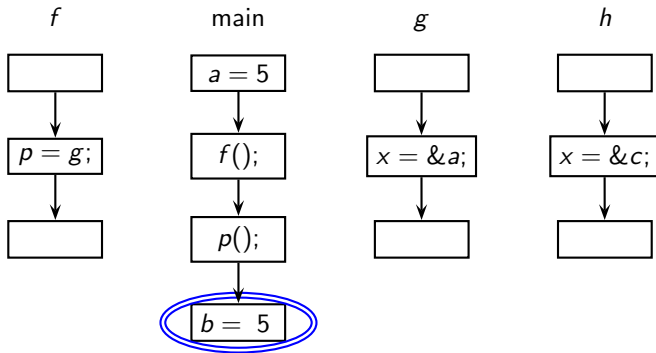
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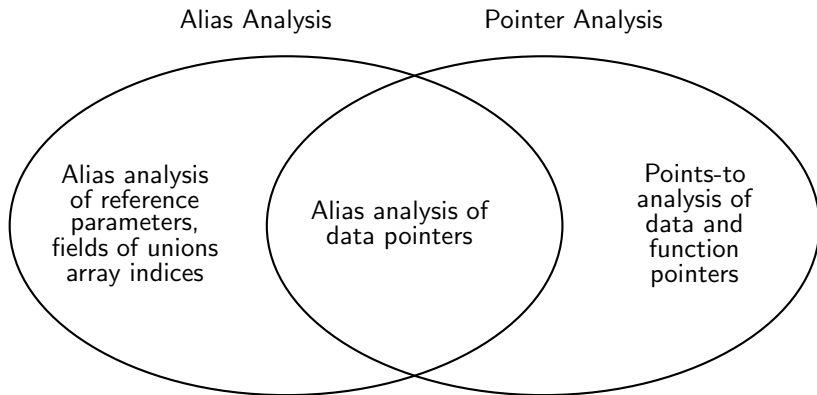


## Pointer Analysis

- Answers the following questions for indirect accesses:
  - ▶ Which data is read?  $x = *y$
  - ▶ Which data is written?  $*x = y$
  - ▶ Which procedure is called?  $p()$  or  $x \rightarrow f()$
- Enables precise data flow and interprocedural control flow analysis
- Computationally intensive analyses are ineffective when supplied with imprecise points-to information, (e.g., model checking, interprocedural analyses)
- Needs to scale to large programs



# The World of Pointer Analysis





## Pointer Analysis Musings

- Pointer analysis collects information about indirect accesses in programs
  - Enables precise data analysis
  - Enable precise interprocedural control flow analysis
- Needs to scale to large programs
- Pointer Analysis Musings
  - Which Pointer Analysis should I Use?  
Michael Hind and Anthony Pioli. ISTAA 2000
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  - 2019 .. 😞



# The Mathematics of Pointer Analysis

In the most general situation

- Alias analysis is undecidable.  
Landi-Ryder [POPL 1991], Landi [LOPLAS 1992],  
Ramalingam [TOPLAS 1994]
- Flow-insensitive alias analysis is NP-hard  
Horwitz [TOPLAS 1997]
- Points-to analysis is undecidable  
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*Adjust your expectations suitably to avoid disappointments!*



# The Engineering of Pointer Analysis

So what should we expect?



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So what should we expect? To quote Hind [PASTE 2001]



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So what should we expect? To quote Hind [PASTE 2001]

- “Fortunately many approximations exist”





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- “**Unfortunately too many** approximations exist!”



# The Engineering of Pointer Analysis

So what should we expect? To quote Hind [PASTE 2001]

- “Fortunately many approximations exist”
- “**Unfortunately too many** approximations exist!”

*Engineering of pointer analysis is much more dominant than its science*



## Pointer Analysis: Precision versus Scalability

- Ideally, an analysis should be
  - Sound
  - Precise
  - Scalable



# Pointer Analysis: Precision versus Scalability

- Ideally, an analysis should be
  - Sound
  - Precise
  - Scalable

## Common belief

- Precision and scalability cannot be achieved together for exhaustive analysis

## Common Practice

- Trade off precision using approximations



## Pointer Analysis: Precision versus Scalability

- Ideally, an analysis should be
  - Sound
  - Precise
  - Scalable
  
- The main factors enhancing the precision of an exhaustive (as against a demand-driven) analysis are
  - Flow sensitivity
  - Context sensitivity
  - Field sensitivity



# Demand-Driven Analysis Vs. Exhaustive Analysis

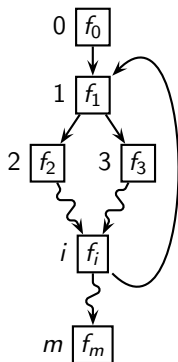
- **Exhaustive.** Compute all possible information
- **Demand-Driven.** Compute only the requested information (by a client)

Different from incremental analysis which also computes only some information but it updates the earlier computed solution

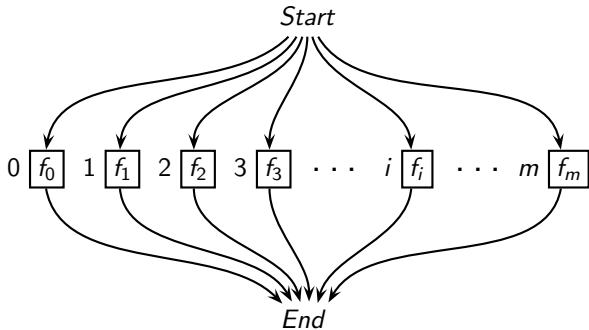


# Flow Sensitivity Vs. Flow Insensitivity

## Flow Sensitive

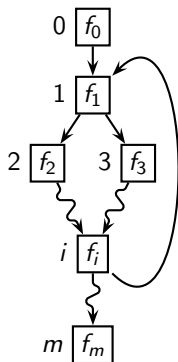


## Flow Insensitive

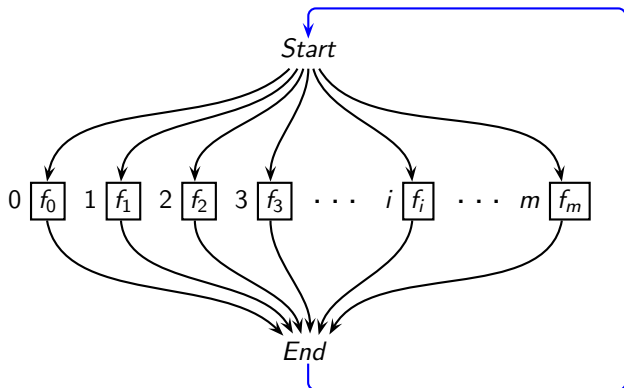


# Flow Sensitivity Vs. Flow Insensitivity

## Flow Sensitive



## Flow Insensitive



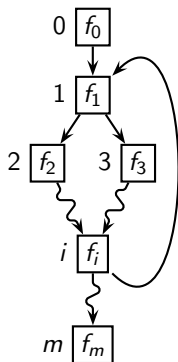
*Assumption: Statements can be executed in any order*



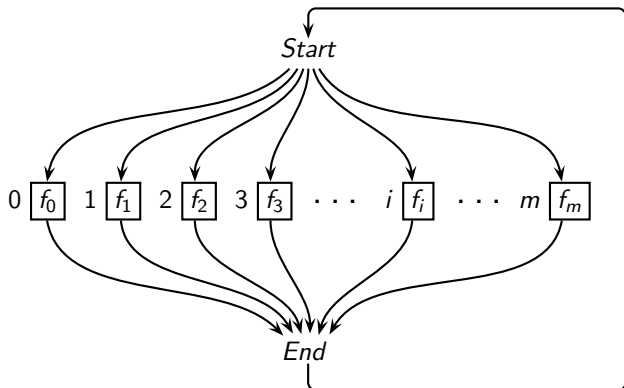


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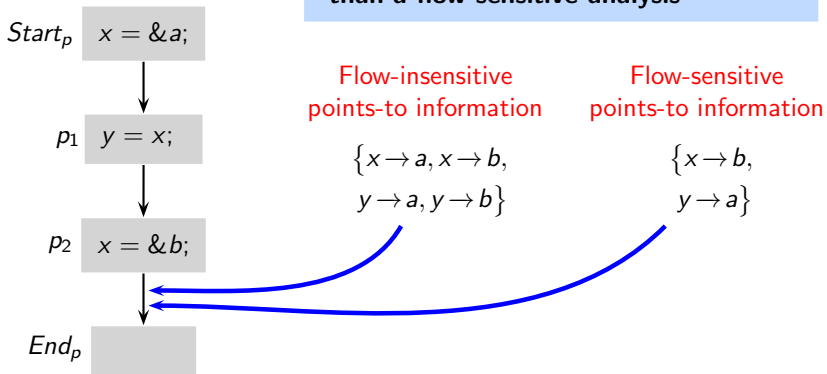


## Flow Insensitive

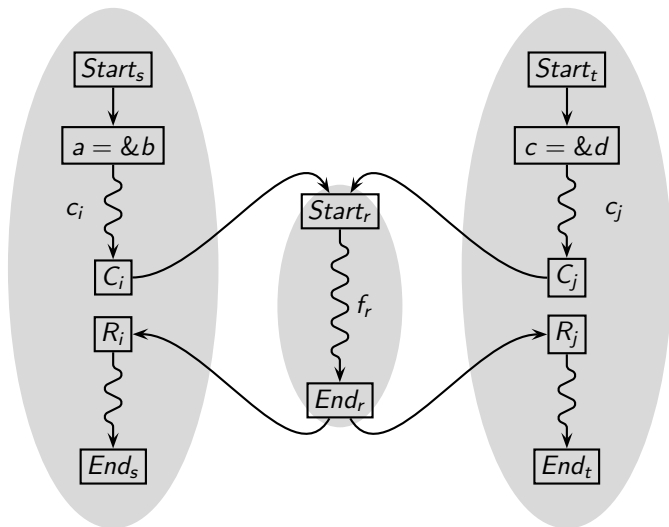


## Flow Sensitivity Vs. Flow Insensitivity

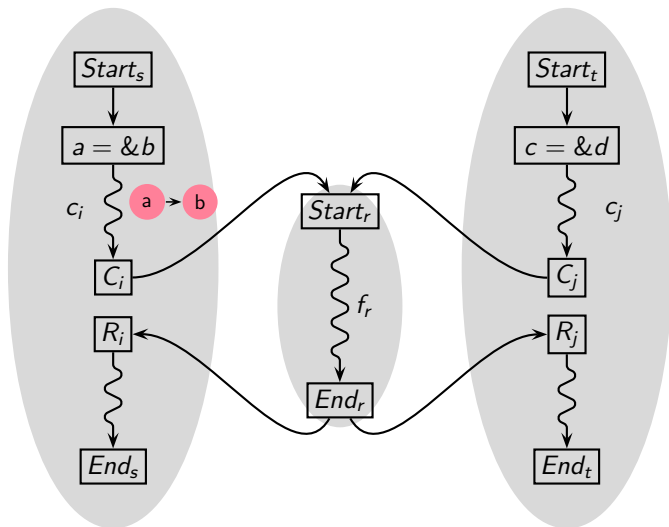
Flow-insensitive analysis is less precise than a flow-sensitive analysis



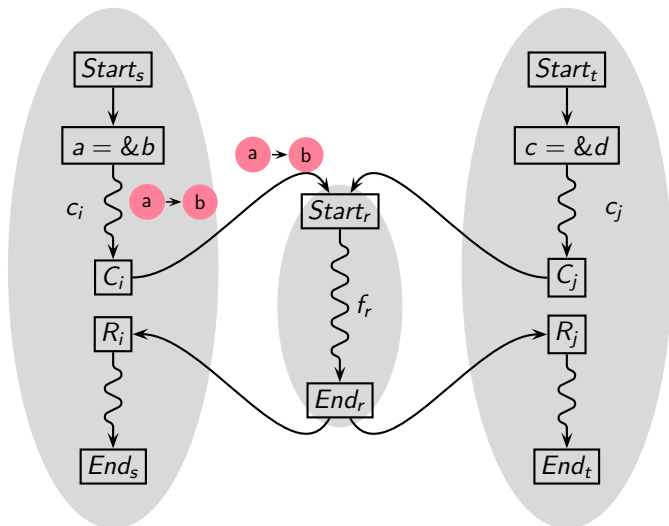
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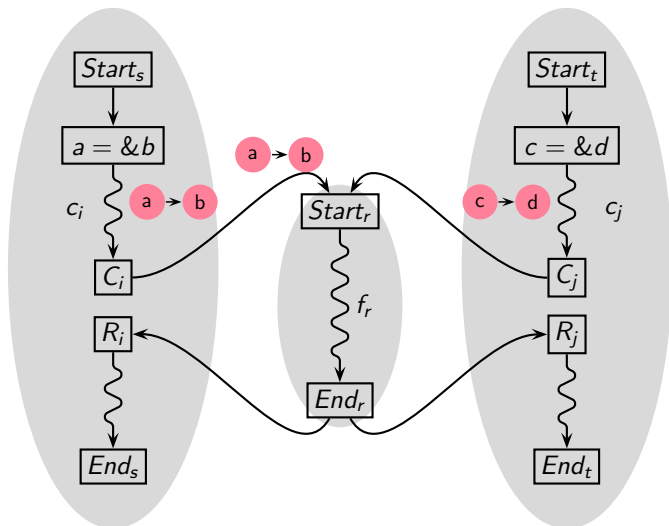
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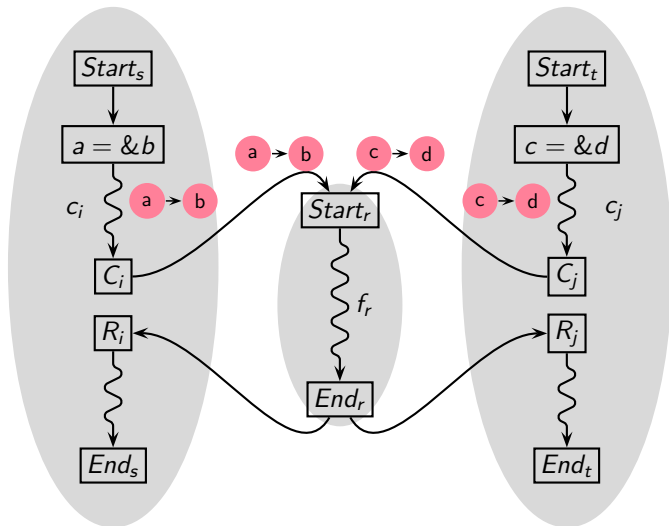
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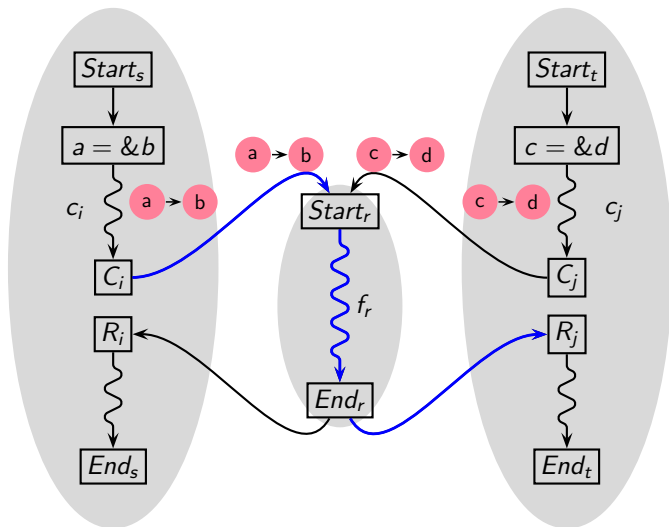
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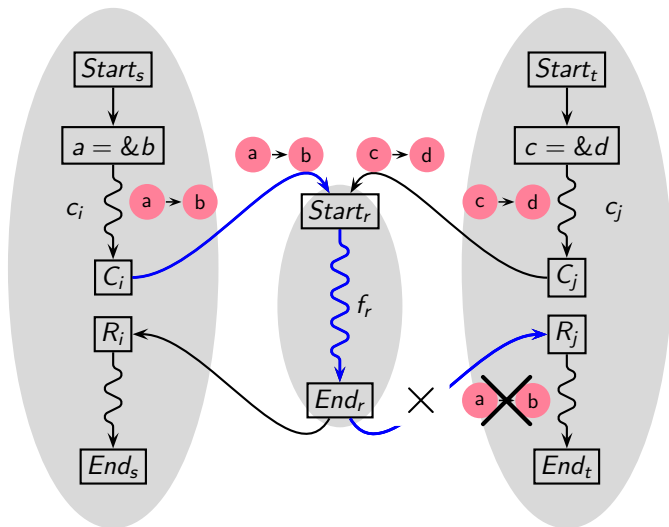


