
FO definable Transformations of Infinite strings

Vrunda Dave, S. Krishna, Ashutosh Trivedi

Outline

- **Introduction**
 - Three formalisms for transductions
 - Related work
 - Aperiodic transformations for Infinite strings
 - Aperiodic two way transducer
 - Aperiodic streaming string transducer
 - Equivalence results and Proof ideas
 - $SST_{sf} \subset FOT = 2WST_{sf} \subset SST_{sf}$
 - Conclusion
-

Introduction

- Three formalisms for transformations:
-

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 - Logic
-

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 - Two way machines
-

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- Three formalisms for transformations:
 - Logic
 - Two way machines
 - One way machines with finite registers
-

Logic Transducer

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[Courcelle'94]

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input

Logic Transducer

[Courcelle'94]

input

a_1

a_2

a_3

a_4

a_5

a_6

a_7

a_8

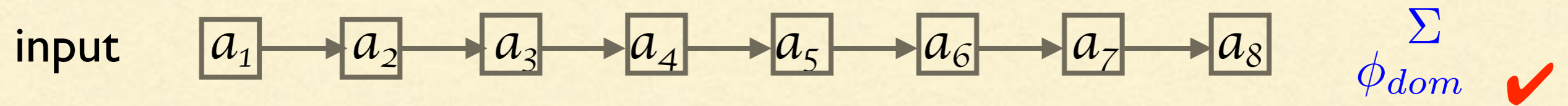
Logic Transducer

[Courcelle'94]

input a_1 a_2 a_3 a_4 a_5 a_6 a_7 a_8 Σ
 ϕ_{dom} ✓

Logic Transducer

[Courcelle'94]



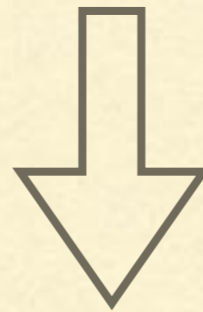
Logic Transducer

[Courcelle'94]

input



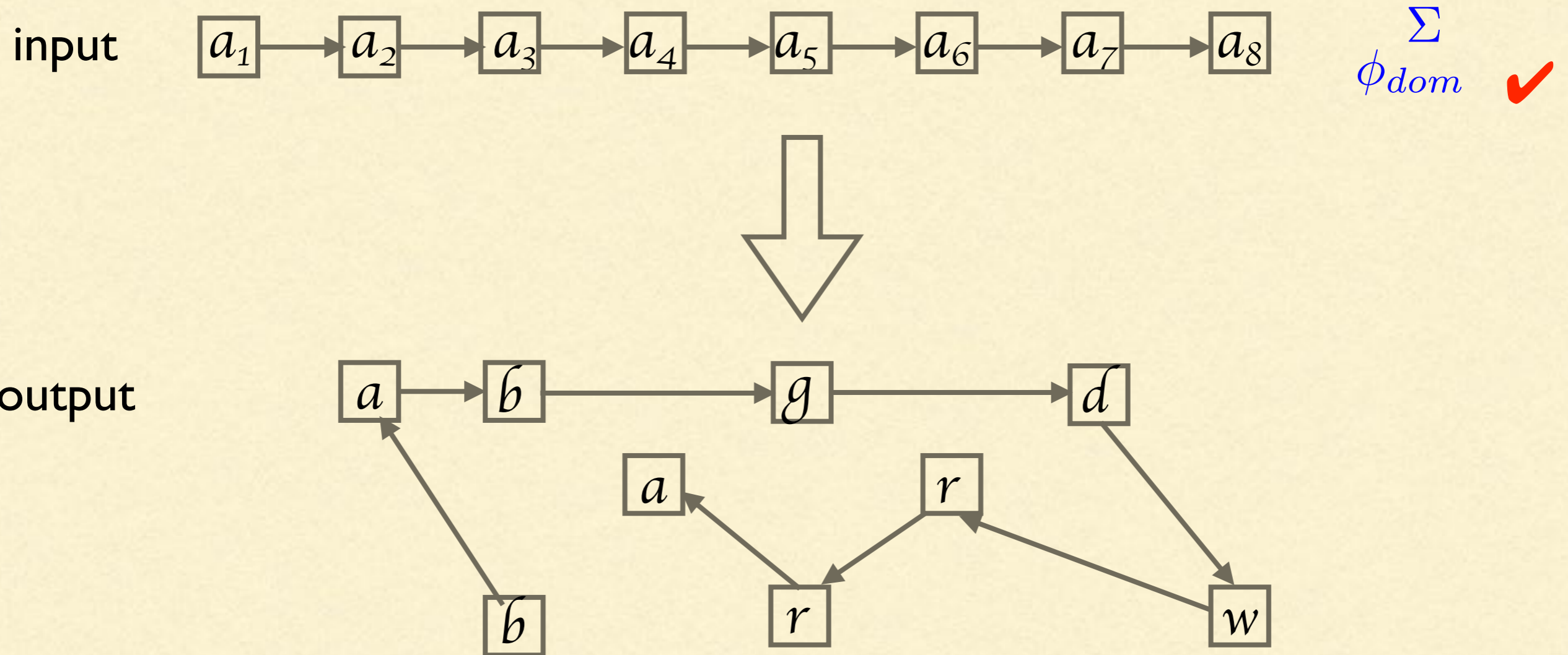
Σ
 ϕ_{dom} ✓



output

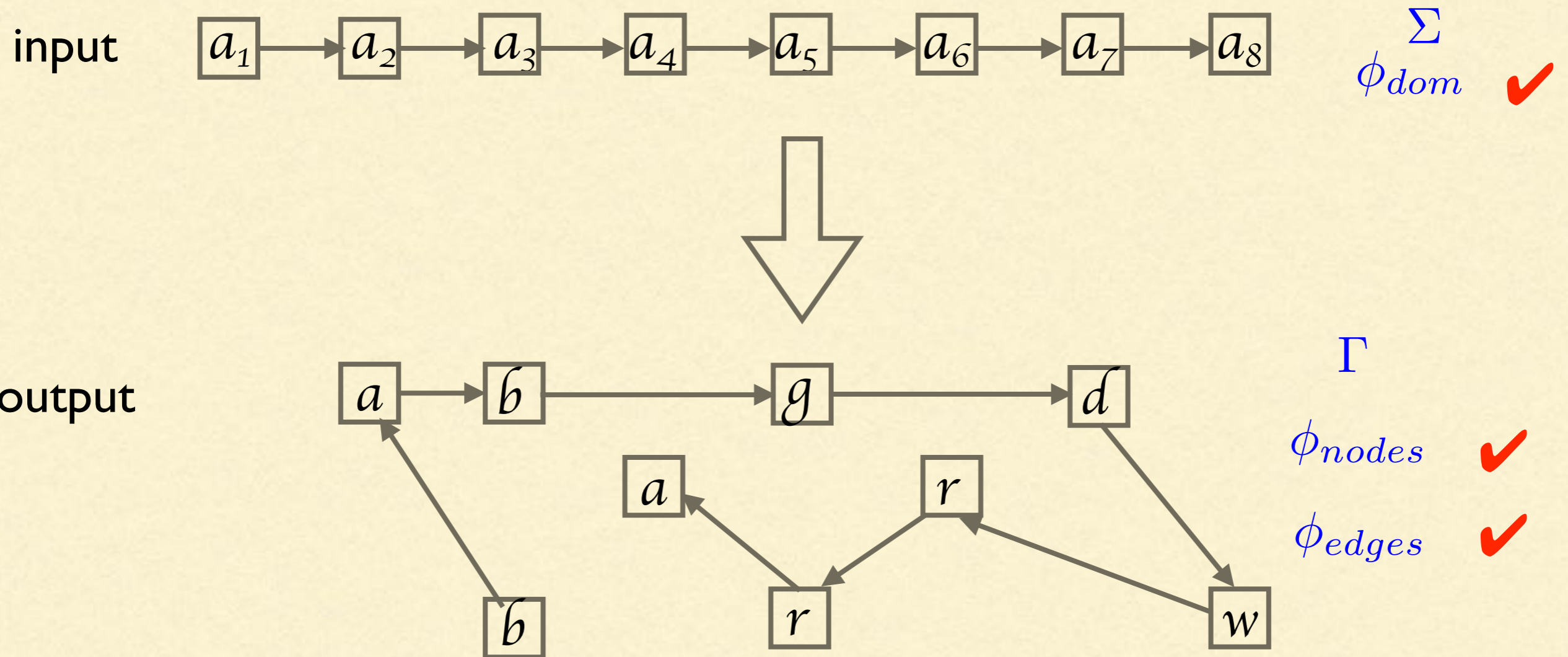
Logic Transducer

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Logic Transducer

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$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

where $u_i \in \{a, b\}^*$ and $v \in \{a, b\}^\omega$

FO/ MSO transducer

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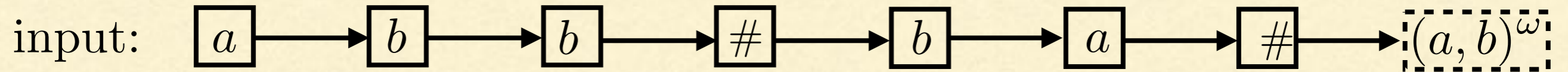
FO/ MSO transducer

input: a b b $\#$ b a $\#$ $(a, b)^\omega$

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

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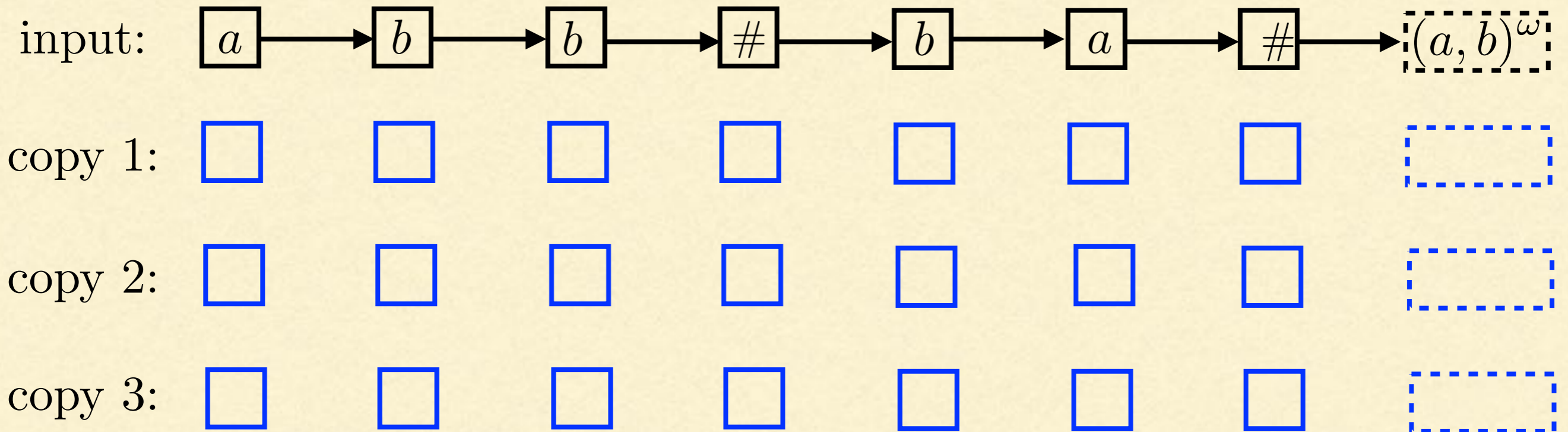
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FO/ MSO transducer



$$\phi_\gamma^1(x) = \phi_\gamma^2(x) = L_\gamma(x) \wedge \neg L_\#(x) \wedge \text{reach}_\#(x)$$

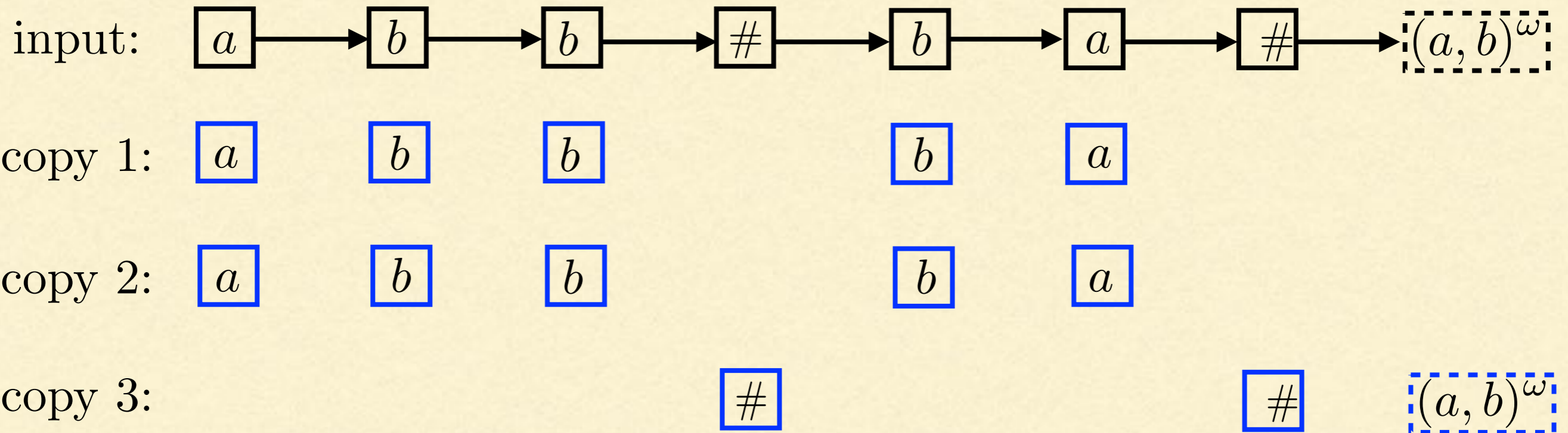
$$\phi_\gamma^3(x) = L_\#(x) \vee \neg \text{reach}_\#(x)$$

$$\text{reach}_\#(x) = \exists y(x \prec y \wedge L_\#(y))$$

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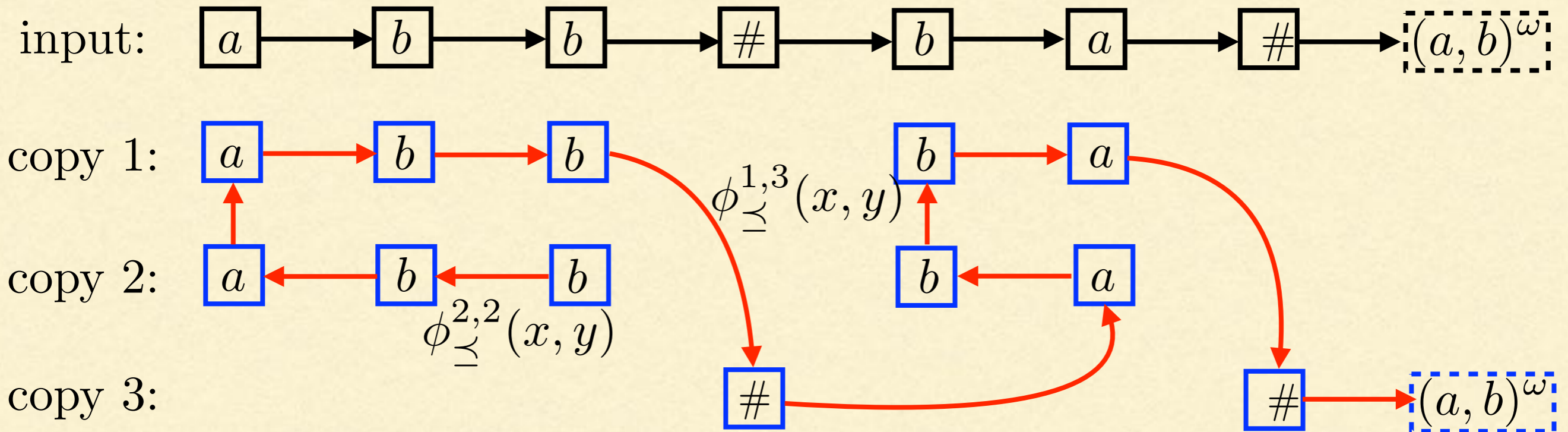
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Two way machine

Two way machine

[Rabin, Scott'59]

[Ehrich, Yau'71]

Two way machine

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input

Two way machine

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input

a_1

a_2

a_3

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a_5

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a_8

Two way machine

[Rabin, Scott'59]

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a_1

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output

Two way machine

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input

a_1 a_2 a_3 a_4 a_5 a_6 a_7 a_8



output



Look-around automaton

Look-around automaton

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Look-around automaton

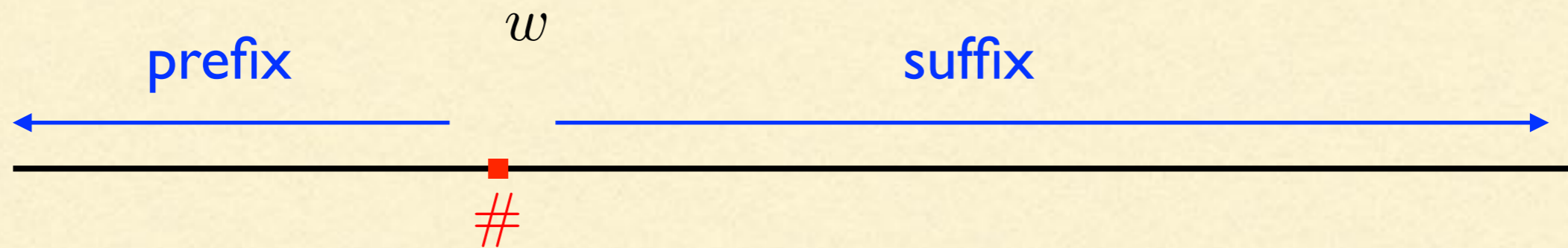
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w



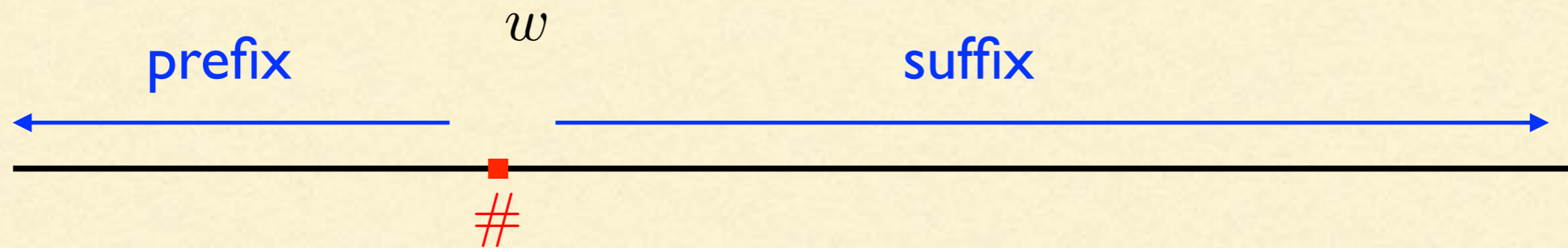
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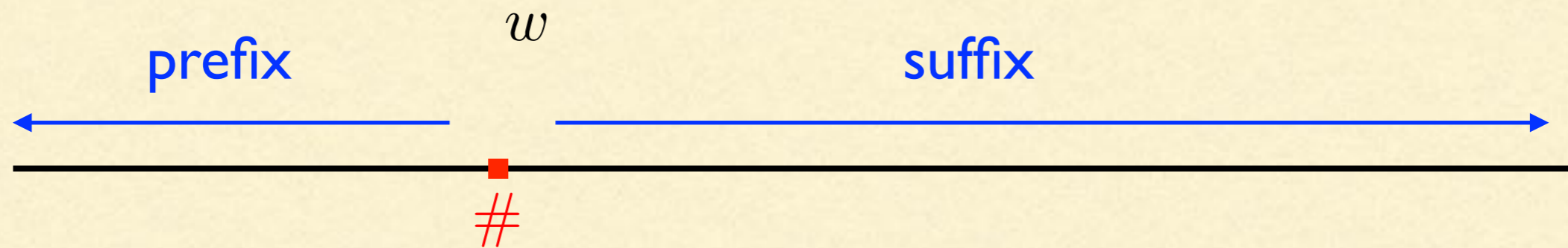
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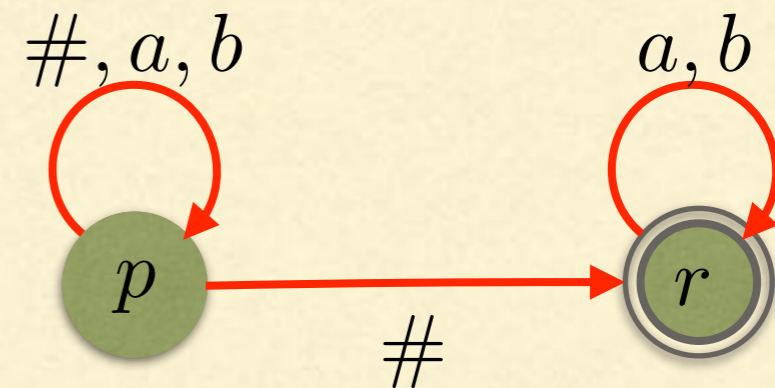
property: suffix does not contain #

Look-around automaton

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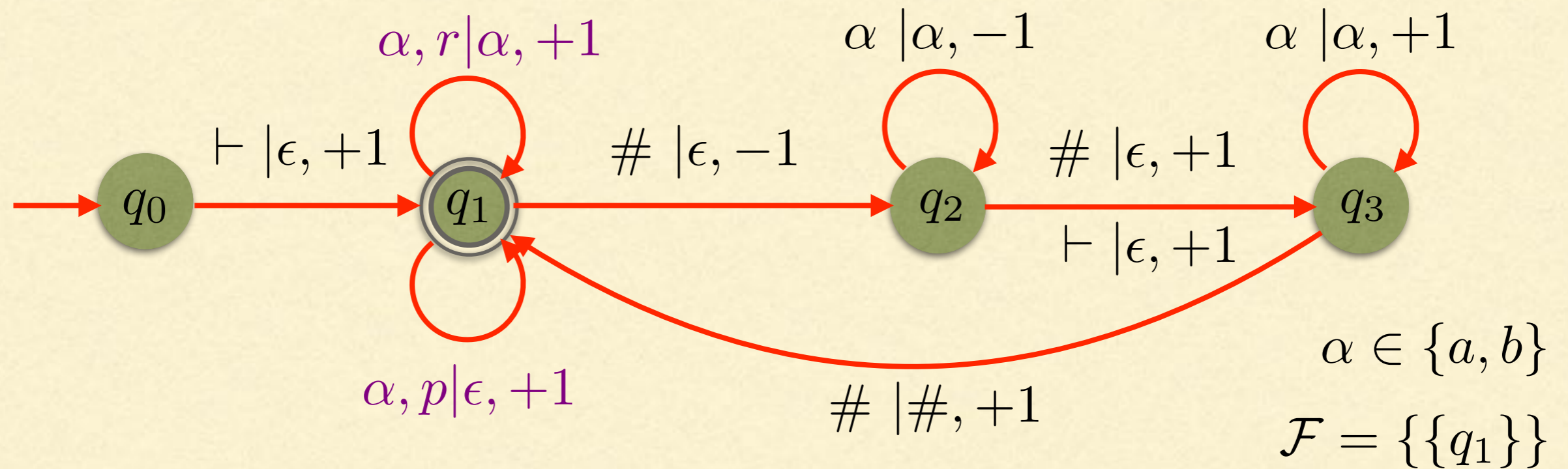
where $u_i \in \{a, b\}^*$ and $v \in \{a, b\}^\omega$

Two way Transducer (2WST)

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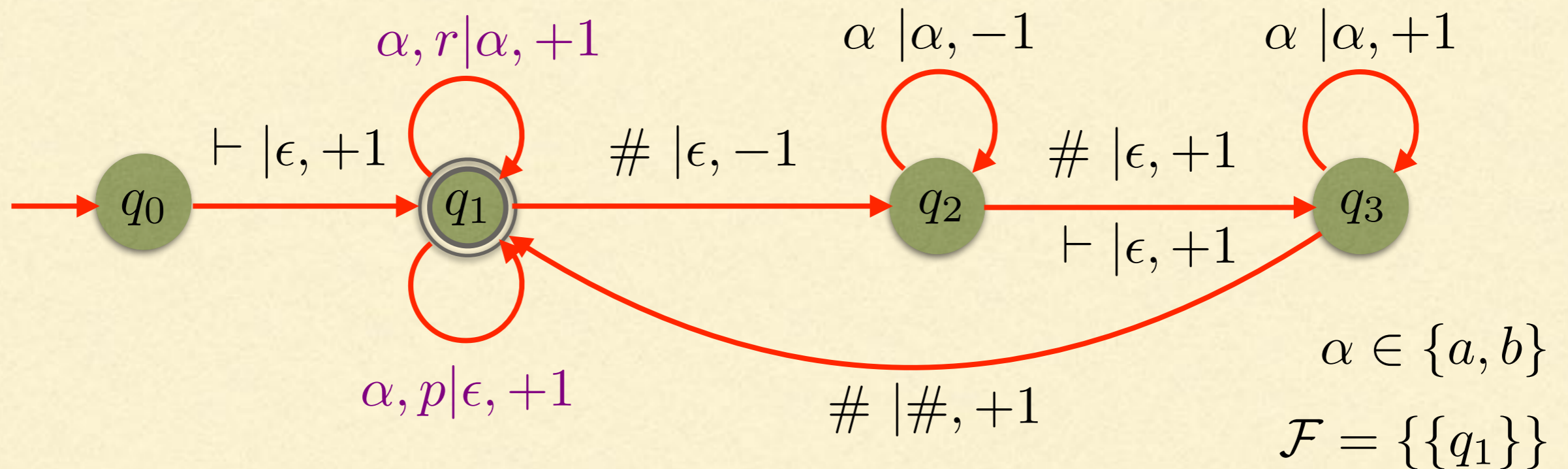
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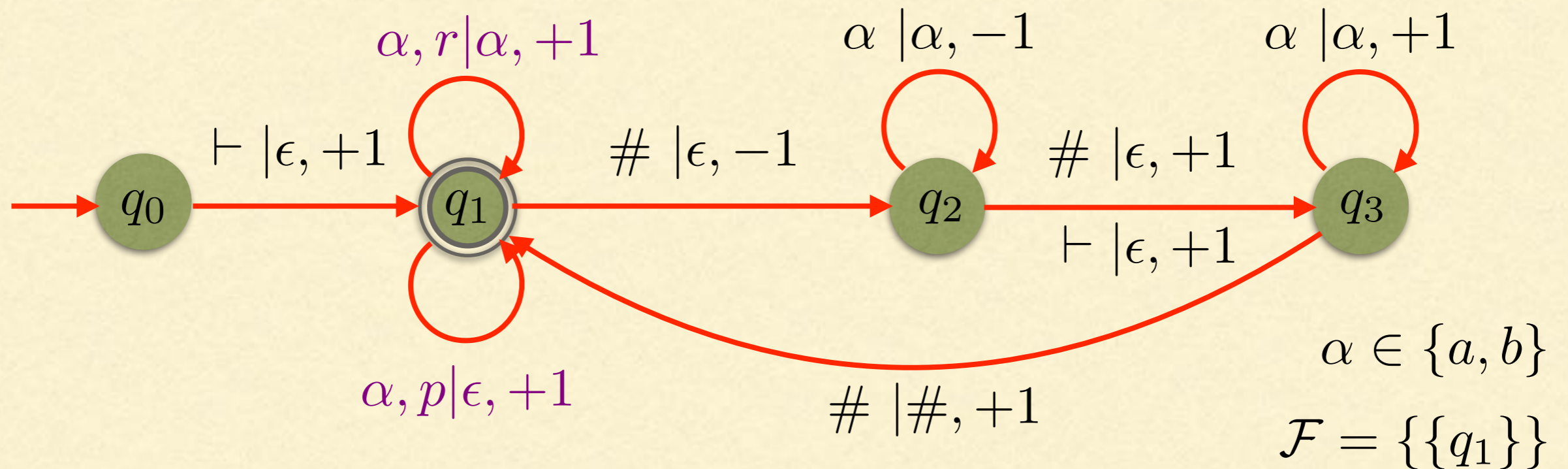
\vdash a b b # (a + b) $^\omega$



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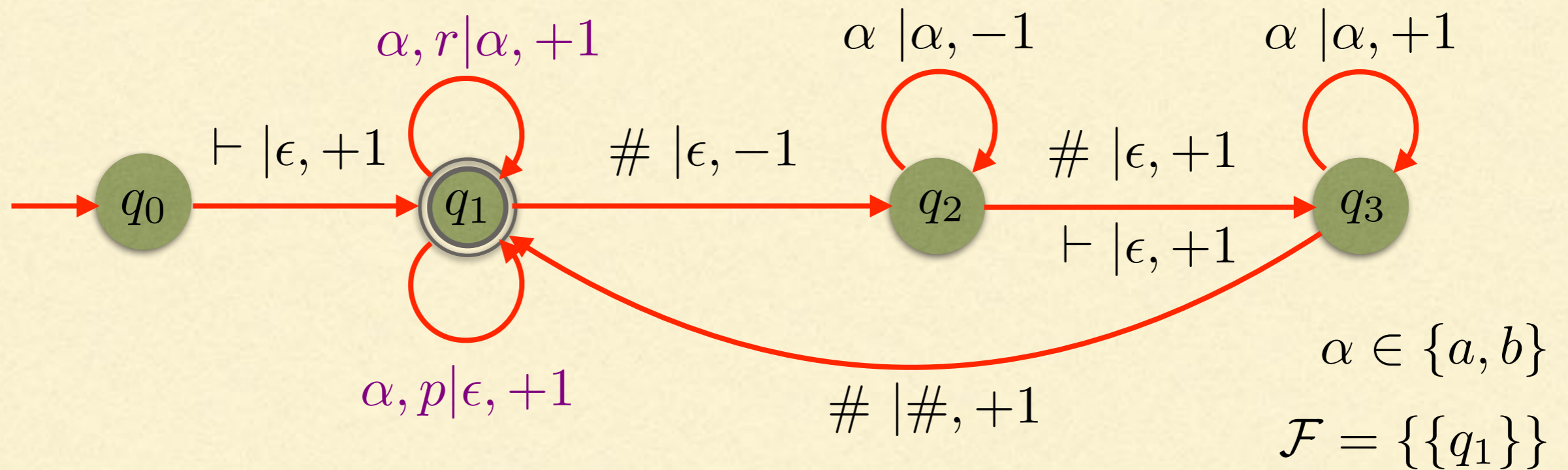
\vdash **a** **b** **b** **#** **(a + b) $^\omega$**



