

Theoretical Abstractions in Data Flow Analysis

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Part 1

About These Slides

CS 618

DFA Theory: About These Slides

1/126

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These slides constitute the lecture notes for CS618 Program Analysis course at IIT Bombay and have been made available as teaching material accompanying the book:

- Uday Khedker, Amitabha Sanyal, and Bageshri Karkare. *Data Flow Analysis: Theory and Practice*. CRC Press (Taylor and Francis Group). 2009.
(Indian edition published by Ane Books in 2013)

Apart from the above book, some slides are based on the material from the following books

- M. S. Hecht. *Flow Analysis of Computer Programs*. Elsevier North-Holland Inc. 1977.
- F. Nielson, H. R. Nielson, and C. Hankin. *Principles of Program Analysis*. Springer-Verlag. 1998.

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DFA Theory: Outline

2/126

Outline

- The need for a more general setting
- The set of data flow values
- The set of flow functions
- Solutions of data flow analyses
- Algorithms for performing data flow analysis
- Complexity of data flow analysis

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Part 2

The Need for a More General Setting

What We Have Seen So Far ...

Analysis	Entity	Attribute at p	Paths
Live variables	Variables	Use	Starting at p Some
Available expressions	Expressions	Availability	Reaching p All
Partially available expressions	Expressions	Availability	Reaching p Some
Anticipable expressions	Expressions	Use	Starting at p All
Reaching definitions	Definitions	Availability	Reaching p Some
Partial redundancy elimination	Expressions	Profitable hoistability	Involving p All



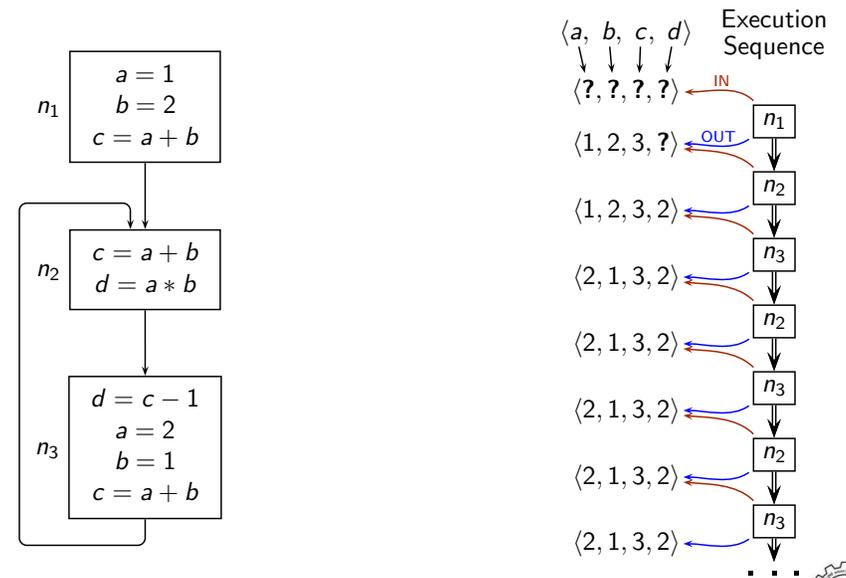
The Need for a More General Setting

- We seem to have covered many variations
- Yet there are analyses that do not fit the same mould of bit vector frameworks
- We use an analysis called *Constant Propagation* to observe the differences

A variable v is a constant with value c at program point p if in every execution instance of p , the value of v is c

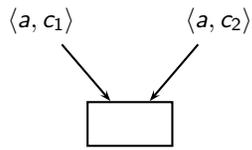


An Introduction to Constant Propagation



Difference #3: Confluence Operation

- Confluence operation $\langle a, c_1 \rangle \sqcap \langle a, c_2 \rangle$



\sqcap	$\langle a, ? \rangle$	$\langle a, \times \rangle$	$\langle a, c_1 \rangle$
$\langle a, ? \rangle$	$\langle a, ? \rangle$	$\langle a, \times \rangle$	$\langle a, c_1 \rangle$
$\langle a, \times \rangle$			
$\langle a, c_2 \rangle$	$\langle a, c_2 \rangle$	$\langle a, \times \rangle$	If $c_1 = c_2$ $\langle a, c_1 \rangle$ Otherwise $\langle a, \times \rangle$

- This is neither \cap nor \cup

What are its properties?

Difference #4: Flow Functions for Constant Propagation

- Flow function for $r = a_1 * a_2$

$\langle a_1, c_1 \rangle, \langle a_2, c_2 \rangle$
 \downarrow
 $r = a_1 * a_2$

<i>mult</i>	$\langle a_1, ? \rangle$	$\langle a_1, \times \rangle$	$\langle a_1, c_1 \rangle$
$\langle a_2, ? \rangle$	$\langle r, ? \rangle$	$\langle r, \times \rangle$	$\langle r, ? \rangle$
$\langle a_2, \times \rangle$	$\langle r, \times \rangle$	$\langle r, \times \rangle$	$\langle r, \times \rangle$
$\langle a_2, c_2 \rangle$	$\langle r, ? \rangle$	$\langle r, \times \rangle$	$\langle r, (c_1 * c_2) \rangle$

- This cannot be expressed in the form

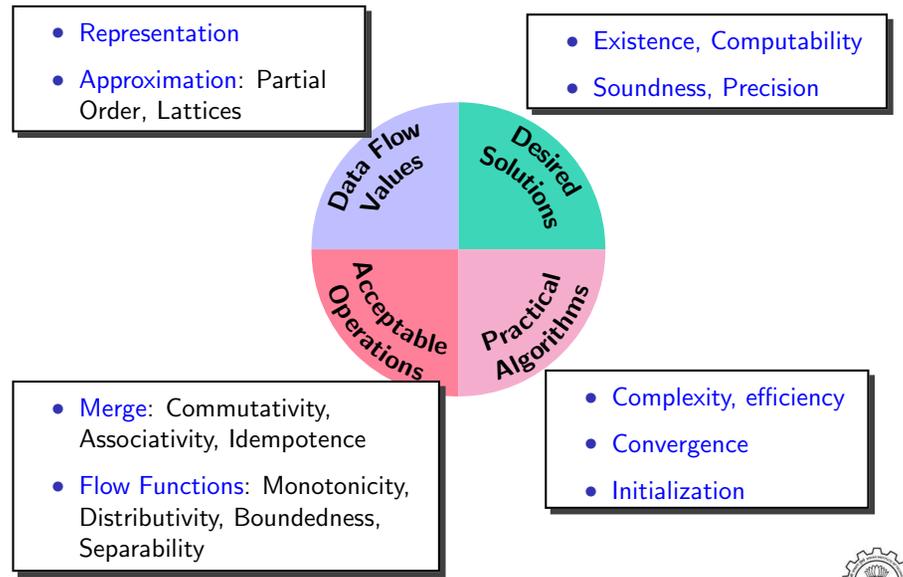
$$f_n(X) = \text{Gen}_n \cup (X - \text{Kill}_n)$$

where Gen_n and Kill_n are constant effects of block n

Difference #5: Solution Computed by Iterative Method

	Iteration #1	Iteration #2	Iteration #3	Desired solution
n_1	$\langle ?, ?, ?, ? \rangle$	$\langle ?, ?, ?, ? \rangle$	$\langle ?, ?, ?, ? \rangle$	$\langle ?, ?, ?, ? \rangle$
n_2	$\langle 1, 2, 3, ? \rangle$	$\langle 1, 2, 3, ? \rangle$	$\langle 1, 2, 3, ? \rangle$	$\langle 1, 2, 3, ? \rangle$
n_3	$\langle 1, 2, 3, ? \rangle$	$\langle \times, \times, 3, 2 \rangle$	$\langle \times, \times, 3, \times \rangle$	$\langle \times, \times, 3, 2 \rangle$
	$\langle 1, 2, 3, 2 \rangle$	$\langle \times, \times, \times, \times \rangle$	$\langle \times, \times, \times, \times \rangle$	$\langle \times, \times, 3, 2 \rangle$
	$\langle 1, 2, 3, 2 \rangle$	$\langle \times, \times, \times, \times \rangle$	$\langle \times, \times, \times, \times \rangle$	$\langle \times, \times, 3, 2 \rangle$
	$\langle 2, 1, 3, 2 \rangle$	$\langle 2, 1, 3, \times \rangle$	$\langle 2, 1, 3, \times \rangle$	$\langle 2, 1, 3, 2 \rangle$

Issues in Data Flow Analysis



Part 3

Data Flow Values: An Overview

Data Flow Values: An Outline of Our Discussion

- The need to define the notion of abstraction
- Lattices, variants of lattices
- Relevance of lattices for data flow analysis
 - ▶ Partial order relation as approximation of data flow values
 - ▶ Meet operations as confluence of data flow values
- Constructing lattices
- Example of lattices



Part 4

A Digression on Lattices

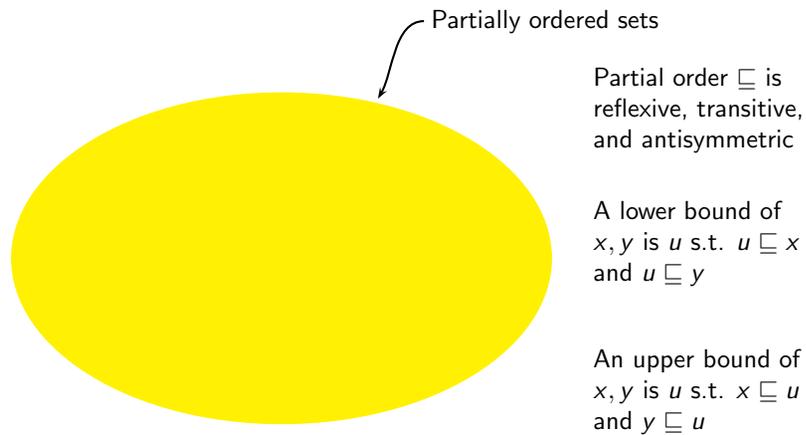
Partially Ordered Sets

Sets in which elements can be compared and ordered

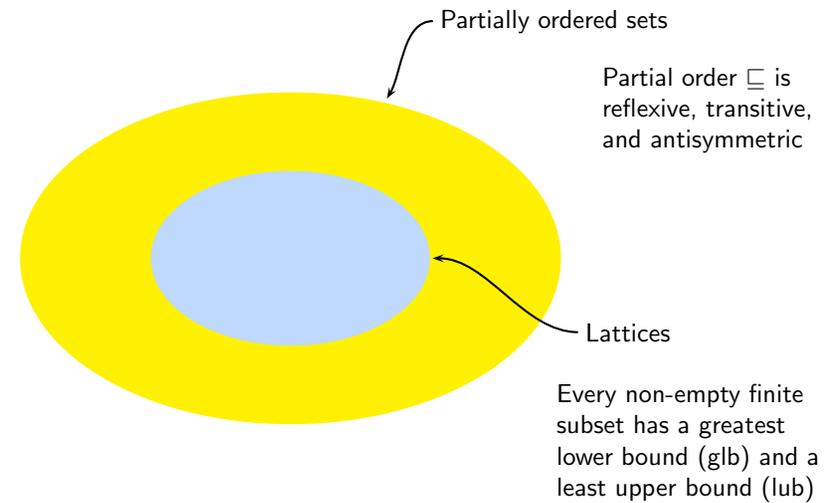
- *Total order*. Every element is comparable with every element (including itself)
- *Discrete order*. Every element is comparable only with itself but not with any other element
- *Partial order*. An element is comparable with some but not necessarily all elements



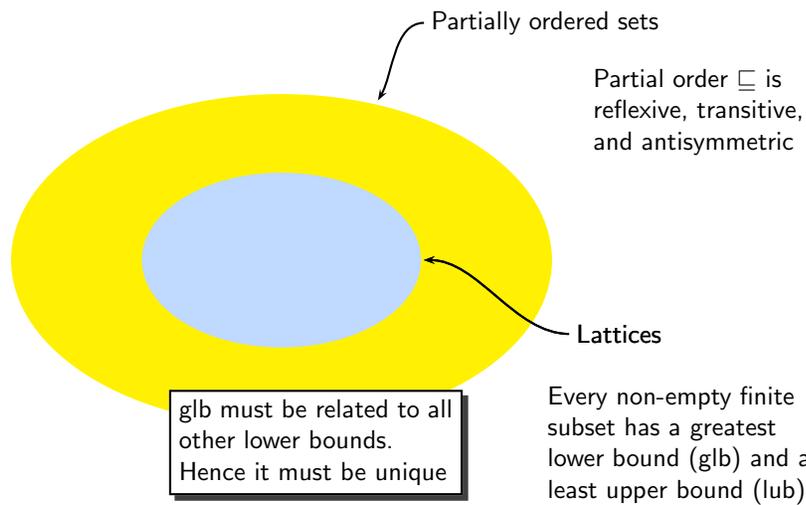
Partially Ordered Sets and Lattices



Partially Ordered Sets and Lattices

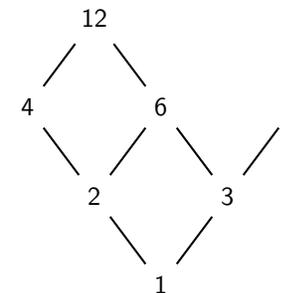


Partially Ordered Sets and Lattices



Partially Ordered Sets

Set $\{1, 2, 3, 4, 6, 9, 12\}$ with \sqsubseteq relation as "divides" (i.e. $a \sqsubseteq b$ iff a divides b)

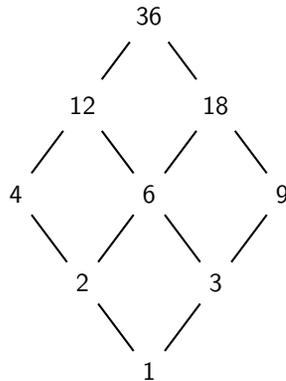


Subset $\{4, 9, 6\}$ and $\{12, 9\}$ do not have an upper bound in the set



Lattice

Set $\{1, 2, 3, 4, 6, 9, 12, 18, 36\}$ with \sqsubseteq relation as “divides”



Complete Lattice

- Lattice: A partially ordered set such that every non-empty finite subset has a glb and a lub

Example: Lattice \mathbb{Z} of integers under “less-than-equal-to” (\leq) relation

- All finite subsets have a glb and a lub
- Infinite subsets do not have a glb or a lub

- Complete Lattice: A lattice in which even \emptyset and infinite subsets have a glb and a lub

Example: Lattice \mathbb{Z} of integers under \leq relation with ∞ and $-\infty$

- ∞ is the **top** element denoted \top : $\forall i \in \mathbb{Z}, i \leq \top$
- $-\infty$ is the **bottom** element denoted \perp : $\forall i \in \mathbb{Z}, \perp \leq i$



$\mathbb{Z} \cup \{\infty, -\infty\}$ is a Complete Lattice

- Infinite subsets of $\mathbb{Z} \cup \{\infty, -\infty\}$ have a glb and lub
- What about the empty set?
 - glb(\emptyset) is \top
Every element of $\mathbb{Z} \cup \{\infty, -\infty\}$ is vacuously a lower bound of an element in \emptyset
OR
Every element in \emptyset is stronger than every element in $\mathbb{Z} \cup \{\infty, -\infty\}$ (because there is no element in \emptyset)
The greatest among these lower bounds is \top
 - lub(\emptyset) is \perp

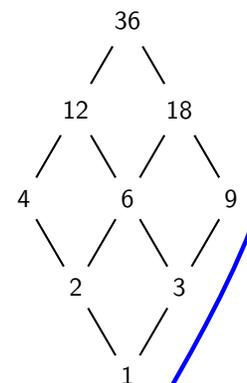


Operations on Lattices

- Meet (\sqcap) and Join (\sqcup)
 - $x \sqcap y$ computes the glb of x and y
 $z = x \sqcap y \Rightarrow z \sqsubseteq x \wedge z \sqsubseteq y$
 - $x \sqcup y$ computes the lub of x and y
 $z = x \sqcup y \Rightarrow z \supseteq x \wedge z \supseteq y$
 - \sqcap and \sqcup are commutative, associative, and idempotent
- Top (\top) and Bottom (\perp) elements

$$\begin{aligned} \forall x \in L, x \sqcap \top &= x \\ \forall x \in L, x \sqcup \top &= \top \\ \forall x \in L, x \sqcap \perp &= \perp \\ \forall x \in L, x \sqcup \perp &= x \end{aligned}$$

Greatest common divisor



$$x \sqcap y = \gcd(x, y)$$

Lowest common multiple

$$x \sqcup y = \text{lcm}(x, y)$$



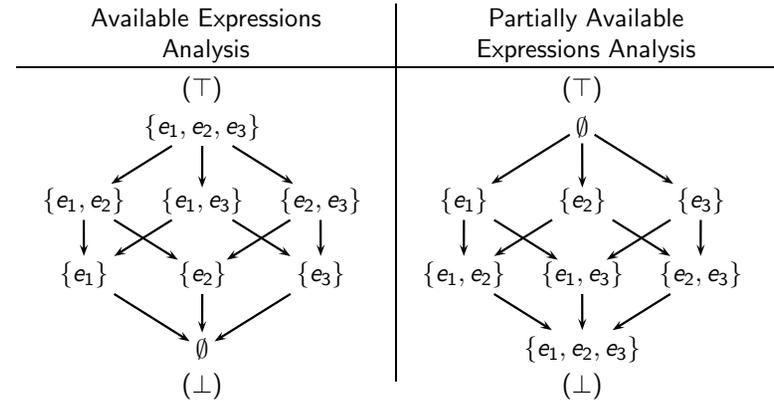
Partial Order and Operations

- For a lattice \sqsubseteq induces \sqcap and \sqcup and vice-versa
- The choices of \sqsubseteq , \sqcap , and \sqcup cannot be arbitrary
They have to be
 - ▶ consistent with each other, and
 - ▶ definable in terms of each other
- For some variants of lattices, \sqcap or \sqcup may not exist
Yet the requirement of its consistency with \sqsubseteq cannot be violated



