

Bit Vector Data Flow Frameworks

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Part 1

About These Slides

CS 618

Bit Vector Frameworks: About These Slides

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These slides constitute the lecture notes for CS618 Program Analysis course at IIT Bombay and have been made available as teaching material accompanying the book:

- Uday Khedker, Amitabha Sanyal, and Bageshri Karkare. *Data Flow Analysis: Theory and Practice*. CRC Press (Taylor and Francis Group). 2009.
(Indian edition published by Ane Books in 2013)

Apart from the above book, some slides are based on the material from the following books

- M. S. Hecht. *Flow Analysis of Computer Programs*. Elsevier North-Holland Inc. 1977.
- F. Nielson, H. R. Nielson, and C. Hankin. *Principles of Program Analysis*. Springer-Verlag. 1998.

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Bit Vector Frameworks: Outline

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Outline

- Live Variables Analysis
- Observations about Data Flow Analysis
- Available Expressions Analysis
- Anticipable Expressions Analysis
- Reaching Definitions Analysis
- Common Features of Bit Vector Frameworks
- Partial Redundancy Elimination

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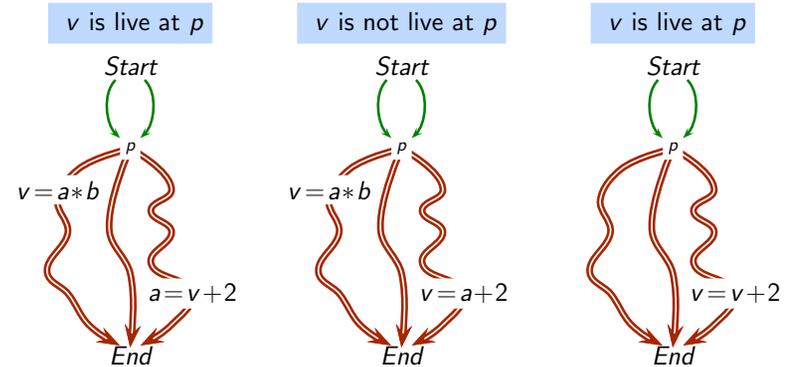
Part 2

Live Variables Analysis

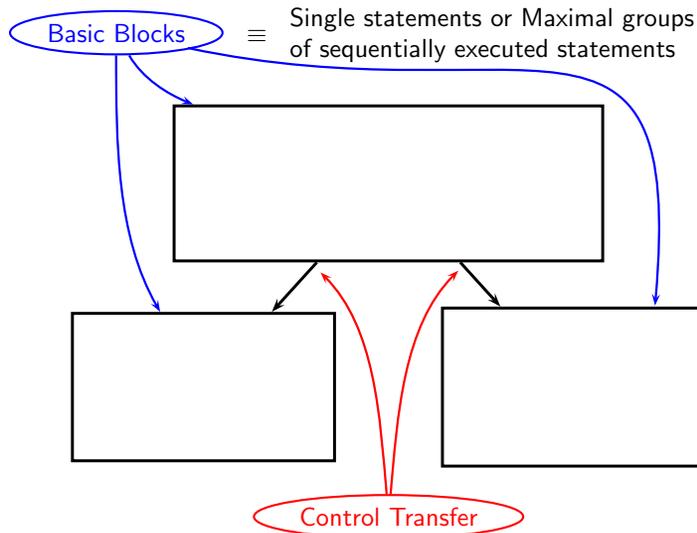
Defining Live Variables Analysis

A variable v is live at a program point p , if **some** path **from p to program exit** contains an r-value occurrence of v which is not preceded by an l-value occurrence of v .

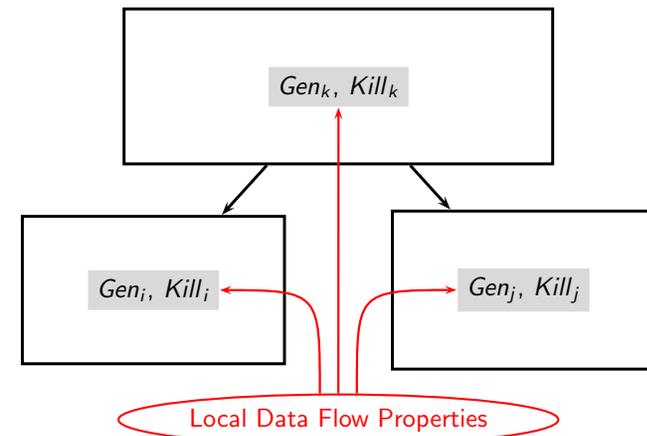
Path based specification



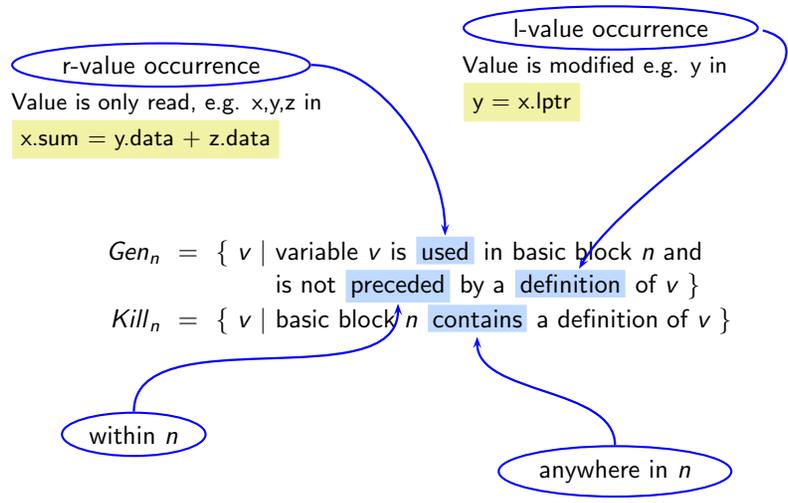
Defining Data Flow Analysis for Live Variables Analysis



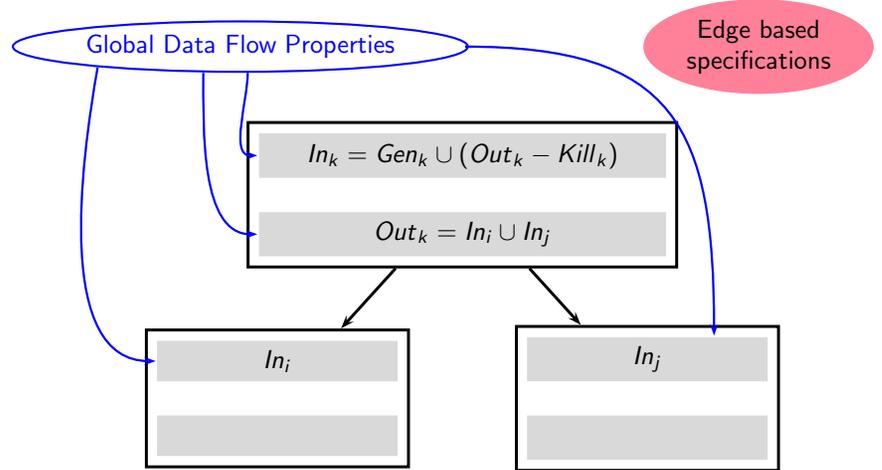
Defining Data Flow Analysis for Live Variables Analysis



Local Data Flow Properties for Live Variables Analysis



Defining Data Flow Analysis for Live Variables Analysis



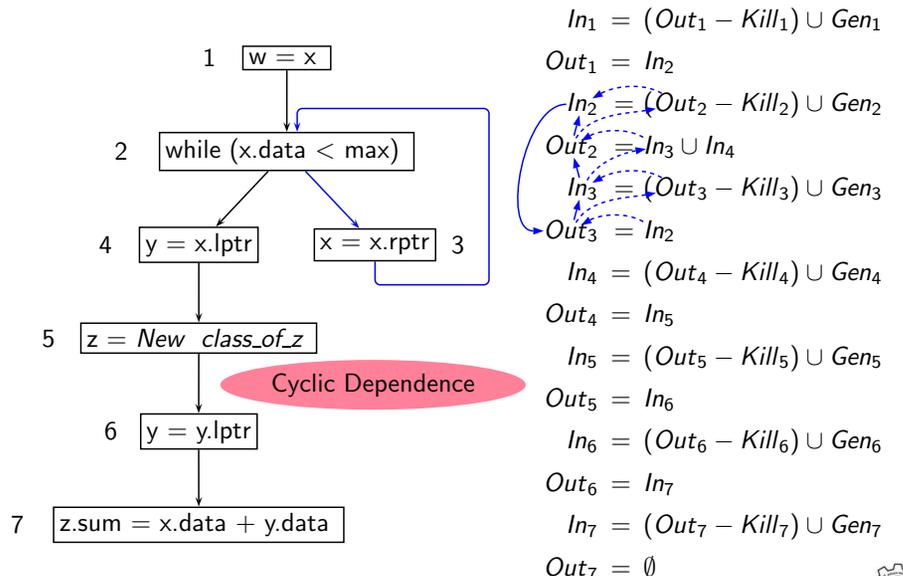
Data Flow Equations For Live Variables Analysis

$$In_n = (Out_n - Kill_n) \cup Gen_n$$

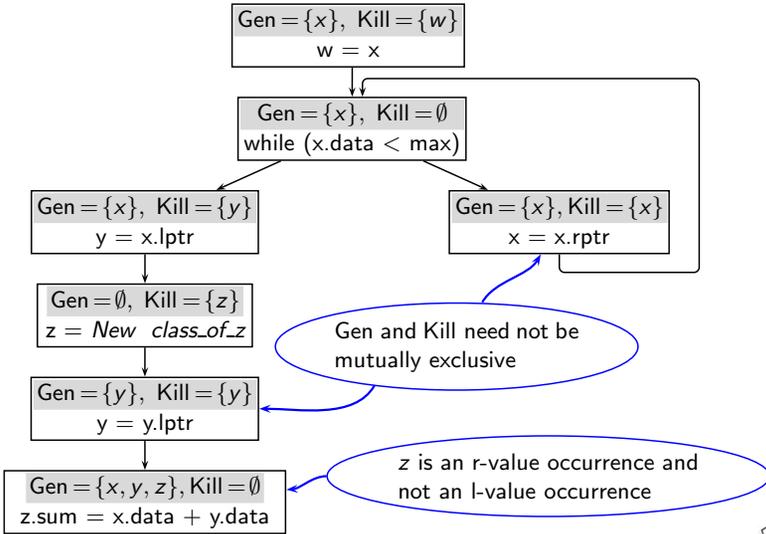
$$Out_n = \begin{cases} BI & n \text{ is End block} \\ \bigcup_{s \in succ(n)} In_s & \text{otherwise} \end{cases}$$

- In_n and Out_n are sets of variables
- BI is boundary information representing the effect of calling contexts
 - \emptyset for local variables except for the values being returned
 - set of global variables used further in any calling context (can be safely approximated by the set of all global variables)