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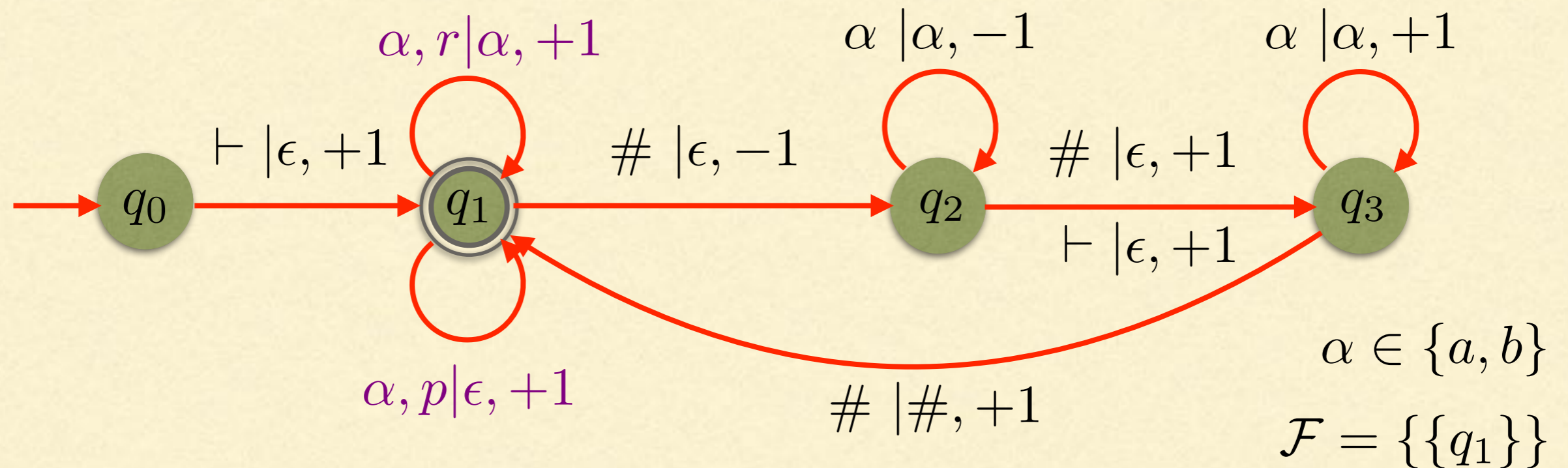
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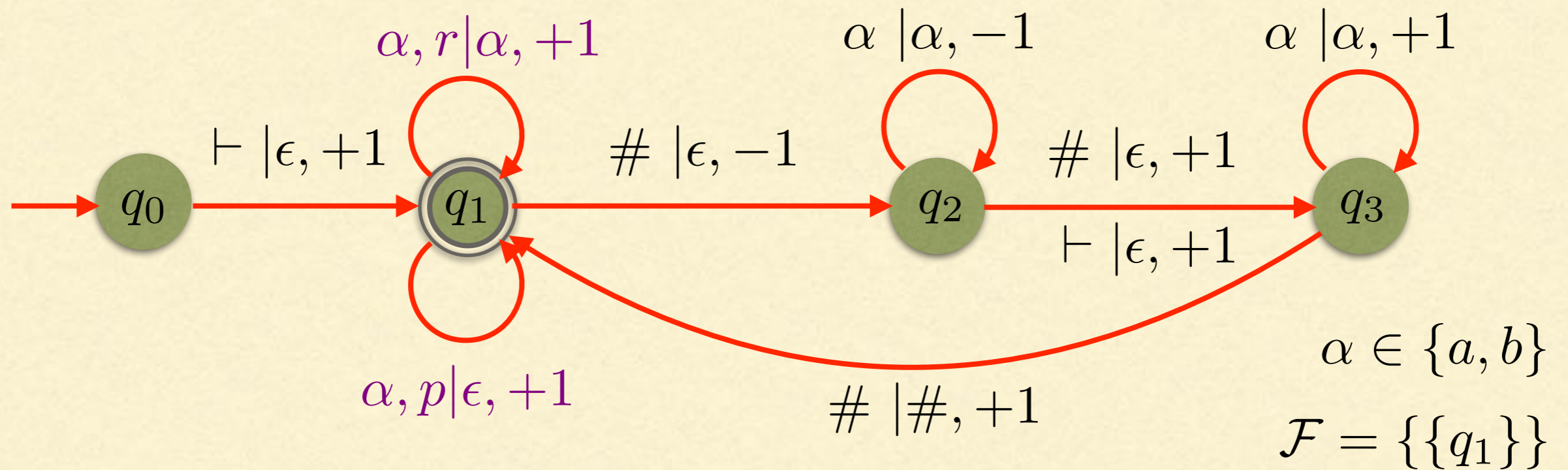
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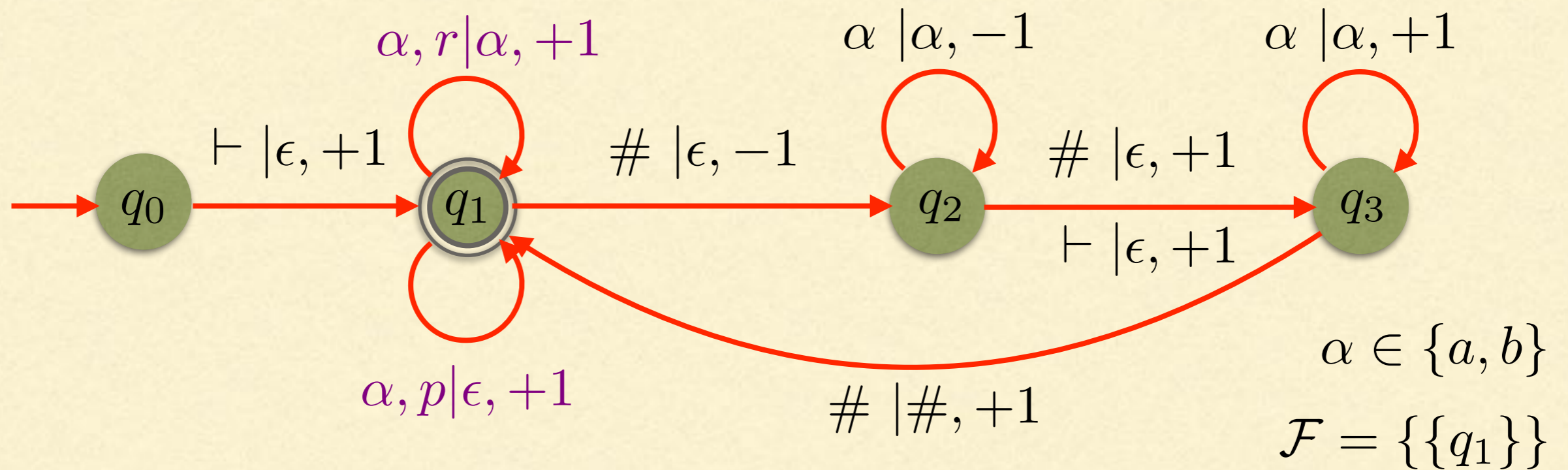


b b a

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Two way Transducer (2WST)



\vdash **a** **b** **b** **#** **(a + b) $^\omega$**

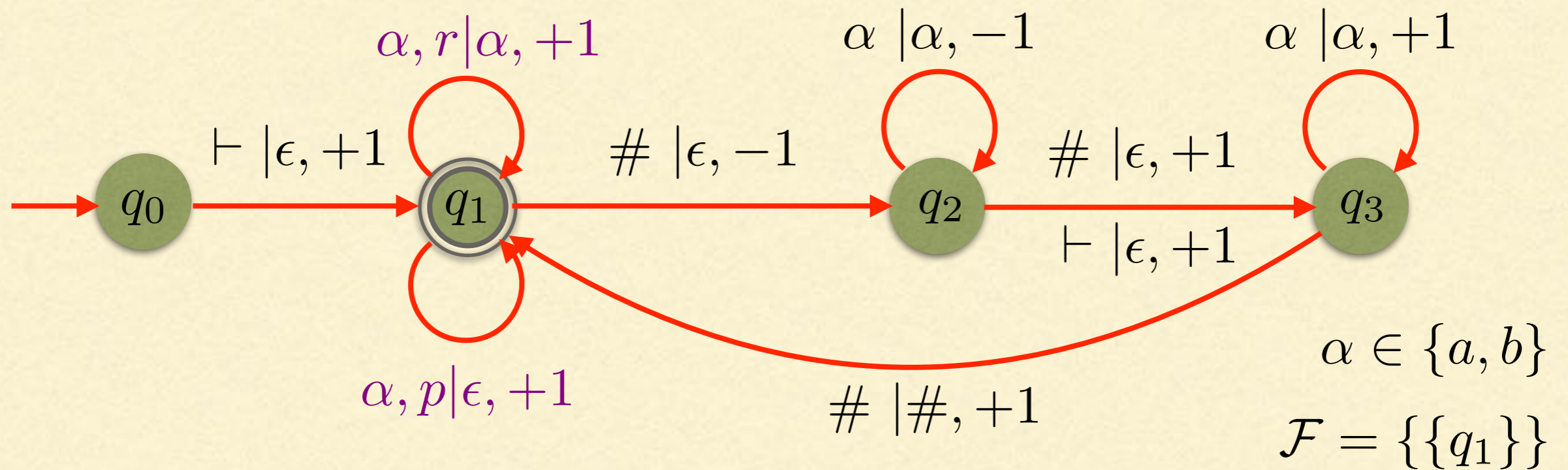


b **b** **a**

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Two way Transducer (2WST)



\vdash **a** **b** **b** **#** $(a + b)^\omega$

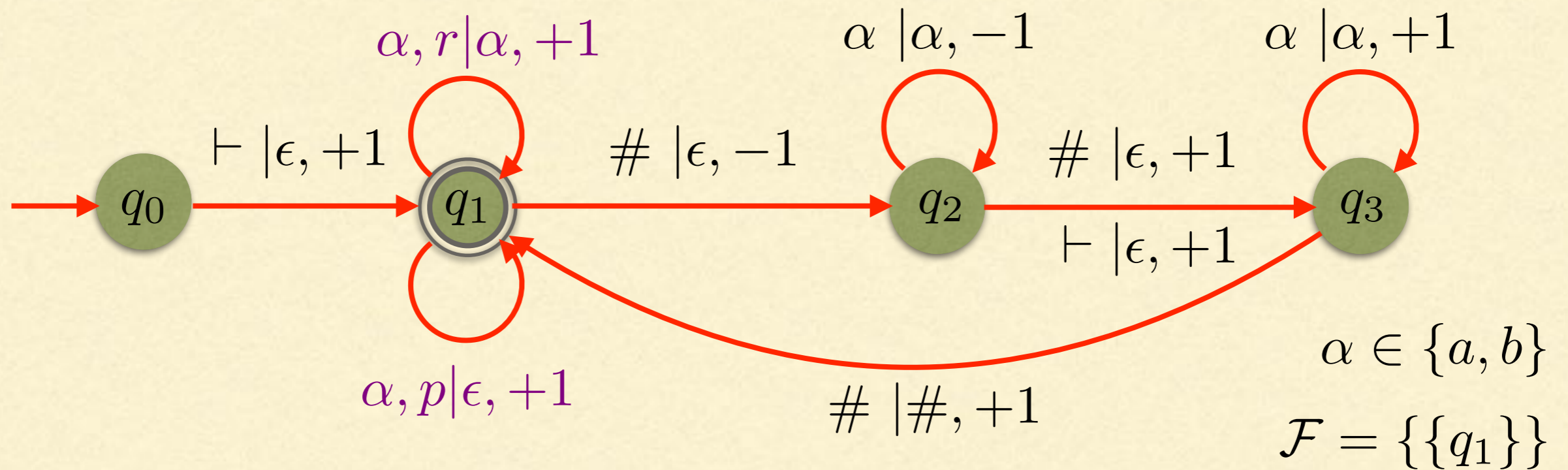
↑

b **b** **a** **a** **b** **b**

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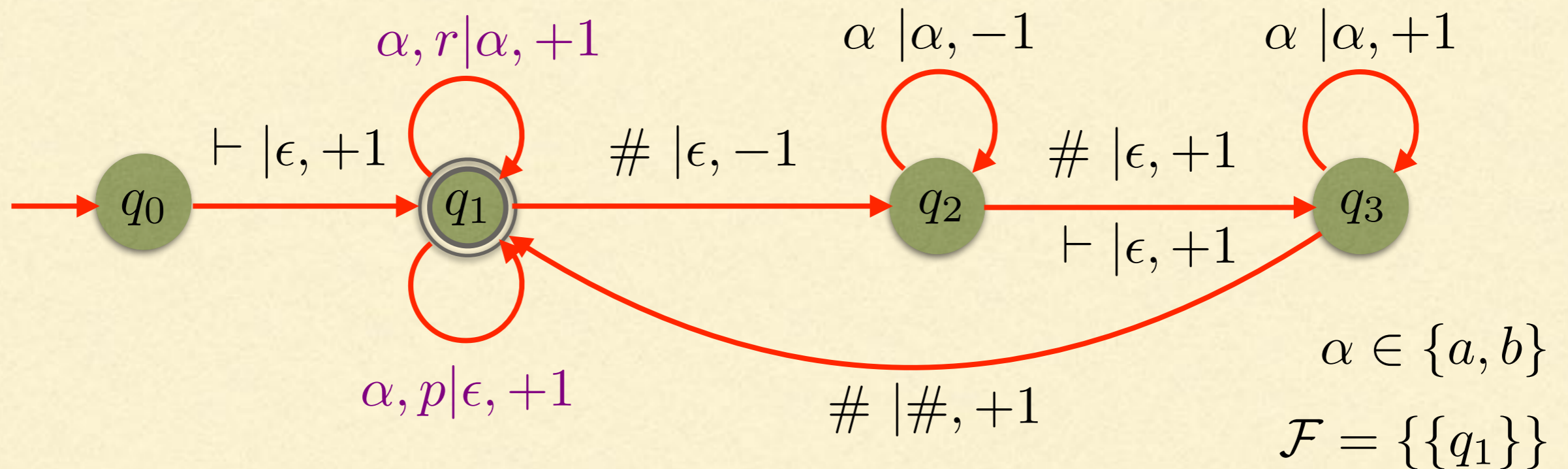
b b a a b b #



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Two way Transducer (2WST)



\vdash a b b # (a + b) $^\omega$

b b a a b b # (a + b) $^\omega$



One way machine with finite registers

One way machine with finite registers

[Alur, Černý'10]

One way machine with finite registers

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input :

a_1

a_2

a_3

a_4

One way machine with finite registers

[Alur, Černý'10]

input : a_1 a_2 a_3 a_4

registers : $x, y, z...$

One way machine with finite registers

[Alur, Černý'10]

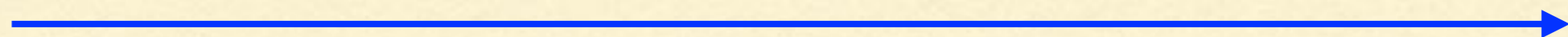
input :

a_1

a_2

a_3

a_4



$$x = ax$$

$$y = bycz$$

$$z = c$$

$$x = \varepsilon$$

$$y = cz$$

$$z = by$$

$$x = ax$$

$$y = bycz$$

$$z = c$$

$$x = \varepsilon$$

$$y = cz$$

$$z = by$$

registers :

x, y, z, \dots

One way machine with finite registers

[Alur, Černý'10]

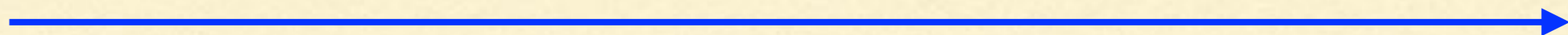
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$$z = by$$

$$x = ax$$

$$y = bycz$$

$$z = c$$

$$x = \varepsilon$$

$$y = cz$$

$$z = by$$

registers :

x, y, z, \dots

output :

$x a y z$

One way machine with finite registers

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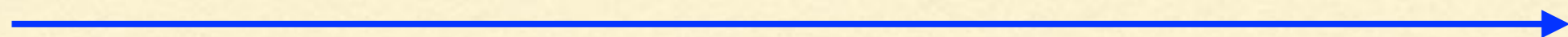
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$$y = bycz$$

$$z = c$$

$$x = \varepsilon$$

$$y = cz$$

$$z = by$$

registers : x, y, z, \dots

output : $x a y z$

copyless update :

One way machine with finite registers

[Alur, Černý'10]

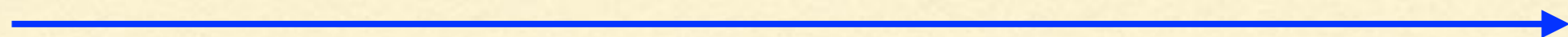
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$$z = by$$

$$x = ax$$

$$y = bycz$$

$$z = c$$

$$x = \varepsilon$$

$$y = cz$$

$$z = by$$

registers : x, y, z, \dots

output : $x a y z$

copyless update :

$$x = ax$$

$$y = bycz$$

$$z = c$$

$$x = ax$$

$$y = bycz$$

$$z = cx$$

One way machine with finite registers

[Alur, Černý'10]

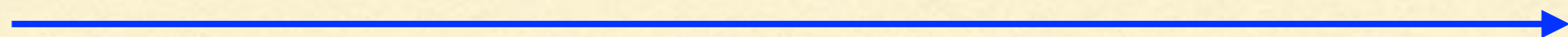
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$$z = by$$

$$x = ax$$

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$$x = \varepsilon$$

$$y = cz$$

$$z = by$$

registers : x, y, z, \dots

output : $x a y z$

copyless update :

$$\begin{aligned} x &= ax \\ y &= bycz \quad \checkmark \\ z &= c \end{aligned}$$

$$\begin{aligned} x &= ax \\ y &= bycz \\ z &= cx \end{aligned}$$

One way machine with finite registers

[Alur, Černý'10]

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a_3

a_4



$$x = ax$$

$$y = bycz$$

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$$z = by$$

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$$y = bycz$$

$$z = c$$

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$$y = cz$$

$$z = by$$

registers : x, y, z, \dots

output : $x a y z$

copyless update :

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$$\begin{aligned} x &= ax \\ y &= bycz \quad \times \\ z &= cx \end{aligned}$$

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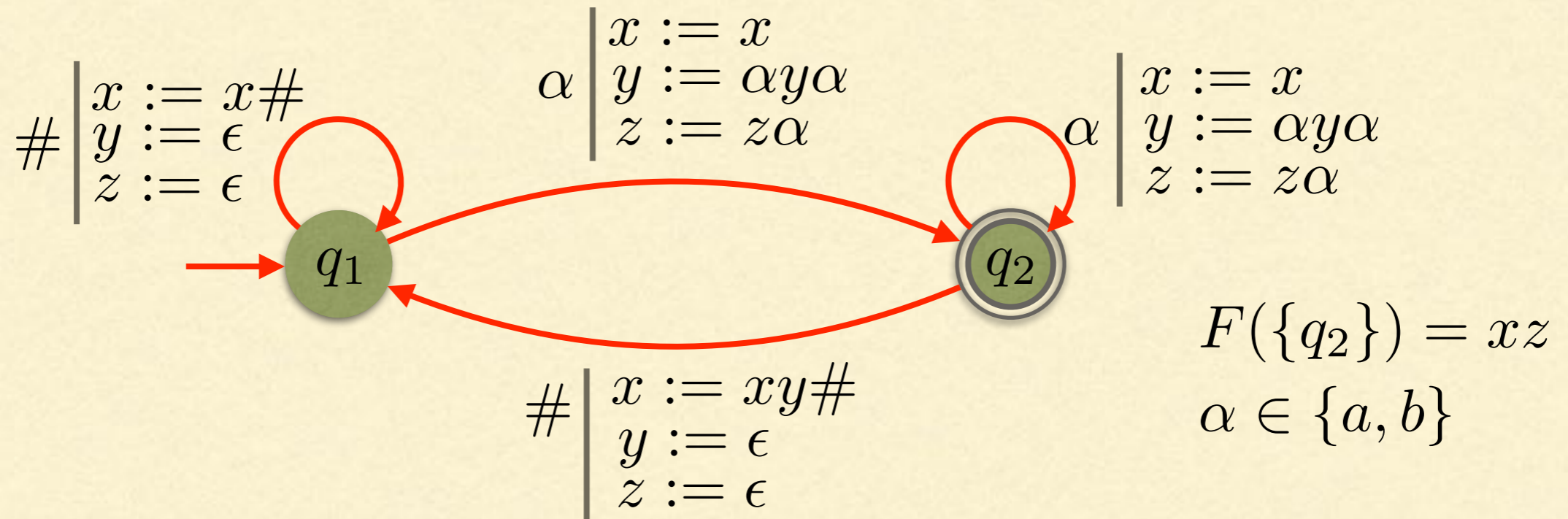
where $u_i \in \{a, b\}^*$ and $v \in \{a, b\}^\omega$

Streaming String Transducer (SST)

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where $u_i \in \{a, b\}^*$ and $v \in \{a, b\}^\omega$

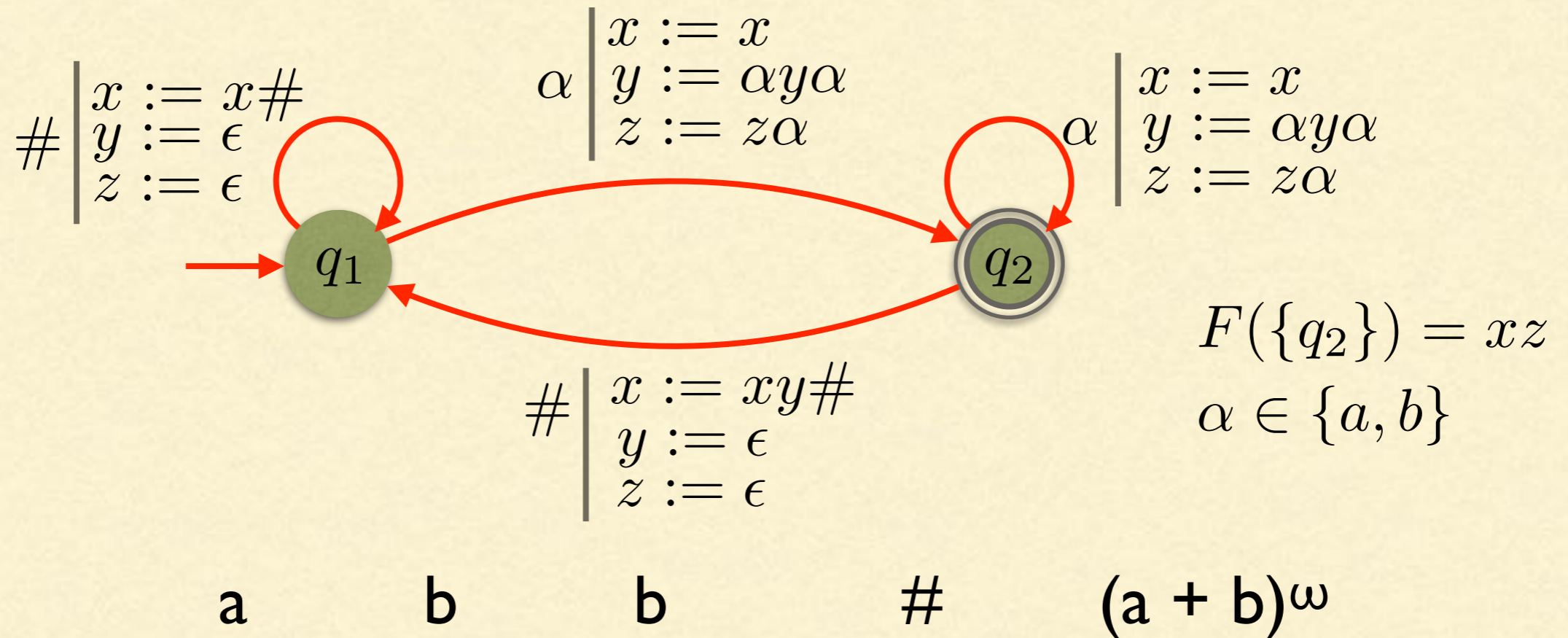
Streaming String Transducer (SST)



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where $u_i \in \{a, b\}^*$ and $v \in \{a, b\}^\omega$

Streaming String Transducer (SST)



$$F(\{q_2\}) = xz$$

$$\alpha \in \{a, b\}$$

x: ϵ

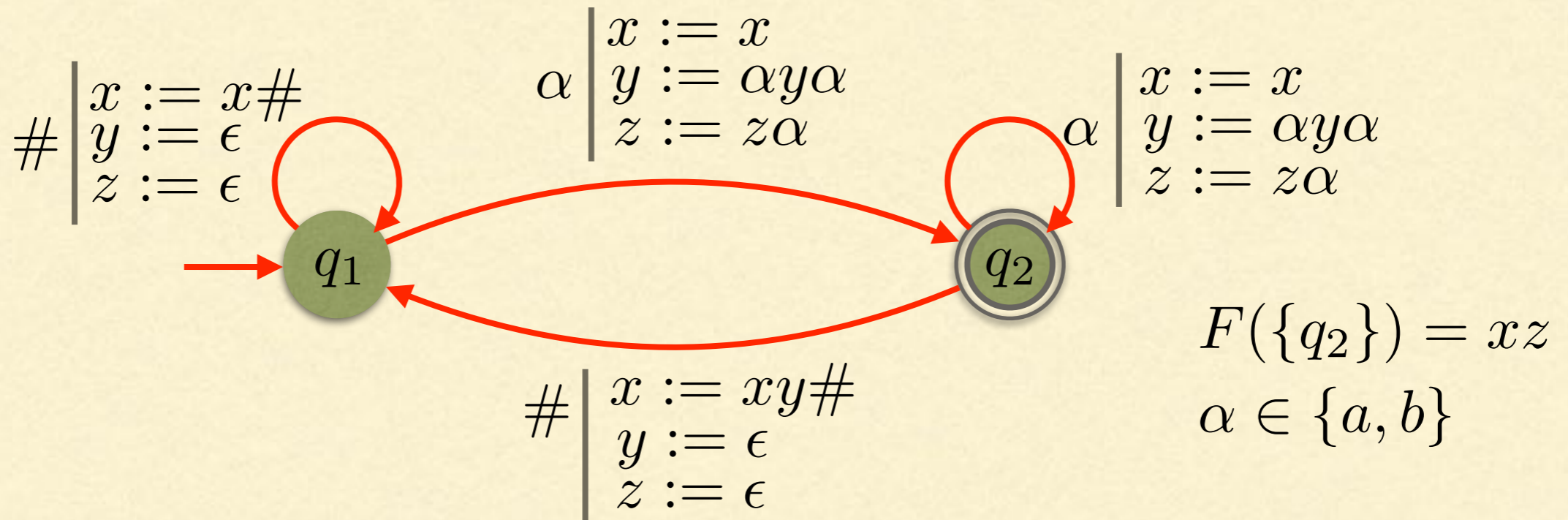
y: ϵ

z: ϵ

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

where $u_i \in \{a, b\}^*$ and $v \in \{a, b\}^\omega$

Streaming String Transducer (SST)



a b b # (a + b) $^\omega$

x: ϵ ϵ

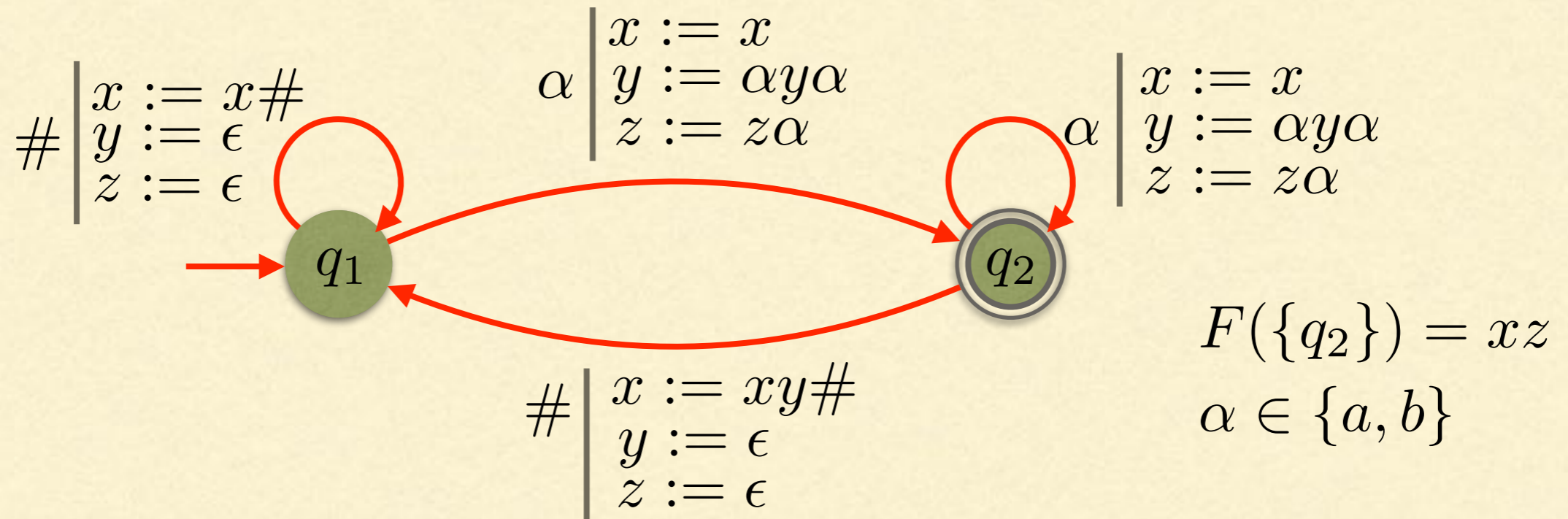
y: ϵ aa

z: ϵ a

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

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Streaming String Transducer (SST)