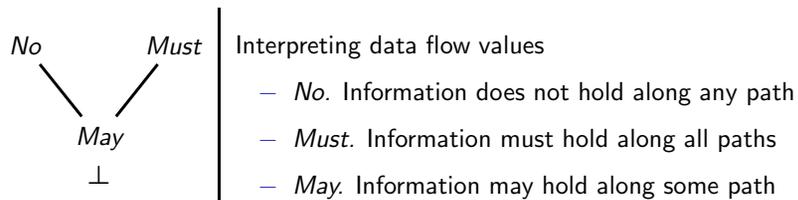
Finite Lattices are Complete

- Any given set of elements has a glb and a lub



Lattice for May-Must Analysis

- There is no \top among the natural values



- An artificial \top can be added



Some Variants of Lattices

A poset L is

- A **lattice** iff each non-empty finite subset of L has a glb and lub
- A **complete lattice** iff each subset of L has a glb and lub
- A **meet semilattice** iff each non-empty finite subset of L has a glb
- A **join semilattice** iff each non-empty finite subset of L has a lub
- A **bounded lattice** iff L is a lattice and has \top and \perp elements



A Bounded Lattice Need Not be Complete (1)

- Let A be all finite subsets of \mathbb{Z}
Then, A is an infinite set
- The poset $L = (A \cup \{\mathbb{Z}\}, \subseteq)$ is a bounded lattice with $\top = \mathbb{Z}$ and $\perp = \emptyset$
The join \sqcup of this lattice is \cup
- To see why, consider a set S containing those subsets of L that do not contain the number 1
There are two possibilities:
 - ▶ S contains only a finite number of sets that not contain 1 (say S_f)
 $\Rightarrow S_f$ is a finite set
 - ▶ S contains *all* finite sets that do not contain 1 (say S_∞)
 $\Rightarrow S_\infty$ is an infinite set

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A Bounded Lattice Need Not be Complete (2)

- S_f contains only a finite number of sets each of which does not contain 1
 - ▶ The union of all its member sets is a finite set excluding 1
 - ▶ Thus S_f has a lub in L
- S_∞ contains *all* finite sets that do not contain 1
 - ▶ Since the number of such sets is infinite, their union is an infinite set
 - ▶ $\mathbb{Z} - \{1\}$ is not contained in L (the only infinite set in L is \mathbb{Z})
 - ▶ S_∞ does not have a lub in L

Hence L is not complete

A Bounded Lattice Need Not be Complete (2)

- S_f contains only a finite number of sets each of which does not contain 1
 - ▶ It may be tempting to assume that \mathbb{Z} is the lub of S_∞ because it is an upper bound of S_∞ and no other upper bound of S_∞ in the lattice is weaker \mathbb{Z}
 - ▶ However, the join operation \cup of L does not compute \mathbb{Z} as the lub of S_∞ (because it must exclude 1)
 - ▶ The join operation \cup is inconsistent with the partial order \supseteq of L . Hence we say that join does not exist for S_∞

A Bounded Lattice Need Not be Complete (2)

- A bounded lattice L has a glb and lub of L in L
- A complete lattice L should have glb and lub of *all* subsets of L
- A lattice L should have glb and lub of *all* finite non-empty subsets of L



Ascending and Descending Chains

- Strictly ascending chain $x \sqsubset y \sqsubset \dots \sqsubset z$
- Strictly descending chain $x \sqsupset y \sqsupset \dots \sqsupset z$
- **DCC**: Descending Chain Condition
All strictly descending chains are finite
- **ACC**: Ascending Chain Condition
All strictly ascending chains are finite

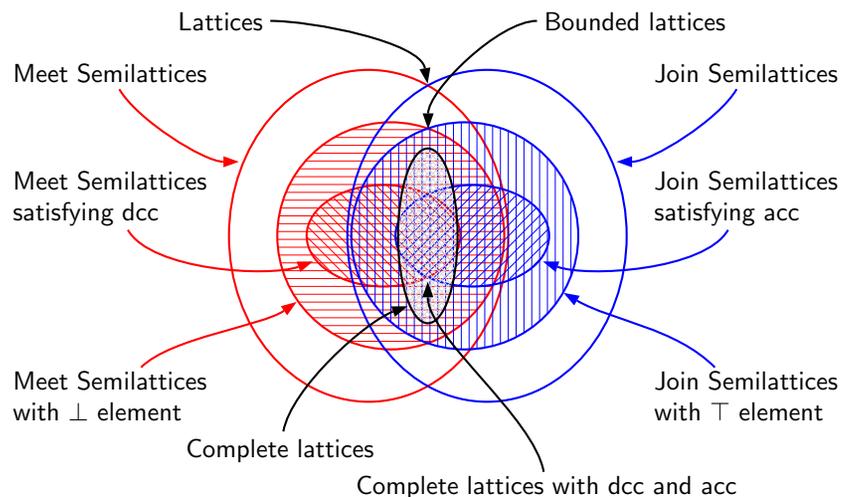


Complete Lattice and Ascending and Descending Chains

- If L satisfies acc and dcc, then
 - ▶ L has finite height, and
 - ▶ L is complete
- A complete lattice need not have finite height (i.e. strict chains may not be finite)
Example:
Lattice of integers under \leq relation with ∞ as \top and $-\infty$ as \perp



Variants of Lattices

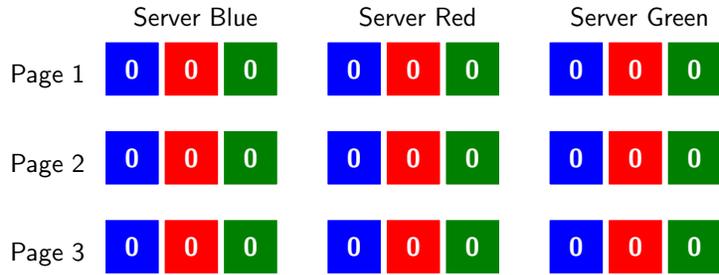


- dcc: descending chain condition
- acc: ascending chain condition

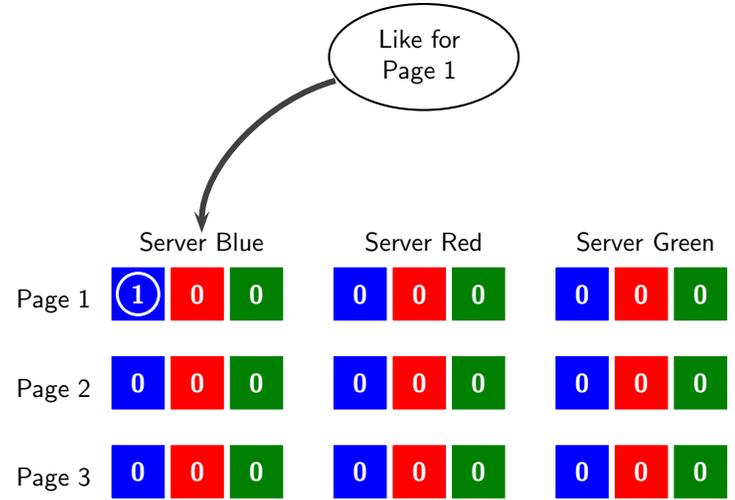


An Example of Lattices: Maintaining Like Counts on Cloud

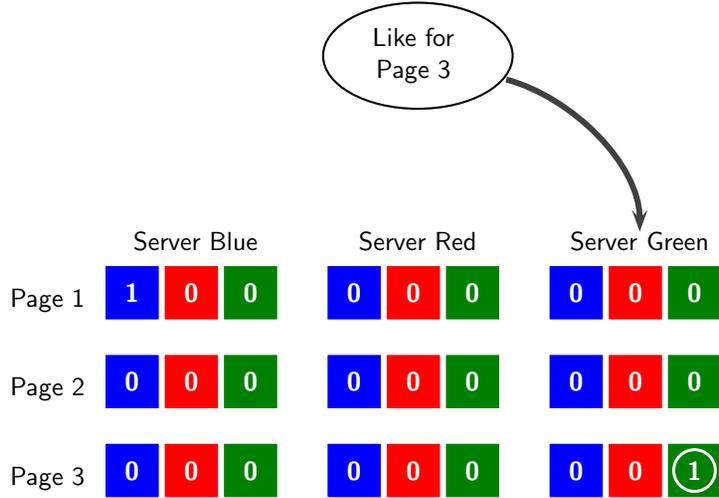
Maintain n servers and divide the traffic
 – Each server maintains an n -tuple for each page
 – Updates the counters for its own slot



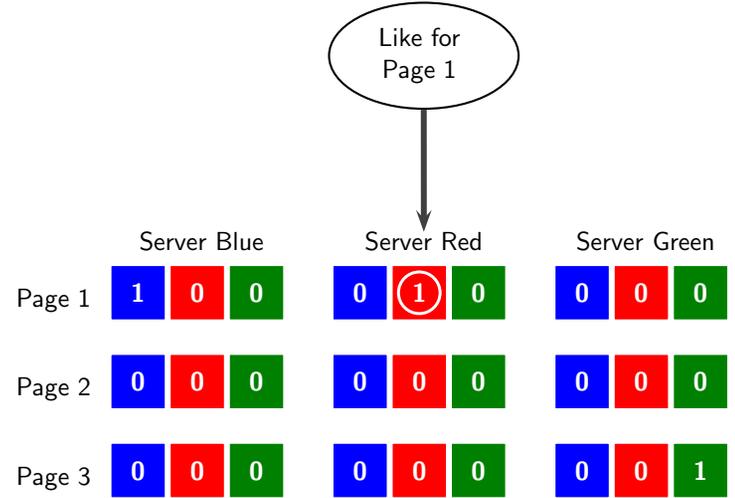
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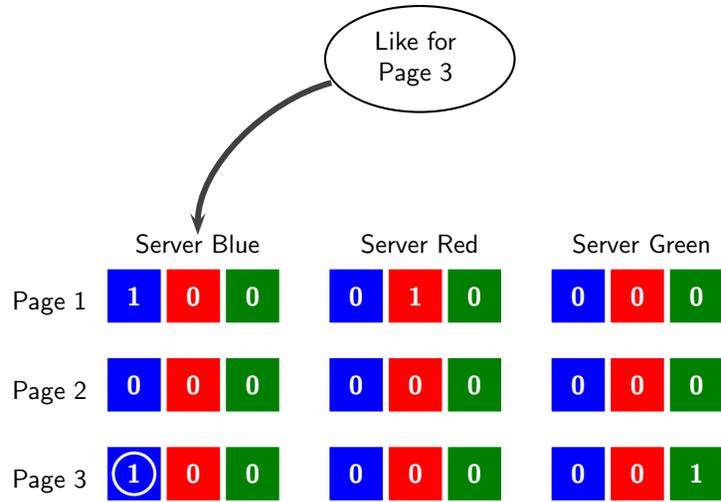
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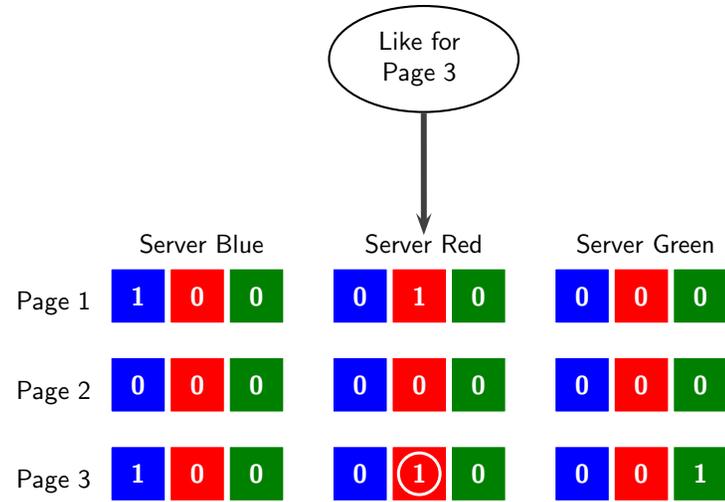
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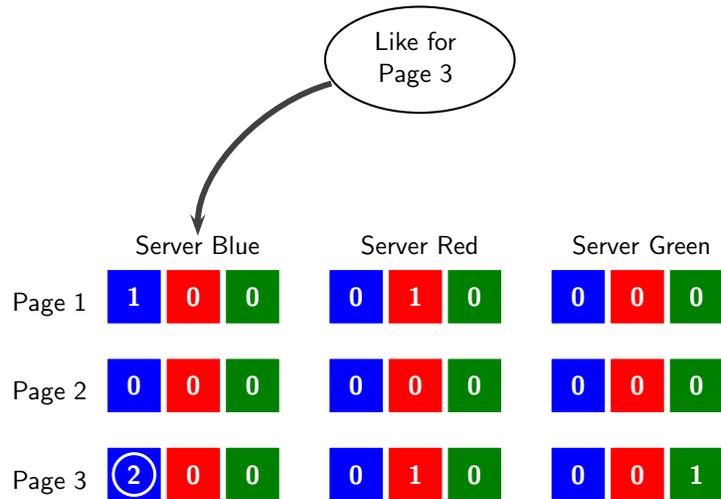
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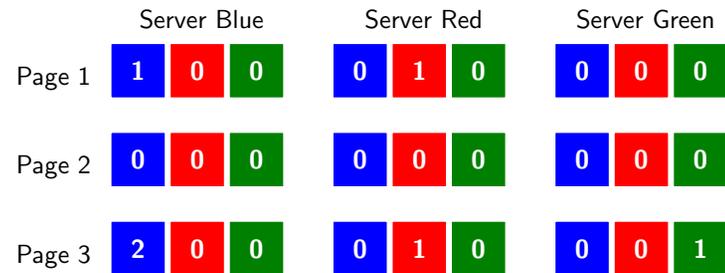


An Example of Lattices: Maintaining Like Counts on Cloud



An Example of Lattices: Maintaining Like Counts on Cloud

Synchronize:
 - Send the data to other servers
 - Update the counters using point-wise max



An Example of Lattices: Maintaining Like Counts on Cloud

Synchronize:
 - Send the data to other servers
 - Update the counters using point-wise max

- Lattice of n -tuples using point-wise \geq as the partial order

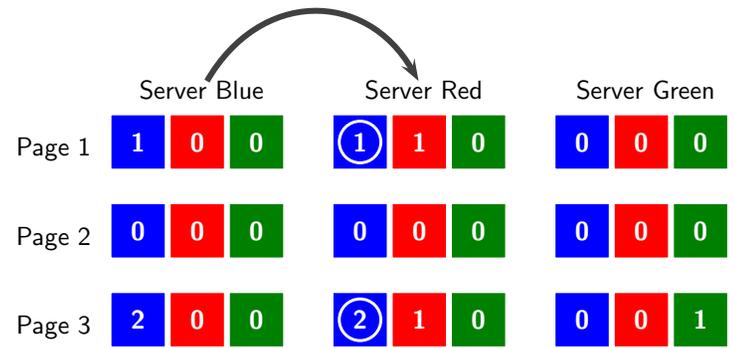
$$\langle x_1, x_2, \dots, x_n \rangle \sqsubseteq \langle y_1, y_2, \dots, y_n \rangle = (x_1 \geq y_1) \wedge (x_2 \geq y_2) \dots \wedge (x_n \geq y_n)$$

- Tuples merged with max operation

$$\langle x_1, x_2, \dots, x_n \rangle \sqcap \langle y_1, y_2, \dots, y_n \rangle = \langle \max(x_1, y_1), \max(x_2, y_2), \dots, \max(x_n, y_n) \rangle$$

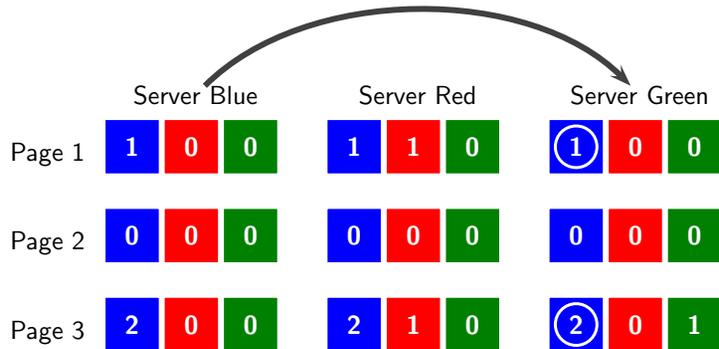
An Example of Lattices: Maintaining Like Counts on Cloud