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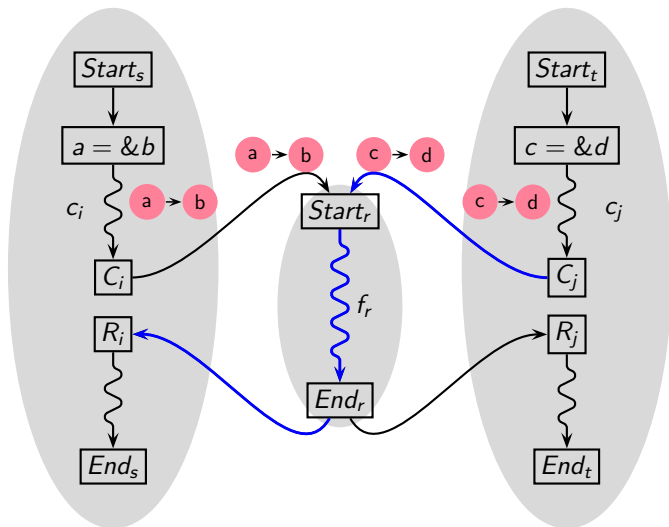




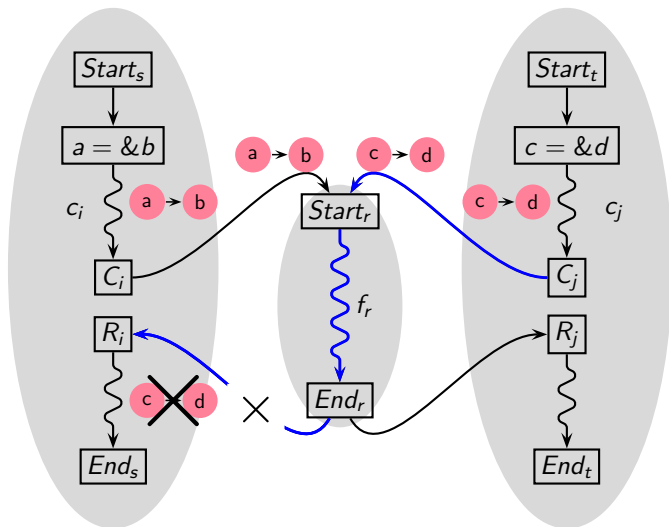
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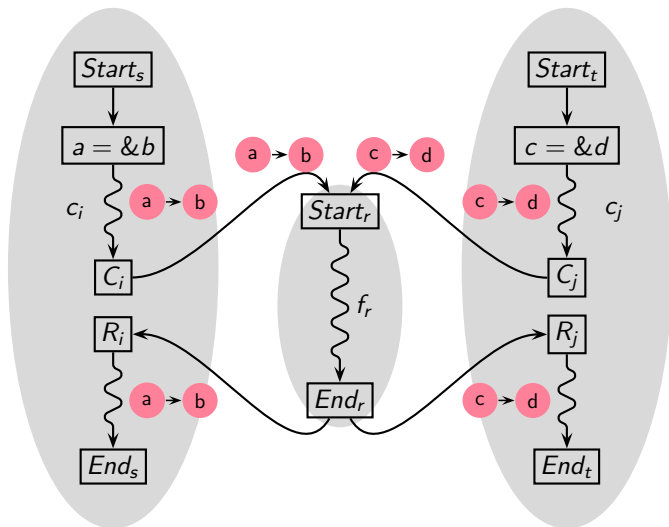
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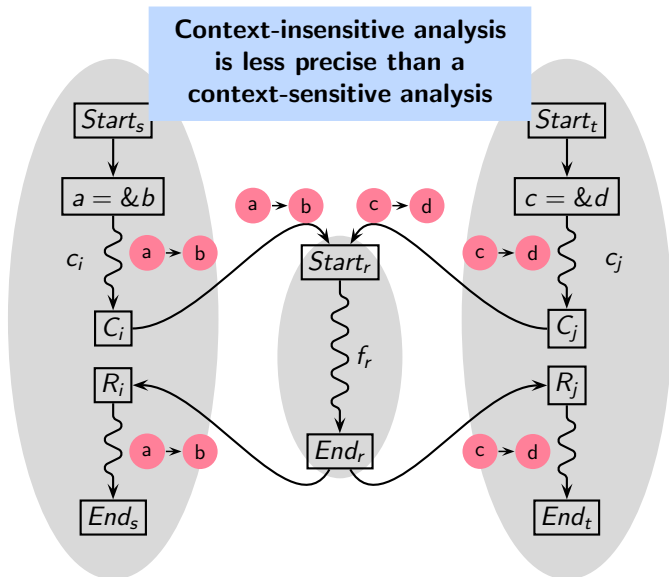
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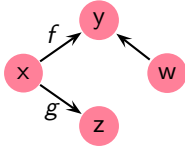
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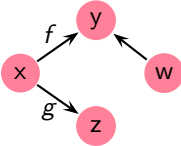
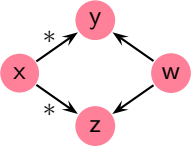


## Field Sensitivity Vs. Field Insensitivity

Program	Field-sensitive points-to graph	Field-insensitive points-to graph
$\begin{aligned}x &\rightarrow f = \&y \\x &\rightarrow g = \&z \\w &= x \rightarrow f\end{aligned}$	 <pre>graph TD; x((x)) -- f --&gt; y((y)); x((x)) -- g --&gt; z((z)); w((w)) --&gt; y((y));</pre>	



# Field Sensitivity Vs. Field Insensitivity

Program	Field-sensitive points-to graph	Field-insensitive points-to graph
$\begin{aligned}x &\rightarrow f = \&y \\x &\rightarrow g = \&z \\w &= x \rightarrow f\end{aligned}$	 <p>A points-to graph with four nodes: x, y, z, and w. Node x has two outgoing edges: one labeled 'f' pointing to node y, and one labeled 'g' pointing to node z. Node w has one outgoing edge labeled with an arrow pointing to node y.</p>	 <p>A points-to graph with four nodes: x, y, z, and w. Node x has two outgoing edges, both labeled with an asterisk '*', pointing to nodes y and z. Node w has one outgoing edge labeled with an arrow pointing to node y.</p>



## Field Sensitivity Vs. Field Insensitivity

Program	Field-sensitive points-to graph	Field-insensitive points-to graph
$x \rightarrow f = \&y$ $x \rightarrow g = \&z$ $w = x \rightarrow f$	<pre>graph TD; x((x)) -- f --&gt; y((y)); x((x)) -- g --&gt; z((z)); w((w)) --&gt; y((y));</pre>	<pre>graph TD; x((x)) -- * --&gt; y((y)); x((x)) -- * --&gt; z((z)); w((w)) --&gt; y((y)); w((w)) --&gt; z((z));</pre>

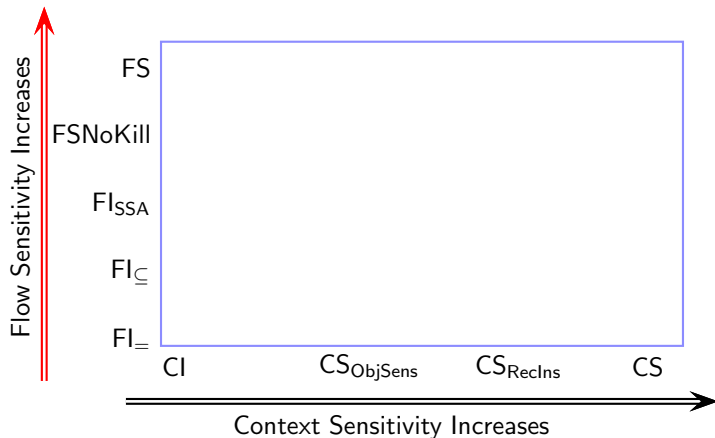
**Field-insensitive analysis is less precise than a field-sensitive analysis**





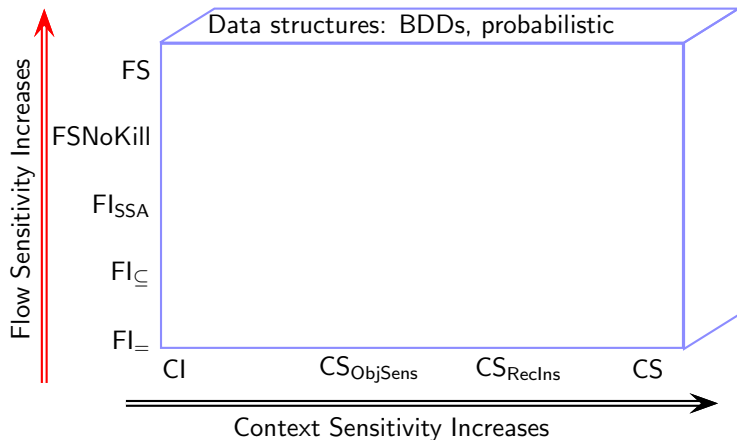
## Pointer Analysis: An Engineer's Landscape

Pointer analysis is a fertile ground for research because the factors that enhance the precision of points-to analysis (flow, context, and field sensitivity), hamper scalability



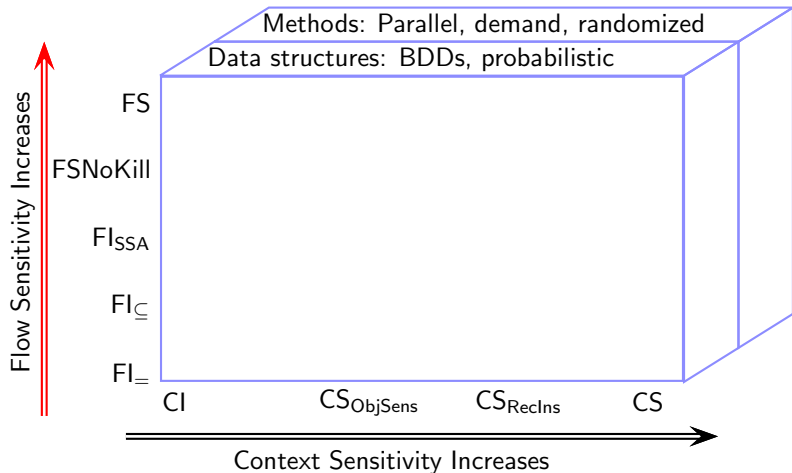
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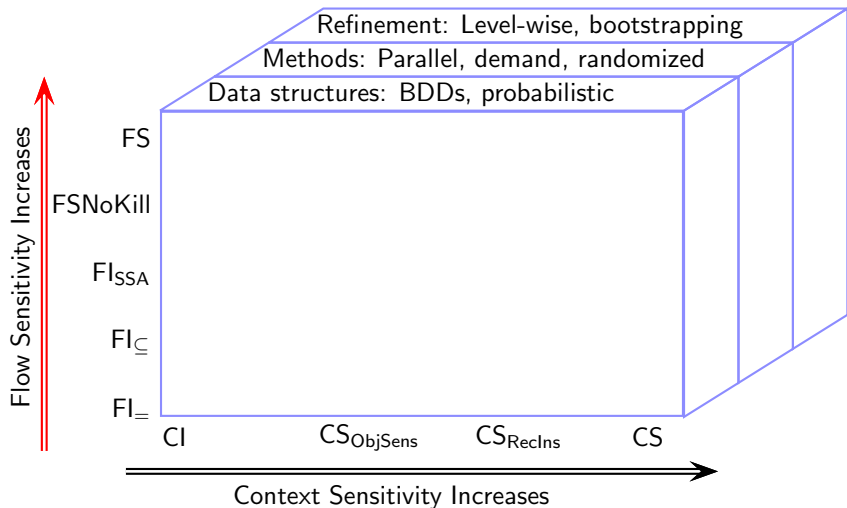
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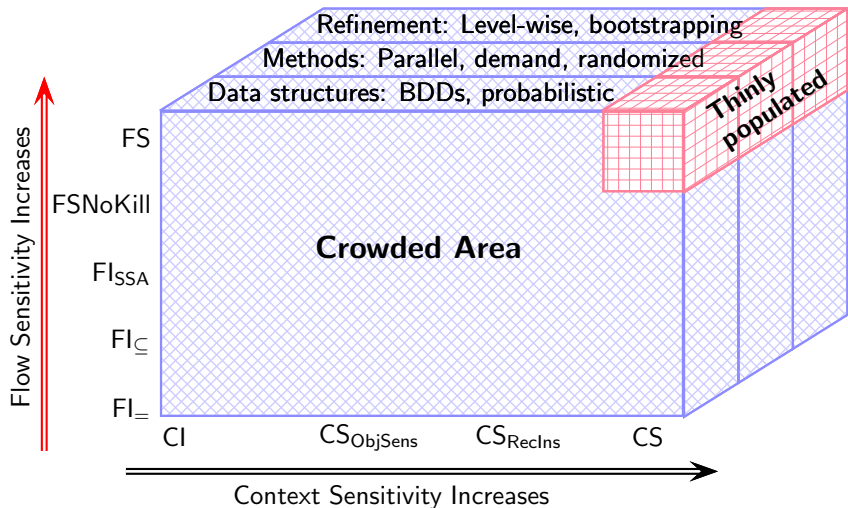
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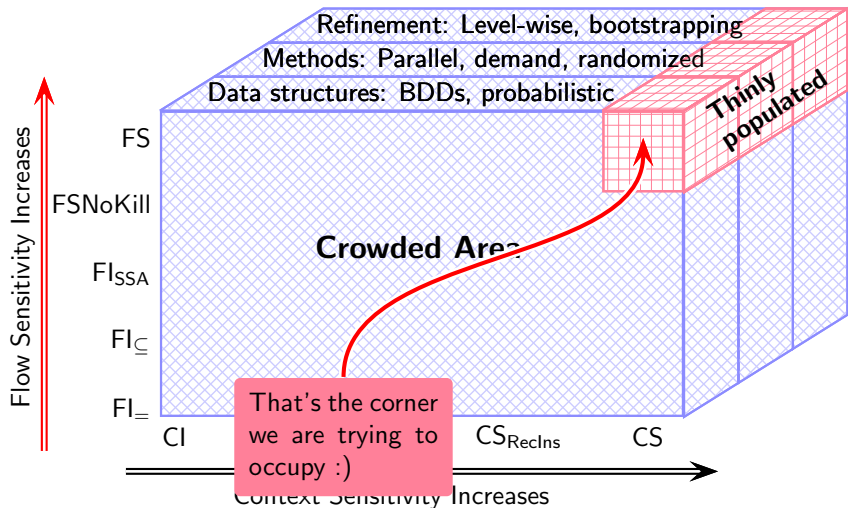
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- Flow-Insensitive Points-to Analysis
- Flow-Sensitive Points-to Analysis



## Pointer Statements

Pointer assignments	Use pointers in expressions
Addr $x = \&y$ Copy $x = y$ Load $x = *y$ $x = y \rightarrow n$ Store $*x = y$ $x \rightarrow n = y$	<i>Use x</i>

- Field accesses such as  $x.n$  are treated as new compile time names
- Containment of  $x.n$  within  $x$  is recorded in terms of offsets
- Heap will be introduced later





## What Does a Use Statement Represent? (1)

Consider the declaration: `int a, *x, **y;`

Source	3-Address representation	Our modelling
<code>*x = a</code>	<code>*x = a</code>	Use $x$
<code>a = *x</code>	<code>a = *x</code>	Use $x$
<code>if (x == NULL)</code>	<code>if (x == NULL)</code>	Use $x$
<code>if (*x == 5)</code>	<code>if (*x == 5)</code>	Use $x$
<code>if (*y == NULL)</code>	<code>t = *y</code> <code>if (t == NULL)</code>	$t = *y$ Use $t$
<code>(**y = a)</code>	<code>t = *y</code> <code>*t = a</code>	$t = *y$ Use $t$

*We retain only the pointers*



## What Does a Use Statement Represent? (2)

Consider the declaration:

```

struct s {
    struct s *n;
    int m;
} a, b, *x;

```

Source	3-Address representation	Our modelling
$a.n = \&b$	$a.n = \&b$	$a.n = \&b$
if ( $x \rightarrow n == NULL$ )	$t = x \rightarrow n$ if ( $t == NULL$ )	$t = x \rightarrow n$ Use $t$
if ( $a.n == NULL$ )	$t = a.n$ if ( $t == NULL$ )	$t = a.n$ Use $t$

*We retain only the pointers*



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# Flow-Sensitive Vs. Flow-Insensitive Pointer Analysis

- Flow-insensitive pointer analysis
  - Inclusion based: Andersen's approach
  - Equality based: Steensgaard's approach
- Flow-sensitive pointer analysis
  - May points-to analysis
  - Must points-to analysis



## Flow Insensitivity in Data Flow Analysis

- Assumption: Statements can be executed in any order.
- Instead of computing point-specific data flow information, summary data flow information is computed.