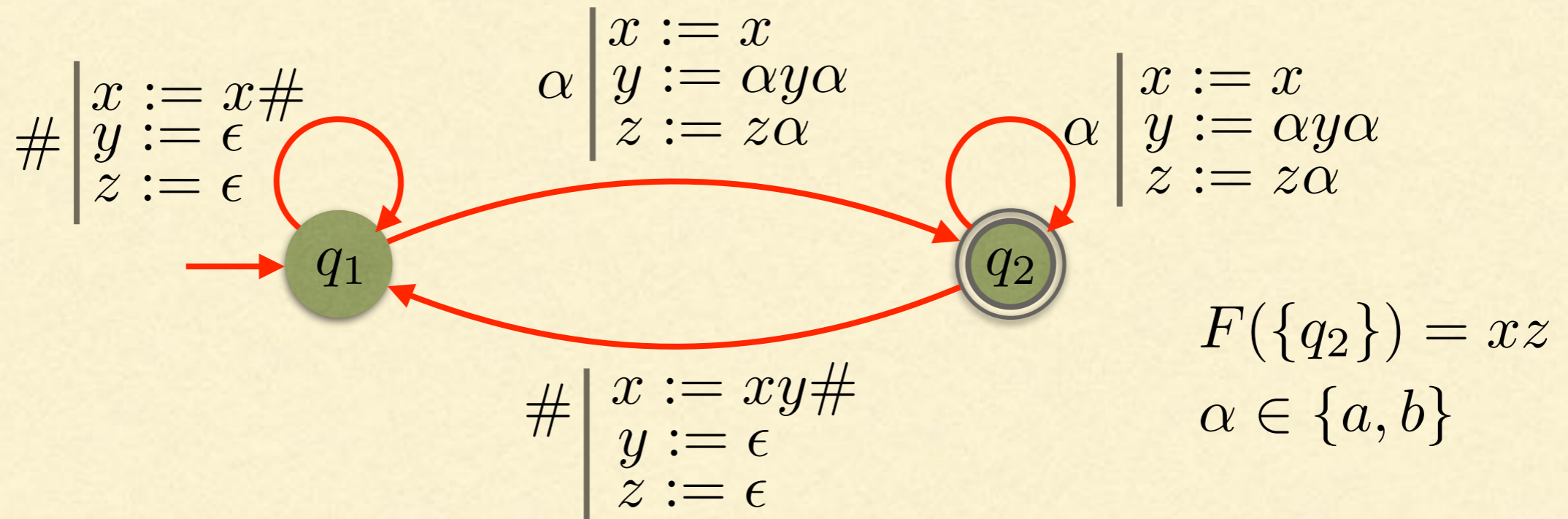


		a	b	b	#	$(a + b)^\omega$
x:	ϵ	ϵ	ϵ	ϵ		
y:	ϵ	aa	baab	bbaabb		
z:	ϵ	a	ab	abb		

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

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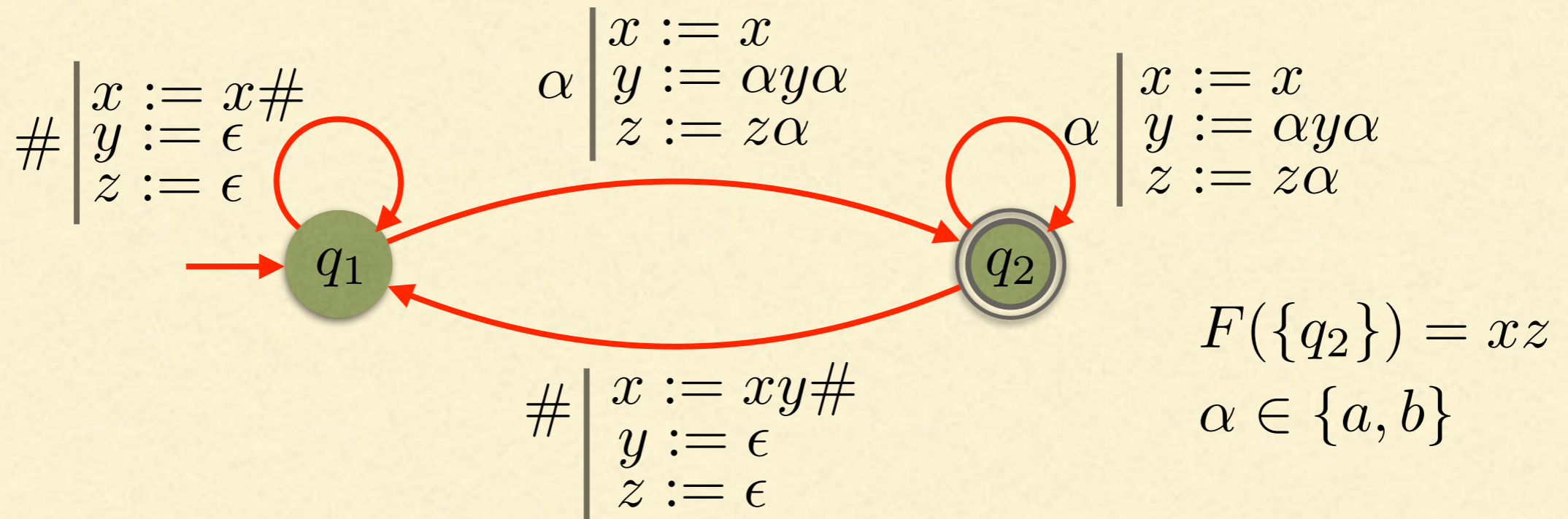


		a	b	b	#	$(a + b)^\omega$
x:	ϵ	ϵ	ϵ	ϵ	bbaabb#	
y:	ϵ	aa	baab	bbaabb	ϵ	
z:	ϵ	a	ab	abb	ϵ	

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

where $u_i \in \{a, b\}^*$ and $v \in \{a, b\}^\omega$

Streaming String Transducer (SST)

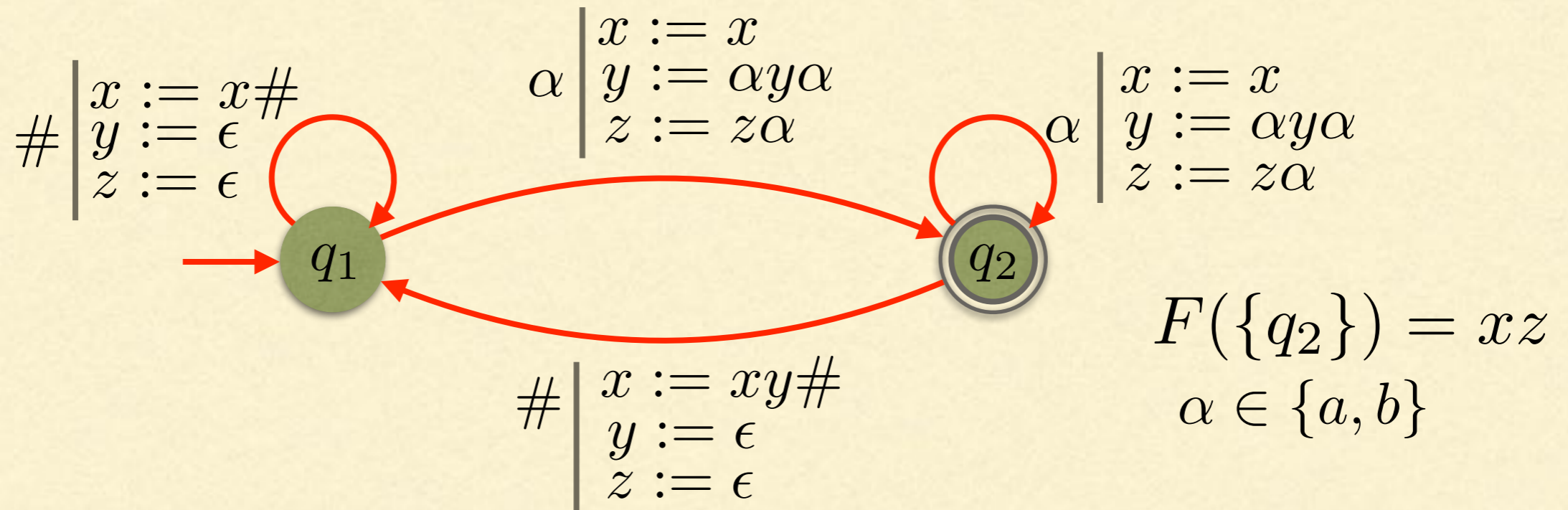


		a	b	b	#	$(a + b)^\omega$
x:	ϵ	ϵ	ϵ	ϵ	bbaabb#	bbaabb#
y:	ϵ	aa	baab	bbaabb	ϵ	
z:	ϵ	a	ab	abb	ϵ	$(a + b)^\omega$

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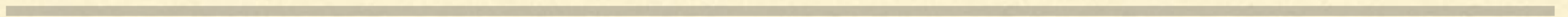
Streaming String Transducer (SST)



		a	b	b	#	$(a + b)^\omega$
x:	ϵ	ϵ	ϵ	ϵ	bbaabb#	bbaabb#
y:	ϵ	aa	baab	bbaabb	ϵ	
z:	ϵ	a	ab	abb	ϵ	$(a + b)^\omega$

Related Work

Related Work



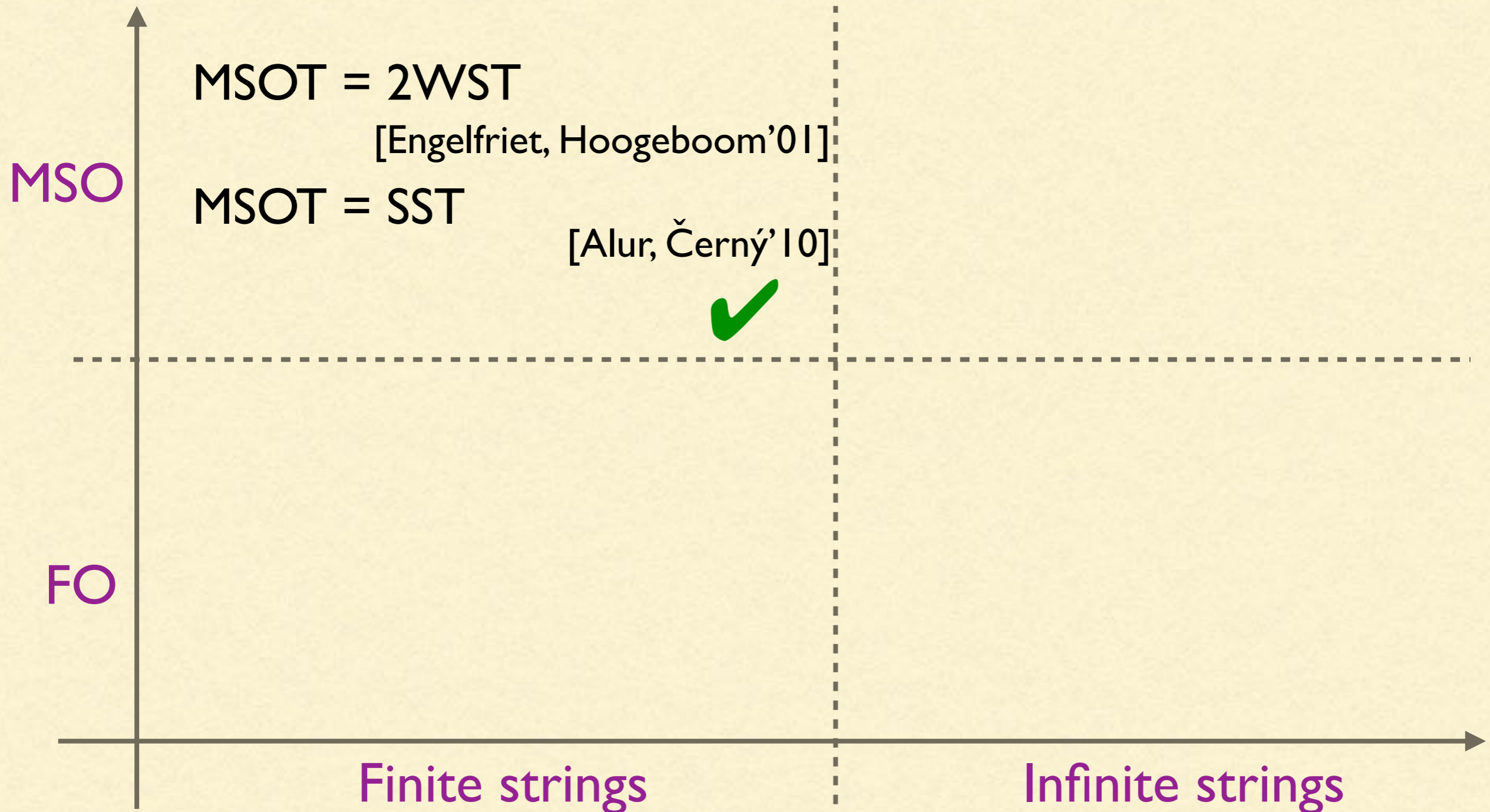
Related Work



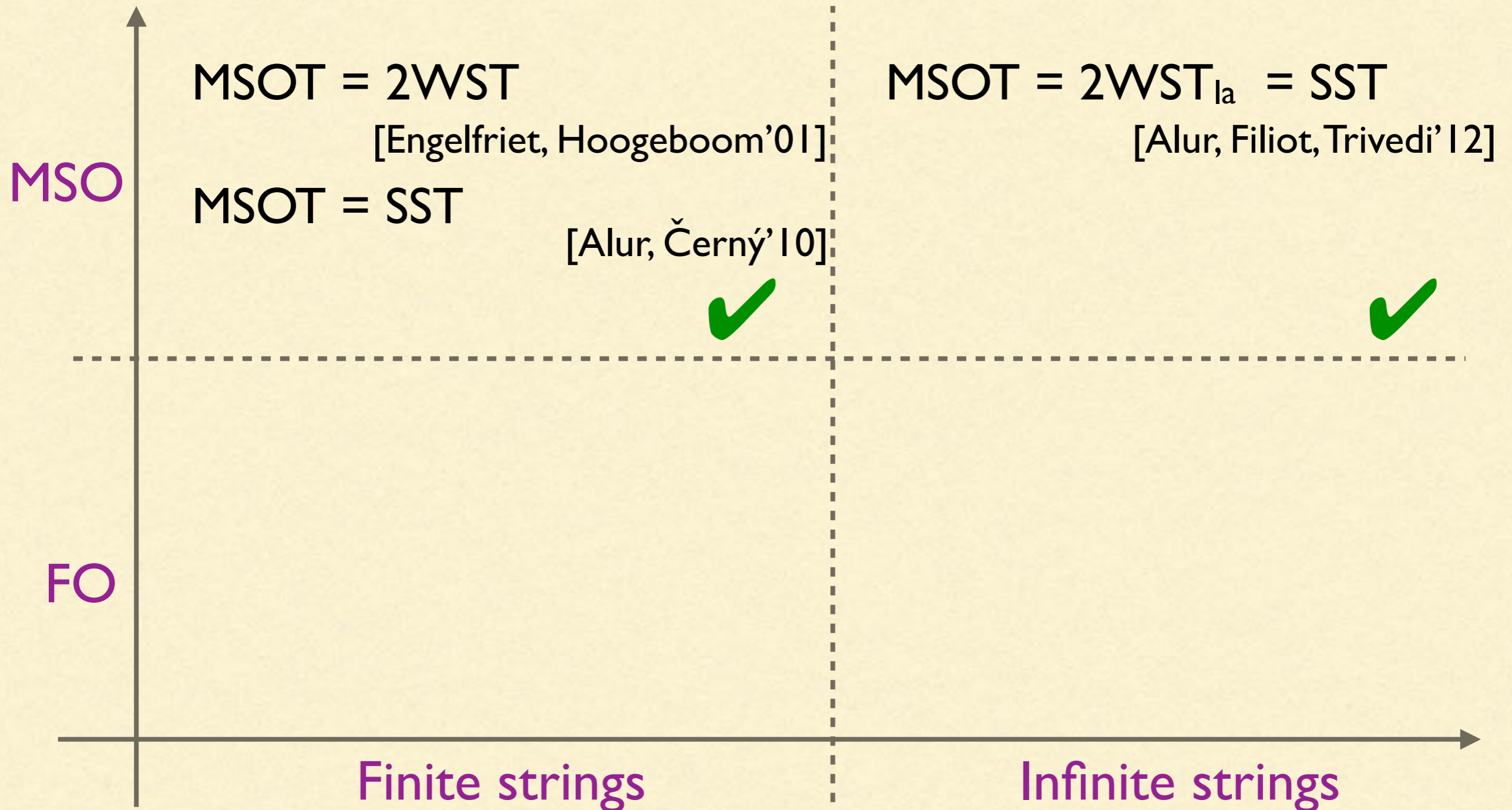
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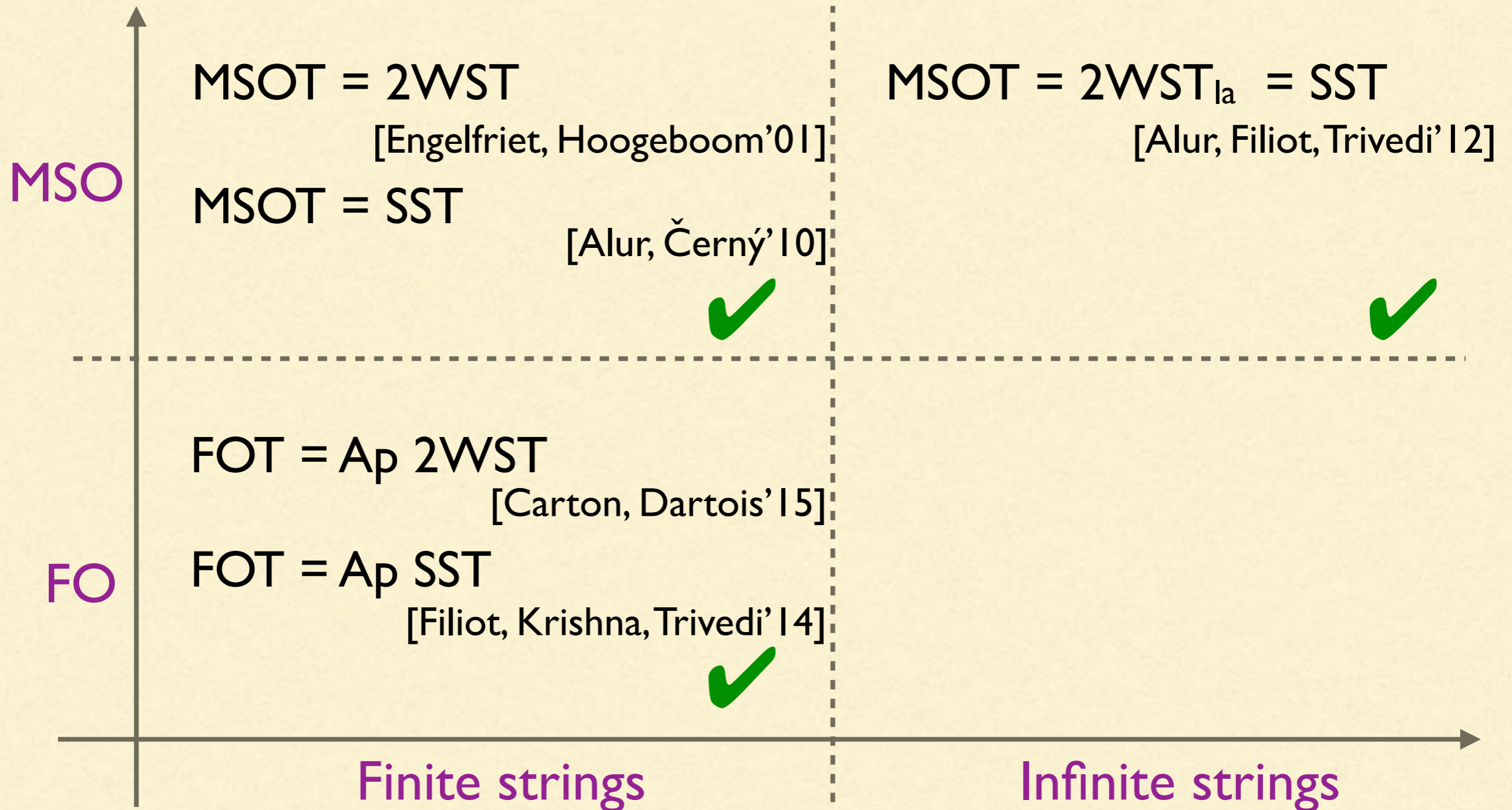
Related Work



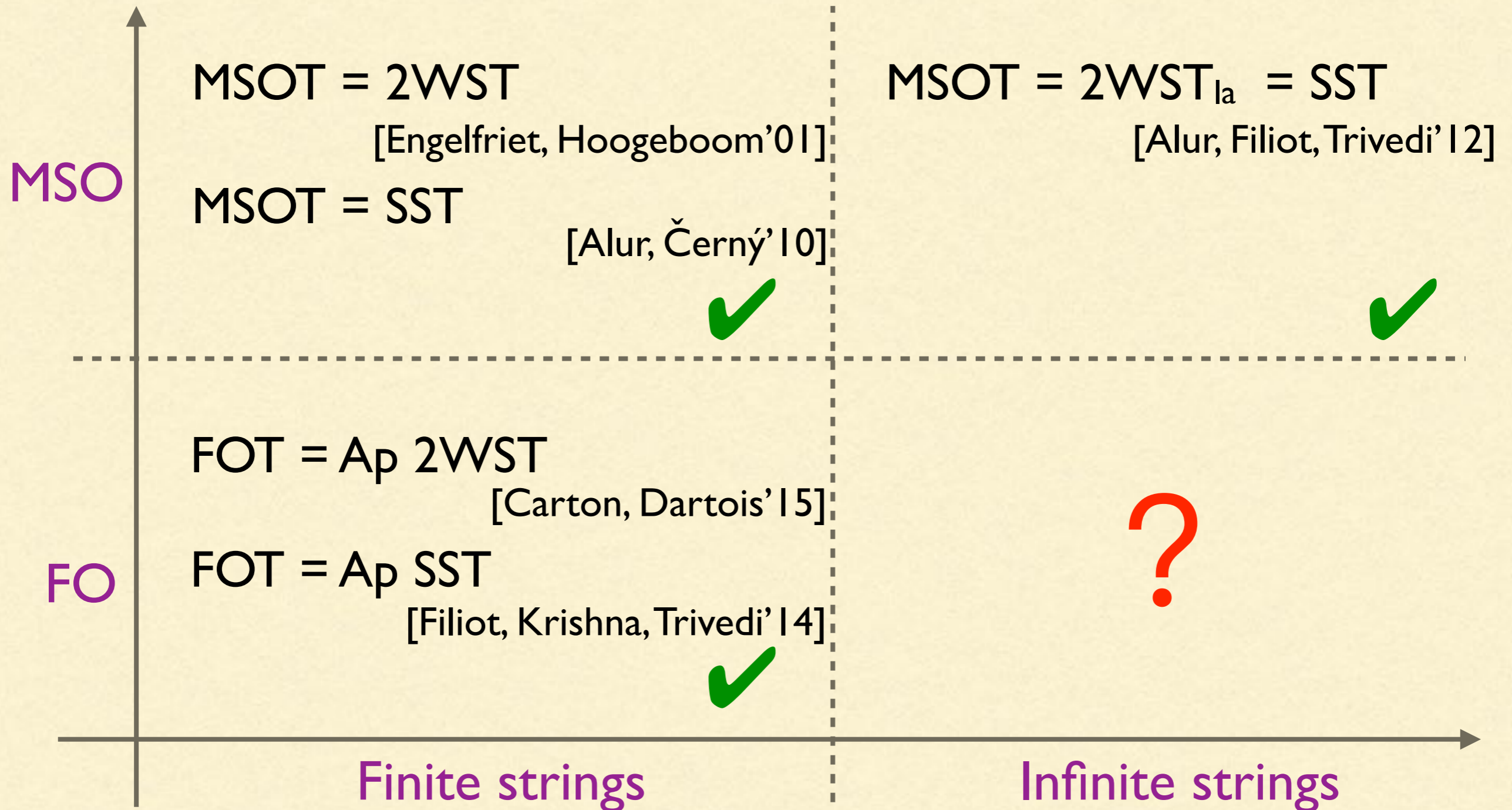
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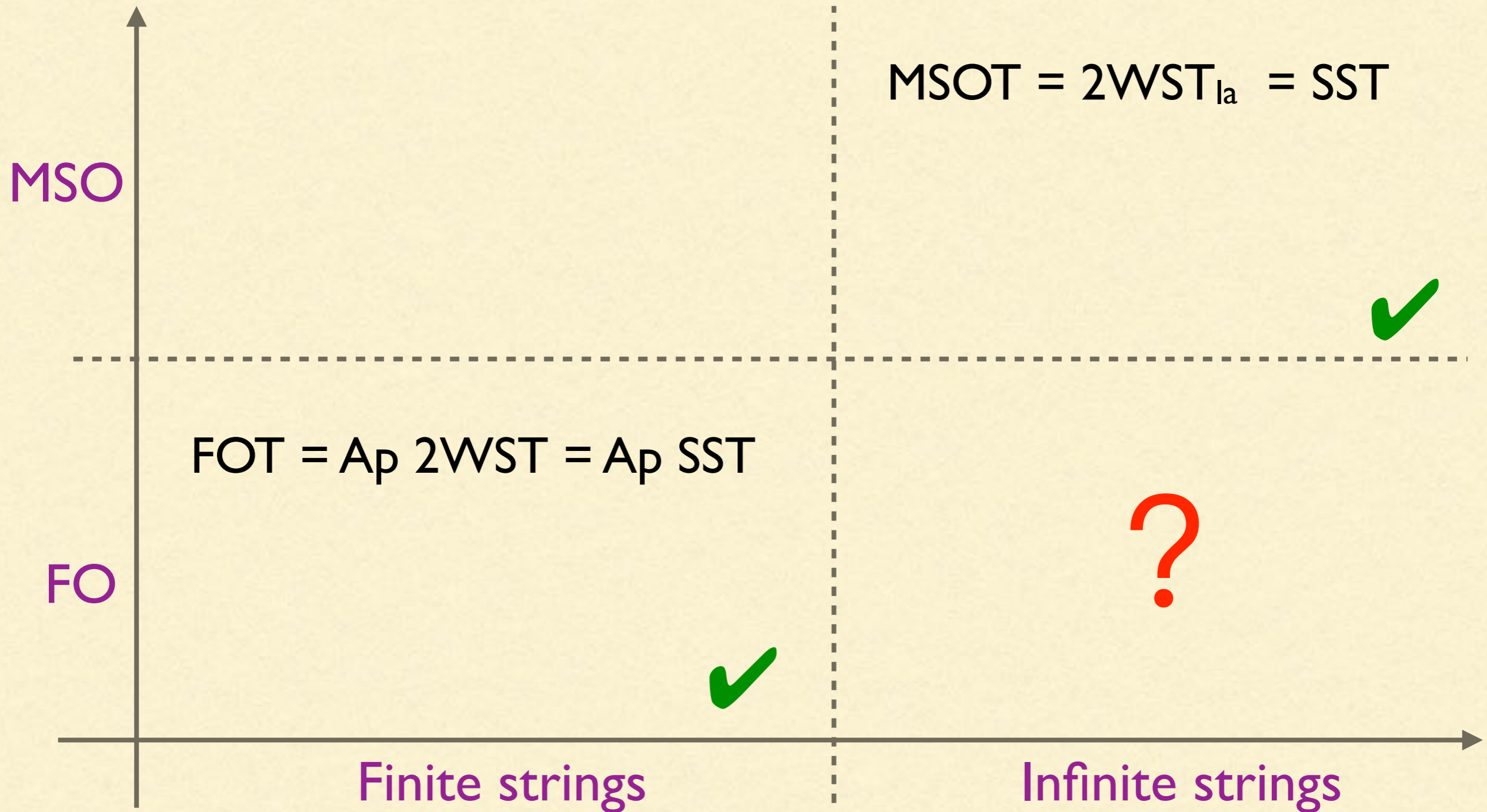
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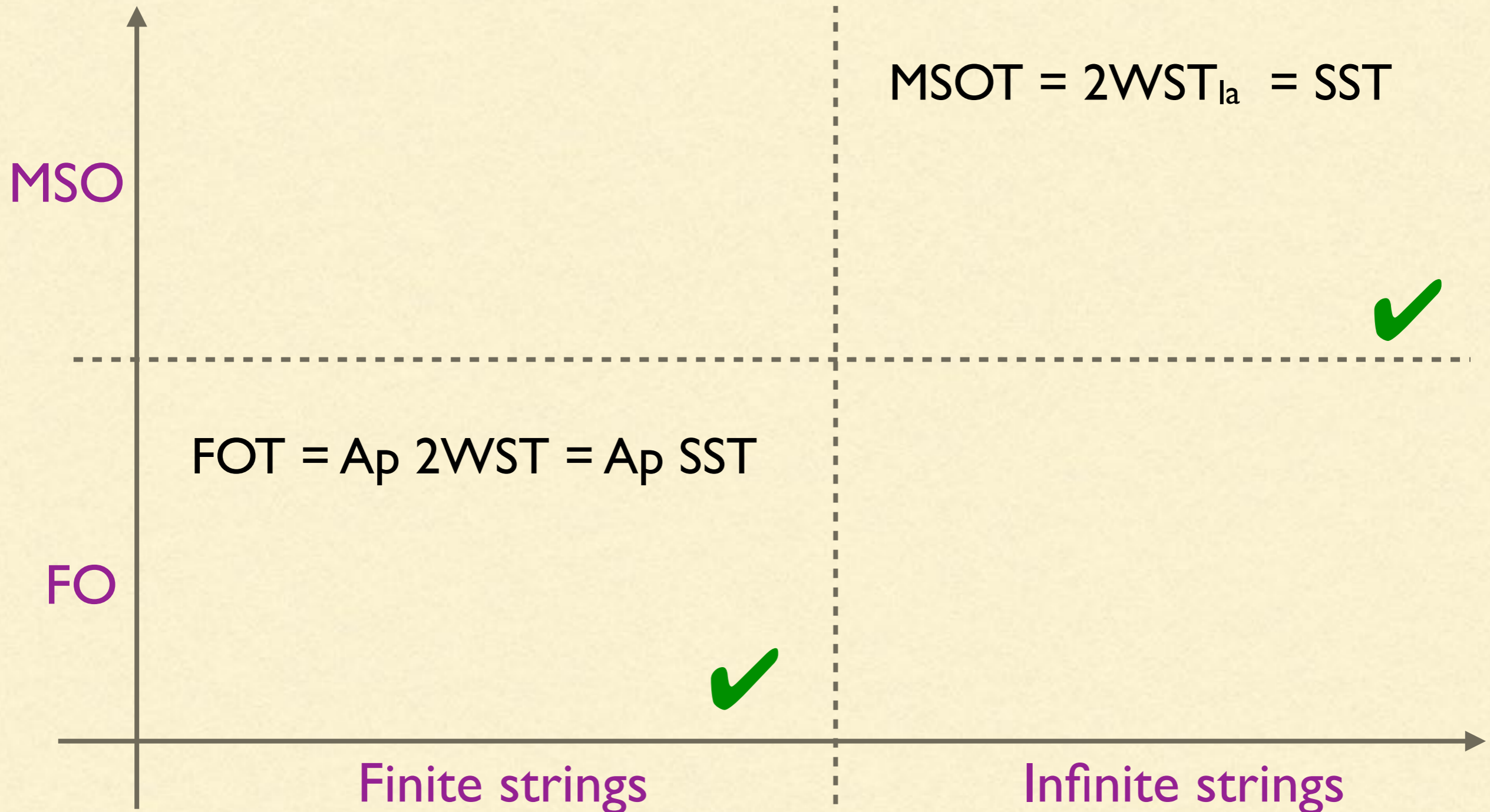
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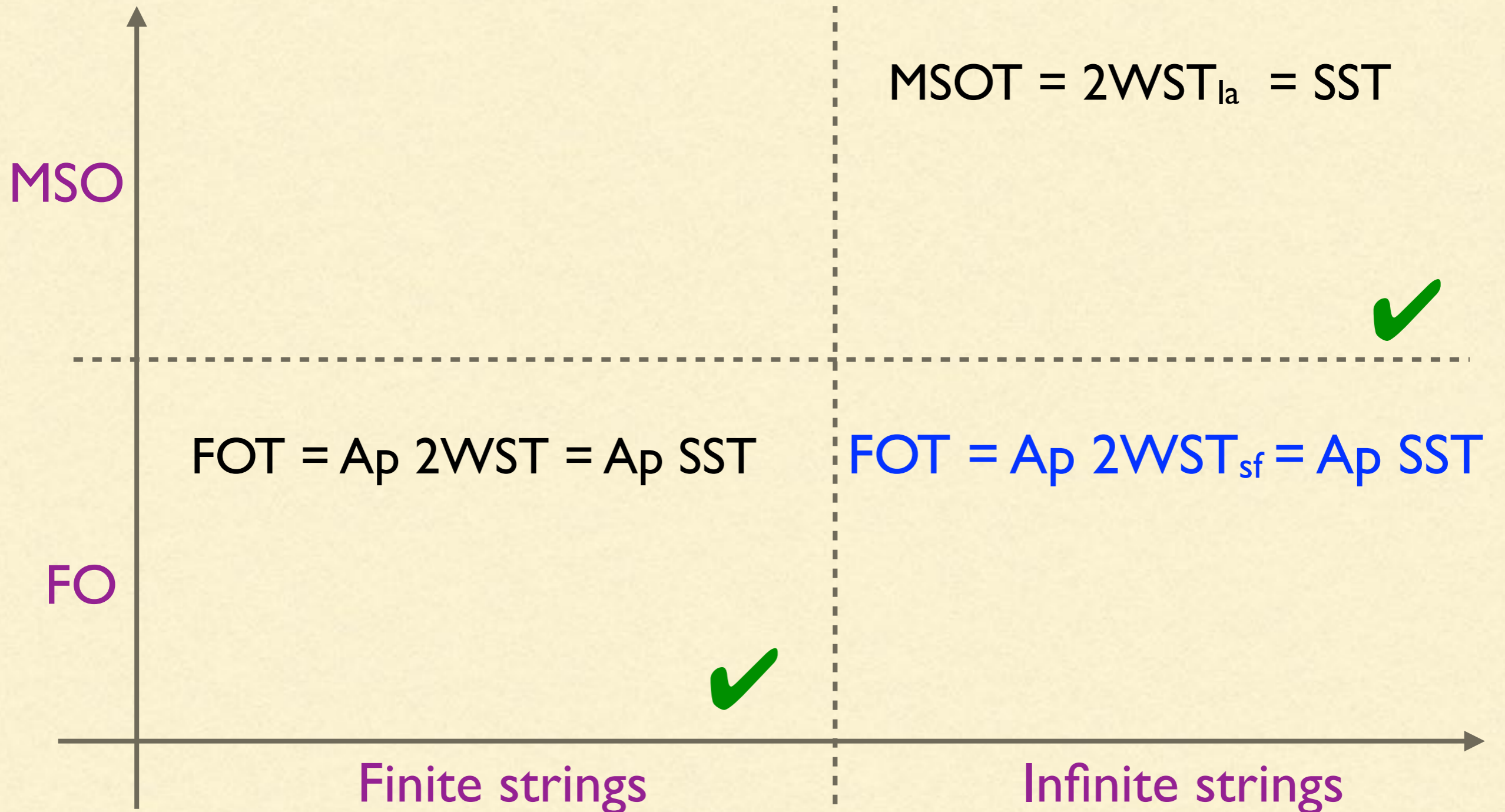
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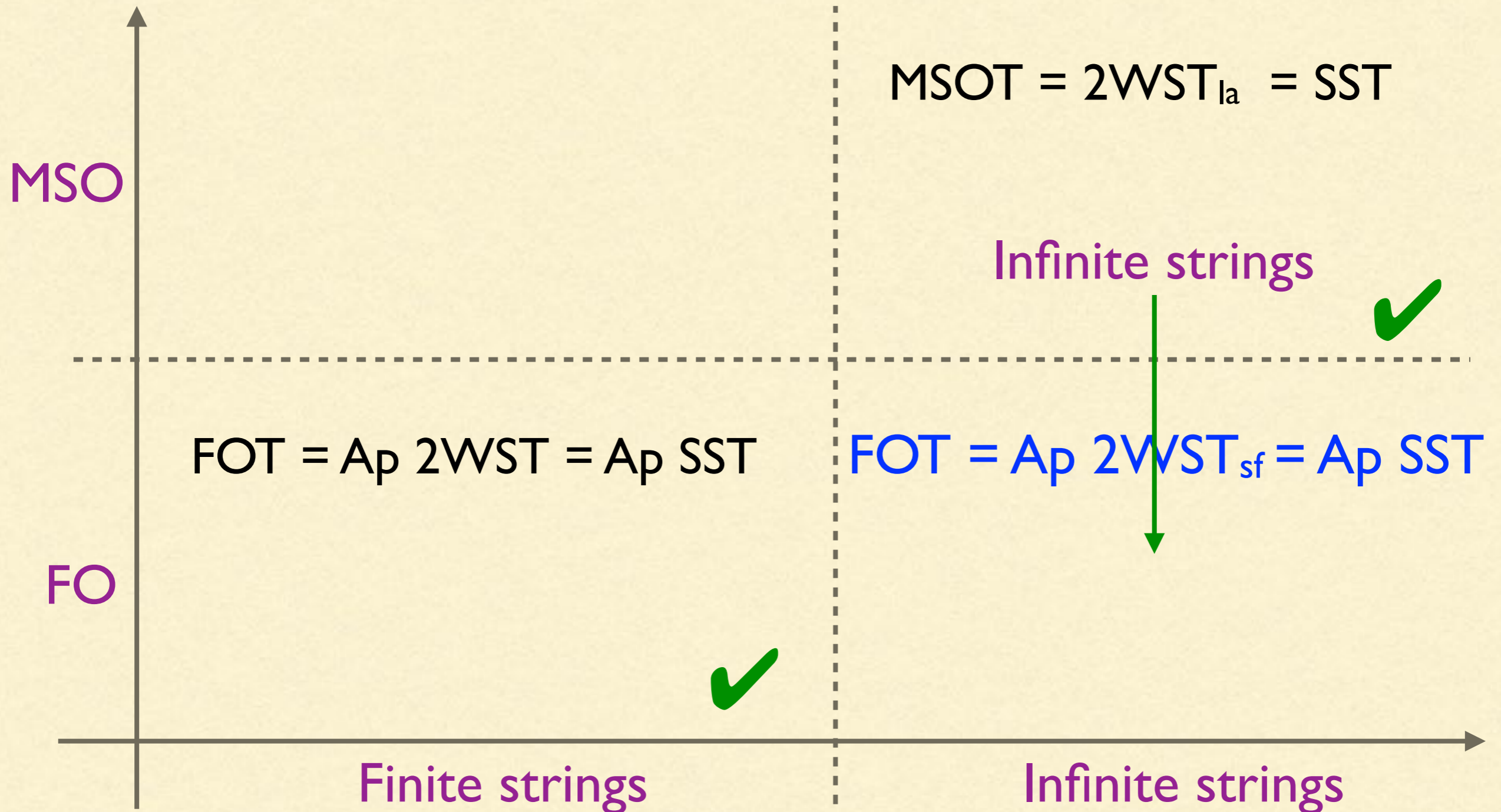
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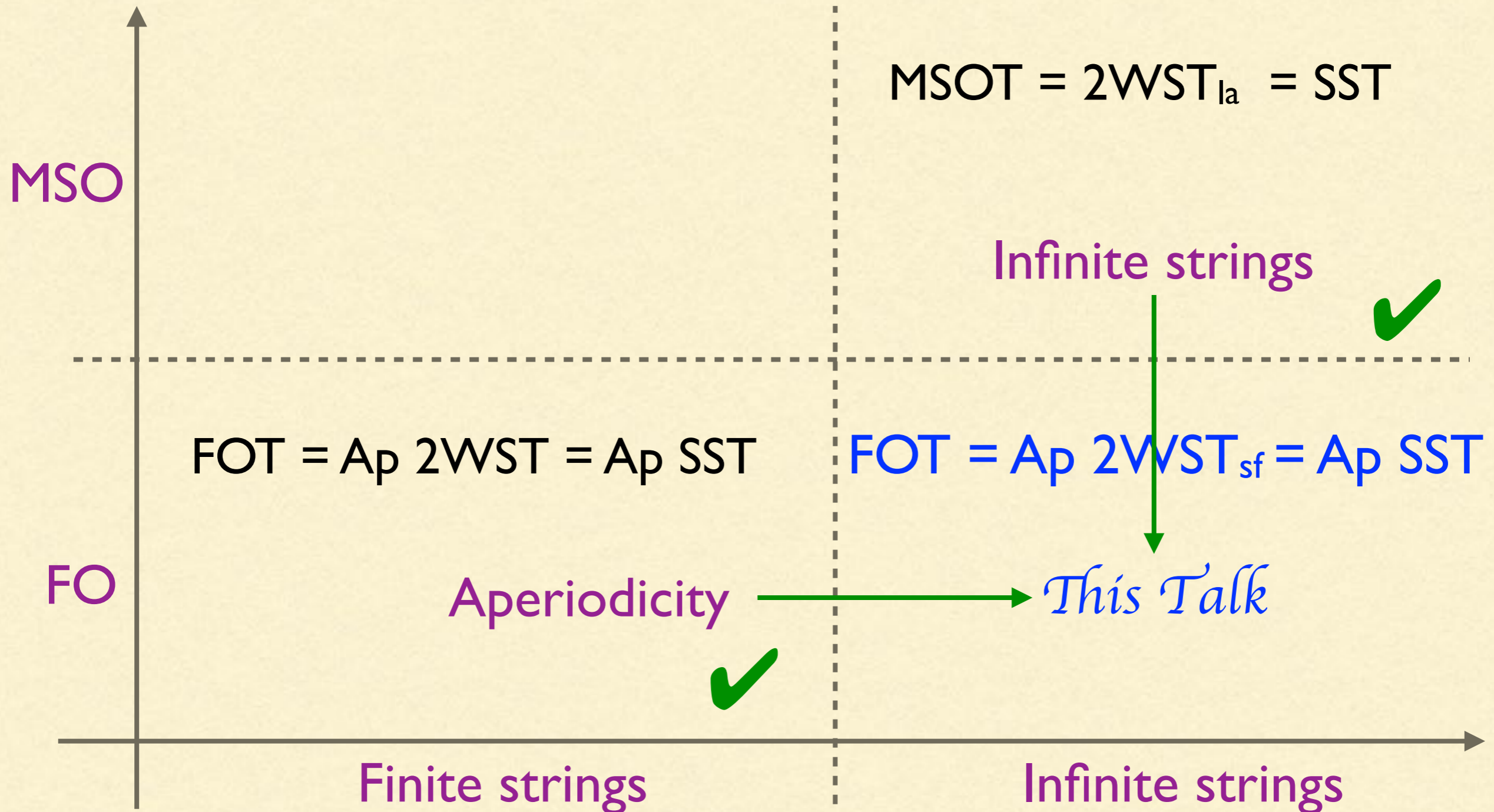
Related Work