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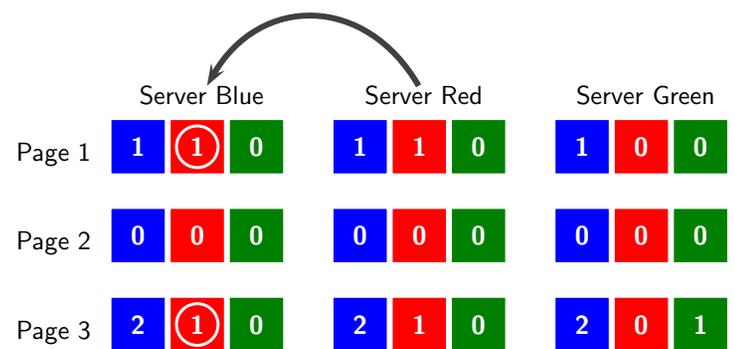
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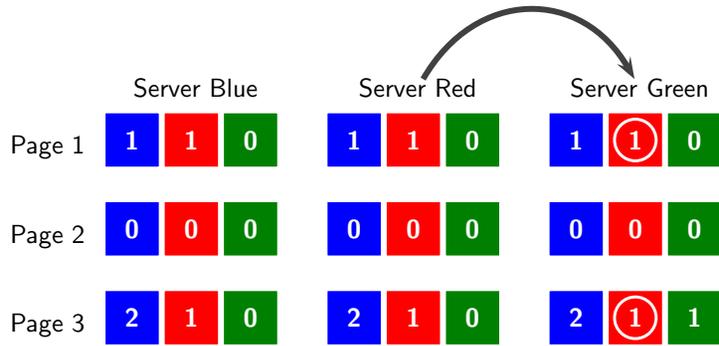
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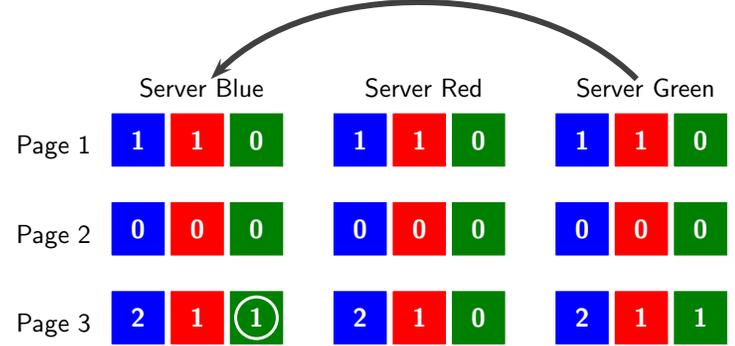
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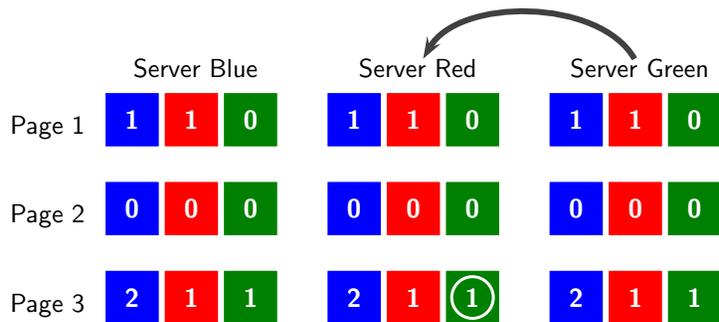
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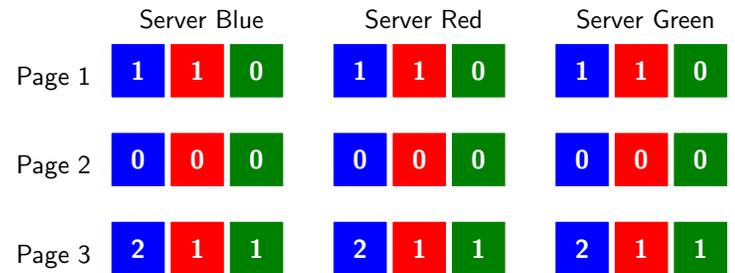
An Example of Lattices: Maintaining Like Counts on Cloud

Synchronize:
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An Example of Lattices: Maintaining Like Counts on Cloud

After synchronization, all servers have the same data Count for a page:
 - Take sum of all counts at any server for the page

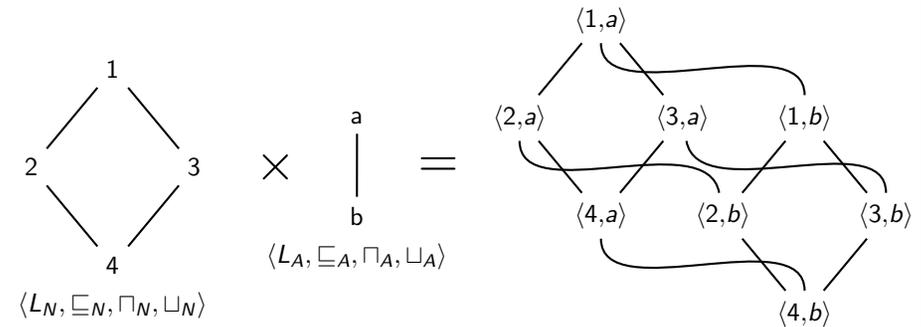


Constructing Lattices

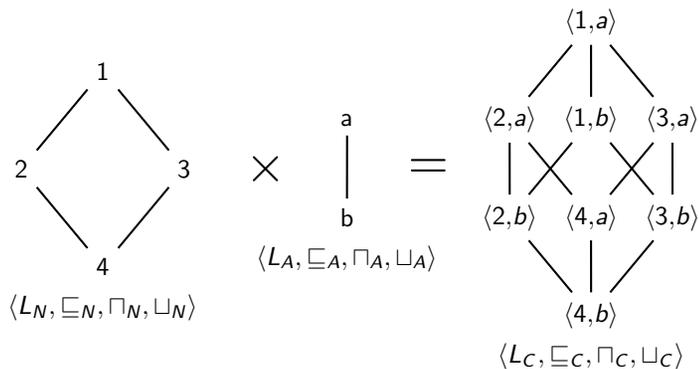
- Powerset construction with subset or superset relation
- Products of lattices
 - ▶ Cartesian product
 - ▶ Lexicographic product
 - ▶ Interval product
 - ▶ Set of mappings
- Lattices on sequences using prefix or suffix as partial orders



Cartesian Product of Lattice



Cartesian Product of Lattice



$$\langle x_1, y_1 \rangle \sqsubseteq_C \langle x_2, y_2 \rangle \Leftrightarrow x_1 \sqsubseteq_N x_2 \wedge y_1 \sqsubseteq_A y_2$$

$$\langle x_1, y_1 \rangle \sqcap_C \langle x_2, y_2 \rangle = \langle x_1 \sqcap_N x_2, y_1 \sqcap_A y_2 \rangle$$

$$\langle x_1, y_1 \rangle \sqcup_C \langle x_2, y_2 \rangle = \langle x_1 \sqcup_N x_2, y_1 \sqcup_A y_2 \rangle$$



Example of Cartesian Product: Concept Lattices

- **Context of concepts.** A collection of objects and their attributes
- **Concepts.** Sets of attributes as exhibited by specific objects
 - ▶ A concept C is a pair (O, A) where
 - O is a set of objects exhibiting attributes in the set A
 - ▶ Every object in O has every attribute in A
- **Partial order.** $(O_2, A_2) \sqsubseteq (O_1, A_1) \Leftrightarrow O_2 \subseteq O_1$
 - ▶ Very few objects have all properties
 - ▶ Since A is the set of attributes common to all objects in O ,

$$O_2 \subseteq O_1 \Rightarrow A_2 \supseteq A_1$$

As the number of chosen objects decreases, the number of common attributes increases

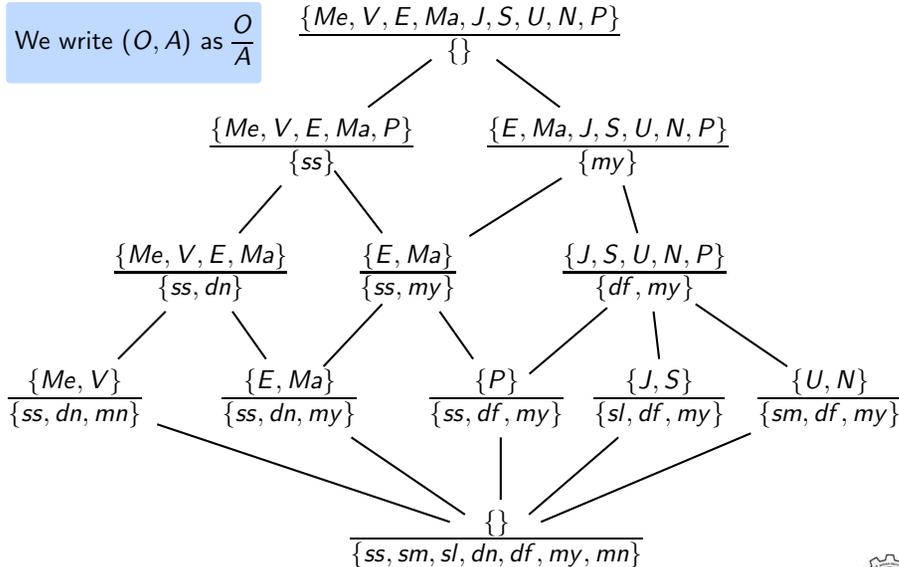


Example of Concept Lattice (1)

From *Introduction to Lattices and Order* by Davey and Priestley [2002]

		Size			Distance from Sun		Moon?	
		Small (ss)	Medium (sm)	Large (sl)	Near (dn)	Far (df)	Yes (my)	No (mn)
Mercury	Me	x			x			x
Venus	V	x			x			x
Earth	E	x			x		x	
Mars	Ma	x			x		x	
Jupiter	J			x		x	x	
Saturn	S			x		x	x	
Uranus	U		x			x	x	
Neptune	N		x			x	x	
Pluto	P	x				x	x	

Example of Concept Lattice (2)



Variants of Products

In each case $L \subseteq L_1 \times L_2$

- Cartesian Product

$$(x_1, x_2) \sqsubseteq (y_1, y_2) \text{ iff } x_1 \sqsubseteq_1 y_1 \wedge x_2 \sqsubseteq_2 y_2$$

- Interval Product

$$(x_1, x_2) \sqsubseteq (y_1, y_2) \text{ iff } x_1 \sqsubseteq_1 y_1 \wedge y_2 \sqsubseteq_2 x_2$$

- Lexicographic Product

$$(x_1, x_2) \sqsubseteq (y_1, y_2) \text{ iff } (x_1 \sqsubset_1 y_1) \vee (x_1 = y_1 \wedge x_2 \sqsubseteq_2 y_2)$$

- Set of mappings $L_1 \rightarrow L_2$

$$(x_1, x_2) \sqsubseteq (y_1, y_2) \text{ iff } x_1 = y_1 \wedge x_2 \sqsubseteq_2 y_2$$

Part 5

Data Flow Values: Details

The Set of Data Flow Values

Meet semilattices satisfying the descending chain condition

- Requirement: glb must exist for all non-empty finite subsets
- Corollary: \perp must exist

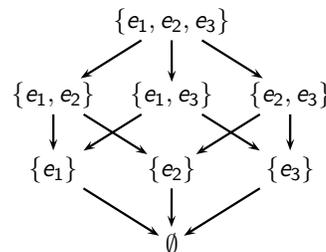
What guarantees the presence of \perp ?

- ▶ Assume that two maximal descending chains terminate at two incomparable elements x_1 and x_2
- ▶ Since this is a meet semilattice, glb of $\{x_1, x_2\}$ must exist (say z)
 - ⇒ Neither of the chains is maximal
 - Both of them can be extended to include z
- ▶ Extending this argument to all strictly descending chains, it is easy to see that \perp must exist
- \top may not exist. Can be added artificially
 - ▶ lub of arbitrary elements may not exist

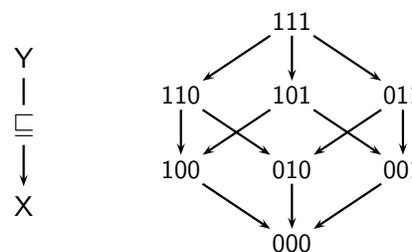


The Set of Data Flow Values For Available Expressions Analysis

- The powerset of the universal set of expressions
- Partial order is the subset relation



Set View of the Lattice



Bit Vector View

Y
|
⊆
↓
X



The Concept of Approximation

- x approximates y iff
 - x can be used in place of y without causing any problems
- Validity of approximation is context specific
 - x may be approximated by y in one context and by z in another
 - ▶ Approximating Money
 - Earnings : Rs. 1050 can be safely approximated by Rs. 1000
 - Expenses : Rs. 1050 can be safely approximated by Rs. 1100
 - ▶ Approximating Time
 - Travel time: 2 hours required can be safely approximated by 3 hours
 - Study time: 3 available days can be safely assumed to be only 2 days



Two Important Objectives in Data Flow Analysis

- The discovered data flow information should be
 - ▶ *Exhaustive*. No optimization opportunity should be missed
 - ▶ *Safe*. Optimizations which do not preserve semantics should not be enabled
- Conservative approximations of these objectives are allowed
- The intended use of data flow information (\equiv context) determines validity of approximations



Context Determines the Validity of Approximations

Will not do incorrect optimization
May prohibit correct optimization

Will not miss any correct optimization
May enable incorrect optimization

Analysis	Application	Safe Approximation	Exhaustive Approximation
Live variables	Dead code elimination	A dead variable is considered live	A live variable is considered dead
Available expressions	Common subexpression elimination	An available expression is considered non-available	A non-available expression is considered available

Spurious Inclusion (blue arrow from Safe to Exhaustive)

Spurious Exclusion (red arrow from Exhaustive to Safe)

Partial Order Captures Approximation

- \sqsubseteq captures valid approximations for **safety**
 - $x \sqsubseteq y \Rightarrow x$ is *weaker than* y
 - The data flow information represented by x can be safely used in place of the data flow information represented by y
 - It may be imprecise, though
- \sqsupseteq captures valid approximations for **exhaustiveness**
 - $x \sqsupseteq y \Rightarrow x$ is *stronger than* y
 - The data flow information represented by x contains every value contained in the data flow information represented by y
 - $x \sqcap y$ will not compute a value weaker than y
 - It may be unsafe, though

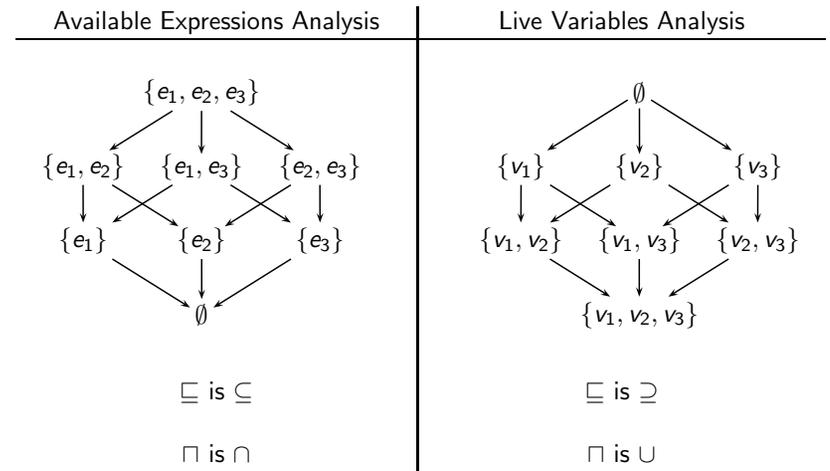
We want most exhaustive information which is also safe

Most Approximate Values in a Complete Lattice

- Top.** $\forall x \in L, x \sqsubseteq \top$ Exhaustive approximation of all values
 - Using \top in place of any data flow value will never miss out (or rule out) any possible value
 - The consequences may be semantically *unsafe*, or *incorrect*
- Bottom.** $\forall x \in L, \perp \sqsupseteq x$ Safe approximation of all values
 - Using \perp in place of any data flow value will never be *unsafe*, or *incorrect*
 - The consequences may be *undefined* or *useless* because this replacement might miss out valid values

Appropriate orientation chosen by design

Setting Up Lattices



Partial Order Relation

- Reflexive** $x \sqsubseteq x$ x can be safely used in place of x
- Transitive** $x \sqsubseteq y, y \sqsubseteq z \Rightarrow x \sqsubseteq z$ If x can be safely used in place of y and y can be safely used in place of z , then x can be safely used in place of z
- Antisymmetric** $x \sqsubseteq y, y \sqsubseteq x \Leftrightarrow x = y$ If x can be safely used in place of y and y can be safely used in place of x , then x must be same as y



Merging Information

- $x \sqcap y$ computes the *greatest lower bound* of x and y i.e. largest z such that $z \sqsubseteq x$ and $z \sqsubseteq y$

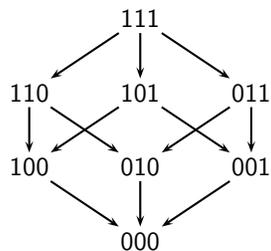
The largest safe approximation of combining data flow information x and y

- Commutative** $x \sqcap y = y \sqcap x$ The order in which the data flow information is merged, does not matter
- Associative** $x \sqcap (y \sqcap z) = (x \sqcap y) \sqcap z$ Allow n-ary merging without any restriction on the order
- Idempotent** $x \sqcap x = x$ No loss of information if x is merged with itself
- \top is the identity of \sqcap
 - Presence of loops \Rightarrow self dependence of data flow information
 - Using \top as the initial value ensure exhaustiveness

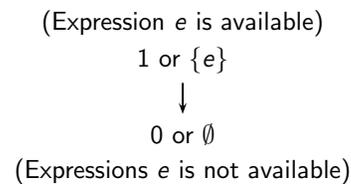


More on Lattices in Data Flow Analysis

L = Lattice for all expressions



\hat{L} = Lattice for a single expression

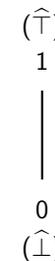


Cartesian products if sets are used, vectors (or tuples) if bit are used

- $L = \hat{L} \times \hat{L} \times \hat{L}$ and $x = \langle \hat{x}_1, \hat{x}_2, \hat{x}_3 \rangle \in L$ where $\hat{x}_i \in \hat{L}$
- $\sqsubseteq = \hat{\sqsubseteq} \times \hat{\sqsubseteq} \times \hat{\sqsubseteq}$ and $\sqcap = \hat{\sqcap} \times \hat{\sqcap} \times \hat{\sqcap}$
- $\top = \hat{\top} \times \hat{\top} \times \hat{\top}$ and $\perp = \hat{\perp} \times \hat{\perp} \times \hat{\perp}$