The summary information is required to be a safe approximation of point-specific information for each point.

*The control flow graph is a complete graph  
(except for the Start and End nodes)*



# Examples of Flow-Insensitive Analyses



## Examples of Flow-Insensitive Analyses

- Type checking/inferencing  
(What about interpreted languages?)



## Examples of Flow-Insensitive Analyses

- Type checking/inferencing  
(What about interpreted languages?)
- Address taken analysis  
Which variables have their addresses taken?





## Examples of Flow-Insensitive Analyses

- Type checking/inferencing  
(What about interpreted languages?)
- Address taken analysis  
Which variables have their addresses taken?
- Side effects analysis  
Does a procedure modify a global variable? Reference Parameter?



## Notation for Andersen's and Steensgaard's Points-to Analysis

- $P_{x.f}$  denotes the set of pointees of pointer variable  $x$  along field  $f$ 
  - $P_{x.*}$  (concisely written as  $P_x$ ) denotes the set of pointees of  $x$
  - If  $x$  is a structure,  $P_x$  is the set of pointees of all fields of  $x$
- $Unify(x, y)$  unifies locations  $x$  and  $y$ 
  - $x$  and  $y$  are treated as equivalent locations
  - the pointees of the unified locations are also unified transitively
- $UnifyPTS(x, y)$  unifies the pointees of  $x$  and  $y$ 
  - $x$  and  $y$  themselves are not unified
- We use  $x.f$  if the pointees of field  $f$  of  $x$  are to be unified



## Andersen's and Steensgaard's Points-to Analysis

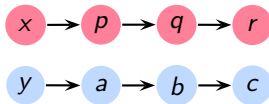
Statement	Andersen's Points-to Sets	Steensgaard's Points-to Sets
$x = \&y$	$P_x \supseteq \{y\}$	$P_x \supseteq \{y\}$ $\forall z \in P_x. \text{Unify}(y, z)$
$x = y$	$P_x \supseteq P_y$	$\text{UnifyPTS}(x, y)$
$x = *y$	$P_x \supseteq P_z. \forall z \in P_y$	$\forall z \in P_y. \text{UnifyPTS}(x, z)$
$*x = y$	$\forall z \in P_x. P_z \supseteq P_y$	$\forall z \in P_x. \text{UnifyPTS}(y, z)$



## Andersen's and Steensgaard's Points-to Analysis

Statement	Andersen's Points-to Sets	Steensgaard's Points-to Sets
$x = \&y$	$P_x \supseteq \{y\}$	$P_x \supseteq \{y\}$ $\forall z \in P_x. \text{Unify}(y, z)$
$x = y$	$P_x \supseteq P_y$	$\text{UnifyPTS}(x, y)$
$x = *y$	$P_x \supseteq P_z. \forall z \in P_y$	$\forall z \in P_y. \text{UnifyPTS}(x, z)$
$*x = y$	$\forall z \in P_x. P_z \supseteq P_y$	$\forall z \in P_x. \text{UnifyPTS}(y, z)$

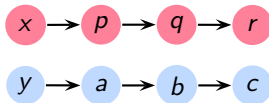
Points-to graph before  
the assignment



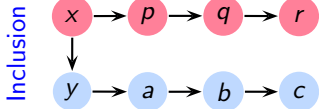
## Andersen's and Steensgaard's Points-to Analysis

Statement	Andersen's Points-to Sets	Steensgaard's Points-to Sets
$x = \&y$	$P_x \supseteq \{y\}$	$P_x \supseteq \{y\}$ $\forall z \in P_x. \text{Unify}(y, z)$
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$x = *y$	$P_x \supseteq P_z. \forall z \in P_y$	$\forall z \in P_y. \text{UnifyPTS}(x, z)$
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Points-to graph before  
the assignment



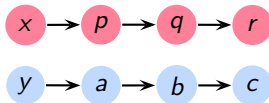
Andersen's graph after  
the assignment



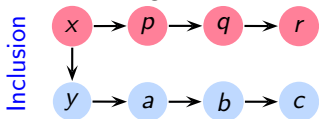
## Andersen's and Steensgaard's Points-to Analysis

Statement	Andersen's Points-to Sets	Steensgaard's Points-to Sets
$x = \&y$	$P_x \supseteq \{y\}$	$P_x \supseteq \{y\}$ $\forall z \in P_x. \text{Unify}(y, z)$
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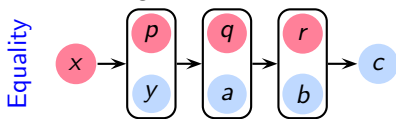
Points-to graph before  
the assignment



Andersen's graph after  
the assignment



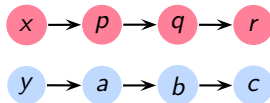
Steensgaard's graph after  
the assignment



## Andersen's and Steensgaard's Points-to Analysis

Statement	Andersen's Points-to Sets	Steensgaard's Points-to Sets
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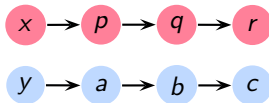
Points-to graph before  
the assignment



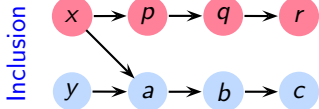
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$x = \&y$	$P_x \supseteq \{y\}$	$P_x \supseteq \{y\}$ $\forall z \in P_x. \text{Unify}(y, z)$
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Points-to graph before  
the assignment



Andersen's graph after  
the assignment

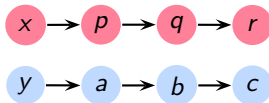




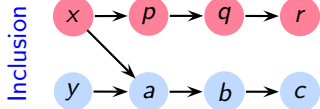
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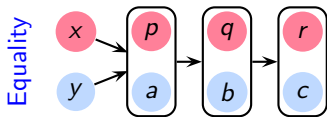
Points-to graph before  
the assignment



Andersen's graph after  
the assignment



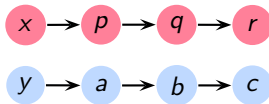
Steensgaard's graph after  
the assignment



## Andersen's and Steensgaard's Points-to Analysis

Statement	Andersen's Points-to Sets	Steensgaard's Points-to Sets
$x = \&y$	$P_x \supseteq \{y\}$	$P_x \supseteq \{y\}$ $\forall z \in P_x. \text{Unify}(y, z)$
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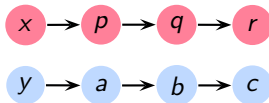
Points-to graph before  
the assignment



## Andersen's and Steensgaard's Points-to Analysis

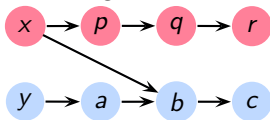
Statement	Andersen's Points-to Sets	Steensgaard's Points-to Sets
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$*x = y$	$\forall z \in P_x. P_z \supseteq P_y$	$\forall z \in P_x. \text{UnifyPTS}(y, z)$

Points-to graph before  
the assignment



Andersen's graph after  
the assignment

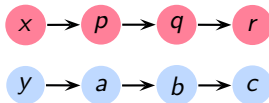
Inclusion



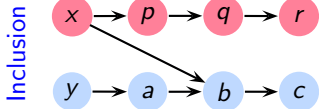
## Andersen's and Steensgaard's Points-to Analysis

Statement	Andersen's Points-to Sets	Steensgaard's Points-to Sets
$x = \&y$	$P_x \supseteq \{y\}$	$P_x \supseteq \{y\}$ $\forall z \in P_x. \text{Unify}(y, z)$
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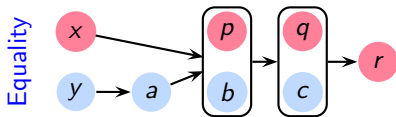
Points-to graph before  
the assignment



Andersen's graph after  
the assignment



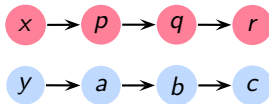
Steensgaard's graph after  
the assignment



## Andersen's and Steensgaard's Points-to Analysis

Statement	Andersen's Points-to Sets	Steensgaard's Points-to Sets
$x = \&y$	$P_x \supseteq \{y\}$	$P_x \supseteq \{y\}$ $\forall z \in P_x. \text{Unify}(y, z)$
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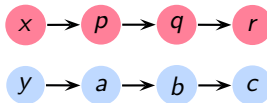
Points-to graph before  
the assignment



## Andersen's and Steensgaard's Points-to Analysis

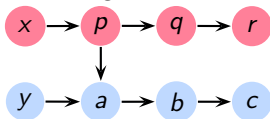
Statement	Andersen's Points-to Sets	Steensgaard's Points-to Sets
$x = \&y$	$P_x \supseteq \{y\}$	$P_x \supseteq \{y\}$ $\forall z \in P_x. \text{Unify}(y, z)$
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Points-to graph before  
the assignment



Andersen's graph after  
the assignment

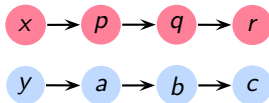
Inclusion



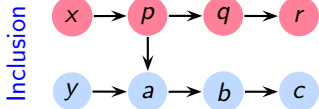
## Andersen's and Steensgaard's Points-to Analysis

Statement	Andersen's Points-to Sets	Steensgaard's Points-to Sets
$x = \&y$	$P_x \supseteq \{y\}$	$P_x \supseteq \{y\}$ $\forall z \in P_x. \text{Unify}(y, z)$
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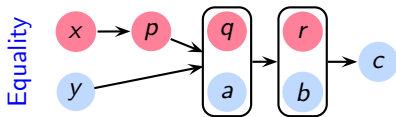
Points-to graph before  
the assignment



Andersen's graph after  
the assignment



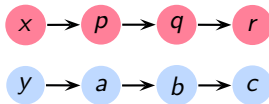
Steensgaard's graph after  
the assignment



## Andersen's and Steensgaard's Points-to Analysis

Statement	Andersen's Points-to Sets	Steensgaard's Points-to Sets
$x = \&y$	$P_x \supseteq \{y\}$	$P_x \supseteq \{y\}$ $\forall z \in P_x. \text{Unify}(y, z)$
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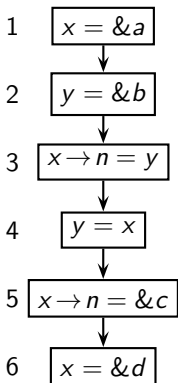
Points-to graph before  
the assignment





## Example of Inclusion Based (aka Andersen's) Points-to Analysis

Program



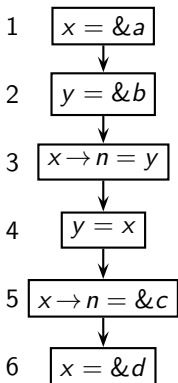
Type declarations

```
struct s {  
    struct s *n;  
    int m;  
} *x, *y, a, b, c, d;
```



## Example of Inclusion Based (aka Andersen's) Points-to Analysis

Program

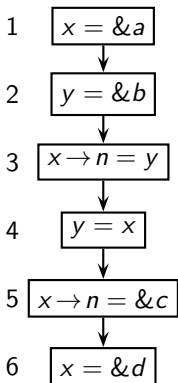


Node	Constraint
1	$P_x \supseteq \{a\}$
2	$P_y \supseteq \{b\}$
3	$\forall z \in P_x, P_{z.n} \supseteq P_y$
4	$P_y \supseteq P_x$
5	$\forall z \in P_x, P_{z.n} \supseteq \{c\}$
6	$P_x \supseteq \{d\}$



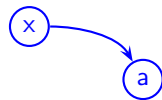
## Example of Inclusion Based (aka Andersen's) Points-to Analysis

Program



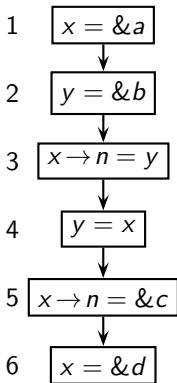
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1	$P_x \supseteq \{a\}$
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Points-to Graph



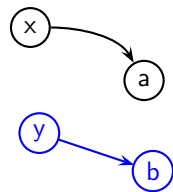
## Example of Inclusion Based (aka Andersen's) Points-to Analysis

Program



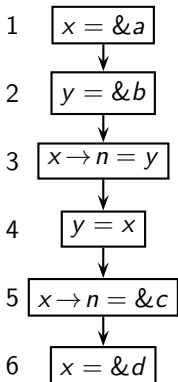
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Points-to Graph



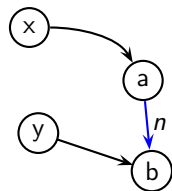
## Example of Inclusion Based (aka Andersen's) Points-to Analysis

Program



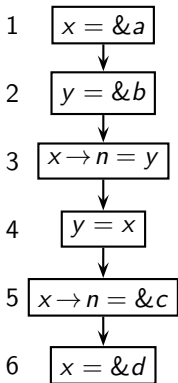
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Points-to Graph



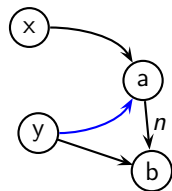
## Example of Inclusion Based (aka Andersen's) Points-to Analysis

Program



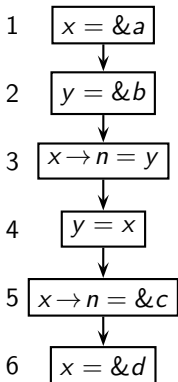
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Points-to Graph



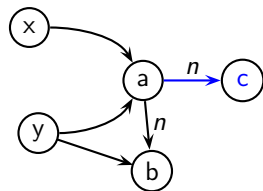
## Example of Inclusion Based (aka Andersen's) Points-to Analysis

Program



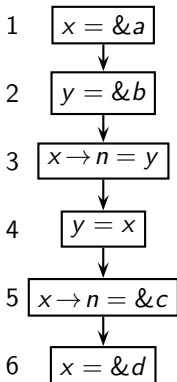
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Points-to Graph



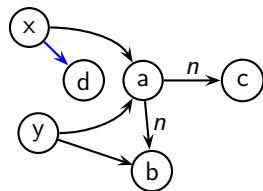
## Example of Inclusion Based (aka Andersen's) Points-to Analysis

Program



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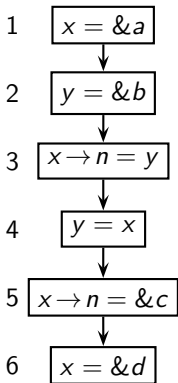
Points-to Graph





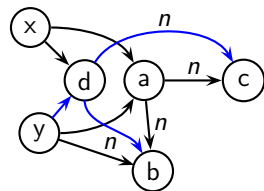
## Example of Inclusion Based (aka Andersen's) Points-to Analysis

Program



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Points-to Graph

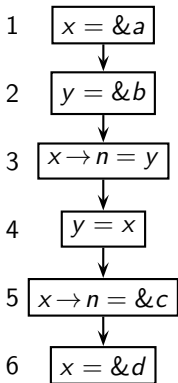


- Since  $P_x$  has changed, constraints 3, 4, and 5 needs to be processed again
- Order of processing the sets influences the efficiency of this fixed point computation significantly
- A plethora of heuristics have been proposed



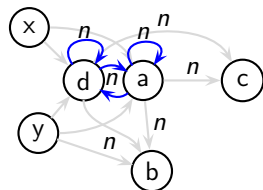
## Example of Inclusion Based (aka Andersen's) Points-to Analysis

Program



Node	Constraint
1	$P_x \supseteq \{a\}$
2	$P_y \supseteq \{b\}$
3	$\forall z \in P_x, P_{z.n} \supseteq P_y$
4	$P_y \supseteq P_x$
5	$\forall z \in P_x, P_{z.n} \supseteq \{c\}$
6	$P_x \supseteq \{d\}$

Points-to Graph

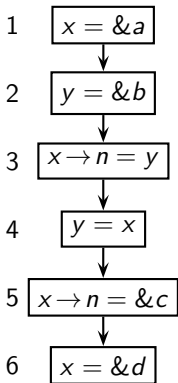


- Since  $P_x$  has changed, constraints 3, 4, and 5 needs to be processed again
- Order of processing the sets influences the efficiency of this fixed point computation significantly
- A plethora of heuristics have been proposed