Related Work



Related Work



Outline

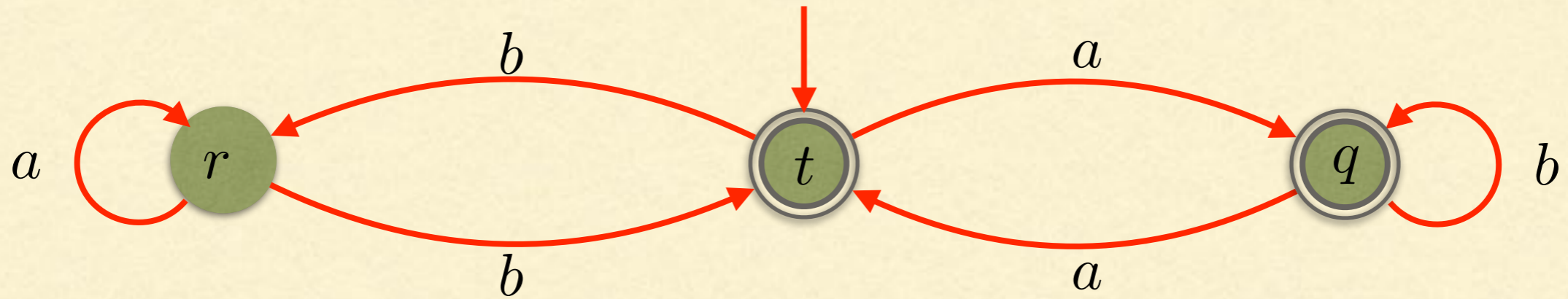
- Introduction
 - Three formalisms for transductions
 - Related work
 - **Aperiodic transformations for Infinite strings**
 - Aperiodic two way transducer
 - Aperiodic streaming string transducer
 - Equivalence results and Proof ideas
 - $SST_{sf} \subset FOT = 2WST_{sf} \subset SST_{sf}$
 - Conclusion
-

Transition monoid of a Finite state automaton

[Schutzenberger'65]

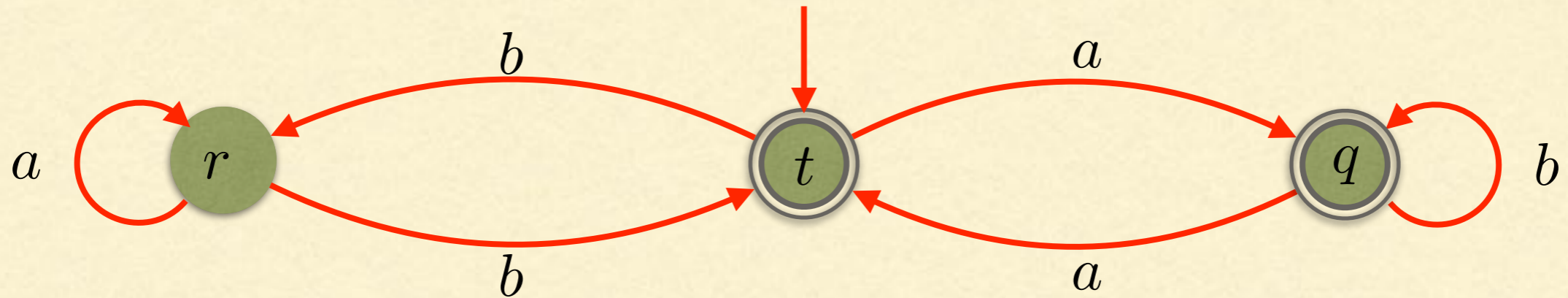
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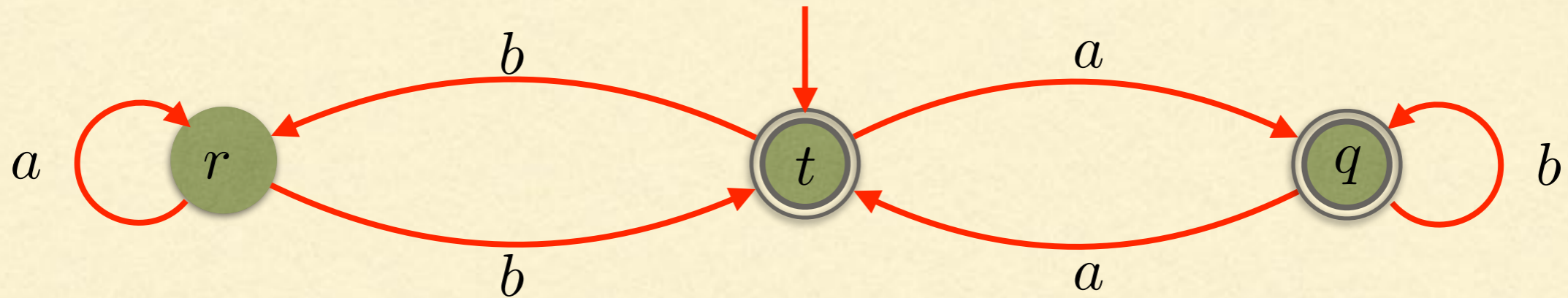


$$\mathcal{M}_A = (M_A, \times, 1)$$

$$M_A \subseteq \{0, 1\}^{|\mathcal{Q}| \times |\mathcal{Q}|}$$

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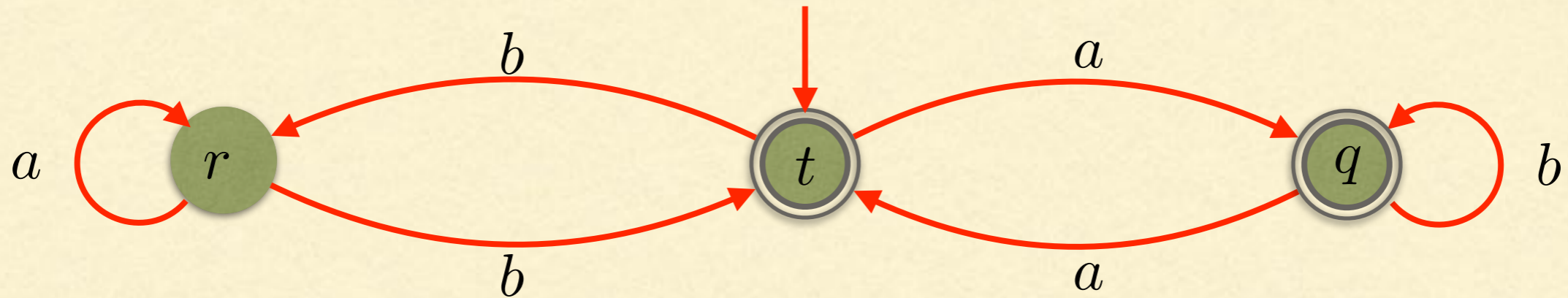
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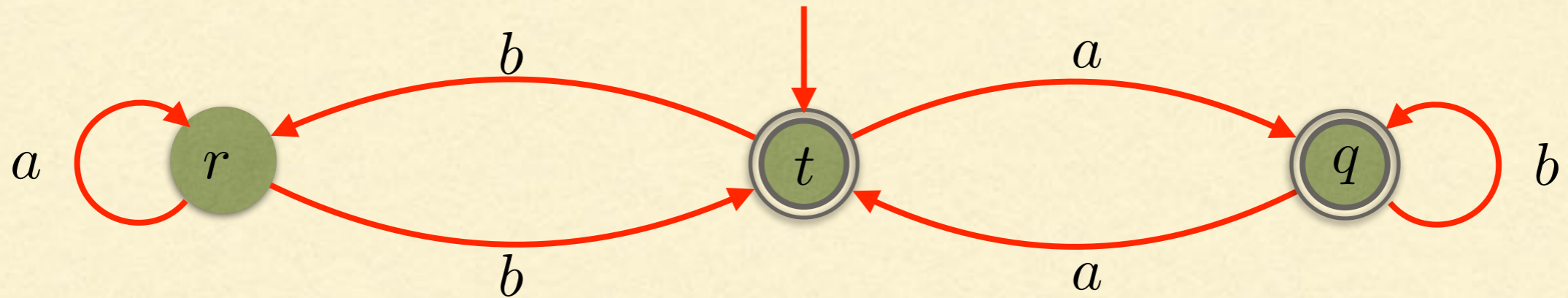
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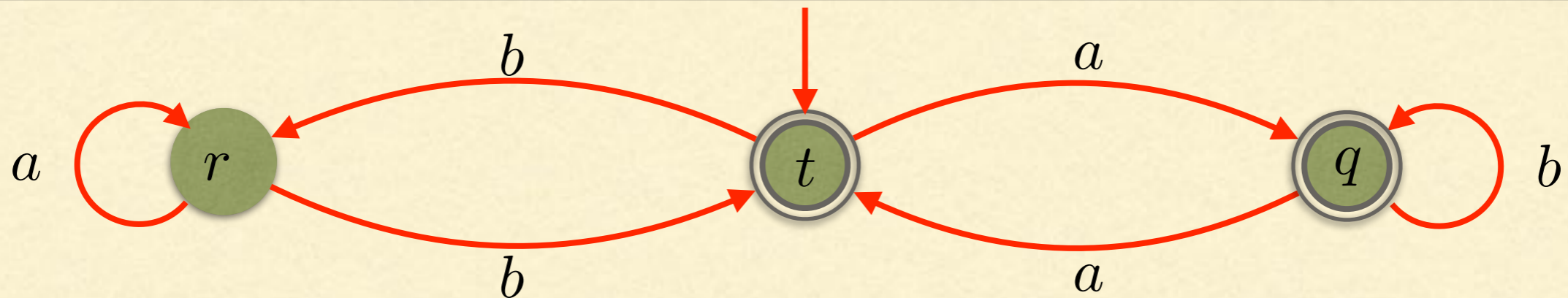
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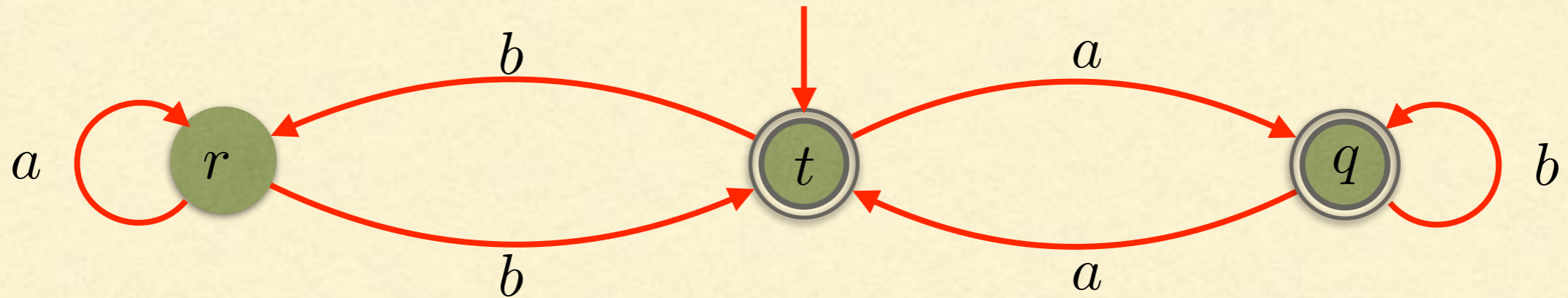
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monoid is aperiodic if $\forall m \in M_{\mathcal{A}} \exists x \in \mathbb{N}$ s.t. $m^x = m^{x+1}$

Transition monoid for Muller automaton example

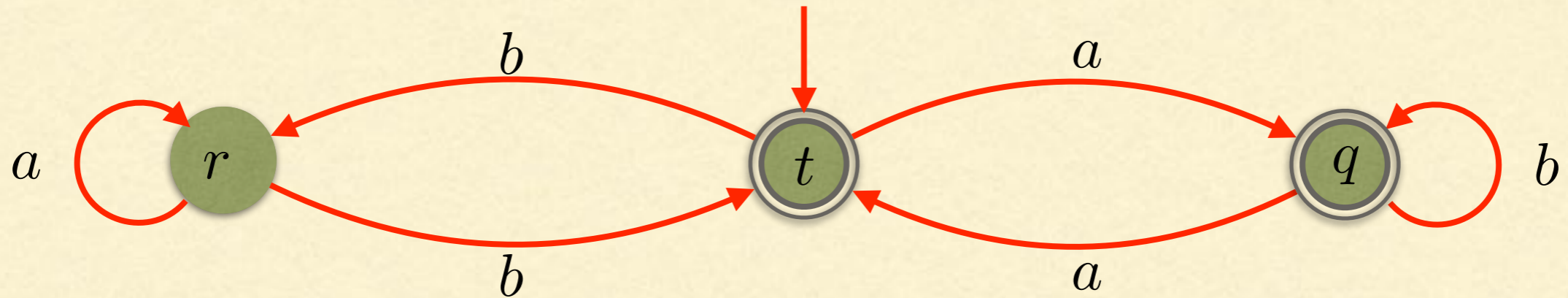
Transition monoid for Muller automaton example



$$\mathcal{F} = \left\{ \begin{array}{l} \{q\}, \\ \{q, t\} \end{array} \right\}$$

$F_1 \quad F_2$

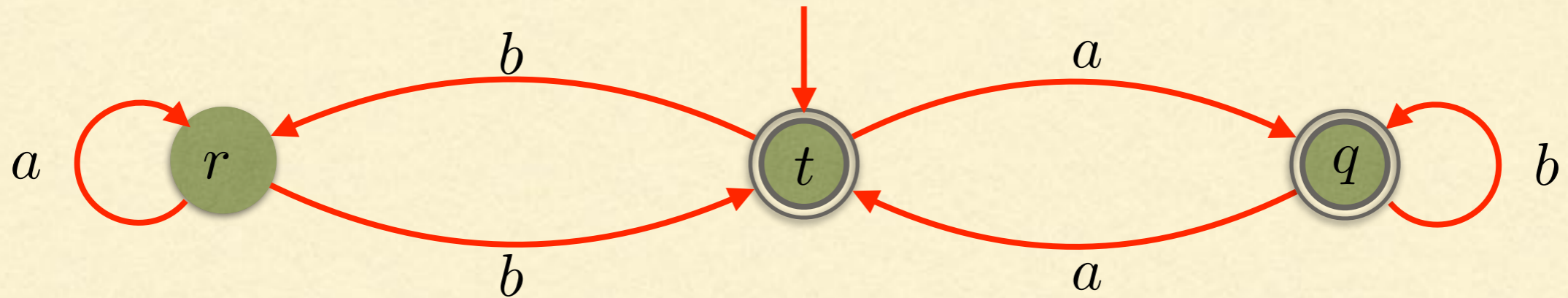
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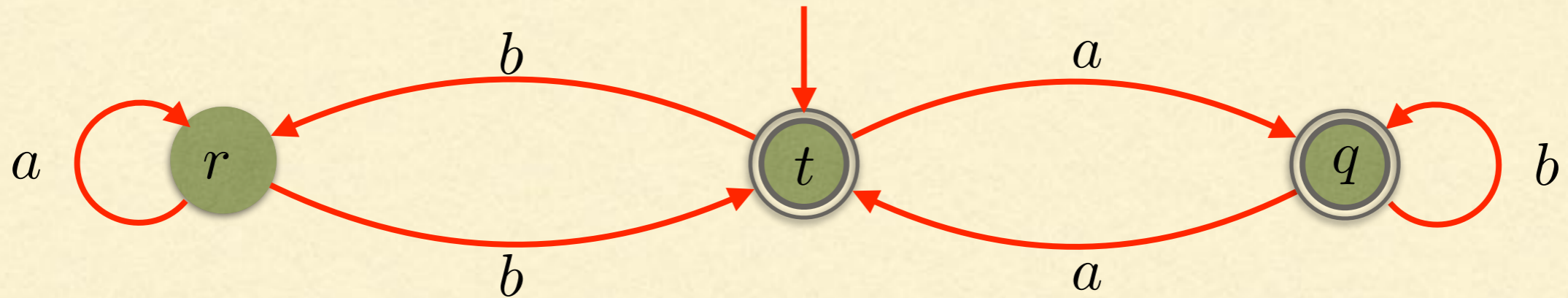


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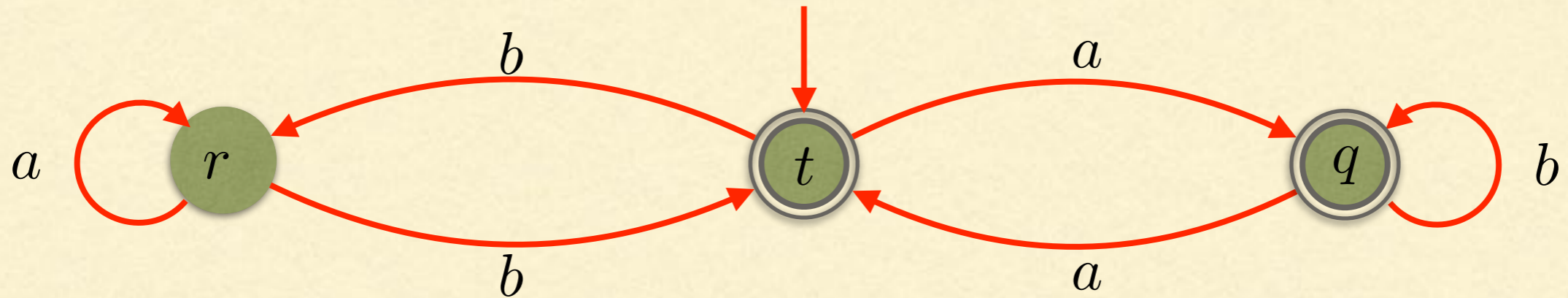
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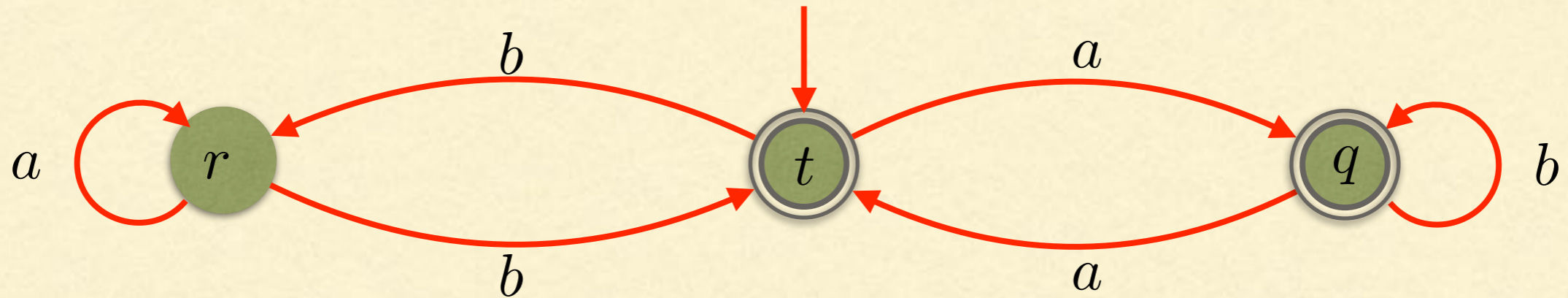
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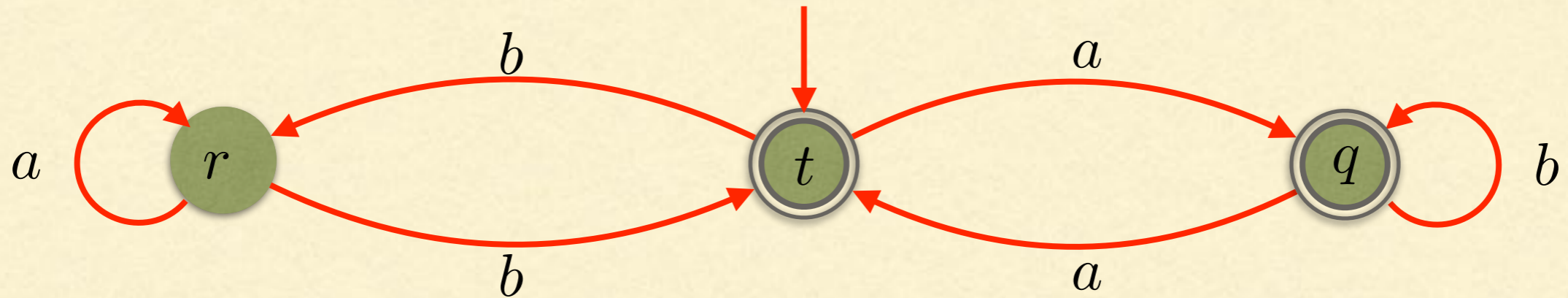
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Partial runs for two way automaton

Partial runs for two way automaton

w



Partial runs for two way automaton

w

one way:



Partial runs for two way automaton

w

one way:



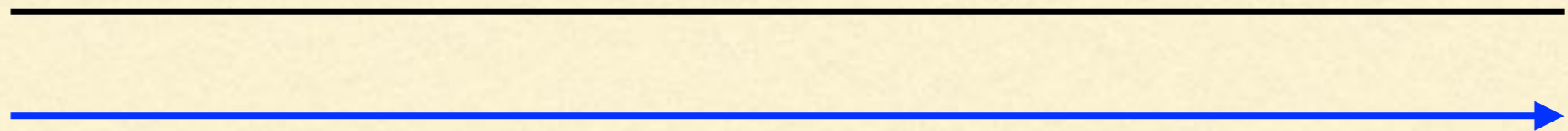
two way:



Partial runs for two way automaton

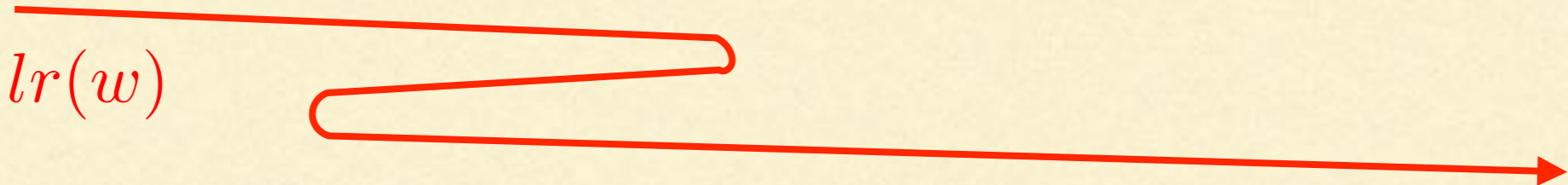
w

one way:



two way:

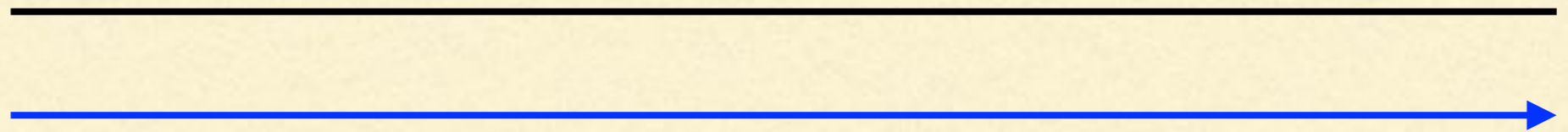
$lr(w)$



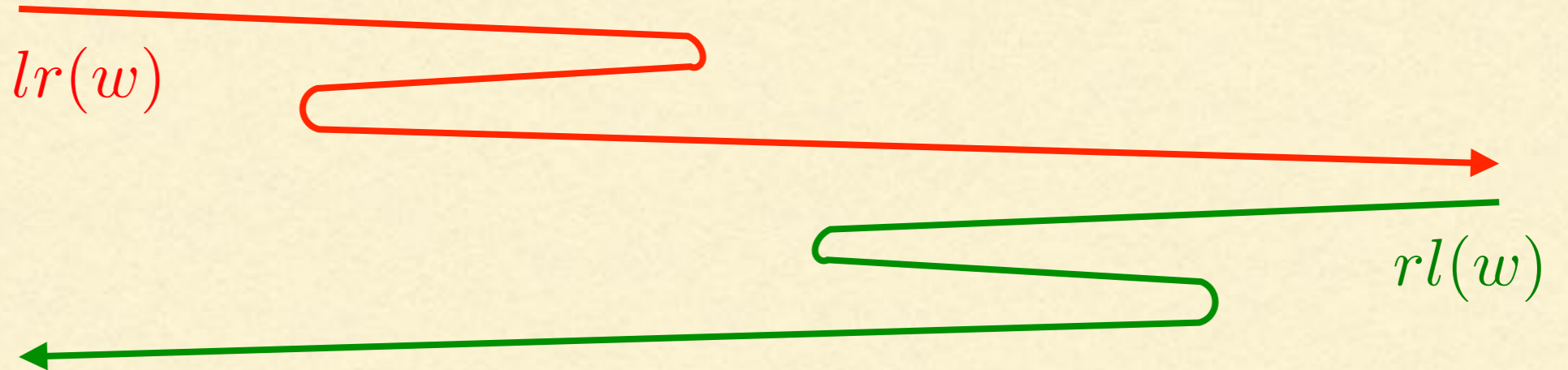
Partial runs for two way automaton

w

one way:



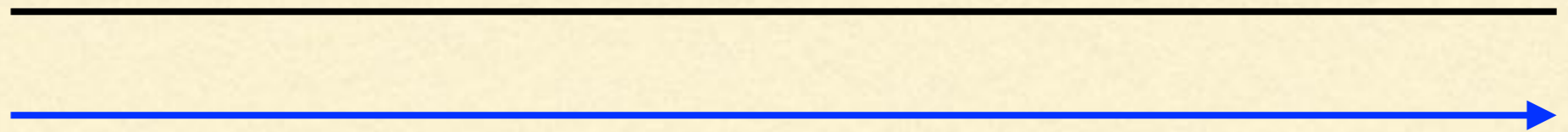
two way:



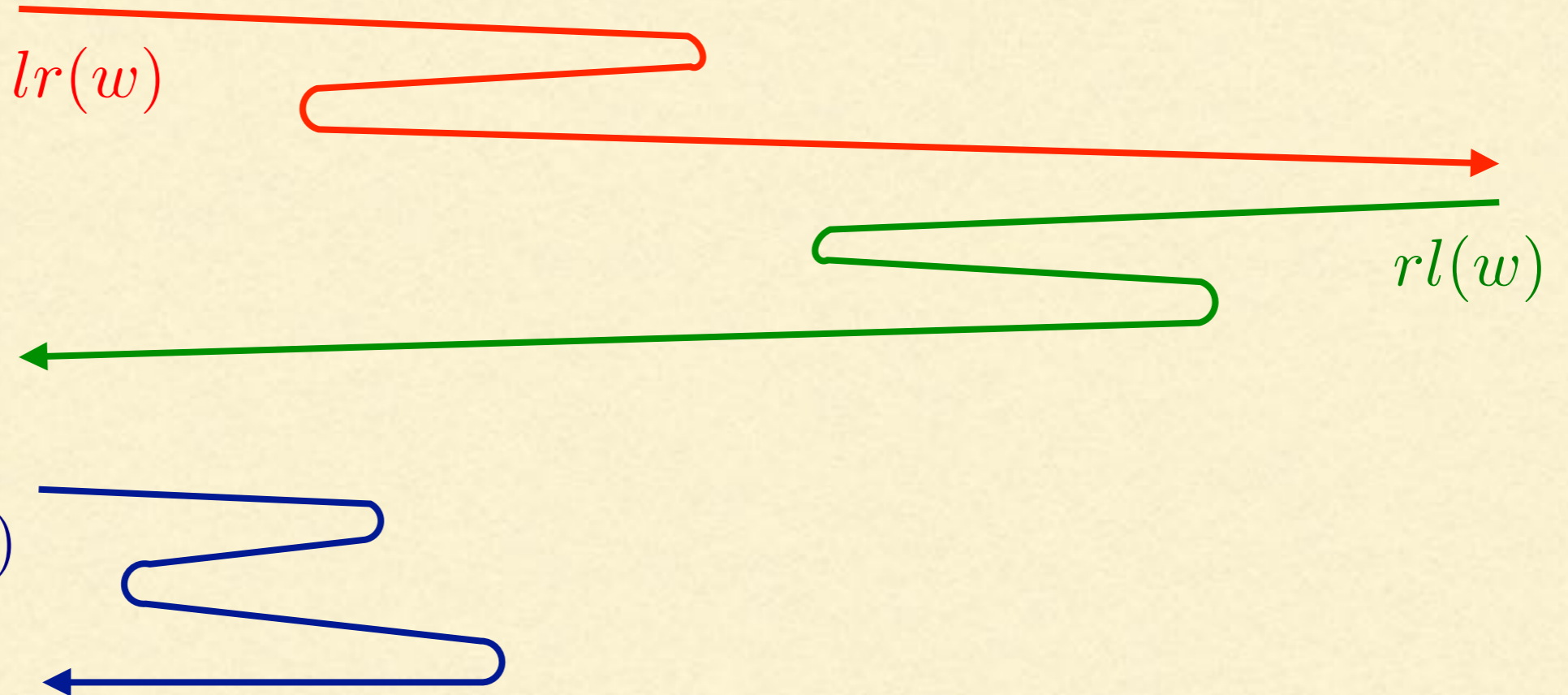
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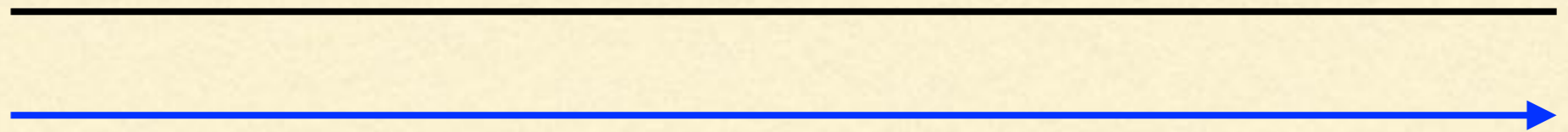
two way:



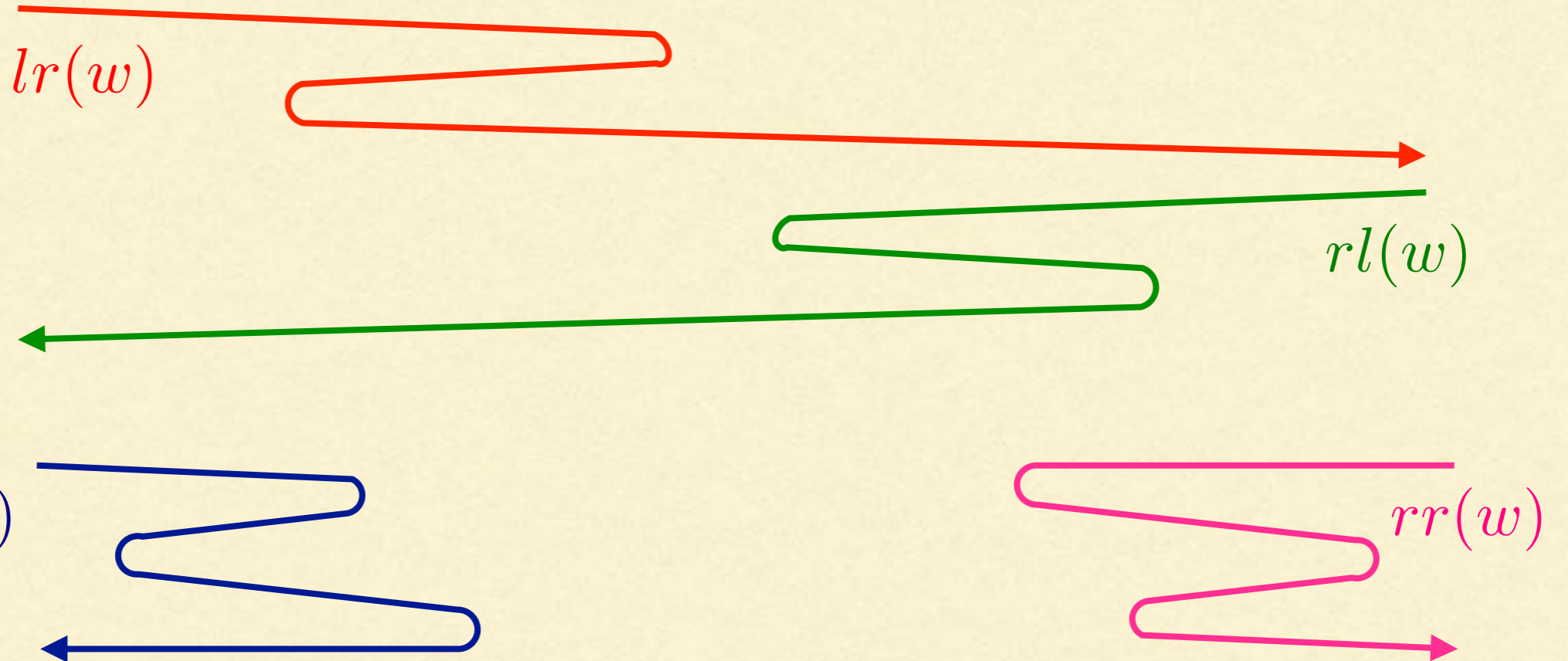
Partial runs for two way automaton

w

one way:

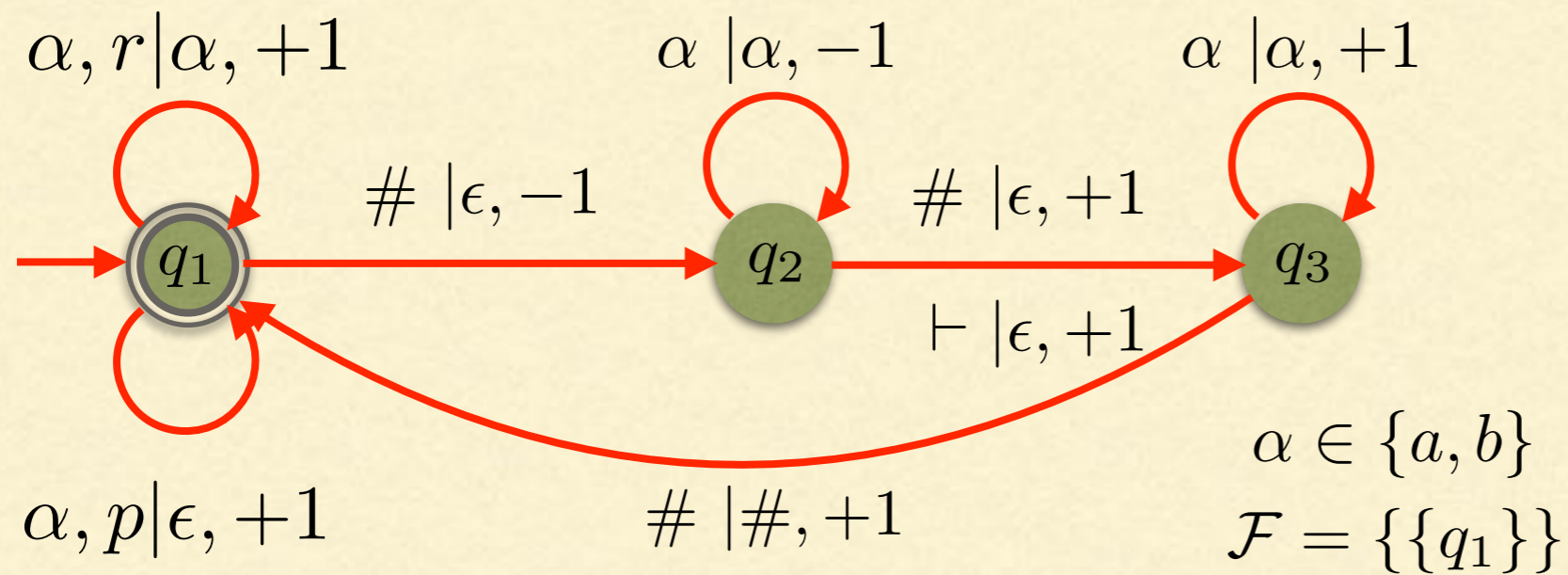


two way:

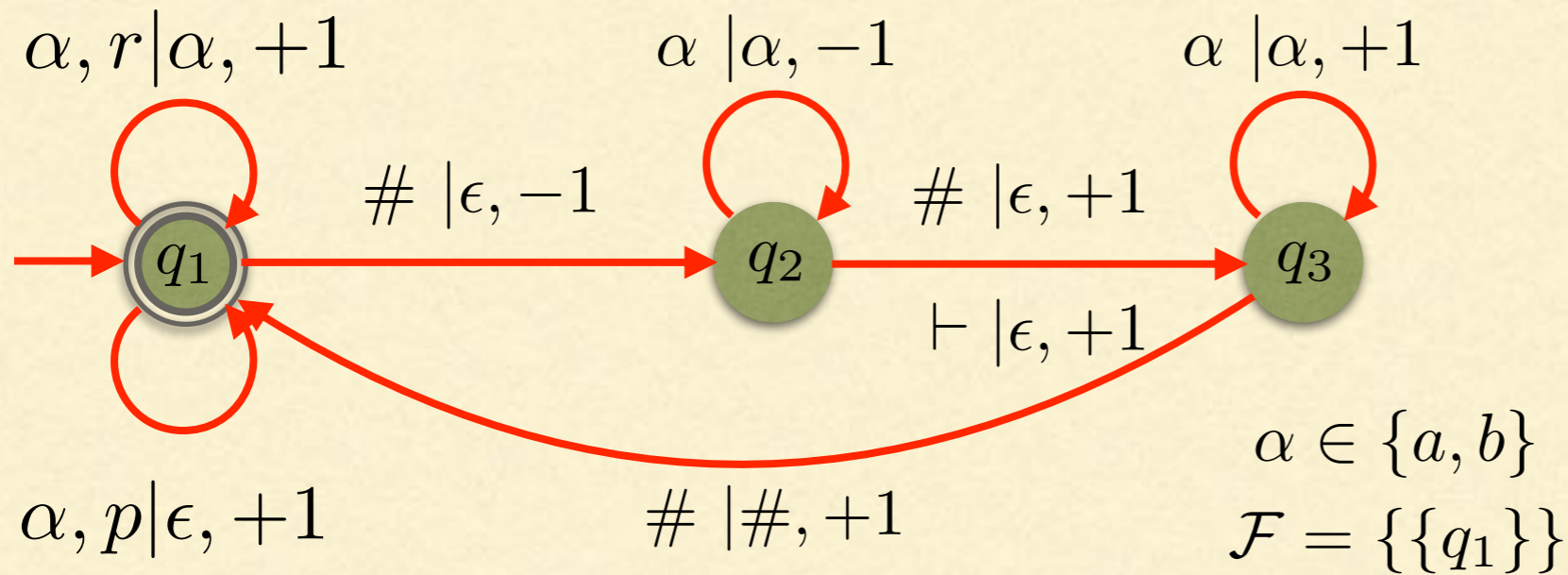


Transition monoid for Two Way Transducer for ω strings

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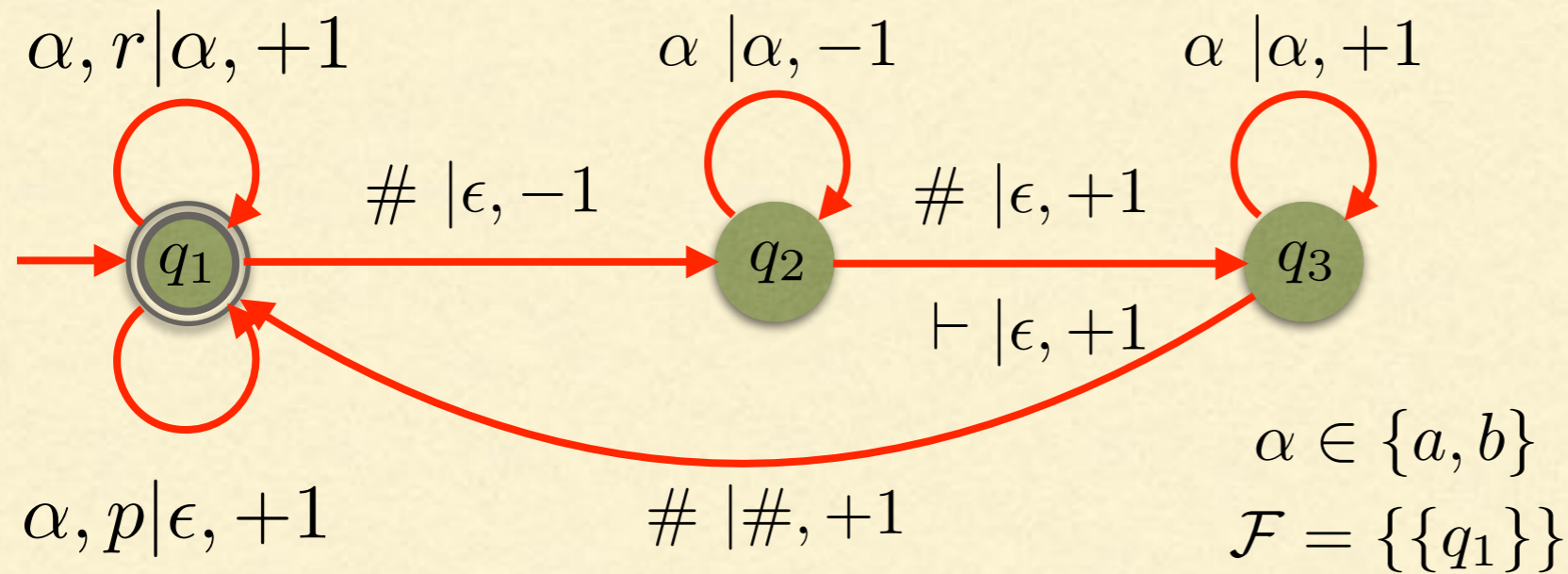


Transition monoid for Two Way Transducer for ω strings



$$M_s = \begin{pmatrix} M_s^{ll} & M_s^{lr} \\ M_s^{rl} & M_s^{rr} \end{pmatrix}$$

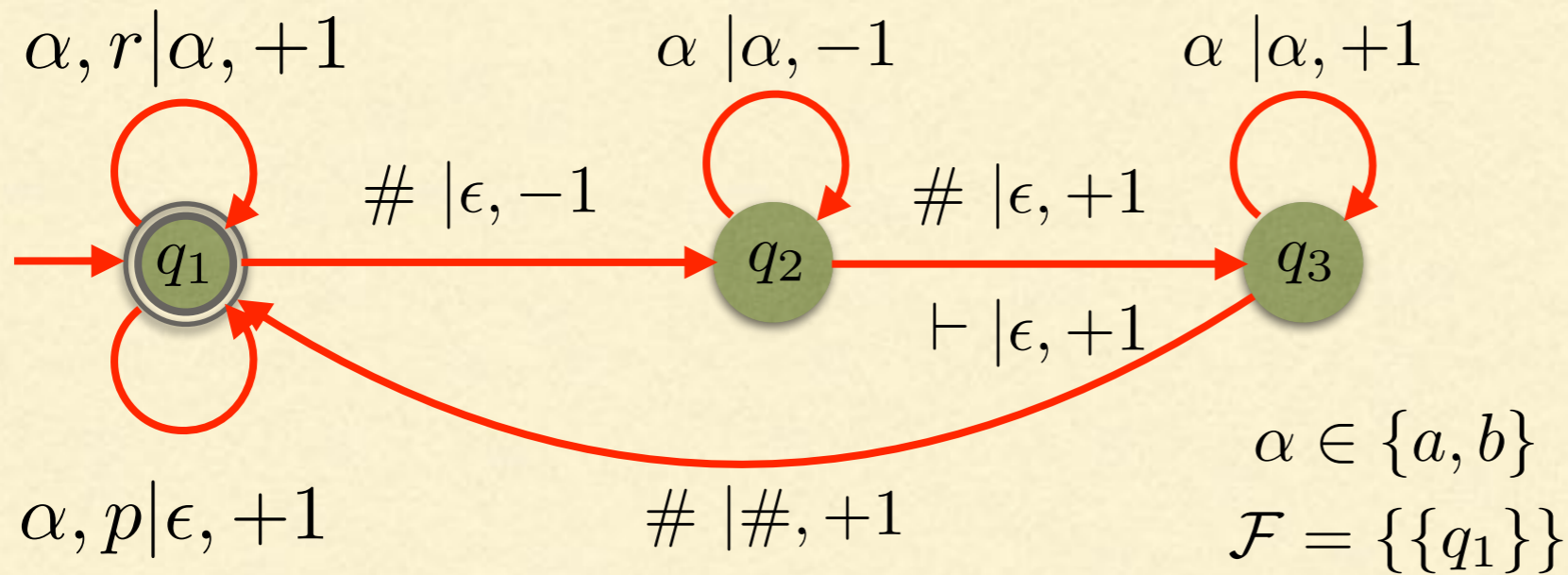
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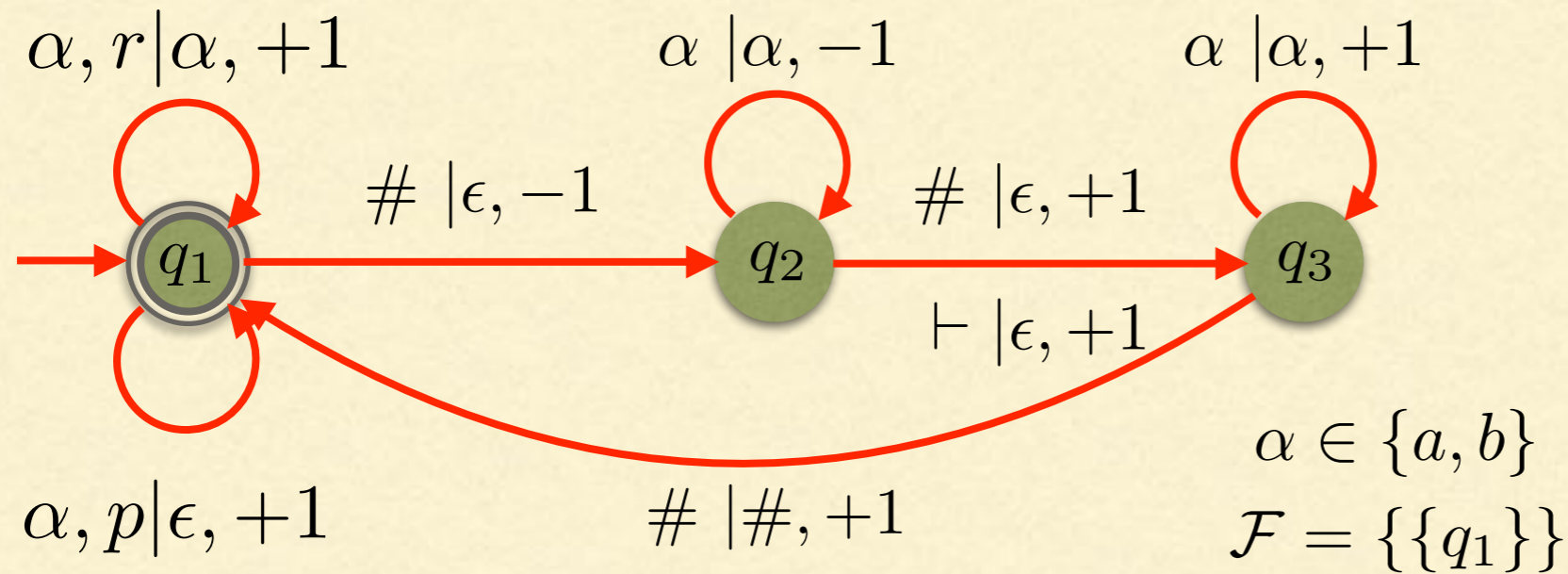
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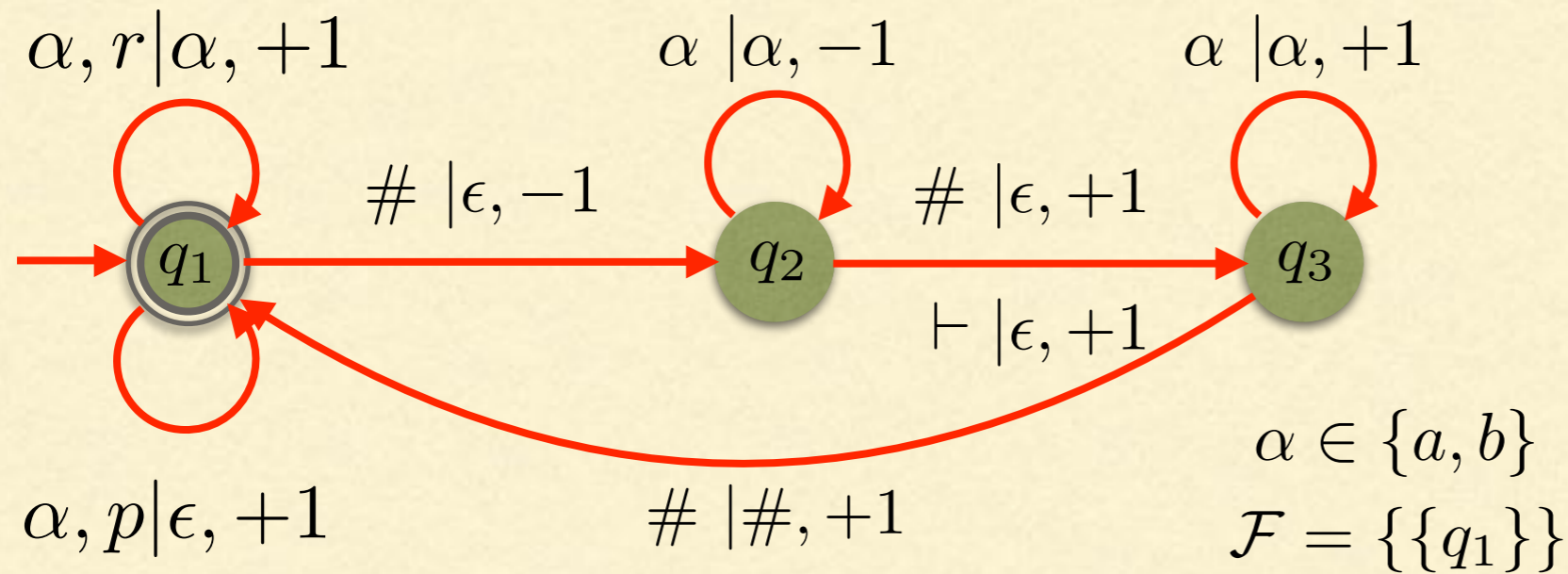
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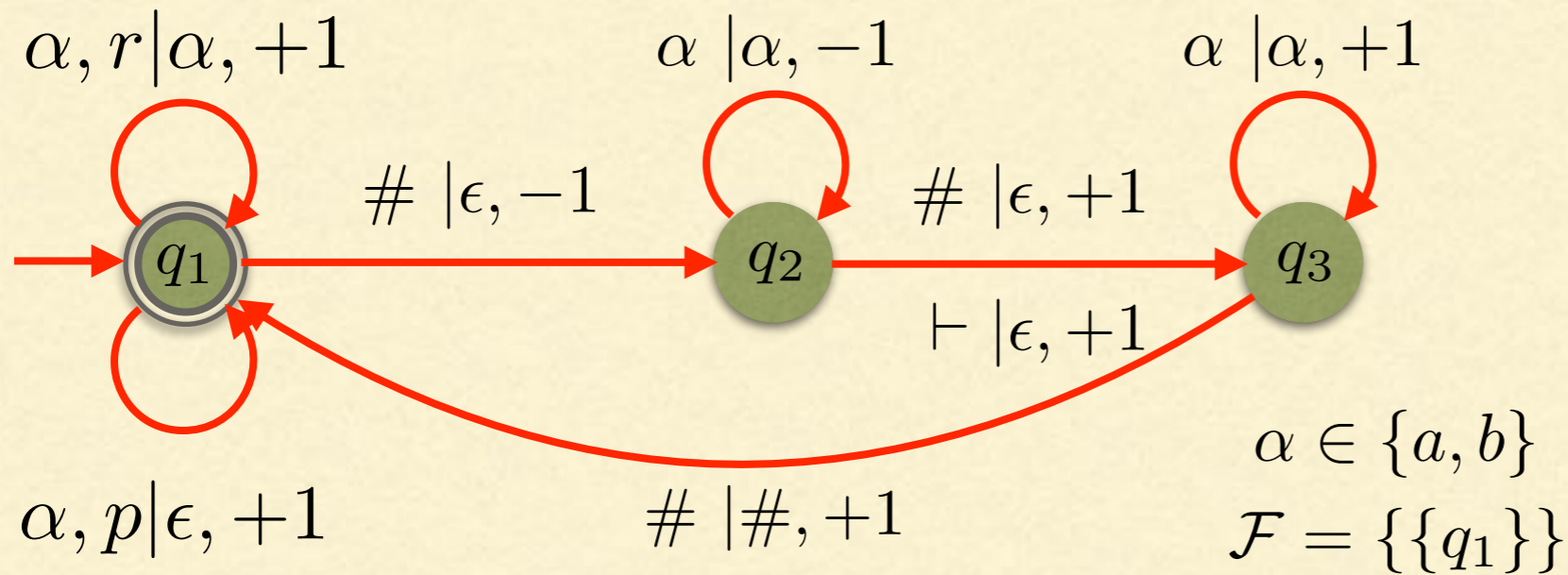
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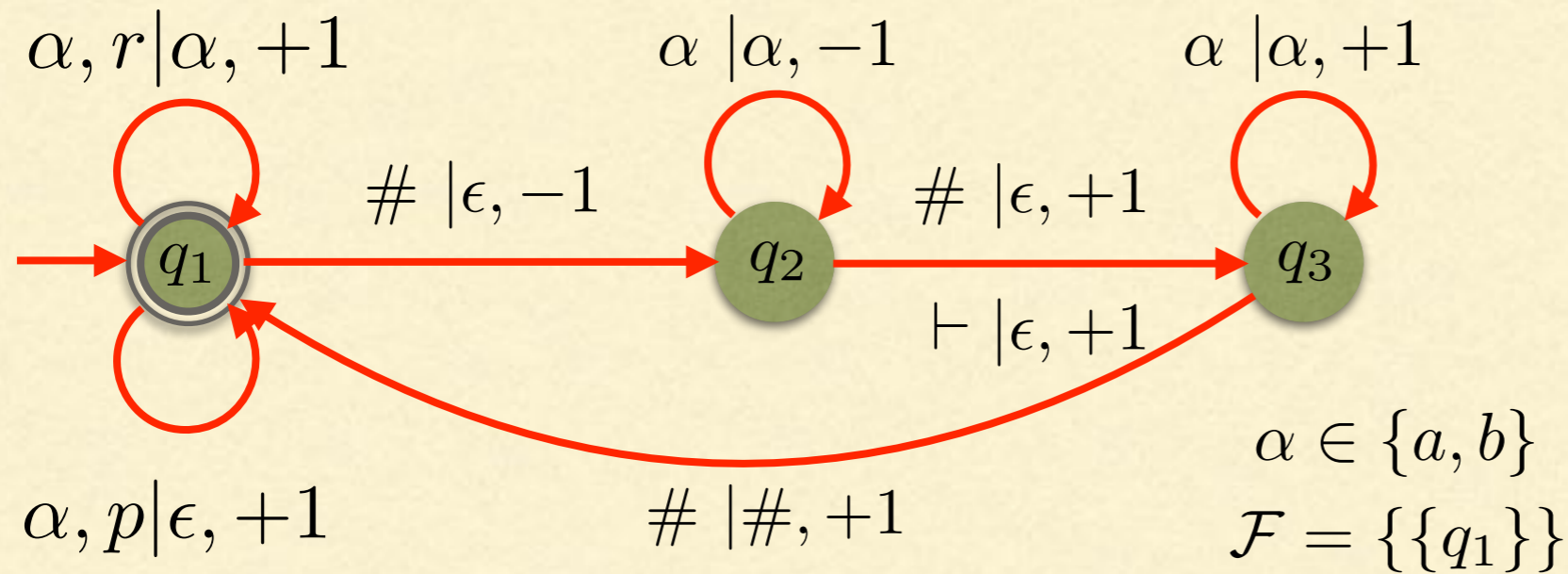
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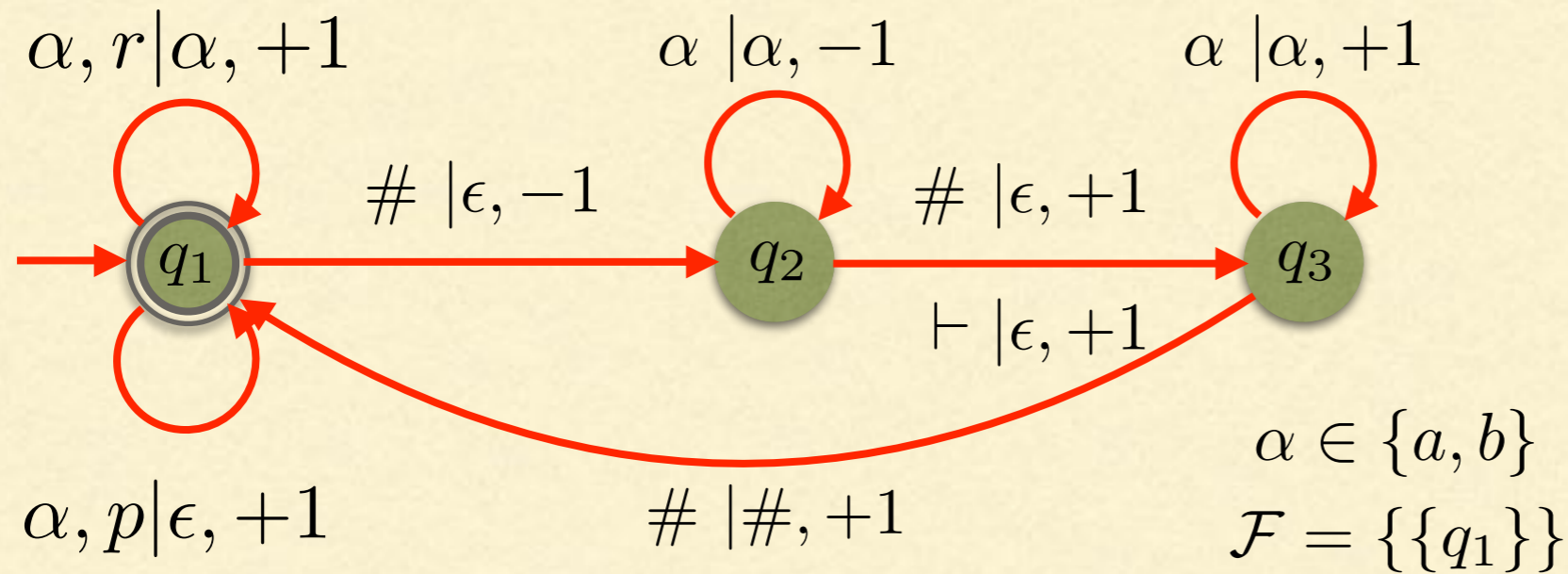