Component Lattice for Data Flow Information Represented By Bit Vectors



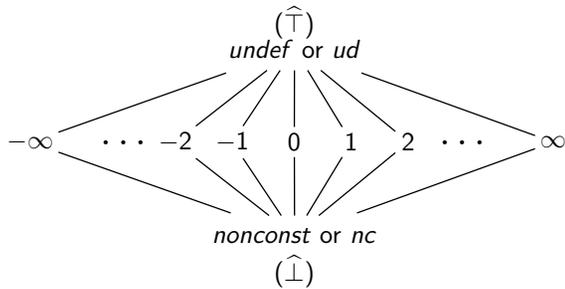
\sqcap is \cap or Boolean AND



\sqcap is \cup or Boolean OR



Component Lattice for Integer Constant Propagation

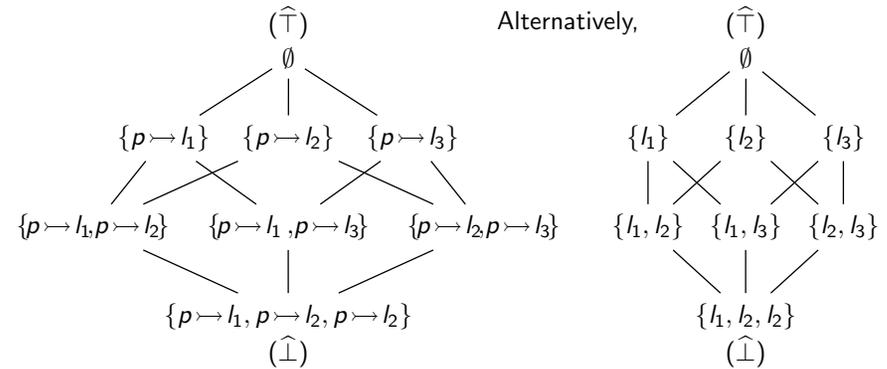


- Overall lattice L is the set of mappings from variables to \hat{L}
- \sqcap and $\hat{\sqcap}$ get defined by \sqsubseteq and $\hat{\sqsubseteq}$

$\hat{\sqcap}$	$\langle a, ud \rangle$	$\langle a, nc \rangle$	$\langle a, c_1 \rangle$
$\langle a, ud \rangle$	$\langle a, ud \rangle$	$\langle a, nc \rangle$	$\langle a, c_1 \rangle$
$\langle a, nc \rangle$	$\langle a, nc \rangle$	$\langle a, nc \rangle$	$\langle a, nc \rangle$
$\langle a, c_2 \rangle$	$\langle a, c_2 \rangle$	$\langle a, nc \rangle$	If $c_1 = c_2$ then $\langle a, c_1 \rangle$ else $\langle a, nc \rangle$

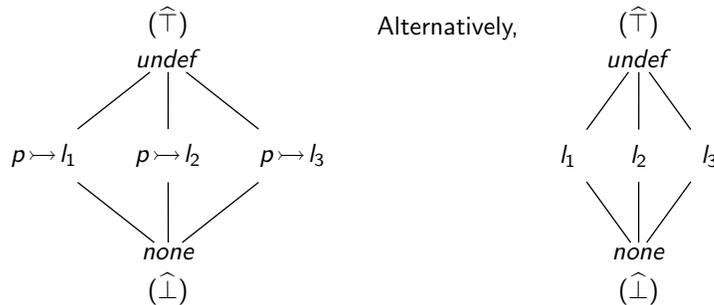
Component Lattice for May Points-To Analysis

- Relation between pointer variables and locations in the memory
- Assuming three locations $l_1, l_2,$ and $l_3,$ the component lattice for pointer p is



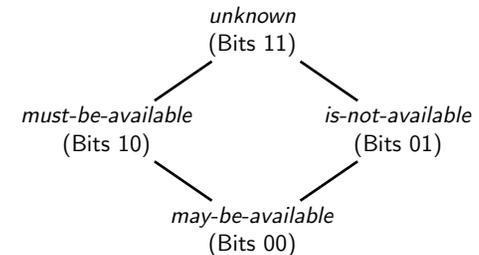
Component Lattice for Must Points-To Analysis

- A pointer can point to at most one location



Combined Total and Partial Availability Analysis

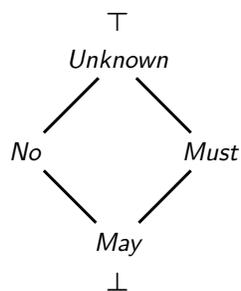
- Two bits per expression rather than one. Can be implemented using AND (as below) or using OR (reversed lattice)



Can also be implemented as a product of 1-0 and 0-1 lattice with AND for the first bit and OR for the second bit

- What approximation of safety does this lattice capture?
Uncertain information (= no optimization) is guaranteed to be safe

General Lattice for May-Must Analysis



Interpreting data flow values

- *Unknown*. Nothing is known as yet
- *No*. Information does not hold along any path
- *Must*. Information must hold along all paths
- *May*. Information may hold along some path

Possible Applications

- Pointer Analysis : No need of separate of *May* and *Must* analyses
eg. $(p \mapsto l, \text{May})$, $(p \mapsto l, \text{Must})$, $(p \mapsto l, \text{No})$, or $(p \mapsto l, \text{Unknown})$
- Type Inferencing for Dynamically Checked Languages



Part 6

Flow Functions

Flow Functions: An Outline of Our Discussion

- Defining flow functions
- Properties of flow functions
(Some properties discussed in the context of solutions of data flow analysis)



The Set of Flow Functions

- F is the set of functions $f : L \rightarrow L$ such that
 - ▶ F contains an identity function
To model “empty” statements, i.e. statements which do not influence the data flow information
 - ▶ F is closed under composition
Cumulative effect of statements should generate data flow information from the same set
 - ▶ For every $x \in L$, there must be a finite set of flow functions $\{f_1, f_2, \dots, f_m\} \subseteq F$ such that

$$x = \prod_{1 \leq i \leq m} f_i(BI)$$

- Properties of f
 - ▶ Monotonicity and Distributivity
 - ▶ Loop Closure Boundedness and Separability



Flow Functions in Bit Vector Data Flow Frameworks

- Bit Vector Frameworks: Available Expressions Analysis, Reaching Definitions Analysis Live variable Analysis, Anticipable Expressions Analysis, Partial Redundancy Elimination etc

- ▶ All functions can be defined in terms of constant Gen and Kill

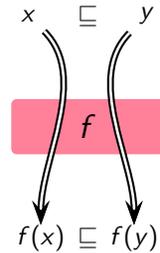
$$f(x) = \text{Gen} \cup (x - \text{Kill})$$

- ▶ Lattices are powersets with partial orders as \subseteq or \supseteq relations
 - ▶ Information is merged using \cap or \cup
 - Flow functions in Strong Liveness Analysis, Pointer Analyses, Constant Propagation, Possibly Uninitialized Variables cannot be expressed using constant Gen and Kill
- Local context alone is not sufficient to describe the effect of statements fully



Monotonicity of Flow Functions

- Partial order is preserved: If x can be safely used in place of y then $f(x)$ can be safely used in place of $f(y)$



$$\forall x, y \in L, x \subseteq y \Rightarrow f(x) \subseteq f(y)$$

- Alternative definition

$$\forall x, y \in L, f(x \sqcap y) \subseteq f(x) \sqcap f(y)$$

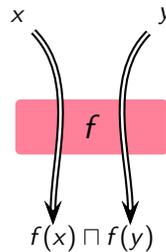
- Merging at intermediate points in shared segments of paths is safe (However, it may lead to imprecision)



Distributivity of Flow Functions

- Merging distributes over function application

$$\forall x, y \in L, f(x \sqcap y) = f(x) \sqcap f(y)$$



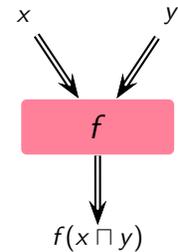
- Merging at intermediate points in shared segments of paths does not lead to imprecision



Distributivity of Flow Functions

- Merging distributes over function application

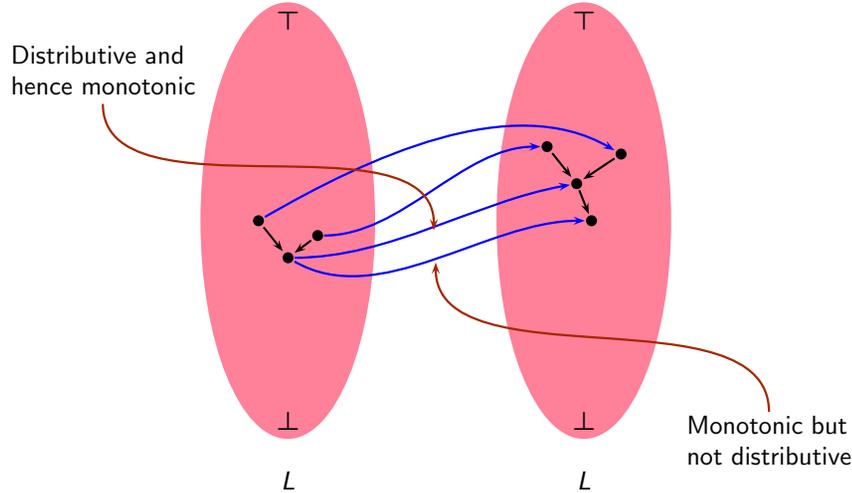
$$\forall x, y \in L, f(x \sqcap y) = f(x) \sqcap f(y)$$



- Merging at intermediate points in shared segments of paths does not lead to imprecision



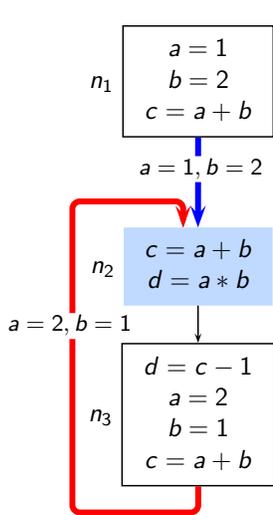
Monotonicity and Distributivity



Distributivity of Bit Vector Frameworks

$$\begin{aligned}
 f(x) &= \text{Gen} \cup (x - \text{Kill}) \\
 f(y) &= \text{Gen} \cup (y - \text{Kill}) \\
 \\
 f(x \cup y) &= \text{Gen} \cup ((x \cup y) - \text{Kill}) \\
 &= \text{Gen} \cup ((x - \text{Kill}) \cup (y - \text{Kill})) \\
 &= (\text{Gen} \cup (x - \text{Kill})) \cup (\text{Gen} \cup (y - \text{Kill})) \\
 &= f(x) \cup f(y) \\
 \\
 f(x \cap y) &= \text{Gen} \cup ((x \cap y) - \text{Kill}) \\
 &= \text{Gen} \cup ((x - \text{Kill}) \cap (y - \text{Kill})) \\
 &= (\text{Gen} \cup (x - \text{Kill})) \cap (\text{Gen} \cup (y - \text{Kill})) \\
 &= f(x) \cap f(y)
 \end{aligned}$$

Non-Distributivity of Constant Propagation

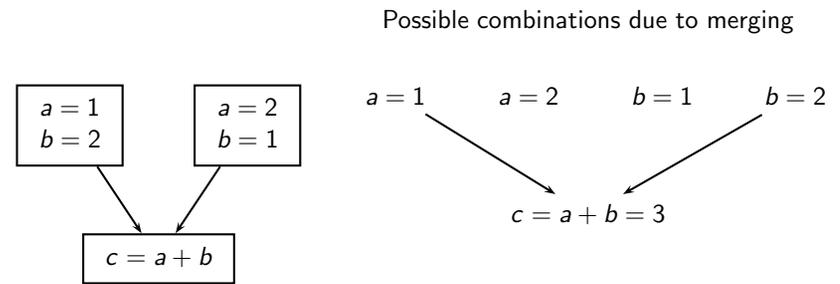


- $x = \langle 1, 2, 3, ud \rangle$ (Along $Out_{n_1} \rightarrow In_{n_2}$)
- $y = \langle 2, 1, 3, 2 \rangle$ (Along $Out_{n_3} \rightarrow In_{n_2}$)
- Function application for block n_2 before merging

$$\begin{aligned}
 f(x) \sqcap f(y) &= f(\langle 1, 2, 3, ud \rangle) \sqcap f(\langle 2, 1, 3, 2 \rangle) \\
 &= \langle 1, 2, 3, 2 \rangle \sqcap \langle 2, 1, 3, 2 \rangle \\
 &= \langle \hat{\perp}, \hat{\perp}, 3, 2 \rangle
 \end{aligned}$$
- Function application for block n_2 after merging

$$\begin{aligned}
 f(x \sqcap y) &= f(\langle 1, 2, 3, ud \rangle \sqcap \langle 2, 1, 3, 2 \rangle) \\
 &= f(\langle \hat{\perp}, \hat{\perp}, 3, 2 \rangle) \\
 &= \langle \hat{\perp}, \hat{\perp}, \hat{\perp}, \hat{\perp} \rangle
 \end{aligned}$$
- $f(x \sqcap y) \sqsubset f(x) \sqcap f(y)$

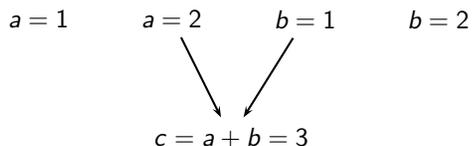
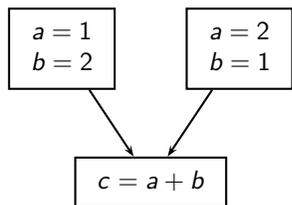
Why is Constant Propagation Non-Distributive?



- Correct combination

Why is Constant Propagation Non-Distributive?

Possible combinations due to merging

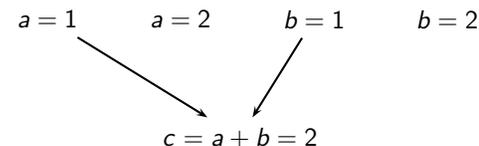
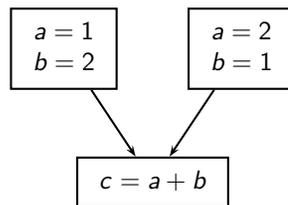


- Correct combination



Why is Constant Propagation Non-Distributive?

Possible combinations due to merging

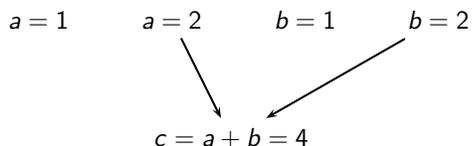
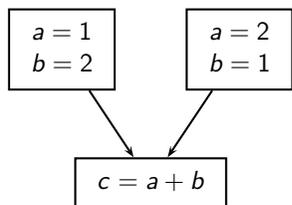


- Wrong combination
- Mutually exclusive information
- No execution path along which this information holds



Why is Constant Propagation Non-Distributive?