## Example of Inclusion Based (aka Andersen's) Points-to Analysis

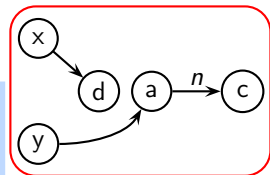
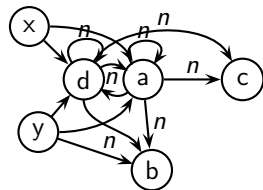
Program



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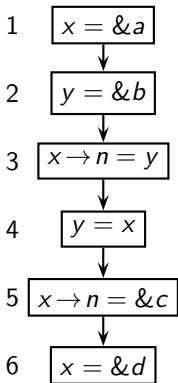
- Actual graph after statement 6 (red box on the right) is much simpler with many edges killed
- $y$  does not point to  $d$  any time in the execution

Points-to Graph



## Example of Inclusion Based (aka Andersen's) Points-to Analysis

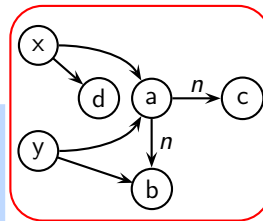
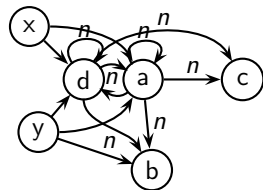
Program



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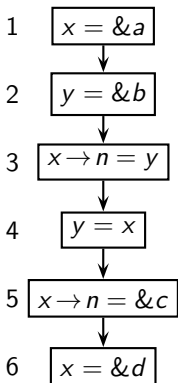
- A union of all graphs at each program point
- $y$  does not point to  $d$  any time in the execution

Points-to Graph



## Example of Equality Based (aka Steensgaard's) Points-to Analysis

Program

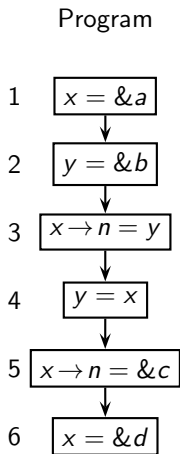


## Example of Equality Based (aka Steensgaard's) Points-to Analysis

Program	Node	Constraint
1 $x = \&a$	1	$P_x \supseteq \{a\}$ $\forall z \in P_x, \text{Unify}(a, z)$
2 $y = \&b$	2	$P_y \supseteq \{b\}$ $\forall z \in P_y, \text{Unify}(b, z)$
3 $x \rightarrow n = y$	3	$\forall z \in P_x, \text{UnifyPTS}(y, z.n)$
4 $y = x$	4	$\text{UnifyPTS}(x, y)$
5 $x \rightarrow n = \&c$	5	$\forall z \in P_x, P_{z.n} \supseteq \{c\}$ $\forall w \in P_{z.n}, \text{Unify}(w, c)$
6 $x = \&d$	6	$P_x \supseteq \{d\}$ $\forall z \in P_x, \text{Unify}(d, z)$

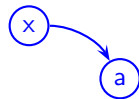


## Example of Equality Based (aka Steensgaard's) Points-to Analysis

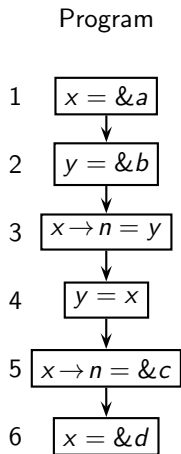


Node	Constraint
1	$P_x \supseteq \{a\}$ $\forall z \in P_x, \text{Unify}(a, z)$
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Points-to Graph

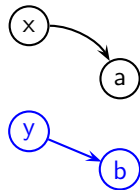


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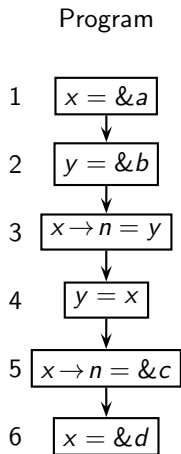
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Points-to Graph



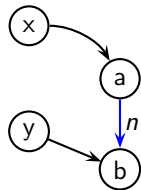


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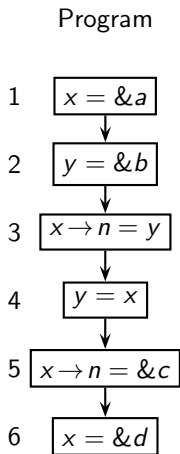


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Points-to Graph

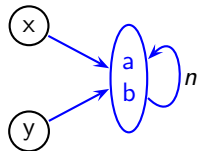


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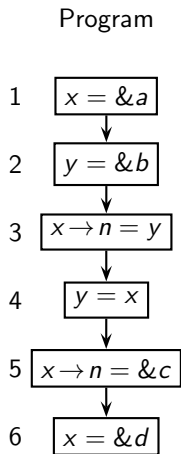


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Points-to Graph

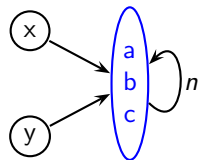


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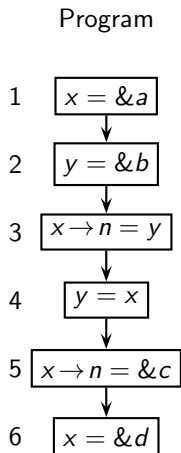


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Points-to Graph

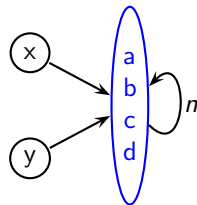


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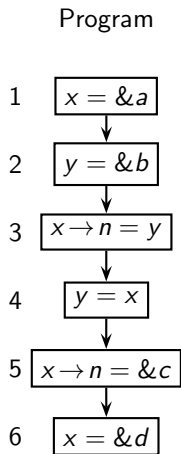


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Points-to Graph

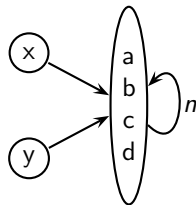


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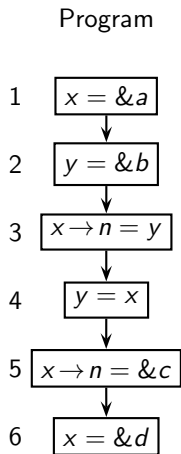
Points-to Graph



No further change



## Example of Equality Based (aka Steensgaard's) Points-to Analysis

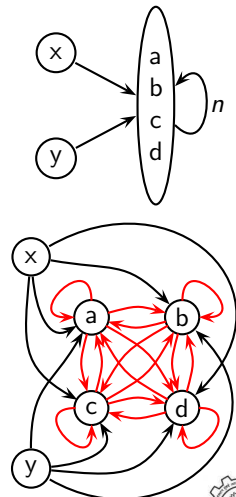


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Red edges represent field  $n$  in the the full blown up graph. It has far more edges than in Andersen's graph

Far more efficient but far less precise

Points-to Graph



## Comparing Equality and Inclusion Based Analyses

- Andersen's algorithm is cubic in number of pointers
- Steensgaard's algorithm is nearly linear in number of pointers



## Comparing Equality and Inclusion Based Analyses

- Andersen's algorithm is cubic in number of pointers
- Steensgaard's algorithm is nearly linear in number of pointers
  - How can it be more efficient by an orders of magnitude?





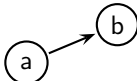
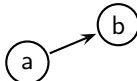
## Efficiency of Equality Based Approach

Program	Andersen's approach	Steensgaard's approach
<pre>a = &amp;b a = &amp;c b.n = &amp;d b.n = &amp;c</pre>		

- Andersen's inclusion based wisdom:
  - Add edges and let the number of successors increase
- Steensgaard's equality based wisdom:
  - Merge multiple successors and maintain a single successor of any node



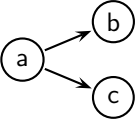
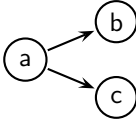
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Program	Andersen's approach	Steensgaard's approach
<pre>a = &amp;b a = &amp;c b.n = &amp;d b.n = &amp;c</pre>	 <pre>graph LR   a((a)) --&gt; b((b))</pre>	 <pre>graph LR   a((a)) --&gt; b((b))</pre>

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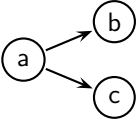
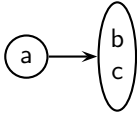
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<pre>a = &amp;b a = &amp;c b.n = &amp;d b.n = &amp;c</pre>	 <pre>graph LR   a((a)) --&gt; b((b))   a --&gt; c((c))</pre>	 <pre>graph LR   a((a)) --&gt; bc([b c])</pre>

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## Efficiency of Equality Based Approach

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<pre> a = &amp;b a = &amp;c b.n = &amp;d b.n = &amp;c           </pre>	<pre> graph LR   a((a)) --&gt; b((b))   a --&gt; c((c))   b -- n --&gt; d((d))           </pre>	<pre> graph LR   a((a)) --&gt; bc((b c))   bc --&gt; d((d))           </pre>

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<pre> a = &amp;b a = &amp;c b.n = &amp;d b.n = &amp;c           </pre>	<pre> graph LR   a((a)) --&gt; b((b))   a --&gt; c((c))   b -- n --&gt; d((d))   c -- n --&gt; d           </pre>	<pre> graph LR   a((a)) --&gt; bc((b c))   bc --&gt; bc   bc --&gt; d((d))           </pre>

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## Efficiency of Equality Based Approach

Program	Andersen's approach	Steensgaard's approach
<pre> a = &amp;b a = &amp;c b.n = &amp;d b.n = &amp;c           </pre>	<pre> graph LR   a((a)) --&gt; b((b))   a --&gt; c((c))   b -- n --&gt; d((d))   c -- n --&gt; d           </pre>	<pre> graph LR   a((a)) --&gt; summary([b c d])   summary -- n --&gt; summary           </pre>

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  - Since a larger number of pointers treated are alike and fewer distinctions are maintained, we get much smaller points-to graphs





## Efficiency of Equality Based Approach

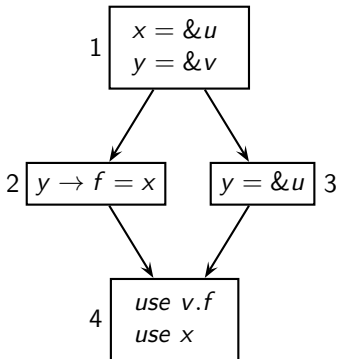
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- Steensgaard's equality based wisdom:
  - Merge multiple successors and maintain a single successor of any node
  - Since a larger number of pointers treated are alike and fewer distinctions are maintained, we get much smaller points-to graphs
  - Efficient *Union-Find* algorithms to merge intersecting subsets



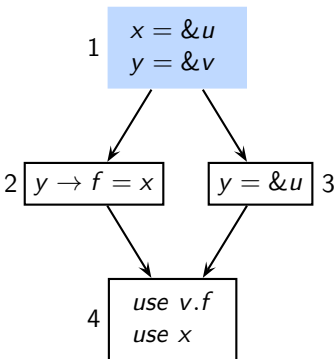
## Inclusion Based (aka Andersen's) Points-to Analysis: Example 2

```
struct s {  
    struct s *f;  
    int n;  
} *x, *y, u, v;
```

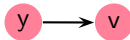
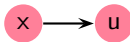


# Inclusion Based (aka Andersen's) Points-to Analysis: Example 2

```
struct s {
  struct s *f;
  int n;
} *x, *y, u, v;
```



- x "points-to" u
- y "points-to" v



Andersen's Points-to Graph

Constraints on  
Points-to Sets

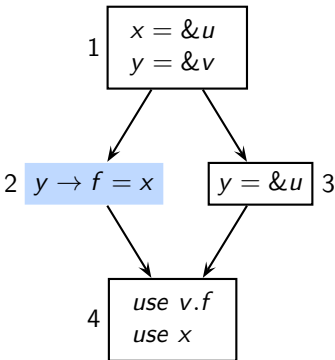
$$P_x \supseteq \{u\}$$

$$P_y \supseteq \{v\}$$

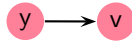
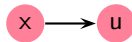


## Inclusion Based (aka Andersen's) Points-to Analysis: Example 2

```
struct s {
  struct s *f;
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```



- The  $f$  field of pointees of  $y$  should point to pointees of  $x$  also
- The  $f$  field of  $v$  should point to  $u$  also



Andersen's Points-to Graph

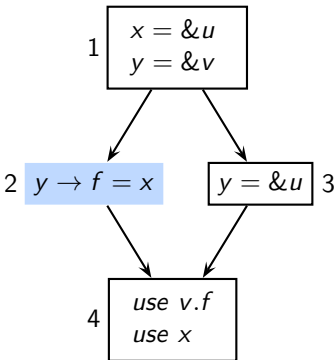
Constraints on  
Points-to Sets

$$\begin{aligned}
 P_x &\supseteq \{u\} \\
 P_y &\supseteq \{v\} \\
 \forall w \in P_y, P_{w.f} &\supseteq P_x
 \end{aligned}$$

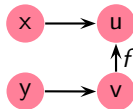


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struct s {
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  int n;
} *x, *y, u, v;
```



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Andersen's Points-to Graph

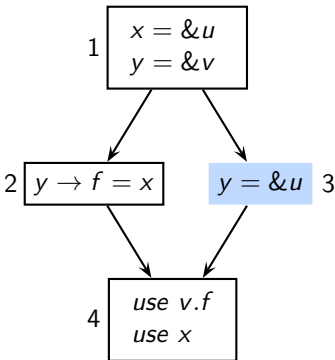
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 \forall w \in P_y, P_{w.f} &\supseteq P_x
 \end{aligned}$$

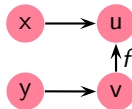


## Inclusion Based (aka Andersen's) Points-to Analysis: Example 2

```
struct s {
  struct s *f;
  int n;
} *x, *y, u, v;
```



- y should point to u also



Andersen's Points-to Graph

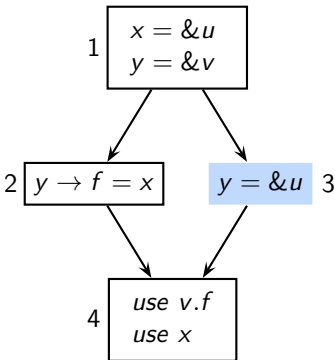
Constraints on  
Points-to Sets

$$\begin{aligned}
 P_x &\supseteq \{u\} \\
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 \forall w \in P_y, P_{w.f} &\supseteq P_x \\
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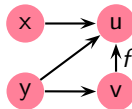


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Andersen's Points-to Graph

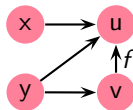
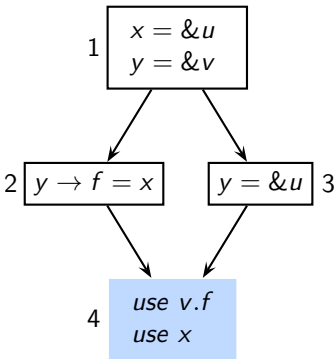
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Andersen's Points-to Graph

Constraints on  
Points-to Sets

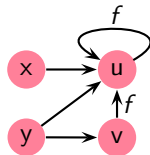
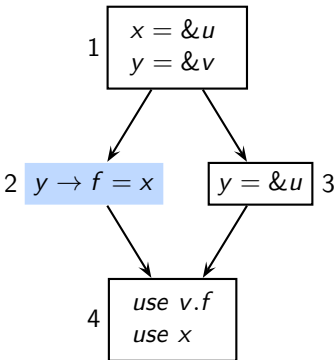
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## Inclusion Based (aka Andersen's) Points-to Analysis: Example 2

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Andersen's Points-to Graph

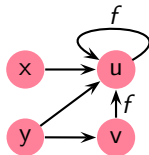
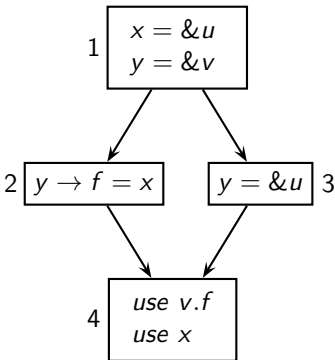
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Andersen's Points-to Graph

Constraints on  
Points-to Sets

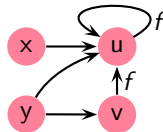
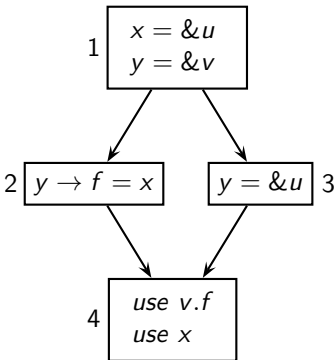
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## Equality Based (aka Steensgaard's) Points-to Analysis: Example 2

```
struct s {
  struct s *f;
  int n;
} *x, *y, u, v;
```