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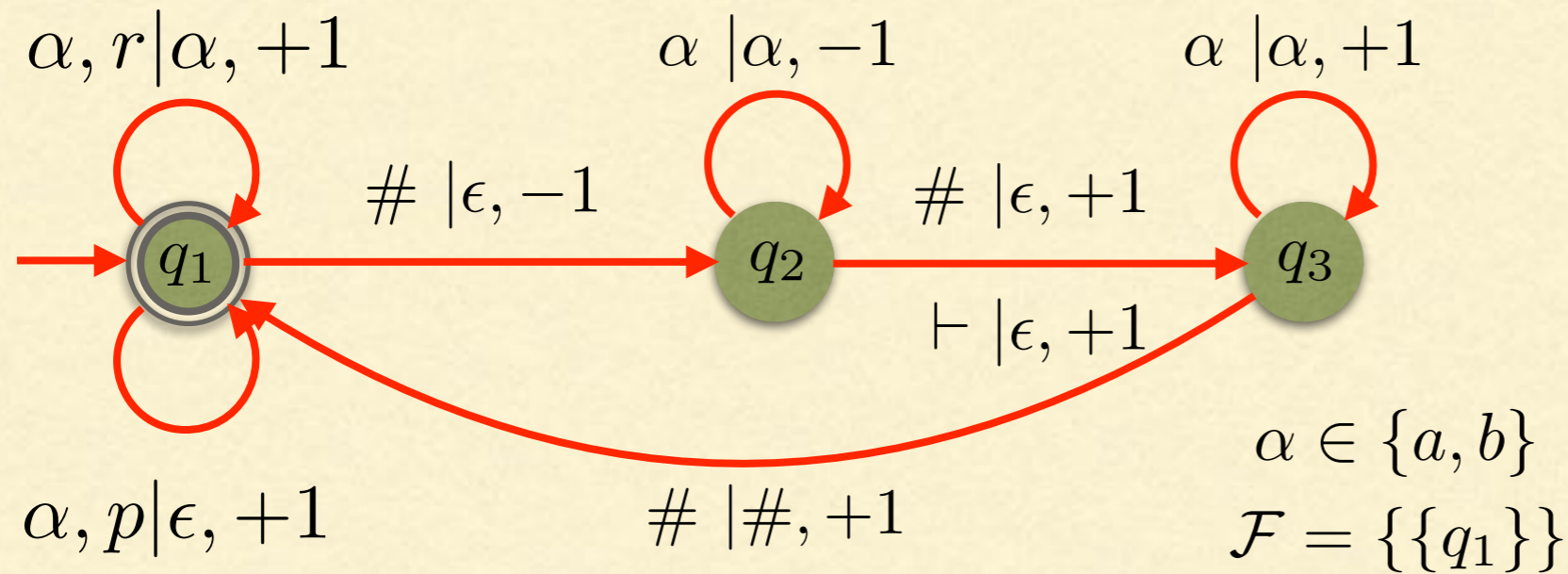


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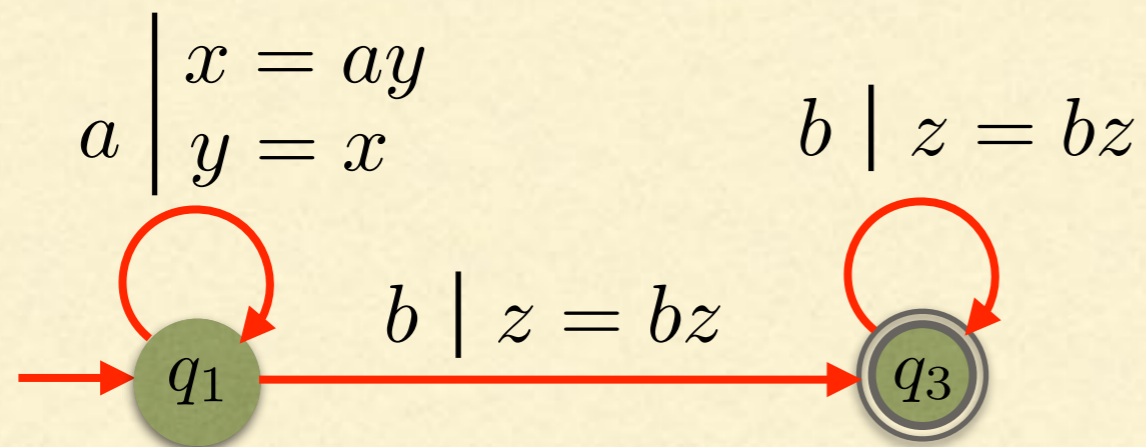
Transition monoid for Streaming String Transducer for ω strings

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Transition monoid for Streaming String Transducer for ω strings

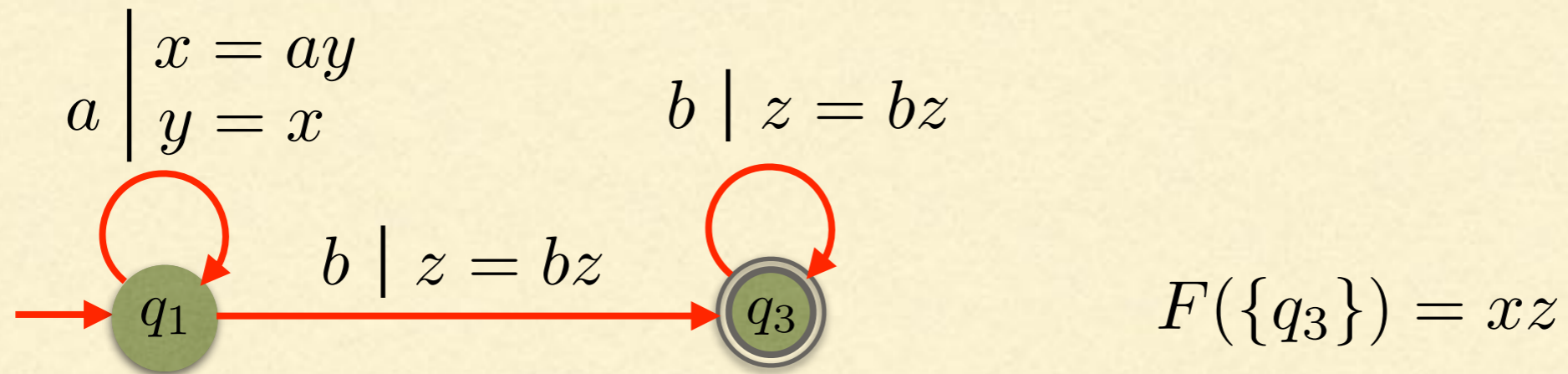
$$f(a^n b^\omega) = a^{\lceil n/2 \rceil} b^\omega$$



$$F(\{q_3\}) = xz$$

Transition monoid for Streaming String Transducer for ω strings

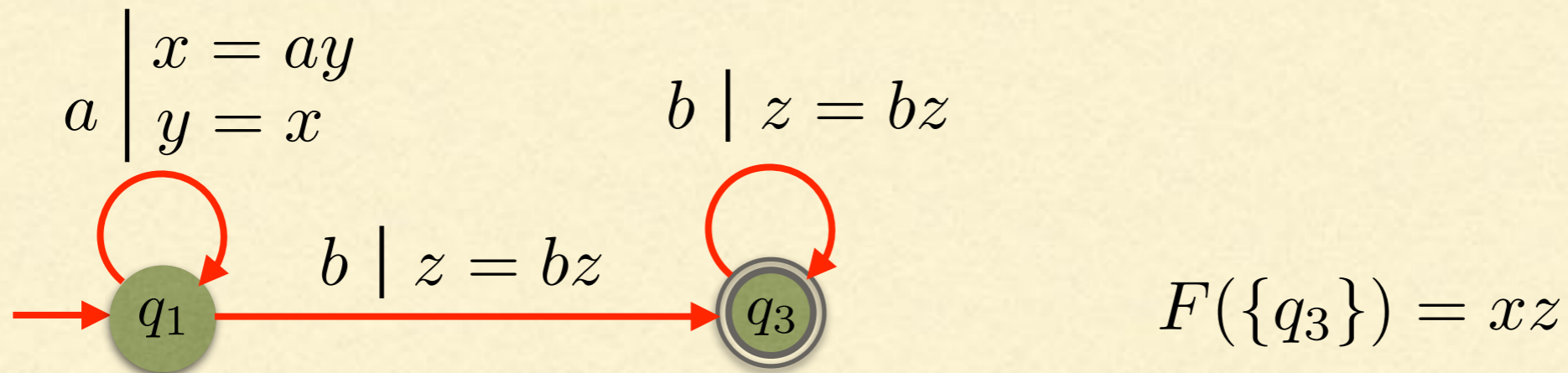
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domain language : $a^* b^\omega$ aperiodic ✓

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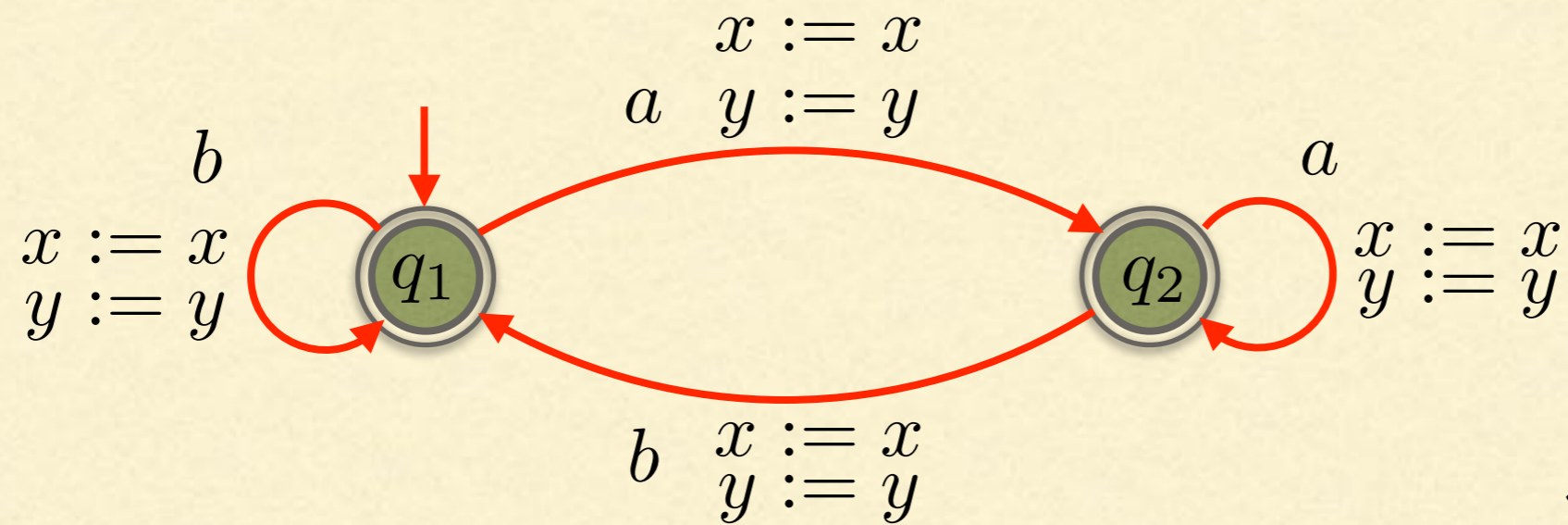


domain language : $a^* b^\omega$ aperiodic ✓

transformation : FO- definable ✗

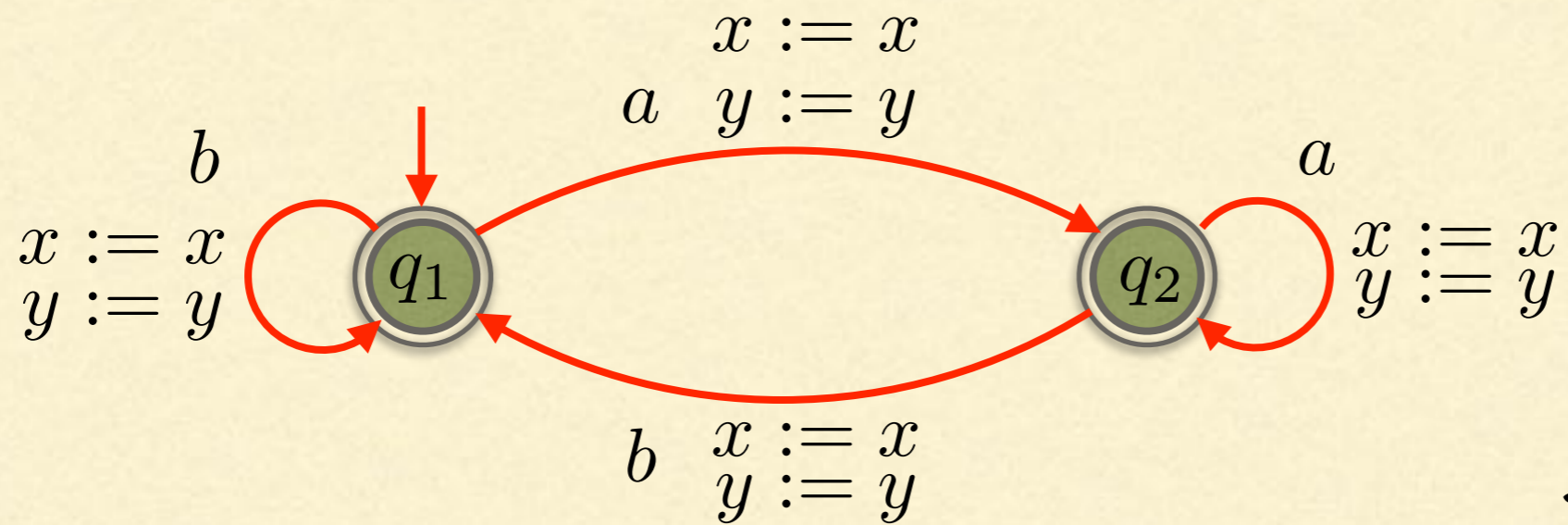
Transition monoid for Streaming String Transducer for ω strings

Transition monoid for Streaming String Transducer for ω strings



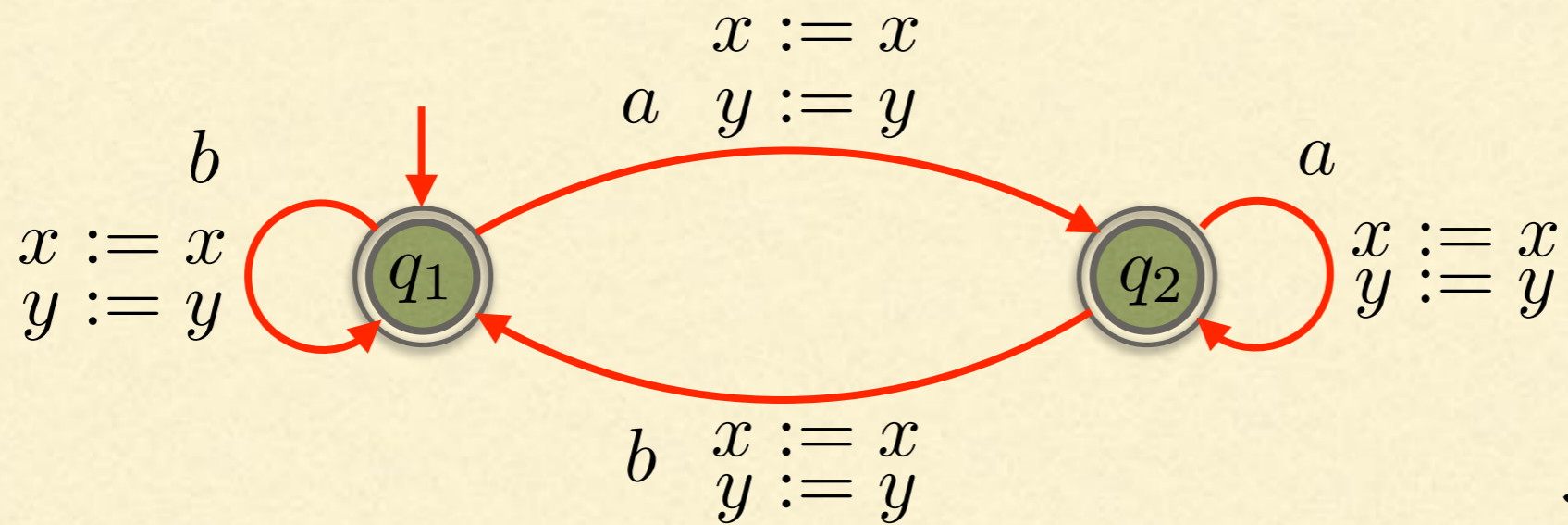
$$\mathcal{F} = \{\{q_1, q_2\}\}$$

Transition monoid for Streaming String Transducer for ω strings



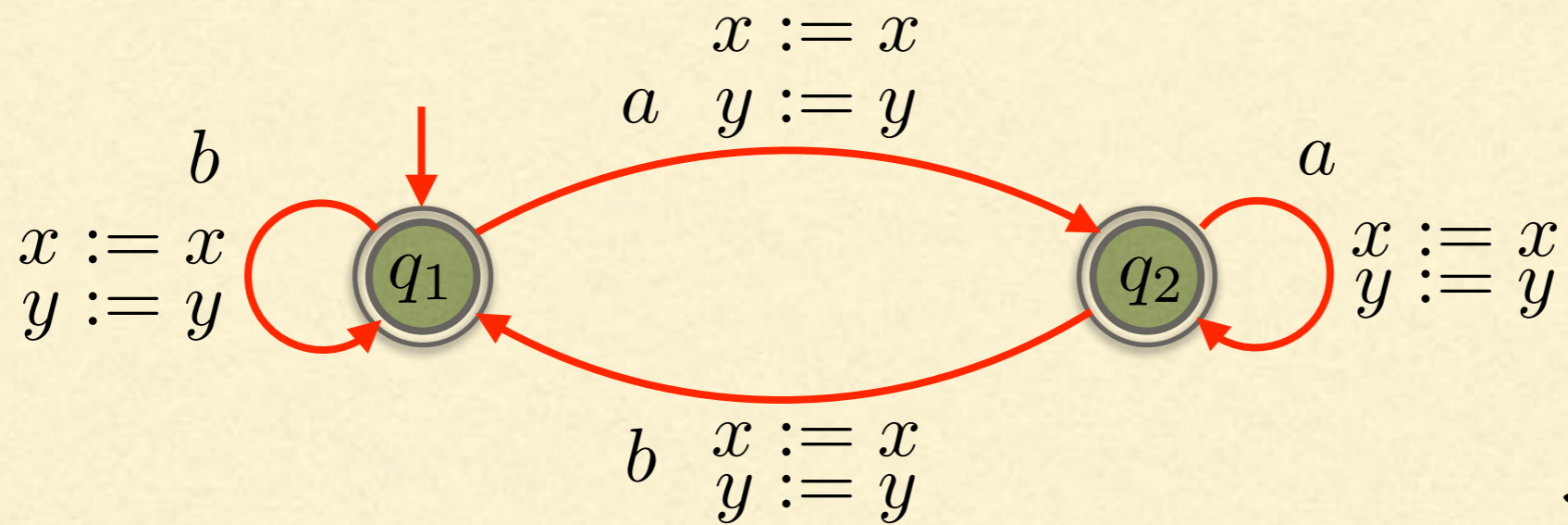
$$M_b = \begin{matrix} & (q_1, x) & (q_1, y) & (q_2, x) & (q_2, y) \\ \begin{matrix} (q_1, x) \\ (q_1, y) \\ (q_2, x) \\ (q_2, y) \end{matrix} & \left(\begin{matrix} & & & \\ & & & \\ & & & \\ & & & \end{matrix} \right) & & & \end{matrix}$$

Transition monoid for Streaming String Transducer for ω strings



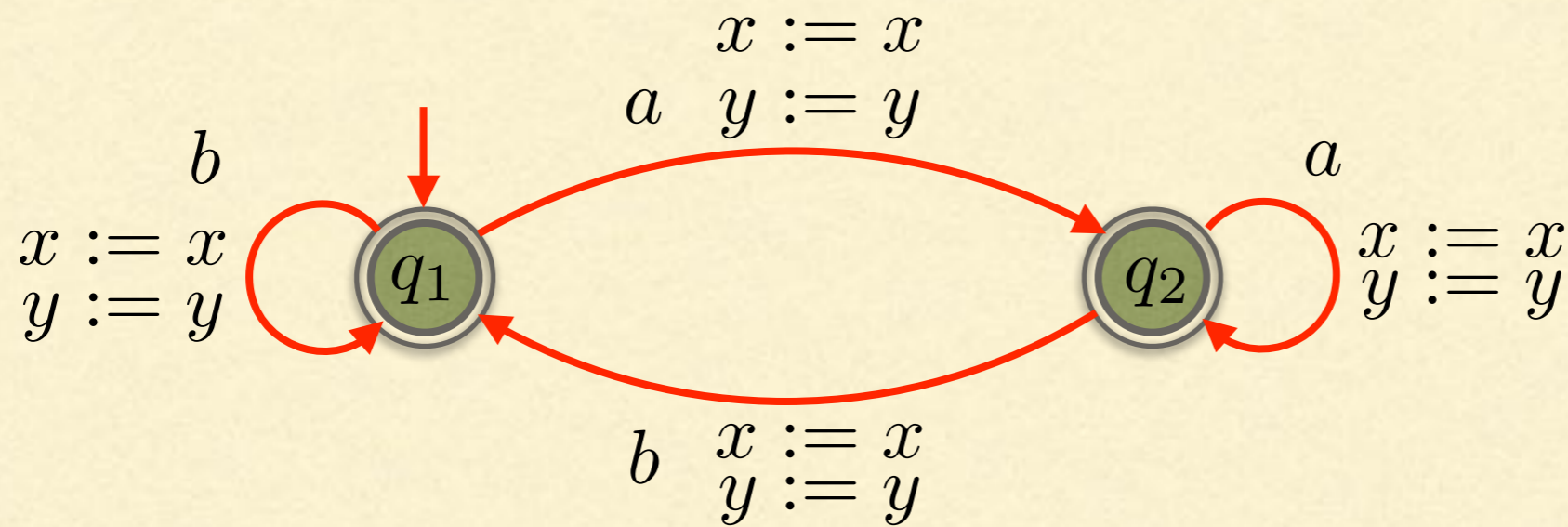
$$M_b = \begin{matrix} & \begin{matrix} (q_1, x) & (q_1, y) & (q_2, x) & (q_2, y) \end{matrix} \\ \begin{matrix} (q_1, x) \\ (q_1, y) \\ (q_2, x) \\ (q_2, y) \end{matrix} & \begin{pmatrix} & & \perp & \perp \\ & & \perp & \perp \\ & & & \\ & & & \end{pmatrix} \end{matrix}$$

Transition monoid for Streaming String Transducer for ω strings



$$M_b = \begin{matrix} & \begin{matrix} (q_1, x) & (q_1, y) & (q_2, x) & (q_2, y) \end{matrix} \\ \begin{matrix} (q_1, x) \\ (q_1, y) \\ (q_2, x) \\ (q_2, y) \end{matrix} & \begin{pmatrix} 1(\{q_1\}) & 0(\{q_1\}) & \perp & \perp \\ 0(\{q_1\}) & 1(\{q_1\}) & \perp & \perp \\ & & & \\ & & & \end{pmatrix} \end{matrix}$$

Transition monoid for Streaming String Transducer for ω strings



$$M_b = \begin{matrix} & \begin{matrix} (q_1, x) & (q_1, y) & (q_2, x) & (q_2, y) \end{matrix} \\ \begin{matrix} (q_1, x) \\ (q_1, y) \\ (q_2, x) \\ (q_2, y) \end{matrix} & \begin{pmatrix} 1(\{q_1\}) & 0(\{q_1\}) & \perp & \perp \\ 0(\{q_1\}) & 1(\{q_1\}) & \perp & \perp \\ 1(1) & 0(1) & \perp & \perp \\ 0(1) & 1(1) & \perp & \perp \end{pmatrix} \end{matrix}$$

Outline

- Introduction
 - Three formalisms for transductions
 - Related work
 - Aperiodic transformations for Infinite strings
 - Aperiodic two way transducer
 - Aperiodic streaming string transducer
 - **Equivalence results and Proof ideas**
 - $SST_{sf} \subset FOT = 2WST_{sf} \subset SST_{sf}$
 - Conclusion
-