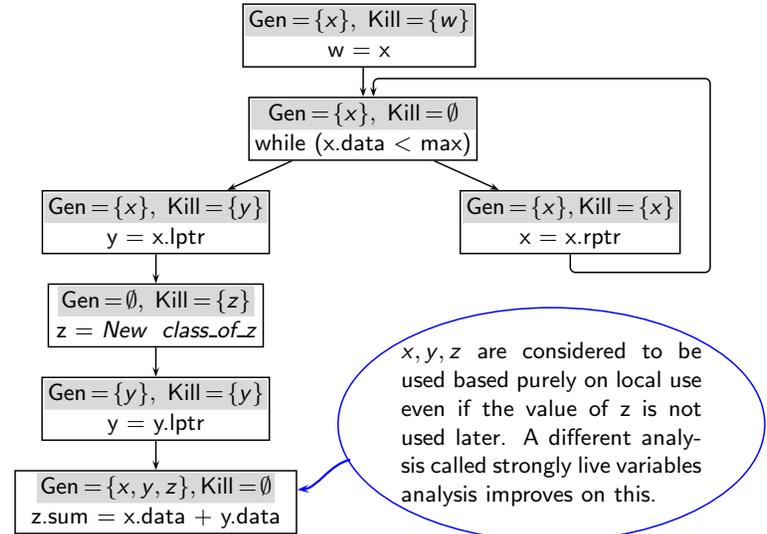
Data Flow Equations for Our Example



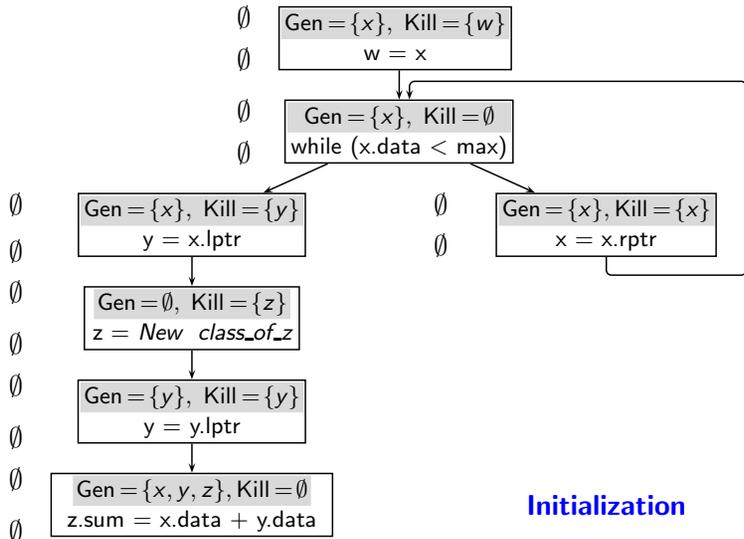
Performing Live Variables Analysis



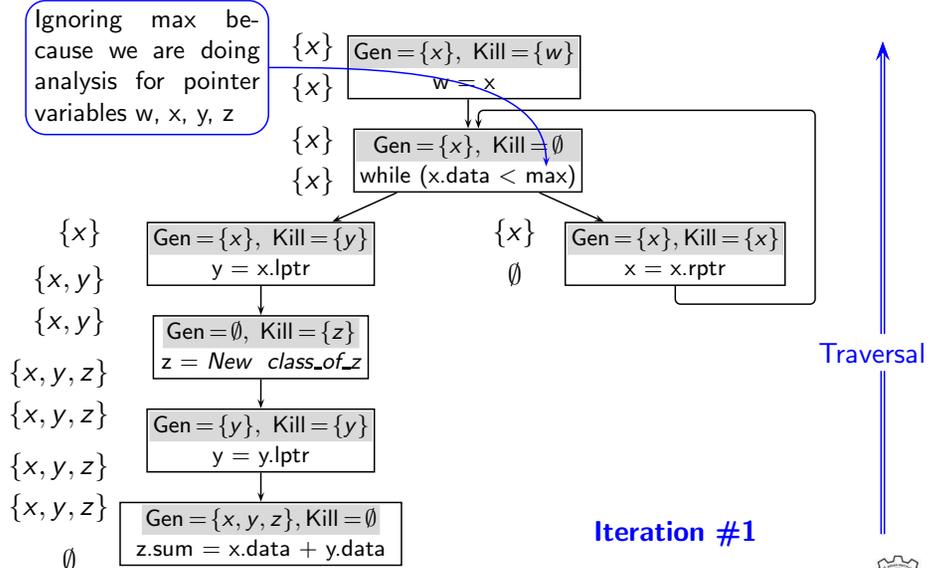
Performing Live Variables Analysis



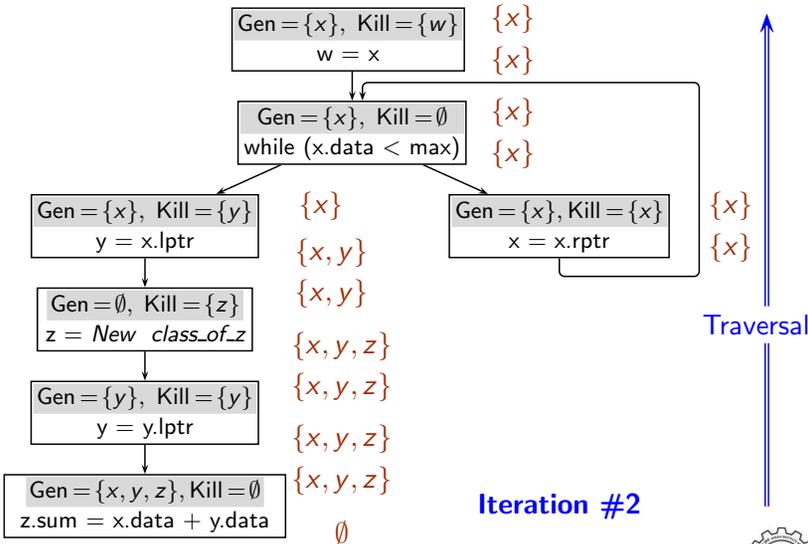
Performing Live Variables Analysis



Performing Live Variables Analysis

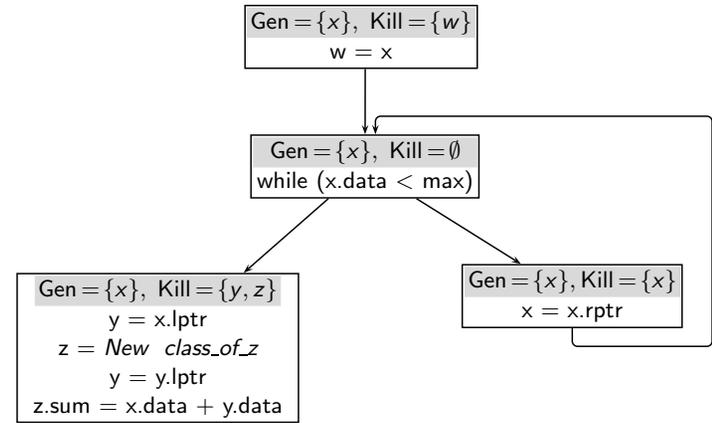


Performing Live Variables Analysis



Performing Live Variables Analysis

Local data flow properties when basic blocks contain multiple statements



Local Data Flow Properties for Live Variables Analysis

$$In_n = Gen_n \cup (Out_n - Kill_n)$$

- Gen_n : Use not preceded by definition

Upwards exposed use

- $Kill_n$: Definition anywhere in a block

Stop the effect from being propagated across a block

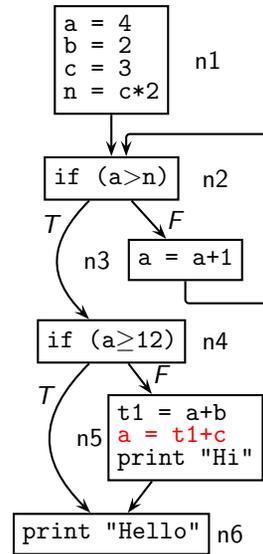
Local Data Flow Properties for Live Variables Analysis

| Case | Local Information | Example | Explanation | |
|------|-------------------|-------------------|----------------------------|---|
| 1 | $v \notin Gen_n$ | $v \notin Kill_n$ | $a = b + c$ $b = c * d$ | liveness of v is unaffected by the basic block |
| 2 | $v \in Gen_n$ | $v \notin Kill_n$ | $a = b + c$ $b = v * d$ | v becomes live before the basic block |
| 3 | $v \notin Gen_n$ | $v \in Kill_n$ | $a = b + c$ $v = c * d$ | v ceases to be live before the basic block |
| 4 | $v \in Gen_n$ | $v \in Kill_n$ | $a = v + c$ $v = c * d$ | liveness of v is killed but v becomes live before the basic block |

Using Data Flow Information of Live Variables Analysis

- Used for register allocation
If variable x is live in a basic block b , it is a potential candidate for register allocation
- Used for dead code elimination
If variable x is not live after an assignment $x = \dots$, then the assignment is redundant and can be deleted as dead code

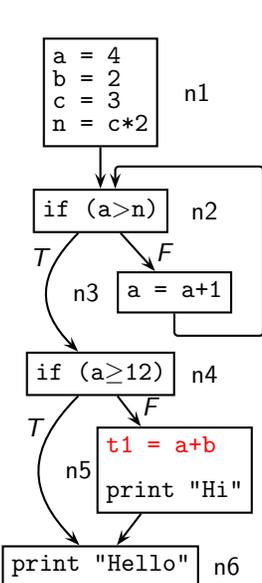
Tutorial Problem 1: Perform Dead Code Elimination



| Local Data Flow Information | | |
|-----------------------------|---------------|------------------|
| | Gen | Kill |
| n1 | \emptyset | $\{a, b, c, n\}$ |
| n2 | $\{a, n\}$ | \emptyset |
| n3 | $\{a\}$ | $\{a\}$ |
| n4 | $\{a\}$ | \emptyset |
| n5 | $\{a, b, c\}$ | $\{a, t1\}$ |
| n6 | \emptyset | \emptyset |

| Global Data Flow Information | | | | |
|------------------------------|------------------|------------------|------------------|------------------|
| | Iteration #1 | | Iteration #2 | |
| | Out | In | Out | In |
| n6 | \emptyset | \emptyset | \emptyset | \emptyset |
| n5 | \emptyset | $\{a, b, c\}$ | \emptyset | $\{a, b, c\}$ |
| n4 | $\{a, b, c\}$ | $\{a, b, c\}$ | $\{a, b, c\}$ | $\{a, b, c\}$ |
| n3 | \emptyset | $\{a\}$ | $\{a, b, c, n\}$ | $\{a, b, c, n\}$ |
| n2 | $\{a, b, c\}$ | $\{a, b, c, n\}$ | $\{a, b, c, n\}$ | $\{a, b, c, n\}$ |
| n1 | $\{a, b, c, n\}$ | \emptyset | $\{a, b, c, n\}$ | \emptyset |

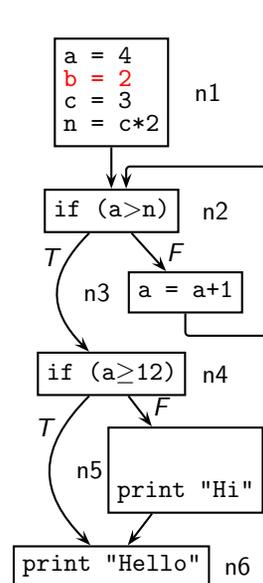
Tutorial Problem 1: Round #2 of Dead Code Elimination



| Local Data Flow Information | | |
|-----------------------------|-------------|------------------|
| | Gen | Kill |
| n1 | \emptyset | $\{a, b, c, n\}$ |
| n2 | $\{a, n\}$ | \emptyset |
| n3 | $\{a\}$ | $\{a\}$ |
| n4 | $\{a\}$ | \emptyset |
| n5 | $\{a, b\}$ | $\{t1\}$ |
| n6 | \emptyset | \emptyset |

| Global Data Flow Information | | | | |
|------------------------------|---------------|---------------|---------------|---------------|
| | Iteration #1 | | Iteration #2 | |
| | Out | In | Out | In |
| n6 | \emptyset | \emptyset | \emptyset | \emptyset |
| n5 | \emptyset | $\{a, b\}$ | \emptyset | $\{a, b\}$ |
| n4 | $\{a, b\}$ | $\{a, b\}$ | $\{a, b\}$ | $\{a, b\}$ |
| n3 | \emptyset | $\{a\}$ | $\{a, b, n\}$ | $\{a, b, n\}$ |
| n2 | $\{a, b\}$ | $\{a, b, n\}$ | $\{a, b, n\}$ | $\{a, b, n\}$ |
| n1 | $\{a, b, n\}$ | \emptyset | $\{a, b, n\}$ | \emptyset |

Tutorial Problem 1: Round #3 of Dead Code Elimination



| Local Data Flow Information | | |
|-----------------------------|-------------|------------------|
| | Gen | Kill |
| n1 | \emptyset | $\{a, b, c, n\}$ |
| n2 | $\{a, n\}$ | \emptyset |
| n3 | $\{a\}$ | $\{a\}$ |
| n4 | $\{a\}$ | \emptyset |
| n5 | \emptyset | \emptyset |
| n6 | \emptyset | \emptyset |

| Global Data Flow Information | | | | |
|------------------------------|--------------|-------------|--------------|-------------|
| | Iteration #1 | | Iteration #2 | |
| | Out | In | Out | In |
| n6 | \emptyset | \emptyset | \emptyset | \emptyset |
| n5 | \emptyset | \emptyset | \emptyset | \emptyset |
| n4 | \emptyset | $\{a\}$ | \emptyset | $\{a\}$ |
| n3 | \emptyset | $\{a\}$ | $\{a, n\}$ | $\{a, n\}$ |
| n2 | $\{a\}$ | $\{a, n\}$ | $\{a, n\}$ | $\{a, n\}$ |
| n1 | $\{a, n\}$ | \emptyset | $\{a, n\}$ | \emptyset |

Some Observations

What Does Data Flow Analysis Involve?

- **Defining the analysis.** Define the properties of execution paths
- **Formulating the analysis.** Define data flow equations
 - ▶ Linear simultaneous equations on sets rather than numbers
 - ▶ Later we will generalize the domain of values
- **Performing the analysis.** Solve data flow equations for the given program flow graph
- Many unanswered questions
Initial value? Termination? Complexity? Properties of Solutions?



A Digression: Iterative Solution of Linear Simultaneous Equations

- Simultaneous equations represented in the form of the product of a matrix of coefficients (**A**) with the vector of unknowns (**x**)

$$\mathbf{Ax} = \mathbf{b}$$

- Start with approximate values
- Compute new values repeatedly from old values
- Two classical methods
 - ▶ Gauss-Seidel Method (Gauss: 1823, 1826), (Seidel: 1874)
 - ▶ Jacobi Method (Jacobi: 1845)



A Digression: An Example of Iterative Solution of Linear Simultaneous Equations

| Equations | Solution |
|-------------------|----------------------|
| $4w = x + y + 32$ | $w = x = y = z = 16$ |
| $4x = y + z + 32$ | |
| $4y = z + w + 32$ | |
| $4z = w + x + 32$ | |

- Rewrite the equations to define $w, x, y,$ and z

$$w = 0.25x + 0.25y + 8$$

$$x = 0.25y + 0.25z + 8$$

$$y = 0.25z + 0.25w + 8$$

$$z = 0.25w + 0.25x + 8$$
- Assume some initial values of $w_0, x_0, y_0,$ and z_0
- Compute $w_i, x_i, y_i,$ and z_i within some margin of error



A Digression: Gauss-Seidel Method

| Equations | Initial Values | Error Margin |
|-------------------------|----------------|---------------------------|
| $w = 0.25x + 0.25y + 8$ | $w_0 = 24$ | $w_{i+1} - w_i \leq 0.35$ |
| $x = 0.25y + 0.25z + 8$ | $x_0 = 24$ | $x_{i+1} - x_i \leq 0.35$ |
| $y = 0.25z + 0.25w + 8$ | $y_0 = 24$ | $y_{i+1} - y_i \leq 0.35$ |
| $z = 0.25w + 0.25x + 8$ | $z_0 = 24$ | $z_{i+1} - z_i \leq 0.35$ |

| Iteration 1 | Iteration 2 | Iteration 3 |
|------------------------|------------------------|----------------------------|
| $w_1 = 6 + 6 + 8 = 20$ | $w_2 = 5 + 5 + 8 = 18$ | $w_3 = 4.5 + 4.5 + 8 = 17$ |
| $x_1 = 6 + 6 + 8 = 20$ | $x_2 = 5 + 5 + 8 = 18$ | $x_3 = 4.5 + 4.5 + 8 = 17$ |
| $y_1 = 6 + 6 + 8 = 20$ | $y_2 = 5 + 5 + 8 = 18$ | $y_3 = 4.5 + 4.5 + 8 = 17$ |
| $z_1 = 6 + 6 + 8 = 20$ | $z_2 = 5 + 5 + 8 = 18$ | $z_3 = 4.5 + 4.5 + 8 = 17$ |

| Iteration 4 | Iteration 5 |
|--------------------------------|-----------------------------------|
| $w_4 = 4.25 + 4.25 + 8 = 16.5$ | $w_5 = 4.125 + 4.125 + 8 = 16.25$ |
| $x_4 = 4.25 + 4.25 + 8 = 16.5$ | $x_5 = 4.125 + 4.125 + 8 = 16.25$ |
| $y_4 = 4.25 + 4.25 + 8 = 16.5$ | $y_5 = 4.125 + 4.125 + 8 = 16.25$ |
| $z_4 = 4.25 + 4.25 + 8 = 16.5$ | $z_5 = 4.125 + 4.125 + 8 = 16.25$ |



A Digression: Jacobi Method

Use values from the current iteration wherever possible

| Equations | Initial Values | Error Margin |
|-------------------------|----------------|---------------------------|
| $w = 0.25x + 0.25y + 8$ | $w_0 = 24$ | $w_{i+1} - w_i \leq 0.35$ |
| $x = 0.25y + 0.25z + 8$ | $x_0 = 24$ | $x_{i+1} - x_i \leq 0.35$ |
| $y = 0.25z + 0.25w + 8$ | $y_0 = 24$ | $y_{i+1} - y_i \leq 0.35$ |
| $z = 0.25w + 0.25x + 8$ | $z_0 = 24$ | $z_{i+1} - z_i \leq 0.35$ |

| Iteration 1 | Iteration 2 |
|------------------------|--------------------------------------|
| $w_1 = 6 + 6 + 8 = 20$ | $w_2 = 5 + 4.75 + 8 = 17.75$ |
| $x_1 = 6 + 6 + 8 = 20$ | $x_2 = 4.75 + 4.5 + 8 = 17.25$ |
| $y_1 = 6 + 5 + 8 = 19$ | $y_2 = 4.5 + 4.4375 + 8 = 16.9375$ |
| $z_1 = 5 + 5 + 8 = 18$ | $z_2 = 4.4375 + 4.375 + 8 = 16.8125$ |

| Iteration 3 | Iteration 4 |
|--|------------------|
| $w_3 = 4.3125 + 4.23375 + 8 = 16.54625$ | $w_4 = 16.20172$ |
| $x_3 = 4.23375 + 4.23375 + 8 = 16.4675$ | $x_4 = 16.17844$ |
| $y_3 = 4.23375 + 4.1365625 + 8 = 16.3703125$ | $y_4 = 16.13637$ |
| $z_3 = 4.1365625 + 4.11 + 8 = 16.3465625$ | $z_4 = 16.09504$ |



Our Method of Performing Data Flow Analysis

- Round robin iteration
 - Essentially Jacobi method
 - Unknowns are the data flow variables In_i and Out_i
 - Domain of values is not numbers
 - Computation in a fixed order
 - ▶ either forward (reverse post order) traversal, or
 - ▶ backward (post order) traversal
- over the control flow graph



Tutorial Problem 2 for Liveness Analysis

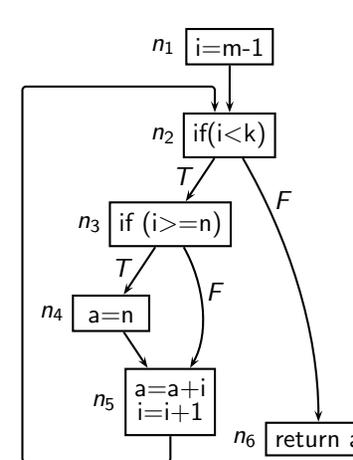
Draw the control flow graph and perform live variables analysis

```

int f(int m, int n, int k)
{
    int a, i;

    for (i=m-1; i<k; i++)
    {
        if (i>=n)
            a = n;
        else
            a = a+i;
    }

    return a;
}
    
```