Possible combinations due to merging



- Wrong combination
- Mutually exclusive information
- No execution path along which this information holds



Part 7

Solutions of Data Flow Analysis

Solutions of Data Flow Analysis: An Outline of Our Discussion

- MoP and MFP assignments and their relationship
- Existence of MoP assignment
 - ▶ Boundedness of flow functions
- Existence and Computability of MFP assignment
 - ▶ Flow functions Vs. function computed by data flow equations
- Safety of MFP solution



Solutions of Data Flow Analysis

- An assignment A associates data flow values with program points
 $A \sqsubseteq B$ if for all program points p , $A(p) \sqsubseteq B(p)$
- Performing data flow analysis

Given

- ▶ A set of flow functions, a lattice, and merge operation
- ▶ A program flow graph with a mapping from nodes to flow functions

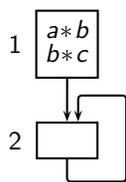
Find out

- ▶ An assignment A which is as exhaustive as possible and is safe



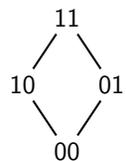
An Example For Available Expressions Analysis

Program

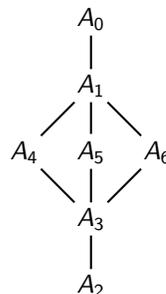


	Some Assignments						
	A_0	A_1	A_2	A_3	A_4	A_5	A_6
In_1	11	00	00	00	00	00	00
Out_1	11	11	00	11	11	11	11
In_2	11	11	00	00	10	01	01
Out_2	11	11	00	00	10	01	10

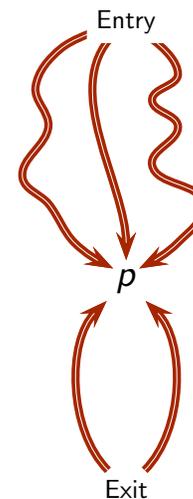
Lattice L of data flow values at a node



Lattice $L \times L \times L \times L$ for data flow values at all nodes



Meet Over Paths (MoP) Assignment



- The largest safe approximation of the information reaching a program point along all **information flow paths**

$$MoP(p) = \bigcap_{\rho \in Paths(p)} f_{\rho}(BI)$$

- ▶ f_{ρ} represents the compositions of flow functions along ρ
- ▶ BI refers to the relevant information from the calling context
- ▶ All execution paths are considered potentially executable by ignoring the results of conditionals

- Any $Info(p) \sqsubseteq MoP(p)$ is safe



Maximum Fixed Point (MFP) Assignment

- Difficulties in computing MoP assignment

- In the presence of cycles there are infinite paths
If all paths need to be traversed \Rightarrow **Undecidability**
- Even if a program is acyclic, every conditional multiplies the number of paths by two
If all paths need to be traversed \Rightarrow **Intractability**

Path based specification

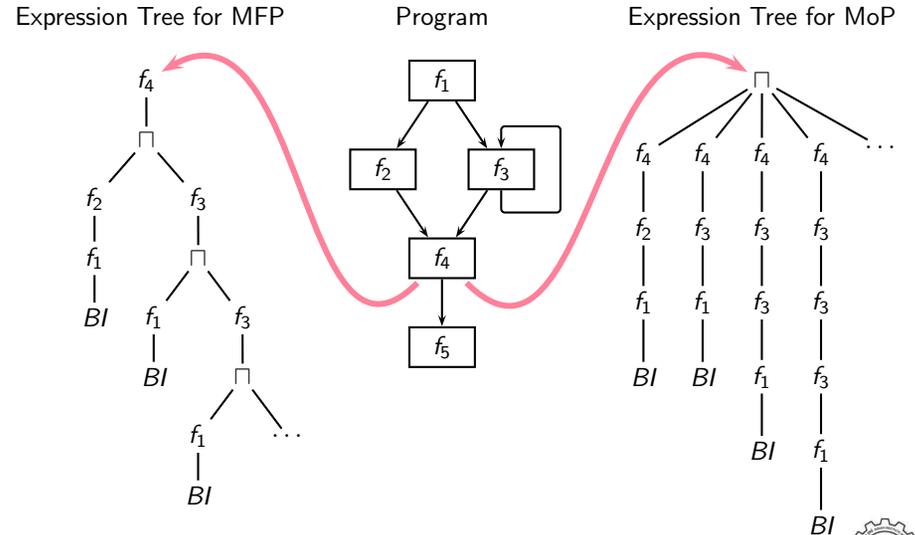


Edge based specifications

- Why not merge information at intermediate points?

- Merging is safe but may lead to imprecision
- Computes fixed point solutions of data flow equations

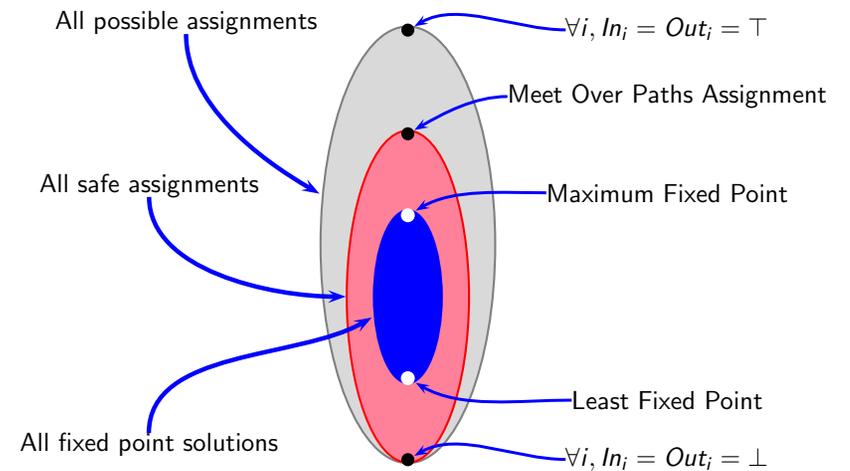
Computing MFP Vs. Computing MoP



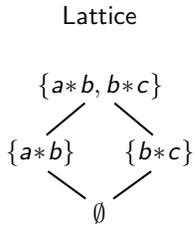
Assignments for Constant Propagation Example

	MoP	MFP
n_1 $a = 1$ $b = 2$ $c = a + b$	$\langle \hat{\top}, \hat{\top}, \hat{\top}, \hat{\top} \rangle$ $\langle 1, 2, 3, \hat{\top} \rangle$	$\langle \hat{\top}, \hat{\top}, \hat{\top}, \hat{\top} \rangle$ $\langle 1, 2, 3, \hat{\top} \rangle$
n_2 $c = a + b$ $d = a * b$	$\langle \hat{\perp}, \hat{\perp}, 3, 2 \rangle$ $\langle \hat{\perp}, \hat{\perp}, 3, 2 \rangle$	$\langle \hat{\perp}, \hat{\perp}, 3, \hat{\perp} \rangle$ $\langle \hat{\perp}, \hat{\perp}, \hat{\perp}, \hat{\perp} \rangle$
n_3 $d = c - 1$ $a = 2$ $b = 1$ $c = a + b$	$\langle \hat{\perp}, \hat{\perp}, 3, 2 \rangle$ $\langle 2, 1, 3, 2 \rangle$	$\langle \hat{\perp}, \hat{\perp}, \hat{\perp}, \hat{\perp} \rangle$ $\langle 2, 1, 3, \hat{\perp} \rangle$

Possible Assignments as Solutions of Data Flow Analyses



An Instance of Available Expressions Analysis

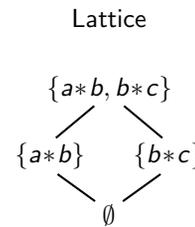


Constant Functions		Dependent Functions	
f	$f(x)$	f	$f(x)$
f_{\top}	$\{a*b, b*c\}$	f_{id}	x
f_{\perp}	\emptyset	f_c	$x \cup \{a*b\}$
f_a	$\{a*b\}$	f_d	$x \cup \{b*c\}$
f_b	$\{b*c\}$	f_e	$x - \{a*b\}$
		f_f	$x - \{b*c\}$

- Is the lattice a meet semilattice?
- What is the meet operation that computes glb?
- Are all strictly descending chains finite?
- Does the function space have an identity function?
- Are all values in the lattice computable from a finite merge of flow functions?
- Is the function space closed under composition?

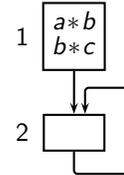


An Instance of Available Expressions Analysis



Constant Functions		Dependent Functions	
f	$f(x)$	f	$f(x)$
f_{\top}	$\{a*b, b*c\}$	f_{id}	x
f_{\perp}	\emptyset	f_c	$x \cup \{a*b\}$
f_a	$\{a*b\}$	f_d	$x \cup \{b*c\}$
f_b	$\{b*c\}$	f_e	$x - \{a*b\}$
		f_f	$x - \{b*c\}$

Program



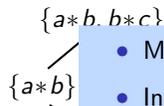
Flow Functions	
Node	Flow Function
1	f_{\top}
2	f_{id}

	Some Possible Assignments					
	A_1	A_2	A_3	A_4	A_5	A_6
In_1	00	00	00	00	00	00
Out_1	11	00	11	11	11	11
In_2	11	00	00	10	01	01
Out_2	11	00	00	10	01	10



An Instance of Available Expressions Analysis

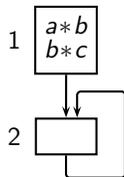
Lattice



- Maximum fixed point assignment
- Initialization for round robin iterative method: 11
- Safe assignment

Constant Functions		Dependent Functions	
f	$f(x)$	f	$f(x)$
f_{\top}	$\{a*b, b*c\}$	f_{id}	x
f_{\perp}	\emptyset	f_c	$x \cup \{a*b\}$
f_a	$\{a*b\}$	f_d	$x \cup \{b*c\}$
f_b	$\{b*c\}$	f_e	$x - \{a*b\}$
		f_f	$x - \{b*c\}$

Program



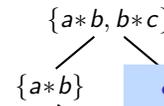
Flow Functions	
Node	Flow Function
1	f_{\top}
2	f_{id}

	Some Possible Assignments					
	A_1	A_2	A_3	A_4	A_5	A_6
In_1	00	00	00	00	00	00
Out_1	11	00	11	11	11	11
In_2	11	00	00	10	01	01
Out_2	11	00	00	10	01	10



An Instance of Available Expressions Analysis

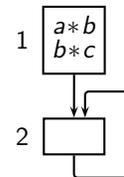
Lattice



- Not a fixed point assignment
- Safe assignment

Constant Functions		Dependent Functions	
f	$f(x)$	f	$f(x)$
f_{\top}	$\{a*b, b*c\}$	f_{id}	x
f_{\perp}	\emptyset	f_c	$x \cup \{a*b\}$
f_a	$\{a*b\}$	f_d	$x \cup \{b*c\}$
f_b	$\{b*c\}$	f_e	$x - \{a*b\}$
		f_f	$x - \{b*c\}$

Program



Flow Functions	
Node	Flow Function
1	f_{\top}
2	f_{id}

	Some Possible Assignments					
	A_1	A_2	A_3	A_4	A_5	A_6
In_1	00	00	00	00	00	00
Out_1	11	00	11	11	11	11
In_2	11	00	00	10	01	01
Out_2	11	00	00	10	01	10



An Instance of Available Expressions Analysis

Lattice

Constant Functions		Dependent Functions	
f	$f(x)$	f	$f(x)$
$\{a*b, b*c\}$	f	f	x
$\{a*b\}$	$f(x)$	$x \cup \{a*b\}$	$x \cup \{b*c\}$
		$x - \{a*b\}$	$x - \{b*c\}$

- Minimum fixed point assignment
- Initialization for round robin iterative method: 00
- Safe assignment

Program

```

1  a*b
   b*c
   |
   v
2  [ ]
   |
   v
   [ ]
  
```

Flow Functions		Some Possible Assignments					
Node	Flow Function	A_1	A_2	A_3	A_4	A_5	A_6
1	f_T	00	00	00	00	00	00
2	f_{id}	11	00	11	11	11	11
In_1		11	00	00	10	01	01
Out_1		11	00	00	10	01	10
In_2		11	00	00	10	01	01
Out_2		11	00	00	10	01	10

An Instance of Available Expressions Analysis

Lattice

Constant Functions		Dependent Functions	
f	$f(x)$	f	$f(x)$
$\{a*b, b*c\}$	f	f	x
$\{a*b\}$	$f(x)$	$x \cup \{a*b\}$	$x \cup \{b*c\}$
		$x - \{a*b\}$	$x - \{b*c\}$

- Fixed point assignment which is neither maximum nor minimum
- Initialization for round robin iterative method: 10
- Safe assignment

Program

```

1  a*b
   b*c
   |
   v
2  [ ]
   |
   v
   [ ]
  
```

Flow Functions		Some Possible Assignments					
Node	Flow Function	A_1	A_2	A_3	A_4	A_5	A_6
1	f_T	00	00	00	00	00	00
2	f_{id}	11	00	11	11	11	11
In_1		11	00	00	10	01	01
Out_1		11	00	00	10	01	01
In_2		11	00	00	10	01	01
Out_2		11	00	00	10	01	10

An Instance of Available Expressions Analysis

Lattice

Constant Functions		Dependent Functions	
f	$f(x)$	f	$f(x)$
$\{a*b, b*c\}$	f	f	x
$\{a*b\}$	$f(x)$	$x \cup \{a*b\}$	$x \cup \{b*c\}$
		$x - \{a*b\}$	$x - \{b*c\}$

- Fixed point assignment which is neither maximum nor minimum
- Initialization for round robin iterative method: 01
- Safe assignment

Program

```

1  a*b
   b*c
   |
   v
2  [ ]
   |
   v
   [ ]
  
```

Flow Functions		Some Possible Assignments					
Node	Flow Function	A_1	A_2	A_3	A_4	A_5	A_6
1	f_T	00	00	00	00	00	00
2	f_{id}	11	00	11	11	11	11
In_1		11	00	00	10	01	01
Out_1		11	00	00	10	01	01
In_2		11	00	00	10	01	01
Out_2		11	00	00	10	01	10

An Instance of Available Expressions Analysis

Lattice

Constant Functions		Dependent Functions	
f	$f(x)$	f	$f(x)$
$\{a*b, b*c\}$	f_T	f_{id}	x
$\{a*b\}$	$\{a*b, b*c\}$	f_c	$x \cup \{a*b\}$
	\emptyset	f_d	$x \cup \{b*c\}$
		f_e	$x - \{a*b\}$
		f_f	$x - \{b*c\}$

- Not a fixed point assignment
- Safe assignment

Program

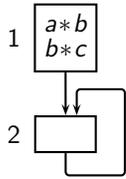
```

1  a*b
   b*c
   |
   v
2  [ ]
   |
   v
   [ ]
  
```

Flow Functions		Some Possible Assignments					
Node	Flow Function	A_1	A_2	A_3	A_4	A_5	A_6
1	f_T	00	00	00	00	00	00
2	f_{id}	11	00	11	11	11	11
In_1		11	00	00	10	01	01
Out_1		11	00	00	10	01	01
In_2		11	00	00	10	01	01
Out_2		11	00	00	10	01	10

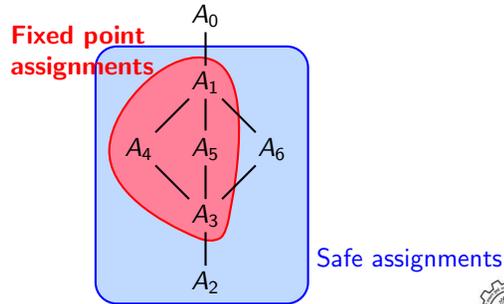
Lattice of Assignments for Available Expressions Analysis

Program



Some Assignments							
	A ₀	A ₁	A ₂	A ₃	A ₄	A ₅	A ₆
In ₁	11	00	00	00	00	00	00
Out ₁	11	11	00	11	11	11	11
In ₂	11	11	00	00	10	01	01
Out ₂	11	11	00	00	10	01	10

Lattice $L \times L \times L \times L$ for all assignments (many assignments omitted, e.g. node 1 could have data flow values 10 and 01)



Existence of an MoP Assignment (1)

$$MoP(p) = \bigsqcap_{\rho \in Paths(p)} f_{\rho}(BI)$$

- If a finite number of paths reach p , then existence of solution trivially follows
 - ▶ Function space is closed under composition
 - ▶ glb exists for all non-empty finite subsets of the lattice (Assuming that the data flow values form a meet semilattice)

Existence of an MoP Assignment (2)

$$MoP(p) = \bigsqcap_{\rho \in Paths(p)} f_{\rho}(BI)$$

- If an infinite number of paths reach p then,

$$MoP(p) = \underbrace{f_{\rho_1}(BI) \sqcap f_{\rho_2}(BI)}_{X_1} \sqcap f_{\rho_3}(BI) \sqcap \dots$$

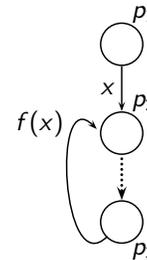
$$\underbrace{\hspace{10em}}_{X_2}$$

$$\underbrace{\hspace{15em}}_{X_3}$$

- Every meet results in a weaker value
- The sequence X_1, X_2, X_3, \dots follows a descending chain
- Since all strictly descending chains are finite, MoP exists (Assuming that our meet semilattice satisfies DCC)

Computability of MoP

Does existence of MoP imply it is computable?