- Treat all pointees of a pointer as “equivalent” locations
- Transitive closure  
Pointees of all equivalent locations become equivalent



Andersen's Points-to Graph



## Equality Based (aka Steensgaard's) Points-to Analysis: Example 2

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struct s {
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} *x, *y, u, v;
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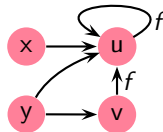
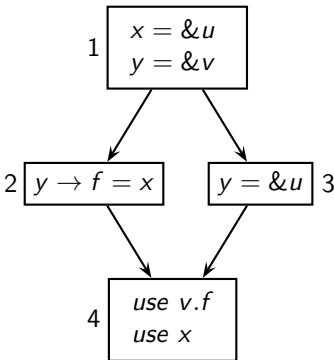
- Treat all pointees of a pointer as “equivalent” locations
- Transitive closure  
Pointees of all equivalent locations become equivalent

Effective additional constraints

---

$Unify(u, v)$   
/\* pointees of  $y$  \*/

---



Andersen's Points-to Graph



## Equality Based (aka Steensgaard's) Points-to Analysis: Example 2

```
struct s {
  struct s *f;
  int n;
} *x, *y, u, v;
```

- Treat all pointees of a pointer as “equivalent” locations
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Pointees of all equivalent locations become equivalent

Effective additional constraints

---

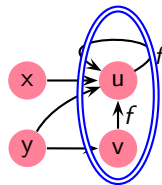
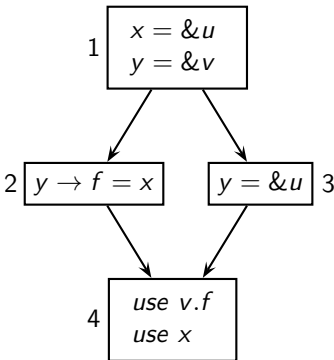

$$\text{Unify}(u, v)$$


---


$$/* \text{pointees of } y */$$


---

$\Rightarrow u, v$  are equivalent



Steensgaard's Points-to Graph



## Equality Based (aka Steensgaard's) Points-to Analysis: Example 2

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struct s {
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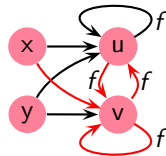
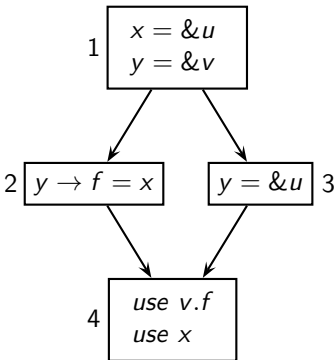
Effective additional constraints

---

$Unify(u, v)$   
/\* pointees of  $y$  \*/

---

$\Rightarrow u, v$  are equivalent



Steensgaard's Points-to Graph



## Equality Based (aka Steensgaard's) Points-to Analysis: Example 2

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struct s {
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Effective additional constraints

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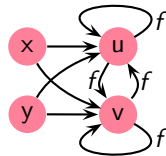
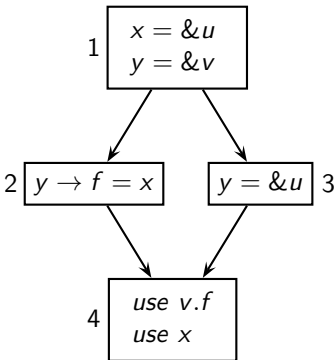

$$\text{Unify}(u, v)$$


---

/\* pointees of  $y$  \*/

---

$\Rightarrow u, v$  are equivalent



Steensgaard's Points-to Graph



# Tutorial Problem for Flow-Insensitive Pointer Analysis

Program

```
p = &q  
r = &s  
t = &p  
u = p  
*t = r
```

Inclusion based

Equality based



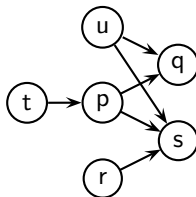


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Equality based

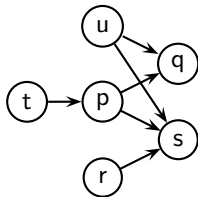


# Tutorial Problem for Flow-Insensitive Pointer Analysis

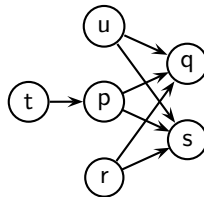
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Equality based

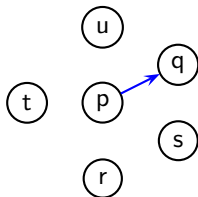


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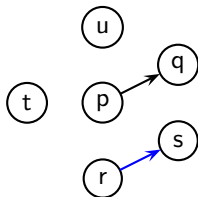


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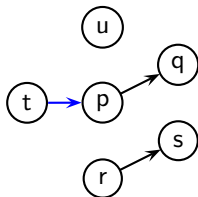


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Equality based

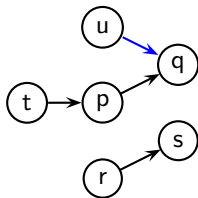


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Equality based

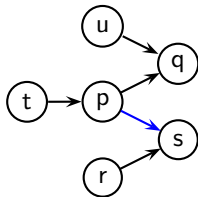


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Equality based

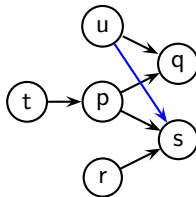


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Equality based



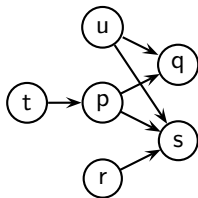


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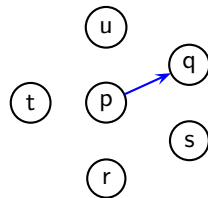
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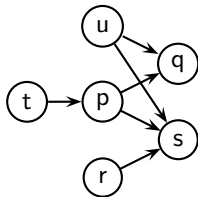


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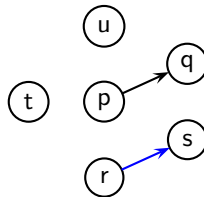
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Equality based

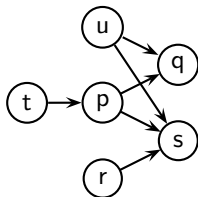


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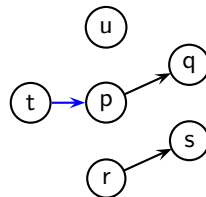
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Equality based

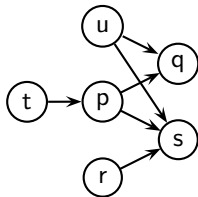


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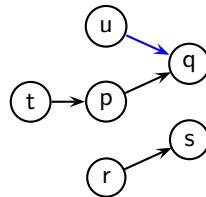
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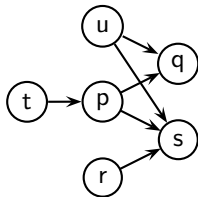


# Tutorial Problem for Flow-Insensitive Pointer Analysis

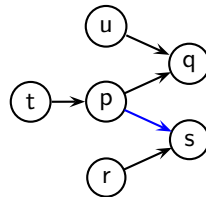
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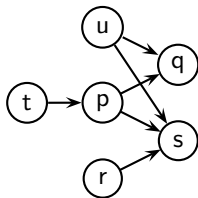


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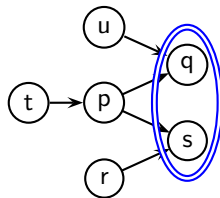
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Inclusion based



Equality based

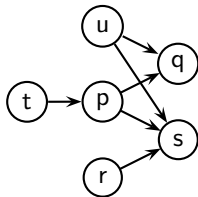


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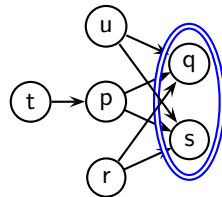
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Equality based

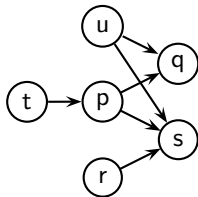


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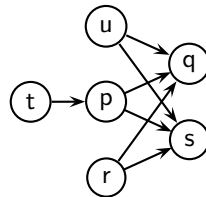
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Equality based



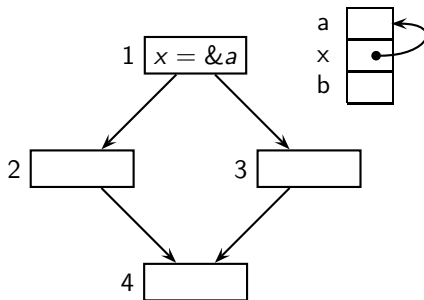


# An Outline of Pointer Analysis Coverage

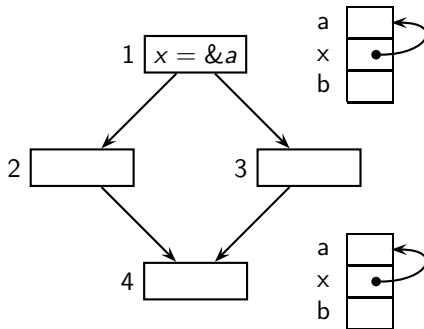
- The larger perspective
- IR for Points-to Analysis
- Flow-Insensitive Points-to Analysis
- Flow-Sensitive Points-to Analysis **Next Topic**



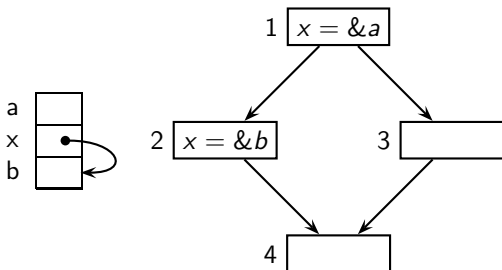
# Must Points-to Information



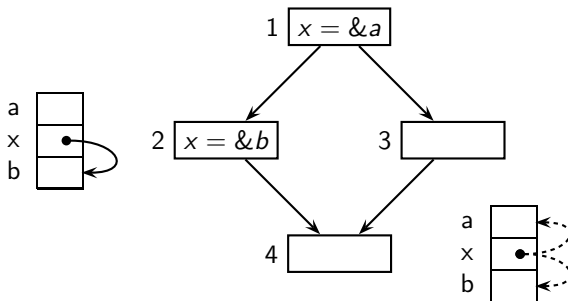
# Must Points-to Information



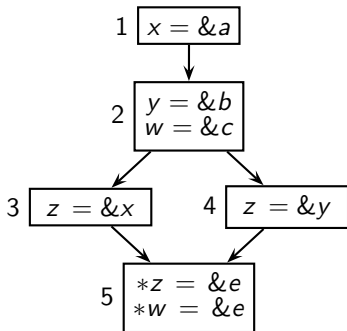
# May Points-to Information



# May Points-to Information



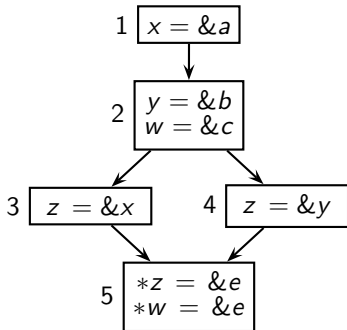
# Strong and Weak Updates



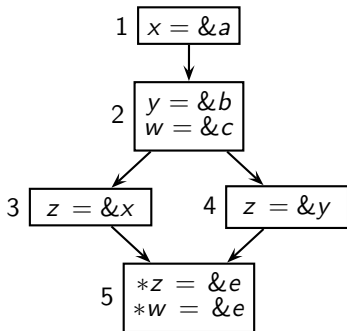
## Strong and Weak Updates

- Weak update: Modification of  $x$  or  $y$  due to  $*z$  in block 5

Only Gen, No Kill



## Strong and Weak Updates

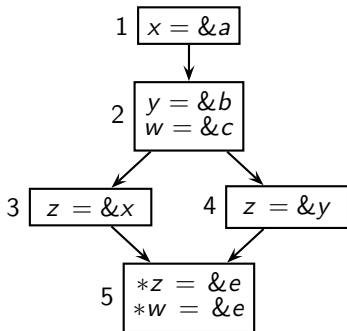


- **Weak update:** Modification of  $x$  or  $y$  due to  $*z$  in block 5  
Only Gen, No Kill
- **Strong update:** Modification of  $c$  due to  $*w$  in block 5  
Both Gen and Kill





## Strong and Weak Updates



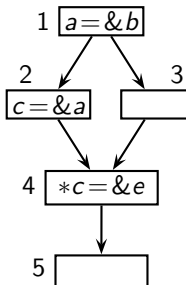
- **Weak update:** Modification of  $x$  or  $y$  due to  $*z$  in block 5  
Only Gen, No Kill
- **Strong update:** Modification of  $c$  due to  $*w$  in block 5  
Both Gen and Kill
- How is this concept related to May/Must nature of information?



# May and Must Analysis for Killing Points-to Information (1)

*MFP of May Points-to Analysis*

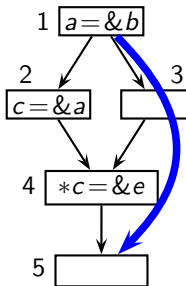
*MFP of Must Points-to Analysis*



# May and Must Analysis for Killing Points-to Information (1)

## MFP of May Points-to Analysis

- $(a, b)$  should be in  $MayIn_5$   
Holds along path 1-3-4
- $(a, b)$  should not be killed in node 4
- Possible if pointee set of  $c$  is  $\emptyset$
- However,  $MayIn_4$  contains  $(c, a)$



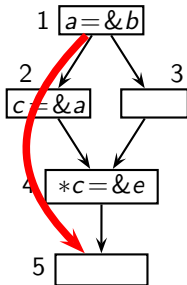
## MFP of Must Points-to Analysis



# May and Must Analysis for Killing Points-to Information (1)

## MFP of May Points-to Analysis

- $(a, b)$  should be in  $MayIn_5$   
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## MFP of Must Points-to Analysis

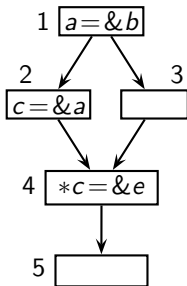
- $(a, b)$  should not be in  $MustIn_5$   
Does not hold along path 1-2-4
- $(a, b)$  should be killed in node 4
- Possible if pointee set of  $c$  is  $\{a\}$
- However, the pointee set of  $c$  is  $\emptyset$  in  $MustIn_4$



# May and Must Analysis for Killing Points-to Information (1)

## MFP of May Points-to Analysis

- $(a, b)$  should be in  $MayIn_5$   
Holds along path 1-3-4
- $(a, b)$  should not be killed in node 4
- Possible if pointee set of  $c$  is  $\emptyset$  (Use  $MustIn_4$ )
- However,  $MayIn_4$  contains  $(c, a)$  (Use  $MustIn_4$ )



## MFP of Must Points-to Analysis

- $(a, b)$  should not be in  $MustIn_5$   
Does not hold along path 1-2-4
- $(a, b)$  should be killed in node 4
- Possible if pointee set of  $c$  is  $\{a\}$  (Use  $MayIn_4$ )
- However, the pointee set of  $c$  is  $\emptyset$  in  $MustIn_4$  (Use  $MayIn_4$ )

For killing points-to information through indirection,

- **Must** points-to analysis should identify pointees of  $c$  using  $MayIn_4$
- **May** points-to analysis should identify pointees of  $c$  using  $MustIn_4$



## May and Must Analysis for Killing Points-to Information (2)

- May Points-to analysis should remove a May points-to pair
  - only if it must be removed along all paths