The Semantics of Return Statement for Live Variables Analysis

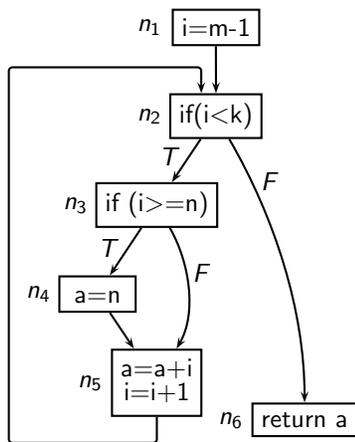
“return a” is modelled by the statement “return_value_in_stack = a”

- If we assume that the statement is executed *within* the block
 $\Rightarrow BI$ can be \emptyset
- If we assume that the statement is executed *outside* of the block and along the edge connecting the procedure to its caller
 $\Rightarrow a \in BI$

Solution of Tutorial Problem 2

| Block | Local Information | | Global Information | | | |
|-------|-------------------|-------------|--------------------|--------------|-------------------------|--------------|
| | Gen_n | $Kill_n$ | Iteration # 1 | | Change in iteration # 2 | |
| | | | Out_n | In_n | Out_n | In_n |
| n_6 | {a} | \emptyset | \emptyset | {a} | | |
| n_5 | {a, i} | {a, i} | \emptyset | {a, i} | {a, i, k, n} | {a, i, k, n} |
| n_4 | {n} | {a} | {a, i} | {i, n} | {a, i, k, n} | {i, k, n} |
| n_3 | {i, n} | \emptyset | {a, i, n} | {a, i, n} | {a, i, k, n} | {a, i, k, n} |
| n_2 | {i, k} | \emptyset | {a, i, n} | {a, i, k, n} | {a, i, k, n} | |
| n_1 | {m} | {i} | {a, i, k, n} | {a, k, m, n} | | |

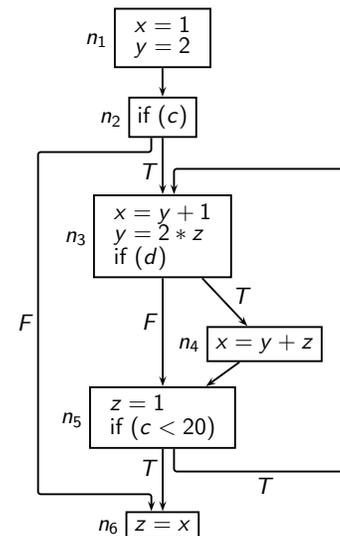
Interpreting the Result of Liveness Analysis for Tutorial Problem 2



- Is a live at the exit of n_5 at the end of iteration 1? Why?
 (We have used post order traversal)
 - Is a live at the exit of n_5 at the end of iteration 2? Why?
 (We have used post order traversal)
 - Show an execution path along which a is live at the exit of n_5
 - Show an execution path along which a is live at the exit of n_3
 - Show an execution path along which a is not live at the exit of n_3
- $n_1 \rightarrow n_2 \rightarrow n_3 \rightarrow n_5 \rightarrow n_2 \rightarrow \dots$
- $n_1 \rightarrow n_2 \rightarrow n_3 \rightarrow n_4 \rightarrow n_2 \rightarrow \dots$

Tutorial Problem 3 for Liveness Analysis

Also write a C program for this CFG without using goto or break

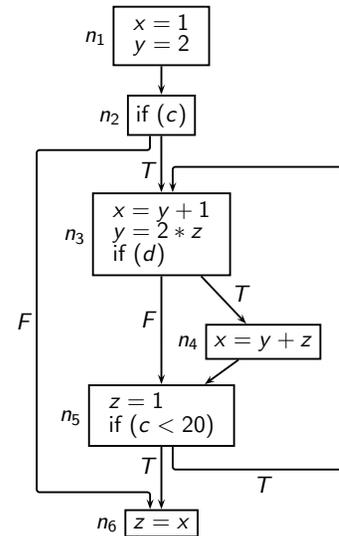


```
void f()
{ int x, y, z;
  int c, d;
  x = 1;
  y = 2;
  if (c)
  { do
    { x = y+1;
      y = 2*z;
      if (d)
        x = y+z;
      z = 1;
    } while (c < 20);
  }
  z = x;
}
```

Solution of Tutorial Problem 3

| Block | Local Information | | Global Information | | | |
|----------------|-------------------|-------------------|--------------------|-----------------|-------------------------|-----------------|
| | Gen _n | Kill _n | Iteration # 1 | | Change in iteration # 2 | |
| | | | Out _n | In _n | Out _n | In _n |
| n ₆ | {x} | {z} | ∅ | {x} | | |
| n ₅ | {c} | {z} | {x} | {x, c} | {x, y, z, c, d} | {x, y, c, d} |
| n ₄ | {y, z} | {x} | {x, c} | {y, z, c} | {x, y, c, d} | {y, z, c, d} |
| n ₃ | {y, z, d} | {x, y} | {x, y, z, c, d} | {y, z, c, d} | {x, y, z, c, d} | |
| n ₂ | {c} | ∅ | {x, y, z, c, d} | {x, y, z, c, d} | | |
| n ₁ | ∅ | {x, y} | {x, y, z, c, d} | {z, c, d} | | |

Interpreting the Result of Liveness Analysis for Tutorial Problem 3



- Why is z live at the exit of n₅?
- Why is z not live at the entry of n₅?
- Why is x live at the exit of n₃ inspite of being killed in n₄?
- Identify the instance of dead code elimination **z = x in n₆**
- Would the first round of dead code elimination cause liveness information to change? **Yes**
- Would the second round of liveness analysis lead to further dead code elimination? **Yes**

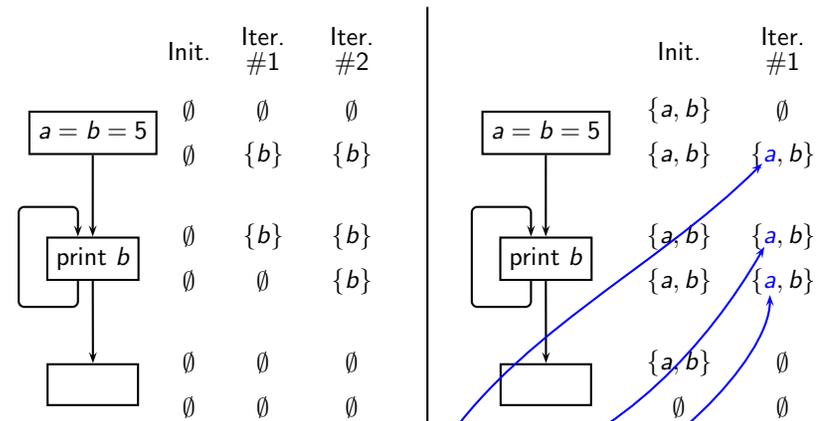
Choice of Initialization

What should be the initial value of internal nodes?

- Confluence is \cup
 - Identity of \cup is \emptyset
 - We begin with \emptyset and let the sets at each program point grow
- A revisit to a program point
- ▶ may consider a new execution path
 - ▶ more variables may be found to be live
 - ▶ a variable found to be live earlier does not become dead

The role of boundary info *BI* explained later in the context of available expressions analysis

How Does the Initialization Affect the Solution?

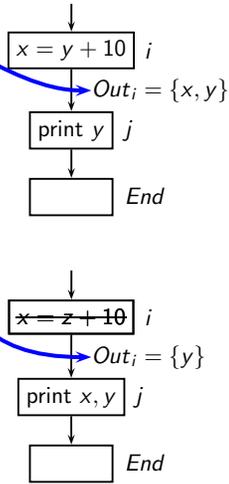


a is spuriously marked live

Soundness and Precision of Live Variables Analysis

Consider dead code elimination based on liveness information

- Spurious inclusion of a non-live variable
 - ▶ A dead assignment may not be eliminated
 - ▶ Solution is sound but may be imprecise
- Spurious exclusion of a live variable
 - ▶ A useful assignment may be eliminated
 - ▶ Solution is unsound
- Given $L_2 \supseteq L_1$ representing liveness information
 - ▶ Using L_2 in place of L_1 is sound
 - ▶ Using L_1 in place of L_2 may not be sound
- The smallest set of all live variables is most precise
 - ▶ Since liveness sets grow (confluence is \cup), we choose \emptyset as the initial conservative value



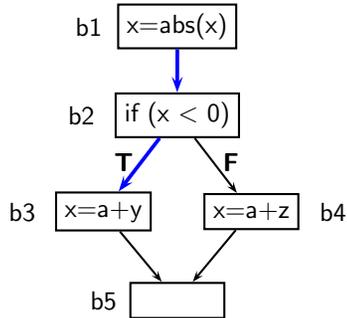
Termination, Convergence, and Complexity

- For live variables analysis,
 - ▶ The set of all variables is finite, and
 - ▶ the confluence operation (i.e. meet) is union, hence
 - ▶ the set associated with a data flow variable can only grow

\Rightarrow Termination is guaranteed
- Since initial value is \emptyset , live variables analysis converges on the smallest set
- How many iterations do we need for reaching the convergence?
- Going beyond live variables analysis
 - ▶ Do the sets always grow for other data flow frameworks?
 - ▶ What is the complexity of round robin analysis for other analyses?

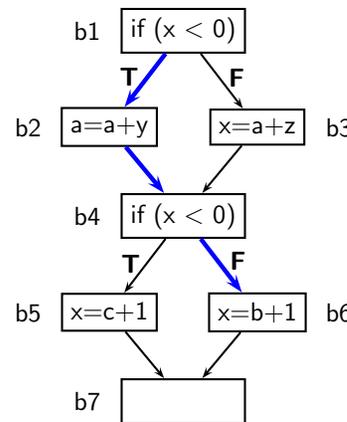
Answered formally in module 2 (Theoretical Abstractions)

Conservative Nature of Analysis (1)



- $abs(n)$ returns the absolute value of n
- Is y live on entry to block $b2$?
- By execution semantics, NO
Path $b1 \rightarrow b2 \rightarrow b3$ is an infeasible execution path
- A compiler makes conservative assumptions:
All branch outcomes are possible
 \Rightarrow Consider every path in CFG as a potential execution path
- Our analysis concludes that y is live on entry to block $b2$

Conservative Nature of Analysis (2)



- Is b live on entry to block $b2$?
- By execution semantics, NO
Path $b1 \rightarrow b2 \rightarrow b4 \rightarrow b6$ is an infeasible execution path
- Is c live on entry to block $b3$?
- Path $b1 \rightarrow b3 \rightarrow b4 \rightarrow b6$ is a feasible execution path
- A compiler make conservative assumptions
 \Rightarrow our analysis is *path insensitive*
Note: It is *flow sensitive* (i.e. information is computed for every control flow points)
- Our analysis concludes that b is live at the entry of $b2$
- Is c live at the entry of $b3$?

Conservative Nature of Analysis at Intraprocedural Level

- We assume that all paths are potentially executable
- Our analysis is path insensitive
 - ▶ The data flow information at a program point p is path insensitive
 - information at p is merged along all paths reaching p
 - ▶ The data flow information reaching p is computed path insensitively
 - information is merged at all shared points in paths reaching p
 - may generate spurious information due to non-distributive flow functions

[More about it in module 2](#)



Conservative Nature of Analysis at Interprocedural Level

- Context insensitivity
 - ▶ Merges of information across all calling contexts
- Flow insensitivity
 - ▶ Disregards the control flow

[More about it in module 4](#)



What About Soundness of Analysis Results?

- No compromises
- We will study it in module 2

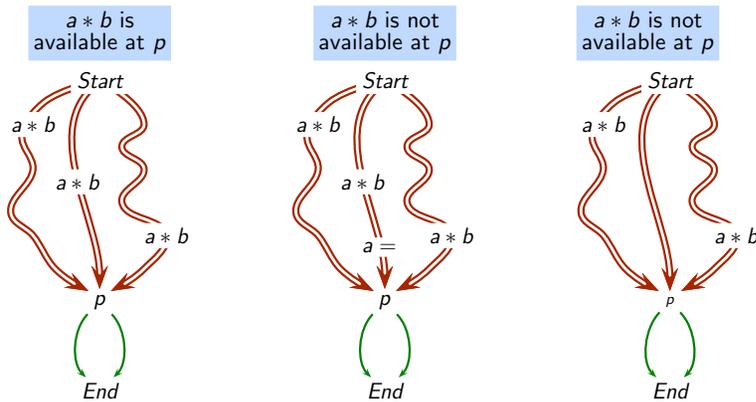


Part 4

Available Expressions Analysis

Defining Available Expressions Analysis

An expression e is available at a program point p , if every path from program entry to p contains an evaluation of e which is not followed by a definition of any operand of e .



Local Data Flow Properties for Available Expressions Analysis

$$Gen_n = \{ e \mid \text{expression } e \text{ is evaluated in basic block } n \text{ and this evaluation is not followed by a definition of any operand of } e \}$$

$$Kill_n = \{ e \mid \text{basic block } n \text{ contains a definition of an operand of } e \}$$

| | Entity | Manipulation | Exposition |
|----------|------------|--------------|------------|
| Gen_n | Expression | Use | Downwards |
| $Kill_n$ | Expression | Modification | Anywhere |



Data Flow Equations For Available Expressions Analysis

$$In_n = \begin{cases} BI & n \text{ is Start block} \\ \bigcap_{p \in \text{pred}(n)} Out_p & \text{otherwise} \end{cases}$$

$$Out_n = Gen_n \cup (In_n - Kill_n)$$

Alternatively,

$$Out_n = f_n(In_n), \quad \text{where}$$

$$f_n(X) = Gen_n \cup (X - Kill_n)$$

- In_n and Out_n are sets of expressions
- BI is \emptyset for expressions involving a local variable



Using Data Flow Information of Available Expressions Analysis

- Common subexpression elimination
 - If an expression is available at the entry of a block n (In_n) and a computation of the expression exists in n such that it is not preceded by a definition of any of its operands ($AntGen_n$)

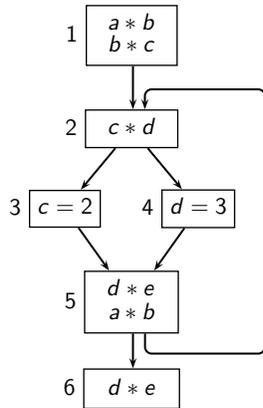
Then the expression is redundant

$$Redundant_n = In_n \cap AntGen_n$$

- A redundant expression is upwards exposed whereas the expressions in Gen_n are downwards exposed



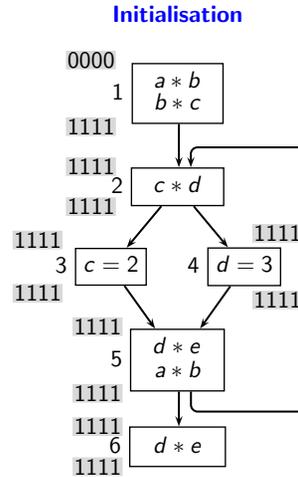
An Example of Available Expressions Analysis



Let $e_1 \equiv a * b$, $e_2 \equiv b * c$, $e_3 \equiv c * d$, $e_4 \equiv d * e$

| Node | Gen | Kill | Available | Redund. |
|------|----------------|------|----------------|---------|
| 1 | { e_1, e_2 } | 1100 | \emptyset | 0000 |
| 2 | { e_3 } | 0010 | \emptyset | 0000 |
| 3 | \emptyset | 0000 | { e_2, e_3 } | 0110 |
| 4 | \emptyset | 0000 | { e_3, e_4 } | 0011 |
| 5 | { e_1, e_4 } | 1001 | \emptyset | 0000 |
| 6 | { e_4 } | 0001 | \emptyset | 0000 |

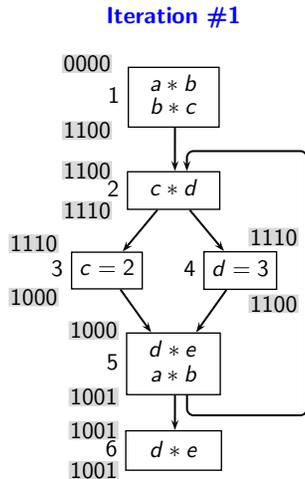
An Example of Available Expressions Analysis