Paths reaching the entry of p_2	Data Flow Value
p_1, p_2	x
p_1, p_2, p_3, p_2	$f(x)$
$p_1, p_2, p_3, p_2, p_3, p_2$	$f(f(x)) = f^2(x)$
$p_1, p_2, p_3, p_2, p_3, p_2, p_3, p_2$	$f(f(f(x))) = f^3(x)$
...	...

$$MoP(p_2) = x \sqcap f(x) \sqcap f^2(x) \sqcap f^3(x) \sqcap f^4(x) \sqcap \dots$$

MoP Computation is Undecidable

There does not exist any algorithm that can compute MoP assignment for every possible instance of every possible monotone data flow framework

- Reducing MPCP (Modified Post's Correspondence Problem) to constant propagation
- MPCP is known to be undecidable
- If an algorithm exists for detecting all constants
⇒ MPCP would be decidable
- Since MPCP is undecidable
⇒ There does not exist an algorithm for detecting all constants
⇒ Static analysis is undecidable

Post's Correspondence Problem (PCP)

- Given strings $u_i, v_i \in \Sigma^+$ for some alphabet Σ , and two k -tuples,

$$U = (u_1, u_2, \dots, u_k)$$

$$V = (v_1, v_2, \dots, v_k)$$

Is there a sequence i_1, i_2, \dots, i_m of one or more integers such that

$$u_{i_1} u_{i_2} \dots u_{i_m} = v_{i_1} v_{i_2} \dots v_{i_m}$$

- For $U = (101, 11, 100)$ and $V = (01, 1, 11001)$ the solution is 2, 3, 2

$$u_2 u_3 u_2 = 1110011$$

$$v_2 v_3 v_2 = 1110011$$

- For $U = (1, 10111, 10)$, $V = (111, 10, 0)$, the solution is 2, 1, 1, 3
- For $U = (01, 110)$, $V = (00, 11)$, there is no solution

Post's Correspondence Problem (PCP)

- Given strings $u_i, v_i \in \Sigma^+$ for some alphabet Σ , and two k -tuples,

$$U = (u_1, u_2, \dots, u_k)$$

$$V = (v_1, v_2, \dots, v_k)$$

Is there a sequence i_1, i_2, \dots, i_m of one or more integers such that

$$u_{i_1} u_{i_2} \dots u_{i_m} = v_{i_1} v_{i_2} \dots v_{i_m}$$

- Sets U and V are finite and contain the same number of strings
- The strings in U and V are finite and are of varying lengths
- For constructing the new strings using the strings in U and V
 - ▶ The strings at the same the index of must be used
 - ▶ There is no limit on the length of the new string

Indices could repeat without any bound

Modified Post's Correspondence Problem (MPCP)

- The first string in the correspondence relation should be the first string from the k -tuple

$$u_1 u_{i_1} u_{i_2} \dots u_{i_m} = v_1 v_{i_1} v_{i_2} \dots v_{i_m}$$

- For $U = (11, 1, 0111, 10)$, $V = (1, 111, 10, 0)$, the solution is 3, 2, 2, 4

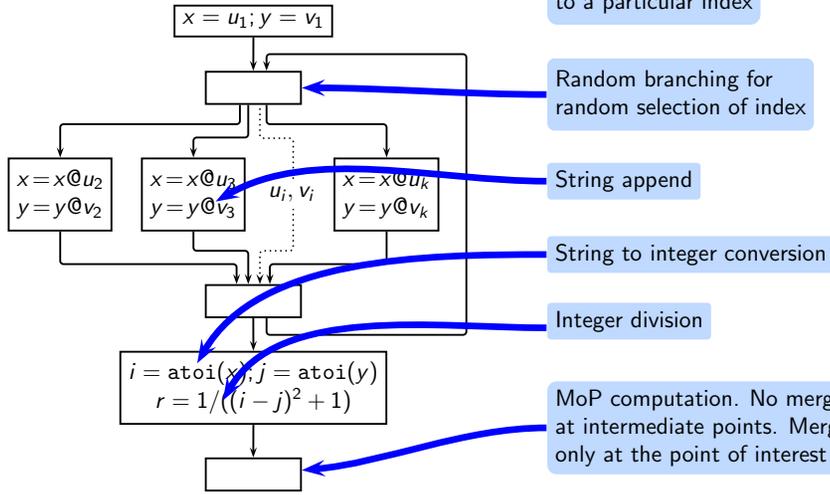
$$u_1 u_3 u_2 u_2 u_4 = 1101111110$$

$$v_1 v_3 v_2 v_2 v_4 = 1101111110$$

Hecht's Reduction of MPCP to Constant Propagation

Given: An instance of MPCP with $\Sigma = \{0, 1\}$

Each block in the loop corresponds to a particular index



Random branching for random selection of index

String append

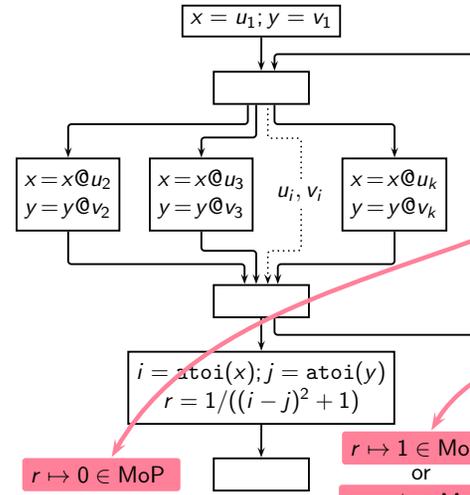
String to integer conversion

Integer division

MoP computation. No merge at intermediate points. Merge only at the point of interest

Hecht's Reduction of MPCP to Constant Propagation

Given: An instance of MPCP with $\Sigma = \{0, 1\}$

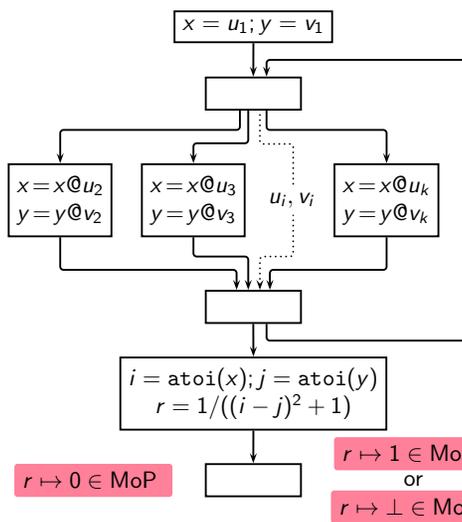


- $i = j \Rightarrow r = 1$
 - $i \neq j \Rightarrow r = 0$
 - If there exists an algorithm which can determine that
 - $r = 0$ along every path (x is never equal to y, MPCP instance does not have a solution)
 - $r = 1$ along some path (some x is equal to y, MPCP instance has a solution)
- Then MPCP is decidable

Hecht's Reduction of MPCP to Constant Propagation

Given: An instance of MPCP with $\Sigma = \{0, 1\}$

The tricky part!!



- $i = j \Rightarrow r = 1$
 - $i \neq j \Rightarrow r = 0$
 - If there exists an algorithm which can determine that
 - $r = 0$ along every path (x is never equal to y, MPCP instance does not have a solution)
 - $r = 1$ along some path (some x is equal to y, MPCP instance has a solution)
- Then MPCP is decidable

Hecht's Reduction of MPCP to Constant Propagation

Given: An instance of MPCP with $\Sigma = \{0, 1\}$

The tricky part!!

- Asserting that no x is equal to y requires us to examine infinitely many (x, y) pairs
 - If we keep finding x and y that are unequal, how long do we wait to decide that there is no x that is equal to y?
 - In a lucky case we may find an x that is equal to y, but there is no guarantee
- MPCP is not decidable
 \Rightarrow Constant Propagation is not decidable
- Descending chains consist of sets of pairs (x, y) with \top as \emptyset
- Since there is no bound on the length of x and y, the number of these sets is infinite
 \Rightarrow DCC is violated

- $i = j \Rightarrow r = 1$
 - $i \neq j \Rightarrow r = 0$
 - If there exists an algorithm which can determine that
 - $r = 0$ along every path (x is never equal to y, MPCP instance does not have a solution)
 - $r = 1$ along some path (some x is equal to y, MPCP instance has a solution)
- Then MPCP is decidable

Is MFP Always Computable?

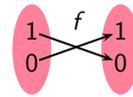
MFP assignment may not be computable

- if the flow functions are non-monotonic, or
- if some strictly descending chain is not finite



Computability of MFP

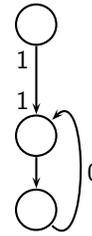
- If f is not monotonic, the computation may not converge



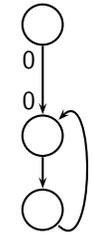
x	$f(x)$	$f^2(x)$	$f^3(x)$	$f^4(x)$...
1	0	1	0	1	...

$$MoP = x \sqcap f(x) \sqcap f^2(x) \sqcap f^3(x) \sqcap \dots = 0$$

- Computing MFP iteratively



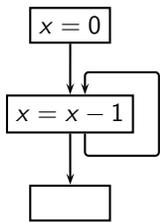
MFP does not exist and is not computable



MFP exist and is computable



Computability of MFP



Hasse diagram

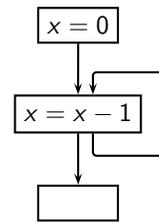
\sqsubseteq	\leq	\leq
\sqcap	min	min
	0	0
	-1	-1
	-2	-2
	-3	-3

	$-\infty$	$-\infty$
MFP exists?	No	Yes
MFP computable?	No	No
MoP exists?	No	Yes

Point of interest



Computability of MFP



- Flow functions are monotonic
- Strictly descending chains are not finite

\sqsubseteq	\leq	\leq
\sqcap	min	min
	0	0
	-1	-1

	$-\infty$	$-\infty$
MFP exists?	No	Yes
MFP computable?	No	No
MoP exists?	No	Yes

Point of interest



Existence and Computation of the Maximum Fixed Point

If L is a meet semilattice satisfying DCC, $f : L \rightarrow L$ is monotonic, then $MFP(f) = f^{k+1}(\top) = f^k(\top)$ such that $f^{j+1}(\top) \neq f^j(\top)$, $j < k$

Claims being made:

- $\exists k$ s.t. $f^{k+1}(\top) = f^k(\top)$
- Since k is finite, $f^k(\top)$ exists and is computable
- $f^k(\top)$ is a fixed point
- $f^k(\top)$ is a the *maximum* fixed point

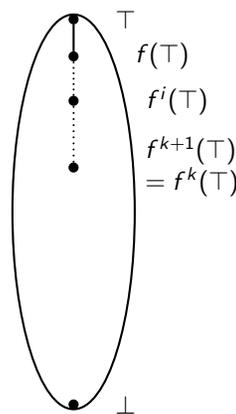
The proof depends on:

- The existence of glb for every pair of values in L
- Finiteness of strictly descending chains
- Monotonicity of f



Existence and Computation of the Maximum Fixed Point

If L is a meet semilattice satisfying DCC, $f : L \rightarrow L$ is monotonic, then $MFP(f) = f^{k+1}(\top) = f^k(\top)$ such that $f^{j+1}(\top) \neq f^j(\top)$, $j < k$



- $\top \supseteq f(\top) \supseteq f^2(\top) \supseteq f^3(\top) \supseteq f^4(\top) \supseteq \dots$
 - Since strictly descending chains are finite, there must exist $f^k(\top)$ such that $f^{k+1}(\top) = f^k(\top)$ and $f^{j+1}(\top) \neq f^j(\top)$, $j < k$
 - If p is a fixed point of f then $p \sqsubseteq f^k(\top)$
- Proof strategy: Induction on i for $f^i(\top)$
- ▶ Basis ($i = 0$): $p \sqsubseteq f^0(\top) = \top$
 - ▶ Inductive Hypothesis: Assume that $p \sqsubseteq f^i(\top)$
 - ▶ Proof: $f(p) \sqsubseteq f(f^i(\top))$ (f is monotonic)
 - $\Rightarrow p \sqsubseteq f(f^i(\top))$ ($f(p) = p$)
 - $\Rightarrow p \sqsubseteq f^{i+1}(\top)$
- Since this holds for every p that is a fixed point, $f^{k+1}(\top)$ must be the Maximum Fixed Point



Fixed Points Computation: Flow Functions Vs. Equations

- Recall that

$$MFP(f) = f^{k+1}(\top) = f^k(\top) \text{ such that } f^{j+1}(\top) \neq f^j(\top), j < k.$$

- ▶ What is f in the above?
- ▶ Flow function of a block? Which block?
- Our method computes the maximum fixed point of data flow equations!
- What is the relation between the maximum fixed point of data flow equations and the MFP defined above?



Fixed Points Computation: Flow Functions Vs. Equations

- Data flow equations for a CFG with N nodes can be written as

$$\begin{aligned} In_1 &= B1 \\ Out_1 &= f_1(In_1) \\ In_2 &= Out_1 \sqcap \dots \\ Out_2 &= f_2(In_2) \\ &\dots \\ In_N &= Out_{N-1} \sqcap \dots \\ Out_N &= f_N(In_N) \end{aligned}$$



Fixed Points Computation: Flow Functions Vs. Equations

- Data flow equations for a CFG with N nodes can be written as

$$\begin{aligned} In_1 &= f_{In_1}(\langle In_1, Out_1, \dots, In_N, Out_N \rangle) \\ Out_1 &= f_{Out_1}(\langle In_1, Out_1, \dots, In_N, Out_N \rangle) \\ In_2 &= f_{In_2}(\langle In_1, Out_1, \dots, In_N, Out_N \rangle) \\ Out_2 &= f_{Out_2}(\langle In_1, Out_1, \dots, In_N, Out_N \rangle) \\ &\dots \\ In_N &= f_{In_N}(\langle In_1, Out_1, \dots, In_N, Out_N \rangle) \\ Out_N &= f_{Out_N}(\langle In_1, Out_1, \dots, In_N, Out_N \rangle) \end{aligned}$$

where each flow function is of the form $L \times L \times \dots \times L \rightarrow L$



Fixed Points Computation: Flow Functions Vs. Equations

- Data flow equations for a CFG with N nodes can be written as

$$\langle In_1, Out_1, \dots, In_N, Out_N \rangle = \langle \begin{array}{l} f_{In_1}(\langle In_1, Out_1, \dots, In_N, Out_N \rangle), \\ f_{Out_1}(\langle In_1, Out_1, \dots, In_N, Out_N \rangle), \\ \dots \\ f_{In_N}(\langle In_1, Out_1, \dots, In_N, Out_N \rangle), \\ f_{Out_N}(\langle In_1, Out_1, \dots, In_N, Out_N \rangle), \end{array} \rangle$$

where each flow function is of the form $L \times L \times \dots \times L \rightarrow L$



Fixed Points Computation: Flow Functions Vs. Equations

- Data flow equations for a CFG with N nodes can be written as

$$\mathcal{X} = \langle \begin{array}{l} f_{In_1}(\mathcal{X}), \\ f_{Out_1}(\mathcal{X}), \\ \dots \\ f_{In_N}(\mathcal{X}), \\ f_{Out_N}(\mathcal{X}), \end{array} \rangle$$

where $\mathcal{X} = \langle In_1, Out_1, \dots, In_N, Out_N \rangle$



Fixed Points Computation: Flow Functions Vs. Equations

- Data flow equations for a CFG with N nodes can be written as

$$\mathcal{X} = \mathcal{F}(\mathcal{X})$$

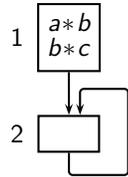
$$\begin{aligned} \text{where } \mathcal{X} &= \langle In_1, Out_1, \dots, In_N, Out_N \rangle \\ \mathcal{F}(\mathcal{X}) &= \langle f_{In_1}(\mathcal{X}), f_{Out_1}(\mathcal{X}), \dots, f_{In_N}(\mathcal{X}), f_{Out_N}(\mathcal{X}) \rangle \end{aligned}$$

We compute the fixed points of function \mathcal{F} defined above



An Instance of Available Expressions Analysis

Program



- Conventional data flow equations

$$\begin{array}{ll} In_1 = 00 & In_2 = Out_1 \cap Out_2 \\ Out_1 = 11 & Out_2 = In_2 \end{array}$$

- Data Flow Equation $\mathcal{X} = \mathcal{F}(\mathcal{X})$ is

$$\mathcal{F}(\langle In_1, Out_1, In_2, Out_2 \rangle) = \langle 00, 11, Out_1 \cap Out_2, In_2 \rangle$$

- The maximum fixed point assignment is

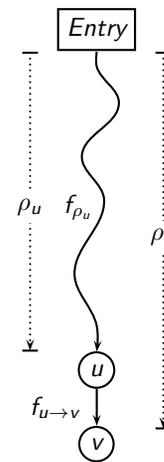
$$\mathcal{F}(\langle 11, 11, 11, 11 \rangle) = \langle 00, 11, 11, 11 \rangle$$

- The minimum fixed point assignment is

$$\mathcal{F}(\langle 00, 00, 00, 00 \rangle) = \langle 00, 11, 00, 00 \rangle$$



Safety of FP Assignment: $FP \sqsubseteq MoP$



- $MoP(v) = \bigsqcap_{\rho \in Paths(v)} f_{\rho}(BI)$
- Proof Obligation: $\forall \rho_v FP(v) \sqsubseteq f_{\rho_v}(BI)$
- Claim 1: $\forall u \rightarrow v, FP(v) \sqsubseteq f_{u \rightarrow v}(FP(u))$
- Proof Outline: Induction on path length

Base case: Path of length 0

$$FP(Entry) = MoP(Entry) = BI$$

Inductive hypothesis: Assume it holds for paths consisting of k edges (say at u)

$$FP(u) \sqsubseteq f_{\rho_u}(BI) \quad (\text{Inductive hypothesis})$$

$$FP(v) \sqsubseteq f_{u \rightarrow v}(FP(u)) \quad (\text{Claim 1})$$

$$\Rightarrow FP(v) \sqsubseteq f_{u \rightarrow v}(f_{\rho_u}(BI))$$

$$\Rightarrow FP(v) \sqsubseteq f_{\rho_v}(BI)$$

This holds for every FP and hence for MFP also



Part 8

Theoretical Abstractions: A Summary

Theoretical Abstractions: A Summary

Necessary and sufficient conditions for designing a data flow framework

- A meet semilattice satisfying dcc
 - Meet: commutative, associative, and idempotent
 - Partial order: reflexive, transitive, and antisymmetric
 - Existence of \perp
- A function space
 - Existence of the identity function
 - Closure under composition
 - Monotonic functions



Performing Data Flow Analysis

Performing Data Flow Analysis

- Algorithms for computing MFP solution
- Complexity of data flow analysis
- Factor affecting the complexity of data flow analysis



Iterative Methods of Performing Data Flow Analysis

Successive recomputation after conservative initialization (\top)

- *Round Robin*. Repeated traversals over nodes in a fixed order

Termination : After values stabilise

- + Simplest to understand and implement
- May perform unnecessary computations

Our examples use this method

- *Work List*. Dynamic list of nodes which need recomputation

Termination : When the list becomes empty

- + Demand driven. Avoid unnecessary computations
- Overheads of maintaining work list



Elimination Methods of Performing Data Flow Analysis

Delayed computations of dependent data flow values of dependent nodes

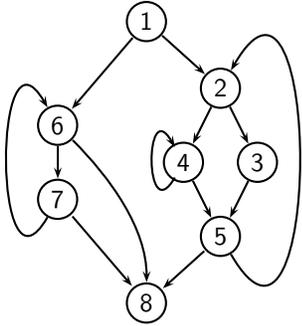
Find suitable single-entry regions

- *Interval Based Analysis*. Uses graph partitioning
- *T_1, T_2 Based Analysis*. Uses graph parsing