Equivalence results

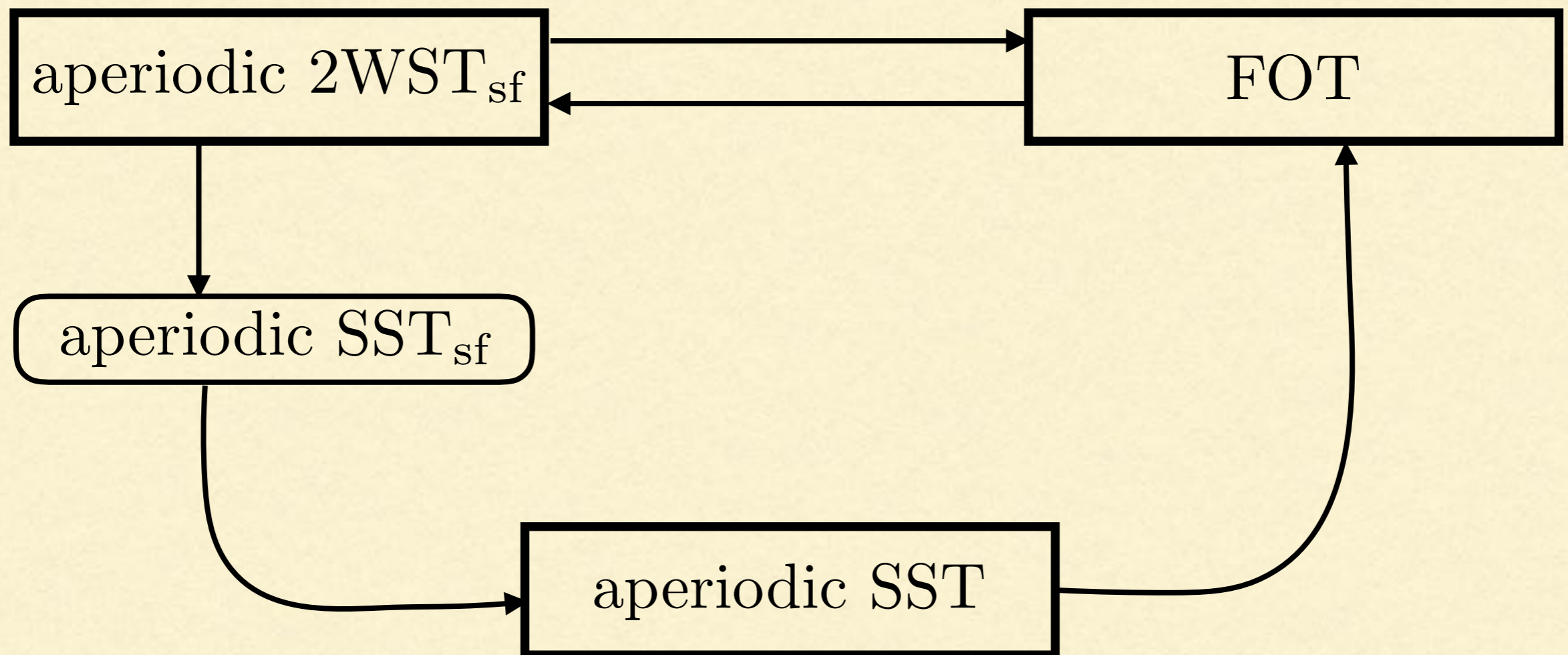
Equivalence results

aperiodic $2WST_{sf}$

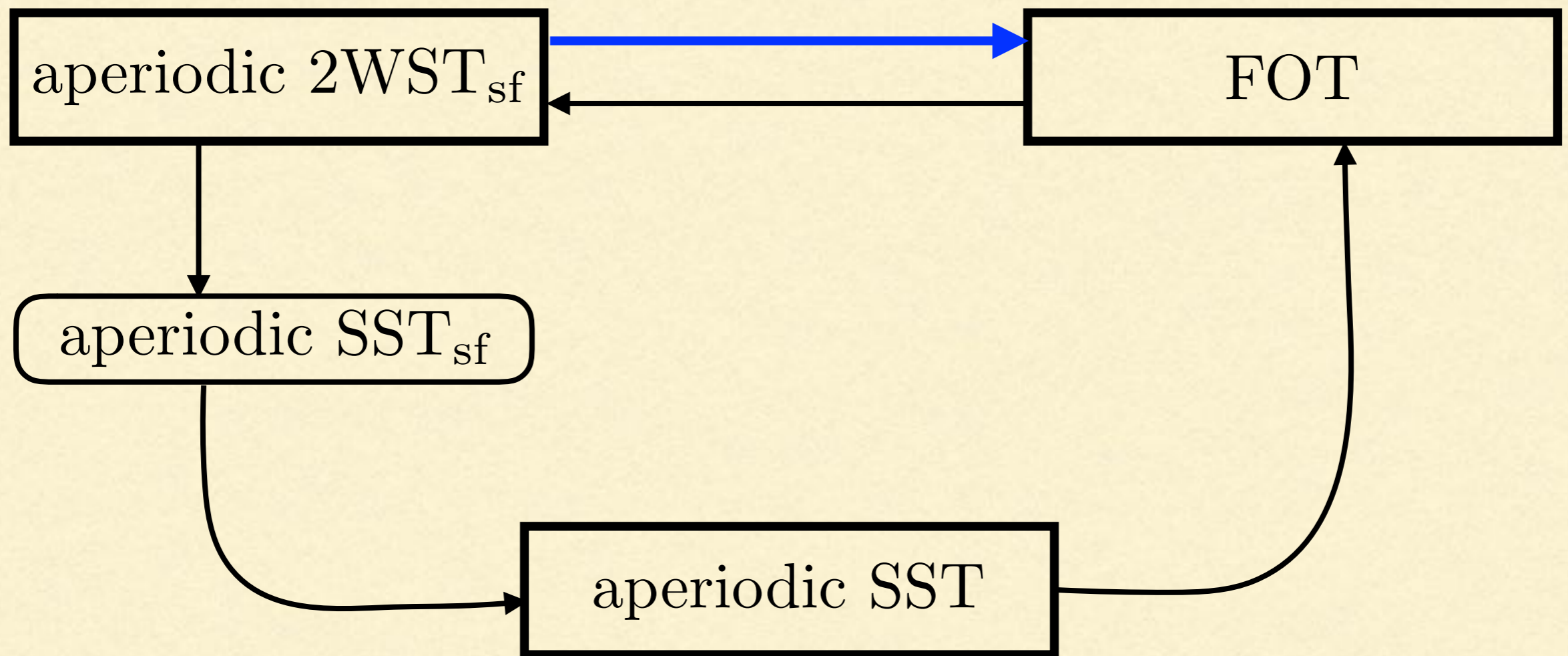
FOT

aperiodic SST

Equivalence results



Results



aperiodic $2\text{WST}_{\text{sf}} \subseteq \text{FOT}$

aperiodic $2\text{WST}_{\text{sf}} \subseteq \text{FOT}$

input

aperiodic $2\text{WST}_{\text{sf}} \subseteq \text{FOT}$

input a_1 a_2 a_3 a_4 a_5 a_6 a_7 a_8

aperiodic $2WST_{sf} \subseteq FOT$

input a_1 a_2 a_3 a_4 a_5 a_6 a_7 a_8 Σ
 ϕ_{dom} ✓

aperiodic $2WST_{sf} \subseteq FOT$

input



Σ
 ϕ_{dom} ✓

aperiodic $2WST_{sf} \subseteq FOT$

input



Σ
 ϕ_{dom} ✓



output

aperiodic $2WST_{sf} \subseteq FOT$

input



Σ
 ϕ_{dom} ✓



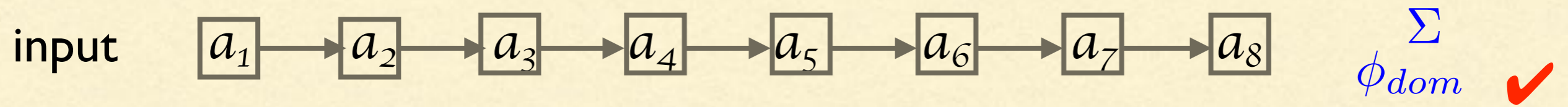
output

q_1

q_2

q_n

aperiodic $2WST_{sf} \subseteq FOT$

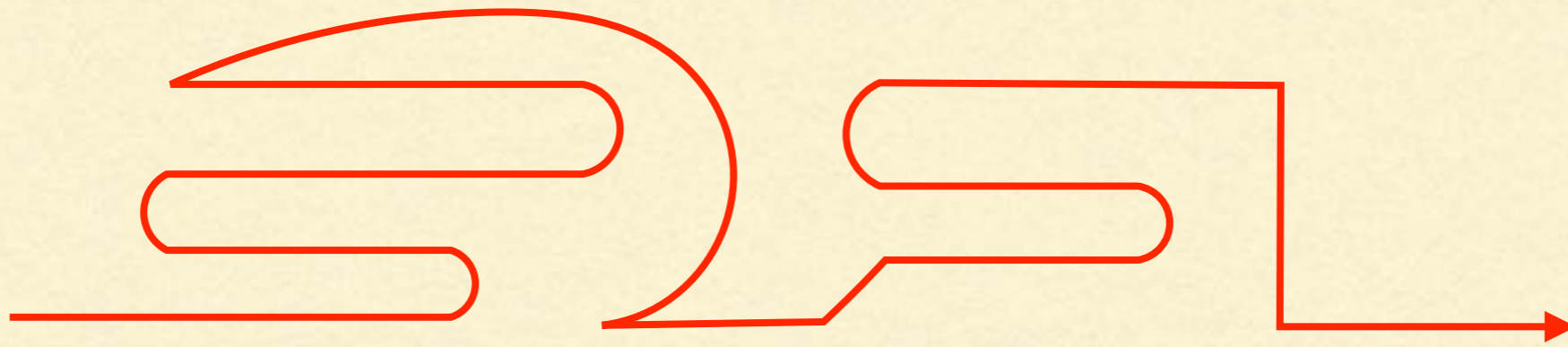


output

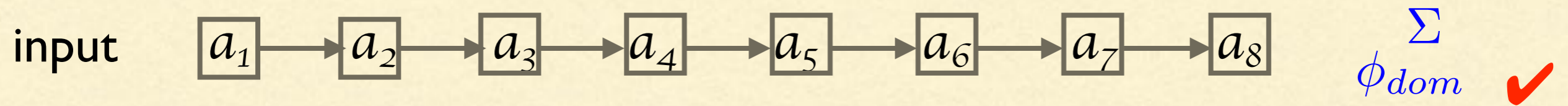
q_1

q_2

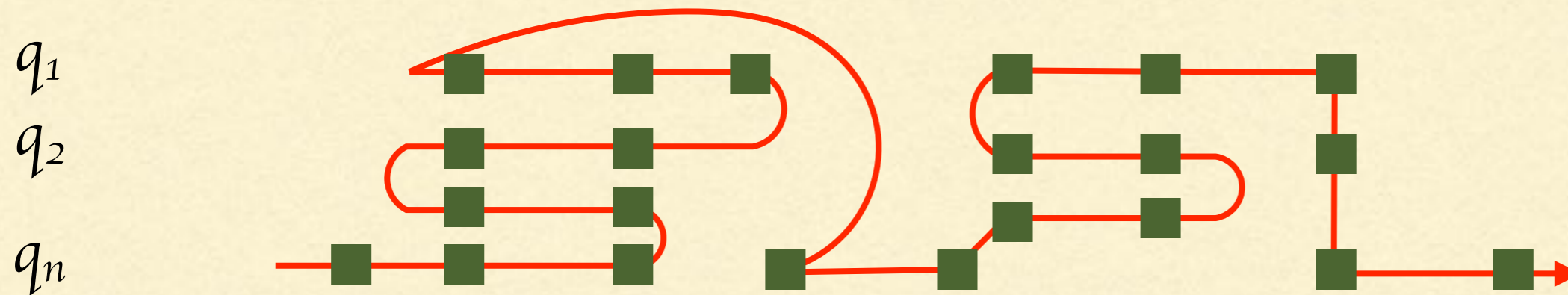
q_n



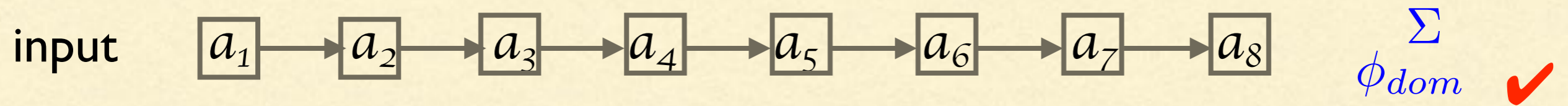
aperiodic $2WST_{sf} \subseteq FOT$



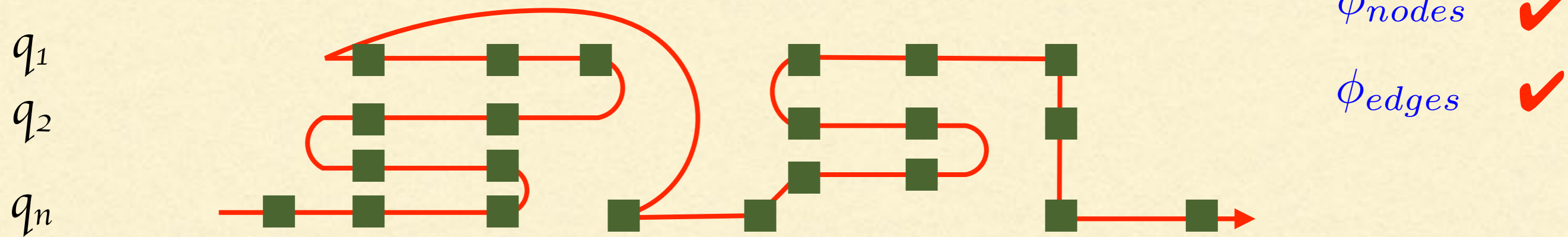
output



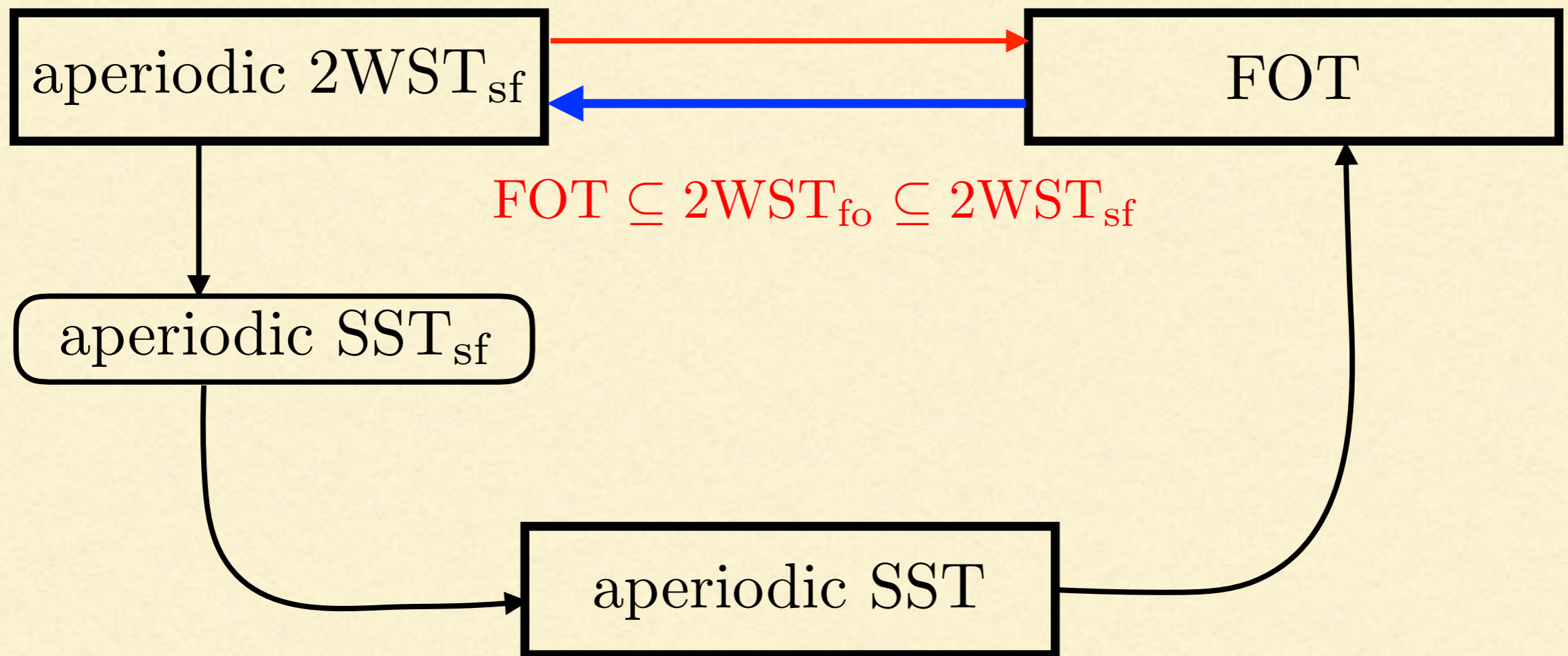
aperiodic $2WST_{sf} \subseteq FOT$



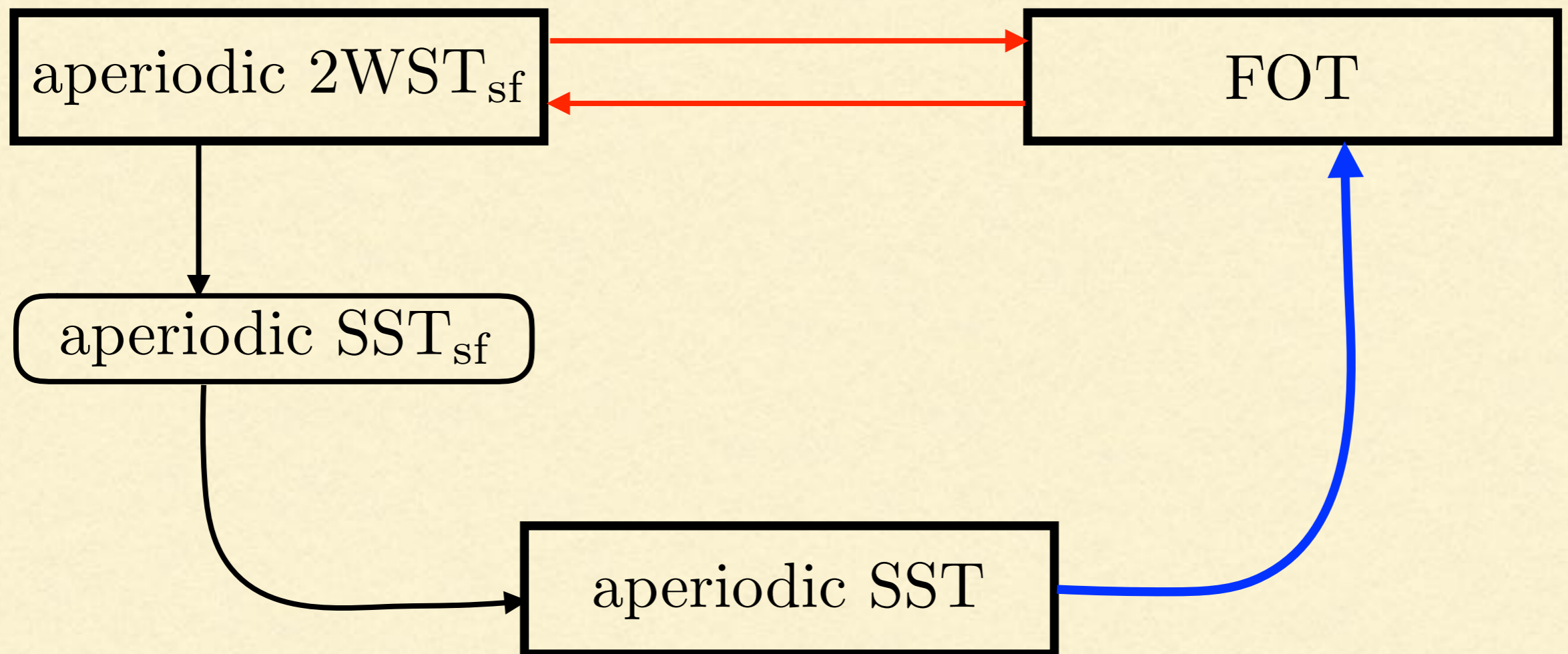
output



Results



Results



Aperiodic SST \subset FOT

[FKT'14]

Aperiodic SST \subset FOT

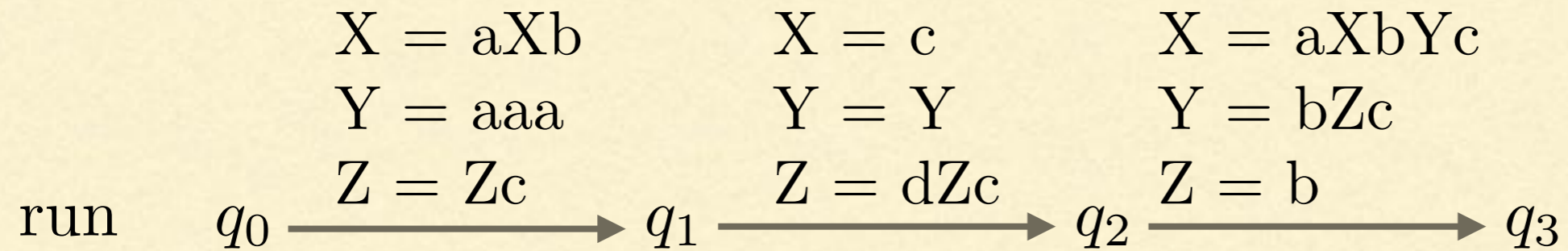
SST output structure :

[FKT'14]

Aperiodic SST \subset FOT

SST output structure :

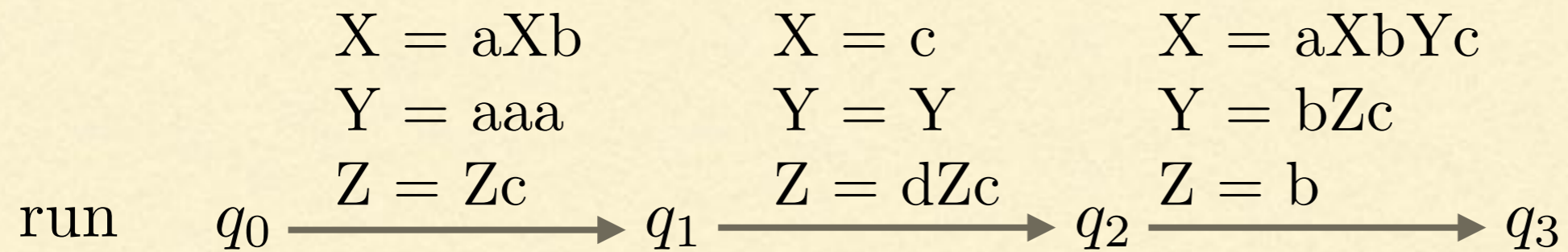
[FKT'14]



Aperiodic SST \subset FOT

SST output structure :

[FKT'14]



X^{in}

X^{out}

Y^{in}

Y^{out}

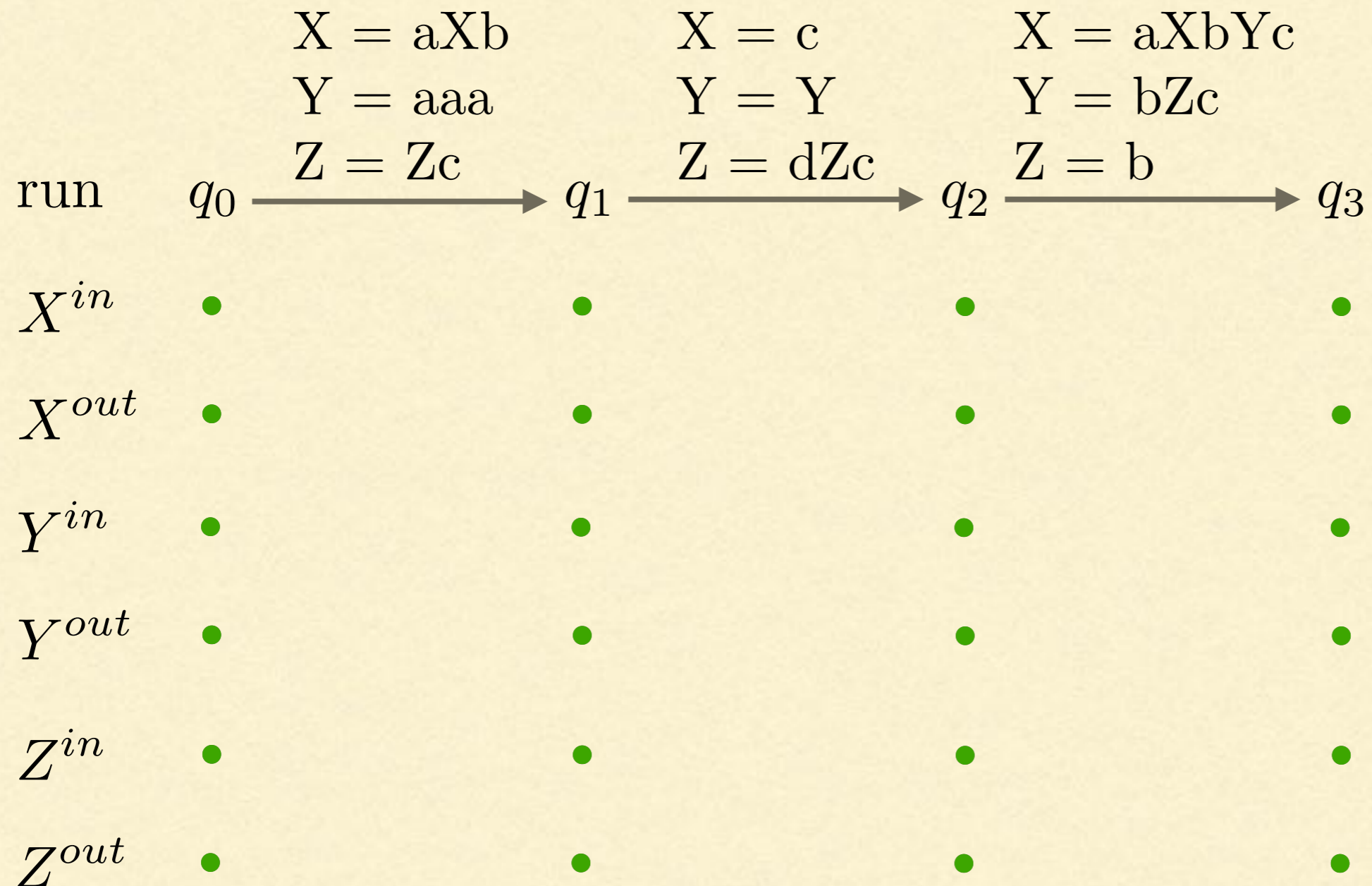
Z^{in}

Z^{out}

Aperiodic SST \subset FOT

SST output structure :

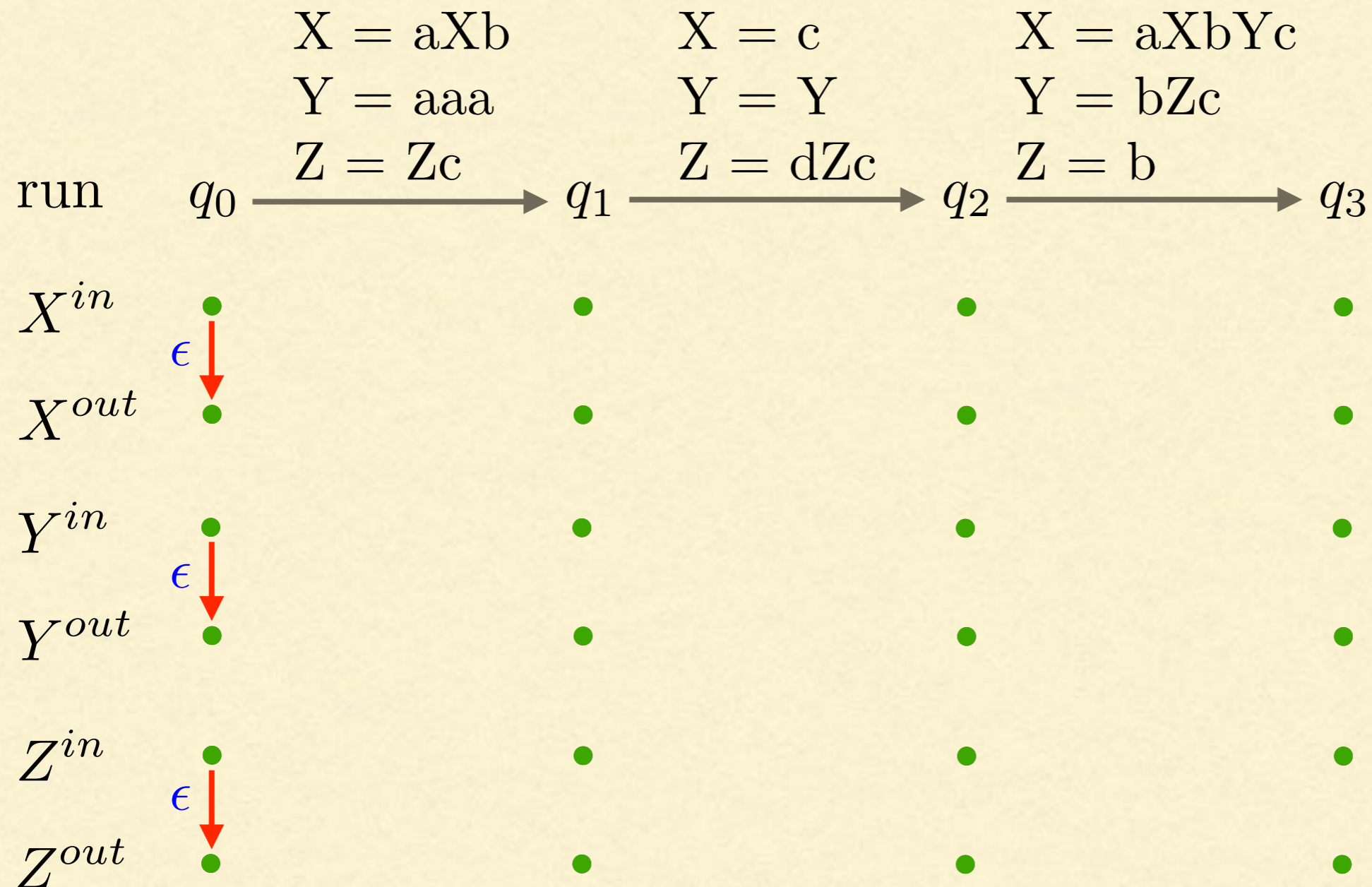
[FKT'14]



Aperiodic SST \subset FOT

SST output structure :

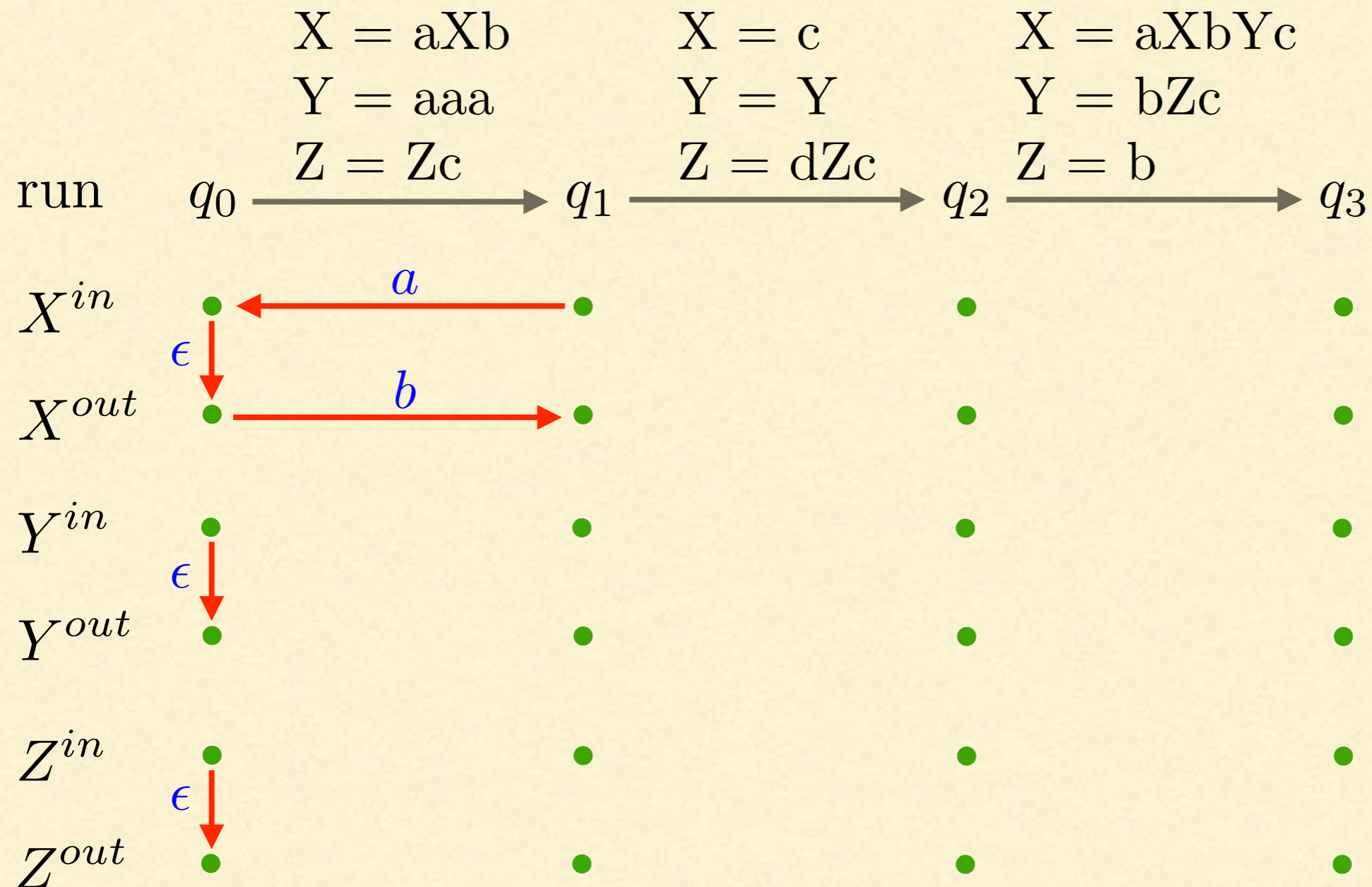
[FKT'14]