Let $e_1 \equiv a * b$, $e_2 \equiv b * c$, $e_3 \equiv c * d$, $e_4 \equiv d * e$

| Node | Gen | Kill | Available | Redund. |
|------|----------------|------|----------------|---------|
| 1 | { e_1, e_2 } | 1100 | \emptyset | 0000 |
| 2 | { e_3 } | 0010 | \emptyset | 0000 |
| 3 | \emptyset | 0000 | { e_2, e_3 } | 0110 |
| 4 | \emptyset | 0000 | { e_3, e_4 } | 0011 |
| 5 | { e_1, e_4 } | 1001 | \emptyset | 0000 |
| 6 | { e_4 } | 0001 | \emptyset | 0000 |

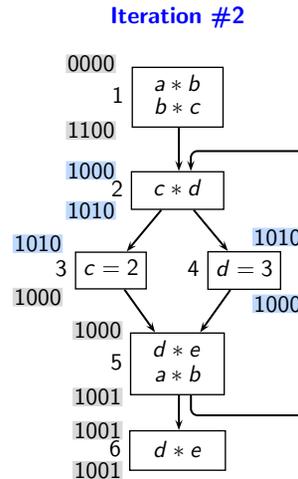
An Example of Available Expressions Analysis



Let $e_1 \equiv a * b$, $e_2 \equiv b * c$, $e_3 \equiv c * d$, $e_4 \equiv d * e$

| Node | Gen | Kill | Available | Redund. |
|------|----------------|------|----------------|---------|
| 1 | { e_1, e_2 } | 1100 | \emptyset | 0000 |
| 2 | { e_3 } | 0010 | \emptyset | 0000 |
| 3 | \emptyset | 0000 | { e_2, e_3 } | 0110 |
| 4 | \emptyset | 0000 | { e_3, e_4 } | 0011 |
| 5 | { e_1, e_4 } | 1001 | \emptyset | 0000 |
| 6 | { e_4 } | 0001 | \emptyset | 0000 |

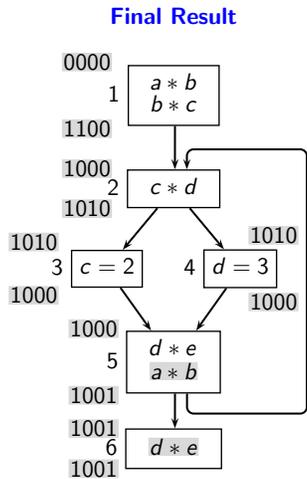
An Example of Available Expressions Analysis



Let $e_1 \equiv a * b$, $e_2 \equiv b * c$, $e_3 \equiv c * d$, $e_4 \equiv d * e$

| Node | Gen | Kill | Available | Redund. |
|------|----------------|------|----------------|---------|
| 1 | { e_1, e_2 } | 1100 | \emptyset | 0000 |
| 2 | { e_3 } | 0010 | \emptyset | 0000 |
| 3 | \emptyset | 0000 | { e_2, e_3 } | 0110 |
| 4 | \emptyset | 0000 | { e_3, e_4 } | 0011 |
| 5 | { e_1, e_4 } | 1001 | \emptyset | 0000 |
| 6 | { e_4 } | 0001 | \emptyset | 0000 |

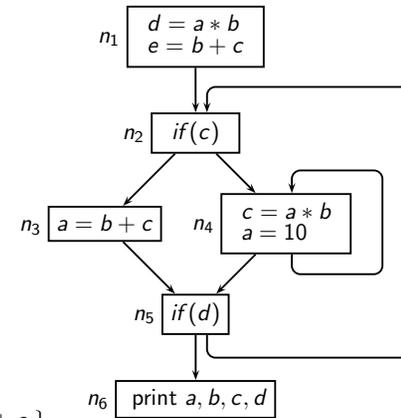
An Example of Available Expressions Analysis



Let $e_1 \equiv a * b$, $e_2 \equiv b * c$, $e_3 \equiv c * d$, $e_4 \equiv d * e$

| Node | Gen | Kill | Available | Redund. |
|------|----------------|----------------|----------------|-------------|
| 1 | { e_1, e_2 } | \emptyset | \emptyset | \emptyset |
| 2 | { e_3 } | \emptyset | { e_1 } | \emptyset |
| 3 | \emptyset | \emptyset | { e_1, e_3 } | \emptyset |
| 4 | \emptyset | { e_3, e_4 } | \emptyset | \emptyset |
| 5 | { e_1, e_4 } | \emptyset | { e_1 } | { e_1 } |
| 6 | { e_4 } | \emptyset | { e_1, e_4 } | { e_4 } |

Tutorial Problem 2 for Available Expressions Analysis



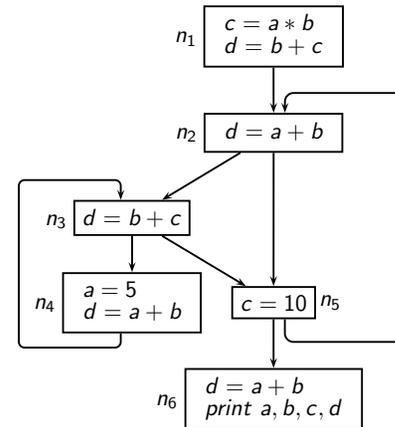
Expr = { $a * b$, $b + c$ }

Solution of the Tutorial Problem 2

Bit vector $\boxed{a * b} \boxed{b + c}$

| Node | Local Information | | | Global Information | | | | Redundant _n |
|-------|-------------------|-------------------|---------------------|--------------------|------------------|--------------------------|------------------|------------------------|
| | | | | Iteration # 1 | | Changes in iteration # 2 | | |
| | Gen _n | Kill _n | AntGen _n | In _n | Out _n | In _n | Out _n | |
| n_1 | 11 | 00 | 11 | 00 | 11 | | | 00 |
| n_2 | 00 | 00 | 00 | 11 | 11 | 00 | 00 | 00 |
| n_3 | 01 | 10 | 01 | 11 | 01 | 00 | | 00 |
| n_4 | 00 | 11 | 10 | 11 | 00 | 00 | | 00 |
| n_5 | 00 | 00 | 00 | 00 | 00 | | | 00 |
| n_6 | 00 | 00 | 00 | 00 | 00 | | | 00 |

Tutorial Problem 3 for Available Expressions Analysis



Expr = { $a * b$, $b + c$, $a + b$ }

Solution of the Tutorial Problem 3

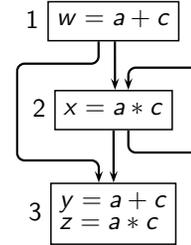
Bit vector $a * b$ $b + c$ $a + b$

| Node | Local Information | | | Global Information | | | | | | Redundant _n |
|----------------|-------------------|-------------------|---------------------|--------------------|------------------|--------------------------|------------------|--------------------------|------------------|------------------------|
| | | | | Iteration # 1 | | Changes in Iteration # 2 | | Changes in Iteration # 3 | | |
| | Gen _n | Kill _n | AntGen _n | In _n | Out _n | In _n | Out _n | In _n | Out _n | |
| n ₁ | 110 | 010 | 100 | 000 | 110 | | | | | 000 |
| n ₂ | 001 | 000 | 001 | 110 | 111 | 100 | 101 | 000 | 001 | 000 |
| n ₃ | 010 | 000 | 010 | 111 | 111 | 001 | 011 | | | 000 |
| n ₄ | 001 | 101 | 000 | 111 | 011 | 011 | | | | 000 |
| n ₅ | 000 | 010 | 000 | 111 | 101 | 001 | 001 | | | 000 |
| n ₆ | 001 | 000 | 001 | 101 | 101 | 001 | 001 | | | 001 |

Why do we need 3 iterations as against 2 for previous problems?

The Effect of BI and Initialization on a Solution

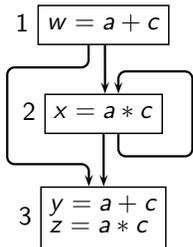
Bit Vector
 $a + c$ $a * c$



| BI | Node | Initialization \cup | | Initialization \emptyset | |
|-------------|------|-----------------------|------------------|----------------------------|------------------|
| | | In _n | Out _n | In _n | Out _n |
| \emptyset | 1 | 00 | 10 | 00 | 10 |
| | 2 | 10 | 11 | 00 | 01 |
| | 3 | 10 | 11 | 01 | 11 |
| \cup | 1 | 11 | 11 | 11 | 11 |
| | 2 | 11 | 11 | 00 | 01 |
| | 3 | 11 | 11 | 01 | 11 |

The Effect of BI and Initialization on a Solution

Bit Vector
 $a + c$ $a * c$

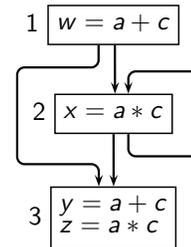


| BI | Node | Initialization \cup | | Initialization \emptyset | |
|-------------|------|-----------------------|------------------|----------------------------|------------------|
| | | In _n | Out _n | In _n | Out _n |
| \emptyset | 1 | 00 | 10 | 00 | 10 |
| | 2 | 10 | 11 | 00 | 01 |
| | 3 | 10 | 11 | 01 | 11 |
| \cup | 1 | 11 | 11 | 11 | 11 |
| | 2 | 11 | 11 | 00 | 01 |
| | 3 | 11 | 11 | 01 | 11 |

This represents the expected availability information leading to elimination of $a + c$ in node 3 ($a * c$ is not redundant in node 3)

The Effect of BI and Initialization on a Solution

Bit Vector
 $a + c$ $a * c$



| BI | Node | Initialization \cup | | Initialization \emptyset | |
|-------------|------|-----------------------|------------------|----------------------------|------------------|
| | | In _n | Out _n | In _n | Out _n |
| \emptyset | 1 | 00 | 10 | 00 | 10 |
| | 2 | 10 | 11 | 00 | 01 |
| | 3 | 10 | 11 | 01 | 11 |
| \cup | 1 | 11 | 11 | 11 | 11 |
| | 2 | 11 | 11 | 00 | 01 |
| | 3 | 11 | 11 | 01 | 11 |

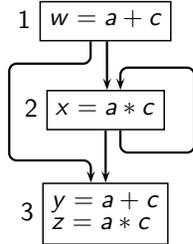
This misses the availability of $a + c$ in node 3

The Effect of BI and Initialization on a Solution

This makes $a * c$ available in node 3 although its computation in node 3 is not redundant

Bit Vector

| | |
|---------|---------|
| $a + c$ | $a * c$ |
|---------|---------|



| BI | Node | Initialization \cup | | Initialization \emptyset | |
|-------------|------|-----------------------|---------|----------------------------|---------|
| | | In_n | Out_n | In_n | Out_n |
| \emptyset | 1 | 00 | 10 | 00 | 10 |
| | 2 | 10 | 11 | 00 | 01 |
| | 3 | 10 | 11 | 01 | 11 |
| \cup | 1 | 11 | 11 | 11 | 11 |
| | 2 | 11 | 11 | 00 | 01 |
| | 3 | 11 | 11 | 01 | 11 |

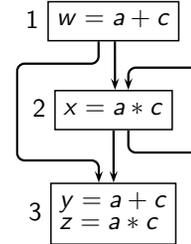


The Effect of BI and Initialization on a Solution

This make $a * c$ available in node 3 and but misses the availability of $a + c$ in node 3

Bit Vector

| | |
|---------|---------|
| $a + c$ | $a * c$ |
|---------|---------|



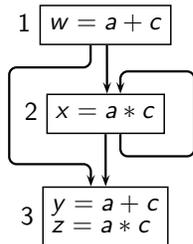
| BI | Node | Initialization \cup | | Initialization \emptyset | |
|-------------|------|-----------------------|---------|----------------------------|---------|
| | | In_n | Out_n | In_n | Out_n |
| \emptyset | 1 | 00 | 10 | 00 | 10 |
| | 2 | 10 | 11 | 00 | 01 |
| | 3 | 10 | 11 | 01 | 11 |
| \cup | 1 | 11 | 11 | 11 | 11 |
| | 2 | 11 | 11 | 00 | 01 |
| | 3 | 11 | 11 | 01 | 11 |



The Effect of BI and Initialization on a Solution

Bit Vector

| | |
|---------|---------|
| $a + c$ | $a * c$ |
|---------|---------|



| BI | Node | Initialization \cup | | Initialization \emptyset | |
|-------------|------|-----------------------|---------|----------------------------|---------|
| | | In_n | Out_n | In_n | Out_n |
| \emptyset | 1 | 00 | 10 | 00 | 10 |
| | 2 | 10 | 11 | 00 | 01 |
| | 3 | 10 | 11 | 01 | 11 |
| \cup | 1 | 11 | 11 | 11 | 11 |
| | 2 | 11 | 11 | 00 | 01 |
| | 3 | 11 | 11 | 01 | 11 |



Some Observations

- Data flow equations do not require a particular order of computation
 - Specification.** Data flow equations define what needs to be computed and not how it is to be computed
 - Implementation.** Round robin iterations perform the actual computation
 - Specification and implementation are distinct
- Initialization governs the quality of solution found
 - Only precision is affected, soundness is guaranteed
 - Associated with "internal" nodes
- BI depends on the semantics of the calling context
 - May cause unsoundness
 - Associated with "boundary" node (specified by data flow equations) Does not vary with the method or order of traversal



Still More Tutorial Problems ☺

A New Data Flow Framework: Partially available expressions analysis

- Expressions that are computed and remain unmodified along some path reaching p
- The data flow equations are same as that of available expressions analysis except that the confluence is changed to \cup

Perform partially available expressions analysis for the example program used for available expressions analysis

Solution of the Tutorial Problem 2 for Partial Availability Analysis

Bit vector $a * b \quad b + c$

| Node | Local Information | | | Global Information | | |
|-------|-------------------|----------|------------|--------------------|------------|---------------|
| | | | | Iteration # 1 | | $ParRedund_n$ |
| | Gen_n | $Kill_n$ | $AntGen_n$ | $PavIn_n$ | $PavOut_n$ | |
| n_1 | 11 | 00 | 11 | 00 | 11 | 00 |
| n_2 | 00 | 00 | 00 | 11 | 11 | 00 |
| n_3 | 01 | 10 | 01 | 11 | 01 | 01 |
| n_4 | 00 | 11 | 10 | 11 | 00 | 10 |
| n_5 | 00 | 00 | 00 | 01 | 01 | 00 |
| n_6 | 00 | 00 | 00 | 01 | 01 | 00 |

Solution of the Tutorial Problem 3 for Partial Availability Analysis

Bit vector $a * b \quad b + c \quad a + b$

| Node | Local Information | | | Global Information | | | | |
|-------|-------------------|----------|------------|--------------------|------------|--------------------------|---------|---------------|
| | | | | Iteration # 1 | | Changes in iteration # 2 | | $ParRedund_n$ |
| | Gen_n | $Kill_n$ | $AntGen_n$ | $PavIn_n$ | $PavOut_n$ | In_n | Out_n | |
| n_1 | 110 | 010 | 100 | 000 | 110 | | | 000 |
| n_2 | 001 | 000 | 001 | 110 | 111 | 111 | | 001 |
| n_3 | 010 | 000 | 010 | 111 | 111 | | | 010 |
| n_4 | 001 | 101 | 000 | 111 | 011 | | | 000 |
| n_5 | 000 | 010 | 000 | 111 | 101 | | | 000 |
| n_6 | 001 | 000 | 001 | 101 | 101 | | | 001 |

Part 5

Reaching Definitions Analysis

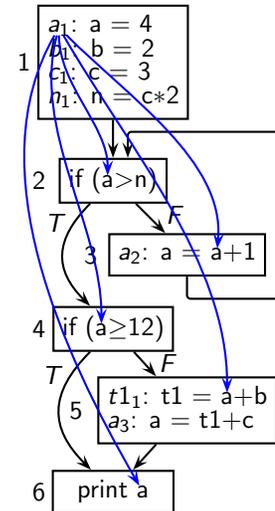
Defining Reaching Definitions Analysis

- A definition $d_x : x = e$ reaches a program point p if it appears (without a redefinition of x) on **some path from program entry to p** (x is a variable and e is an expression)
- Application : Copy Propagation
A use of a variable x at a program point p can be replaced by y if $d_x : x = y$ is the only definition which reaches p and y is not modified between the point of d_x and p .