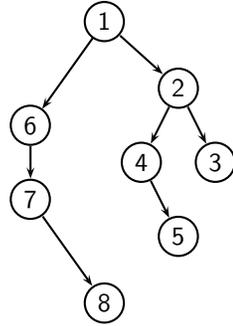


Classification of Edges in a Graph

Graph G

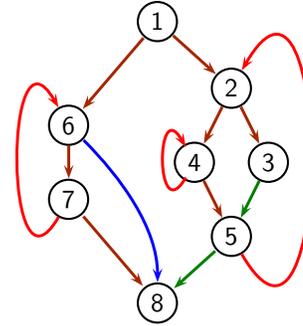


A depth first spanning tree of G

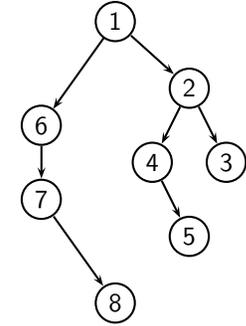


Classification of Edges in a Graph

Graph G



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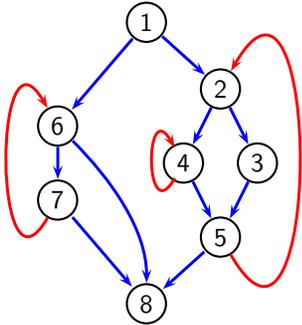


- Back edges →
- Forward edges →
- Tree edges →
- Cross edges →

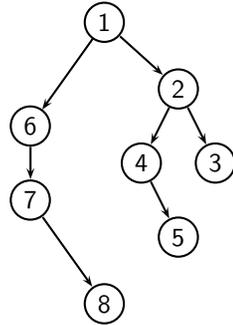


Classification of Edges in a Graph

Graph G



A depth first spanning tree of G



- Back edges →
- Forward edges →

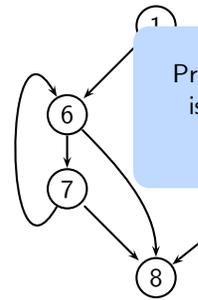
For data flow analysis, we club *tree*, *forward*, and *cross* edges into *forward* edges. Thus we have just forward or back edges in a control flow graph



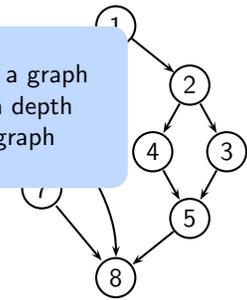
Reverse Post Order Traversal

- A reverse post order (rpo) is a topological sort of the graph obtained after removing back edges

Graph G



G' obtained after removing back edges of G



Practically, RPO of a graph is determined by a depth search over the graph

- Some possible RPOs for G are: (1, 2, 3, 4, 5, 6, 7, 8), (1, 6, 7, 2, 3, 4, 5, 8), (1, 6, 2, 7, 4, 3, 5, 8), and (1, 2, 6, 7, 3, 4, 5, 8)



Round Robin Iterative Algorithm

```

1  In0 = BI
2  for all j ≠ 0 do
3    Inj = ⊤
4  change = true
5  while change do
6    { change = false
7      for j = 1 to N - 1 do
8        { temp = ∏p∈pred(j) fp(Inp)
9          if temp ≠ Inj then
10         { Inj = temp
11           change = true
12         }
13       }
14     }

```

- Computation of Out_j has been left implicit
Works fine for unidirectional frameworks
- \top is the identity of \sqcap (line 3)
- Reverse postorder (rpo) traversal for efficiency (line 7)
- rpo traversal AND no loops \Rightarrow no need of initialization

Complexity of Round Robin Iterative Algorithm

- Unidirectional bit vector frameworks
 - ▶ Construct a spanning tree T of G to identify postorder traversal
 - ▶ Traverse G in reverse postorder for forward problems and Traverse G in postorder for backward problems
 - ▶ Depth $d(G, T)$: Maximum number of back edges in any acyclic path

Task	Number of iterations
First computation of In and Out	1
Convergence (until $change$ remains true)	$d(G, T)$
Verifying convergence ($change$ becomes false)	1

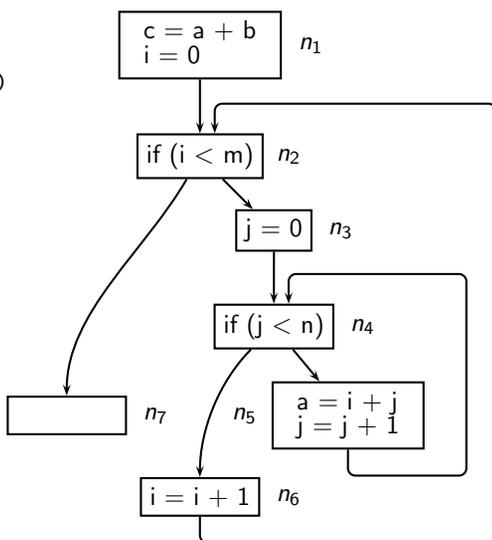
- What about bidirectional bit vector frameworks?
- What about other frameworks?

Example C Program with $d(G, T) = 2$

```

1 void fun(int m, int n)
2 {
3   int i,j,a,b,c;
4   c=a+b;
5   i=0;
6   while(i<m)
7   {
8     j=0;
9     while(j<n)
10    {
11      a=i+j;
12      j=j+1;
13    }
14    i=i+1;
15  }
16 }

```

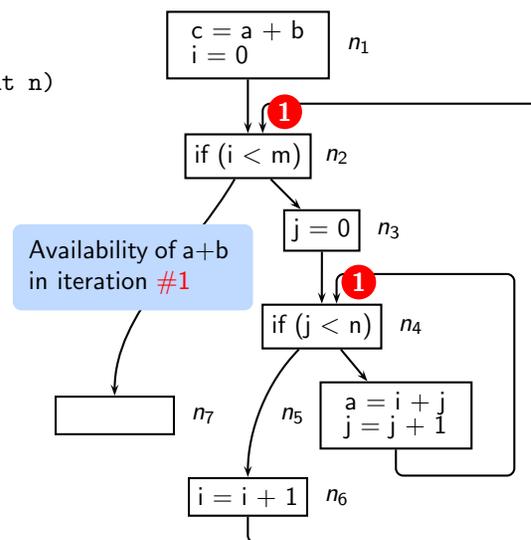


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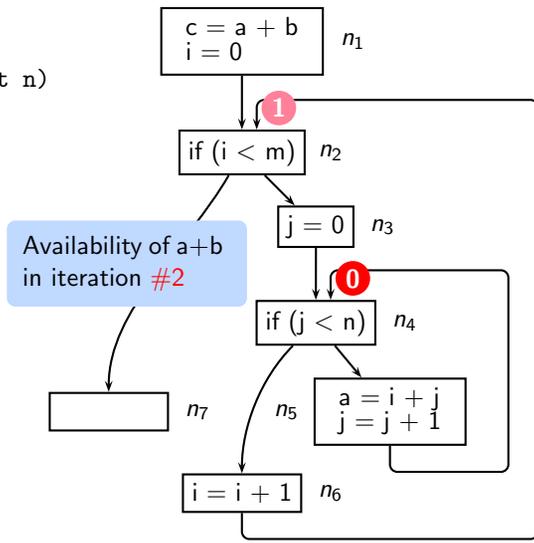
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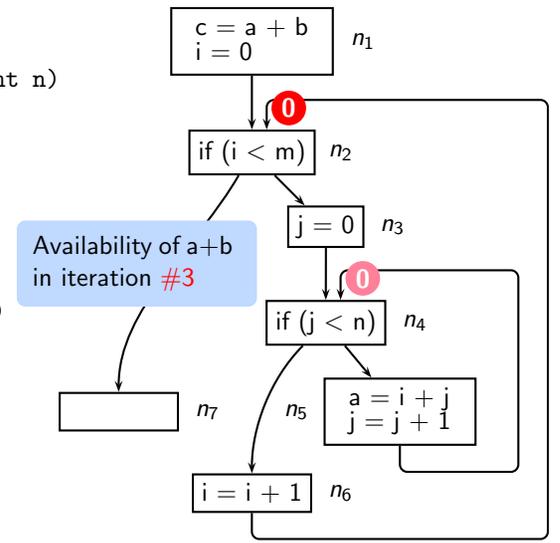
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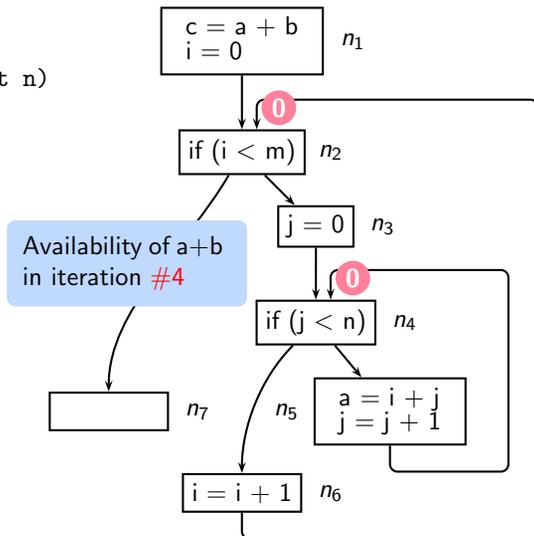
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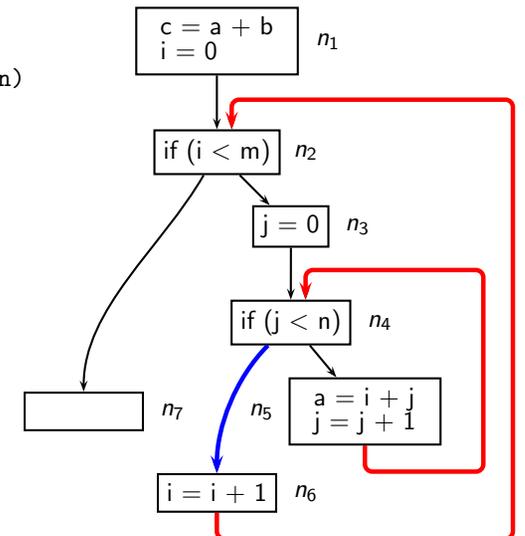