Aperiodic SST \subset FOT

SST output structure :

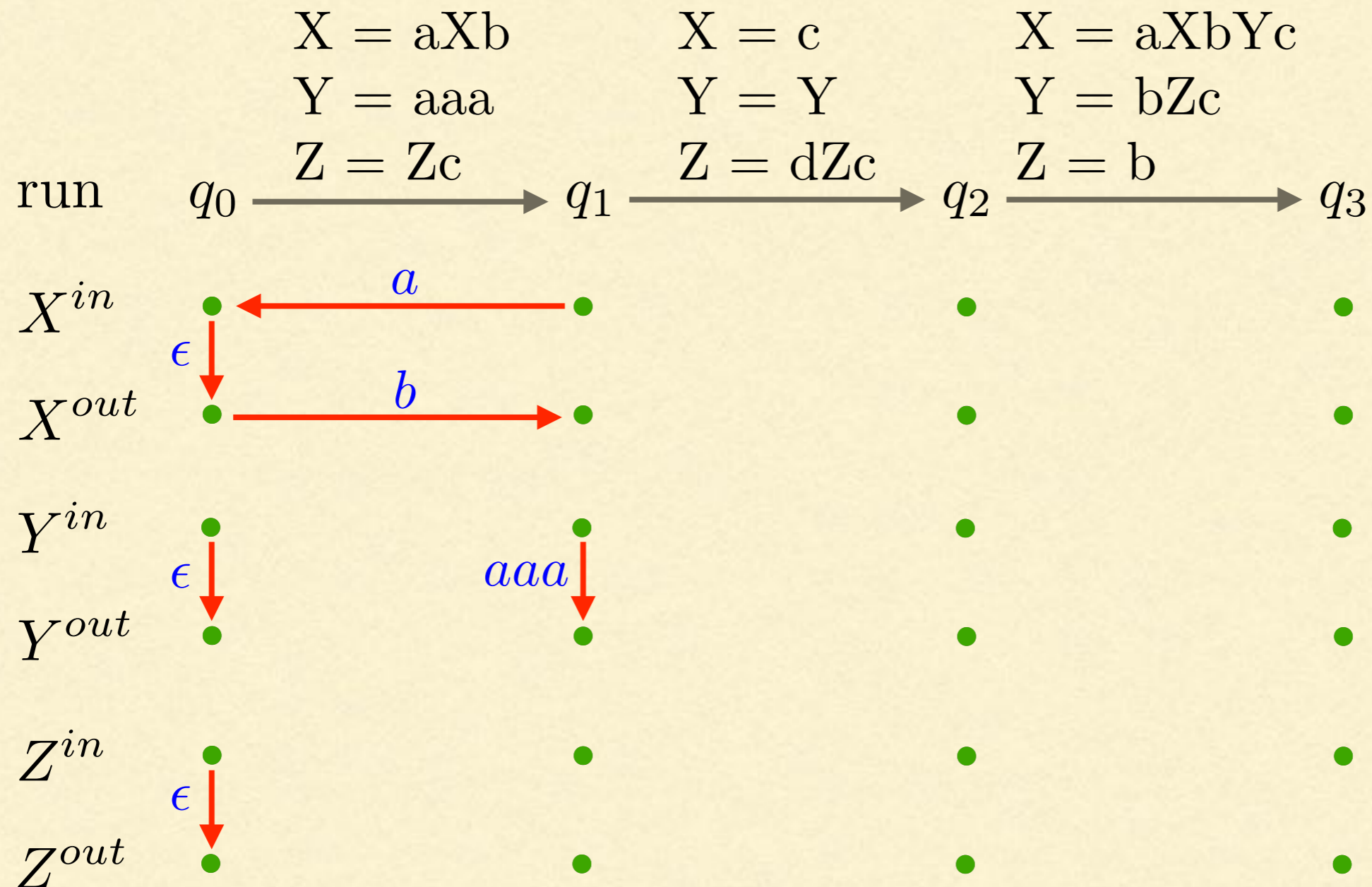
[FKT'14]



Aperiodic SST \subset FOT

SST output structure :

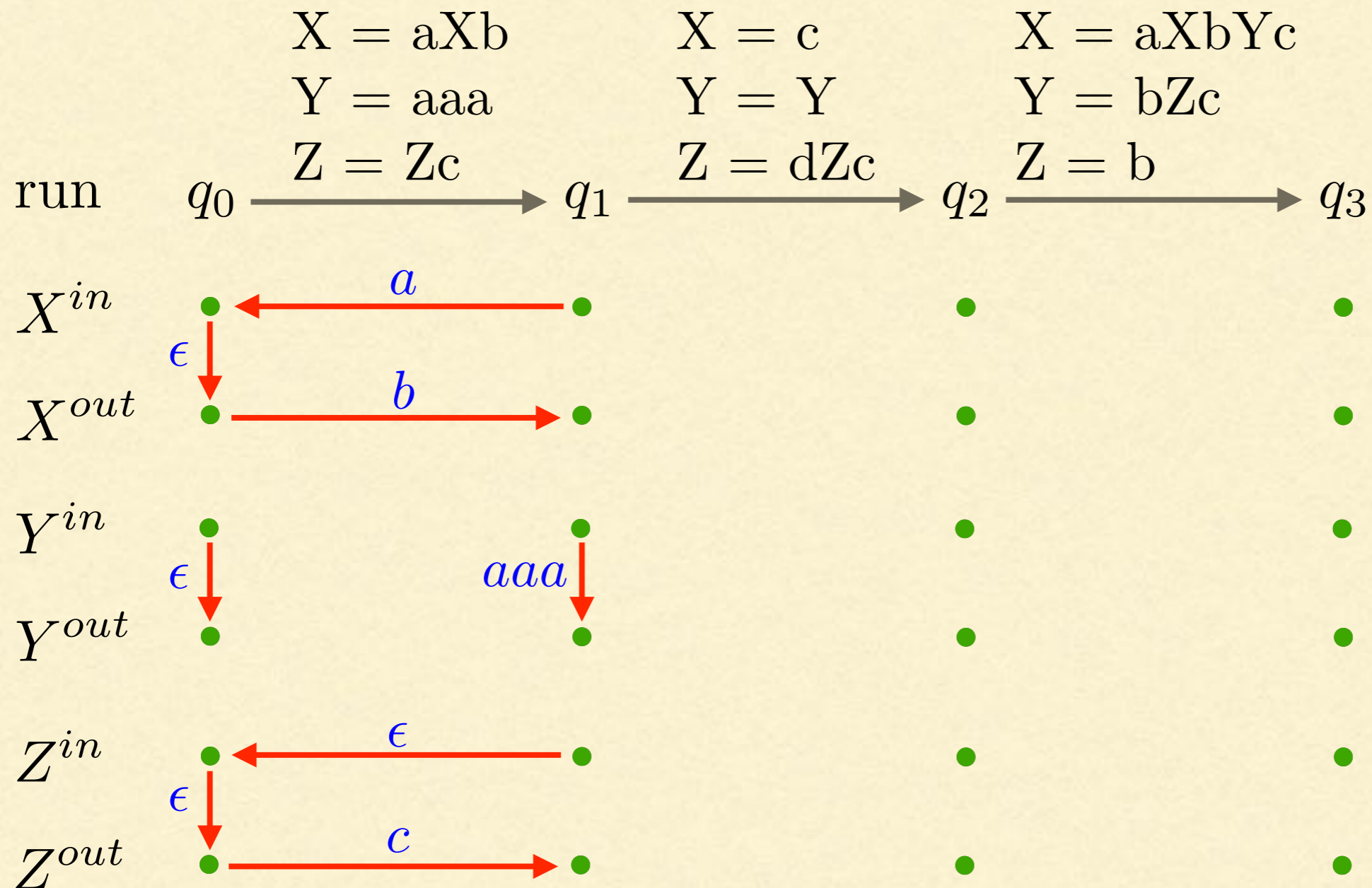
[FKT'14]



Aperiodic SST \subset FOT

SST output structure :

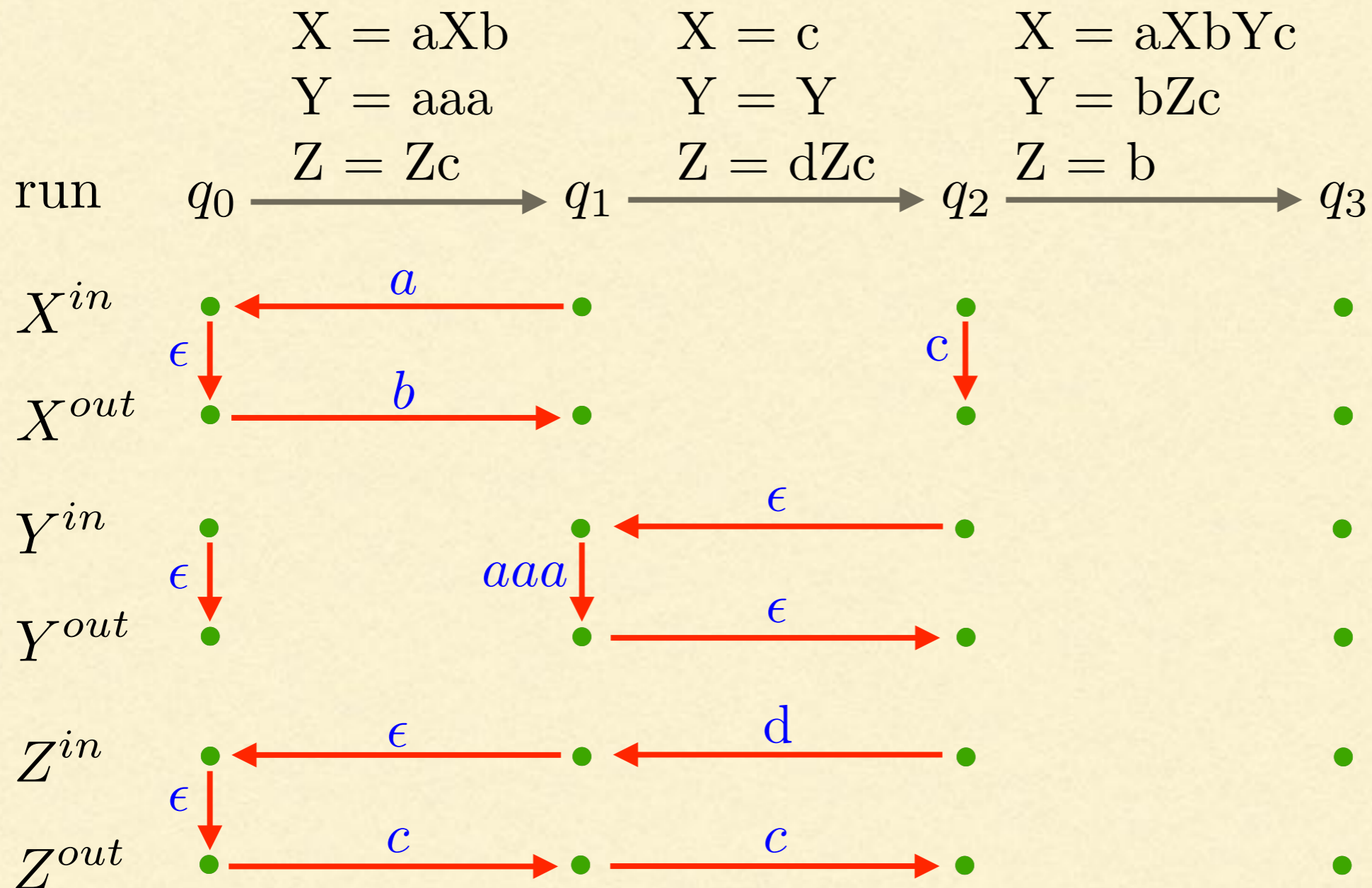
[FKT'14]



Aperiodic SST \subset FOT

SST output structure :

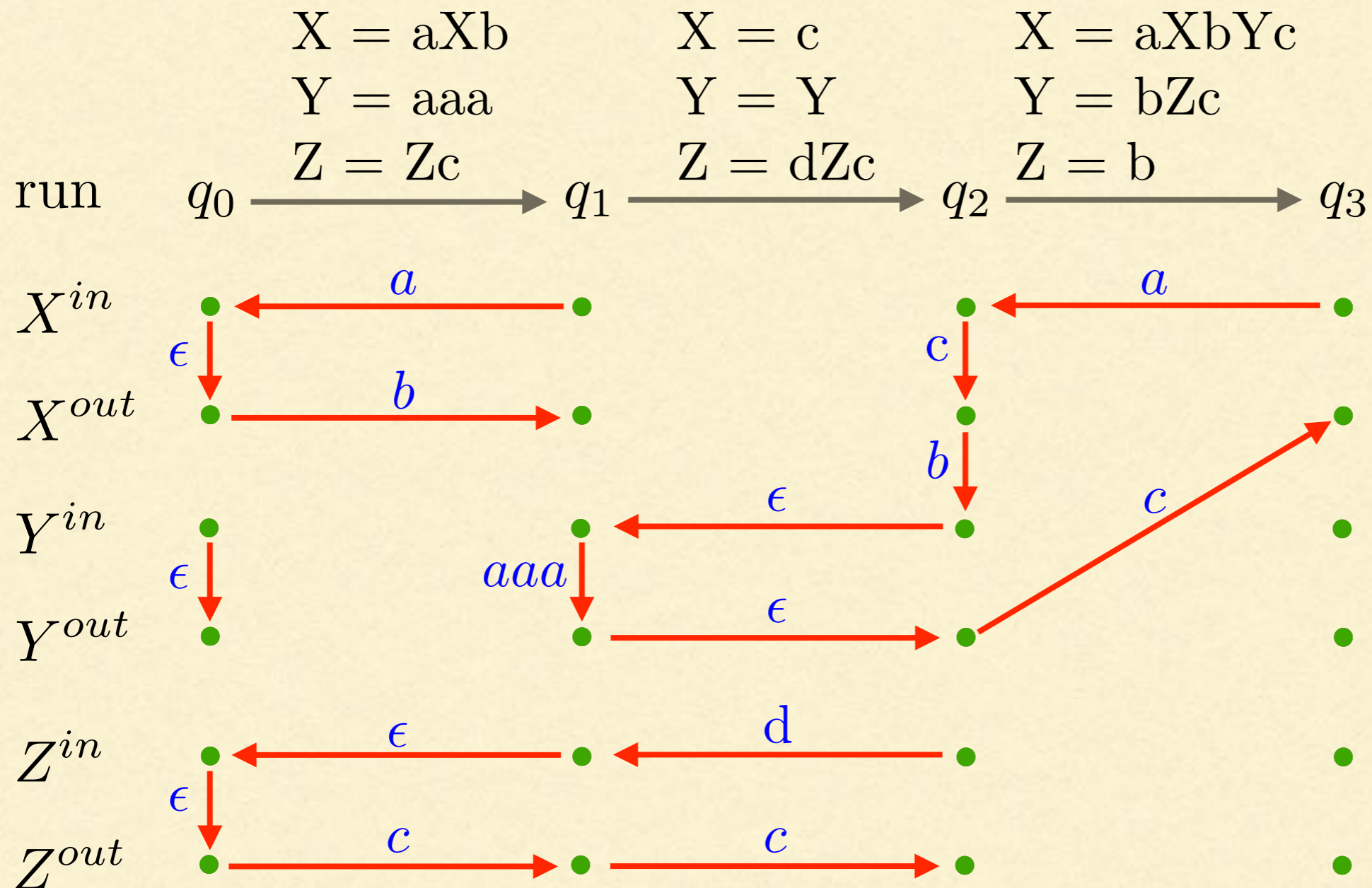
[FKT'14]



Aperiodic SST \subset FOT

SST output structure :

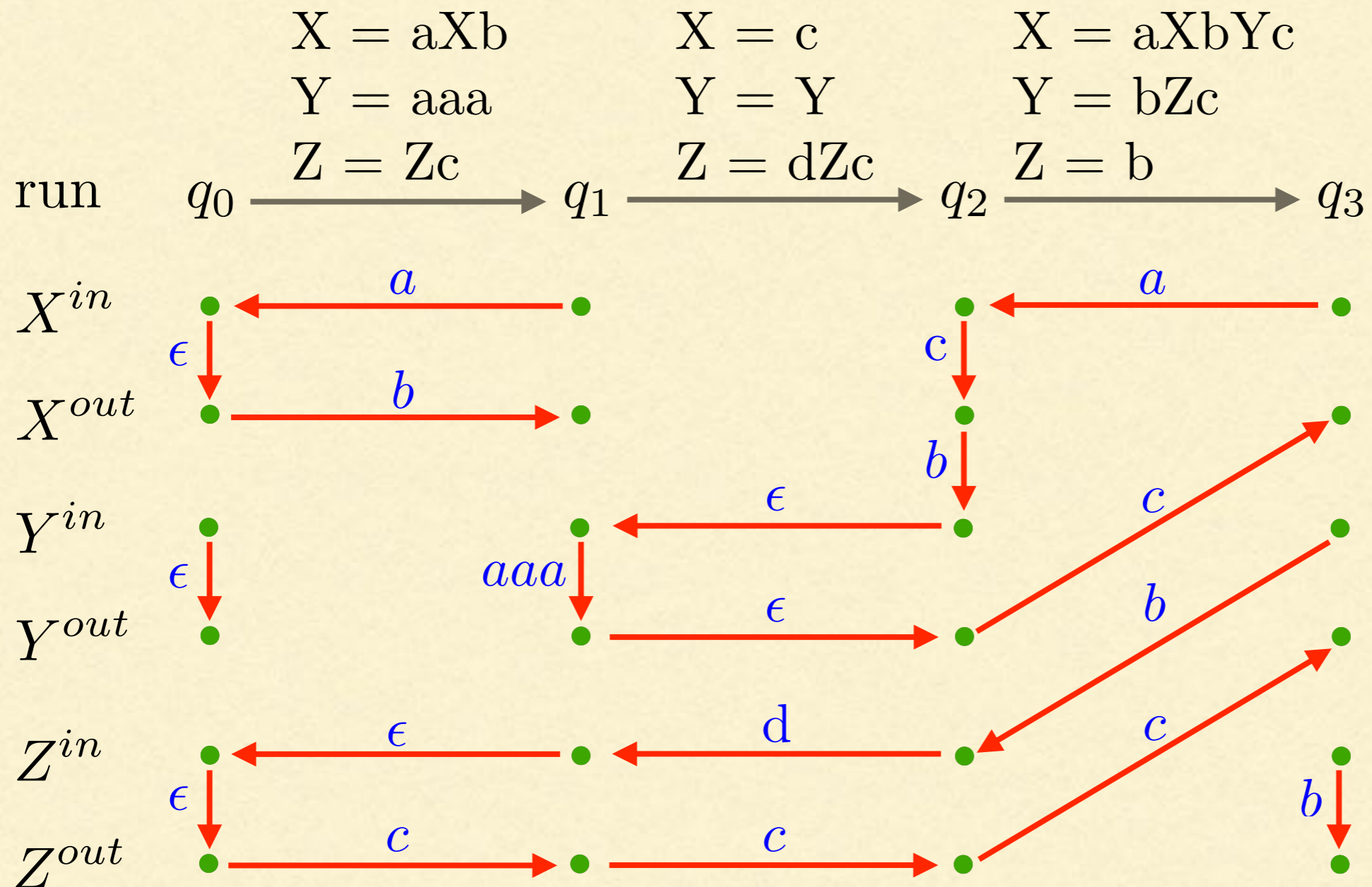
[FKT'14]



Aperiodic SST \subset FOT

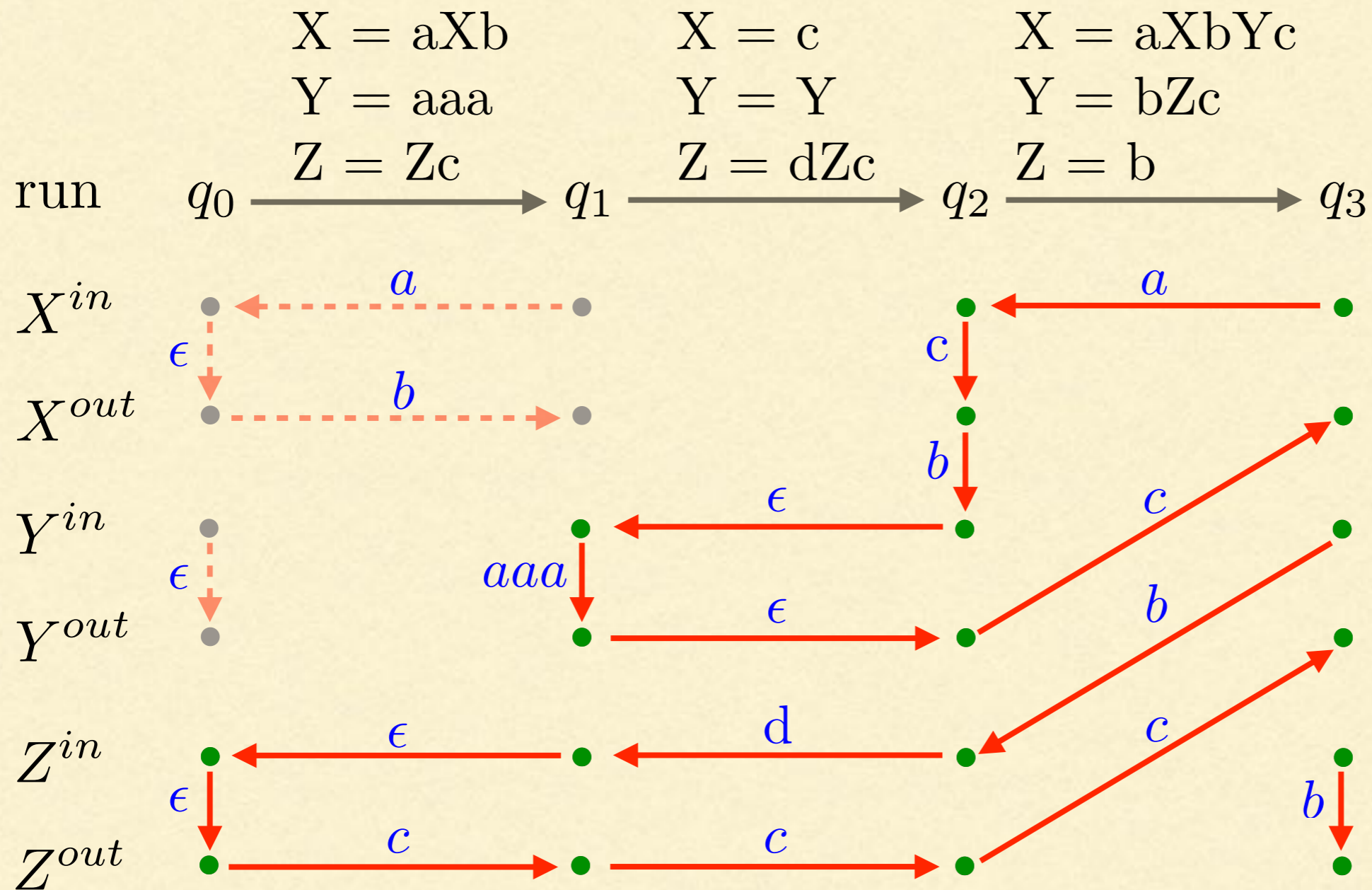
SST output structure :

[FKT'14]



Aperiodic SST \subset FOT

SST output structure :

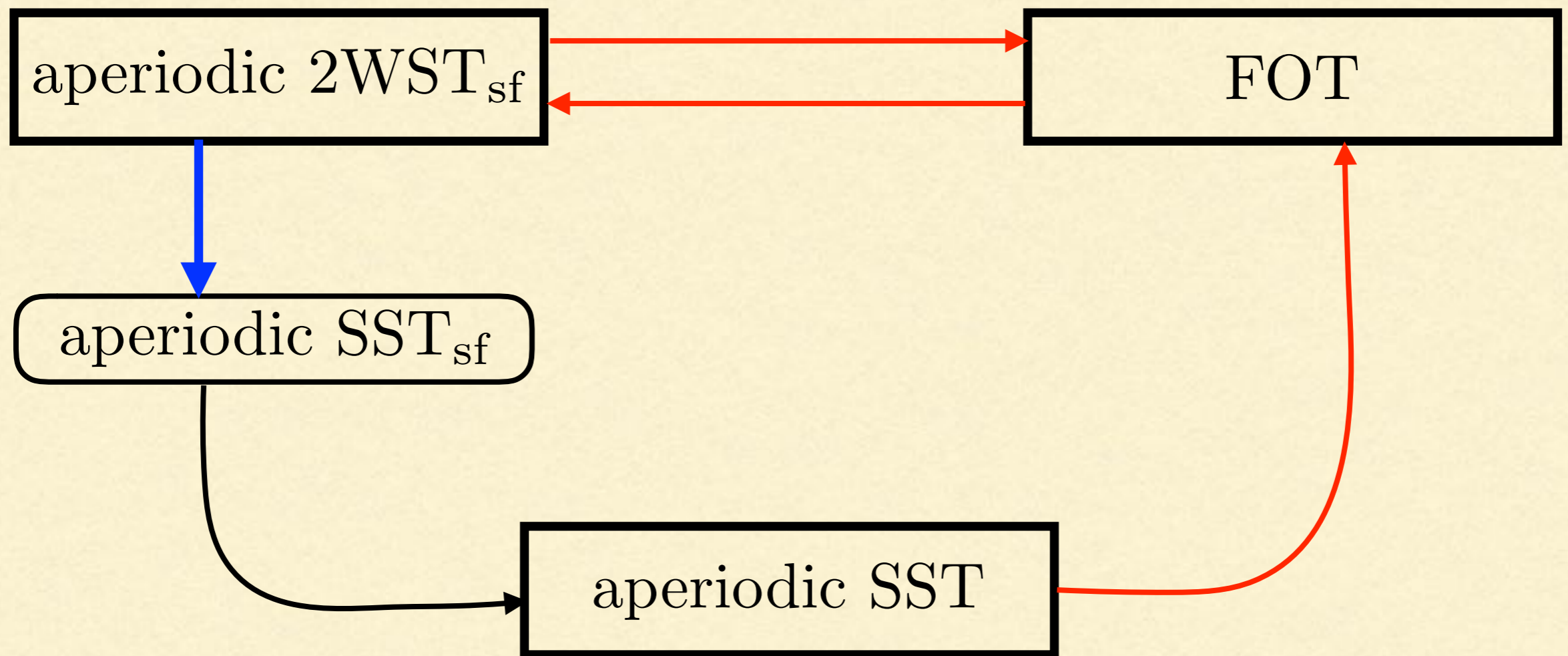


Aperiodic SST \subset FOT

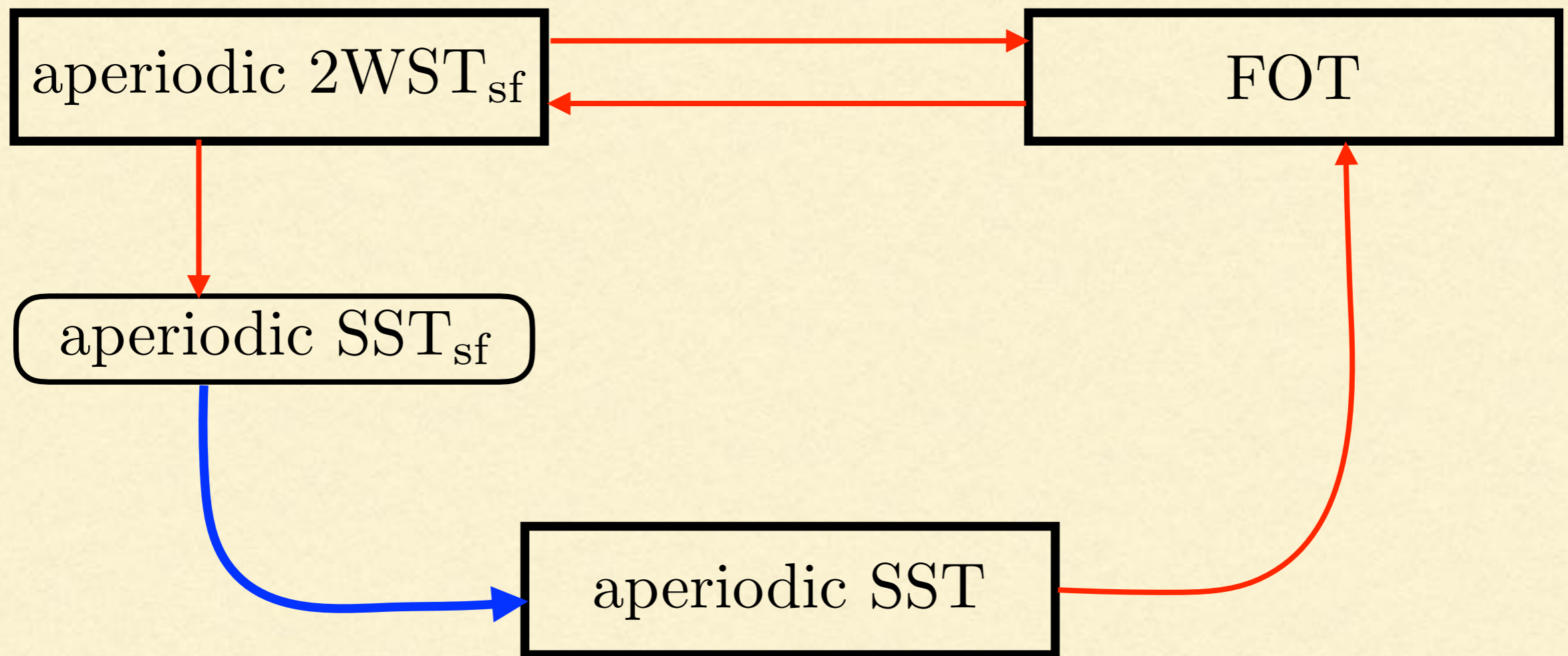
Claim 1: $\forall X, Y \in \mathcal{X}, \forall d, e \in \{in, out\}, \forall s \in \text{dom}(\mathbb{T}), \forall i, j \in \text{dom}(s),$
 $(X^d, i) \rightsquigarrow (Y^e, j)$ is FO-definable.

Claim 2: $\phi_q(x)$ is FO definable

Results



Results



Conclusion

Conclusion

- We have defined
 - Transition monoid for muller automaton
 - Transition monoid for 2WST and SST of infinite string
-

Conclusion

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Language :

FO logic

|||

Aperiodic Automata

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- Equivalence Results

Language :

FO logic

|||

Aperiodic Automata

Transducers :

FO transducer

|||

Aperiodic Transducer

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