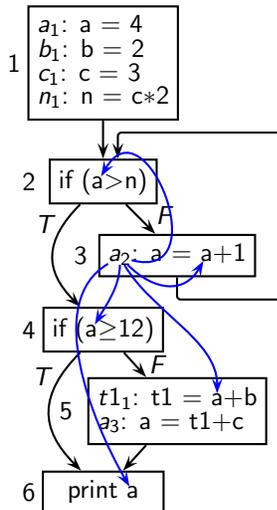
Using Reaching Definitions for Def-Use and Use-Def Chains

Def-Use Chains



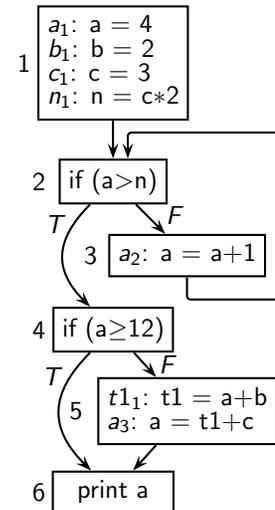
Using Reaching Definitions for Def-Use and Use-Def Chains

Def-Use Chains

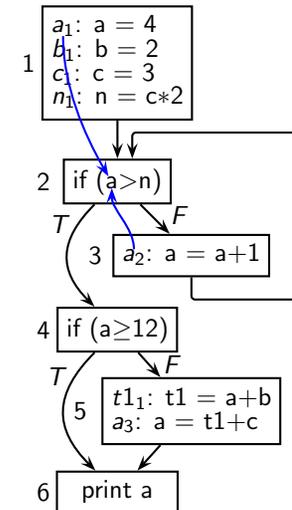


Using Reaching Definitions for Def-Use and Use-Def Chains

Def-Use Chains

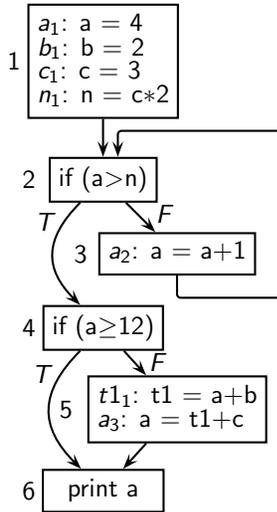


Use-Def Chains

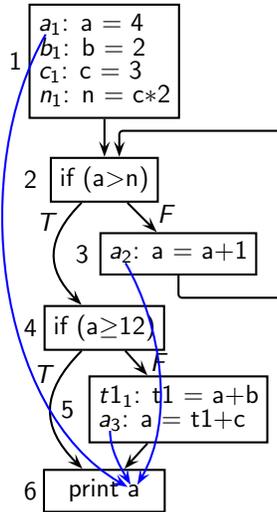


Using Reaching Definitions for Def-Use and Use-Def Chains

Def-Use Chains

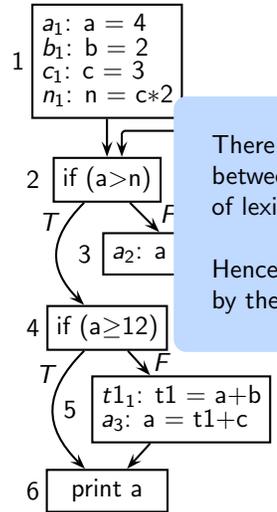


Use-Def Chains



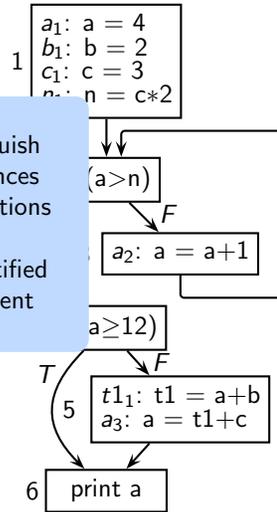
Using Reaching Definitions for Def-Use and Use-Def Chains

Def-Use Chains



There is a need to distinguish between different occurrences of lexically identical definitions
Hence a definition is identified by the label of the statement

Use-Def Chains



Defining Data Flow Analysis for Reaching Definitions Analysis

Let d_v be a definition of variable v

$Gen_n = \{ d_v \mid \text{variable } v \text{ is defined in basic block } n \text{ and this definition is not followed (within } n \text{) by a definition of } v \}$

$Kill_n = \{ d_v \mid \text{basic block } n \text{ contains a definition of } v \}$

| | Entity | Manipulation | Exposition |
|----------|------------|--------------|------------|
| Gen_n | Definition | Occurrence | Downwards |
| $Kill_n$ | Definition | Occurrence | Anywhere |

Data Flow Equations for Reaching Definitions Analysis

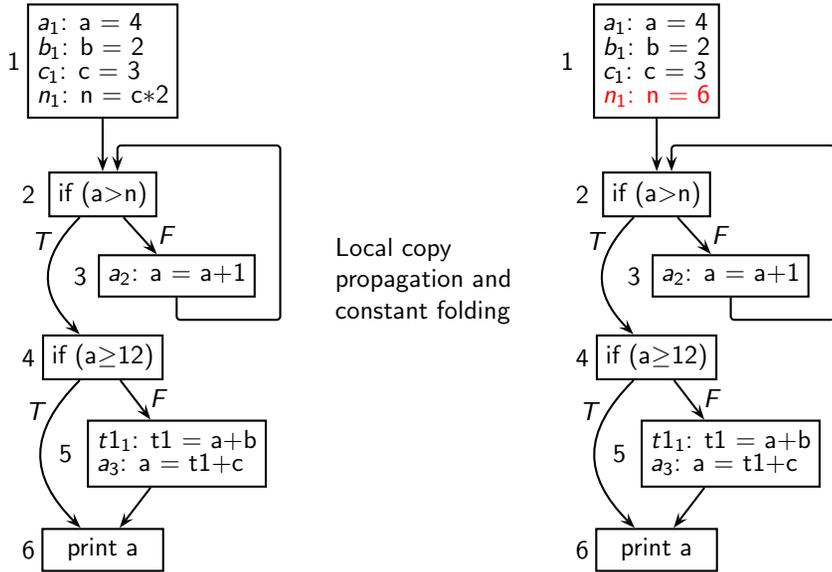
$$In_n = \begin{cases} BI & n \text{ is Start block} \\ \bigcup_{p \in \text{pred}(n)} Out_p & \text{otherwise} \end{cases}$$

$$Out_n = Gen_n \cup (In_n - Kill_n)$$

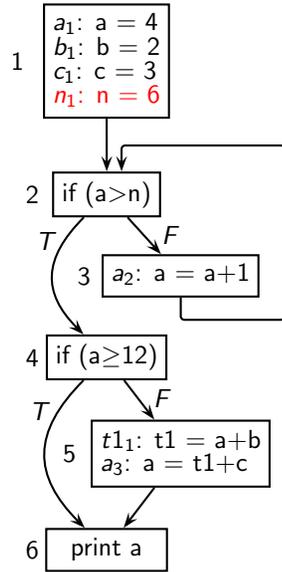
$$BI = \{ d_x : x = \text{undef} \mid x \in \text{Var} \}$$

In_n and Out_n are sets of definitions

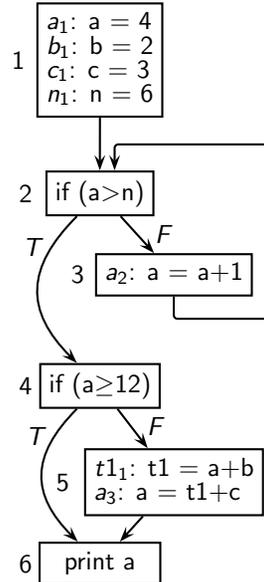
Tutorial Problem for Copy Propagation



Local copy propagation and constant folding



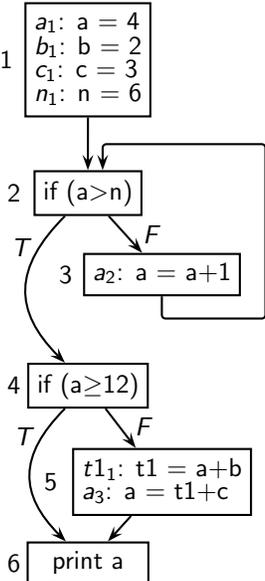
Tutorial Problem for Copy Propagation



| | Gen | Kill |
|----|--|--|
| n1 | {a ₁ , b ₁ , c ₁ , n ₁ } | {a ₀ , a ₁ , a ₂ , a ₃ , b ₀ , b ₁ , c ₀ , c ₁ , n ₀ , n ₁ } |
| n2 | ∅ | ∅ |
| n3 | {a ₂ } | {a ₀ , a ₁ , a ₂ , a ₃ } |
| n4 | ∅ | ∅ |
| n5 | {a ₃ } | {a ₀ , a ₁ , a ₂ , a ₃ } |
| n6 | ∅ | ∅ |

- Temporary variable t1 is ignored
- For variable v, v₀ denotes the definition v = ?
This is used for defining BI

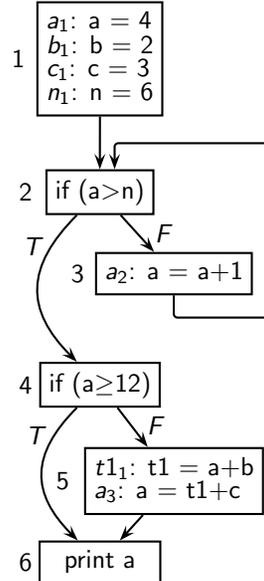
Tutorial Problem for Copy Propagation



| | Gen | Kill |
|----|--|--|
| n1 | {a ₁ , b ₁ , c ₁ , n ₁ } | {a ₀ , a ₁ , a ₂ , a ₃ , b ₀ , b ₁ , c ₀ , c ₁ , n ₀ , n ₁ } |
| n2 | ∅ | ∅ |
| n3 | {a ₂ } | {a ₀ , a ₁ , a ₂ , a ₃ } |
| n4 | ∅ | ∅ |
| n5 | {a ₃ } | {a ₀ , a ₁ , a ₂ , a ₃ } |
| n6 | ∅ | ∅ |

| | Iteration #1 | |
|----|---|---|
| | In | Out |
| n1 | {a ₀ , b ₀ , c ₀ , n ₀ } | {a ₁ , b ₁ , c ₁ , n ₁ } |
| n2 | {a ₁ , b ₁ , c ₁ , n ₁ } | {a ₁ , b ₁ , c ₁ , n ₁ } |
| n3 | {a ₁ , b ₁ , c ₁ , n ₁ } | {a ₂ , b ₁ , c ₁ , n ₁ } |
| n4 | {a ₁ , b ₁ , c ₁ , n ₁ } | {a ₁ , b ₁ , c ₁ , n ₁ } |
| n5 | {a ₁ , b ₁ , c ₁ , n ₁ } | {a ₃ , b ₁ , c ₁ , n ₁ } |
| n6 | {a ₁ , a ₃ , b ₁ , c ₁ , n ₁ } | {a ₁ , a ₃ , b ₁ , c ₁ , n ₁ } |

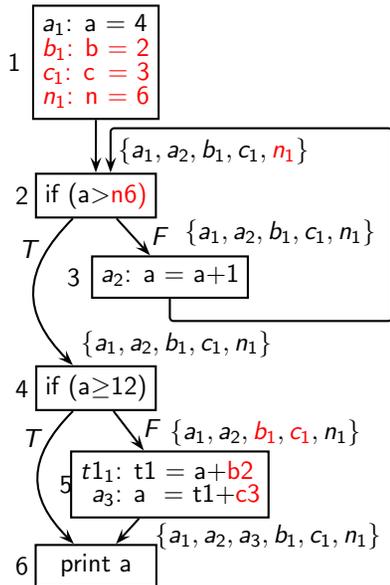
Tutorial Problem for Copy Propagation



| | Gen | Kill |
|----|--|--|
| n1 | {a ₁ , b ₁ , c ₁ , n ₁ } | {a ₀ , a ₁ , a ₂ , a ₃ , b ₀ , b ₁ , c ₀ , c ₁ , n ₀ , n ₁ } |
| n2 | ∅ | ∅ |
| n3 | {a ₂ } | {a ₀ , a ₁ , a ₂ , a ₃ } |
| n4 | ∅ | ∅ |
| n5 | {a ₃ } | {a ₀ , a ₁ , a ₂ , a ₃ } |
| n6 | ∅ | ∅ |

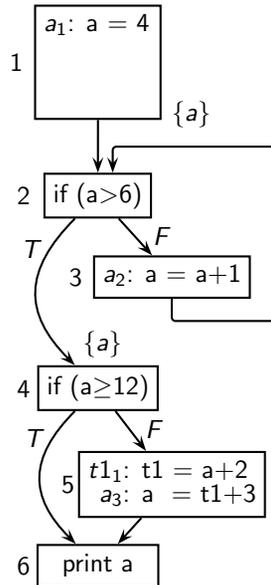
| | Iteration #2 | |
|----|--|--|
| | In | Out |
| n1 | {a ₀ , b ₀ , c ₀ , n ₀ } | {a ₁ , b ₁ , c ₁ , n ₁ } |
| n2 | {a ₁ , a ₂ , b ₁ , c ₁ , n ₁ } | {a ₁ , a ₂ , b ₁ , c ₁ , n ₁ } |
| n3 | {a ₁ , a ₂ , b ₁ , c ₁ , n ₁ } | {a ₂ , b ₁ , c ₁ , n ₁ } |
| n4 | {a ₁ , a ₂ , b ₁ , c ₁ , n ₁ } | {a ₁ , a ₂ , b ₁ , c ₁ , n ₁ } |
| n5 | {a ₁ , a ₂ , b ₁ , c ₁ , n ₁ } | {a ₃ , b ₁ , c ₁ , n ₁ } |
| n6 | {a ₁ , a ₂ , a ₃ , b ₁ , c ₁ , n ₁ } | {a ₁ , a ₂ , a ₃ , b ₁ , c ₁ , n ₁ } |

Tutorial Problem for Copy Propagation



- RHS of n_1 is constant and hence cannot change
- In block 2, n can be replaced by 6
- RHS of b_1 and c_1 are constant and hence cannot change
- In block 5, b can be replaced by 2 and c can be replaced by 3

Tutorial Problem for Copy Propagation



So what is the advantage?