Kill should remove **ONLY strong updates**

⇒ should use Must Points-to information

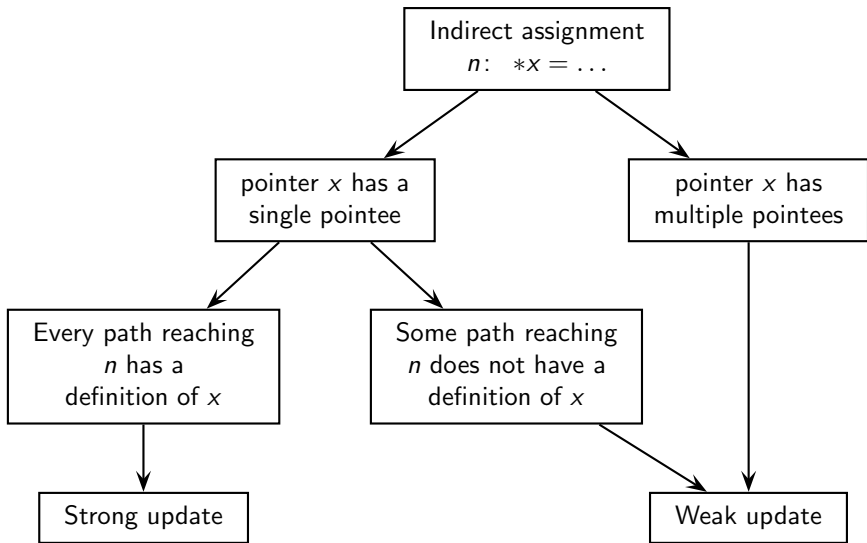
- Must Points-to analysis should remove a Must points-to pair
  - if it can be removed along any path

Kill should remove **ALL weak updates**

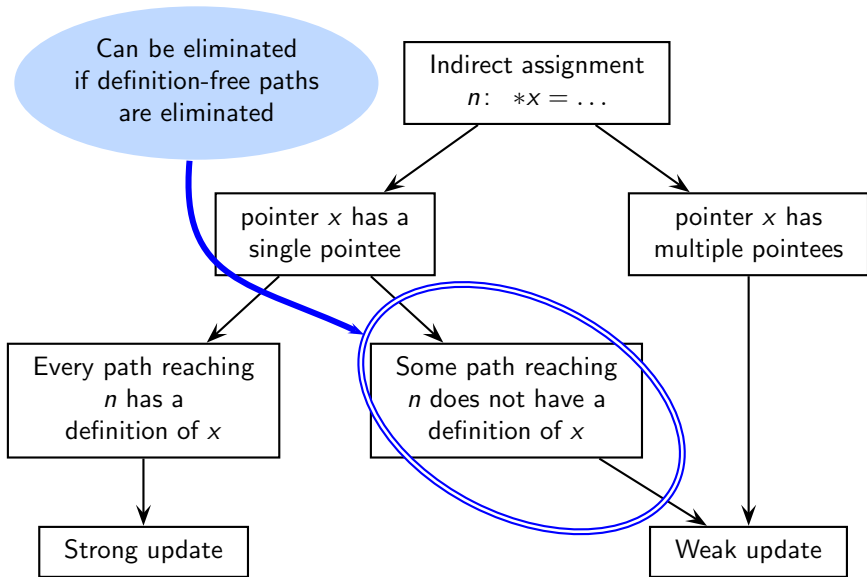
⇒ should use May Points-to information



# Distinguishing Between Strong and Weak Updates

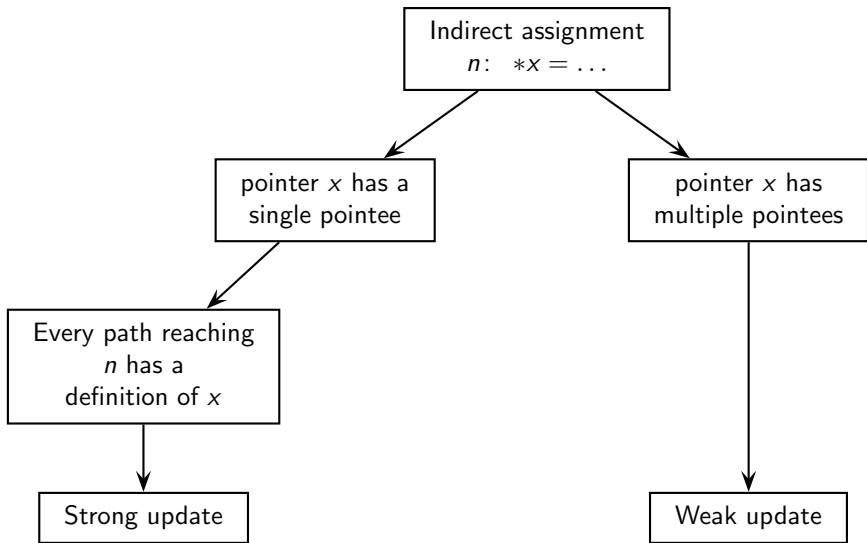


## Distinguishing Between Strong and Weak Updates

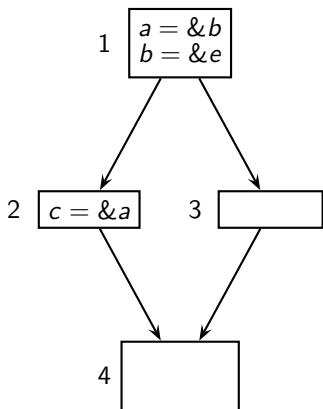




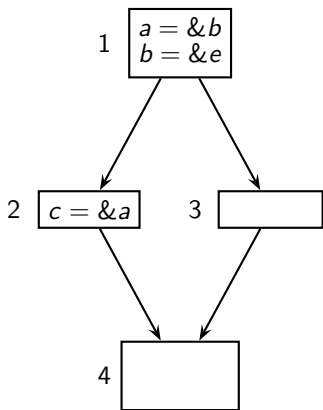
# Distinguishing Between Strong and Weak Updates



# Discovering Must Points-to Information from May Points-to Information



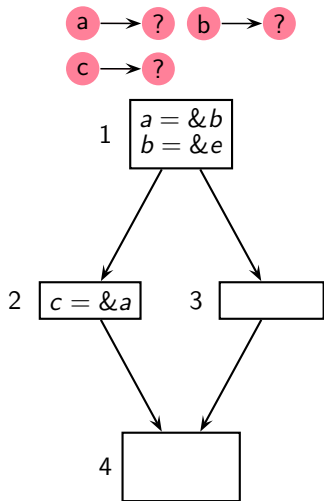
# Discovering Must Points-to Information from May Points-to Information



- *Bl.* every pointer points to “?”  
Assume that  $e$  is a scalar



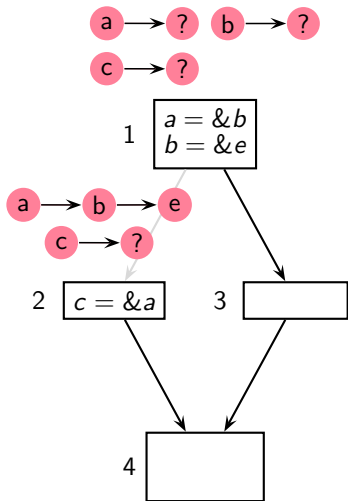
# Discovering Must Points-to Information from May Points-to Information



- *Bl.* every pointer points to "?"  
Assume that  $e$  is a scalar



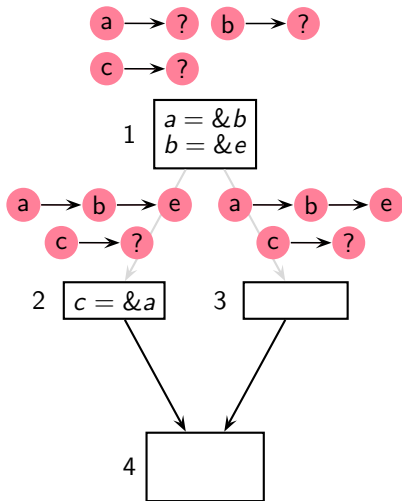
# Discovering Must Points-to Information from May Points-to Information



- *Bl.* every pointer points to “?”  
Assume that `e` is a scalar
- Perform usual may points-to analysis



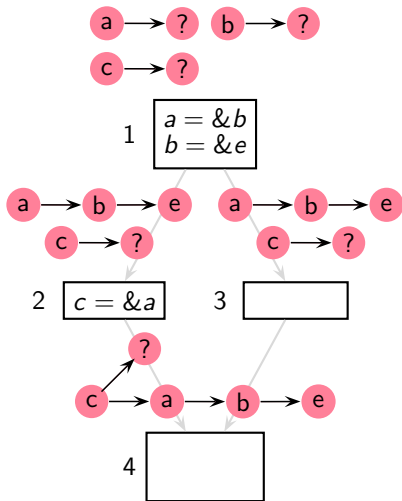
# Discovering Must Points-to Information from May Points-to Information



- *Bl.* every pointer points to “?”  
Assume that *e* is a scalar
- Perform usual may points-to analysis



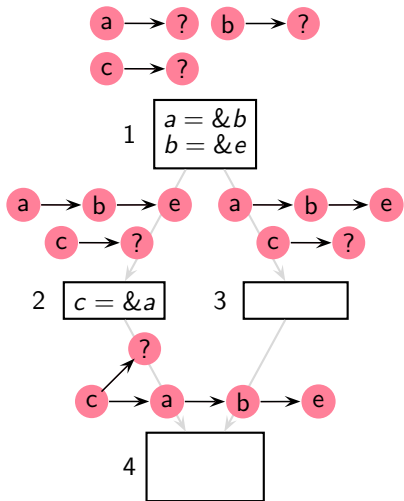
# Discovering Must Points-to Information from May Points-to Information



- *Bl.* every pointer points to "?"  
Assume that  $e$  is a scalar
- Perform usual may points-to analysis



# Discovering Must Points-to Information from May Points-to Information

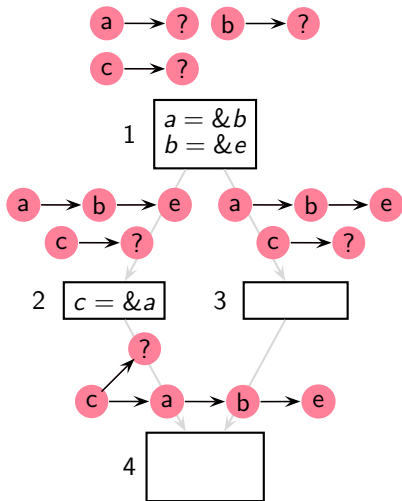


- *Bl.* every pointer points to "?"  
Assume that  $e$  is a scalar
- Perform usual may points-to analysis
- Since  $c$  has multiple pointees, it is a MAY relation





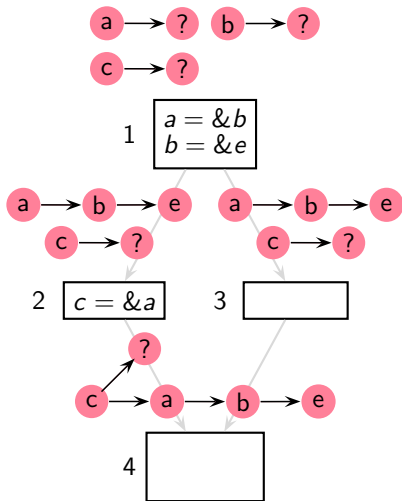
# Discovering Must Points-to Information from May Points-to Information



- *Bl.* every pointer points to "?"  
Assume that  $e$  is a scalar
- Perform usual may points-to analysis
- Since  $c$  has multiple pointees, it is a MAY relation
- Since  $a$  has a single pointee, it is a MUST relation



## Discovering Must Points-to Information from May Points-to Information



The use of “?” to derive Must is valid under the following conditions

If there is a definition free path from *Start* to node  $i$  for pointer  $x$ , then  $(x, ?)$  must reach  $In_i$  during the very first visit to node  $i$  in the analysis.

Conversely, if there is no definition free path from *Start* to node  $i$  for pointer  $x$ , then  $(x, ?)$  must *not* reach  $In_i$  during the very first visit to node  $i$  in the analysis.



## Relevant Algebraic Operations on Relations (1)

- Let  $\mathbf{P} \subseteq V$  be the set of pointer variables
- May-points-to information:  $\mathcal{A} = \langle 2^{\mathbf{P} \times V}, \supseteq \rangle$
- Standard algebraic operations on points-to relations  
Given relation  $R \subseteq \mathbf{P} \times V$  and  $X \subseteq \mathbf{P}$ ,
  - Relation *application*  $R X = \{v \mid u \in X \wedge (u, v) \in R\}$
  - Relation *restriction*  $(R|_X) R|_X = \{(u, v) \in R \mid u \in X\}$



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(Find out the pointees of the pointers contained in  $X$ )
- Relation *restriction*  $(R|_X)$   $R|_X = \{(u, v) \in R \mid u \in X\}$   
(Restrict the relation only to the pointers contained in  $X$  by removing points-to information of other pointers)



## Relevant Algebraic Operations on Relations (2)

Let

$$V = \{a, b, c, d, e, f, g, ?\}$$

$$P = \{a, b, c, d, e\}$$

$$R = \{(a, b), (a, c), (b, d), (c, e), (c, g), (d, a), (e, ?)\}$$

$$X = \{a, c\}$$

Then,

$$R X = \{v \mid u \in X \wedge (u, v) \in R\}$$

$$R|_X = \{(u, v) \in R \mid u \in X\}$$



## Relevant Algebraic Operations on Relations (2)

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Then,

$$R X = \{v \mid u \in X \wedge (u, v) \in R\}$$

$$= \{b, c, e, g\}$$

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## Relevant Algebraic Operations on Relations (2)

Let

$$V = \{a, b, c, d, e, f, g, ?\}$$

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$$X = \{a, c\}$$

Then,

$$R X = \{v \mid u \in X \wedge (u, v) \in R\}$$

$$= \{b, c, e, g\}$$

$$R|_X = \{(u, v) \in R \mid u \in X\}$$

$$= \{(a, b), (a, c), (c, e), (c, g)\}$$





## Points-to Analysis Data Flow Equations

$$Pin_n = \begin{cases} V \times \{?\} & n \text{ is } Start_p \\ \bigcup_{p \in pred(n)} Pout_p & \text{otherwise} \end{cases}$$
$$Pout_n = \left( Pin_n - \left( Kill_n \times V \right) \right) \cup \left( Def_n \times Pointee_n \right)$$

- $Pin/Pout$ : sets of may points-to pairs
- $Kill_n$ ,  $Def_n$ , and  $Pointee_n$  are defined in terms of  $Pin_n$



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- *Pin/Pout*: sets of may points-to pairs
- *Kill<sub>n</sub>*, *Def<sub>n</sub>*, and *Pointee<sub>n</sub>* are defined in terms of *Pin<sub>n</sub>*

Pointers whose  
points-to relations should  
be removed for  
strong update



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Pointers that are defined (i.e. pointers in which addresses are stored)



## Points-to Analysis Data Flow Equations

Pointees (i.e. locations whose addresses are stored)

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- $Pin/Pout$ : sets of may points-to pairs
- $Kill_n$ ,  $Def_n$ , and  $Pointee_n$  are defined in terms of  $Pin_n$



## Extractor Functions for Points-to Analysis

Values defined in terms of  $Pin_n$  (denoted  $P$ )

	$Def_n$	$Kill_n$	$Pointee_n$
$use\ x$			
$x = \&a$			
$x = y$			
$x = *y$			
$*x = y$			
other			



## Extractor Functions for Points-to Analysis

Values defined in terms of  $Pin_n$  (denoted  $P$ )

	$Def_n$	$Kill_n$	$Pointee_n$
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Pointers that are defined (i.e. pointers in which addresses are stored)



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	$Def_n$	$Kill_n$	$Pointee_n$
$use\ x$			
$x = \&a$			
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$*x = y$			
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Pointers whose  
points-to relations should  
be removed for  
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## Extractor Functions for Points-to Analysis

Values defined in terms of  $Pin_n$  (denoted  $P$ )

	$Def_n$	$Kill_n$	$Pointee_n$
$use\ x$	$\emptyset$	$\emptyset$	$\emptyset$
$x = \&a$			
$x = y$			
$x = *y$			
$*x = y$			
other			



## Extractor Functions for Points-to Analysis

Values defined in terms of  $Pin_n$  (denoted  $P$ )

	$Def_n$	$Kill_n$	$Pointee_n$
$use\ x$	$\emptyset$	$\emptyset$	$\emptyset$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$			
$x = *y$			
$*x = y$			
other			



## Extractor Functions for Points-to Analysis

Values defined in terms of  $Pin_n$  (denoted  $P$ )

	$Def_n$	$Kill_n$	$Pointee_n$
$use\ x$	$\emptyset$	$\emptyset$	$\emptyset$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$P\{y\}$
$x = *y$			
$*x = y$			
other			

Pointees of  $y$  in  $Pin_n$  are the targets of defined pointers



## Extractor Functions for Points-to Analysis

Values defined in terms of  $Pin_n$  (denoted  $P$ )

	$Def_n$	$Kill_n$	$Pointee_n$
$use\ x$	$\emptyset$	$\emptyset$	$\emptyset$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$P\{y\}$
$x = *y$	$\{x\}$	$\{x\}$	$P(P\{y\} \cap \mathbf{P})$
$*x = y$			
other			