3 + 1 iterations for available expressions analysis

Example C Program with $d(G,T) = 2$

```

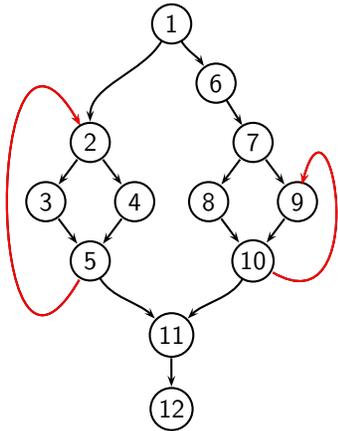
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3 + 1 iterations for available expressions analysis

Complexity of Bidirectional Bit Vector Frameworks

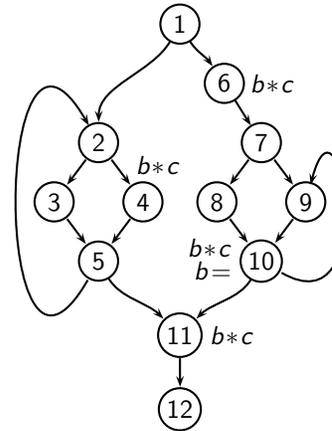
Example: Consider the following CFG for PRE



- Node numbers are in reverse post order
- Back edges in the graph are $n_5 \rightarrow n_2$ and $n_{10} \rightarrow n_9$
- $d(G, T) = 1$
- Actual iterations : 5



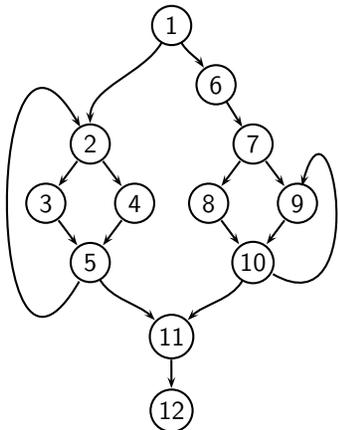
Complexity of Bidirectional Bit Vector Frameworks



	Pairs of <i>Out, In</i> Values						Final values & transformation
	Initial-ization	Changes in Iterations					
		#1	#2	#3	#4	#5	
	O,I	O,I	O,I	O,I	O,I	O,I	
12	0,1	0,0					0,0
11	1,1	0,1		0,0			0,0
10	1,1			0,1			0,1 Delete
9	1,1			1,0			1,0 Insert
8	1,1				1,0		1,0 Insert
7	1,1			0,0			0,0
6	1,1	1,0		0,0			0,0
5	1,1		0,0				0,0
4	1,1		0,1	0,0			0,0
3	1,1		0,0				0,0
2	1,1		1,0	0,0			0,0
1	1,1	0,0					0,0



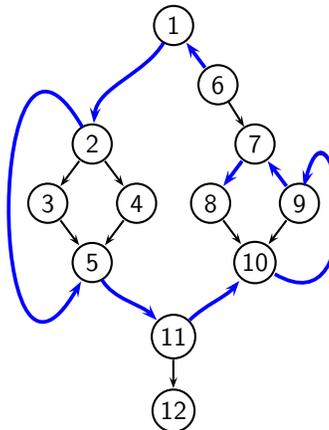
An Example of Information Flow in Our PRE Analysis



- $PavIn_6$ becomes 0 in the first iteration
- This cause many all other values to become 0
- Here we see a particular sequence of changes
- Incorporating the effect of this sequence of changes requires 5 iterations
- Number of iterations is not related to depth (which is 1 for this graph)



An Example of Information Flow in Our PRE Analysis



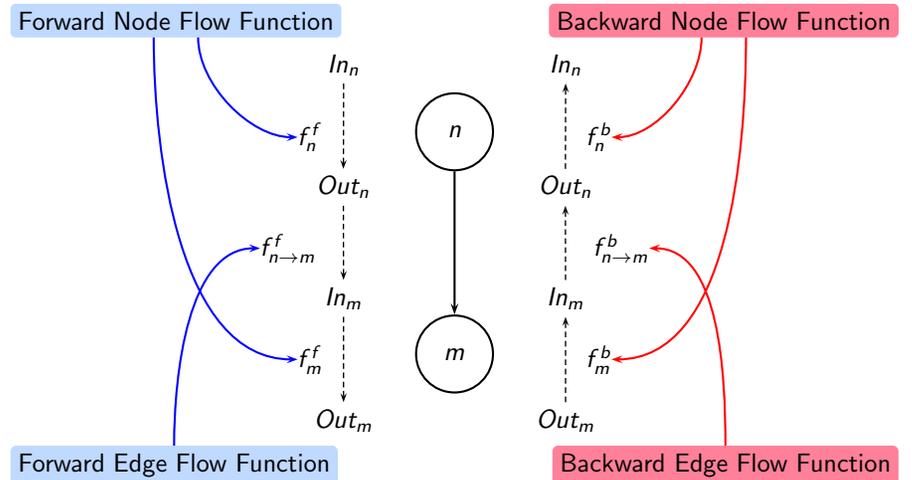
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- Number of iterations is not related to depth (which is 1 for this graph)



Information Flow and Information Flow Paths

- Default value at each program point: \top
- *Information flow path*
Sequence of adjacent program points along which data flow values change
- A change in the data flow at a program point could be
 - ▶ *Generation of information*
Change from \top to a non- \top due to local effect (i.e. $f(\top) \neq \top$)
 - ▶ *Propagation of information*
Change from x to y such that $y \sqsubseteq x$ due to global effect
- Information flow path (ifp) need not be a graph theoretic path

Edge and Node Flow Functions



General Data Flow Equations

$$In_n = \begin{cases} BI_{Start} \sqcap f_n^b(Out_n) & n = Start \\ \left(\prod_{m \in pred(n)} f_{m \rightarrow n}^f(Out_m) \right) \sqcap f_n^b(Out_n) & \text{otherwise} \end{cases}$$

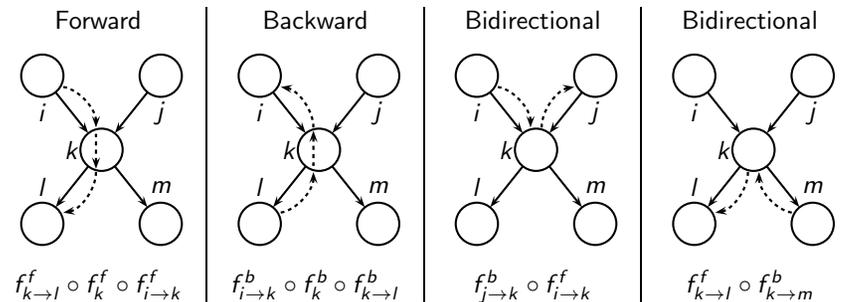
$$Out_n = \begin{cases} BI_{End} \sqcap f_n^f(In_n) & n = End \\ \left(\prod_{m \in succ(n)} f_{m \rightarrow n}^b(In_m) \right) \sqcap f_n^f(In_n) & \text{otherwise} \end{cases}$$

- Edge flow functions are typically identity

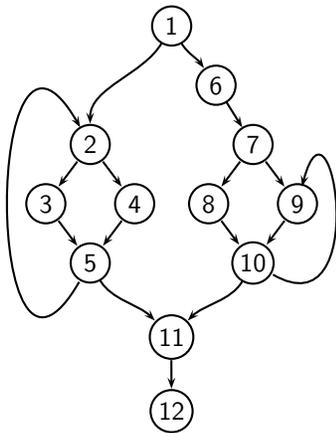
$$\forall x \in L, f(x) = x$$
- If particular flows are absent, the corresponding flow functions are

$$\forall x \in L, f(x) = \top$$

Modelling Information Flows Using Edge and Node Flow Functions



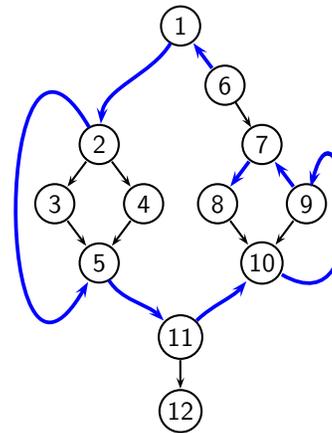
Information Flow Paths in PRE



- Information could flow along arbitrary paths
- Theoretically predicted number : 144
- Actual iterations : 5
- Not related to depth (1)



Information Flow Paths in PRE



- Information could flow along arbitrary paths
- Theoretically predicted number : 144
- Actual iterations : 5
- Not related to depth (1)



Complexity of Worklist Algorithms for Bit Vector Frameworks

- Assume n nodes and r entities
- Total number of data flow values = $2 \cdot n \cdot r$
- A data flow value can change at most once
- Complexity is $\mathcal{O}(n \cdot r)$
- *Must be same for both unidirectional and bidirectional frameworks*
(Number of data flow values does not change!)

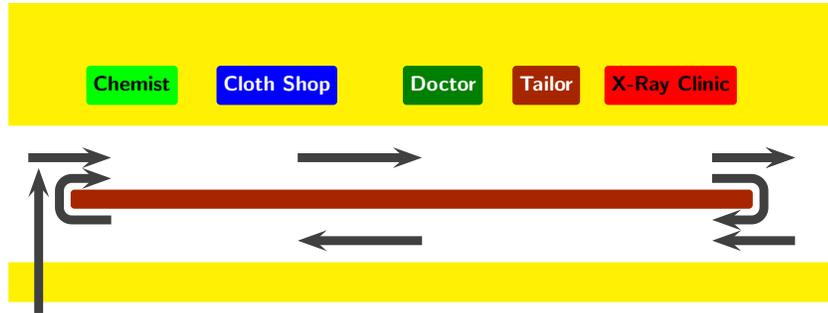


Lacuna with Older Estimates of PRE Complexity

- Lacuna with PRE : Complexity
 - ▶ r is typically $\mathcal{O}(n)$
 - ▶ Assuming that at most one data flow value changes in one traversal
 - ▶ Worst case number of traversals = $\mathcal{O}(n^2)$
- Practical graphs may have upto 50 nodes
 - ▶ Predicted number of traversals : 2,500
 - ▶ Practical number of traversals : ≤ 5
- No explanation for about 14 years despite dozens of efforts
- Not much experimentation with performing advanced optimizations involving bidirectional dependency



Complexity of Round Robin Iterative Method



- Buy OTC (Over-The-Counter) medicine No U-Turn 1 Trip
 - Buy cloth. Give it to the tailor for stitching No U-Turn 1 Trip
 - Buy medicine with doctor's prescription 1 U-Turn 2 Trips
 - Buy medicine with doctor's prescription 2 U-Turns 3 Trips
- The diagnosis requires X-Ray

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Information Flow Paths and Width of a Graph

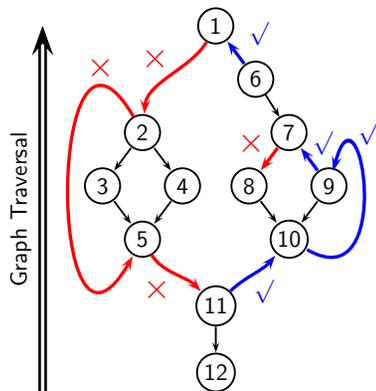
- A traversal $u \rightarrow v$ in an ifp is
 - *Compatible* if u is visited *before* v in the chosen graph traversal
 - *Incompatible* if u is visited *after* v in the chosen graph traversal
- Every incompatible edge traversal requires one additional iteration
- Width of a program flow graph with respect to a data flow framework
Maximum number of incompatible traversals in any ifp, no part of which is bypassed
- Width + 1 iterations are sufficient to converge on MFP solution
(1 additional iteration may be required for verifying convergence)

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Complexity of Bidirectional Bit Vector Frameworks



- Every "incompatible" edge traversal
⇒ **One additional graph traversal**
- Max. Incompatible edge traversals
= *Width* of the graph = **4**
- Maximum number of traversals =
 $1 + \text{Max. incompatible edge traversals} = 5$

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Width Subsumes Depth

- Depth is applicable only to unidirectional data flow frameworks
- Width is applicable to both unidirectional and bidirectional frameworks
- For a given graph for a unidirectional bit vector framework,
 $\text{Width} \leq \text{Depth}$
Width provides a tighter bound

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Tutorial Problem

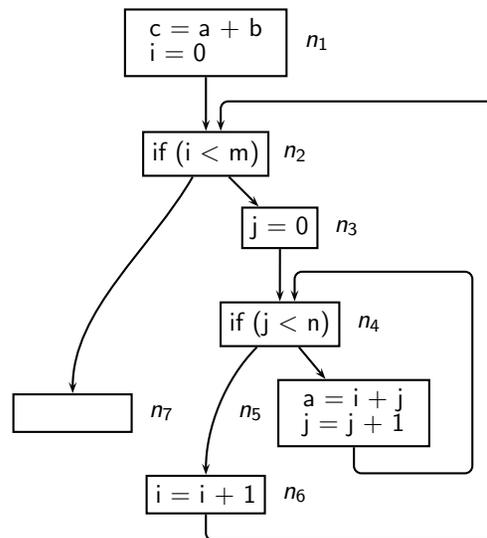
Perform work list based iterative analysis for earlier examples. Assume that the work list follows FIFO (First in First Out) policy

Show the trace of the analysis in the following format:

Step	Node	Remaining work list	Out DFV	Change?	Node Added	Resulting work list
------	------	---------------------	---------	---------	------------	---------------------



Tutorial Problem for Work List Based Analysis



For available expressions analysis

- Round robin method needs 3+1 iterations
- Total number of nodes processed = $7 \times 4 = 28$
- We illustrate work list method for expression $a + b$ (other expressions are unavailable in the first iteration because of BI)



Tutorial Problem for Work List Based Analysis

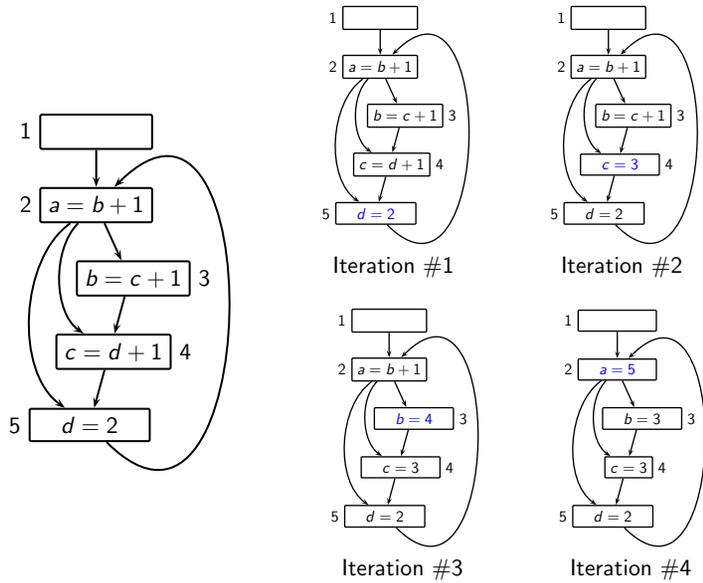
Step	Node	Remaining work list	Out DFV	Change?	Node Added	Resulting work list
1	n_1	$n_2, n_3, n_4, n_5, n_6, n_7$	1	No		$n_2, n_3, n_4, n_5, n_6, n_7$
2	n_2	n_3, n_4, n_5, n_6, n_7	1	No		n_3, n_4, n_5, n_6, n_7
3	n_3	n_4, n_5, n_6, n_7	1	No		n_4, n_5, n_6, n_7
4	n_4	n_5, n_6, n_7	1	No		n_5, n_6, n_7
5	n_5	n_6, n_7	0	Yes	n_4	n_6, n_7, n_4
6	n_6	n_7, n_4	1	No		n_7, n_4
7	n_7	n_4	1	No		n_4
8	n_4		0	Yes	n_5, n_6	n_5, n_6
9	n_5	n_6	0	No		n_6
10	n_6		0	Yes	n_2	n_2
11	n_2		0	Yes	n_3, n_7	n_3, n_7
12	n_3	n_7	0	Yes	n_4	n_7, n_4
13	n_7	n_4	0	Yes		n_4
14	n_4		0	No		Empty \Rightarrow End



Part 10

Precise Modelling of General Flows

Complexity of Constant Propagation?



Part 11

Extra Topics

Tarski's Fixed Point Theorem

Given monotonic $f : L \rightarrow L$ where L is a complete lattice

Define

$$p \text{ is a fixed point of } f : \text{Fix}(f) = \{p \mid f(p) = p\}$$

$$f \text{ is reductive at } p : \text{Red}(f) = \{p \mid f(p) \sqsubseteq p\}$$

$$f \text{ is extensive at } p : \text{Ext}(f) = \{p \mid f(p) \sqsupseteq p\}$$

Then

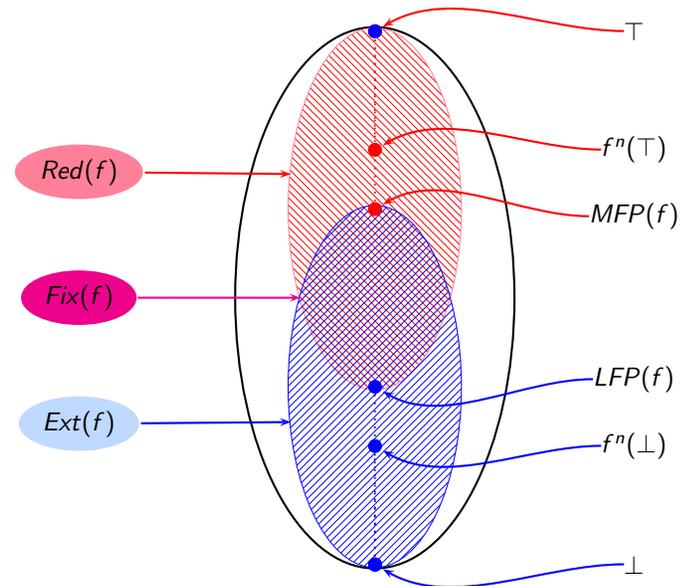
$$\text{LFP}(f) = \bigsqcap \text{Red}(f) \in \text{Fix}(f)$$

$$\text{MFP}(f) = \bigsqcup \text{Ext}(f) \in \text{Fix}(f)$$

Guarantees only existence, not computability of fixed points

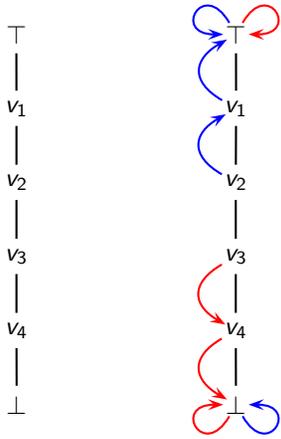


Fixed Points of a Function



Examples of Reductive and Extensive Sets

Finite L Monotonic $f : L \rightarrow L$

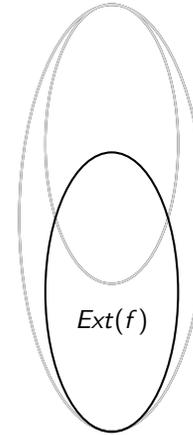


$$\begin{aligned}
 \text{Red}(f) &= \{\top, v_3, v_4, \perp\} \\
 \text{Ext}(f) &= \{\top, v_1, v_2, \perp\} \\
 \text{Fix}(f) &= \text{Red}(f) \cap \text{Ext}(f) \\
 &= \{\top, \perp\} \\
 \text{MFP}(f) &= \text{lub}(\text{Ext}(f)) \\
 &= \text{lub}(\text{Fix}(f)) \\
 &= \top \\
 \text{LFP}(f) &= \text{glb}(\text{Red}(f)) \\
 &= \text{glb}(\text{Fix}(f)) \\
 &= \perp
 \end{aligned}$$



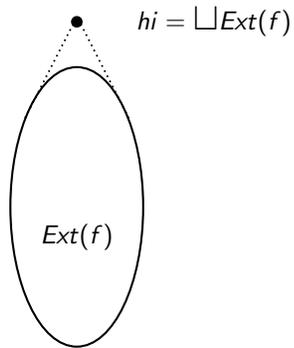
Existence of MFP: Proof of Tarski's Fixed Point Theorem

- Claim 1: Let $X \subseteq L$.
 $\forall x \in X, p \sqsupseteq x \Rightarrow p \sqsupseteq \sqcup(X)$.
- In the following we use $\text{Ext}(f)$ as X



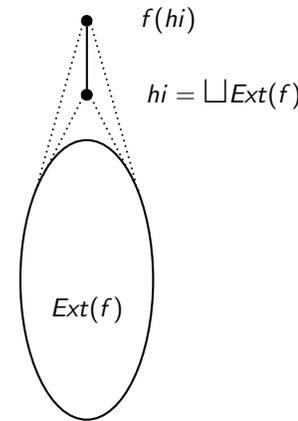
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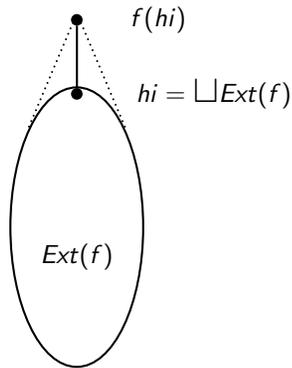
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- $\forall p \in \text{Ext}(f), hi \sqsupseteq p$
- $hi \sqsupseteq p \Rightarrow f(hi) \sqsupseteq f(p) \sqsupseteq p$ (monotonicity)
 $\Rightarrow f(hi) \sqsupseteq hi$ (claim 1)



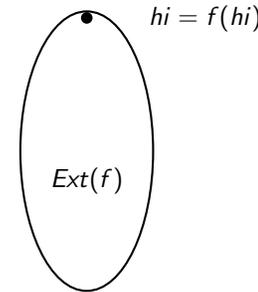
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- f is extensive at hi also: $hi \in Ext(f)$



Existence of MFP: Proof of Tarski's Fixed Point Theorem

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 $\Rightarrow f(hi) \sqsupseteq hi$ (claim 1)
- f is extensive at hi also: $hi \in Ext(f)$
- $f(hi) \sqsupseteq hi \Rightarrow f^2(hi) \sqsupseteq f(hi)$
 $\Rightarrow f(hi) \in Ext(f)$
 $\Rightarrow hi \sqsupseteq f(hi)$ (from 3)
 $\Rightarrow hi = f(hi) \Rightarrow hi \in Fix(f)$
- $Fix(f) \subseteq Ext(f)$ (by definition)
 $\Rightarrow hi \sqsupseteq p, \forall p \in Fix(f)$

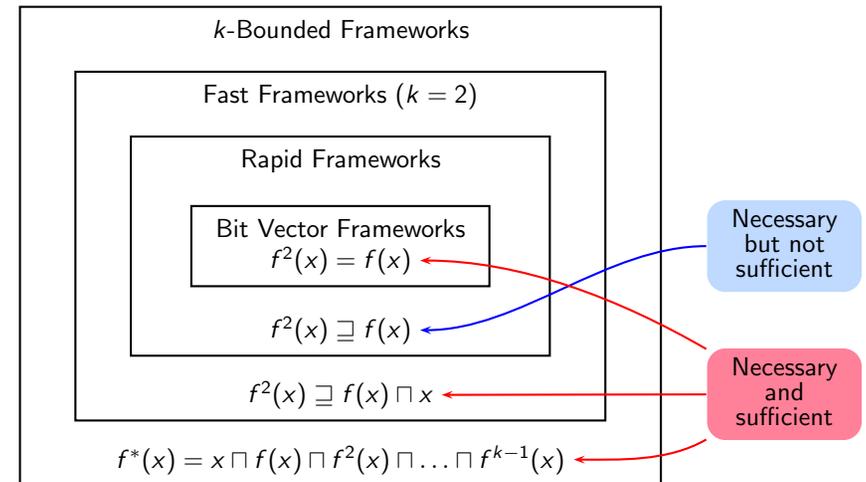


Existence and Computation of the Maximum Fixed Point

- For monotonic $f : L \rightarrow L$
 - Existence: $MFP(f) = \sqcup Ext(f) \in Fix(f)$
 Requires L to be complete
 - Computation: $MFP(f) = f^{k+1}(\top) = f^k(\top)$ such that
 $f^{j+1}(\top) \neq f^j(\top), j < k$.
 Requires all *strictly descending* chains to be finite
- Finite strictly descending and ascending chains
 \Rightarrow Completeness of lattice
- Completeness of lattice $\not\Rightarrow$ Finite strictly descending chains
- \Rightarrow Even if MFP exists, it may not be reachable unless all strictly descending chains are finite

Framework Properties Influencing Complexity

Depends on the loop closure properties of the framework



Complexity of Round Robin Iterative Algorithm

- Unidirectional rapid frameworks

Task	Number of iterations	
	Irreducible G	Reducible G
Initialisation	1	1
Convergence (until <i>change</i> remains true)	$d(G, T) + 1$	$d(G, T)$
Verifying convergence (<i>change</i> becomes false)	1	1