Dead Code Elimination

- Only a is live at the exit of 1
- Assignments of b , c , and n are dead code
- Can be deleted

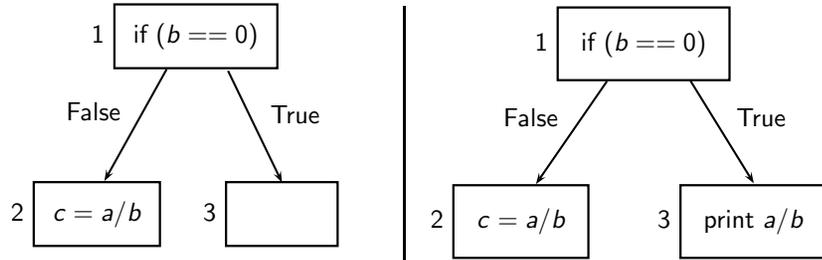
Part 6

Anticipable Expressions Analysis

Defining Anticipable Expressions Analysis

- An expression e is anticipable at a program point p , if every path from p to the program exit contains an evaluation of e which is not preceded by a redefinition of any operand of e .
- Application : Safety of Code Placement

Safety of Code Placement



Placing a/b at the exit of 1 is unsafe
 (\equiv can change the behaviour of the optimized program)

A guarded computation of an expression should not be converted to an unguarded computation

Defining Data Flow Analysis for Anticipable Expressions Analysis

$Gen_n = \{ e \mid \text{expression } e \text{ is evaluated in basic block } n \text{ and this evaluation is not preceded (within } n) \text{ by a definition of any operand of } e \}$

$Kill_n = \{ e \mid \text{basic block } n \text{ contains a definition of an operand of } e \}$

| | Entity | Manipulation | Exposition |
|----------|------------|--------------|------------|
| Gen_n | Expression | Use | Upwards |
| $Kill_n$ | Expression | Modification | Anywhere |

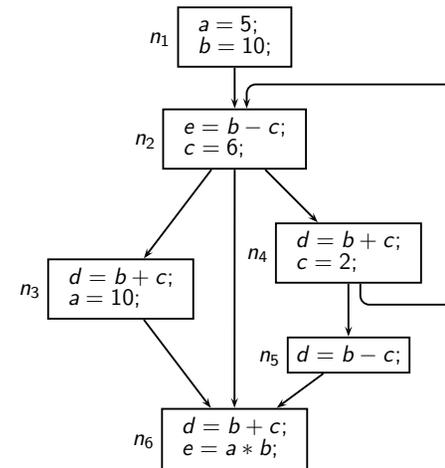
Data Flow Equations for Anticipable Expressions Analysis

$$In_n = Gen_n \cup (Out_n - Kill_n)$$

$$Out_n = \begin{cases} BI & n \text{ is End block} \\ \bigcap_{s \in succ(n)} In_s & \text{otherwise} \end{cases}$$

In_n and Out_n are sets of expressions

Tutorial Problem 1 for Anticipable Expressions Analysis



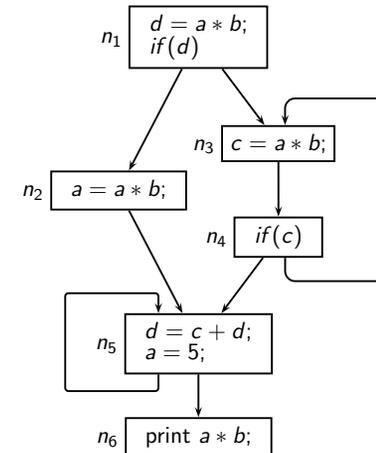
$Expr = \{ a * b, b + c, b - c \}$

Solution of Tutorial Problem 1

| Block | Local Information | | Global Information | | | |
|-------|-------------------|----------|--------------------|--------|-------------------------|--------|
| | | | Iteration # 1 | | Change in iteration # 2 | |
| | Gen_n | $Kill_n$ | Out_n | In_n | Out_n | In_n |
| n_6 | 110 | 000 | 000 | 110 | | |
| n_5 | 001 | 000 | 110 | 111 | | |
| n_4 | 010 | 011 | 111 | 110 | 001 | 010 |
| n_3 | 010 | 100 | 110 | 010 | | |
| n_2 | 001 | 011 | 010 | 001 | | |
| n_1 | 000 | 111 | 001 | 000 | | |



Tutorial Problem 2 for Anticipable Expressions Analysis



$$\mathbb{E}pr = \{ a * b, c + d \}$$


Solution of Tutorial Problem 2

| Block | Local Information | | Global Information | | | |
|-------|-------------------|----------|--------------------|--------|-------------------------|--------|
| | | | Iteration # 1 | | Change in iteration # 2 | |
| | Gen_n | $Kill_n$ | Out_n | In_n | Out_n | In_n |
| n_6 | 10 | 00 | 00 | 10 | | |
| n_5 | 01 | 11 | 10 | 01 | 00 | |
| n_4 | 00 | 00 | 01 | 01 | 00 | 00 |
| n_3 | 10 | 01 | 01 | 10 | 00 | |
| n_2 | 10 | 10 | 01 | 11 | | |
| n_1 | 10 | 01 | 10 | 10 | | |



Part 7

*Common Features of Bit
Vector Data Flow Frameworks*

Defining Local Data Flow Properties

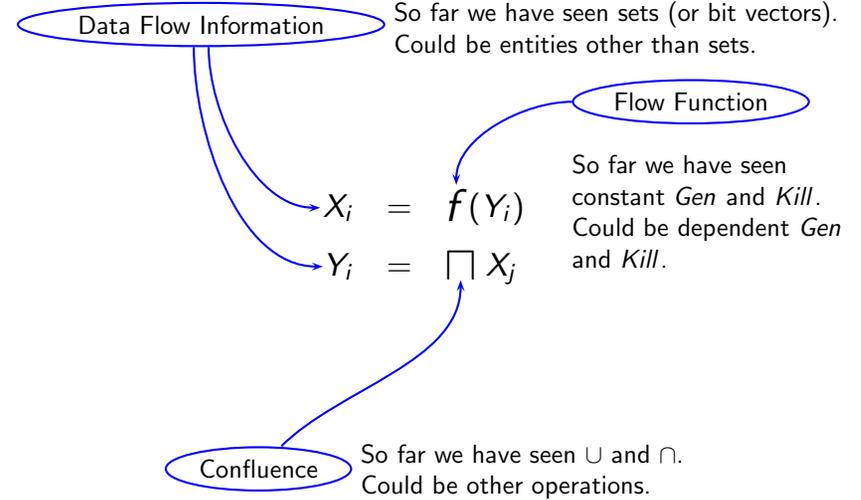
- Live variables analysis

| | Entity | Manipulation | Exposition |
|----------|----------|--------------|------------|
| Gen_n | Variable | Use | Upwards |
| $Kill_n$ | Variable | Modification | Anywhere |

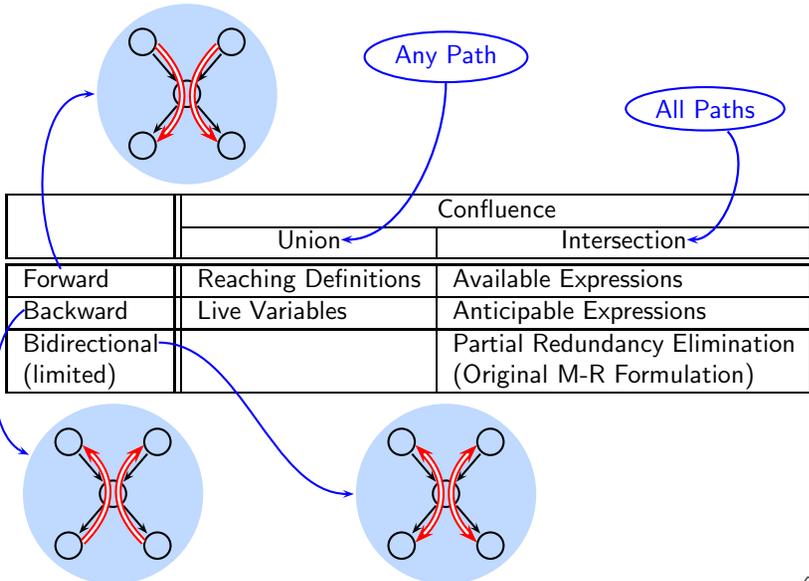
- Analysis of expressions

| | Entity | Manipulation | Exposition | |
|----------|------------|--------------|--------------|----------------|
| | | | Availability | Anticipability |
| Gen_n | Expression | Use | Downwards | Upwards |
| $Kill_n$ | Expression | Modification | Anywhere | Anywhere |

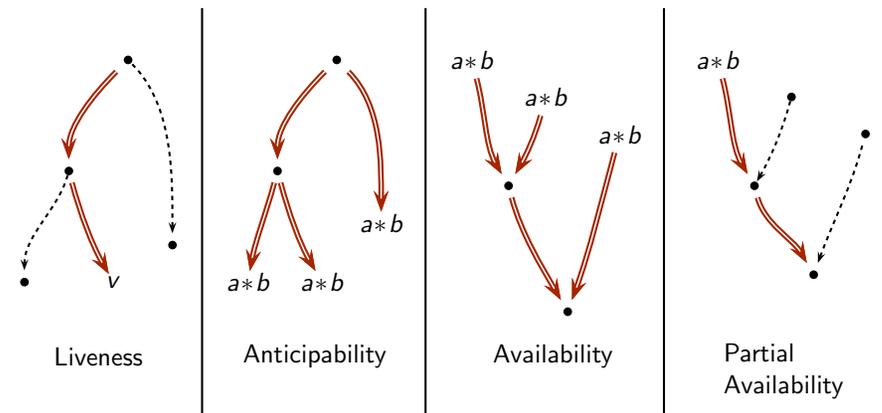
Common Form of Data Flow Equations



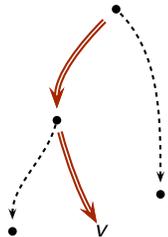
A Taxonomy of Bit Vector Data Flow Frameworks



Data Flow Paths Discovered by Data Flow Analysis



Data Flow Paths Discovered by Data Flow Analysis



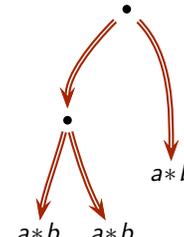
Liveness

Sequence of blocks (n_1, n_2, \dots, n_k) which is a prefix of some potential execution path starting at n_1 such that:

- n_k contains an upwards exposed use of v , **and**
- no other block on the path contains an assignment to v .



Data Flow Paths Discovered by Data Flow Analysis



Anticipability

Sequence of blocks (n_1, n_2, \dots, n_k) which is a prefix of some potential execution path starting at n_1 such that:

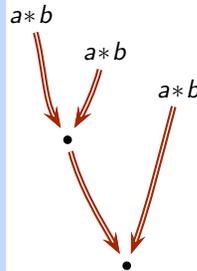
- n_k contains an upwards exposed use of $a * b$, **and**
- no other block on the path contains an assignment to a or b , **and**
- every path starting at n_1 is an anticipability path of $a * b$.



Data Flow Paths Discovered by Data Flow Analysis

Sequence of blocks (n_1, n_2, \dots, n_k) which is a prefix of some potential execution path starting at n_1 such that:

- n_1 contains a downwards exposed use of $a * b$, **and**
- no other block on the path contains an assignment to a or b , **and**
- every path ending at n_k is an availability path of $a * b$.



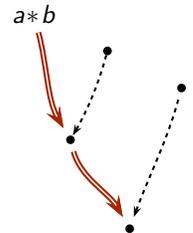
Availability



Data Flow Paths Discovered by Data Flow Analysis

Sequence of blocks (n_1, n_2, \dots, n_k) which is a prefix of some potential execution path starting at n_1 such that:

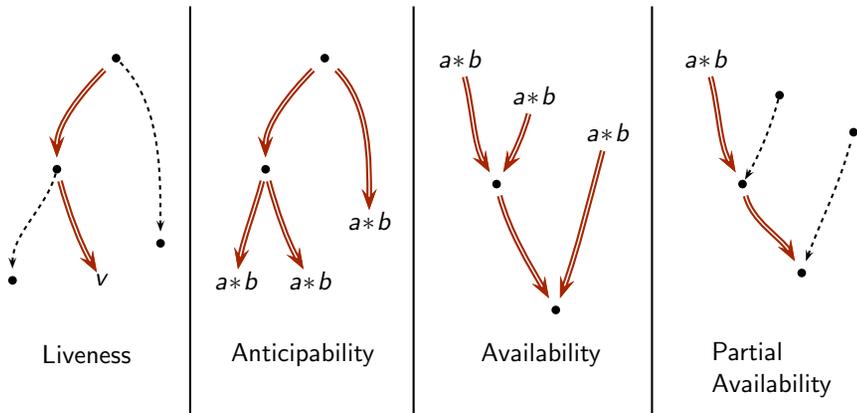
- n_1 contains a downwards exposed use of $a * b$, **and**
- no other block on the path contains an assignment to a or b .



Partial Availability



Data Flow Paths Discovered by Data Flow Analysis



Part 9

Partial Redundancy Elimination

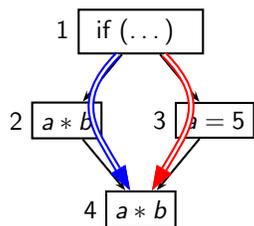
Precursor: Common Subexpression Elimination

| Code Fragment | Flow Graph | Remarks |
|---|------------|---|
| <pre> if (...) c = a*b; else d = a*b; e = a*b; </pre> | | <ul style="list-style-type: none"> a and b are not modified along paths $1 \rightarrow 2 \rightarrow 4$ and $1 \rightarrow 3 \rightarrow 4$ Computation of $a * b$ in 4 is redundant Previous value can be used |

Precursor: Common Subexpression Elimination

| Code Fragment | Flow Graph | Remarks |
|---|------------|---|
| <pre> if (...) c = a*b; else d = a*b; e = a*b; </pre> | | <ul style="list-style-type: none"> a and b are not modified along paths $1 \rightarrow 2 \rightarrow 4$ and $1 \rightarrow 3 \rightarrow 4$ Computation of $a * b$ in 4 is redundant Previous value can be used |

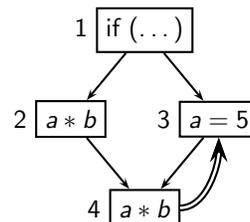
Partial Redundancy Elimination



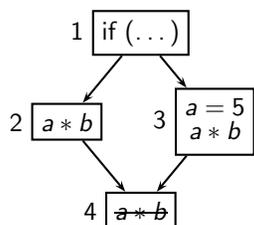
- Computation of $a * b$ in 4 is
 - ▶ redundant along path $1 \rightarrow 2 \rightarrow 4$, but ...
 - ▶ not redundant along path $1 \rightarrow 3 \rightarrow 4$



Code Hoisting for Partial Redundancy Elimination



Code Hoisting for Partial Redundancy Elimination

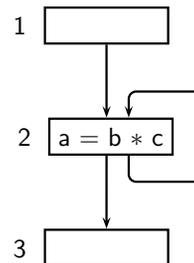


- Computation of $a * b$ in 3 becomes totally redundant
- Can be deleted

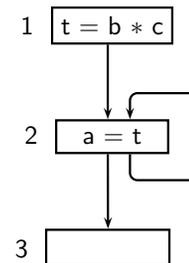


PRE Subsumes Loop Invariant Movement

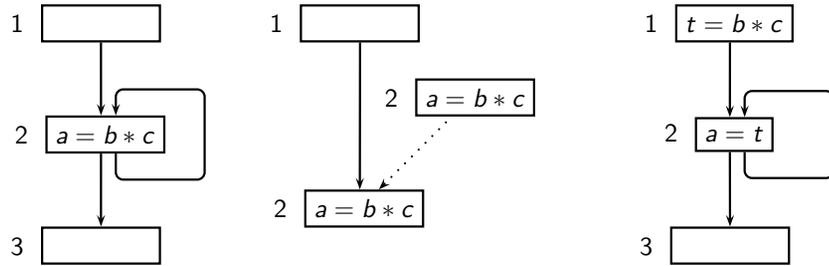
What's that?