Pointees of those  
pointees of  $y$  in  $Pin_n$  which  
are pointers



## Extractor Functions for Points-to Analysis

Values defined in terms of  $Pin_n$  (denoted  $P$ )

	$Def_n$	$Kill_n$	$Pointee_n$
$use\ x$	$\emptyset$	$\emptyset$	$\emptyset$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$P\{y\}$
$x = *y$	$\{x\}$	$\{x\}$	$P(P\{y\} \cap \mathbf{P})$
$*x = y$	$P\{x\} \cap \mathbf{P}$	$Must(P)\{x\} \cap \mathbf{P}$	$P\{y\}$
other			

Pointees of  
 $x$  in  $Pin_n$  receive new  
addresses



## Extractor Functions for Points-to Analysis

Values defined in terms of  $P_{in}$

Strong update using  
must-points-to information  
computed from  $P_{in}$

	$Def_n$	$Kill_n$	
$use\ x$	$\emptyset$	$\emptyset$	$\emptyset$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$P\{y\}$
$x = *y$	$\{x\}$	$\{y\}$	$P(P\{y\} \cap \mathbf{P})$
$*x = y$	$P\{x\} \cap \mathbf{P}$	$Must(P)\{x\} \cap \mathbf{P}$	$P\{y\}$
other			

$$Must(R) = \bigcup_{z \in \mathbf{P}} \{z\} \times \begin{cases} \{w\} & R\{z\} = \{w\} \wedge w \neq ? \\ \emptyset & \text{otherwise} \end{cases}$$



## Extractor Functions for Points-to Analysis

Values defined in terms of  $P_{in}$

Strong update using  
must-points-to information  
computed from  $P_{in}$

	$Def_n$	$Kill_n$	
$use\ x$	$\emptyset$	$\emptyset$	$\emptyset$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$P\{y\}$
$x = *y$	$\{x\}$	$\{y\}$	$P(P\{y\} \cap \mathbf{P})$
$*x = y$	$P\{x\} \cap \mathbf{P}$	$Must(P)\{x\} \cap \mathbf{P}$	$P\{y\}$
other			

$$Must(R) = \left( \bigcup_{z \in \mathbf{P}} \{z\} \right) \times \begin{cases} \{w\} & R\{z\} = \{w\} \wedge w \neq ? \\ \emptyset & \text{otherwise} \end{cases}$$

Find out  
must-pointees of  
all pointers





## Extractor Functions for Points-to Analysis

Values defined in terms of  $P_{in}$

Strong update using  
must-points-to information  
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	$Def_n$	$Kill_n$	
$use\ x$	$\emptyset$	$\emptyset$	$\emptyset$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$P\{y\}$
$x = *y$	$\{x\}$	$\{y\}$	$P(P\{y\} \cap \mathbf{P})$
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other			

$$Must(R) = \bigcup_{z \in \mathbf{P}} \{z\} \times \begin{cases} \{w\} & R\{z\} = \{w\} \wedge w \neq ? \\ \emptyset & \text{otherwise} \end{cases}$$

$z$  has a single pointee  
 $w$  in must-points-to  
relation



## Extractor Functions for Points-to Analysis

Values defined in terms of  $P_{in}$

Strong update using  
must-points-to information  
computed from  $P_{in}$

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$use\ x$	$\emptyset$	$\emptyset$	$\emptyset$
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$x = *y$	$\{x\}$	$\{y\}$	$P(P\{y\} \cap \mathbf{P})$
$*x = y$	$P\{x\} \cap \mathbf{P}$	$Must(P)\{x\} \cap \mathbf{P}$	$P\{y\}$
other			

$$Must(R) = \bigcup_{z \in \mathbf{P}} \{z\} \times \begin{cases} \{w\} & R\{z\} = \{w\} \wedge w \neq ? \\ \emptyset & \text{otherwise} \end{cases}$$

$z$  has no pointee  
in must-points-to  
relation



## Extractor Functions for Points-to Analysis

Values defined in terms of  $Pin_n$  (denoted  $P$ )

	$Def_n$	$Kill_n$	$Pointee_n$
$use\ x$	$\emptyset$	$\emptyset$	$\emptyset$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$P\{y\}$
$x = *y$	$\{x\}$	$\{x\}$	$P(P\{y\} \cap \mathbf{P})$
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# Extractor Functions for Points-to Analysis

Values defined in terms of  $Pin_n$  (denoted  $P$ )

	$Def_n$	$Kill_n$	$Pointee_n$
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$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$P\{y\}$
$x = *y$	$\{x\}$	$\{x\}$	$P(P\{y\} \cap \mathbf{P})$
$*x = y$	$P\{x\} \cap \mathbf{P}$	$Must(P)\{x\} \cap \mathbf{P}$	$P\{y\}$
other			

$$Must(R) = \bigcup_{z \in \mathbf{P}} \{z\} \times \begin{cases} \{w\} \\ \emptyset \end{cases} \quad \begin{array}{l} R\{z\} = \{w\} \wedge w \neq ? \\ \text{otherwise} \end{array}$$

Pointees of  $y$  in  $Pin_n$  are the targets of defined pointers



## Extractor Functions for Points-to Analysis

Values defined in terms of  $Pin_n$  (denoted  $P$ )

	$Def_n$	$Kill_n$	$Pointee_n$
$use\ x$	$\emptyset$	$\emptyset$	$\emptyset$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$P\{y\}$
$x = *y$	$\{x\}$	$\{x\}$	$P(P\{y\} \cap \mathbf{P})$
$*x = y$	$P\{x\} \cap \mathbf{P}$	$Must(P)\{x\} \cap \mathbf{P}$	$P\{y\}$
other	$\emptyset$	$\emptyset$	$\emptyset$

$$Must(R) = \bigcup_{z \in \mathbf{P}} \{z\} \times \begin{cases} \{w\} & R\{z\} = \{w\} \wedge w \neq ? \\ \emptyset & \text{otherwise} \end{cases}$$



## Extractor Functions for Points-to Analysis

Values defined in terms of  $Pin_n$  (denoted  $P$ )

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## Extractor Functions for Points-to Analysis

Values defined in terms of  $Pin_n$  (denoted  $P$ )

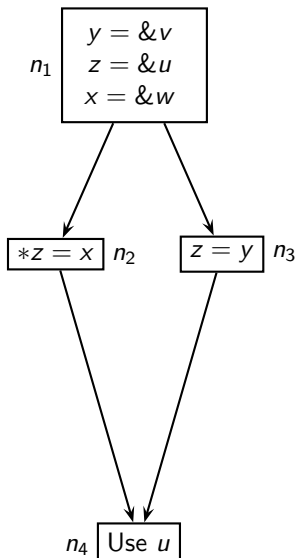
	$Def_n$	$Kill_n$	$Pointee_n$
$use\ x$	$\emptyset$	$\emptyset$	$\emptyset$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$P\{y\}$
$x = *y$	$\{x\}$	$\{x\}$	$P(P\{y\} \cap \mathbf{P})$
$*x = y$	$P\{x\} \cap \mathbf{P}$	$Must(P)\{x\} \cap \mathbf{P}$	$P\{y\}$
other	$\emptyset$	$\emptyset$	$\emptyset$

$$Must(R) = \bigcup_{z \in \mathbf{P}} \{z\} \times \begin{cases} \{w\} & R\{z\} = \{w\} \wedge w \neq ? \\ \emptyset & \text{otherwise} \end{cases}$$



## An Example of Flow-Sensitive May Points-to Analysis

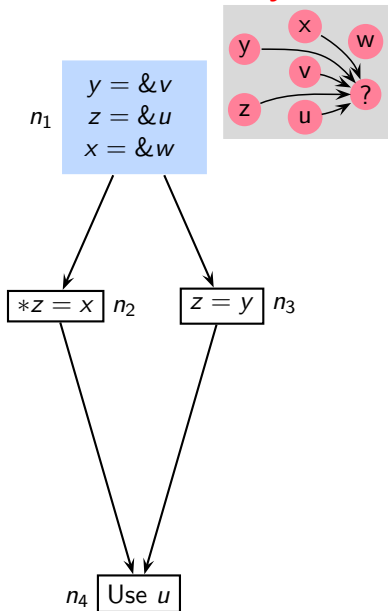
```
int w;  
int *u, *v, *x;  
int **y, **z;
```





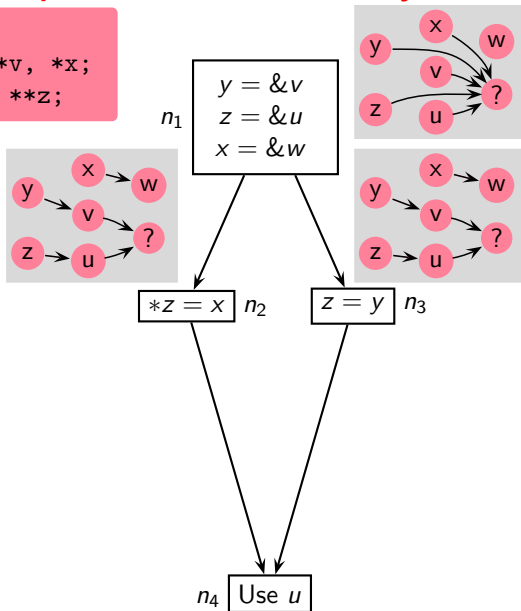
## An Example of Flow-Sensitive May Points-to Analysis

```
int w;
int *u, *v, *x;
int **y, **z;
```



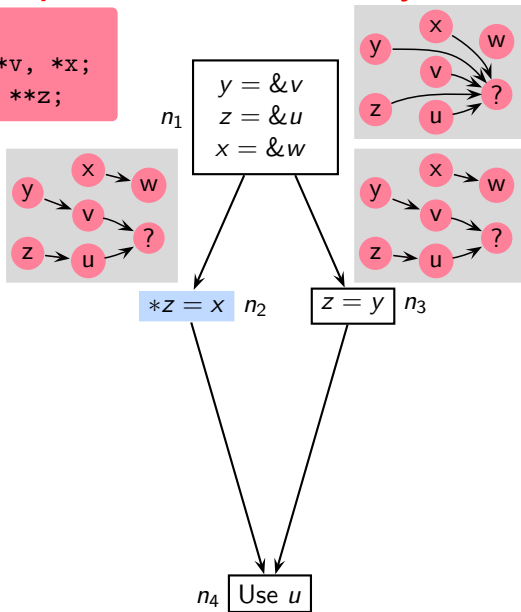
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int w;
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int **y, **z;
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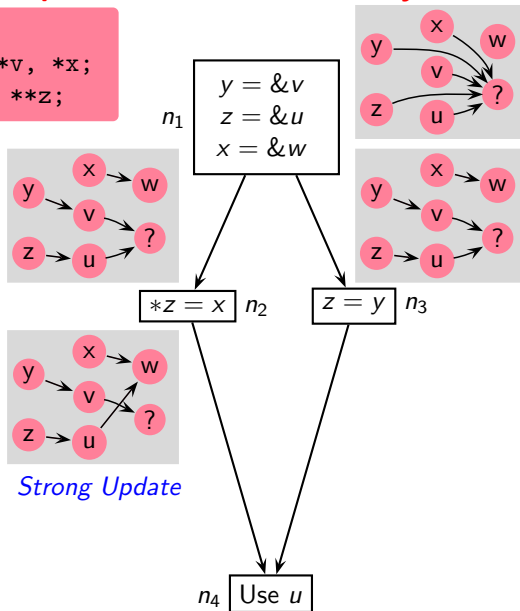
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int w;
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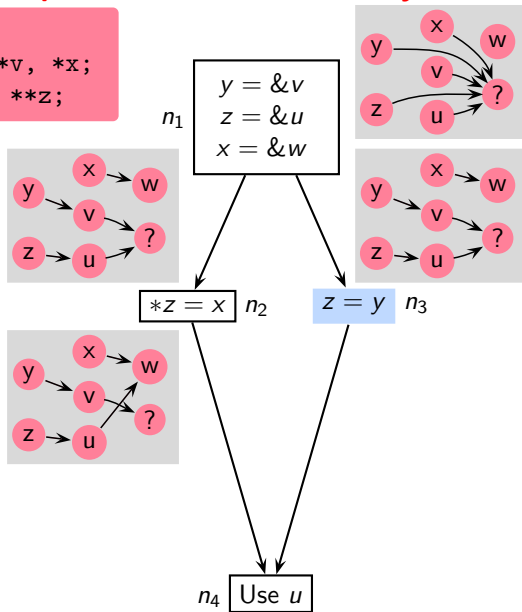
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int **y, **z;
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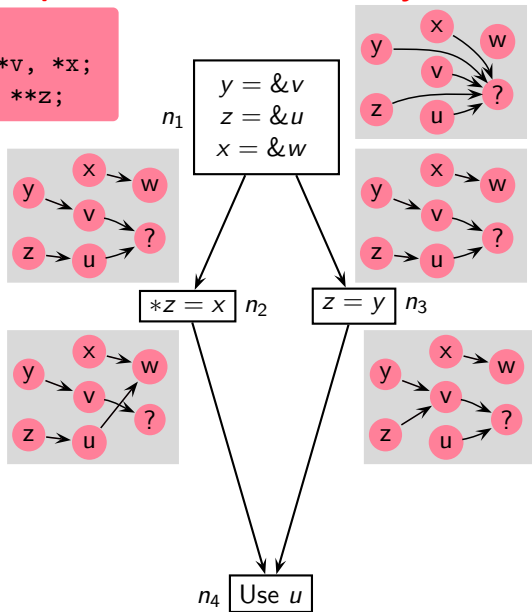
## An Example of Flow-Sensitive May Points-to Analysis

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int w;
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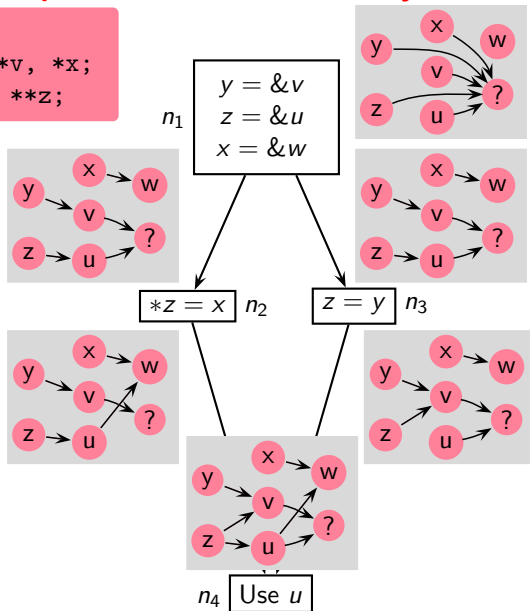
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int *u, *v, *x;
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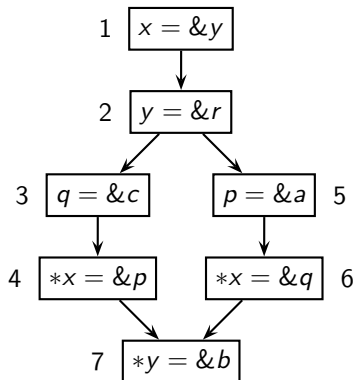
# An Example of Flow-Sensitive May Points-to Analysis

```
int w;
int *u, *v, *x;
int **y, **z;
```



# Tutorial Problem for Flow-Sensitive Pointer Analysis

```
int a, b, c, *p, *q, *r;  
int **y, ***x;
```





## Solution of Tutorial Problem

	$P_{in_n}$	$P_{out_n}$
1	$\{(p, ?), (q, ?), (r, ?), (x, ?), (y, ?)\}$	$\{(p, ?), (q, ?), (r, ?), (x, y), (y, ?)\}$
2	$\{(p, ?), (q, ?), (r, ?), (x, y), (y, ?)\}$	$\{(p, ?), (q, ?), (r, ?), (x, y), (y, r)\}$
3	$\{(p, ?), (q, ?), (r, ?), (x, y), (y, r)\}$	$\{(p, ?), (q, c), (r, ?), (x, y), (y, r)\}$
4	$\{(p, ?), (q, c), (r, ?), (x, y), (y, r)\}$	$\{(p, ?), (q, c), (r, ?), (x, y), (y, p)\}$
5	$\{(p, ?), (q, ?), (r, ?), (x, y), (y, r)\}$	$\{(p, a), (q, ?), (r, ?), (x, y), (y, r)\}$
6	$\{(p, a), (q, ?), (r, ?), (x, y), (y, r)\}$	$\{(p, a), (q, ?), (r, ?), (x, y), (y, q)\}$
7	$\{(p, ?), (p, a), (q, ?), (q, c),$ $(r, ?), (x, y), (y, p)(y, q)\}$	$\{(p, ?), (p, a), (p, b), (q, ?), (q, c), (q, b),$ $(r, ?), (x, y), (y, p)(y, q)\}$



# Extractor Functions in the Presence of Structures (1)

- We extend pointer to use field names as follows:
  - pointer  $x$  is represented by  $(x, *)$ , and
  - pointer field  $f$  of structure variable  $x$  is represented by  $(x, f)$
  - points-to information is of the form  $((x, f) y)$
- For simplicity, we
  - separate LHS and RHS assuming that
  - only legal, type-correct pointer expressions are used in a statement
- From LHS, we extract *Def* and *Kill* as the sets of  $(x, *)$  or  $(a, f)$   
( $x$  is a pointer variable and  $a$  is a structure variable)
- From RHS, we extract *Pointee* as the sets of variables  $x$



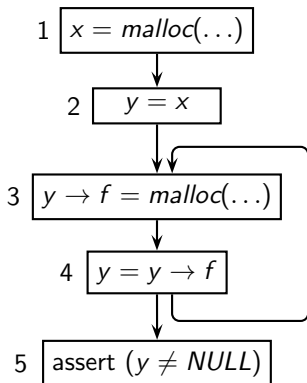
## What About Heap Data?