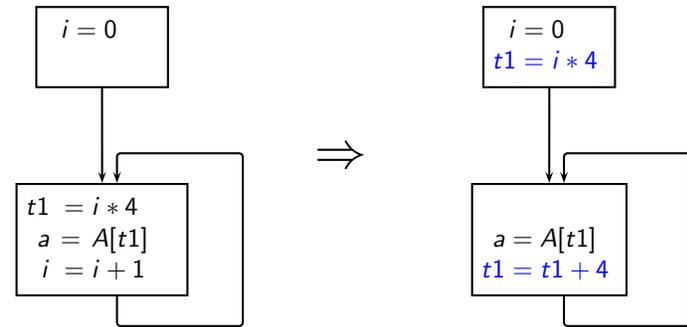
Translate to



PRE Subsumes Loop Invariant Movement

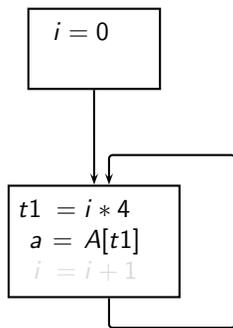


PRE Can be Used for Strength Reduction



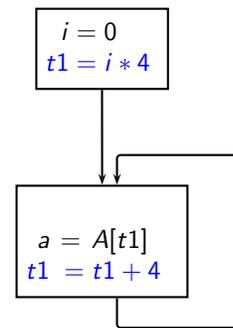
- * in the loop has been replaced by +
- $i = i + 1$ in the loop has been eliminated

PRE Can be Used for Strength Reduction



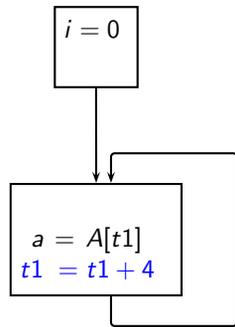
- Delete $i = i + 1$
- Expression $i * 4$ becomes loop invariant

PRE Can be Used for Strength Reduction



- Delete $i = i + 1$
- Expression $i * 4$ becomes loop invariant
- Hoist it and increment $t1$ in the loop

PRE Can be Used for Strength Reduction



- $*$ in the loop has been replaced by $+$
- $i = i + 1$ in the loop has been eliminated



Performing Partial Redundancy Elimination

1. Identify partial redundancies
2. Identify program points where computations can be inserted
3. Insert expressions
4. Partial redundancies become total redundancies
 \implies Delete them.

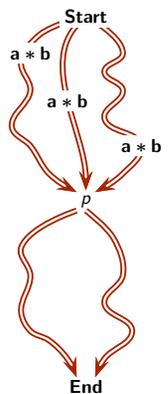
Morel-Renvoise Algorithm (CACM, 1979.)



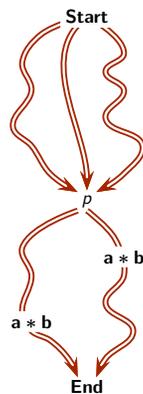
Defining Hoisting Criteria

- An expression can be safely inserted at a program point p if it is

Available at p



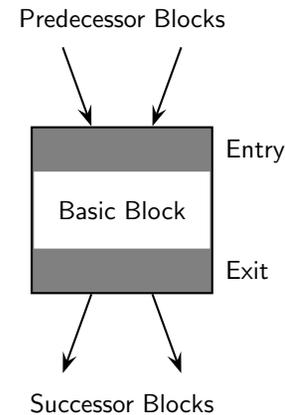
Anticipable at p



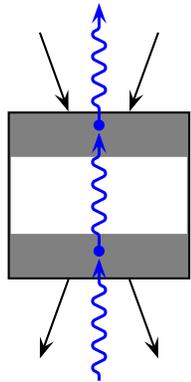
- ▶ If it is available at p , then there is no need to insert it at p .
- ▶ If it is anticipable at p then all such occurrences should be hoisted to p .
- ▶ *An expression should be hoisted to p provided it can be hoisted to p along all paths from p to exit.*



Safety of Hoisting an Expression

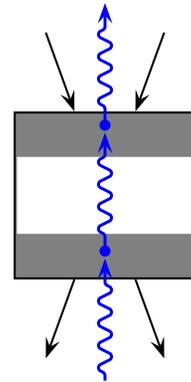


Safety of Hoisting an Expression



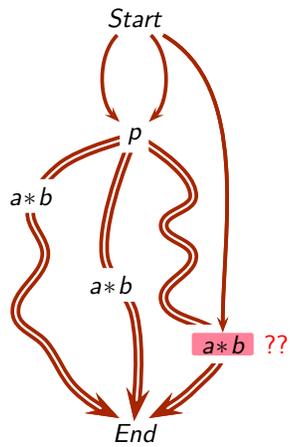
- Safety of hoisting to the exit of a block
 - S.1 Hoist only if it can be hoisted out of the entries of all successor blocks
- Safety of hoisting to the entry of a block
 - S.2 Hoist only if
 - S.2.a it is upwards exposed, or
 - S.2.b it can be hoisted to its exit and is transparent in the block
- Safety of hoisting out of the entry of a block
 - S.3 Hoist only if for each predecessor
 - S.3.a it can be hoisted to its exit, or
 - S.3.b it is available at its exit.

Safety of Hoisting an Expression



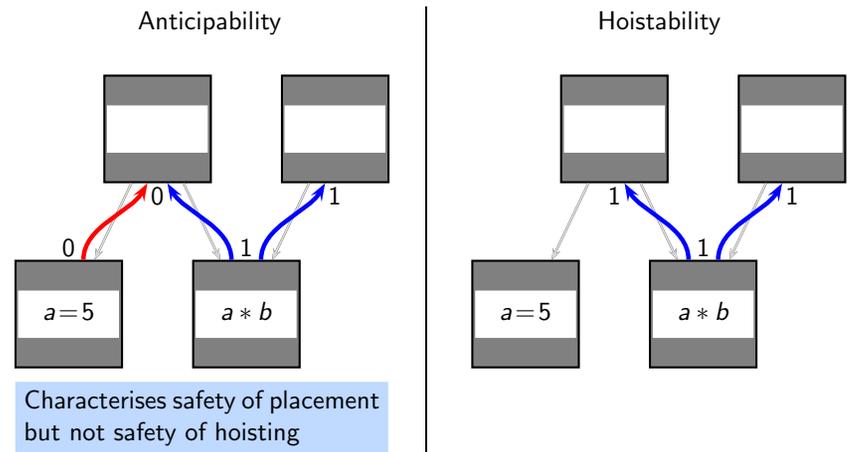
- Safety of hoisting to the exit of a block
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- Safety of hoisting out of the entry of a block
 - S.3 Hoist only if for each predecessor
 - S.3.a it can be hoisted to its exit, or
 - S.3.b it is available at its exit.

Anticipability and Code Hoisting

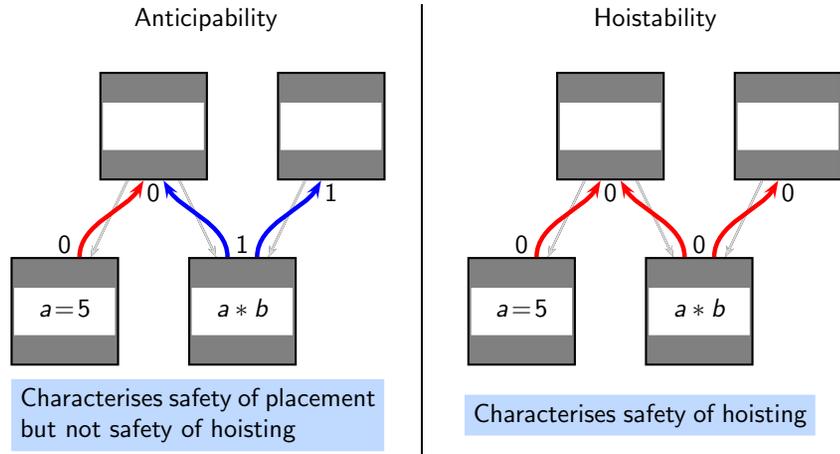


- What is the meaning of the assertion "*a * b is anticipable at program point p*"
 - ▶ *a * b* is computed along every path from *p* to *End* before *a* or *b* are modified
 - ▶ The value computed at *p* would be same as the next value computed on any path
 - ▶ *a * b* can be safely inserted at *p*
- It does not say that the subsequent computations of *a * b* can be deleted (Expression may not be available at the subsequent points)
- Hoisting involves
 - ▶ making the expressions available and
 - ▶ deleting their subsequent computations

A Comparison of Anticipability and Hoistability

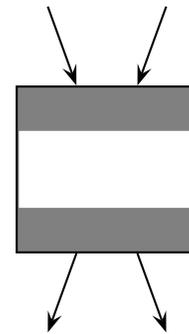


A Comparison of Anticipability and Hoistability



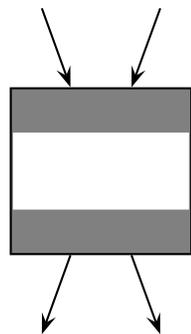
Hoist an expression to the entry of a block only if it can be hoisted out of the block into all predecessor blocks

Revised Safety Criteria of Hoisting an Expression



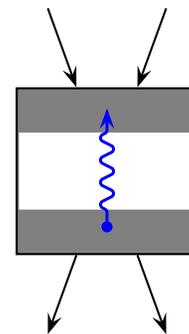
- *Safety of hoisting to the exit of a block*
 - S.1 Hoist only if it can be hoisted out of the entries of all successor blocks
- *Safety of hoisting to the entry of a block*
 - S.2 Hoist only if
 - S.2.a it is upwards exposed, or
 - S.2.b it can be hoisted to its exit and is transparent in the block
- *Safety of hoisting out of the entry of a block*
 - S.3 Hoist only if for each predecessor
 - S.3.a it can be hoisted to its exit, or
 - S.3.b it is available at its exit.

Revised Safety Criteria of Hoisting an Expression



- *Safety of hoisting to the exit of a block*
 - S.1 Hoist only if it can be hoisted out of the entries of all successor blocks
- *Safety of hoisting to the entry of a block*
 - S.2 Hoist only if
 - S.2.a it is upwards exposed, or
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 - S.3 Hoist only if for each predecessor
 - S.3.a it can be hoisted to its exit, or
 - S.3.b it is available at its exit.

Desirability of Hoisting an Expression



- *Desirability of hoisting to the entry of a block*
 - D.1 Hoist only if it is partially available

Final Hoisting Criteria

- *Safety of hoisting to the exit of a block*
 - S.1 Hoist only if it can be hoisted out of the entries of all successor blocks
- *Safety of hoisting to the entry of a block*
 - S.2 Hoist only if
 - S.2.a it is upwards exposed, or
 - S.2.b it can be hoisted to its exit and is transparent in the block
 - S.3 Hoist only if for each predecessor
 - S.3.a it can be hoisted to its exit, or
 - S.3.b it is available at its exit.
- *Desirability of hoisting to the entry of a block*
 - D.1 Hoist only if it is partially available



From Hoisting Criteria to Data Flow Equations (1)

First Level Global Data Flow Properties in PRE

- Partial Availability.

$$PavIn_n = \begin{cases} BI & n \text{ is Start block} \\ \bigcup_{p \in pred(n)} PavOut_p & \text{otherwise} \end{cases}$$

$$PavOut_n = Gen_n \cup (PavIn_n - Kill_n)$$

- Total Availability.

$$AvIn_n = \begin{cases} BI & n \text{ is Start block} \\ \bigcap_{p \in pred(n)} AvOut_p & \text{otherwise} \end{cases}$$

$$AvOut_n = Gen_n \cup (AvIn_n - Kill_n)$$



From Hoisting Criteria to Data Flow Equations (2)

- *Safety of hoisting to the exit of a block*
 - S.1 Hoist only if it can be hoisted out of the entries of all successor blocks
- *Safety of hoisting to the entry of a block*
 - S.2 Hoist only if
 - S.2.a it is upwards exposed, or
 - S.2.b it can be hoisted to its exit and is transparent in the block
 - S.3 Hoist only if for each predecessor
 - S.3.a it can be hoisted to its exit, or
 - S.3.b it is available at its exit.
- *Desirability of hoisting to the entry of a block*
 - D.1 Hoist only if it is partially available

$$\forall s \in succ(n), \quad Out_n \subseteq In_s$$

$$In_n \subseteq AntGen_n \cup (Out_n - Kill_n)$$

$$\forall p \in pred(n), \quad In_n \subseteq AvOut_p \cup Out_p$$

$$In_n \subseteq PavIn_n$$



From Hoisting Criteria to Data Flow Equations (3)

$$\forall s \in succ(n), \quad Out_n \subseteq In_s$$

$$In_n \subseteq AntGen_n \cup (Out_n - Kill_n)$$

$$\forall p \in pred(n), \quad In_n \subseteq AvOut_p \cup Out_p$$

$$In_n \subseteq PavIn_n$$

Find out the largest such set



From Hoisting Criteria to Data Flow Equations (3)

$$\forall s \in succ(n),$$

$$Out_n \subseteq In_s$$

$$In_n \subseteq AntGen_n \cup$$

$$(Out_n - Kill_n)$$

$$\forall p \in pred(n),$$

$$In_n \subseteq AvOut_p \cup$$

$$Out_p$$

$$In_n \subseteq PavIn_n$$

Desirability: D.1

$$In_n = PavIn_n$$

Expressions should be partially available, and

From Hoisting Criteria to Data Flow Equations (3)

$$\forall s \in succ(n),$$

$$Out_n \subseteq In_s$$

$$In_n \subseteq AntGen_n \cup$$

$$(Out_n - Kill_n)$$

$$\forall p \in pred(n),$$

$$In_n \subseteq AvOut_p \cup$$

$$Out_p$$

$$In_n \subseteq PavIn_n$$

Safety: S.2.a

$$In_n = PavIn_n \cap (AntGen_n \cup$$

$$Out_n)$$

Expressions should be upwards exposed, or

From Hoisting Criteria to Data Flow Equations (3)

$$\forall s \in succ(n),$$

$$Out_n \subseteq In_s$$

$$In_n \subseteq AntGen_n \cup$$

$$(Out_n - Kill_n)$$

$$\forall p \in pred(n),$$

$$In_n \subseteq AvOut_p \cup$$

$$Out_p$$

$$In_n \subseteq PavIn_n$$

Safety: S.2.b

$$In_n = PavIn_n \cap (AntGen_n \cup$$

$$Out_n)$$

Expressions can be hoisted to the exit and are transparent in the block

From Hoisting Criteria to Data Flow Equations (3)

$$\forall s \in succ(n),$$

$$Out_n \subseteq In_s$$

$$In_n \subseteq AntGen_n \cup$$

$$(Out_n - Kill_n)$$

$$\forall p \in pred(n),$$

$$In_n \subseteq AvOut_p \cup$$

$$Out_p$$

$$In_n \subseteq PavIn_n$$

Safety: S.3.b

$$In_n = PavIn_n \cap (AntGen_n \cup (Out_n - Kill_n))$$

$$\cap_{p \in pred(n)} (Out_p \cup$$

$$In_n)$$

For every predecessor, expressions can be hoisted to its exit, or

From Hoisting Criteria to Data Flow Equations (3)

$$\forall s \in succ(n),$$

$$Out_n \subseteq In_s$$

Safety: S.3.a

$$In_n \subseteq AntGen_n \cup$$

$$(Out_n - Kill_n)$$

$$In_n = PavIn_n \cap \left(AntGen_n \cup (Out_n - Kill_n) \right)$$

$$\bigcap_{p \in pred(n)} \left(Out_p \cup AvOut_p \right)$$

$$\forall p \in pred(n),$$

$$In_n \subseteq AvOut_p \cup$$

$$Out_p$$

$$In_n \subseteq PavIn_n$$

... expressions are available at the exit of the same predecessor

From Hoisting Criteria to Data Flow Equations (3)

$$\forall s \in succ(n),$$

$$Out_n \subseteq In_s$$

$$In_n \subseteq AntGen_n \cup$$

$$(Out_n - Kill_n)$$

$$In_n = PavIn_n \cap \left(AntGen_n \cup (Out_n - Kill_n) \right)$$

$$\bigcap_{p \in pred(n)} \left(Out_p \cup AvOut_p \right)$$

$$\forall p \in pred(n),$$

$$In_n \subseteq AvOut_p \cup$$

$$Out_p$$

$$Out_n = \begin{cases} BI & n \text{ is End block} \\ \text{otherwise} \end{cases}$$

$$In_n \subseteq PavIn_n$$

Boundary condition

From Hoisting Criteria to Data Flow Equations (3)

$$\forall s \in succ(n),$$

$$Out_n \subseteq In_s$$

Safety: S.1

$$In_n \subseteq AntGen_n \cup$$

$$(Out_n - Kill_n)$$

$$In_n = PavIn_n \cap \left(AntGen_n \cup (Out_n - Kill_n) \right)$$

$$\bigcap_{p \in pred(n)} \left(Out_p \cup AvOut_p \right)$$

$$\forall p \in pred(n),$$

$$In_n \subseteq AvOut_p \cup$$

$$Out_p$$

$$Out_n = \begin{cases} BI & n \text{ is End block} \\ \bigcap_{s \in succ(n)} In_s & \text{otherwise} \end{cases}$$

$$In_n \subseteq PavIn_n$$

Expressions should be hoisted to the exit of a block if they can be hoisted to the entry of all successors

From Hoisting Criteria to Data Flow Equations (3)

$$\forall s \in succ(n),$$

$$Out_n \subseteq In_s$$

$$In_n \subseteq AntGen_n \cup$$

$$(Out_n - Kill_n)$$

$$In_n = PavIn_n \cap \left(AntGen_n \cup (Out_n - Kill_n) \right)$$

$$\bigcap_{p \in pred(n)} \left(Out_p \cup AvOut_p \right)$$

$$\forall p \in pred(n),$$

$$In_n \subseteq AvOut_p \cup$$

$$Out_p$$

$$Out_n = \begin{cases} BI & n \text{ is End block} \\ \bigcap_{s \in succ(n)} In_s & \text{otherwise} \end{cases}$$

$$In_n \subseteq PavIn_n$$

Anticipability and PRE (Hoistability) Data Flow Equations

| PRE Hoistability | Anticipability |
|--|--|
| $In_n = PavIn_n \cap (AntGen_n \cup (Out_n - Kill_n))$ $\bigcap_{p \in pred(n)} (Out_p \cup AvOut_p)$ $Out_n = \begin{cases} BI & n \text{ is End block} \\ \bigcap_{s \in succ(n)} In_s & \text{otherwise} \end{cases}$ | $In_n = AntGen_n \cup (Out_n - Kill_n)$ $Out_n = \begin{cases} BI & n \text{ is End block} \\ \bigcap_{s \in succ(n)} In_s & \text{otherwise} \end{cases}$ |

PRE Hoistability is anticipability restricted by

- safety of hoisting and
- partial availability

Deletion Criteria in PRE

- An expression is redundant in node n if
 - ▶ it can be placed at the entry (i.e. can be "hoisted" out) of n , AND
 - ▶ it is upwards exposed in node n .

$$Redundant_n = In_n \cap AntGen_n$$

- A hoisting path for an expression e begins at n if $e \in Redundant_n$
- This hoisting path extends against the control flow.