- Compile time entities, abstract entities, or summarized entities
- Three options:
  - Represent all heap locations by a single abstract heap location
  - Represent all heap locations of a particular type by a single abstract heap location
  - Represent all heap locations allocated at a given memory allocation site by a single abstract heap location
- Summarization of pointer expression: Usually based on the length of pointer expression



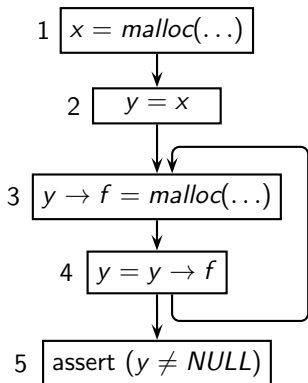
# Allocation Site Based Abstraction of Points-to Graph

Program

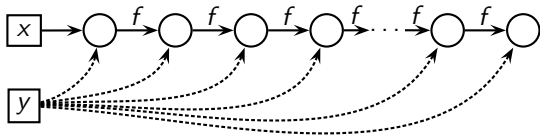


# Allocation Site Based Abstraction of Points-to Graph

Program

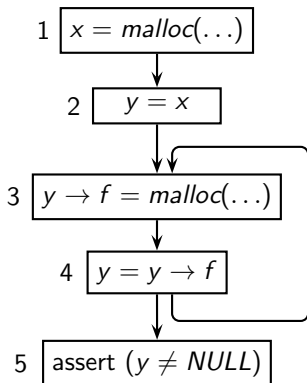


Memory graph representing multiple executions

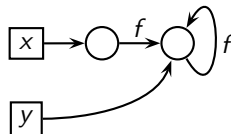
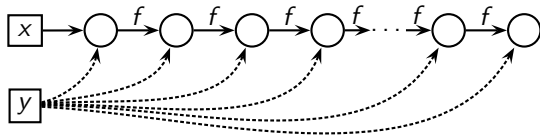


# Allocation Site Based Abstraction of Points-to Graph

Program



Memory graph representing multiple executions

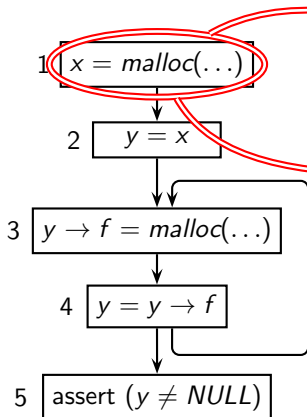


Allocation-site based  
points-to graph

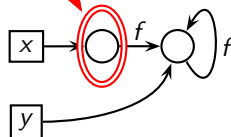
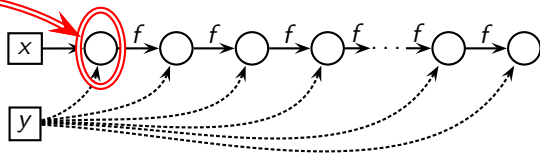


# Allocation Site Based Abstraction of Points-to Graph

Program



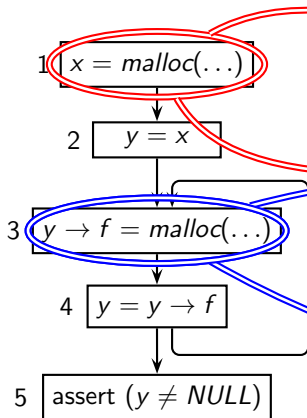
Memory graph representing multiple executions



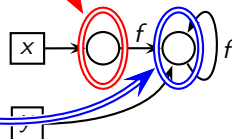
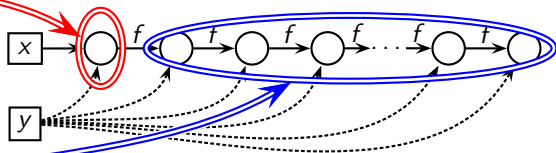
Allocation-site based  
points-to graph

# Allocation Site Based Abstraction of Points-to Graph

Program



Memory graph representing multiple executions



Allocation-site based  
points-to graph





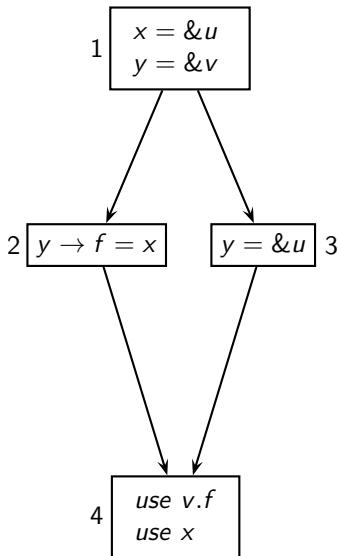
## Extractor Functions in the Presence of Structures (2)

LHS	$Def_n$	$Kill_n$
$x$	$\{(x, *)\}$	$\{(x, *)\}$
$*x$	$\{(z, *) \mid z \in A\{(x, *)\}\}$	$\{(z, *) \mid z \in Must(A)\{(x, *)\}\}$
$x \rightarrow f$	$\{(z, f) \mid z \in A\{(x, *)\}\}$	$\{(z, f) \mid z \in Must(A)\{(x, *)\}\}$
$x.f$	$\{(x, f)\}$	$\{(x, f)\}$

RHS	$Pointee_n$
$\&y$	$\{y\}$
$y$	$\{z \mid z \in A\{(y, *)\}\}$
$*y$	$\{z \mid z \in A\{(w, *)\}, w \in A\{(y, *)\}\}$
$y \rightarrow f$	$\{z \mid z \in A\{(w, f)\}, w \in A\{(y, *)\}\}$
$y.f$	$\{z \mid z \in A\{(y, f)\}\}$



# An Example of Flow-Sensitive May Points-to Analysis



## Type Information

```

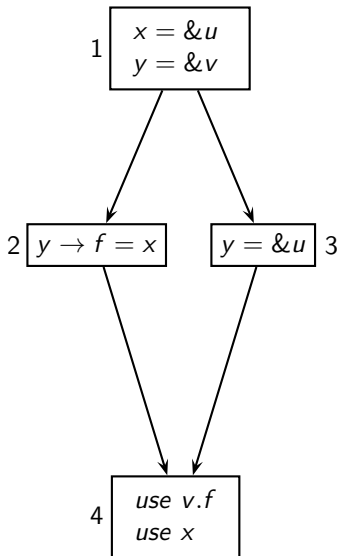
struct s {
    struct s *f;
    int n;
} *x, *y, u, v;
  
```

## Andersen's Points-to Graph

## Steensgaard's Points-to Graph



# An Example of Flow-Sensitive May Points-to Analysis

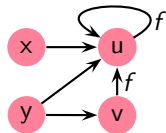


## Type Information

```

struct s {
    struct s *f;
    int n;
} *x, *y, u, v;
  
```

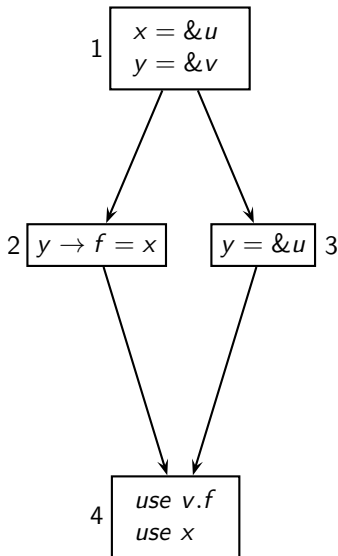
## Andersen's Points-to Graph



## Steensgaard's Points-to Graph



# An Example of Flow-Sensitive May Points-to Analysis

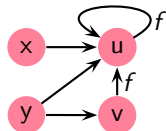


## Type Information

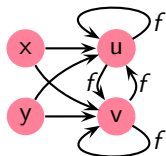
```

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```

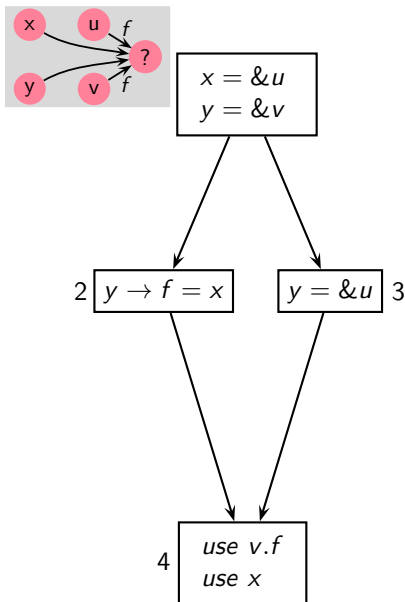
## Andersen's Points-to Graph



## Steensgaard's Points-to Graph



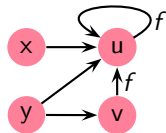
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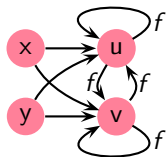
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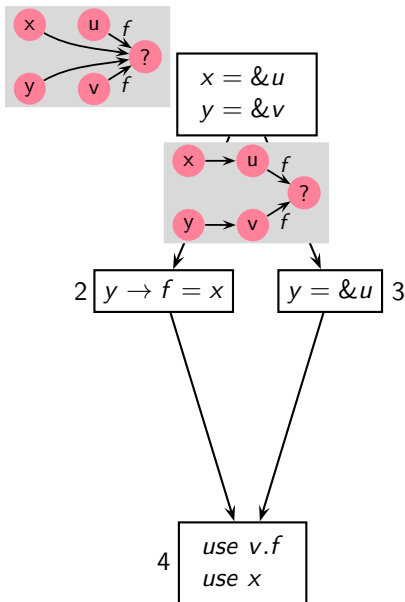
## Andersen's Points-to Graph



## Steensgaard's Points-to Graph



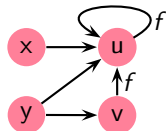
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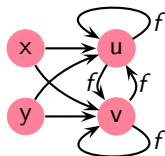
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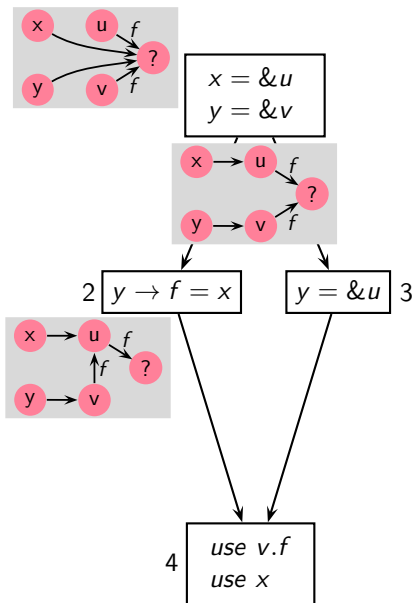
## Andersen's Points-to Graph



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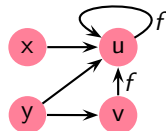
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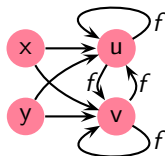
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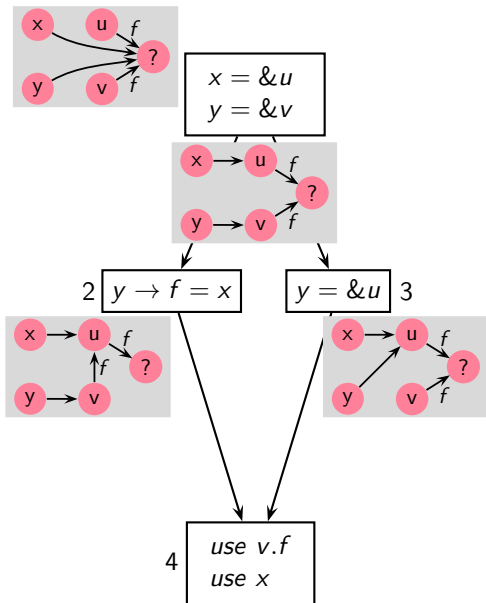
## Andersen's Points-to Graph



## Steensgaard's Points-to Graph



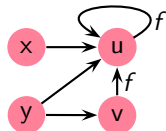
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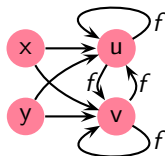
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## Andersen's Points-to Graph

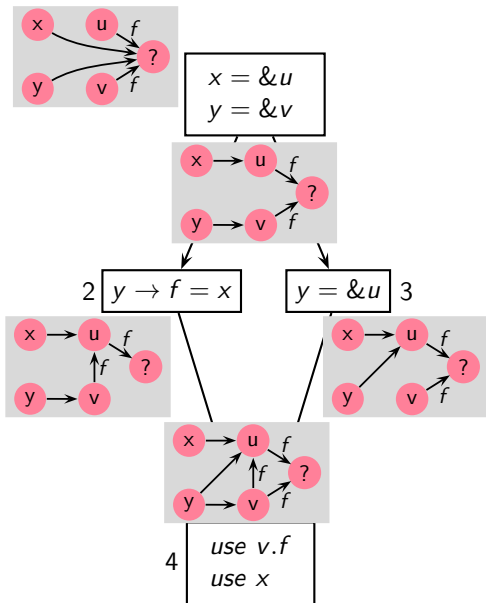


## Steensgaard's Points-to Graph





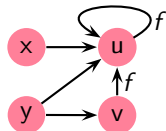
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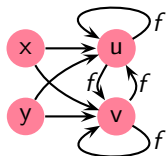
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## Andersen's Points-to Graph

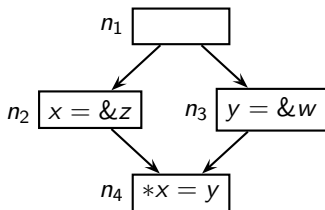


## Steensgaard's Points-to Graph

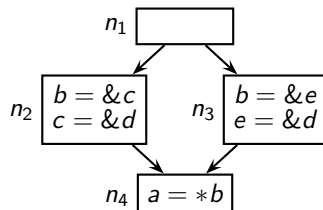


# Non-Distributivity of Points-to Analysis

May Points-to

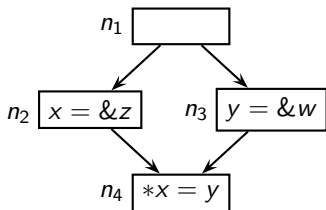


Must Points-to



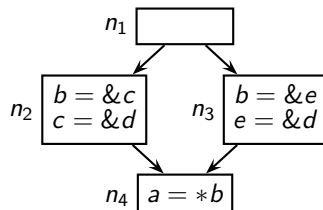
# Non-Distributivity of Points-to Analysis

May Points-to



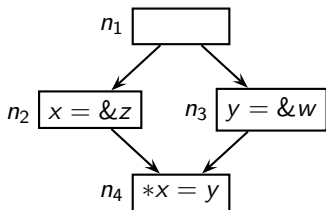
$z \mapsto w$  is spurious

Must Points-to



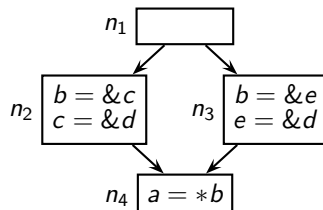
## Non-Distributivity of Points-to Analysis

May Points-to



$z \rightarrow w$  is spurious

Must Points-to



$a \rightarrow d$  is missing