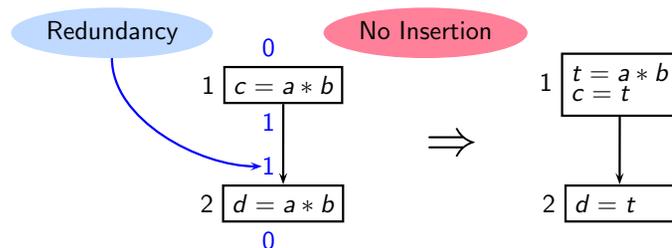
Insertion Criteria in PRE

- An expression is inserted at the exit of node n is
 - ▶ it can be placed at the exit of n , AND
 - ▶ it is not available at the exit of n , AND
 - ▶ it cannot be hoisted out of n , OR it is modified in n .

$$Insert_n = Out_n \cap (\neg AvOut_n) \cap (\neg In_n \cup Kill_n)$$

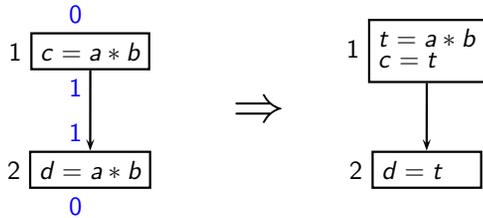
- A hoisting path for an expression e ends at n if $e \in Insert_n$

Performing PRE by Computing In/Out: Simple Cases (1)

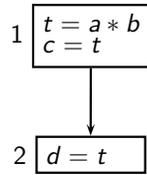


| Node | First Level Values | | | | Init. | | Iter. 1 | | Iter. 2 | | Redund. | Insert |
|------|--------------------|------|-------|-------|-------|----|---------|----|---------|----|---------|--------|
| | AntGen | Kill | PavIn | AvOut | Out | In | Out | In | Out | In | | |
| 2 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | 1 | 0 |
| 1 | 1 | 0 | 0 | 1 | 1 | 1 | 1 | 0 | 1 | 0 | 0 | 0 |

Performing PRE by Computing In/Out: Simple Cases (1)



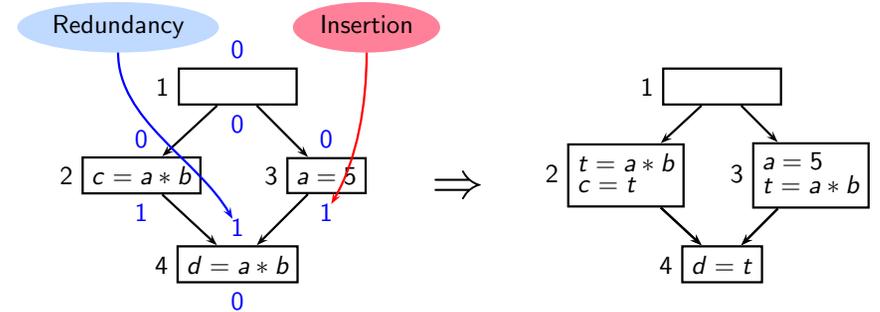
⇒



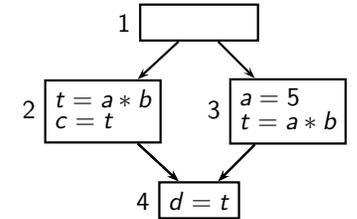
This is an instance of Common Subexpression Elimination



Performing PRE by Computing In/Out: Simple Cases (2)



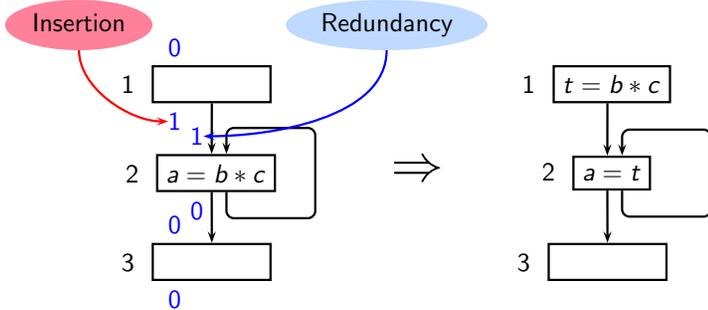
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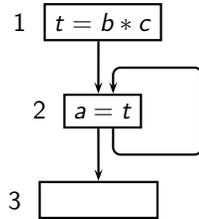
| Node | First Level Values | | | | Init. | | Iter. 1 | | Iter. 2 | | Redund. | Insert |
|------|--------------------|------|-------|-------|-------|----|---------|----|---------|----|---------|--------|
| | AntGen | Kill | PavIn | AvOut | Out | In | Out | In | Out | In | | |
| 4 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | 1 | 0 |
| 3 | 0 | 1 | 0 | 0 | 1 | 1 | 1 | 0 | 1 | 0 | 0 | 1 |
| 2 | 1 | 0 | 0 | 1 | 1 | 1 | 1 | 0 | 1 | 0 | 0 | 0 |
| 1 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 |



Performing PRE by Computing In/Out: Simple Cases (3)



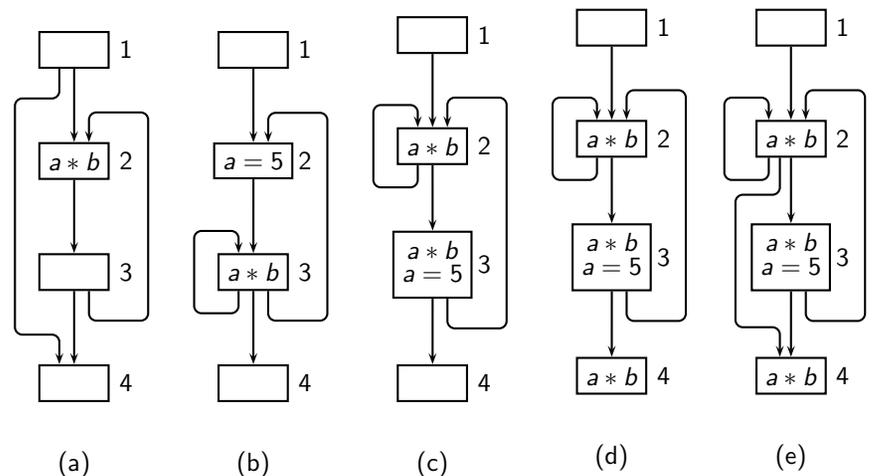
⇒



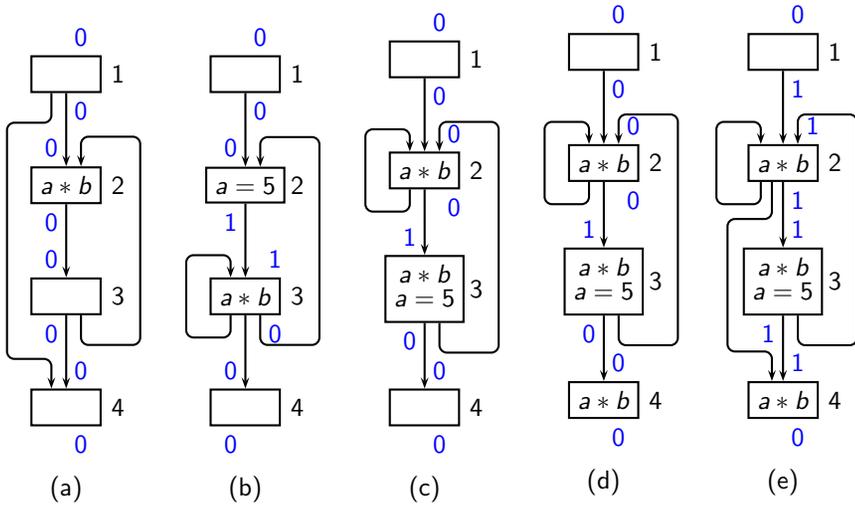
| Node | First Level Values | | | | Init. | | Iter. 1 | | Iter. 2 | | Redund. | Insert |
|------|--------------------|------|-------|-------|-------|----|---------|----|---------|----|---------|--------|
| | AntGen | Kill | PavIn | AvOut | Out | In | Out | In | Out | In | | |
| 3 | 0 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 |
| 2 | 1 | 0 | 1 | 1 | 1 | 1 | 0 | 1 | 0 | 1 | 1 | 0 |
| 1 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 0 | 1 | 0 | 0 | 1 |



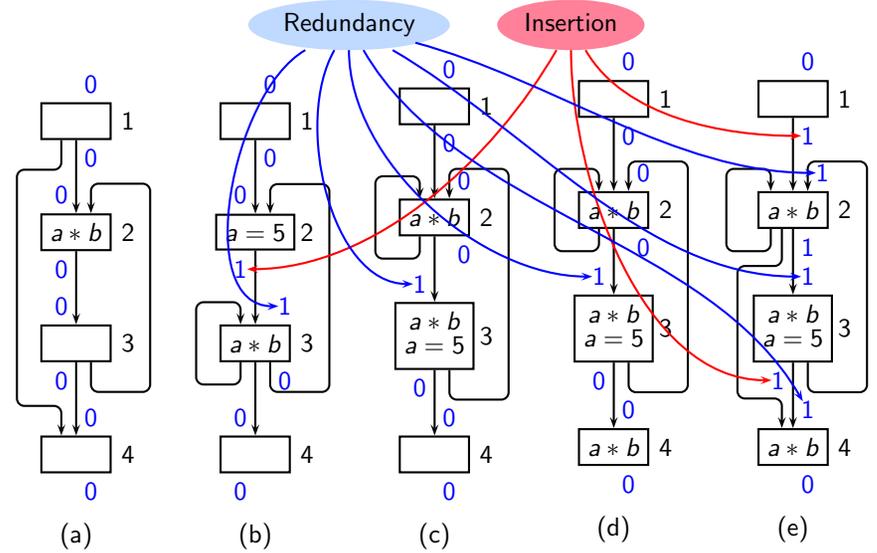
Tutorial Problems for PRE



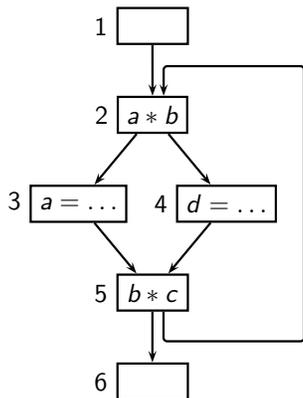
Tutorial Problems for PRE



Tutorial Problems for PRE



Further Tutorial Problem for PRE



Let $\{a * b, b * c\} \equiv$ bit string 11

| Node n | $Kill_n$ | $AntGen_n$ | $PavIn_n$ | $AvOut_n$ |
|----------|----------|------------|-----------|-----------|
| 1 | 00 | 00 | 00 | 00 |
| 2 | 00 | 10 | 11 | 10 |
| 3 | 10 | 00 | 11 | 00 |
| 4 | 00 | 00 | 11 | 10 |
| 5 | 00 | 01 | 11 | 01 |
| 6 | 00 | 00 | 11 | 01 |

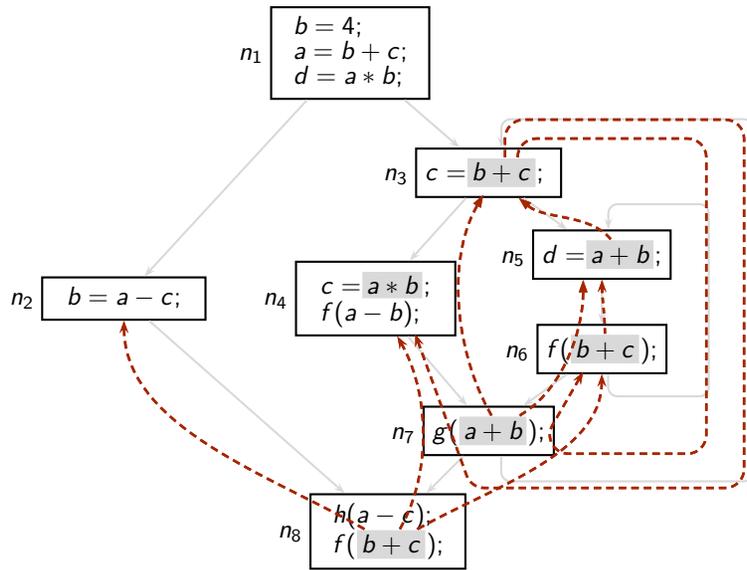
- Compute $In_n/Out_n/Redundant_n/Insert_n$
- Identify hoisting paths

Result of PRE Data Flow Analysis of the Running Example

Bit vector $\{a * b \mid a + b \mid a - b \mid a - c \mid b + c\}$

| Block | Global Information | | | | | | | |
|-------|----------------------|-----------|---------------|--------|--------------------------|--------|--------------------------|--------|
| | Constant information | | Iteration # 1 | | Changes in iteration # 2 | | Changes in iteration # 3 | |
| | $PavIn_n$ | $AvOut_n$ | Out_n | In_n | Out_n | In_n | Out_n | In_n |
| n_8 | 11111 | 00011 | 00000 | 00011 | | | | 00001 |
| n_7 | 11101 | 11000 | 00011 | 01001 | 00001 | | | |
| n_6 | 11101 | 11001 | 01001 | 01001 | | | 01000 | |
| n_5 | 11101 | 11000 | 01001 | 01001 | | 01000 | | |
| n_4 | 11100 | 10100 | 01001 | 11100 | | 11000 | | |
| n_3 | 11101 | 10000 | 01000 | 01001 | | 00001 | | |
| n_2 | 10001 | 00010 | 00011 | 00000 | | | 00001 | |
| n_1 | 00000 | 10001 | 00000 | 00000 | | | | |

Hoisting Paths for Some Expressions in the Running Example



Optimized Version of the Running Example

